

P1. B  $[B] \underbrace{(1,1,1)}_{x_1}, \underbrace{(2,3,4)}_{x_2}, \underbrace{(4,3,2)}_{x_3}, \underbrace{(4,2,3)}_{x_4}$

$$\left. \begin{array}{l} x_2 - x_1 = (1, 2, 3) \\ x_3 - x_1 = (3, 2, 1) \\ x_4 - x_1 = (3, 1, 2) \end{array} \right] \Rightarrow \text{rank} \left( \begin{bmatrix} 1 & 2 & 3 \\ 3 & 2 & 1 \\ 3 & 1 & 2 \end{bmatrix} \right) = 3, \text{ 可知道3個vector不共平面}$$

沒有發生退化, 故必定可以被 3D perceptron hypothesis shattered.

P2.C

當  $N=1$  時:  $\{0, x\}$ , 2 種



當  $N=2$  時:  $\{00, xx, ox, xo\}$ , 4 種



當  $N=3$  時:  $\{0xx, x00, ox0, x0x, 00x, xx0\}$ , 6 種



只有  $2N$  符合規律

P3.A Without loss of generality, 令  $d=1$

此 donut hypothesis 可視為在  $x$  軸正向上的 positive interval hypothesis

By slide . 24. P15, positive interval hypothesis  $m_H(H) = \binom{N+1}{2} + 1$  #

故選 [A]

P4.D  $m_H(1) = \binom{2}{2} + 1 = 2$

$$m_H(2) = \binom{3}{2} + 1 = 4$$

$$m_H(3) = \binom{4}{2} + 1 = 7 \neq 8 \leftarrow \text{break point}$$

故  $d_{VC}(H) = 2$  #

# P5.C

[a] 1個 positive interval 有 2 個 degree of freedom, 2 個 positive interval 有 4 個 d.o.f.

$$\text{故 } d_{vc}(H) = 4$$

[b]  $\mathbb{R}^2$  中的長方形有 4 個 d.o.f., 分別是中心  $x, y$  座標與長寬

$$\text{故 } d_{vc}(H) = 4$$

[c] 根據 slide 24. p32. perception hypothesis set  $d_{vc} = d + 1$

當  $d=4$  時,  $d_{vc}=5$ , 且限制  $w_0 > 0$  不影響  $d_{vc}$ . 因為我們可以將原亦能被 hypothesis set shattered 的  $x$  input 平移至正半平面.  $d_{vc}$  仍是 5 #

[d] 三次多項式  $(w_0 + w_1x + w_2x^2 + w_3x^3)$ . 有 4 個 d.o.f 可以決定. 故  $d_{vc}(H) = 4$  #

P6.A

1個 binary classifier 只有 1 个 degree of freedom, 就是決定 Binary classifier 的 threshold  
若有 1126 個 binary classifier 就有 1126 个 degree of freedom, 故  $d_c$  最多是 1126.

By Hoeffding inequality

$$P[|E_{in}(g) - E_{out}(g)| > \epsilon] \leq 2M \exp(-2\epsilon^2 N)$$

這是壞事發生的機率的 upper bound, 換言之, 若要找好事發生的機率的 lower bound, 公式能寫成:

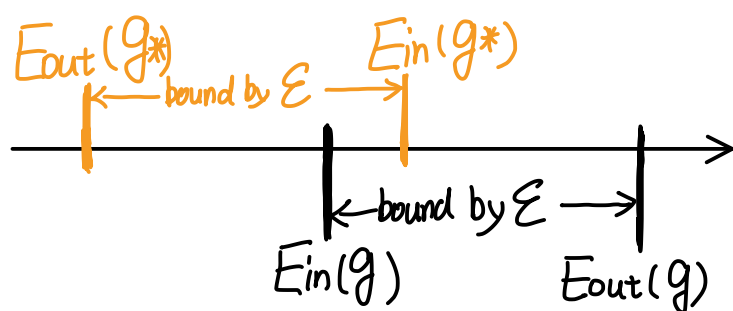
$$\Rightarrow P[|E_{in}(g) - E_{out}(g)| < \epsilon] \geq 1 - 2M \exp(-2\epsilon^2 N)$$

$g^*$  也能用 Hoeffding inequality 寫一樣的式子

$$\Rightarrow P[|E_{in}(g^*) - E_{out}(g^*)| < \epsilon] \geq 1 - 2M \exp(-2\epsilon^2 N)$$

