MATH 2055

Second Order Homogeneous LDEs

Examples of Second Order DEs

Examples of second-order differential equations

Differential equation	Physical problem	Quantities	Constitutive law
$\frac{\mathrm{d}}{\mathrm{d}x} \left(Ak \frac{\mathrm{d}T}{\mathrm{d}x} \right) + Q = 0$	One-dimensional heat flow	T = temperature $A = area$ $k = thermal conductivity$ $Q = heat supply$	Fourier $q = -k dT/dx$ $q = \text{heat flux}$
$\frac{\mathrm{d}}{\mathrm{d}x} \left(AE \frac{\mathrm{d}u}{\mathrm{d}x} \right) + h = 0$	Axially loaded elastic bar	 u = displacement A = area E = Young's modulus b = axial loading 	Hooke $\sigma = E du/dx$ $\sigma = stress$
$S\frac{d^2w}{dx^2} + p = 0$	Transversely loaded flexible string	w = deflection S = string force p = lateral loading	

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Differential equation	Physical problem	Quantities	Constitutive law
$\frac{\mathrm{d}}{\mathrm{d}x} \left(AD \frac{\mathrm{d}c}{\mathrm{d}x} \right) + Q = 0$	One-dimensional diffusion	 c = iron concentration A = area D = diffusion coefficient Q = ion supply 	Fick $q = -D dc/dx$ $q = ion flux$
$\frac{\mathrm{d}}{\mathrm{d}x} \left(A \gamma \frac{\mathrm{d}V}{\mathrm{d}x} \right) + Q = 0$	One-dimensional electric current	V = voltage A = area γ = electric conductivity Q = electric charge supply	Ohm $q = -\gamma dV/dx$ $q = \text{electric charge flux}$
$\frac{\mathrm{d}}{\mathrm{d}x} \left(A \frac{D^2}{32\mu} \frac{\mathrm{d}p}{\mathrm{d}x} \right) + Q = 0$	Laminar flow in pipe (Poiseuille flow)	$p = \text{pressure}$ $A = \text{area}$ $D = \text{diameter}$ $\mu = \text{viscosity}$ $Q = \text{fluid supply}$	$q = -(D^2/32\mu) dp/dx$ q = volume flux q = mean velocity

Wronskian

• A set of n functions $y_1(x), y_2(x), \dots, y_n(x)$, is said to be **linearly dependent** (LD) over an interval I if there exist n constants c_1, c_2, \dots, c_n , not all zero, such that

$$c_1 y_1(x) + c_2 y_2(x) + \dots + c_n y_n(x) = 0$$

• Otherwise the set of functions is said to be linearly independent (LI)

Wronskian

A set of n functions $y_1(x), y_2(x), \dots, y_n(x)$, is **linearly independent** over an interval I if and only if the determinant (**Wronski determinant**, or **Wronskian**)

$$W(y_1, y_2, \dots, y_n) = \begin{vmatrix} y_1 & y_2 & \cdots & y_n \\ y'_1 & y'_2 & \cdots & y'_n \\ \vdots & \vdots & \ddots & \vdots \\ y_1^{(n-1)} & y_2^{(n-1)} & y_n^{(n-1)} & y_n^{(n-1)} \end{vmatrix} \neq 0$$

Check linear dependency of set of fn's given below $\cos x$, $\sin x$

Sol'n:

$$W(\cos x, \sin x) = \begin{vmatrix} \cos x & \sin x \\ -\sin x & \cos x \end{vmatrix}$$
$$= \cos^2 x + \sin^2 x$$
$$= 1 \neq 0$$

 $\therefore \cos x$, $\sin x$ are LI

Recall that if $\begin{bmatrix} a & b \\ c & d \end{bmatrix}$ is a 2 by 2 matrix, its determinant is the product of the main (upper-left to lower right) diagonal minus the product of the other diagonal.

That is, det = ad - bc.

The solution of the

$$y'' - 2y'' - 15 = 0,$$

$$y = C_1 e^{5x} + C_2 e^{-3x}$$

is composed of the two component functions,

$$y_1(x) = e^{5x}$$
 & $y_2(x) = e^{-3x}$

$$W(e^{5x}, e^{-3x}) = \begin{vmatrix} e^{5x} & e^{-3x} \\ 5e^{5x} & -3e^{-3x} \end{vmatrix} = -3e^{2x} - 5e^{2x} = -8e^{2x} \neq 0 \ \forall \ x$$

It is impossible to turn e^{5x} into e^{-3x} by multiplying one or the other by a constant. These two component functions are linearly independent.

The functions

$$y_1(x) = e^{4x}$$
 & $y_2(x) = 5e^{4x}$

are **not** linearly independent. The Wronskian is

$$W(e^{4x}, 5e^{4x}) = \begin{vmatrix} e^{4x} & 5e^{4x} \\ 4e^{4x} & 20e^{4x} \end{vmatrix} = 20e^{8x} - 20e^{8x} = 0 \ \forall \ x$$

Note that one function can be made into the other by multiplying by a constant, e.g.

$$y_1(x) = \frac{1}{5}y_2(x)$$
 or $y_2(x) = 5y_1(x)$

The functions

$$(x) = x^2 + 2x$$
, $y_2(x) = 3x + 1$, $y_3(x) = 2x^2 + x - 1$

are **not** linearly independent. Since the Wronskian is

$$W(y_1, y_2, y_3) = \begin{vmatrix} x^2 + 2x & 3x + 1 & 2x^2 + x - 1 \\ 2x + 2 & 3 & 4x + 1 \\ 2 & 0 & 4 \end{vmatrix}$$

$$W(y_1, y_2, y_3) = 2 \begin{vmatrix} 3x+1 & 2x^2+x-1 \\ 3 & 4x+1 \end{vmatrix} + 4 \begin{vmatrix} x^2+2x & 3x+1 \\ 2x+2 & 3 \end{vmatrix}$$

$$W(y_1, y_2, y_3) = 0 \ \forall \ x$$

Existence and Uniqueness Theorem

$$y'' + p(x)y' + q(x)y = 0$$
 (1)

$$y = c_1 y_1 + c_2 y_2$$
 (2)

$$y(x_0) = k_0, y'(x_0) = k_1$$
 (3)

If p(x) and q(x) are **continuous** function on some open interval I and x_0 is in I, then the initial value problem consisting of (1) and (3) has a **unique** solution y(x) on the interval I.

