

MATH 2055

Introduction to Differential Equations

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Course Website

- <http://akademik.marmara.edu.tr/mustafa.yilmaz/teaching> for
Syllabus, assignments, etc...
- <https://www.wolframalpha.com> for interactive answer check

Exams

- 2 Midterms:
 - Midterm 1: will be announced
 - Midterm 2: will be announced
- Final Exam: will be announced

Grading Scheme & Grading Scale

- Scheme:
 - 9% HW, 24% Midterm 1, 27% Midterm 2, 40% Final Exam
- Scale:
 - Relative Evaluation System (Curve)

Mathematical Symbols And Abbreviations

Symbol	Say	Means
\therefore	therefore	therefore
\because	because	because
\forall	for all	for all
\Leftrightarrow	if and only if or <i>iff</i>	if and only if or <i>iff</i>
\propto	proportional to	proportional to
\Rightarrow	implies	calculation on left of symbol imply those on the right
<i>fn</i>	function	function
wrt	with respect to	with respect to
LHS	Left-hand side	Left-hand side
RHS	right-hand side	right-hand side

Mathematical Symbols And Abbreviations

Symbol	Say	Means
$\frac{dy}{dx}$	Dee y dee x	Differentiate fn y wrt x
$\frac{d^2y}{dx^2}$	Dee 2 y dee x squared	Double differentiate fn y wrt x Second derivative of fn y
$\frac{\partial y}{\partial x}, y_x$	Partial y wrt x	Partial derivative of y wrt x
$f'(x)$	f prime of x or f prime	Differentiate fn f(x) wrt x , equivalent to $\frac{dy}{dx}$ if y=f(x)
y'	y prime	Differentiate fn y wrt x , equivalent to $\frac{dy}{dx}$ if y=f(x)
\dot{x} (dot above variable x)	x dot	Differentiate fn x wrt t

Mathematical Symbols And Abbreviations

Symbol	Say	Means
$f''(x)$	f double prime of x or f double prime	Differentiate fn $f(x)$ wrt x twice, Second derivative of fn $f(x)$, equivalent to $\frac{d^2y}{dx^2}$, y'' if $y=f(x)$
\ddot{x}	x double dot	Differentiate fn x wrt t twice, Second derivative of fn x , equivalent to $\frac{d^2x}{dt^2}$
$f'''(x)$	f triple prime of x or f double prime	Differentiate fn $f(x)$ wrt x three times, Third derivative of fn $f(x)$, equivalent to $\frac{d^3y}{dx^3}$, y''' if $y=f(x)$

Mathematical Symbols And Abbreviations

Symbol	Say	Means
\ddot{x}	x triple dot	Differentiate fn x wrt t three times, Third derivative of fn x , equivalent to $\frac{d^3x}{dt^3}$
$f^{(4)}(x)$	fourth derivative of $f(x)$ or f to four in parenthesis	Differentiate fn $f(x)$ wrt x four times, Fourth derivative of fn $f(x)$, equivalent to $\frac{d^4y}{dx^4}$, $y^{(4)}$ if $y=f(x)$
\mathcal{L}	Laplace Transform	converts a time domain function to complex-domain function by integration from zero to infinity

Terminology

- This course deals with *ordinary differential equations*, which are equations that contain one or more derivatives of a function of a single variable. Such equations can be used to model a rich variety of phenomena of interest in the sciences, engineering, economics, ecological studies, and other areas.
- *Functions*: dependent variables and independent variables.

Concepts of differential equations

- In general, a differential equation is an equation that contains an unknown function and its derivatives. The order of a differential equation is the order of the highest derivative that occurs in the equation.
- A function $y = f(x)$ is called a solution of a differential equation if the equation is satisfied when $y = f(x)$ and its derivatives are substituted into the equation.

e.g.

Show that $y = 2e^{2x}$ is a particular solution of the ordinary differential equation:

$$\frac{d^2y}{dx^2} - \frac{dy}{dx} - 2y = e^x$$

Taking derivatives of fn

$$y' = 4e^{2x}$$

$$y'' = 8e^{2x}$$

Substituting into the DE, $8e^{2x} - 4e^{2x} - 2(2e^{2x}) = 0$

so

$$\boxed{y = 2e^{2x}} \quad \text{sol'n of the DE.}$$

Why?

