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STAT-445/645: Applied Multivariate Analysis

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What to do today?

Part I. Introduction and Preparation

Part I.1. General Introduction

Part I.2. Review on Matrix Algebra (Chp 2.1-4, Supplement 2A)

I.2.1. Why do we need matrix/vector algebra in STAT445/645?

I.2.2. Notation and Basic Definitions

I.2.3. Vector Operations

I.2.4. Matrix Operations

Part I.3. Introduction to R

Part I.4. Multivariate Random Variables and Distributions (Chp 1, 2.5-6, 3)

Part I.4.1 Random Vectors and Matrices (Chp 2.5)

Part I.4.2 Mean Vectors and Covariance Matrices (Chp 2.6)

I.2.2. Notation and Basic Definitions

- ▶ a real number; a **scalar**; a physical quantity
- ▶ A **vector** is a group of p numbers/elements arranged in a *column*: a p -dim vector.
- ▶ A $p \times q$ **matrix** is a group of mk numbers/elements arranged into a rectangular array with p *rows* and q *columns*.

I.2.3. Vector Operations

- ▶ **scalar multiplication, addition, subtraction;**
- ▶ **inner product, length of a vector, angle between two vectors**

I.2.4. Matrix Operations

- ▶ transpose , scalar multiplication, addition, subtraction.

Properties. Associative property; distributive property; commutative property

- ▶ matrix multiplication. The product of $p \times q$ matrix $\mathbf{A} = (a_{ij})$ and $q \times k$ matrix $\mathbf{B} = (b_{ij})$ is $\mathbf{AB} = \mathbf{C} = (c_{ij})$, a $p \times k$ matrix with $c_{ij} = \sum_{l=1}^q a_{il} b_{lj}$.

Properties. Associative; distributive over addition; not commutative (!); $(\mathbf{AB})' = \mathbf{B}' \mathbf{A}'$

- ▶ inverse of a square matrix $\mathbf{A} = (a_{ij})$ is $\mathbf{B} = \mathbf{A}^{-1}$ such that $\mathbf{BA} = \mathbf{AB} = \mathbf{I}$, the identity matrix.

- ▶ If \mathbf{A}^{-1} exists, \mathbf{A} is *invertible* (*nonsingular, full rank*).
- ▶ $(\mathbf{AB})^{-1} = \mathbf{B}^{-1}\mathbf{A}^{-1}$ if well-defined.
- ▶ $(\mathbf{A}')^{-1} = (\mathbf{A}^{-1})'$ if well-defined.
- ▶ If $\mathbf{A}'\mathbf{A} = \mathbf{I}$, \mathbf{A} is **orthogonal**. Iff $\mathbf{A}' = \mathbf{A}^{-1}$, \mathbf{A} is **orthogonal**.

- The **determinant** of a square matrix $\mathbf{A} = (a_{ij})_{k \times k}$ is denoted by $|\mathbf{A}|$ or $\det(\mathbf{A})$:

$$\begin{aligned} |\mathbf{A}| &= a_{11}, & k = 1 \\ |\mathbf{A}| &= \sum_{j=1}^k (-1)^{1+j} a_{1j} |\mathbf{A}_{1j}|, & k > 1 \end{aligned}$$

where \mathbf{A}_{1j} is the $(k - 1) \times (k - 1)$ matrix obtained from \mathbf{A} after deleting its first row and j th column.

e.g.

$$\begin{vmatrix} 1 & 2 \\ 3 & 4 \end{vmatrix} = 1 * |4|(-1)^2 + 2 * |3|(-1)^3 = -2$$

$$\begin{vmatrix} 3 & 1 & 6 \\ 7 & 4 & 5 \\ 2 & -7 & 1 \end{vmatrix} = 3 * \begin{vmatrix} 4 & 5 \\ -7 & 1 \end{vmatrix} (-1)^2 + 1 * \begin{vmatrix} 7 & 5 \\ 2 & 1 \end{vmatrix} (-1)^3 + 6 * \begin{vmatrix} 7 & 4 \\ 2 & -7 \end{vmatrix} (-1)^4 = -222.$$

Property. $|\mathbf{A}| = |\mathbf{A}'|$; $|\mathbf{A}^{-1}| = |\mathbf{A}|^{-1}$; $|\mathbf{AB}| = |\mathbf{A}| |\mathbf{B}|$; $|c\mathbf{A}| = c^k |\mathbf{A}|$.

