

Advanced Energy Vehicle Project

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Introduction

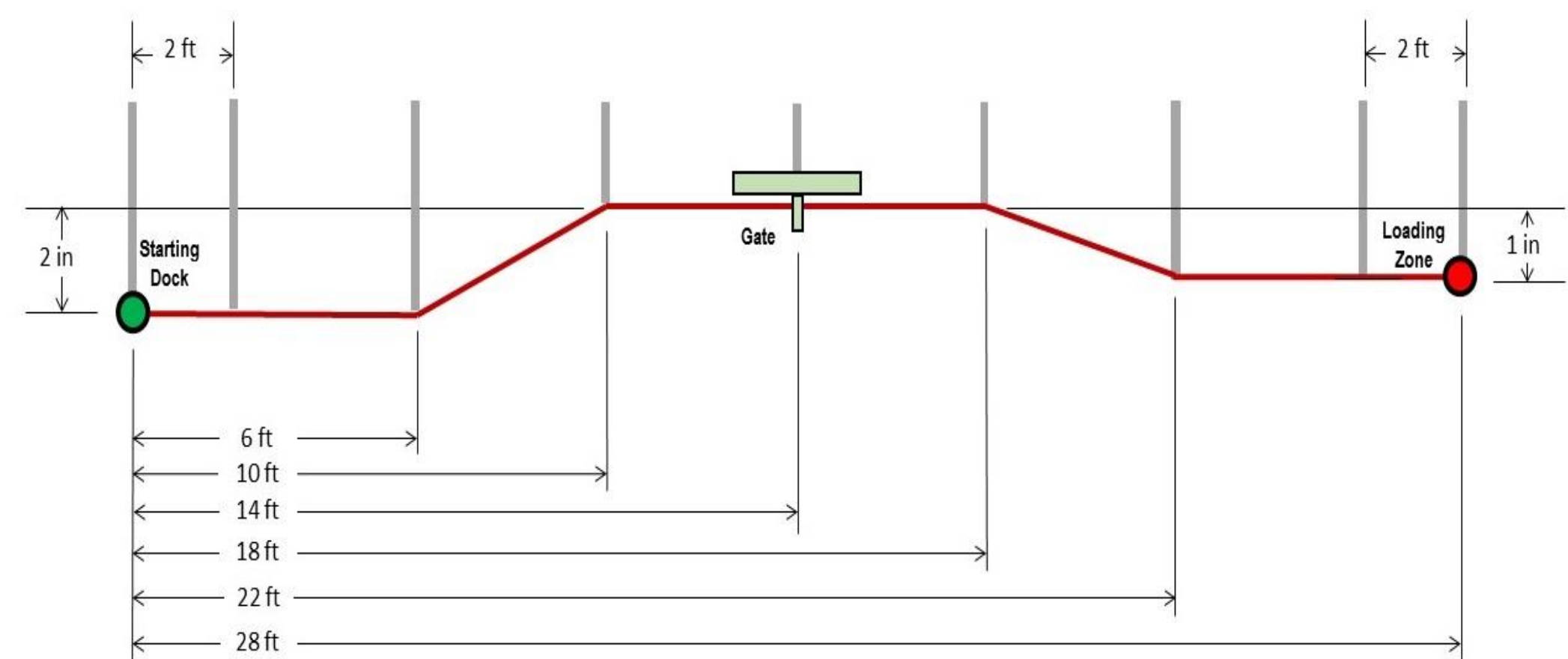


Figure 1.0 The Elevated AEV Test Track

- We are creating an autonomous, electric-powered vehicle
- The goal is to create the most energy and time efficient vehicle under the \$500k budget
- This is our final product after various testing and development

