BEACON AGGREGATION Objective function EvoCom2 Gianduja2E Gianduja3 Gianduja2 ${\tt EvoCom3}$ ${\tt Gianduja3E}$ BEACON DECISION Objective function 10000 15000Gianduja2E EvoCom2 Gianduja3 Gianduja2 EvoCom3 Gianduja3E BEACON STOP Objective function Ē 16000EvoCom2 Gianduja2E Gianduja3 Gianduja2 Gianduja3E EvoCom3

Figure 1: Thick gray boxes represent the results of robot experiments; Thick white boxes those of pseudo-reality; thip gray ones, those of simulations.

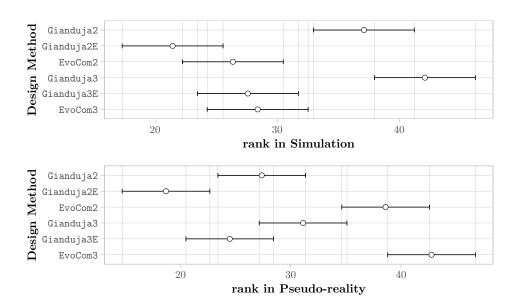


Figure 2: Thick gray boxes represent the results of robot experiments; Thick white boxes those of pseudo-reality; thin gray ones, those of simulations.