- The **trace** of a square matrix $\mathbf{A} = (a_{ij})_{k \times k}$ is

$$tr(\mathbf{A}) = \sum_{i=1}^k a_{ii}.$$

- $tr(c\mathbf{A}) = c * tr(\mathbf{A})$.
- $tr(\mathbf{A} + \mathbf{B}) = tr(\mathbf{A}) + tr(\mathbf{B})$.
- $tr(\mathbf{AB}) = tr(\mathbf{BA})$.
- $tr(\mathbf{AA}') = \sum_{i=1}^k \sum_{j=1}^k a_{ij}^2$.

- **partitioned matrices** e.g.

$$\mathbf{A} = \begin{pmatrix} \mathbf{A}_{11} & \mathbf{A}_{12} \\ \mathbf{A}_{21} & \mathbf{A}_{22} \end{pmatrix}$$

$$\mathbf{AB} = \begin{pmatrix} \mathbf{A}_{11} & \mathbf{A}_{12} \\ \mathbf{A}_{21} & \mathbf{A}_{22} \end{pmatrix} \begin{pmatrix} \mathbf{B}_{11} & \mathbf{B}_{12} \\ \mathbf{B}_{21} & \mathbf{B}_{22} \end{pmatrix}$$

- ▶ A square matrix \mathbf{A} is **positive (semi-positive) definitive** if $\mathbf{x}'\mathbf{A}\mathbf{x} > 0 (\geq 0)$ for any $\mathbf{x} \neq 0$.
e.g. If $\mathbf{A} = \mathbf{B}'\mathbf{B}$, \mathbf{A} is (semi -) positive definite.
- ▶ **eigenvalue** and **eigenvector**: for a square matrix \mathbf{A} , if there are λ and nonzero \mathbf{x} such that $\mathbf{Ax} = \lambda\mathbf{x}$, λ and \mathbf{x} are \mathbf{A} 's eigenvalue and eigenvector, respectively.
 - ▶ If $\lambda_1, \dots, \lambda_k$ are all the eigenvalues of $\mathbf{A}_{k \times k}$, $tr(\mathbf{A}) = \sum_{j=1}^k \lambda_j$ and $det(\mathbf{A}) = \prod_{j=1}^k \lambda_j$.
 - ▶ $\mathbf{A}_{k \times k}$ is positive definite (semi-positive definite) iff all its eigenvalues are positive (non-negative).

Recall

I.2.1. Why do we need matrix/vector algebra in STAT445/645?

For example, consider

$$Y = \beta_0 + \beta X + \epsilon, \quad E(\epsilon) = 0, \quad V(\epsilon) = \sigma^2$$

with observations $\{(x_1, y_1), \dots, (x_n, y_n)\}$ from n independent units. That is, for $i = 1, \dots, n$,

$$y_i = \beta_0 + \beta x_i + \epsilon_i, \quad E(\epsilon_i) = 0, \quad V(\epsilon_i) = \sigma^2$$

with $\epsilon_1, \dots, \epsilon_n$ indpt.

- ▶ LSE: $\hat{\beta} = \frac{S_{XY}}{S_{XX}} = \frac{\sum_{i=1}^n (x_i - \bar{x})(y_i - \bar{y})}{\sum_{i=1}^n (x_i - \bar{x})^2}; \quad \hat{\beta}_0 = \bar{y} - \hat{\beta}\bar{x}.$
- ▶ $V(\hat{\beta}) = \sigma^2 / S_{XX}$ and $V(\hat{\beta}_0) = \sigma^2 \left[\frac{1}{n} + \frac{\bar{x}^2}{S_{XX}} \right];$
- ▶ $\hat{\sigma}^2 = \frac{1}{n-2} \sum_{i=1}^n (y_i - \hat{y}_i)^2$ with $e_i = y_i - \hat{y}_i = y_i - [\hat{\beta}_0 + \hat{\beta}x_i].$

What if to consider

$$Y = \beta_0 + \beta_1 X_1 + \dots + \beta_p X_p + \epsilon, \quad E(\epsilon) = 0, \quad V(\epsilon) = \sigma^2$$

with observations $\{(x_{11}, \dots, x_{p1}, y_1), \dots, (x_{1n}, \dots, x_{pn}, y_n)\}$ from n independent units?