Design Process

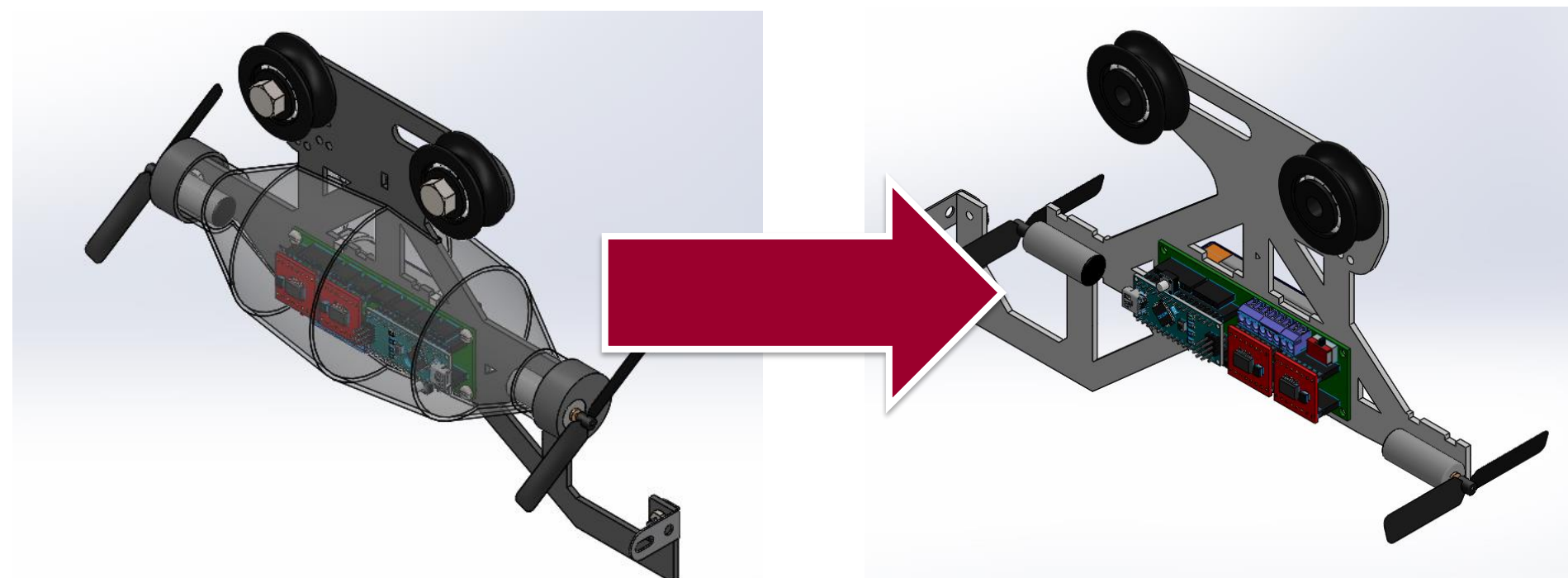


Figure 2.0 AEV with Shell

Figure 3.0 Current AEV

- The design of an unnecessary aerodynamic shell was dropped.

```
193 //Once vehicle reached first sensor =
194 unsigned long totalStopTime = 7*1000;
195 unsigned long startTime = millis();
196
197 //Now the vehicle should be moving forward
198 //Now the first sensor should already be reached
199 //We need to stop the vehicle
200 while(millis() - startTime < totalStopTime)
201 {
202   //If the vehicle is moving forward
203   if (getVehicleDirection() == 1)
204     motorSpeed(BackMotor, breakingSpeed);
205   goFor(breakingTime);
206   motorSpeed(BackMotor, RestSpeed);
207 }
```

Figure 4.0 Complex Code

Figure 5.0 Simple Code

- Complex code was simplified to increase consistency.