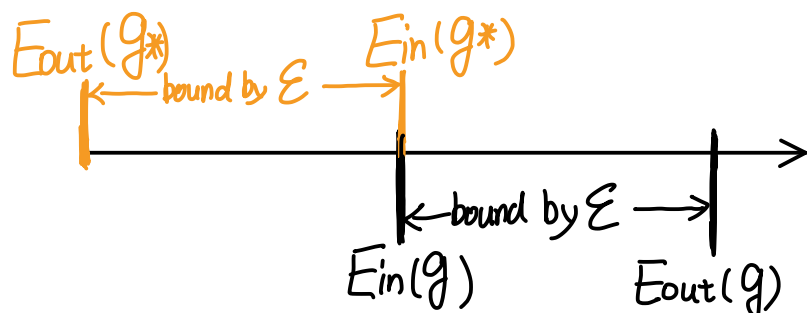
由於  $g = \operatorname{argmin}_{h \in H} E_{in}(h)$ , 故  $E_{in}(g) \leq E_{in}(g^*)$

我們可以利用 inequality 的 boundary (考慮最糟狀況) 在數線上畫出下图



且由於  $E_{in}(g) \leq E_{in}(g^*)$  的限制, 我們知道  $E_{out}(g)$  與  $E_{out}(g^*)$  相距最遠的 case 發生在  $E_{in}(g) = E_{in}(g^*)$  時, 如下圖所示, 此時

$E_{out}(g)$  與  $E_{out}(g^*)$  bound by  $\epsilon + \epsilon = 2\epsilon$



所以我們可以寫:  $P[|E_{out}(g) - E_{out}(g^*)| < \underline{2\epsilon}] \geq 1 - \delta$

其中  $1 - \delta = 1 - 2M \exp(-2\varepsilon^2 N)$

$$\Rightarrow \delta = 2M \exp(-2\varepsilon^2 N)$$

$$\Rightarrow \ln\left(\frac{\delta}{2M}\right) = -2\varepsilon^2 N$$

$$\Rightarrow \frac{1}{2N} \ln\left(\frac{2M}{\delta}\right) = \varepsilon^2$$

$$\Rightarrow \varepsilon = \sqrt{\frac{1}{2N} \ln\left(\frac{2M}{\delta}\right)}$$

而我們要的 upper bound 是  $2\varepsilon$ , 故答案為  $2\varepsilon = 2\sqrt{\frac{1}{2N} \ln\left(\frac{2M}{\delta}\right)}$  #



P8.B By L4 投影片, P. 25: positive rays  $m_H(N) = N + 1$

$$4m_H(2N) \exp(-\frac{1}{8} \epsilon^2 N), \text{ 代入 } \epsilon = 0.1$$

$$\Rightarrow 4(2N+1) \exp(-\frac{1}{8} \cdot 0.01 \cdot N) \text{ --- ①}$$

$$\text{代 } N=10000 \text{ 代入 ① 式 } \Rightarrow 0.298$$

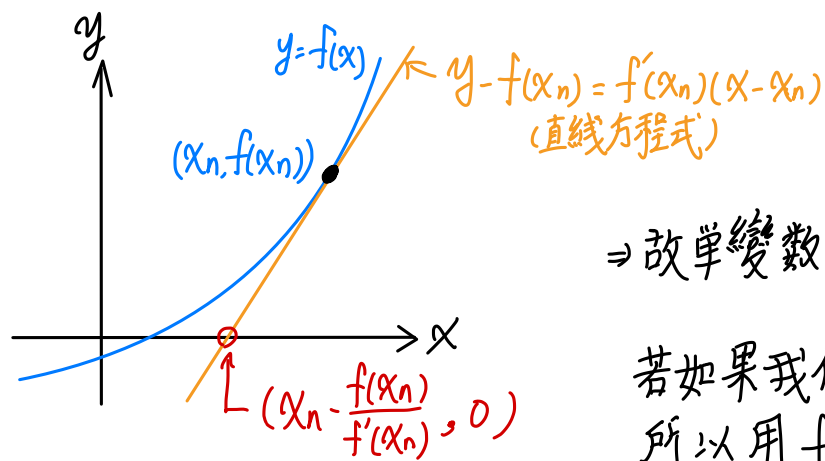
$$\text{代 } N=11000 \text{ 代入 ① 式 } \Rightarrow \underline{0.094}_{\#} \leq 0.1 \text{ 故选 } \underline{B}_{\#}$$