Linear Dependence and Independence of Sol'n

- Suppose that (1) has continuous coefficients p(x) and q(x) on an open interval I. Then two solutions y_1 and y_2 of (1) on I are linear dependent on I if and only if their Wronskian W is zero at some x_0 in I.
- Furthermore, if W=0 for $x=x_0$, then W=0 on I; hence if there is an x_1 in I at which W is not zero, then y_1,y_2 are liner independent on I.

Linear Dependence and Independence of Sol'n

Typically, solutions to linear, homogeneous, autonomic *n*th-order differential equations appear in the following ways:

- As functions of the form e^{r_1x} , e^{r_2x} , ..., e^{r_nx} , where $r_1, r_2, ..., r_n$ are all different real numbers. These will always be **linearly independent**.
- As functions of the form e^{rx} , xe^{rx} , x^2e^{rx} , These will also be **linearly independent**. (We have not seen a case like this yet. We will.)
- As trigonometric functions $\sin(bx)$, $\cos(bx)$ or $e^{ax}\sin(bx)$, $e^{ax}\cos(bx)$. These will also be **linearly independent**.

A General Solution of (1) includes All Sol'ns

$$y'' + p(x)y' + q(x)y = 0 (1)$$

Theorem 3 (Existence of a general solution)

If p(x) and q(x) are continuous on an open interval I, then (1) has a general solution on I.

A General Solution of (1) includes All Sol'ns

Theorem 4 (General solution)

Suppose that (1) has continuous coefficients p(x) and q(x) on some open interval I. Then every solution y = y(x) of (1) is of the form

$$y = c_1 y_1(x) + c_2 y_2(x)$$

where y_1, y_2 form a basis of solutions of (1) on I and c_1, c_2 are suitable constants. Hence (1) does not have singular solutions (i.e., solutions not obtainable from a general solution)

Exercises - Solve

Check if the given pair of functions are linearly dependent or not.

(a)
$$f(t) = e^t$$
, $g(t) = e^{-t}$

(b)
$$f(t) = \sin \omega t$$
, $g(t) = \cos \omega t$

(c)
$$f(t) = t + 1$$
, $g(t) = 4t + 4$

(d)
$$f(t) = 2t$$
, $g(t) = |t|$

Suppose $y_1(t), y_2(t)$ are two solutions of y'' + p(t)y' + q(t)y = 0 Then

- I. We have either $W(y_1, y_2) \equiv 0$ or $W(y_1, y_2)$ never zero;
- II. If $W(y_1, y_2) \neq 0$, then $y = c_1y_1 + c_2y_2$ is the general solution.

They are also called to form a fundamental set of solutions.

As a consequence, for any IC's $y(t_0) = y_0$, $y'(t_0) = y'_0$, there is a unique set of (c_1, c_2) that give a unique solution.

Illustration of Theorem 2

Example 1:

$$y'' + w^2y = 0$$

has sol'ns

$$y_1 = \cos wx$$
, $y_2 = \sin wx$

 $W(\cos wx, \sin wx) = 1 \Longrightarrow y = c_1 \cos wx + c_2 \sin wx$

Example 2:

$$y'' - 2y' + y = 0,$$

has sol'ns

$$y_1 = e^x$$
, $y_2 = xe^x$

$$W(e^x, xe^x) = e^{2x}, \Longrightarrow y = (c_1 + c_2 x)e^x$$

Abel's Theorem

Let y_1, y_2 be two (linearly independent) solutions to

$$y'' + p(t)y' + q(t)y = 0$$

on an open interval I. Then, the Wronskian $W(y_1,y_2)$ on I is given by

$$W(y_1, y_2)(t) = Ce^{\int -p(t) dt}$$

for some constant C depending on y_1, y_2 , but independent on t in I.

Example: Given

$$t^2y'' - t(t+2)y' + (t+2)y = 0$$

Find $W(y_1, y_2)$ without solving the equation.

Sol'n: We first find the p(t)

$$p(t) = -t(t+2)$$

which is valid for $t \neq 0$. By Abel's Theorem, we have

$$W(y_1, y_2)(t) = Ce^{\int -p(t) dt} = Ce^{\int t(t+2) dt} = Ce^{t+2\ln|t|} = t^2Ce^t$$

Example: For the equation

$$2t^2y'' + 3ty' - y = 0$$
, $t > 0$

given one solution $y_1 = 1/t$, find a second linearly independent solution.

Sol'n: By Abel's Theorem, and choose C=1, we have

$$W(y_1, y_2)(t) = Ce^{\int -p(t) dt} = Ce^{\int -\frac{3t}{2t^2} dt} = t^{-3/2}$$

By definition of the Wronskian,

$$W(y_1, y_2) = y_1 y_2' - y_1' y_2 = \frac{y_2'}{t} + \frac{y_2}{t^2} = t^{-3/2}$$

Solve this for y_2 (taking C=0): $y_2=\frac{2}{3}\sqrt{t}$

Exercises

Exercise: If y_1, y_2 are two solutions of

$$ty'' + 2y' + te^t y = 0$$

and $W(y_1, y_2)(1) = 2$, find $W(y_1, y_2)(5)$.

Exercise: If $W(f,g) = 3e^{4t}$, and $f = e^{2t}$, find g.

Exercise: Consider the equation

$$t^2y'' - t(t + 2)y' + (t + 2)y = 0, t > 0$$

Given $y_1 = t$, find the general solution.

Exercise: Given the equation $t^2y'' - (t - \frac{3}{16})y = 0$, t > 0 and

$$y_1 = t^{1/4} e^{2\sqrt{t}}$$
, find y_2 .

Linear Second Order DEs

The most general linear second order differential equation is in the form.

$$p(t)y'' + q(t)y' + r(t)y = g(t)$$

if one or more of p(t), q(t), r(t) is not constant, the above equation has variable coefficients.

The constant coefficient linear second order differential equation is

$$ay'' + by' + cy = g(t)$$

where a, b, c are all constants.

Linear Second Order DEs

Initially we will make our life easier by looking at differential equations

with g(t) = 0.

When g(t) = 0 we call the differential equation homogeneous (HDE),

when $g(t) \neq 0$ we call the differential equation non-homogeneous.