- One of the most important application of calculus is differential equations, which often arise in describing some phenomenon in engineering, physical science etc.
 - Population Dynamics
 - Circuit Design
 - Astrophysics
 - Geodesics (Pure Math)

Differential Equations

- The following are examples of physical phenomena involving rates of change:
 - Motion of fluids
 - Motion of mechanical systems
 - Flow of current in electrical circuits
 - Dissipation of heat in solid objects
 - Seismic waves
 - Population dynamics

Differential Equations (DE's)

- Equations that describe rates of change
- Equations that involve derivatives:

e.g., $p''(t) = -mg$

(Falling object)

$$y'(t) = y(t)(1 - y(t))$$

(Logistic Equation)

$$u(t, x)_{tt} = cu(t, x)_{xx}$$

(Wave Equation)

$$L \frac{d^2 Q(t)}{dt^2} + R \frac{dQ(t)}{dt} + \frac{1}{C} Q(t) = E(t)$$

(Current)

$$y'' + y = 4x^2$$

$$y''(x) + y(x) = 4x^2$$

$$\frac{d^2 y(x)}{dx^2} + y(x) = 4x^2$$

y : function of x

x : independent variable

Two Types

Ordinary (ODE)

(Only One Independent Variable)

$$p''(t) = -mg$$

$$y'(t) = y(t)(1 - y(t))$$

$$L \frac{d^2 Q(t)}{dt^2} + R \frac{dQ(t)}{dt} + \frac{1}{C} Q(t) = E(t)$$

$$\frac{dv}{dt} = 9.8 - 0.2v, \quad \frac{dp}{dt} = 0.5p - 450$$

involves only **total derivatives** $\frac{df(x)}{dx}$

Partial (PDE)

(Multiple Independent Variables)

$$\alpha^2 \frac{\partial^2 u(x,t)}{\partial x^2} = \frac{\partial u(x,t)}{\partial t} \quad (\text{heat equation})$$

$$a^2 \frac{\partial^2 u(x,t)}{\partial x^2} = \frac{\partial^2 u(x,t)}{\partial t^2} \quad (\text{wave equation})$$

$$u(t, x)_{tt} = cu(t, x)_{xx}$$

involves **partial derivatives** $\frac{\partial f(x, y)}{\partial x}, \frac{\partial f(x, y)}{\partial y}$

This Class

Ordinary
(Only One Independent Variable)

$$p''(t) = -mg$$

$$y'(t) = y(t)(1 - y(t))$$

$$L \frac{d^2 Q(t)}{dt^2} + R \frac{dQ(t)}{dt} + \frac{1}{C} Q(t) = E(t)$$

$$\frac{dy}{dx} + 2 = 0,$$

$$\frac{d^2 y}{dx^2} + \frac{dy}{dx} = e^x$$

Ordinary Differential Equations (ODE)

Definition: A differential equation is an equation containing an unknown function and its derivatives.

**Examples:
(ex.'s)**

1. $\frac{dy}{dx} = 2x + 3$

2. $\frac{d^2y}{dx^2} + 3\frac{dy}{dx} + ay = 0$

3. $\frac{d^3y}{dx^3} + \left(\frac{dy}{dx}\right)^4 + 6y = 3$

y is **dependent** variable (dep. var.) and **x** is **independent** variable (ind. var.)

Partial Differential Equations (PDE)

Definition: Partial Differential Equation: Differential equations that involve two or more independent variables are called partial differential equations.

ex.'s :

1. $\frac{\partial^2 y}{\partial x^2} = \frac{\partial y}{\partial t}$
2. $u(t, x)_{tt} = cu(t, x)_{xx}$
3. $u_t + uu_x = 1 + u_{xx}$

y & u are dependent variables and x and t are independent variables

Order (O)

The order of a differential equation is the *highest derivative* that appears in the differential equation.

Equation	ind. var.	dep. var.	Order
$\left(\frac{dy}{dx}\right)^2 + 2 = 0$	x	y	1
$xy' - y^2 = 3x$	x	y	1
$\frac{d^2y}{dx^2} + \frac{dy}{dx} = e^x$	x	y	2
$u(t, x)_{tt} = cu(t, x)_{xx}$	x, t	u	2
$z^{(iv)} + z'' = -y$	y	z	4
$\frac{d^4w}{dt^4} - w^2 = e^{-2t}$	t	w	4

Degree (D)

The degree of a differential equation is the power of the *highest derivative* term.