$$\text{代 } N=12000 \text{ 代入 ① 式 } \Rightarrow 0.029$$

$$\text{代 } N=13000 \text{ 代入 ① 式 } \Rightarrow 0.009$$

$$\text{代 } N=14000 \text{ 代入 ① 式 } \Rightarrow 0.003$$

P9.B



⇒ 故單變數的求根方式是  $x_{n+1} = x_n - \frac{f(x_n)}{f'(x_n)}$

若如果我們要求極值, 等同於在找  $f'(x)=0$  的根  
 所以用  $f'(x_n)$  替換  $f(x_n)$ , 我們可以得到

$$x_{n+1} = x_n - \frac{f'(x_n)}{f''(x_n)}$$

接下來將單變數的公式換成矩陣形式:  $\vec{w}_{n+1} = \vec{w}_n - (A_E(u))^{-1} b_E(u)$

PI0.D By L5 投影片 P.30

$$\nabla E_{in}(W) = \frac{1}{N} \sum_{i=1}^N \theta(-y_n W^T x_n) (-y_n x_n), \text{ where } \theta(s) = \frac{1}{1 + e^{-s}}$$

$$\text{求 } \frac{d}{dW} \nabla E_{in}(W) = \frac{1}{N} \sum_{i=1}^N \frac{d}{dW} \left[ \frac{-y_n x_n}{1 + e^{y_n W^T x_n}} \right]$$

$$= \frac{1}{N} \sum_{i=1}^N (-y_n x_n) \cdot \frac{-1}{(1 + e^{y_n W^T x_n})^2} \cdot e^{y_n W^T x_n} \cdot (y_n x_n)$$

$$= \frac{1}{N} \sum_{i=1}^N \underbrace{(y_n^2)}_{1, \because y_n \in \{-1, 1\}} \cdot \left( \frac{e^{y_n W^T x_n}}{1 + 2e^{y_n W^T x_n} + e^{2y_n W^T x_n}} \right) \cdot (x_n x_n^T)$$

$$= \frac{1}{N} \sum_{i=1}^N \left( \frac{1}{e^{-y_n W^T x_n} + 2 + e^{y_n W^T x_n}} \right) \cdot (x_n x_n^T)$$

$$= \frac{1}{N} \sum_{i=1}^N \underbrace{\left( \frac{1}{1 + e^{-y_n W^T x_n}} \right)}_{\text{}} \cdot \underbrace{\left( \frac{1}{1 + e^{y_n W^T x_n}} \right)}_{\text{}} \cdot (x_n x_n^T), \quad h_z(x) = \frac{1}{1 + e^{W_z^T x}} \text{ 代换}$$

$$= \frac{1}{N} \sum_{i=1}^N h_z(-y_n x_n) \cdot h_z(y_n x_n) \cdot (x_n x_n^T) \quad \#$$

P11.C 舉反例說明

設  $A = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}$ , 則  $A^{\dagger} = \begin{bmatrix} \frac{1}{4} & \frac{1}{4} \\ \frac{1}{4} & \frac{1}{4} \end{bmatrix}$ ,  $AA^{\dagger} = \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} \end{bmatrix} \neq \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}_{\#}$

考慮 normal distribution  $f(x) = \frac{1}{\sigma\sqrt{2\pi}} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$

將  $\mu = w^T x_n$ ,  $\sigma^2 = a^2$ ,  $x = y_n$  代入上式

$$f(y_n) = \frac{1}{a\sqrt{2\pi}} \cdot e^{-\frac{(y_n - w^T x_n)^2}{2a^2}}$$

$$\text{likelihood} = \prod_{n=1}^N f(y_n) = \prod_{n=1}^N \frac{1}{a\sqrt{2\pi}} \cdot e^{-\frac{(y_n - w^T x_n)^2}{2a^2}}$$

$$\text{取 } \ln : \frac{N}{a\sqrt{2\pi}} + \sum_{n=1}^N \left[ -\frac{(y_n - w^T x_n)^2}{2a^2} \right]$$

$$\Rightarrow \frac{N}{a\sqrt{2\pi}} + \left(-\frac{1}{2a^2}\right) \cdot \sum_{n=1}^N (y_n - w^T x_n)^2$$

