

Pl. C

$$E_{\text{aug}}(w) = E_{\text{in}}(w) + \frac{\lambda}{N} w^T w$$

微分

$$\Rightarrow \nabla E_{\text{aug}}(w) = \nabla E_{\text{in}}(w) + \frac{2\lambda}{N} w \quad \text{代入 update rule 得}$$

$$w(t+1) \leftarrow w(t) - \eta \left[ \nabla E_{\text{in}}(w(t)) + \frac{2\lambda}{N} \cdot w(t) \right]$$

$$\Rightarrow w(t+1) \leftarrow \underbrace{\left[ 1 - \frac{2\lambda\eta}{N} \right]}_{\#}^S w(t) - \eta \nabla E(w(t))$$

故选 C

P2.B By Silde 27. P29

$$\nabla E_{in}(W_{REG}) + \frac{2\lambda}{N}(W_{REG}) = 0$$

$$\Rightarrow \frac{2}{N} \sum_{n=1}^N (w - y_n) + \frac{2\lambda}{N} w = 0$$

$$\Rightarrow \frac{2}{N} (NW - \sum_{n=1}^N y_n) + \frac{2\lambda}{N} w = 0$$

$$\Rightarrow NW - \sum_{n=1}^N y_n + \lambda w = 0$$

$$\Rightarrow w(N+\lambda) = \sum_{n=1}^N y_n$$

$$\Rightarrow w = \frac{\sum_{n=1}^N y_n}{N+\lambda}$$

$$\begin{aligned} C &= (w^*)^2 \\ &= \left( \frac{\sum_{n=1}^N y_n}{N+\lambda} \right)^2 \end{aligned}$$

# 选 B

P3.D 若  $W$  与  $W^T$  存在线性关系，则 2 式子仍能维持等价关系。

令  $W = V \cdot \tilde{W}$ , 代入下式

$$\min_{W \in R^{d+1}} \frac{1}{N} \sum_{n=1}^N (W^T x_n - y_n)^2 + \frac{\lambda}{N} (W^T U W)$$

$$\Rightarrow \min_{W \in R^{d+1}} \frac{1}{N} \sum_{n=1}^N (\tilde{W}^T V^T x_n - y_n)^2 + \frac{\lambda}{N} (\tilde{W}^T V^T U V \tilde{W}) \dots \textcircled{1}$$

$$\min_{W \in R^{d+1}} \frac{1}{N} \sum_{n=1}^N (\tilde{W}^T V x_n - y_n)^2 + \frac{\lambda}{N} (\tilde{W}^T \tilde{W}) \quad (\text{V}^T = V, \because V \text{ 是对角矩阵}) \dots \textcircled{2}$$

比较①② 2 式可知，当  $V^T U V = I$  时，2 式相等

因此  $U = (V^{-1})^2$  #

P4.C

$$\min_{w \in \mathbb{R}^{d+1}} E \left[ \frac{1}{N} \sum_{n=1}^N (w^\top \Phi(x_n) - y_n)^2 \right] \dots \text{上式}$$

用 matrix 代換上式  $\tilde{X} = \begin{bmatrix} -\Phi(x_1)^\top \\ -\Phi(x_2)^\top \\ \vdots \\ -\Phi(x_n)^\top \end{bmatrix}, Y = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix}$

$$\min_{w \in \mathbb{R}^{d+1}} E \left[ \frac{1}{N} (\tilde{X} w - Y)^2 \right]$$

對  $w$  偏微

$$E \left[ \frac{2}{N} \tilde{X}^\top (\tilde{X} w - Y) \right] = 0$$

$$\Rightarrow E[\tilde{X} \tilde{X}^\top w] = E[\tilde{X}^\top Y]$$

代入:  $\tilde{X} = \begin{bmatrix} -\Phi(x_1)^\top \\ -\Phi(x_2)^\top \\ \vdots \\ -\Phi(x_n)^\top \end{bmatrix} = \begin{bmatrix} x_1^\top \\ x_2^\top \\ \vdots \\ x_n^\top \end{bmatrix} + \begin{bmatrix} \varepsilon_1 \\ \varepsilon_2 \\ \vdots \\ \varepsilon_n \end{bmatrix} = X + \varepsilon$

$$\Rightarrow E[(X + \varepsilon)^\top (X + \varepsilon) w] = E[(X + \varepsilon)^\top Y]$$

$$\Rightarrow E[(X^\top X + 2X^\top \varepsilon + \varepsilon^\top \varepsilon) w] = E[X^\top Y + \varepsilon^\top Y]$$

