

### QUESTION 1 c)

$$\text{STABILITY: } u_j^{n+1} = u_j^{n-1} - \frac{c \Delta t}{\Delta x} (u_{j+1}^n - u_{j-1}^n)$$

$$u_m^K = \bar{u}_m^K + \epsilon_m^K$$

$$\Rightarrow \bar{u}_j^{n+1} + \epsilon_j^{n+1} = \bar{u}_j^{n-1} + \epsilon_j^{n-1} - \frac{c \Delta t}{\Delta x} (\bar{u}_{j+1}^n + \epsilon_{j+1}^n - \bar{u}_{j-1}^n + \epsilon_{j-1}^n)$$

$$\Rightarrow \epsilon_j^{n+1} = \epsilon_j^{n-1} - \frac{c \Delta t}{\Delta x} (\epsilon_{j+1}^n - \epsilon_{j-1}^n)$$

$$\Rightarrow G = \frac{\epsilon_j^{n+1}}{\epsilon_j^n} = \frac{\epsilon_j^{n-1}}{\epsilon_j^n} - \frac{c \Delta t}{\Delta x} \left( \frac{\epsilon_{j+1}^n}{\epsilon_j^n} - \frac{\epsilon_{j-1}^n}{\epsilon_j^n} \right)$$

$$\epsilon_j^n = e^{at} e^{ik_n \Delta x} ; \frac{c \Delta t}{\Delta x}$$

$$\Rightarrow G = \frac{e^{a(t-\Delta t)} e^{ik_n x}}{e^{at} e^{ik_n x}} - \sigma \left( \frac{e^{at} e^{ik_n (x+\Delta x)}}{e^{at} e^{ik_n x}} - \frac{e^{at} e^{ik_n (x-\Delta x)}}{e^{at} e^{ik_n x}} \right)$$

$$e^{-a \Delta t} - \sigma \left( e^{ik_n \Delta x} - e^{-ik_n \Delta x} \right)$$

$$\Rightarrow G = \frac{1}{G} - \sigma \left( 2i \sin(k_n \Delta x) \right)$$

We Multiply by  $G$  on each side

$$\Rightarrow G^2 = 1 - \sigma G \left( 2i \sin(k_n \Delta x) \right)$$

$$\Rightarrow G^2 + \sigma G \left( 2i \sin(k_n \Delta x) \right) - 1$$

$$G_{1,2} = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

$$b = 2i \sigma \sin(kr \Delta x) \Rightarrow b^2 = -4 \sigma^2 \sin^2(kr \Delta x)$$

$$\Rightarrow b^2 - 4ac = -4 \sigma^2 \sin^2(kr \Delta x) + 4$$

$$\Rightarrow G = \frac{-i \cancel{2} \sigma \sin(kr \Delta x) \pm \sqrt{\cancel{4} (1 - \sigma^2 \sin^2(kr \Delta x))}}{\cancel{2}}$$

$$\Rightarrow |G| = \left| -i \sigma \sin(kr \Delta x) \pm \sqrt{1 - \sigma^2 \sin^2(kr \Delta x)} \right| \leq 1$$

$$\Rightarrow |G|^2 = \sigma^2 \sin^2(kr \Delta x) + 1 - \sigma^2 \sin^2(kr \Delta x) = 1$$

$$\Rightarrow |G|^2 = 1 = |G| \quad \text{THE CONDITION } |G| \leq 1 \text{ IS RESPECTED HOW EVER}$$

WE NEED TO VERIFY THE  $\Delta = 1 - \sigma^2 \sin^2(kr \Delta x) > 0$

$$\Rightarrow \sigma^2 \sin^2(kr \Delta x) \leq 1$$

$$\Rightarrow \sigma^2 \leq 1$$

WORST CASE  $\sin^2(kr \Delta x) = 1$

$$\Rightarrow \sigma = \frac{c \Delta t}{\Delta x} \leq 1$$

if  $\Delta = b^2 - 4ac \leq 0$  THERE WOULD BE

An imaginary part that would add to  $-i \sigma \sin(kr \Delta x)$

## ACCURACY

LET'S DEVELOP IN TAYLOR

$$U_j^{n+1} = U_j^n - \frac{C \Delta t}{\Delta x} (U_{j+1}^n - U_{j-1}^n) \Rightarrow U_j^{n+1} - U_j^n = \frac{C \Delta t}{\Delta x} (U_{j+1}^n - U_{j-1}^n) \quad (1)$$