What if to study how (Y_1, \dots, Y_k) depends on (X_1, \dots, X_p) ?

⇒ **vector/matrix algebra** as a tool for communication in general, together with software packages such as R and SAS to conduct the required computing.

Multiple linear regression model. $Y = \beta' \mathbf{x} + \epsilon$ with
 $E(\epsilon) = 0$, $V(\epsilon) = \sigma^2$, where

$$\beta = \begin{pmatrix} \beta_0 \\ \beta_1 \\ \vdots \\ \beta_p \end{pmatrix}, \quad \mathbf{x} = \begin{pmatrix} 1 \\ x_1 \\ \vdots \\ x_p \end{pmatrix}.$$

with observations $\{(x_{11}, \dots, x_{p1}, y_1), \dots, (x_{1n}, \dots, x_{pn}, y_n)\}$ from independent units $i = 1, \dots, n$, $\mathbf{y} = \mathbf{X}' \beta + \epsilon$, where

$$\mathbf{y} = \begin{pmatrix} y_1 \\ \vdots \\ y_n \end{pmatrix}, \quad \mathbf{X} = \begin{pmatrix} 1 & 1 & \dots & 1 \\ x_{11} & x_{12} & \dots & x_{1n} \\ \vdots & \vdots & \dots & \vdots \\ x_{p1} & x_{p2} & \dots & x_{pn} \end{pmatrix}, \quad \epsilon = \begin{pmatrix} \epsilon_1 \\ \vdots \\ \epsilon_n \end{pmatrix}$$

with $E(\epsilon) = \mathbf{0}$ and $V(\epsilon) = \sigma^2 \mathbf{I}$.

► LSE for $\hat{\beta} = (\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\mathbf{y}$.

► $V(\hat{\beta}) = \sigma^2(\mathbf{X}'\mathbf{X})^{-1}$

► $\hat{\sigma}^2 = \frac{1}{n-(p+1)}\mathbf{e}'\mathbf{e}$ with

$$\mathbf{e} = \begin{pmatrix} e_1 \\ \vdots \\ e_n \end{pmatrix} = \begin{pmatrix} y_1 - \hat{y}_1 \\ \vdots \\ y_n - \hat{y}_n \end{pmatrix} = \mathbf{y} - \hat{\mathbf{y}} = \mathbf{y} - \mathbf{X}'\hat{\beta}$$

as $e_i = y_i - \hat{y}_i = y_i - \hat{\beta}' \mathbf{x}_i$ for $i = 1, \dots, n$.

Part I.3. Introduction to R

Part I.4.1 Random Vectors and Matrices (Chp 2.5)

Review on (univariate) random variable:

- ▶ **random variable.** $X : \mathcal{S} \longrightarrow \mathcal{R}$
- ▶ **distribution.** The cumulative distribution function (cdf) of X :
 $F(x) = P(X \leq x)$
 - ▶ If X is discrete and all its possible values are a_1, a_2, \dots ,
 $F(x) = \sum_{a_j \leq x} p(a_j)$ with its probability mass function (pmf)
 $p(x) = P(X = x)$ for $x = a_1, a_2, \dots$
 - ▶ If X is continuous, $F(x) = \int_{-\infty}^x f(u)du$ with its probability density function (pdf) $f(x)$ for $-\infty < x < \infty$.
- ▶ Examples
 - ▶ e.g. “tossing a coin”: $\mathcal{S} = \{H, T\}$; $X = 1/0$ if getting H/T .
 - ▶ e.g. “waiting time for a bus”: X with $0 < X < a$.

The commonly-used (univariate) distributions, discrete/continuous?

Part I.4.1 Random Vectors and Matrices (Chp 2.5)

- ▶ random vector (multivariate random variable).

$$\mathbf{X} = \begin{pmatrix} X_1 \\ X_2 \\ \vdots \\ X_p \end{pmatrix} = (X_1, X_2, \dots, X_p)'$$

is a p-dim random vector if X_1, \dots, X_p are r.v.s.