$E(\varepsilon) = 0$   
 $\downarrow E(\varepsilon^\top \varepsilon) = \sigma^2 I$

$$\Rightarrow X^\top X w + O + \sigma^2 w = X^\top Y + O$$

$$\Rightarrow (X^\top X + \sigma^2 I) w = X^\top Y$$

$$\Rightarrow \underline{w = (X^\top X + \sigma^2 I)^{-1} X^\top Y}$$

$$\text{下式: } \min_{w \in \mathbb{R}^{d+1}} \frac{1}{N} \sum_{n=1}^N (w^T x_n - y_n)^2 + \frac{\lambda}{N} \|w\|_2^2$$

用前頁一樣的方式換成 matrix form

$$\min_{w \in \mathbb{R}^{d+1}} \frac{1}{N} (Xw - Y)^T + \frac{\lambda}{N} (w^T w)$$

(對  $w$  偏微分  
↓

$$\frac{2}{N} X^T (Xw - Y) + \frac{2\lambda}{N} w = 0$$

$$\Rightarrow \frac{2}{N} X^T X w - \frac{2}{N} X^T Y + \frac{2\lambda}{N} w = 0$$

$$\Rightarrow (X^T X + \frac{2\lambda}{N} I) w = X^T Y$$

代入  $w$

$$\Rightarrow (X^T X + \frac{2\lambda}{N} I) (X^T X + \tilde{\sigma}^2 I)^{-1} X^T Y = X^T Y$$

上述等式要成立必須滿足

$$\tilde{\sigma}^2 = \frac{2\lambda}{N}$$

$$\Rightarrow \lambda = \frac{N\tilde{\sigma}^2}{2} \# \quad \text{故选 } C$$

P5.D

$$\min_{y \in \mathbb{R}} \frac{1}{N} \sum_{n=1}^N (y - y_n)^2 + \frac{\alpha K}{N} \Omega(y)$$

↓ 对  $y$  微分 = 0

$$\frac{1}{N} \sum_{n=1}^N 2(y - y_n) + \frac{\alpha K}{N} \cdot \frac{d}{dy} \Omega(y) = 0$$

$$\Rightarrow \frac{2}{N} \left( Ny - \sum_{n=1}^N y_n \right) + \frac{\alpha K}{N} \cdot \frac{d}{dy} \Omega(y) = 0$$

$$\Rightarrow 2Ny - 2 \sum_{n=1}^N y_n + \alpha K \frac{d}{dy} \Omega(y) = 0$$

代入  $y^* = \frac{\sum_{n=1}^N y_n + \alpha}{N + \alpha K}$ , 進入上式 等號會成立

$$\Rightarrow 2N \frac{\sum_{n=1}^N y_n + \alpha}{N + \alpha K} - 2 \sum_{n=1}^N y_n + \alpha K \frac{d}{dy} \Omega(y^*) = 0$$

$$\begin{aligned} \Rightarrow \frac{d}{dy} \Omega(y^*) &= \frac{1}{\alpha K} \cdot \frac{-2N \left( \sum_{n=1}^N y_n + \alpha \right) + 2(N + \alpha K) \sum_{n=1}^N y_n}{N + \alpha K} \\ &= \frac{-2N \sum_{n=1}^N y_n - 2N\alpha + 2N \sum_{n=1}^N y_n + 2\alpha K \sum_{n=1}^N y_n}{(N + \alpha K)(\alpha K)} \\ &= \frac{-\frac{2N}{K} + 2 \sum_{n=1}^N y_n}{N + \alpha K} \\ &= \frac{\frac{2 \sum_{n=1}^N y_n}{N + \alpha K}}{N + \alpha K} + \frac{-\frac{2N}{K(N + \alpha K)}}{N + \alpha K} + \frac{\frac{2\alpha}{N + \alpha K}}{N + \alpha K} - \frac{\frac{2\alpha}{N + \alpha K}}{N + \alpha K} \end{aligned}$$

$$= 2 \cdot \underbrace{\left( \frac{\sum_{n=1}^N y_n + \alpha}{N + \alpha K} \right)}_{y^*} - 2 \cdot \underbrace{\frac{N + \alpha K}{(N + \alpha K)K}}_{\cancel{(N + \alpha K)K}}$$

$$= 2 \cdot y^* - 2 \cdot \frac{1}{K}$$

$$\Rightarrow \frac{d}{dy} \Omega(y^*) = 2(y^* - \frac{1}{K}) \xrightarrow{\text{積分}} \Omega(y) = \underline{(y - \frac{1}{K})^2} \# \text{達 D}$$