Example

$$y(x) = 6\cos(4x) - 17\sin(4x)$$
 is a solution of
$$y'' + 16y = 0$$

$$y' = -24\sin(4x) - 68\cos(4x)$$

$$y'' = -96\cos(4x) + 272\sin(4x)$$
 By substitution:
$$y'' + 16y = 0$$

$$F(x, y, y', y'') = 0$$

$$F(x, y(x), y'(x), y(x)'') = 0$$

Example

Consider the simple, 2nd-order LDE

$$y'' - 12x = 0$$

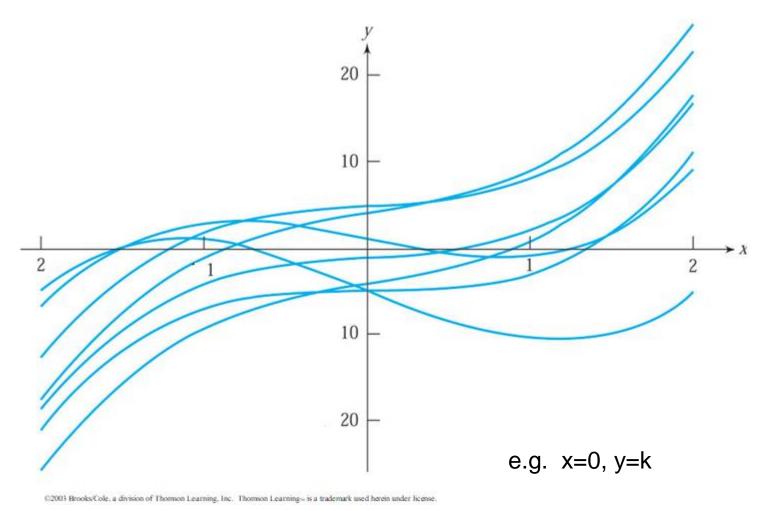
$$y'' - 12x = 0 \qquad \Rightarrow \qquad y'' = 12x$$

$$y' = \int y''(x)dx \qquad = \int 12xdx \qquad = 6x^2 + C$$

$$y = \int y'(x)dx \qquad = \int (6x^2 + C)dx \qquad = 2x^3 + Cx + K$$

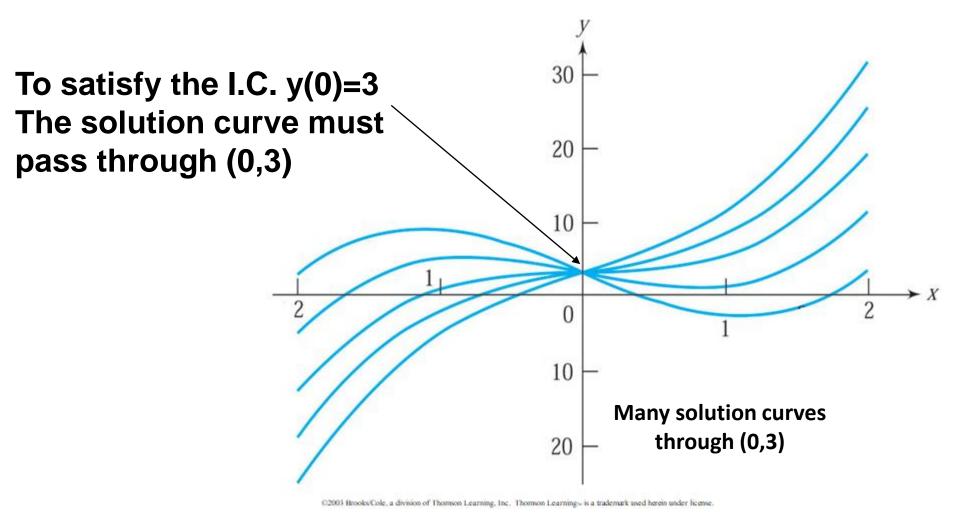
To determine C and K, we need **two** initial conditions, one specify **a point** lying on the **solution curve** and the other its **slop**e at that point, e.g. y(0) = K, y'(0) = C

Example - continued



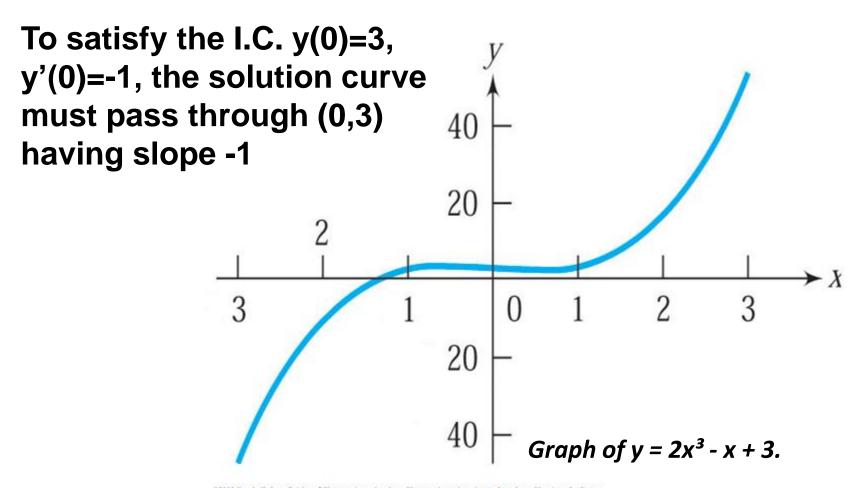
Graphs of $y = 2x^3 + Cx + K$ for various values of C and K.

Example - continued



Graphs of $y = 2x^3 + Cx + 3$ for various values of C.

Example - continued



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Linear Differential Operators

Consider the linear differential equation of the n-th order

$$a_0(x)\frac{d^n y}{dx^n} + a_1(x)\frac{d^{n-1} y}{dx^{n-1}} + \dots + a_{n-1}(x)\frac{dy}{dx} + a_n(x)y = F(x)$$

Using the differential operator D this equation can be written as

$$L(D)y(x) = F(x)$$

where L(D) is the differential polynomial equal to

$$L(D) = a_0(x)D^n + a_1(x)D^{n-1} + \dots + a_{n-1}(x)D + a_n(x)$$

In other words, the operator L(D) is an algebraic polynomial, in which the differential operator D plays the role of a variable.

