

YILDIZ TECHNICAL UNIVERSITY 2022 – FALL SEMESTER INDUSTRIAL MEASUREMENT SYSTEMS MKT4171 KADİR ERKAN KEMALETTİN KARA 1806A004 HOMEWORK1

Industrial Measurement Systems | MKT 4171 Kemalettin KARA 1806AOO4 BJ. HW1

$$\overline{X} = \frac{X_1 + X_2 + \dots + X_n}{n} = \frac{\stackrel{?}{\sum} \times}{n} = \frac{127.411}{2.5} = 5.09644$$

b) Average devolation

dn = xn- X -> deviation for one sample.

 $devation A11 \Rightarrow [4.617-5.0964] + [4.436-5.09644] + [5.039-5.09644] + [6.053-5.09644] + [4.602-5.09644] + [4.859-5.09644] + [4.859-5.09644] + [5.606-5.09644] + [5.242-5.09644] + [5.513-5.09644] + [5.242-5.09644] + [5.513-5.09644] + [5.35-5.09644] + [4.850-5.09644] + [4.850-5.09644] + [5.317-5.09644] + [5.317-5.09644] + [5.33-5.09644] + [6.850-5.09644] + [5.439-5.09644]$

Std = Average Dev. =
$$\sqrt{\frac{E d\ell^2}{n-1}}$$

= $\sqrt{\frac{3.60880616}{24}} = 0.3877717413$

Variance is square of standard deviation

Question 2 a) Unear fit 4=ax+b -> A.X=B=> AT.A.X=AT.B= 0 0,5 11,5 2 2,5 3 3,5 4 4,5 5 0 9 1 1 1 1 1 1 1 1 6) 2nd order Polynomial fit matrix are bolow; Y=qx2+bx+c For this question 0175 0151 Applaying 2025 15 ATAX=ATB 6.25 215 2013 (4 = 149x = 0.38x-azz 26.3 --01234 12,25 3,5 1 20,25 4,5 1 C) 3rd order polynomial fit. $Y = ax^{3} + 6x^{2} + cx + d$ 0,175 0,75 -1 = 0 a + 0 b + 0 c + d 0 = 0,125a + 025b +0,5c +d 3,375 7.25 115=10+16+1c+d 16 3= 3375a+2,256+1,56+d 2013 2,5 15,65 6,75 4 = Eathb + 2c +d 62.875 17,25 3,5 E=1,5625 a + 6,256 +2,50+8 16 91115 2015 45 25 125 26,3 = 91,125a + 20,25b + 4,5c +d 36 = 125a + 25b +5c+d

A, X=B.

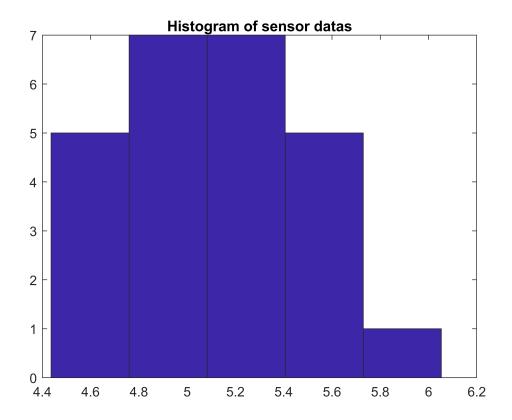
Equations obtained by forthing the motion A^{T} , A, $X=A^{T}$. B) Into the Place are solve A = 0.19 A = 0.19 A = 0.19 A = 0.19 A = 0.19 A = 0.19 A = 0.19 A = 0.19 A = 0.19 A = 0.19 A = 0.19 A = 0.19 A = 0.19 A = 0.19 A = 0.19 A = 0.19 A = 0.19 A = 0.19

KEMALETTİN KARA 1806A004 - HW1

QUESTION 1

```
reading = [4.617,4.436,5.039,6.053,4.642,4.859,5.583,5.606,5.242,5.513,5.435,4.809,5.214,4.850
total =0;
devTotal = 0;
deviations=[];
```

```
%%%%%%%% Standard deviation calculation and variance  %%%%
std = sqrt(sum(deviations.^2)/(size(reading,2)-1));
var = std^2;
```

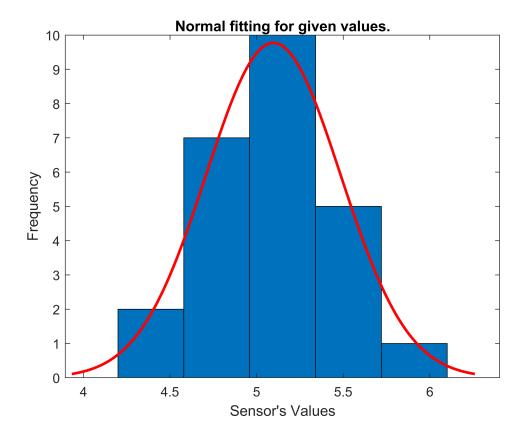


QUESTION 1 - PART F

```
% Normal distribution has two parameter and these parameters are declared
% in above mean and standard deviation.

% Normal distribution fitting
figure;
histfit(reading)

ylabel("Frequency")
xlabel("Sensor's Values")
title("Normal fitting for given values.")
```