P6.B

$$\nabla \tilde{E}_{\text{aug}}(w) \Rightarrow \nabla \left( \tilde{E}_{\text{in}}(w) + \frac{\lambda}{N} \|w\|^2 \right) = 0$$

$$\Rightarrow \nabla \tilde{E}_{\text{in}}(w) + \frac{\lambda}{N} \frac{\partial}{\partial w} \|w\|^2 = 0$$

$$\Rightarrow \underline{\frac{\partial}{\partial w} (E_{\text{in}}(w^*) + \frac{1}{2} (w - w^*)^T H (w - w^*))} + \frac{\lambda}{N} \frac{\partial}{\partial w} \|w\|^2 = 0$$

$$\Rightarrow \frac{1}{2} [H(w - w^*) + H(w - w^*)] + \frac{\lambda}{N} \frac{\partial}{\partial w} (w^T w) = 0$$

$$\Rightarrow H(w - w^*) + \frac{2\lambda}{N} w = 0$$

$$\Rightarrow Hw - HW^* + \frac{2\lambda}{N} w = 0$$

$$\Rightarrow \left( H + \frac{2\lambda}{N} I \right) w = HW^*$$

$$\Rightarrow \underline{w = \left( H + \frac{2\lambda}{N} I \right)^{-1} HW^*}$$

P7.A 每次都会 predict minority, 而每次 validation set 刚好都是 minority.

$$E_{100cv}(\text{Algorithm}) = \frac{1}{2N} [N \cdot 0 + N \cdot 0] = 0_{\#}$$

P8.C

train: $(x_1, y_1) = (2, 0)$ $(x_2, y_2) = (\rho, -2)$	test $(x_3, y_3) = (-2, 0)$	constant hypothesis $\hat{h}(x) = 1$ $E_{\text{Squ}} = (1-0)^2 = 1$	linear hypothesis $\hat{h}(x) = \frac{2}{\rho-2}x + \frac{-4}{\rho-2}$ $E_{\text{Squ}} = \underline{\underline{(\frac{-8}{\rho-2}-0)^2}}$
train: $(x_1, y_1) = (2, 0)$ $(x_3, y_3) = (-2, 0)$	test $(x_2, y_2) = (\rho, -2)$	$\hat{h}(x) = 0$ $E_{\text{Squ}} = (2-0)^2 = 4$	$\hat{h}(x) = 0$ $E_{\text{Squ}} = (2-0)^2 = 4$
train: $(x_2, y_2) = (\rho, -2)$ $(x_3, y_3) = (-2, 0)$	test $(x_1, y_1) = (2, 0)$	$\hat{h}(x) = 1$ $E_{\text{Squ}} = (1-0)^2 = 1$	$\hat{h}(x) = \frac{2}{\rho+2}x + \frac{4}{\rho+2}$ $E_{\text{Squ}} = \underline{\underline{(\frac{8}{\rho+2}-0)^2}}$

$$\frac{64}{(\rho-2)^2} + \frac{64}{(\rho+2)^2} = 2$$

$$\Rightarrow \underline{\underline{\rho \pm 8.6713}}$$

P9. B

$$E\left(\frac{1}{K} \sum_{n=N-K+1}^N (y_n - \bar{y})^2\right)$$

$$\Rightarrow E\left(\frac{1}{K} \sum_{n=N-K+1}^N (y_n^2 - 2y_n \bar{y} + \bar{y}^2)\right)$$

$y_1, \dots, y_N$  是 i.i.d sample 得來

$$\Rightarrow \frac{1}{K} \sum_{n=N-K+1}^N (E(y_n^2) - 2E(y_n \bar{y}) + E(\bar{y}^2))$$

$$\Rightarrow \frac{1}{K} \sum_{n=N-K+1}^N \left( \sigma^2 - 2E(y_n \cdot \frac{\sum_{n=1}^{N-K} y_n}{N-K}) + E\left(\frac{\sum_{n=1}^{N-K} y_n}{N-K} \cdot \frac{\sum_{n=1}^{N-K} y_n}{N-K}\right) \right)$$

$$\Rightarrow \frac{1}{K} \sum_{n=N-K+1}^N \left[ \sigma^2 - \frac{2}{N-K} E(y_n \cdot \underbrace{\sum_{n=1}^{N-K} y_n}_{\downarrow \text{i.i.d.}}) + \frac{1}{(N-K)^2} \cdot E\left(\left(\sum_{n=1}^{N-K} y_n\right)^2\right) \right]$$