Linear Differential Operators

We denote by D the simplest differential operator, that is,

$$D = \frac{d}{dx}$$
 or $D = \frac{d}{dt}$

D acting on a function y, "returns" the first derivative of this function Dy(x) = y'(x)

Higher order derivatives can be written in terms of D, that is,

$$\frac{d^2y}{dx^2} = \frac{d}{dx} \left(\frac{dy}{dx} \right) = D(Dy) = D^2y$$

where D^2 is just the composition of D with itself. Similarly,

$$\frac{d^n y}{dx^n} = D^n y$$

some properties of the operator L(D)

• The operator L(D) is linear:

$$L(D)[c_1y_1+c_2y_2]=c_1L(D)y_1+c_2L(D)y_2$$

In the case of several operators L(D), M(D) and N(D) (the degree of the differential polynomials can be different), the following properties also hold:

Commutative law of addition:

$$L(D)+M(D) = M(D)+L(D)$$

some properties of the operator L(D)

Associative law of addition:

$$[L(D)+M(D)] + N(D) = L(D)+[M(D)+N(D)]$$

For two operators L(D) and M(D), one can also define the multiplication operation:

$$[L(D) \cdot M(D)]y(x) = L(D) \cdot [M(D)y(x)]$$

It is important to note that the multiplication operation is commutative for differential operators with constant coefficients, that is for the operators of the form

$$L(D) = a_0 D^n + a_1 D^{n-1} + a_{n-1} D + a_n$$

where a_0, \dots, a_n are constant numbers.

some properties of the operator L(D)

Commutative law of multiplication:

$$L(D) \cdot M(D) = M(D) \cdot L(D)$$

Associative law of multiplication:

$$[L(D) \cdot M(D)] \cdot N(D) = L(D) \cdot [M(D) \cdot N(D)]$$

• Distributive law of multiplication over addition:

$$L(D) \cdot [M(D) + N(D)] = L(D) \cdot M(D) + L(D) \cdot N(D)$$

We also mention another useful property of the operator

$$D^m D^n = D^{m+n}$$

$$y'' + 4y' + 3y = 0$$

We use the convention and rewrite the DE

symbolically, Since formerly

$$D^2 + 4D + 3 = (D+3)(D+1)$$

we see that:

$$L(D) = (D+3)(D+1)$$

$$y'' + y' - 2y = 0$$

rewrite the DE

$$D^{2}y + Dy - 2y = 0$$

$$(D^{2} + D - 2)y = 0 \Rightarrow L(D) = D^{2} + D - 2$$

$$D^{2} + D - 2 = (D + 2)(D - 1)$$

$$L(D) = (D + 2)(D - 1)$$

$$y''' + 8y = 0$$

rewrite the DE

$$D^{3}y + 8y = 0$$

$$(D^{3} + 8)y = 0$$

$$\Rightarrow L(D) = D^{3} + 8$$

$$D^{3} + 8 = (D + 2)(D^{2} - 2D + 4)$$

$$L(D) = (D + 2)(D^{2} - 2D + 4)$$

example

$$y^{IV} - 2y^{\prime\prime} + y = 0$$

rewrite the DE

$$D^{4}y - 2D^{2}y + y = 0$$

$$(D^{4} - 2D^{2} + 1)y = 0 \Rightarrow L(D) = D^{4} - 2D^{2} + 1$$

$$D^{4} - 2D^{2} + 1 = (D^{2} - 1)^{2}$$

$$L(D) = (D^{2} - 1)^{2}$$

Solving Second Order, Linear, Homogeneous ODE with Constant Coefficients

Consider the sol'n of the type

$$y(t) = e^{rt}$$

Substituting in

$$ay'' + by' + cy = 0$$

We have

$$a(r^2e^{rt}) + b(re^{rt}) + ce^{rt} = 0$$

$$ar^2 + br + c = 0$$
 as $e^{rt} \neq 0$

Solving Second Order, Linear, Homogeneous ODE with Constant Coefficients

$$ar^2 + br + c = 0$$

Above equation is typically called the characteristic (auxiliary, m) equation

This will be a quadratic equation and so we should expect two roots, $r_1 \& r_2$. Once we have these two roots we have two solutions to the differential equation.

$$y_1(t) = e^{r_1 t}$$
 & $y_2(t) = e^{r_2 t}$

Characteristic Equation Cases

Case 1: Distinct Real Roots, $r_1 \neq r_2$

$$a^2 - 4b > 0 \implies y = c_1 e^{r_1 x} + c_2 e^{r_2 x}$$

Case 2: Double roots, $r_1 = r_2 = r$

$$a^2 - 4b = 0 \implies y = (c_1 + c_2 x)e^{r_1 x}$$

Case 3: Complex root, $r_{1,2} = \alpha \mp i\beta$

$$a^2 - 4b < 0 \implies y = e^{\alpha x} (A \cos \beta x + B \sin \beta x)$$

Example: Find two sol'ns to y'' - 9y = 0.

Sol'n: The characteristic equation is

$$r^2 - 9 = 0 \Rightarrow r_{1,2} = \pm 3$$

The two roots are 3 and -3. Therefore, two solutions are

$$y_1(t) = e^{3t}$$
 & $y_2(t) = e^{-3t}$

The general solution is $y_c(t) = c_1 e^{3t} + c_2 e^{-3t}$

Example: Find two sol'ns to

$$6y'' - y' - 2y = 0$$

Sol'n: The characteristic equation is

$$6r^2 - r - 2r = 0 \Rightarrow (2r + 1)(3r - 2) = 0 \Rightarrow r_{1,2} = \frac{-1}{2}, \frac{2}{3}$$

The two roots are 3 and -3. Therefore, two solutions are

$$y_1(t) = e^{-(1/2)t}$$
 & $y_2(t) = e^{(2/3)t}$
 $y_c(t) = c_1 e^{-(1/2)t} + c_2 e^{(2/3)t}$

