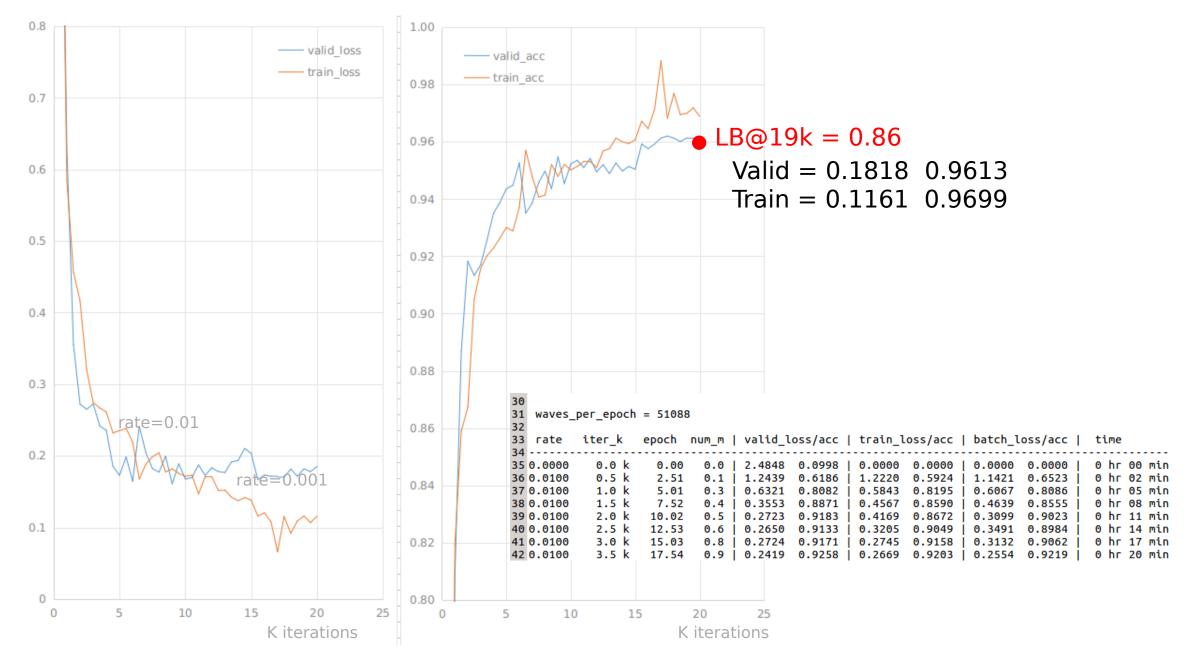
Some results for melspectrogram/ MFCC/ raw wave nets

<u> 1. raw wave (1d)</u>

```
class Simple1dNet(nn.Module):
   def init (self, in shape=(1,16000), num classes=12 ):
       super(Simple1dNet, self). init ()
       self.convla = ConvBnld( 1, 8, kernel size=3, stride=1)
       self.conv1b = ConvBn1d( 8, 8, kernel size=3, stride=1)
       self.conv2a = ConvBn1d( 8, 16, kernel size=3, stride=1)
       self.conv2b = ConvBn1d( 16, 16, kernel size=3, stride=1)
       self.conv3a = ConvBn1d( 16, 32, kernel size=3, stride=1)
       self.conv3b = ConvBn1d( 32, 32, kernel size=3, stride=1)
       self.conv4a = ConvBn1d( 32, 64, kernel size=3, stride=1)
       self.conv4b = ConvBn1d( 64, 64, kernel size=3, stride=1)
       self.conv5a = ConvBn1d( 64,128, kernel size=3, stride=1)
       self.conv5b = ConvBn1d(128,128, kernel size=3, stride=1)
       self.conv6a = ConvBn1d(128,256, kernel size=3, stride=1)
       self.conv6b = ConvBn1d(256,256, kernel size=3, stride=1)
       self.conv7a = ConvBn1d(256,256, kernel size=3, stride=1)
       self.conv7b = ConvBnld(256,256, kernel size=3, stride=1)
       self.conv8a = ConvBn1d(256,512, kernel size=3, stride=1)
       self.conv8b = ConvBn1d(512,512, kernel size=3, stride=1)
       self.conv9a = ConvBn1d(512,512, kernel size=3, stride=1)
       self.conv9b = ConvBn1d(512,512, kernel size=3, stride=1)
       \#self.linear1 = nn.Linear(512*31,1024)
       self.conv10a = ConvBn1d( 512,1024, kernel size=3, stride=1)
       self.conv10b = ConvBn1d(1024,1024, kernel size=3, stride=1)
       self.linear1 = nn.Linear(1024,512)
       self.linear2 = nn.Linear(512,256)
       self.fc
                    = nn.Linear(256, num classes)
```

```
def forward(self, x):
    #print(x.size())
   x = F.relu(self.convla(x),inplace=True)
   x = F.relu(self.conv1b(x),inplace=True)
   x = F.max poolld(x, kernel size=2, stride=2)
   #print(x.size())
   x = F.relu(self.conv2a(x),inplace=True)
   x = F.relu(self.conv2b(x),inplace=True)
   x = F.max poolld(x, kernel size=2, stride=2)
   #print(x.size())
   x = F.relu(self.conv3a(x),inplace=True)
   x = F.relu(self.conv3b(x),inplace=True)
   x = F.max poolld(x, kernel size=2, stride=2)
    #print(x.size())
   x = F.dropout(x,p=0.10,training=self.training)
   x = F.relu(self.conv4a(x),inplace=True)
   x = F.relu(self.conv4b(x),inplace=True)
   x = F.max poolld(x, kernel size=2, stride=2)
   #print(x.size())