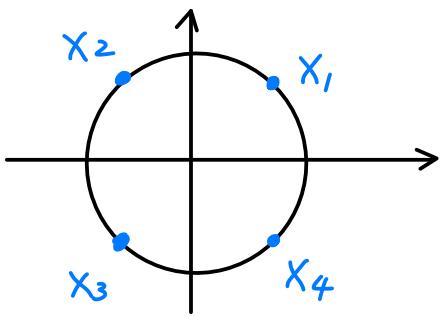
$$\Rightarrow \frac{1}{K} \sum_{n=N-K+1}^N \left[ \sigma^2 - \frac{2}{N-K} \underbrace{E(y_n) \cdot E\left(\sum_{n=1}^{N-K} y_n\right)}_{\text{"0}} + \frac{1}{(N-K)^2} \cdot \left[ \frac{\text{Var}\left(\sum_{n=1}^{N-K} y_n\right) + E\left(\left(\sum_{n=1}^{N-K} y_n\right)^2\right)}{(N-K)\sigma^2} \right] \right]$$

$$\Rightarrow \frac{1}{K} \sum_{n=N-K+1}^N \left[ \sigma^2 + \frac{(N-K)\sigma^2}{(N-K)^2} \right]$$

$$\Rightarrow \underbrace{\sigma^2 + \frac{\sigma^2}{(N-K)}}_{\#}$$

P10\_A

$y_1$	$y_2$	$y_3$	$y_4$	$E_{in}(\omega^*)\%$
+	+	+	+	0
+	+	+	-	0
+	+	-	+	0
+	-	+	+	0
-	+	+	+	0
+	+	-	-	0
+	-	+	-	$\frac{1}{4}$
-	+	+	-	0
+	-	-	+	0
-	+	-	+	$\frac{1}{4}$
-	-	+	+	0
-	-	-	+	0
-	-	+	-	0
-	+	-	-	0
+	-	-	-	0
-	-	-	-	0



$$\Rightarrow \frac{1}{16} \left( \frac{1}{4} + \frac{1}{4} \right) = \underline{\underline{\frac{1}{32}}}_{\#}$$

PII, B

$$E_{\text{out}}(g) = P \cdot E_+ + (1-P) E_- = E_{\text{out}}(g_-) = P$$

$$\Rightarrow P E_+ + E_- - P E_- = P$$

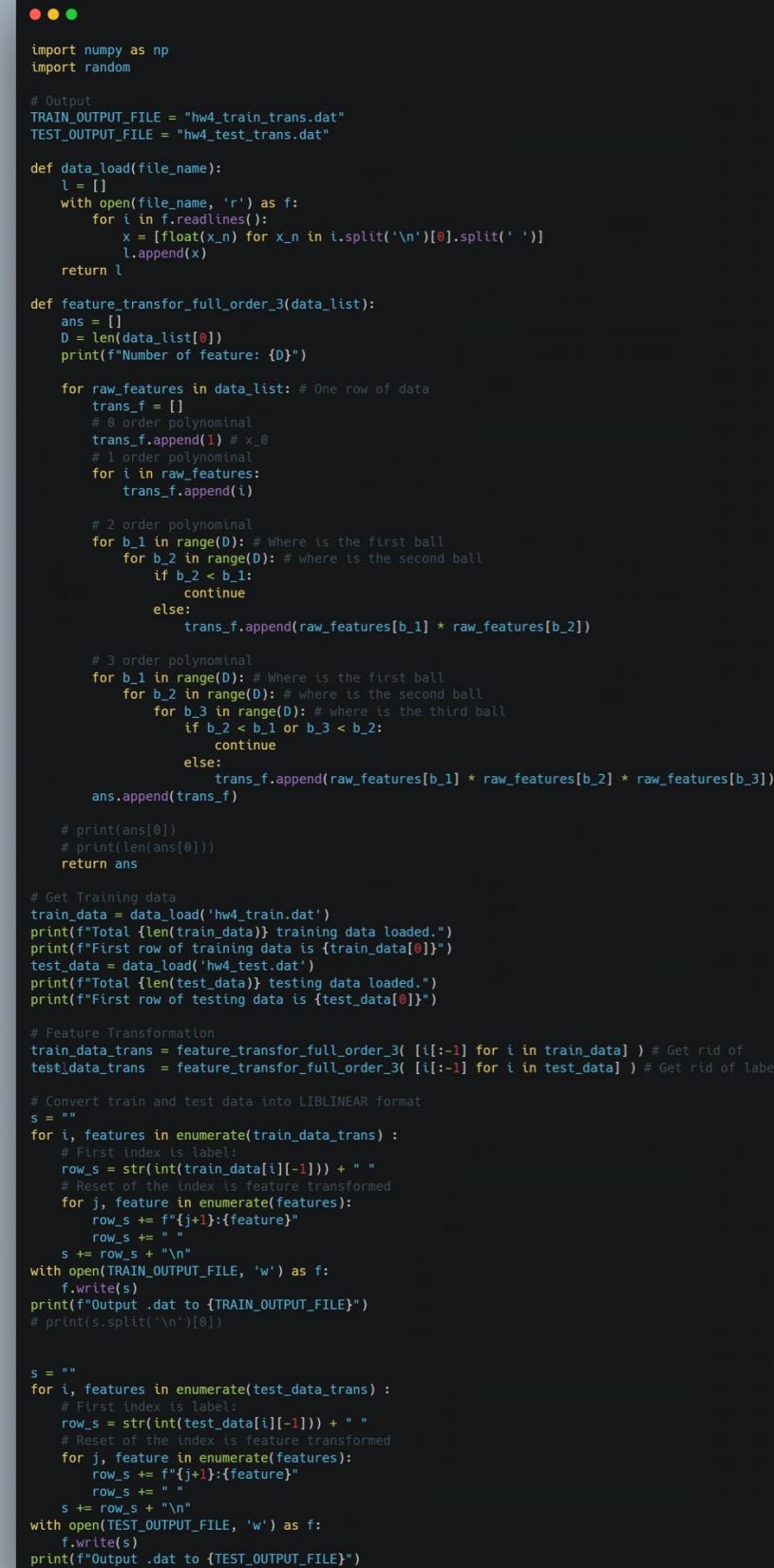
$$\Rightarrow E_+ + \frac{E_-}{P} - E_- = 1$$