Example: Find two sol'ns to

$$y'' + 5y' + 4y = 0$$

Sol'n: The characteristic equation is

$$6r^2 - r - 2r = 0 \Rightarrow (r+1)(r+4) = 0 \Rightarrow r_{1,2} = -1, -4$$

The two roots are 3 and -3. Therefore, two solutions are

$$y_1(t) = e^{-t}$$
 & $y_2(t) = e^{-4t}$
 $y_c(t) = c_1 e^{-t} + c_2 e^{-4t}$

Example: Solve the following IVP

$$y'' + 11y' + 24y = 0$$
, $y(0) = 0$, $y'(0) = -7$

Sol'n: The characteristic equation is

$$r^2 + 11r + 24 = 0 \Rightarrow (r+8)(r+3) = 0 \Rightarrow r = -8, -3$$

The general solution and its derivative is

$$y_c(t) = c_1 e^{-3t} + c_2 e^{-8t}$$
$$y'_c(t) = -3c_1 e^{-3t} - 8c_2 e^{-8t}$$

Putting the initial conditions, we have the following system of equations

$$0 = y_c(0) = c_1 + c_2$$
$$-7 = y'_c(0) = -3c_1 - 8c_2$$

Solving we get

$$c_1 = \frac{-7}{5}$$
 & $c_2 = \frac{7}{5}$

Thus the solution is

$$y_c(t) = \frac{-7}{5} e^{-3t} + \frac{7}{5} e^{-8t}$$

Example: Solve the following IVP

$$y'' + y' - 2y = 0, y(0) = 4, y'(0) = -5$$

Solution: The characteristic equation is

$$r^2 + r - 2 = 0 \Rightarrow (r + 2)(r - 1) = 0 \Rightarrow r = 1, -2$$

The general solution and its derivative is

$$y_c(t) = c_1 e^t + c_2 e^{-2t}$$
$$y'_c(t) = c_1 e^t - 2c_2 e^{-2t}$$

Putting the initial conditions, we have the following system of equations

$$4 = y_c(0) = c_1 + c_2$$

$$-5 = y'_c(0) = c_1 - 2c_2$$

Solving we get

$$c_1 = 1 & c_2 = 3$$

Thus the solution is

$$y_c(t) = e^t + 3e^{-2t}$$

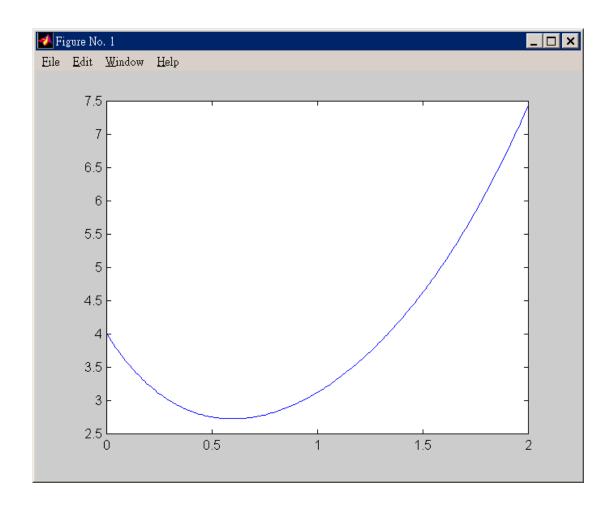
Plot Particular Solution

MATLAB Code:

t=[0:0.01:2];

y=exp(t)+3*exp(-2*t);

plot(t,y)



Reduction of Order

Let $y(x) = y_1(x)$ be the known solution of second order DE

$$a_2(x)y'' + a_1(x)y' + a_0(x)y = 0$$

Assume $y_2 = u(x)y_1(x)$ is the other solution. Then

$$a_2(x)y_2''(x) + a_1(x)y_2'(x) + a_0(x)y_2(x) = 0$$

$$a_2(x)\{u(x)y_1(x)\}'' + a_1(x)\{u(x)y_1(x)\}' + a_0(x)u(x)y_1(x) = 0$$

Reduction of Order

$$a_{2}(x)\{u''(x)y_{1}(x) + 2u'(x)y_{1}'(x) + u(x)y_{1}''(x)\} + a_{1}(x)\{u'(x)y_{1}(x) + u(x)y_{1}'(x)\} + a_{0}(x)u(x)y_{1}(x) = 0$$

$$u''(x)a_{2}(x)y_{1}(x) + u'(x)\{2a_{2}(x)y_{1}'(x) + a_{1}(x)y_{1}(x)\}$$

$$+ u(x)\{a_{2}(x)y_{1}''(x) + a_{1}(x)y_{1}'(x) + a_{0}(x)y_{1}(x)\} = 0$$
Since

$$a_2(x)y_1''(x) + a_1(x)y_1'(x) + a_0(x)y_1(x) = 0$$

Reduction of Order

therefore

$$u''(x)a_{2}(x)y_{1}(x) + u'(x)\{2a_{2}(x)y_{1}'(x) + a_{1}(x)y_{1}(x)\} = 0$$

$$u''(x)a_{2}(x)y_{1}(x) = -u'(x)\{2a_{2}(x)y_{1}'(x) + a_{1}(x)y_{1}(x)\}$$

$$\frac{u''(x)}{u'(x)} = -\left(\frac{2y_{1}'(x)}{y_{1}(x)} + \frac{a_{1}(x)}{a_{2}(x)}\right) \implies u(x) = \int \frac{e^{-\int \frac{a_{1}(x)}{a_{2}(x)}dx}}{y_{1}^{2}}dx$$

$$y_{2} = u(x)y_{1}(x) = y_{2} = y_{1}(x)\int \frac{e^{-\int \frac{a_{1}(x)}{a_{2}(x)}dx}}{y_{1}^{2}}dx$$

Example: Solve the following IVP

$$y'' - 4y' + 4y = 0$$
, $y(0) = 3$, $y'(0) = 1$

Sol'n: The characteristic equation is

$$r^2 - 4r + 4 = 0 \Rightarrow (r - 2)^2 = 0 \Rightarrow r = 2,2$$

The general solution is

$$y_c(t) = c_1 e^{2t} + c_2 e^{2t}$$

But it is written as

$$y_c(t) = (c_1 + c_2)e^{2t} = Ce^{2t}$$
 where $C = c_1 + c_2$

Therefore we have to use Reduction of Order

$$y_2 = u(t)y_1(t) = u(t)e^{2t}$$

its derivatives are

$$y'_{2}(t) = 2u(t)e^{2t} + u'(t)e^{2t}$$
$$y''_{2}(t) = 4u(t)e^{2t} + 4u'(t)e^{2t} + u''(t)e^{2t}$$

