

HW3

1. Use the Lagrange interpolating polynomials of degree one, two, three and four to approximate $\cos(0.750) = 0.7317$ if $\cos(0.698) = 0.7661$,

$$\cos(0.733) = 0.7432, \cos(0.768) = 0.7193, \cos(0.803) = 0.6946.$$

Find the error bound.

2. Use iterated inverse interpolation to find an approximation to the solution $x - e^{-x} = 0$ using the data $e^{-0.3} = 0.740818$, $e^{-0.4} = 0.670320$, $e^{-0.5} = 0.606531$, $e^{-0.6} = 0.548812$.

3. A car travelling along a straight road is clocked at a number of points. The data from the observations are given in the following table, where the time T is in seconds, the distance D is in feet, and the speed V is in feet per second.

T	0	3	5	8	13
D	0	200	375	620	990
V	75	77	80	74	72

- Use a Hermite polynomial to predict the position of the car and its speed when $t = 10$ s.
- Use the derivative of the Hermite polynomial to determine whether the car ever exceeds a 55 mi/h speed limit on the road. If so, what is the first time the car exceeds this speed?
- What is the predicted maximum speed for the car ?

1. Use the Lagrange interpolating polynomials of degree one, two, three and four to approximate $\cos(0.750) = 0.7317$ if $\cos(0.698) = 0.7661$, $\cos(0.733) = 0.7432$, $\cos(0.768) = 0.7193$, $\cos(0.803) = 0.6946$.

Find the error bound.

```
PS C:\Users\afatf\Desktop\E94116067_numerical_hw3>
● Order 1: 0.76610000 , Error Bound: 0.03500000
Order 2: 0.73207714 , Error Bound: 0.00122500
Order 3: 0.73171633 , Error Bound: 0.00004287
Order 4: 0.73170396 , Error Bound: 0.00000150
○ PS C:\Users\afatf\Desktop\E94116067_numerical_hw3>
```

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```
PS C:\Users\afatf\Desktop\E94116067_numerical_hw3>
● x: 0.56714309
○ PS C:\Users\afatf\Desktop\E94116067_numerical_hw3>
```

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```
PS C:\Users\afatf\Desktop\E94116067_numerical_hw3>
● a: 762.019231 ft
  b: No, time: -20.614540 s
  c: 80.027817 ft/s
○ PS C:\Users\afatf\Desktop\E94116067_numerical_hw3>
```