Equation	ind. var.	dep. var.	Order	Degree
$\left(\frac{dy}{dx}\right)^2 + 2 = 0$	x	y	1	2
$\frac{d^2y}{dx^2} + \frac{dy}{dx} = e^x$	x	y	2	1
$z^{(iv)} + z'' = -y$	y	z	4	1

Linear Differential Equations (LDE)

If a differential equation can be written as:

$$a_0(t)y^{(n)} + a_1(t)y^{(n-1)} + \dots + a_n y = g(t)$$

A differential equation is called *linear* if there are

- no multiplications among dependent variables and
- their derivatives.

The term $g(t)$ is called a **forcing function**.

Linear Differential Equations (LDE)

In other words, all coefficients are functions of independent variables.

Equation	ind. var.	dep. var.	Order	Degree	Linear
$\left(\frac{dy}{dx}\right)^2 + 2 = 0$	x	y	1	2	-
$\frac{d^2y}{dx^2} + \frac{dy}{dx} = e^x$	x	y	2	1	OK
$z^{(iv)} + z'' = -y$	y	z	4	1	OK

Non-linear Differential Equations

Differential equations that do not satisfy the definition of linear are non-linear.

Equation	ind. var.	dep. var.	Order	Degree	Linear	Non-Linear
$\left(\frac{dy}{dx}\right)^2 + 2 = 0$	x	y	1	2	-	OK
$\frac{d^2y}{dx^2} + \frac{dy}{dx} = e^x$	x	y	2	1	OK	-
$z^{(iv)} + z'' = -y$	y	z	4	1	OK	-

Constant Coefficient Linear ODE

Linear Differential equations with Constant Coefficient

$$b_m \frac{d^m y}{dt^m} + b_{m-1} \frac{d^{m-1} y}{dt^{m-1}} + \dots + b_1 \frac{dy}{dt} + b_0 y = f(t)$$

$$3 \frac{d^4 y}{dt^4} + 5 \frac{d^3 y}{dt^3} + 7 \frac{d^2 y}{dt^2} + 8 \frac{dy}{dt} + 4y = \cos 5t + t^2$$

ex.'s :

Equation	ind. var.	dep. var.	Order	Degree	Linear	Non-Linear	Type
$\left(\frac{dy}{dx}\right)^2 + 2 = 0$	x	y	1	2	-	OK	ODE
$\frac{d^2y}{dx^2} + \frac{dy}{dx} = e^x$	x	y	2	1	OK	-	ODE
$z^{(iv)} + z'' = -y$	y	z	4	1	OK	-	ODE
$y' + ay = bt$	t	y	1	1	OK	-	ODE
$f'' + f' + g(t)f = h(t)$	t	f	2	1	OK	-	ODE
$\frac{dy}{dx} = 2x + 3$	x	y	1	1	OK	-	ODE
$\frac{d^3y}{dx^3} + \left(\frac{dy}{dx}\right)^4 + 6y = 3$	x	y	3	1	-	OK	ODE
$\frac{\partial^2 y}{\partial x^2} = \frac{\partial y}{\partial t}$	x, t	y	2	1	OK	-	PDE
$u(t, x)_{tt} = cu(t, x)_{xx}$ or $\frac{\partial^2 u}{\partial t^2} = c \frac{\partial^2 u}{\partial x^2}$	x, t	u	2	1	OK	-	PDE

Solutions to Differential Equations

Three important questions in the study of differential equations:

- Is there a solution? (Existence)
- If there is a solution, is it unique? (Uniqueness)
- If there is a solution, how do we find it?
 - (Analytical Solution, Numerical Approximation, etc.)

General Solution (gen. sol'n)

- Solutions obtained from integrating the differential equations are called *general solutions*.
- The general solution of an order ODE contains *arbitrary constants* resulting from integrating times.
- Geometrically, the general solution of an ODE is a family of infinitely many solution curves, one for each value of the constant c .

e.g., $y'' + 4y = 0$, sol'n: $y = \sin 2x$ for $x \in \mathbb{R}$

$y' = \frac{y}{x} + 1$, sol'n: $y = x \ln x$ for $x > 0$

Particular Solution

- Particular solutions are the solutions obtained by assigning specific values to the arbitrary constants in the general solutions.
- A particular solution does not contain any arbitrary constants.