$$\Rightarrow \frac{1}{P} = \frac{1 - E_+ + E_-}{E_-}$$

$$\Rightarrow P = \frac{E_-}{E_- - E_+ + 1} \#$$

# P12.B

```
1 TRAIN='hw4_test_trans.dat'
2 TEST='hw4_test_trans.dat'
3
4 ./train -q -s 0 -c 5000 -e 0.000001 ../$TRAIN; ./predict ../$TEST $TRAIN.model 123.csv
5 ./train -q -s 0 -c 50 -e 0.000001 ../$TRAIN; ./predict ../$TEST $TRAIN.model 123.csv
6 ./train -q -s 0 -c 0.5 -e 0.000001 ../$TRAIN; ./predict ../$TEST $TRAIN.model 123.csv
7 ./train -q -s 0 -c 0.005 -e 0.000001 ../$TRAIN; ./predict ../$TEST $TRAIN.model 123.csv
8 ./train -q -s 0 -c 0.00005 -e 0.000001 ../$TRAIN; ./predict ../$TEST $TRAIN.model 123.csv
```



```
import numpy as np
import random

# Output
TRAIN_OUTPUT_FILE = "hw4_train_trans.dat"
TEST_OUTPUT_FILE = "hw4_test_trans.dat"

def data_load(file_name):
    l = []
    with open(file_name, 'r') as f:
        for i in f.readlines():
            x = [float(x_n) for x_n in i.split('\n')[0].split(' ')]
            l.append(x)
    return l

def feature_transform_full_order_3(data_list):
    ans = []
    D = len(data_list[0])
    print(f"Number of feature: {D}")

    for raw_features in data_list: # One row of data
        trans_f = []
        # 0 order polynomial
        trans_f.append(1) # x_0
        # 1 order polynomial
        for i in raw_features:
            trans_f.append(i)

        # 2 order polynomial
        for b_1 in range(D): # Where is the first ball
            for b_2 in range(D): # where is the second ball
                if b_2 < b_1:
                    continue
                else:
                    trans_f.append(raw_features[b_1] * raw_features[b_2])

        # 3 order polynomial
        for b_1 in range(D): # Where is the first ball
            for b_2 in range(D): # where is the second ball
                for b_3 in range(D): # where is the third ball
                    if b_2 < b_1 or b_3 < b_2:
                        continue
                    else:
                        trans_f.append(raw_features[b_1] * raw_features[b_2] * raw_features[b_3])
        ans.append(trans_f)

    # print(ans[0])
    # print(len(ans[0]))
    return ans

# Get Training data
train_data = data_load('hw4_train.dat')
print(f"Total {len(train_data)} training data loaded.")
print(f"First row of training data is {train_data[0]}")
test_data = data_load('hw4_test.dat')
print(f"Total {len(test_data)} testing data loaded.")
print(f"First row of testing data is {test_data[0]}")

# Feature Transformation
train_data_trans = feature_transform_full_order_3( [i[:-1] for i in train_data] ) # Get rid of
test_data_trans = feature_transform_full_order_3( [i[:-1] for i in test_data] ) # Get rid of label

# Convert train and test data into LIBLINEAR format
s = ""
for i, features in enumerate(train_data_trans) :
    # First index is label:
    row_s = str(int(train_data[i][-1])) + " "
    # Reset of the index is feature transformed
    for j, feature in enumerate(features):
        row_s += f"{j+1}:{feature}"
        row_s += " "
    row_s += "\n"
    s += row_s + "\n"
with open(TRAIN_OUTPUT_FILE, 'w') as f:
    f.write(s)
print(f"Output .dat to {TRAIN_OUTPUT_FILE}")
# print(s.split('\n')[0])

s = ""
for i, features in enumerate(test_data_trans) :
    # First index is label:
    row_s = str(int(test_data[i][-1])) + " "
    # Reset of the index is feature transformed
    for j, feature in enumerate(features):
        row_s += f"{j+1}:{feature}"
        row_s += " "
    row_s += "\n"
    s += row_s + "\n"
with open(TEST_OUTPUT_FILE, 'w') as f:
    f.write(s)
print(f"Output .dat to {TEST_OUTPUT_FILE}")
```