   x = F.dropout(x,p=0.10,training=self.training)
   x = F.relu(self.conv5a(x),inplace=True)
   x = F.relu(self.conv5b(x),inplace=True)
   x = F.max poolld(x, kernel size=2, stride=2)
    #print(x.size())
    x = F.adaptive avg poolld(x,1)
    x = x.view(x.size(0), -1)
    x = F.dropout(x,p=0.50,training=self.training)
    x = F.relu(self.linearl(x),inplace=True)
    x = F.dropout(x,p=0.50,training=self.training)
    x = F.relu(self.linear2(x),inplace=True)
    x = self.fc(x)
    return x #logits
```

/root/share/project/kaggle/tensorflow/results/simple1d_net-10a/checkpoint/00019000_model.pth



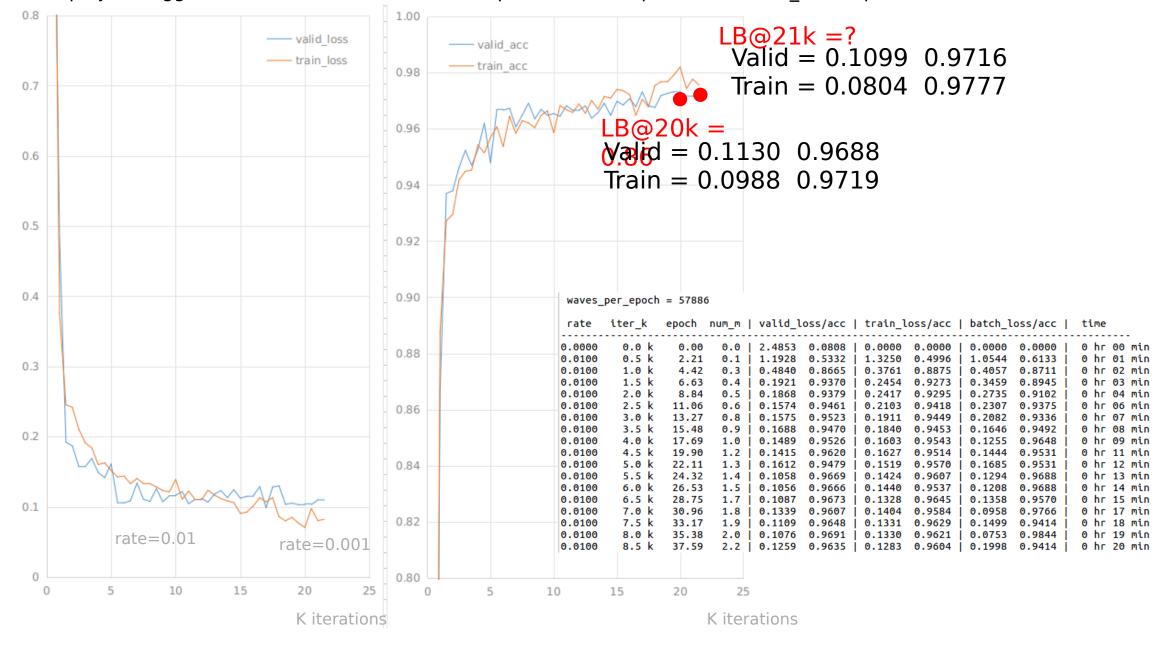
2. melspectrogram (2d)

```
class SeResNet3(nn.Module):
   def init (self, in shape=(1,40,101), num classes=12):
       super(SeResNet3, self). init ()
       in channels = in shape[0]
       self.layerla = ConvBn2d(in channels, 16, kernel size=(3, 3), stride=(1, 1))
       self.layer1b = ResBlock(16, 16)
       self.layer2a = ConvBn2d(16, 32, kernel size=(3, 3), stride=(1, 1))
       self.layer2b = ResBlock(32, 32)
       self.layer2c = ResBlock(32, 32)
       self.layer3a = ConvBn2d(32, 64, kernel size=(3, 3), stride=(1, 1))
       self.layer3b = ResBlock(64, 64)
       self.layer3c = ResBlock(64, 64)
       self.layer4a = ConvBn2d(64,128, kernel size=(3, 3), stride=(1, 1))
       self.layer4b = ResBlock(128,128)
       self.layer4c = ResBlock(128,128)
       self.layer5a = ConvBn2d(128, 256, kernel size=(3, 3), stride=(1, 1))
       self.layer5b = nn.Linear(256,256)
       self.fc = nn.Linear(256,num classes)
```

```
class ConvBn2d(nn.Module):
    def init (self, in channels, out channels, kernel size=3, padding=1, dilation=1, stride=1
        super(ConvBn2d, self). init ()
        self.conv = nn.Conv2d(in channels, out channels, kernel size=kernel size, padding=paddin
        self.bn = nn.BatchNorm2d(out channels)
        if is bn is False:
           self.bn =None
    def forward(self,x):
        x = self.conv(x)
       if self.bn is not None:
           x = self.bn(x)
        return x
class SeScale(nn.Module):
   def __init__(self, channel, reduction=16):
        super(SeScale, self). init ()
        self.fcl = nn.Conv2d(channel, reduction, kernel size=1, padding=0)
        self.fc2 = nn.Conv2d(reduction, channel, kernel size=1, padding=0)
    def forward(self, x):
        x = F.adaptive avg pool2d(x,1)
       x = self.fcl(x)
       x = F.relu(x, inplace=True)
       x = self.fc2(x)
       x = F.sigmoid(x)