QUESTION 1 - PART G

Summing of all element in the reading: 127.411000

fprintf("Sum of deviations: %f\n",devTotal)

Sum of deviations: 7.558560

fprintf("Average mean: %f\n",averageMean)

Average mean: 5.096440

fprintf("Deviation mean: %f\n",deviationMean)

Deviation mean: 0.302342

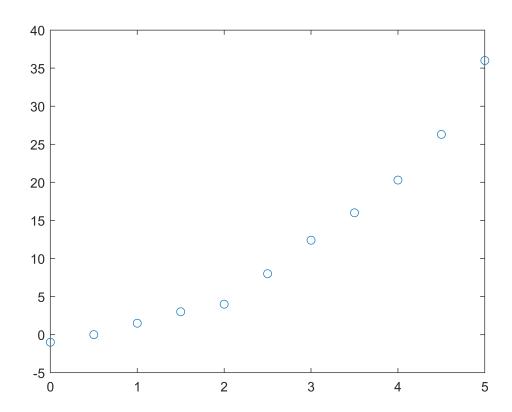
fprintf("Standard deviation: %f\n",std)

Standard deviation: 0.387772

fprintf("Variance: %f\n",var)

Variance: 0.150367

QUESTION 2



A) LINEAR FIT

```
func1 = 1×2
6.9273 -5.8182
```

```
c = func1' %transpoze
c = 2×1
```

6.9273 -5.8182

func1 = polyfit(X,Y,1)

```
poly1 = vpa(poly2sym(func1),3);
X1=X
```

```
X1 = 1×11
0 0.5000 1.0000 1.5000 2.0000 2.5000 3.0000 3.5000 · · ·
```

Y1=polyval(func1,X1) $Y1 = 1 \times 11$ -5.8182 -2.3545 1.1091 8.0364 11.5000 14.9636 18.4273 ... 4.5727 b) 2nd Order Polynomial Fit func2=polyfit(X,Y,2) $func2 = 1 \times 3$ 1.4890 -0.5179 -0.2343 c=func2' %transpoze $c = 3 \times 1$ 1.4890 -0.5179 -0.2343 poly2=vpa(poly2sym(func2),3) $poly2 = 1.49 x^2 - 0.518 x - 0.234$ X2=X $X2 = 1 \times 11$ 3.5000 ... 0 0.5000 1.0000 1.5000 2.0000 2.5000 3.0000 Y2=polyval(func2,X2) $Y2 = 1 \times 11$ -0.2343 -0.1210 0.7368 2.3392 4.6860 7.7774 11.6133 16.1937 ... c) 3rd Order Polynomial Fit func3=polyfit(X,Y,3) $func3 = 1 \times 4$ 0.1896 0.0671 2.1932 -1.0874 c=func3' %transpoze $c = 4 \times 1$ 0.1896 0.0671 2.1932 -1.0874 poly3=vpa(poly2sym(func3),3)

```
poly3 = 0.19 x^3 + 0.0671 x^2 + 2.19 x - 1.09
```

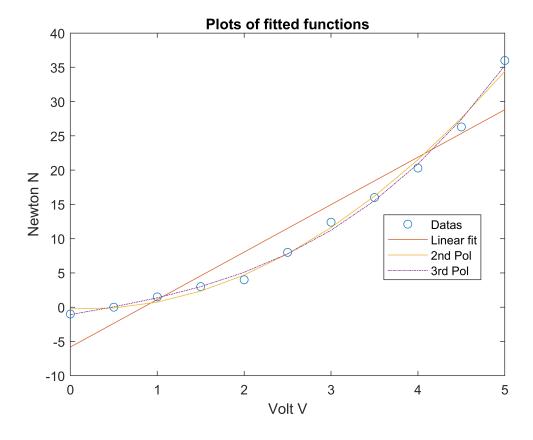
X3=X

X3 = 1×11 0 0.5000 1.0000 1.5000 2.0000 2.5000 3.0000 3.5000 · · ·

Y3=polyval(func3,X3)

Y3 = 1×11 -1.0874 0.0497 1.3625 2.9932 5.0841 7.7774 11.2152 15.5396 · · ·

```
plot(X,Y,'o',X1,Y1,'-',X2,Y2,'-',X3,Y3,'-.')
title("Plots of fitted functions")
xlabel("Volt V")
ylabel("Newton N")
legend('Datas','Linear fit','2nd Pol','3rd Pol','Location', 'Best')
```



func1

func1 = 1×2 6.9273 -5.8182

func2

```
func2 = 1×3
1.4890 -0.5179 -0.2343
```

func3

```
func3 = 1×4
0.1896 0.0671 2.1932 -1.0874
```

%KEMALETTİN KARA HOMEWORK1 END

Comparison and Comment

When I compared it with hand calculations, I noticed that there were errors due to rounding errors. In general, I think that hand calculations will be a hundred percent match when these errors are ignored. That's all I can see, thank you sir.