Final AEV Design

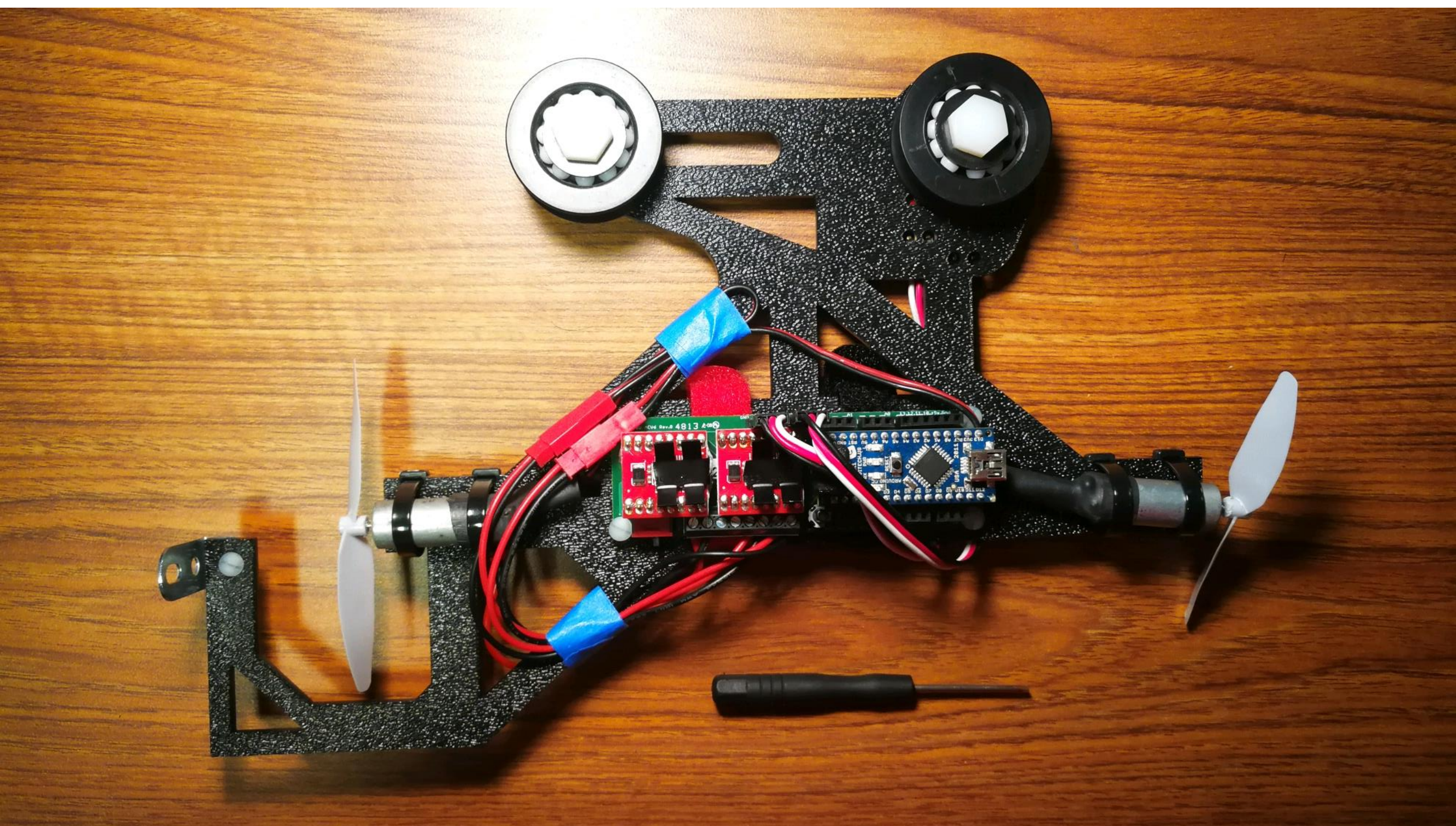


Figure 6.0 Team P Final AEV Model and Design

Core Features

1. Propeller Size and Positioning:



Figure 7.0 3-inch Propeller

- The 3in propeller was chosen over the 2in for it increases thrust exponentially