        return x
class ResBlock(nn.Module):
    def init (self, in planes, out planes, reduction=16):
        super(ResBlock, self). init ()
        assert(in planes==out planes)
        self.conv bn1 = ConvBn2d(in planes, out planes, kernel size=3, padding=1, stride=1)
        self.conv bn2 = ConvBn2d(out planes, out planes, kernel size=3, padding=1, stride=1)
        self.scale = SeScale(out planes, reduction)
    def forward(self, x):
        z = F.relu(self.conv bn1(x),inplace=True)
       z = self.conv bn2(z)
       z = self.scale(z)*z + x
       z = F.relu(z,inplace=True)
        return z
```

```
def forward(self, x):
    x = F.relu(self.layerla(x),inplace=True)
   x = self.layer1b(x)
    x = F.max pool2d(x, kernel size=(2,2), stride=(2,2))
    x = F.dropout(x,p=0.1,training=self.training)
   x = F.relu(self.layer2a(x),inplace=True)
   x = self.laver2b(x)
   x = self.layer2c(x)
    x = F.max pool2d(x, kernel size=(2,2), stride=(2,2))
   x = F.dropout(x,p=0.2,training=self.training)
    x = F.relu(self.layer3a(x),inplace=True)
   x = self.layer3b(x)
    x = self.layer3c(x)
    x = F.max pool2d(x, kernel size=(2,2), stride=(2,2))
    x = F.dropout(x,p=0.2,training=self.training)
    x = F.relu(self.layer4a(x),inplace=True)
    x = self.layer4b(x)
    x = self.layer4c(x)
    x = F.dropout(x,p=0.2,training=self.training)
   x = F.relu(self.layer5a(x),inplace=True)
    x = F.adaptive avg pool2d(x,1)
    x = x.view(x.size(0), -1)
    x = F.relu(self.layer5b(x))
    x = F.dropout(x,p=0.2,training=self.training)
   x = self.fc(x)
    return x #logits
```

/root/share/project/kaggle/tensorflow/results/se-resnet3-spect-02a/checkpoint/00021000 model.pth



3. mfcc(2d)

```
class VggNet1(nn.Module):
    def init (self, in shape=(1,40,101), num classes=12):
       super(VggNet1, self). init ()
       self.convla = ConvBn2d(1, 8, kernel size=(3, 3), stride=(1, 1))
       self.conv1b = ConvBn2d(8, 8, kernel size=(3, 3), stride=(1, 1))
       self.conv2a = ConvBn2d(8, 16, kernel size=(3, 3), stride=(1, 1))
       self.conv2b = ConvBn2d(16, 16, kernel size=(3, 3), stride=(1, 1))
       self.conv3a = ConvBn2d(16, 32, kernel size=(3, 3), stride=(1, 1))
       self.conv3b = ConvBn2d(32, 32, kernel size=(3, 3), stride=(1, 1))
       self.linear1 = nn.Linear(32*12*5,512)
       self.linear2 = nn.Linear(512,256)
       self.fc
                   = nn.Linear(256, num classes)
   def forward(self, x):
       x = F.relu(self.convla(x),inplace=True)