我們想求 min error, 故乘上 -1

$$\Rightarrow -\frac{N}{a\sqrt{2\pi}} + \frac{1}{2a^2} \cdot [y^T y - 2y^T X w + (w^T X)^T] \leftarrow \text{此為 Error } \nabla E_{in}(w)$$

$$\text{求 } \nabla E_{in}(w) = 0$$

$$\frac{d}{dw} \left[ -\frac{N}{a\sqrt{2\pi}} + \frac{1}{2a^2} \cdot [y^T y - 2w^T X y + (w^T X)^T] \right] = 0$$

$$\Rightarrow \frac{1}{2a^2} [-2X^T y + 2X^T X w^T] = 0$$

$$\Rightarrow X^T X w^T = a^2 X^T y$$

$$\Rightarrow \underline{w^T = a^2 (X^T X)^{-1} X^T y} \quad \#$$

P13.D

```
import random
import numpy as np
import math

N_TRAIN = 200 # Number of training data
N_TEST = 5000 # Number of testing data
N_REPEAT = 100

def sign(x):
    if x >= 0:
        return 1
    else:
        return -1

Ein_acc = 0
for seed in range(N_REPEAT):
    random.seed(a=seed)
    # Generate training/testing data
    train_data = []
    test_data = []
    for _ in range(N_TRAIN + N_TEST):
        y = random.randint(0, 1)
        if y == 1:
            x1 = np.random.normal(2, math.sqrt(0.6), 1)[0]
            x2 = np.random.normal(3, math.sqrt(0.6), 1)[0]
        elif y == 0: # -1
            y = -1
            x1 = np.random.normal(0, math.sqrt(0.4), 1)[0]
            x2 = np.random.normal(4, math.sqrt(0.4), 1)[0]
        if len(train_data) < N_TRAIN:
            train_data.append((1, x1, x2, y))
        else:
            test_data.append((1, x1, x2, y))

    # Linear regression
    X = []
    Y = []
    for i in range(N_TRAIN):
        X.append(train_data[i][:3])
        Y.append([train_data[i][3]])
    X = np.array(X)
    Y = np.array(Y)
    X_pseudo = np.linalg.pinv(X, rcond=1e-15, hermitian=False)
    W_lin = np.matmul(X_pseudo, Y)

    # Calculate Ein (error on training dataset)
    for i in range(N_TRAIN):
        s = np.dot(W_lin.reshape(3), np.array(train_data[i][:3]))
        Ein_acc += (Y[i]*s-1)**2 * (1/N_TRAIN)

print("Ein = " + str(Ein_acc / N_REPEAT))
```

P14, D

```
import random
import numpy as np
import math

N_TRAIN = 200 # Number of training data
N_TEST = 5000 # Number of testing data
N_REPEAT = 100

def sign(x):
    if x >= 0:
        return 1
    else:
        return -1

ans_acc = 0
for seed in range(N_REPEAT):
    random.seed(a=seed)
    # Generate training/testing data
    train_data = []
    test_data = []
    for _ in range(N_TRAIN + N_TEST):
        y = random.randint(0, 1)
        if y == 1:
            x1 = np.random.normal(2, math.sqrt(0.6), 1)[0]
            x2 = np.random.normal(3, math.sqrt(0.6), 1)[0]
        elif y == 0: # -1
            y = -1
            x1 = np.random.normal(0, math.sqrt(0.4), 1)[0]
            x2 = np.random.normal(4, math.sqrt(0.4), 1)[0]
        if len(train_data) < N_TRAIN:
            train_data.append((1, x1, x2, y))
        else:
            test_data.append((1, x1, x2, y))

    # Linear regression
    X = []
    Y = []
    for i in range(N_TRAIN):
        X.append(train_data[i][:3])
        Y.append([train_data[i][3]])
    X = np.array(X)
    Y = np.array(Y)
    X_pseudo = np.linalg.pinv(X, rcond=1e-15, hermitian=False)
    W_lin = np.matmul(X_pseudo, Y)

    # Calculate Ein (error on training dataset)
    Ein_acc = 0
    for i in range(N_TRAIN):
        s = np.dot(W_lin.reshape(3), np.array(train_data[i][:3]))
        if sign(train_data[i][3]*s) != 1:
            Ein_acc += 1 * (1/N_TRAIN)

    # Calculate Eout (error on testing dataset)
    Eout_lin_acc = 0
    for i in range(N_TEST):
        s = np.dot(W_lin.reshape(3), np.array(test_data[i][:3]))
        if sign(test_data[i][3]*s) != 1:
            Eout_lin_acc += 1 * (1/N_TEST)

    ans_acc += abs(Ein_acc - Eout_lin_acc)

print("ans = " + str(ans_acc/N_REPEAT))
```



P15.B