Substituting in DE

$$\underbrace{4u(t)e^{2t} + 4u'(t)e^{2t} + u''(t)e^{2t}}_{y''} \quad \underbrace{-4(2u(t)e^{2t} + u'(t)e^{2t})}_{-4y'} \quad \underbrace{+4u(t)e^{2t}}_{+4y} = 0$$

$$u''(t)e^{2t} = 0 \implies u''(t) = 0$$

 $u'(t) = c_2 \implies u(t) = c_1 + c_2 t$

then

$$y_2(t) = u(t)e^{2t} = (c_1 + c_2t)e^{2t}$$

Number of repeated roots	Multiply known sol'n by
2	$c_1 + c_2 t$
3	$c_1 + c_2 t + c_3 t^2$
4	$c_1 + c_2 t + c_3 t^2 + c_4 t^3$

or we can write directly according to table

$$y_2(t) = c_1 e^{2t} + c_2 t e^{2t}$$

The general solution and its derivative is

$$y_c(t) = c_1 e^{2t} + c_2 t e^{2t}$$

$$y'_{c}(t) = 2c_{1}e^{2t} + c_{2}e^{2t} + 2c_{2}te^{2t}$$

Putting the initial conditions, we have the following system of equations

$$3 = y_c(0) = c_1$$

$$1 = y'_{c}(0) = 2c_1 + c_2$$

Solving we get

$$c_1 = 3$$
 & $c_2 = -5$

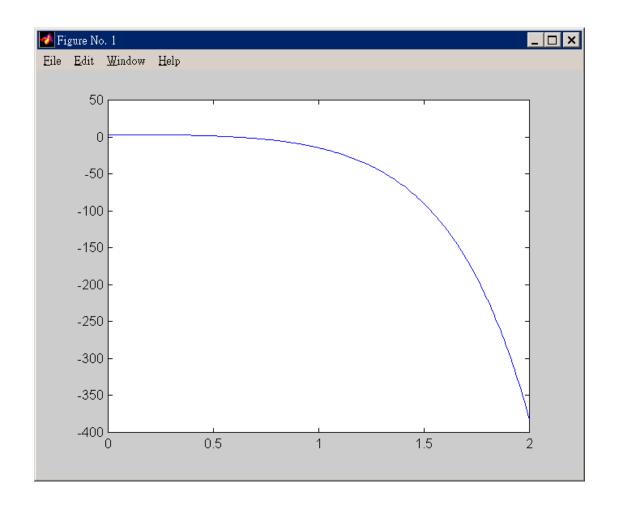
Thus the solution is

$$y(t) = (3 - 5t)e^{2t}$$

Plot Particular Solution

MATLAB Code:

t=[0:0.01:2]; y=(3-5*t).*exp(2*t); plot(t,y)



What is the correct form of the solution of

$$y'' - 6y' + 9y = 0$$

Solution: The characteristic equation is

$$r^2 - 6r + 9 = 0 \Rightarrow (r - 3)^2 = 0 \Rightarrow r_{1,2} = 3.3$$

The general solution is

$$y_c = (C_1 + C_2 x)e^{3x}$$

Solve

$$y''' + 3y'' + 3y' + y = 0$$

Solution: The auxiliary polynomial is

$$r^3 + 3r^2 + 3r + 1 = 0 \implies (r+1)^3 = 0 \implies r_{1,2,3} = -1$$

Thus, is the root of this polynomial, with multiplicity 3. The individual solutions are

$$y_1 = e^{-x}$$
, $y_2 = xe^{-x}$ & $y_3 = x^2e^{-x}$

The general solution is

$$y = (C_1 + C_2 x + C_3 x^2)e^{-x}$$

Solve

$$y''' - 2y'' - 7y' - 4y = 0$$

Solution: The auxiliary polynomial is

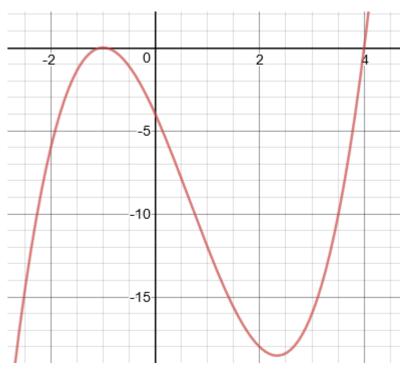
$$r^3 - 2r^2 - 7r - 4 = 0$$

It's difficult to factor a cubic, so we graph it to locate its roots: The graph appears to pass through r = 4, and glance the r-axis at r = -1, which suggests a root of multiplicity 2.

The possible factorization is

$$(r+1)^2(r-4) = 0$$

(You should expand this to verify that this is true.)



Example - continued

The general solution is $y = C_1 e^{4x} + [C_2 + C_3 x] e^{-x}$

We now check that the individual solutions are linearly independent by finding the Wronskian:

$$W(e^{4x}, e^{-x}, xe^{-x}) = \begin{vmatrix} e^{4x} & e^{-x} & xe^{-x} \\ 4e^{4x} & -e^{-x} & (1-x)e^{-x} \\ 16e^{4x} & e^{-x} & (x-2)e^{-x} \end{vmatrix} = \begin{vmatrix} 1 & 1 & x \\ 4 & -1 & (1-x) \\ 16 & 1 & (x-2) \end{vmatrix} e^{2x}$$

$$= e^{2x} \begin{bmatrix} \begin{vmatrix} -1 & (1-x) \\ 1 & (x-2) \end{vmatrix} - 1 \begin{vmatrix} 4 & (1-x) \\ 16 & (x-2) \end{vmatrix} + x \begin{vmatrix} 4 & -1 \\ 16 & 1 \end{vmatrix} \end{bmatrix}$$
$$= 25e^{2x} \neq 0$$

Thus, the three individual solutions are linearly independent.