Explicit Solution

Any solution that is given in the form $y = f(x)$ (*independent variable*).

$$\text{ex.'s: } \begin{array}{l} A(r) = \pi r^2 + c \\ y(t) = e^{-t} + c \end{array} \quad \text{etc.}$$

For most differential equations, it is *impossible* to find an explicit formula for the solution.

Implicit Solution

Any solution that isn't in explicit form $f(x,y)=0$.

$$\begin{array}{l} y^2 x^2 = c \\ \text{ex.'s: } \sin(xy) = c \\ \quad \quad x e^y = c \end{array} \quad \text{etc.}$$

Initial Value Problems

- An ODE together with an initial condition is called an ***initial value problem (IVP)*** .

$$\bullet \quad F(x, y, y') = 0, \quad y(x_0) = y_0 \quad \Rightarrow \quad \text{initial condition}$$

Graphically, the particular integral curve passes through point (x_0, y_0)

Boundary Value Problems

- Problems with specified boundary conditions are called ***boundary value problems (BVP's)***.

$$\bullet F(x, y, y', y'') = 0, \quad y(x_0) = y_0, y(x_1) = y_1 \Rightarrow \text{boundary conditions}$$

The objective is to obtain a ***unique*** solution

Initial Condition (IC)

In many physical problems we need to find the particular solution that satisfies a condition of the form $\mathbf{y}(\mathbf{x}_0)=\mathbf{y}_0$. Constrains that are specified at the initial point, generally time point, are called ***initial conditions***.

ex.'s:

$$\begin{array}{ll} y'+y=0 & y(0)=1 \\ z'=1 & z(1)=-1 \\ y'+y=2 & y(1)=-5 \end{array}$$

General solution to (3): $y = 2 + ke^{-x}$

$$\because y(1) = 2 + ke^{-1} = -5 \quad \therefore k = -7e, \quad y = 2 - 7e^{1-x}$$

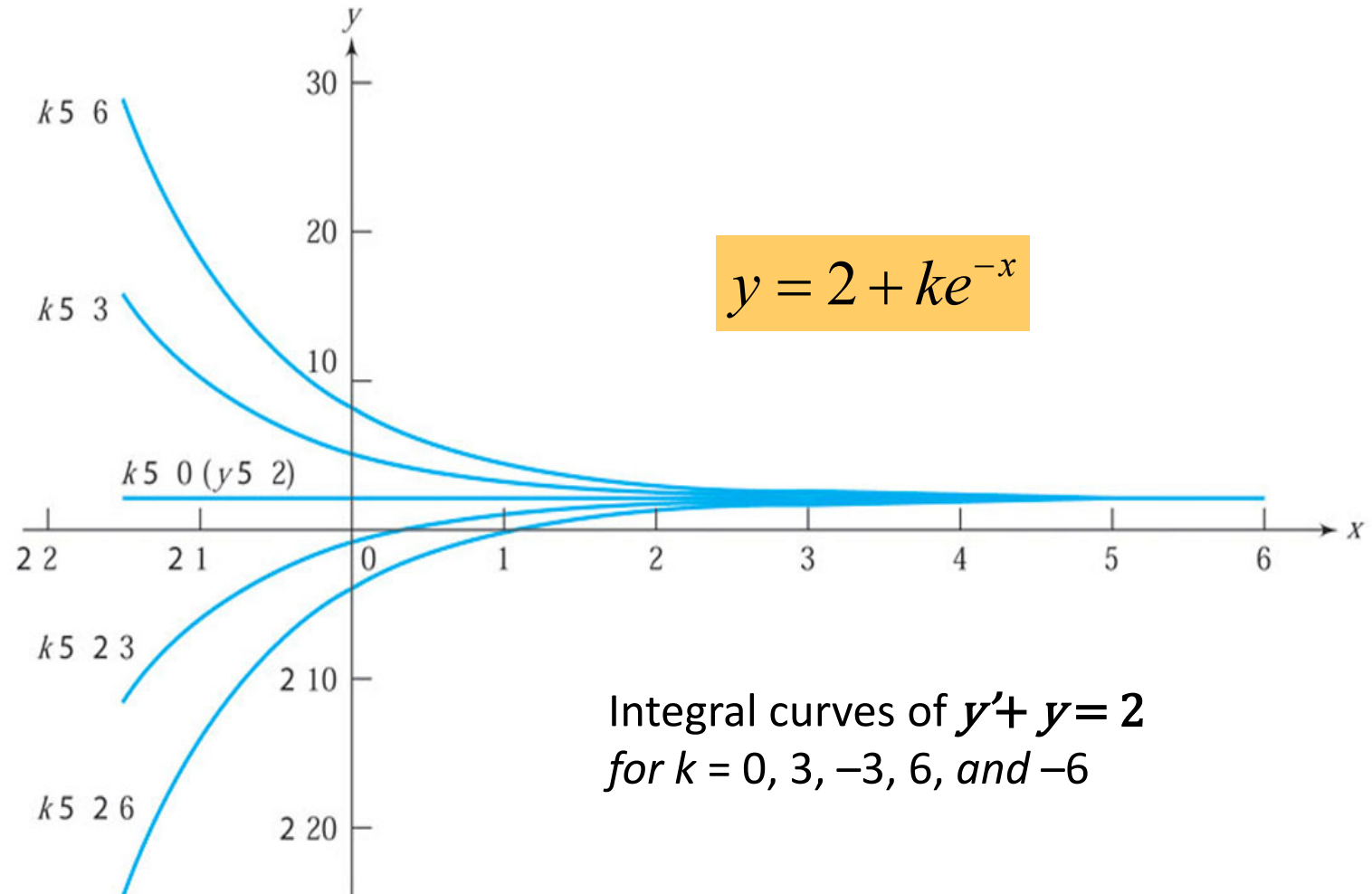
Boundary Condition (BC)