Dynamic Thrust Equation
 $F = \text{thrust (N)}, d = \text{prop diam. (in.)}, \text{RPM} = \text{prop rotations/min.}, \text{pitch} = \text{prop pitch (in.)}, V_0 = \text{propeller forward airspeed (m/s)}$

$$F = 4.392399 \times 10^{-8} \cdot \text{RPM} \cdot \frac{d^{3.5}}{\sqrt{\text{pitch}}} (4.23333 \times 10^{-4} \cdot \text{RPM} \cdot \text{pitch} - V_0)$$

Figure 7.1 Thrust Equation

2. Custom-made Support Arm:

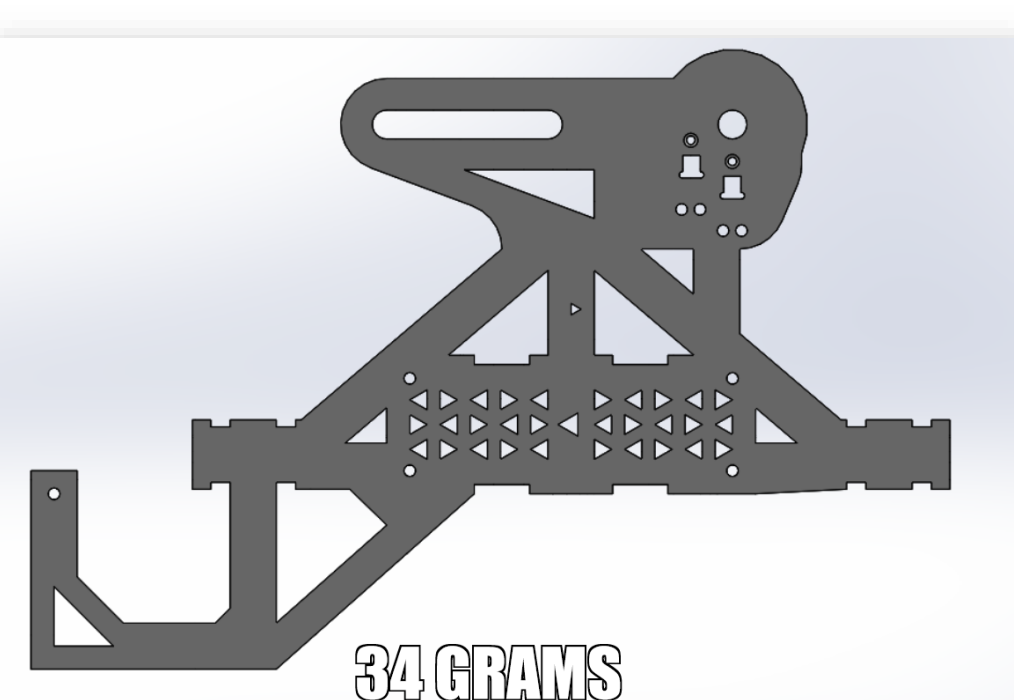


Figure 8.0 Central Support Arm

- Lightweight
- Two-direction Motor Support
- Provide Clearance for Propellers

3. Hybrid Braking System:

- A hybrid braking system incorporates a combination of coasting and power braking.
- This can be done by allowing the AEV to coast and then brake with the reverse motor.
- The hybrid braking approach increases accuracy and precision and also decreases the amount of power used.

4. Propelling Method:

- There are 3 possible propelling methods for our AEV, pulling, pushing, and hybrid.
- From our R&D tests, the pulling motor configuration was shown to be the most effective.
- The pulling propeller method can be used in both directions due to our design choices.

