How to use 3DGEMS Dataset with Gazebo ROS??

Step-1:

Install turtlebot3 package from source (if you already have it you can skip this step):

```
cd ~/catkin_ws/src/
git clone -b melodic-devel https://github.com/ROBOTIS-GIT/turtlebot3.git
cd ~/catkin_ws && catkin_make
```

Step-2:

Install turtlebot3 simulation package (if you already have it you can skip this step):

```
cd ~/catkin_ws/src/
git clone -b melodic-devel
https://github.com/ROBOTIS-GIT/turtlebot3_simulations.git
cd ~/catkin_ws && catkin_make
```

Step-3:

Go to 3DGEMS

Download all the models given in the website i.e, files like:

furniture.tar.gz, kitchen.tar.gz, food.tar.gz, electronics.tar.gz, decoration.tar.gz, etc. files. Extract them.

These folders contain subfolders with 3D models of chair, table, laptop, etc. (Example names of subfolders: chair_1, table_dining, laptop_pc_1)

Copy all these subfolder to the following folder:

/catkin_ws/src/turtlebot3_simulations/turtlebot3_gazebo/models

Step-4:

Now, also download the **world.tar.gz** file from the website.

Extract it and

Now copy **office_small.world** file to the following folder /catkin_ws/src/turtlebot3_simulations/turtlebot3_gazebo/worlds

and rename office_small.world to office_env_small.world

Step-5:

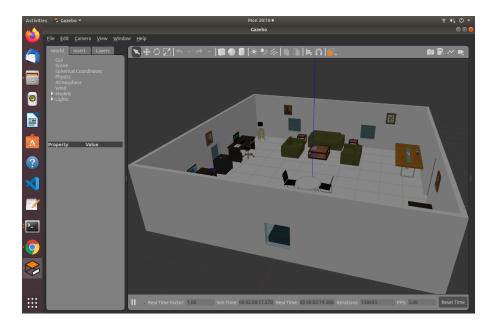
Now, download the file <u>office_env_small.launch</u>
And copy to the folder /catkin_ws/src/turtlebot3_simulations/turtlebot3_gazebo/launch

Step-6:

Now, to launch the small office environment for turtlebot3 follow the following steps:

```
export TURTLEBOT3_MODEL=waffle
roslaunch turtlebot3_gazebo office_env_small.launch
```

You can easily launch the environment as shown below example:



Now, you can perform any task with turtlebot3 in this environment.

You can launch any environment by changing the **.world** file name in the launch file as below: (Change the darken part):