P.13.B

```
1 TRAIN='hw4_train_trans.dat'
2 TEST='hw4_train_trans.dat'
3
4 ./train -q -s 0 -c 5000 -e 0.000001 ../$TRAIN; ./predict ../$TEST $TRAIN.model 123.csv
5 ./train -q -s 0 -c 50 -e 0.000001 ../$TRAIN; ./predict ../$TEST $TRAIN.model 123.csv
6 ./train -q -s 0 -c 0.5 -e 0.000001 ../$TRAIN; ./predict ../$TEST $TRAIN.model 123.csv
7 ./train -q -s 0 -c 0.005 -e 0.000001 ../$TRAIN; ./predict ../$TEST $TRAIN.model 123.csv
8 ./train -q -s 0 -c 0.00005 -e 0.000001 ../$TRAIN; ./predict ../$TEST $TRAIN.model 123.csv
```

P14.C

```
TRAIN='hw4_p14_train.dat'
TEST='hw4_p14_val.dat'

./train -q -s 0 -c 5000 -e 0.000001 ../$TRAIN; ./predict ../$TEST $TRAIN.model 123.csv
./train -q -s 0 -c 50 -e 0.000001 ../$TRAIN; ./predict ../$TEST $TRAIN.model 123.csv
./train -q -s 0 -c 0.5 -e 0.000001 ../$TRAIN; ./predict ../$TEST $TRAIN.model 123.csv
./train -q -s 0 -c 0.005 -e 0.000001 ../$TRAIN; ./predict ../$TEST $TRAIN.model 123.csv
./train -q -s 0 -c 0.00005 -e 0.000001 ../$TRAIN; ./predict ../$TEST $TRAIN.model 123.csv

# Test on real testing set
./train -q -s 0 -c 0.005 -e 0.000001 ../$TRAIN; ./predict ../$TEST $TRAIN.model 123.csv
./predict ..//hw4_test_trans.dat $TRAIN.model 123.csv
```