Constraints that are specified at the boundary points, generally space points, are called ***boundary conditions***.

$$\begin{array}{lll} \text{ex.'s:} & z''+z'+z=1 & z(0)=2 \quad z(2)=-1 \\ & f''+f=0 & f(0)=0 \quad f(\pi/2)=1 \end{array}$$

Integral Curves, Solution Curves

- A graph of the solution of an ODE is called a ***solution curve***, or an ***integral curve*** of the equation.
- Help to comprehend the behavior of solution



Families of Solutions

- A solution containing an arbitrary constant (parameter) represents a set $G(x, y, c) = 0$ of solutions to an ODE called a ***one-parameter family of solutions***.
- A solution to an n -th order ODE is a ***n-parameter family of solutions*** $F(x, y, y', \dots, y^n) = 0$.
- Since the parameter can be assigned an infinite number of values, an ODE can have an infinite number of solutions.

Direction Field

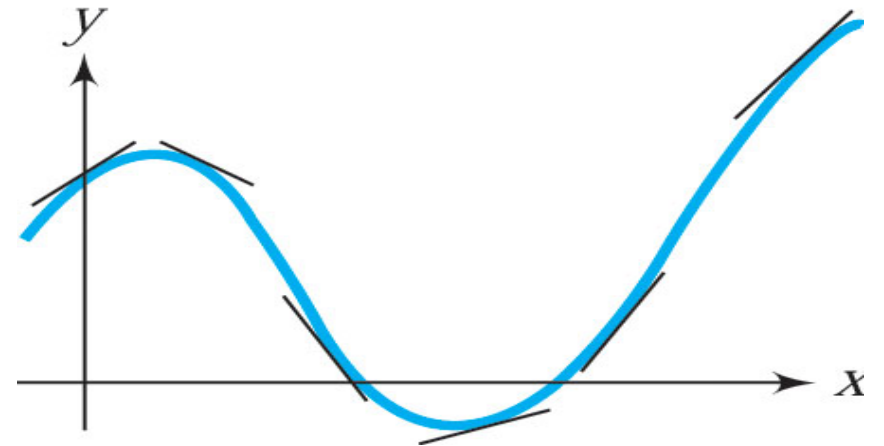
- Suppose we are asked to sketch the graph of the solution of the initial-value problem $y' = f(x, y), y(x_0) = y_0$. The equation tells us that the slope at any point (x, y) on the graph is $f(x, y)$.
- A plot of short line segments drawn at various points in the x, y -plane showing the slope of the solution curve this is called a “*direction field*” for the differential equation.
- The direction field gives us the “*flow of solutions*”.

Direction Field

- We plot small lines representing slopes at each coordinate (x,y) in the xy -plane. From this, we can infer solution curves. Short tangent segments suggest the shape of the curve

- Giving $F(x, y, y') = 0$, instead of solving for y ,

solving for $y' = \frac{dy}{dx} = f(x, y)$ $\begin{cases} \text{slope} \\ \text{direction field} \end{cases}$



Direction Field

ex. 1: Sketch a direction field for $y' = x + y$.