- ▶ **distribution.** The cdf of \mathbf{X} is the joint cumulative distribution function (joint cdf) of X_1, \dots, X_p : for $\mathbf{x} = (x_1, x_2, \dots, x_p)'$,

$$F(\mathbf{x}) = P(\mathbf{X} \leq \mathbf{x}) = P(X_1 \leq x_1, \dots, X_p \leq x_p).$$

- ▶ Iff X_1, \dots, X_p are mutually independent from each other,

$$F(\mathbf{x}) = P(X_1 \leq x_1) \dots P(X_p \leq x_p) = \prod_{j=1}^p F_{X_j}(x_j),$$

the product of X_1, \dots, X_p 's (*marginal*) cdfs.

Part I.4.1 Random Vectors and Matrices (Chp 2.5)

Examples

- ▶ e.g. “tossing a coin twice”:

$\mathcal{S} = \{(H, H), (H, T), (T, H), (T, T)\}$; $X_1 = 1$ or 0 if the 1st toss gets H or T and $X_2 = 1$ or 0 if the 2nd toss gets H or T .

- ▶ distribution?

- ▶ e.g. “three housemates’ waiting time for a bus”:

$\mathbf{X} = (X_1, X_2, X_3)'$ with $0 < X_j < a_j$.

- ▶ distribution?

Part I.4.1 Random Vectors and Matrices (Chp 2.5)

Example of Multivariate Data. Consider variables X_1 =tumor stage, X_2 =age, X_3 =sex, X_4 =blood pressure, ... in a study. Suppose the study has n subjects with $\mathbf{X}_1, \dots, \mathbf{X}_n$ their observations on the p -dim r.v. $\mathbf{X} = (X_1, \dots, X_p)'$.

$$\begin{pmatrix} X_{11} & X_{12} & \dots & X_{1p} \\ X_{21} & X_{22} & \dots & X_{2p} \\ \vdots & \vdots & \dots & \vdots \\ X_{n1} & X_{n2} & \dots & X_{np} \end{pmatrix} = \begin{pmatrix} \mathbf{X}'_1 \\ \mathbf{X}'_2 \\ \vdots \\ \mathbf{X}'_n \end{pmatrix}$$

is a $n \times p$ **random matrix**.

- ▶ Often assume the n observations *independent and identically distributed* (iid).

That is, $\mathbf{X}_1, \dots, \mathbf{X}_n$ form a *random sample of size n* from the population.

Part I.4.2 Mean Vectors and Covariance Matrices (Chp 2.6)

Review on (univariate) random variable:

- ▶ **expectation (population mean).** r.v. X 's expectation, denoted by $E(X)$.
 - ▶ If X is discrete and all its possible values are a_1, a_2, \dots with its probability mass function (pmf) $p(x) = P(X = x)$ for $x = a_1, a_2, \dots$,

$$E(X) = \sum_{\text{all } a_j} a_j p(a_j) = a_1 p(a_1) + a_2 p(a_2) + \dots$$

- ▶ If X is continuous with its probability density function (pdf) $f(x)$ for $-\infty < x < \infty$,

$$E(X) = \int_{-\infty}^{\infty} xf(x)dx.$$

- ▶ **(population) variance.** r.v. X 's variance, denoted by $V(X)$, is $E[X - E(X)]^2 = E(X^2) - (EX)^2$.

► **Examples.**

- e.g. “tossing a coin”: $\mathcal{S} = \{H, T\}$; $X = 1/0$ if getting H/T : $E(X) = 1/2$ and $V(X) = 1/4$ for an even coin.
- e.g. “waiting time for a bus”: X with $0 < X < a$: $E(X) = a/2$ and $V(X) = a^2/12$ for $X \sim U(0, a)$.
- **covariance.** Two r.v.. X and Y 's covariance is
$$\text{Cov}(X, Y) = E[X - E(X)][Y - E(Y)] = E(XY) - (EX)(EY).$$
 - If X and Y are indpt, $\text{Cov}(X, Y) = 0$.
 - If $\text{Cov}(X, Y) = 0$, are X and Y indpt?
 - **(population) correlation coefficient.**

$$\text{corr}(X, Y) = \text{Cov}(X, Y) / \sqrt{V(X)V(Y)}$$

Part I.4.2 Mean Vectors and Covariance Matrices (Chp 2.6)

- expectation (**population mean**). p -dim random vector \mathbf{X} 's expectation:

$$E(\mathbf{X}) = \begin{pmatrix} E(X_1) \\ E(X_2) \\ \vdots \\ E(X_p) \end{pmatrix},$$

denoted by $\mu = (\mu_1, \dots, \mu_p)'$.