       x = F.relu(self.conv1b(x),inplace=True)
       x = F.max pool2d(x, kernel size=(2,2), stride=(2,2))
       x = F.dropout(x,p=0.2,training=self.training)
       x = F.relu(self.conv2a(x),inplace=True)
       x = F.relu(self.conv2b(x),inplace=True)
       x = F.max pool2d(x, kernel size=(2,2), stride=(2,2))
       x = F.dropout(x,p=0.2,training=self.training)
       x = F.relu(self.conv3a(x),inplace=True)
       x = F.relu(self.conv3b(x),inplace=True)
       x = F.max pool2d(x, kernel size=(2,2), stride=(2,2))
       x = F.dropout(x,p=0.2,training=self.training)
       x = x.view(x.size(0), -1)
       x = F.relu(self.linear1(x),inplace=True)
       x = F.dropout(x,p=0.2,training=self.training)
       x = F.relu(self.linear2(x),inplace=True)
       x = self.fc(x)
       return x #logits
```

/root/share/project/kaggle/tensorflow/results/vgg1_net-06b/checkpoint/00083000_model.pth 0.8 1.00 valid loss valid acc train loss train acc 0.98 0.7 0.96 0.6 B@83k = 0.1821 0.95320.94 Train = $0.1803 \ 0.9488$ 0.5 0.92 0.4 0.90 waves_per_epoch = 51088 rate iter k epoch num m| valid loss/acc | train loss/acc | batch loss/acc | 0.0 k 0.88 0.00 0.0100 0.5 k 1.25 0.9850 0.6660 1.2023 0.5926 0.5938 0 hr 01 min 0.3 0.0100 1.0 k 2.51 0.6628 0.7852 0.8045 0.7359 0.7815 0.7500 0 hr 03 min 0.0100 1.5 k 3.76 0.4714 0.8416 0.6400 0.7953 0.7717 0.7578 0 hr 04 min 0.0100 2.0 k 5.01 0.5584 0.8138 0.6133 0.7992 0.6682 0.7500 0 hr 06 min 2.5 k 6.26 0.0100 0.4070 0.8622 0.5415 0.8172 0.5128 0.8125 0 hr 08 min 0.86 3.0 k 7.52 0.8700 0.8254 0.6335 0.7891 0.0100 0.3844 0.5453 0 hr 09 min 3.5 k 8.77 0.5630 0.8281 0.0100 0.3471 0.8828 0.4641 0.8527 0.2 0.0100 4.0 k 10.02 0.3392 0.8934 0.4467 0.8578 0.4552 0.8438 0 hr 13 min 4.5 k 11.27 0.8629 0.0100 0.2808 0.9043 0.4337 0.5054 0.8203 0 hr 14 min 5.0 k 12.53 0.9068 0.0100 0.2796 0.4043 0.8723 0.8750 0 hr 16 min 0.84 5.5 k 13.78 0.0100 0.2816 0.9024 0.8703 0.5822 6.0 k 15.03 0.0100 0.3261 0.8868 0.4005 0.8691 0.3281 0.8594 0 hr 19 min 6.5 k 16.29 0.2524 0.9124 0.8691 0.9141 0 hr 21 min 0.0100 0.1 7.0 k 17.54 0.2599 0.9180 0.3840 0.8762 0.3712 0.8672 0 hr 22 min 0.0100 0.0100 7.5 k 18.79 0.2400 0.9205 0.4027 0.8742 0.8281 0 hr 24 min 0.82 8.0 k 20.04 0.9199 0.3603 0.0100 0.2436 0.8888 0.4499 0.8438 0 hr 26 min 0.9255 0.0100 8.5 k 21.30 0.2336 0.3585 0.8887 0.4363 0.8750 0 hr 27 min 9.0 k 22.55 0.0100 0.2169 0.9317 0.3959 0.8691 0.2485 0.9141 0 0.80 100 0 20 40 60 80 20 40 60 80 100 K iterations K iterations