ACKNOWLEDGEMENTS

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Result

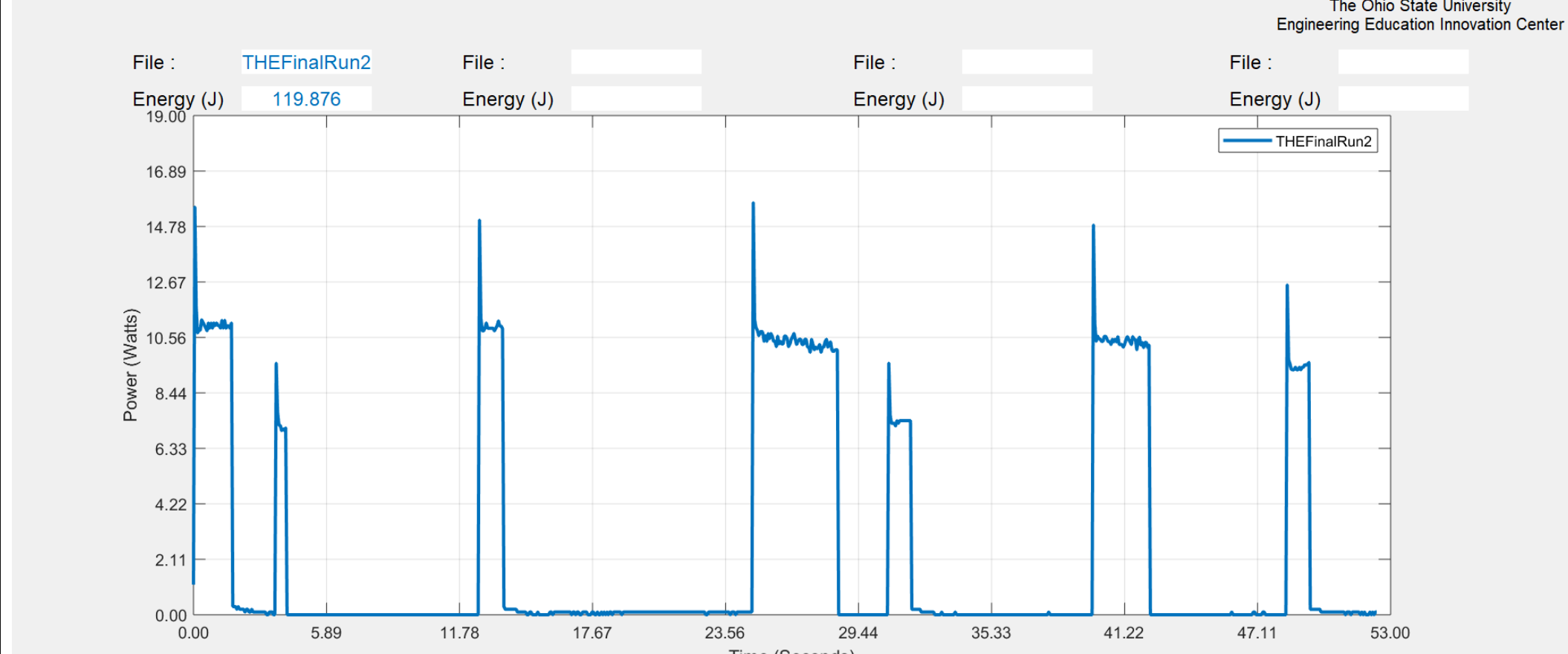


Figure 9.0 Final Performance Test Result (Best 1 of 3)

- Time Used: 50 s
- Energy Used: 119.8 J

Comparison to Class Average

- 51 seconds vs. 55 seconds
- 120.9 Joules vs. 224 Joules

- Capital Cost: \$148,540
- Final Cost: \$534,014.04

Table 10.0 Total Cost Analysis

	Best 2 of 3 Runs
Capital Costs	\$ 148,540
Energy Costs	\$ 185,450
Time Costs	\$ 166,500
Accuracy Penalty	1.052631579
R&D Costs	\$ -
Safety Violations	\$ 15,000
TOTAL COST	\$ 534,014.04

Conclusion

- A lightweight vehicle with a support arm was created for use and testing for energy efficiency
- The propellers were tested and found to be more efficient using a bigger size and a pulling method
- Hybrid braking was used for accuracy in Performance testing