At each (x,y) coordinate, we determine y' . Some examples are:

At $(1,1)$ we have $y' = 2$.

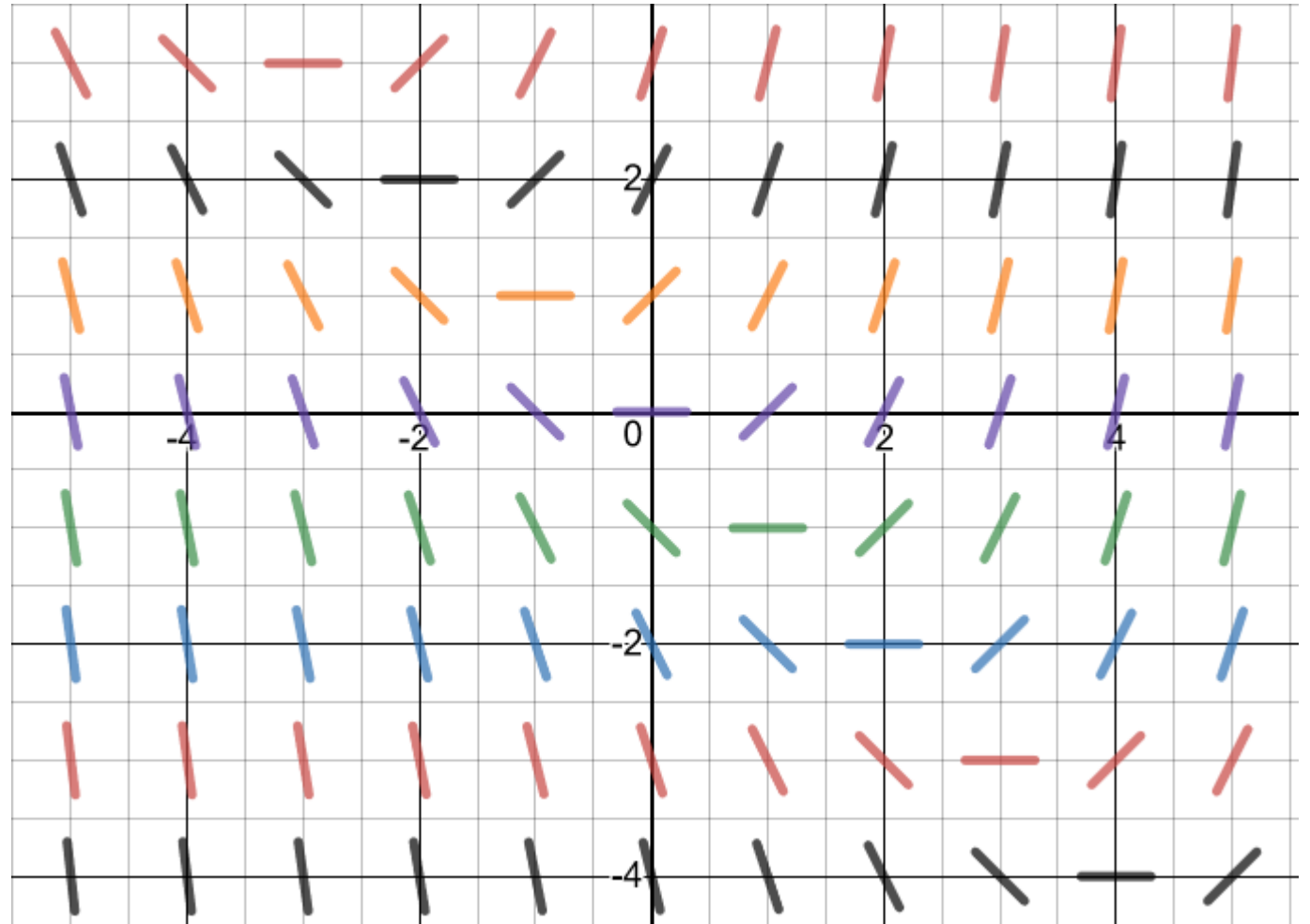
At $(2,-3)$, we have $y' = -1$. And so on.

