BFS search in miniKanren

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The syntax of a programming language should reflect its semantics. When using a disjunction operator in relational programming, a programmer would expect all clauses of this disjunction to share the same chance of being explored, as these clauses are written in parallel. The existing disjunctive operators in miniKanren, however, prioritize their clauses by the order of which these clauses are written down. We have devised a new search strategy that searches evenly in all clauses. Based on our statistics, miniKanren slows down by a constant factor after applying our search strategy. (tested with very-recursiveo, need more tests)

ACM Reference Format:

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1 INTRODUCTION

OUTLINE:

(About miniKanren) (Why the left clauses are explored more frequently?

(How to solve the problem?)

(Summary of later sections)

2 COST OF ANSWERS

The cost of an answer is the number of relation applications needed to find the answer. We use the miniKanren relation repeato in Fig. 1 to demonstrate the cost of answers. We borrow this idea from Silvija Seres's work [*]. repeato relates x with a list whose elements are all xs. The run expression uses repeato to generate 4 lists whose elements are all *s. The order of the answers reflects the order miniKanren discovers them. The leftmost answer is discovered first. The order here is not suprising: to generate the answer '(), miniKanren needs to apply repeato only once. And it needs more applications of repeato to find the later answers that are more complicated. In this example, the cost of each answer is the same as one more than the number of *s. No answer of zero cost exists.

For the above run, both search strategies produces answers in increasing order of costs, i.e. both of them are *cost-respecting*. In more complicated cases, however, interleaving DFS does not always produces answers in cost-repecting order. For instance, with iDFS the run in Fig. 2 produces answers in a seemingly random order. In contrast, the same run with BFS produces answers in an expected order (Fig. 3).

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```
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     (defrel (repeato x out)
49
       (conde
50
          [(== '() out)]
51
          [(fresh (res)
52
             (== '(,x . ,res) out)
53
             (repeato x res))]))
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55
     > (run 4 q
56
          (repeato '* q))
57
     '(() (*) (* *) (* * *))
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59
                                          Fig. 1. repeato
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62
     > (run 12 q
63
          (conde
64
            [(repeato 'a q)]
65
            [(repeato 'b q)]
66
            [(repeato 'c q)]))
67
     '(() (a) ()
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69
       (a a) () (a a a)
70
       (b) (a a a a) (c)
71
       (a a a a a) (b b) (a a a a a a))
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73
                           Fig. 2. run a program with interleaving depth-first search
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76
     > (run 12 q
77
          (conde
78
            [(repeato 'a q)]
79
            [(repeato 'b q)]
80
            [(repeato 'c q)]))
81
     '(()()()
82
       (a) (b) (c)
83
       (a a) (b b) (c c)
84
       (a a a) (b b b) (c c c))
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86
```

Fig. 3. run a program with breadth-first search

Although all answers by iDFS is not in cost-respecting order, the answers from each case are in cost-respecting order. The problem is that iDFS strategy prioritizes the first conde case considerablely. In general, when every conde case are equally productive, the iDFS strategy takes $1/2^i$ answers from the *i*-th case, except the last case, which share the same portion as the second last.

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3 CHANGE SEARCH STRATEGY

Now we change the search strategy and optimize the system in three steps. The result of these steps are mk-1, mk-2, and mk-3 respectively. The initial miniKanren is named mk-0, which is the miniKanren in TRS2.

3.1 representation of search space

In mk-0, search space is represented by streams. Streams can be finite or infinite. Finite streams are just lists. And infinite streams are improper lists, whose last cdr is a procedure which takes no arguments and returns a stream when involked. Cars of streams are (possibly incomplete) answers. We call the cars the mature part, and the last cdr the immature part.

(connect stream with cost)

3.2 initial version

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(explain mk-0's append-inf)

```
(define (append-inf s-inf t-inf)
  (cond
    ((null? s-inf) t-inf)
    ((pair? s-inf)
     (cons (car s-inf)
       (append-inf (cdr s-inf) t-inf)))
    (else (lambda ()
            (append-inf t-inf (s-inf))))))
```

To make the search BFS, we just need to have append-inf combines mature parts in the fashion of append, and combine non-empty immature parts by contructing a new procedure.

```
(define (append-inf s-inf t-inf)
  (let loop ([s? #t] [s-inf s-inf] [t-inf t-inf])
      ((pair? s-inf)
       (cons (car s-inf)
         (loop s? (cdr s-inf) t-inf)))
      ((null? s-inf) t-inf)
      (s? (loop #f t-inf s-inf))
      (else (lambda ()
              (append-inf (t-inf) (s-inf)))))))
```

stepstone of optimization

Make irrelevant parts in mK representation-independent w.r.t. search space, and combine mature part and immature part with cons.

3.4 optimization

The goal is to express BFS explicitly with queue, so that we don't have to generate all answers of the same cost at once.

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Interesting changes: (1) put thunks in a list; (2) change force-inf (introduced in 4.B) so that it can make progress in all thunks (3) use a queue to manage thunks in take-inf.

4 CONCLUSION

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REFERENCES

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