- (**population**) variance. p -dim r.v. \mathbf{X} 's variance:

$$V(\mathbf{X}) = E[\mathbf{X} - E(\mathbf{X})][\mathbf{X} - E(\mathbf{X})]' = E(\mathbf{X}\mathbf{X}') - (E\mathbf{X})(E\mathbf{X})',$$

denoted by

$$\Sigma = E[\mathbf{X} - E(\mathbf{X})][\mathbf{X} - E(\mathbf{X})]' = \begin{pmatrix} \sigma_{11} & \sigma_{12} & \dots & \sigma_{1p} \\ \sigma_{21} & \sigma_{22} & \dots & \sigma_{2p} \\ \vdots & \vdots & \dots & \vdots \\ \sigma_{p1} & \sigma_{p2} & \dots & \sigma_{pp} \end{pmatrix} = (\sigma_{ij})$$

with $\sigma_{ij} = \sigma_{ji} = \text{Cov}(X_i, X_j)$.

Part I.4.2 Mean Vectors and Covariance Matrices (Chp 2.6)

Remarks on Σ .

- ▶ symmetric, (semi-)positive definite and thus invertible.
- ▶ the mean of the *outer product* of the *centered* random vector and itself.
- ▶ If X_1, \dots, X_p are indpt, $\Sigma = \text{diag}(\sigma_{11}, \dots, \sigma_{pp})$. How about vice versa?

population correlation matrix. A standardized variance-covariance matrix:

$$\rho = \begin{pmatrix} 1 & \rho_{12} & \dots & \rho_{1p} \\ \rho_{21} & 1 & \dots & \rho_{2p} \\ \vdots & \vdots & \dots & \vdots \\ \rho_{p1} & \rho_{p2} & \dots & 1 \end{pmatrix} = (\rho_{ij})$$

with $\rho_{ij} = \text{corr}(X_i, X_j)$.

- ▶ symmetric, positive definite and thus invertible.
- ▶ If X_1, \dots, X_p are indpt, $\rho = \mathbf{I}$. How about vice versa?

$$\mathbf{V} = \begin{pmatrix} \sigma_{11} & 0 & \dots & 0 \\ 0 & \sigma_{22} & \dots & 0 \\ \vdots & \vdots & \dots & \vdots \\ 0 & 0 & \dots & \sigma_{pp} \end{pmatrix} = diag(\sigma_{11}, \dots, \sigma_{pp}),$$

$$\mathbf{V}^{1/2} = diag(\sqrt{\sigma_{11}}, \dots, \sqrt{\sigma_{pp}}), \quad \mathbf{V}^{-1/2} = diag\left(\frac{1}{\sqrt{\sigma_{11}}}, \dots, \frac{1}{\sqrt{\sigma_{pp}}}\right).$$

$$\boldsymbol{\rho} = \mathbf{V}^{-1/2} \boldsymbol{\Sigma} \mathbf{V}^{-1/2}, \quad \boldsymbol{\Sigma} = \mathbf{V}^{1/2} \boldsymbol{\rho} \mathbf{V}^{1/2}$$

$$\rho_{ij} = \sigma_{ij} / \sqrt{\sigma_{ii}} / \sqrt{\sigma_{jj}}.$$

Example. “three housemates’ waiting time for a bus”: $\mathbf{X} = (X_1, X_2, X_3)'$ with X_1, X_2, X_3 indpt and following $U(0, a_1)$, $U(0, a_2)$, $U(0, a_3)$.

- ▶ $\mu = E(\mathbf{X}) = (a_1/2, a_2/2, a_3/2)'.$
- ▶ $V(\mathbf{X}) = diag(a_1^2, a_2^2, a_3^2)/12.$

What will we study in the next class?

- ▶ **Part I. Introduction and Preparation**
 - ▶ *I.1. General Introduction*
 - ▶ *I.2. Review on Matrix Algebra*
 - ▶ *I.3. Introduction to R*
 - ▶ **I.4. Multivariate Random Variables and Distributions
(Chp 1, 2.5-6, 3)**
 - ▶ *I.4.1 Random Vectors and Matrices (Chp 2.5)*
 - ▶ *I.4.2 Mean Vectors and Covariance Matrices (Chp 2.6)*
 - ▶ **I.4.3 Descriptive Multivariate Analysis (Chp 1)**