$$U_j^{n+1} = U_j^n + \Delta t \frac{\partial u}{\partial t} + \frac{\Delta t^2}{2} \frac{\partial^2 u}{\partial t^2} + \frac{\Delta t^3}{6} \frac{\partial^3 u}{\partial t^3} + \dots$$

$$U_j^{n-1} = U_j^n - \Delta t \frac{\partial u}{\partial t} + \frac{\Delta t^2}{2} \frac{\partial^2 u}{\partial t^2} - \frac{\Delta t^3}{6} \frac{\partial^3 u}{\partial t^3} + \dots$$

$$U_j^{n+1} - U_j^{n-1} = 2 \Delta t \frac{\partial u}{\partial t} + \frac{2 \Delta t^3}{6} \frac{\partial^3 u}{\partial t^3} + \frac{2 \Delta t^5}{120} \frac{\partial^5 u}{\partial t^5} + \dots \quad (2)$$

$$U_{j+1}^n - U_{j-1}^n = 2 \Delta x \frac{\partial u}{\partial x} + \frac{2 \Delta x^3}{6} \frac{\partial^3 u}{\partial x^3} + \frac{2 \Delta x^5}{120} \frac{\partial^5 u}{\partial x^5} + \dots \quad (3)$$

(2) (3) into (1)

$$\Rightarrow 2 \Delta t \frac{\partial u}{\partial t} + \frac{2 \Delta t^3}{6} \frac{\partial^3 u}{\partial t^3} + \frac{2 \Delta t^5}{120} \frac{\partial^5 u}{\partial t^5} + \dots = - \frac{C \Delta t}{\Delta x} \left( 2 \Delta x \frac{\partial u}{\partial x} + \frac{2 \Delta x^3}{6} \frac{\partial^3 u}{\partial x^3} + \frac{2 \Delta x^5}{120} \frac{\partial^5 u}{\partial x^5} + \dots \right)$$

$$\Rightarrow \Delta t \frac{\partial u}{\partial t} + \frac{\Delta t^3}{6} \frac{\partial^3 u}{\partial t^3} + \frac{\Delta t^5}{120} \frac{\partial^5 u}{\partial t^5} + \dots = - \frac{C \Delta t}{\Delta x} \left( \Delta x \frac{\partial u}{\partial x} + \frac{\Delta x^3}{6} \frac{\partial^3 u}{\partial x^3} + \frac{\Delta x^5}{120} \frac{\partial^5 u}{\partial x^5} + \dots \right)$$

$$\Rightarrow \frac{\partial u}{\partial t} + C \frac{\partial u}{\partial x} = \frac{\Delta x^2}{6} \frac{\partial^3 u}{\partial x^3} + \frac{\Delta x^4}{120} \frac{\partial^5 u}{\partial x^5} - \frac{\Delta t^2}{6} \frac{\partial^3 u}{\partial t^3} - \frac{\Delta t^4}{120} \frac{\partial^5 u}{\partial t^5}$$

$$\Rightarrow = O(\Delta x^2) + O(\Delta t^2)$$

CONSISTENCY

$$\lim_{\substack{\Delta t \rightarrow 0 \\ \Delta x \rightarrow 0}} \left( \overset{10}{\frac{\Delta x^2}{6}} \frac{\partial^3 u}{\partial x^3} + \overset{10}{\frac{\Delta x^4}{120}} \frac{\partial^5 u}{\partial x^5} - \overset{10}{\frac{\Delta t^2}{6}} \frac{\partial^3 u}{\partial t^3} - \overset{10}{\frac{\Delta t^4}{120}} \frac{\partial^5 u}{\partial t^5} \right) = 0$$

THIS ALGORITHM IS CONSISTENT