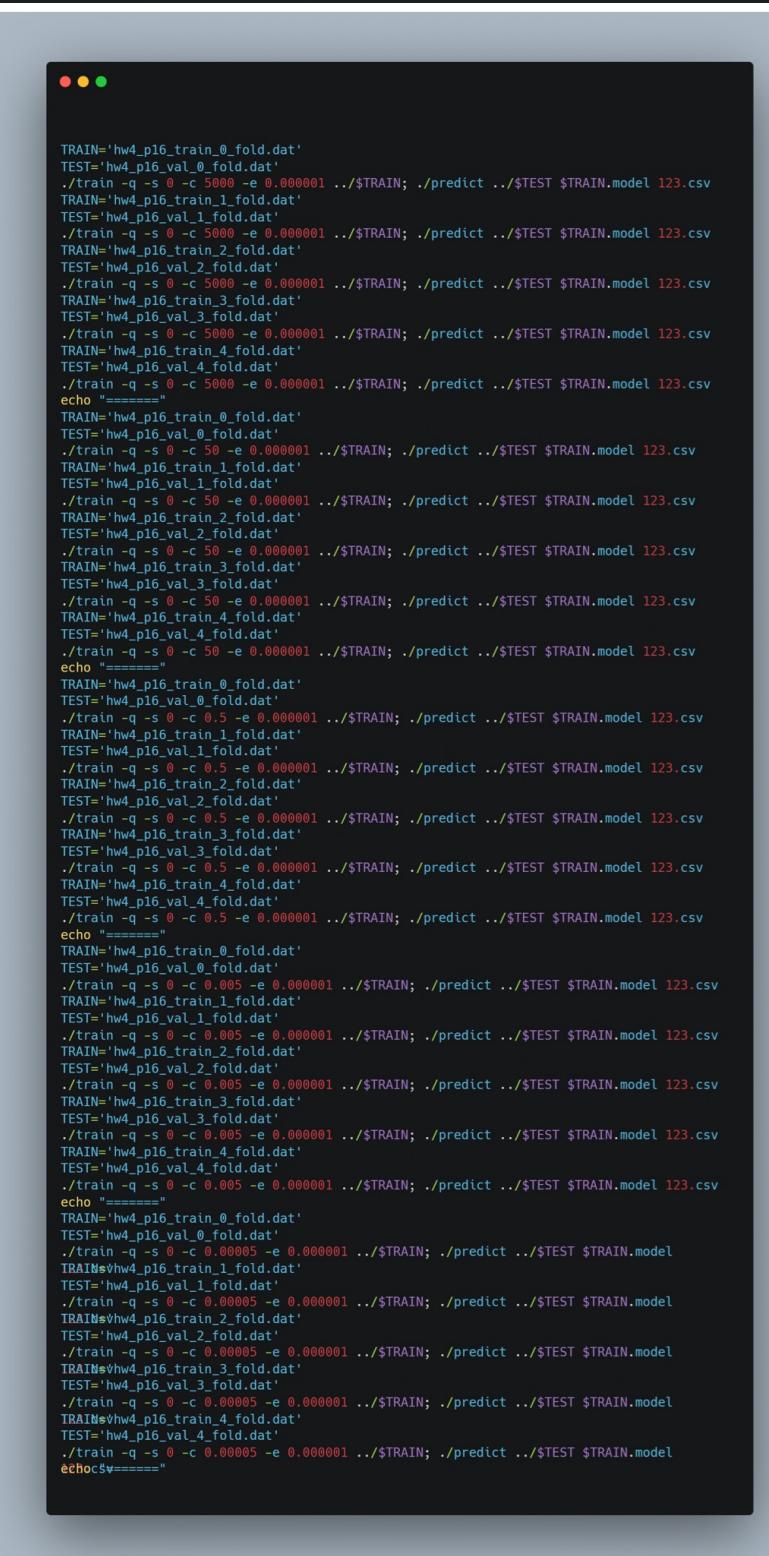
P15,D

```
1 TRAIN='hw4_train_trans.dat'
2 TEST='hw4_test_trans.dat'
3
4 # Test on real testing set
5 ./train -q -s 0 -c 0.005 -e 0.000001 ../$TRAIN; ./predict ../$TEST $TRAIN.model 123.csv\
```