Euler Formula - Proof

$$e^{ix} = \cos x + i \sin x$$

$$e^{x} = 1 + x + \frac{x^{2}}{2!} + \frac{x^{3}}{3!} + \dots = \sum_{n=0}^{\infty} \frac{x^{n}}{n!}$$
Maclaurin Series
$$\cos x = 1 - \frac{x^{2}}{2!} + \frac{x^{4}}{4!} - \frac{x^{6}}{6!} + \dots = \sum_{n=0}^{\infty} \frac{(-1)^{n} x^{2n}}{(2n)!}$$

$$\sin x = x - \frac{x^{3}}{3!} + \frac{x^{5}}{5!} - \frac{x^{7}}{7!} + \dots = \sum_{n=0}^{\infty} \frac{(-1)^{n} x^{2n+1}}{(2n+1)!}$$

Euler Formula - Proof

$$e^{ix} = \cos x + i \sin x$$

$$e^{ix} = 1 + ix + \frac{(ix)^2}{2!} + \frac{(ix)^3}{3!} + \dots = \sum_{n=0}^{\infty} \frac{(ix)^n}{n!}$$

$$= 1 + ix - \frac{x^2}{2!} - \frac{ix^3}{3!} + \frac{x^4}{4!} + \frac{ix^5}{5!} - \frac{x^6}{6!} - \frac{ix^7}{7!} + \dots$$

$$= \left(1 - \frac{x^2}{2!} + \frac{x^4}{4!} - \frac{x^6}{6!} + \dots\right) + i\left(x - \frac{x^3}{3!} + \frac{x^5}{5!} - \frac{x^7}{7!} + \dots\right)$$

$$=\cos x + i\sin x$$

Euler Formula

$$e^{ix} = \cos x + i \sin x$$

$$e^{i\pi} = -1$$

$$e^{i2\pi} = 1$$

$$e^{i\pi/2} = \cos \frac{\pi}{2} + i \sin \frac{\pi}{2} = 0 + i$$

$$e^{-i\pi/2} = -1$$

Complex Exponential Function

$$z = s + it$$

$$e^{z} = e^{s+it} = e^{s}e^{it} = e^{s}(\cos t + i\sin t)$$

$$\bar{z} = s - it$$

$$e^{\bar{z}} = e^{s-it} = e^{s}e^{-it} = e^{s}(\cos t - i\sin t)$$

$$r_1 = \alpha + i\beta \quad \& \quad r_2 = \alpha - i\beta$$

$$y = c_1 e^{r_1 x} + c_2 e^{r_2 x} = c_1 e^{(\alpha + i\beta)x} + c_2 e^{(\alpha - i\beta)x}$$

$$y = e^{\alpha x} (c_1 e^{i\beta x} + c_2 e^{-i\beta x})$$

$$y = e^{\alpha x} [c_1 (\cos \beta x + i \sin \beta x) + c_2 (\cos \beta x - i \sin \beta x)]$$

$$y = e^{\alpha x} [(c_1 + c_2) \cos \beta x + (ic_1 - ic_2) \sin \beta x]$$

$$y = e^{\alpha x} (A \cos \beta x + B \sin \beta x)$$

Example: Solve the following IVP

$$y'' - 4y' + 9y = 0$$
, $y(0) = 0$, $y'(0) = -8$

Sol'n: The characteristic equation is

$$r^2 - 4r + 9 = 0 \Rightarrow r_{1,2} = 2 \pm \sqrt{5}i$$
.

The general solution and its derivative is

$$y_c(t) = c_1 e^{2t} \cos \sqrt{5}t + c_2 e^{2t} \sin \sqrt{5}t$$

Putting the initial conditions, we have the following system of equations

$$0 = y_c(0) = c_1$$

SO

$$y_c(t) = c_2 e^{2t} \sin \sqrt{5}t$$

$$y'_c(t) = 2c_2 e^{2t} \sin \sqrt{5}t + \sqrt{5}c_2 e^{2t} \cos \sqrt{5}t$$

$$y'_c(0) = \sqrt{5}c_2 \Rightarrow -8 = \sqrt{5}c_2 \Rightarrow c_2 = \frac{-8}{\sqrt{5}}$$

Thus the solution is

$$y(t) = \frac{-8}{\sqrt{5}}e^{2t}\sin\sqrt{5}t$$

Example: Solve the following IVP

$$y'' + 0.2y' + 4.01y = 0$$
, $y(0) = 0$, $y'(0) = 2$

Sol'n: The characteristic equation is

$$r^2 + 0.2r + 4.01 = 0 \Rightarrow r_{1,2} = -0.1 \pm 2i$$

The general solution and its derivative is

$$y_c(t) = e^{-0.1t} (A\cos 2t + B\sin 2t)$$

Putting the initial conditions, we have the following system of equations

$$0 = y_c(0) = A$$

SO

$$y_c(t) = Be^{-0.1t} \sin 2t$$

 $y'_c(t) = e^{-0.1t}(-0.1B \sin 2t + 2B \cos 2t)$
 $2 = y'_c(0) = 2B \Rightarrow B = 1$

Thus the solution is

$$y(t) = e^{-0.1t} \sin 2t$$

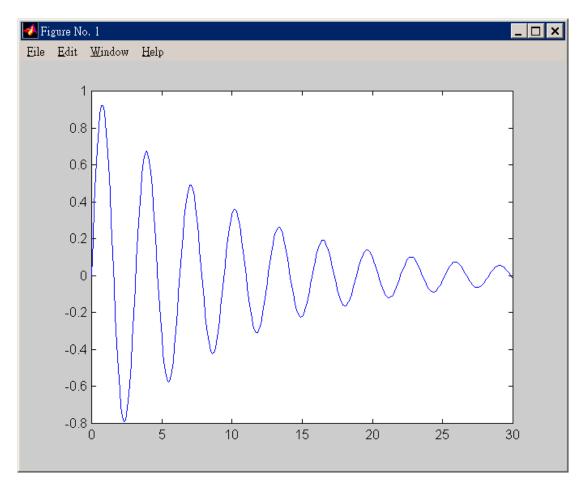
Plot Particular Solution

MATLAB Code

x=[0:0.1:30];

y=exp(-0.1*t).*sin(2*t);

plot(t,y)



Find the general solution of

$$y''' + y'' - 4y' - 4y = 0$$

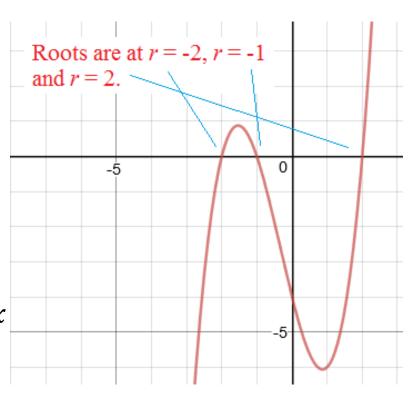
Solution: The auxiliary polynomial is

$$r^3 + r^2 - 4r - 4 = 0$$

To locate roots, we graph it:

Thus, we conclude that the general solution is

$$y = C_1 e^{-2x} + C_2 e^{-x} + C_3 e^{2x}$$



Solve

$$y^{iv} + 8y'' + 16y = 0.$$

Solution: The auxiliary polynomial is

$$r^4 + 8r^2 + 16 = 0 \implies (r^2 + 4)^2 = 0 \implies r_{1,2} = \pm 2i$$

 $r_{3,4} = \pm 2i$

Thus, both complex and conjugate each of multiplicity 2. The individual solutions are

$$y_1 = \cos 2x$$
 $y_3 = x \cos 2x$
 $y_2 = \sin 2x$ $y_4 = x \sin 2x$

The general solution is

$$y = (C_1 + C_3 x) \cos 2x + (C_2 + C_4 x) \sin 2x$$

Solve

$$y^{iv} + 4y''' + 14y'' + 20y' + 25y = 0$$

Solution: The auxiliary polynomial is

$$r^{4} + 4r^{3} + 14r^{2} + 20r + 25 = 0$$

$$(r^{2} + 2r + 5)^{2} = 0 \implies \begin{aligned} r_{1,2} &= -1 \pm 2i \\ r_{3,4} &= -1 \pm 2i \end{aligned}$$

The general solution is:

$$y = e^{-x}[(C_1 + C_3 x)\cos 2x + (C_2 + C_4 x)\sin 2x]$$

There is no general way to factor quartic polynomials. The above polynomial was factored using Wolframalpha.

Solve

$$y^{\nu} - 2y^{i\nu} - 5y^{\prime\prime\prime} - 2y^{\prime\prime} + 52y^{\prime} - 56y = 0$$

Solution: The m-eqn is $r^5 - 2r^4 - 5r^3 - 2r^2 + 52r - 56$

Its graph is shown at the right.

Note that there appears to be a root at 2, and that it passes tangentially through the horizontal axis, so the root probably has multiplicity 3.

0 2

However, we need to actually verify this using synthetic division.

Example - continued

A remainder of 0 indicates that 2 is a root

Repeat the process with the new coefficients

Again, a remainder of 0 indicates that 2 is a root one more time

Repeat yet again

Remainder 0 shows that 2 is a root a third time. Thus, 2 is a root of multiplicity 3

Example - continued

After showing that 2 is a root of multiplicity 3, the coefficients of the remaining factors are 1, 4 and 7.

$$r^5 - 2r^4 - 5r^3 - 2r^2 + 52r - 56 = 0 \Rightarrow (r - 2)^3(r^2 + 4r + 7) = 0$$

Using the quadratic formula on the factor

$$r^2 + 4r + 7 = 0 \Rightarrow r_{4,5} = -2 \pm i\sqrt{3}$$

The general solution is

$$y = (C_1 + C_2 x + C_3 x^2)e^{2x} + e^{-2x} (C_4 \cos \sqrt{3}x + C_5 \sin \sqrt{3}x)$$

Summary of Cases I–III

Case	Roots of m eqn.	Basis of DE	General Solution of DE
I	Distinct real m_1, m_2	e^{m_1x} , e^{m_2x}	$y = c_1 e^{m_1 x} + c_2 e^{m_2 x}$
II	Real double root $m_{1,2} = a$	e^{ax} , xe^{ax}	$y = (c_1 + c_2 x)e^{ax}$
III	Complex conjugate $m_{1,2} = \alpha \pm i\beta$	$e^{\alpha x}\cos\beta x$, $e^{\alpha x}\sin\beta x$	$y = e^{\alpha x} (A \cos \beta x + B \sin \beta x)$

Exercises: Solve the following IVPs

$$y'' + 3y' - 10y = 0$$
, $y(0) = 4$, $y'(0) = -2$ Ans:
 $y = \frac{2}{7}e^{-5t}(9e^{7t} + 5)$
 $3y'' - 2y' - 8y = 0$, $y(0) = -6$, $y'(0) = -18$
 $y = \frac{1}{5}(9e^{-4t/3} - 39e^{2t})$
 $4y'' - 5y' = 0$, $y(-2) = 0$, $y'(-2) = 7$
 $y = \frac{28}{5}(e^{5(t+2)/4} - 1)$
 $y'' - 8y' + 17y = 0$, $y(0) = -4$, $y'(0) = -1$

 $y = e^{4t} (15 \sin t - 4 \cos t)$

Exercises: Solve the following IVPs

$$4y'' - 24y' + 37y = 0, \quad y(\pi) = 1, \quad y'(\pi) = 0 \qquad \text{Ans:}$$

$$y = e^{3(t-\pi)} \left(\sin \frac{t}{2} + 6 \cos \frac{t}{2} \right)$$

$$y'' + 16y = 0, \quad y(\pi/2) = -1, \quad y'(\pi/2) = 4$$

$$y = (\sin t - \cos t)$$

$$16y'' - 40y' + 25y = 0, \quad y(0) = 3, \quad y'(0) = -\frac{9}{4}$$

$$y = -3e^{5t/4}(2x - 1)$$

$$y'' + 14y' + 49y = 0, \quad y(-4) = -1, \quad y'(-4) = 5$$

$$y = -e^{-7(t+4)}(2x + 9)$$

Exercises: Solve the following IVPs

$$y'' - 6y' - 2y = 0$$
 ans: $y = e^{3t} \left(c_1 e^{-\sqrt{11}t} + c_2 e^{\sqrt{11}t} \right)$
 $4y'' + 4y' - 3y = 0$, ans: $y = c_1 e^{t/2} + c_2 e^{-3t/2}$
 $2y'' - 9y' = 0$, ans: $y = c_1 e^{9t/2} + c_2$
 $y'' + 4y' + 4y = 0$, ans: $y = e^{-2t} (c_1 + c_2 t)$
 $9y'' - 30y' + 25y = 0$, ans: $y = e^{5t/3} (c_1 + c_2 t)$
 $y'' - 2y' + 2y = 0$, ans: $y = e^t (c_1 \cos t + c_2 \sin t)$
 $4y'' + 4y' + 10y = 0$, ans: $y = e^{-t/2} (c_1 \cos t + c_2 \sin t)$