P16, B

```
### P16
n_fold = 5
with open('hw4_train_trans.dat', 'r') as f:
    lines = f.readlines()
    for fold in range(n_fold):
        s_train = ""
        s_val = ""
        for i, line in enumerate(lines):
            if (i >= fold*40 and i < (fold+1)*40):
                s_val += line
            else:
                s_train += line
        print(len(s_train.split('\n')))
        print(len(s_val.split('\n')))

        with open(f'hw4_p16_train_{fold}_fold.dat', 'w') as f:
            f.write(s_train)
        with open(f'hw4_p16_val_{fold}_fold.dat', 'w') as f:
            f.write(s_val)
```



```
TRAIN='hw4_p16_train_0_fold.dat'
TEST='hw4_p16_val_0_fold.dat'
./train -q -s 0 -c 5000 -e 0.000001 ..$TRAIN; ./predict ..$TEST $TRAIN.model 123.csv
TRAIN='hw4_p16_train_1_fold.dat'
TEST='hw4_p16_val_1_fold.dat'
./train -q -s 0 -c 5000 -e 0.000001 ..$TRAIN; ./predict ..$TEST $TRAIN.model 123.csv
TRAIN='hw4_p16_train_2_fold.dat'
TEST='hw4_p16_val_2_fold.dat'
./train -q -s 0 -c 5000 -e 0.000001 ..$TRAIN; ./predict ..$TEST $TRAIN.model 123.csv
TRAIN='hw4_p16_train_3_fold.dat'
TEST='hw4_p16_val_3_fold.dat'
./train -q -s 0 -c 5000 -e 0.000001 ..$TRAIN; ./predict ..$TEST $TRAIN.model 123.csv
TRAIN='hw4_p16_train_4_fold.dat'
TEST='hw4_p16_val_4_fold.dat'
./train -q -s 0 -c 5000 -e 0.000001 ..$TRAIN; ./predict ..$TEST $TRAIN.model 123.csv
echo "====="
TRAIN='hw4_p16_train_0_fold.dat'
TEST='hw4_p16_val_0_fold.dat'
./train -q -s 0 -c 50 -e 0.000001 ..$TRAIN; ./predict ..$TEST $TRAIN.model 123.csv
TRAIN='hw4_p16_train_1_fold.dat'
TEST='hw4_p16_val_1_fold.dat'
./train -q -s 0 -c 50 -e 0.000001 ..$TRAIN; ./predict ..$TEST $TRAIN.model 123.csv
TRAIN='hw4_p16_train_2_fold.dat'
TEST='hw4_p16_val_2_fold.dat'
./train -q -s 0 -c 50 -e 0.000001 ..$TRAIN; ./predict ..$TEST $TRAIN.model 123.csv
TRAIN='hw4_p16_train_3_fold.dat'
TEST='hw4_p16_val_3_fold.dat'
./train -q -s 0 -c 50 -e 0.000001 ..$TRAIN; ./predict ..$TEST $TRAIN.model 123.csv
TRAIN='hw4_p16_train_4_fold.dat'
TEST='hw4_p16_val_4_fold.dat'
./train -q -s 0 -c 50 -e 0.000001 ..$TRAIN; ./predict ..$TEST $TRAIN.model 123.csv
echo "====="
TRAIN='hw4_p16_train_0_fold.dat'
TEST='hw4_p16_val_0_fold.dat'
./train -q -s 0 -c 0.5 -e 0.000001 ..$TRAIN; ./predict ..$TEST $TRAIN.model 123.csv
TRAIN='hw4_p16_train_1_fold.dat'
TEST='hw4_p16_val_1_fold.dat'
./train -q -s 0 -c 0.5 -e 0.000001 ..$TRAIN; ./predict ..$TEST $TRAIN.model 123.csv
TRAIN='hw4_p16_train_2_fold.dat'
TEST='hw4_p16_val_2_fold.dat'
./train -q -s 0 -c 0.5 -e 0.000001 ..$TRAIN; ./predict ..$TEST $TRAIN.model 123.csv
TRAIN='hw4_p16_train_3_fold.dat'
TEST='hw4_p16_val_3_fold.dat'
./train -q -s 0 -c 0.5 -e 0.000001 ..$TRAIN; ./predict ..$TEST $TRAIN.model 123.csv
TRAIN='hw4_p16_train_4_fold.dat'
TEST='hw4_p16_val_4_fold.dat'
./train -q -s 0 -c 0.5 -e 0.000001 ..$TRAIN; ./predict ..$TEST $TRAIN.model 123.csv
echo "====="
TRAIN='hw4_p16_train_0_fold.dat'
TEST='hw4_p16_val_0_fold.dat'
./train -q -s 0 -c 0.005 -e 0.000001 ..$TRAIN; ./predict ..$TEST $TRAIN.model 123.csv
TRAIN='hw4_p16_train_1_fold.dat'
TEST='hw4_p16_val_1_fold.dat'
./train -q -s 0 -c 0.005 -e 0.000001 ..$TRAIN; ./predict ..$TEST $TRAIN.model 123.csv
TRAIN='hw4_p16_train_2_fold.dat'
TEST='hw4_p16_val_2_fold.dat'
./train -q -s 0 -c 0.005 -e 0.000001 ..$TRAIN; ./predict ..$TEST $TRAIN.model 123.csv
TRAIN='hw4_p16_train_3_fold.dat'
TEST='hw4_p16_val_3_fold.dat'
./train -q -s 0 -c 0.005 -e 0.000001 ..$TRAIN; ./predict ..$TEST $TRAIN.model 123.csv
TRAIN='hw4_p16_train_4_fold.dat'
TEST='hw4_p16_val_4_fold.dat'
./train -q -s 0 -c 0.005 -e 0.000001 ..$TRAIN; ./predict ..$TEST $TRAIN.model 123.csv
echo "====="
TRAIN='hw4_p16_train_0_fold.dat'
TEST='hw4_p16_val_0_fold.dat'
./train -q -s 0 -c 0.0005 -e 0.000001 ..$TRAIN; ./predict ..$TEST $TRAIN.model
TRAIN='hw4_p16_train_1_fold.dat'
TEST='hw4_p16_val_1_fold.dat'
./train -q -s 0 -c 0.0005 -e 0.000001 ..$TRAIN; ./predict ..$TEST $TRAIN.model
TRAIN='hw4_p16_train_2_fold.dat'
TEST='hw4_p16_val_2_fold.dat'
./train -q -s 0 -c 0.0005 -e 0.000001 ..$TRAIN; ./predict ..$TEST $TRAIN.model
TRAIN='hw4_p16_train_3_fold.dat'
TEST='hw4_p16_val_3_fold.dat'
./train -q -s 0 -c 0.0005 -e 0.000001 ..$TRAIN; ./predict ..$TEST $TRAIN.model
TRAIN='hw4_p16_train_4_fold.dat'
TEST='hw4_p16_val_4_fold.dat'
./train -q -s 0 -c 0.0005 -e 0.000001 ..$TRAIN; ./predict ..$TEST $TRAIN.model
echo "====="
```