We do this for “all” possible points in the plane. We get...

example 1: Continuation

Direction field for

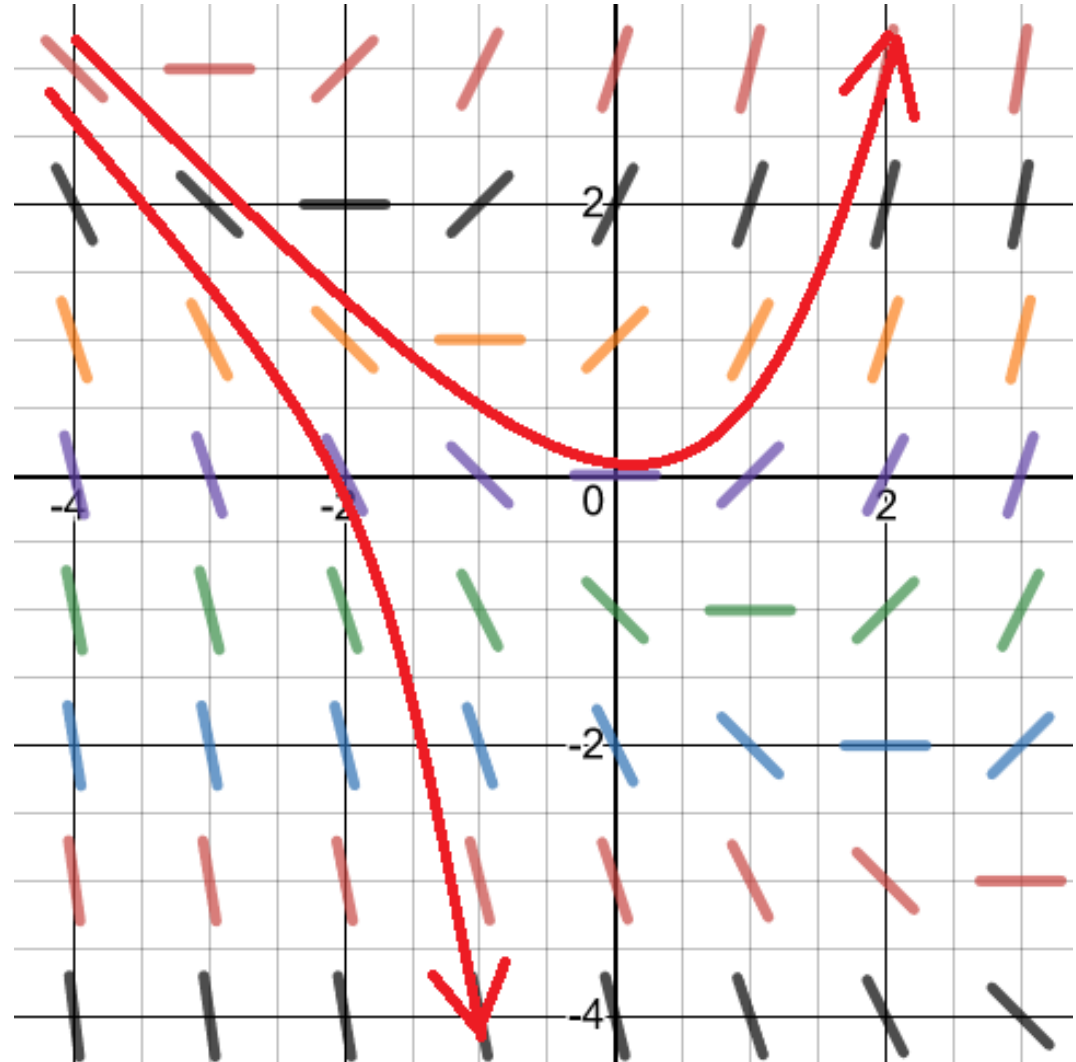
$$y' = x + y$$



ex. 1: Continuation

We can infer possible solution curves.

If you know a point on a particular curve, the rest of the curve can be inferred by “following” the direction field. (*We always read left to right, i.e. x is increasing*).



Direction Field

ex. 2: Sketch the direction field for $y' = y^3 - 4y$.

Hint: note that this only depends on y . Thus, if we find one slope-line for a particular y -value, we can extend it left and right.

Another hint: Note that $y' = 0$ represents a horizontal slope-line and this occurs when $y^3 - 4y = 0$. Factoring, we have

$$y(y^2 - 4) = y(y + 2)(y - 2) = 0.$$

Thus, when $y = 2, -2$ or 0 , then $y' = 0$.

ex. 2: Continuation

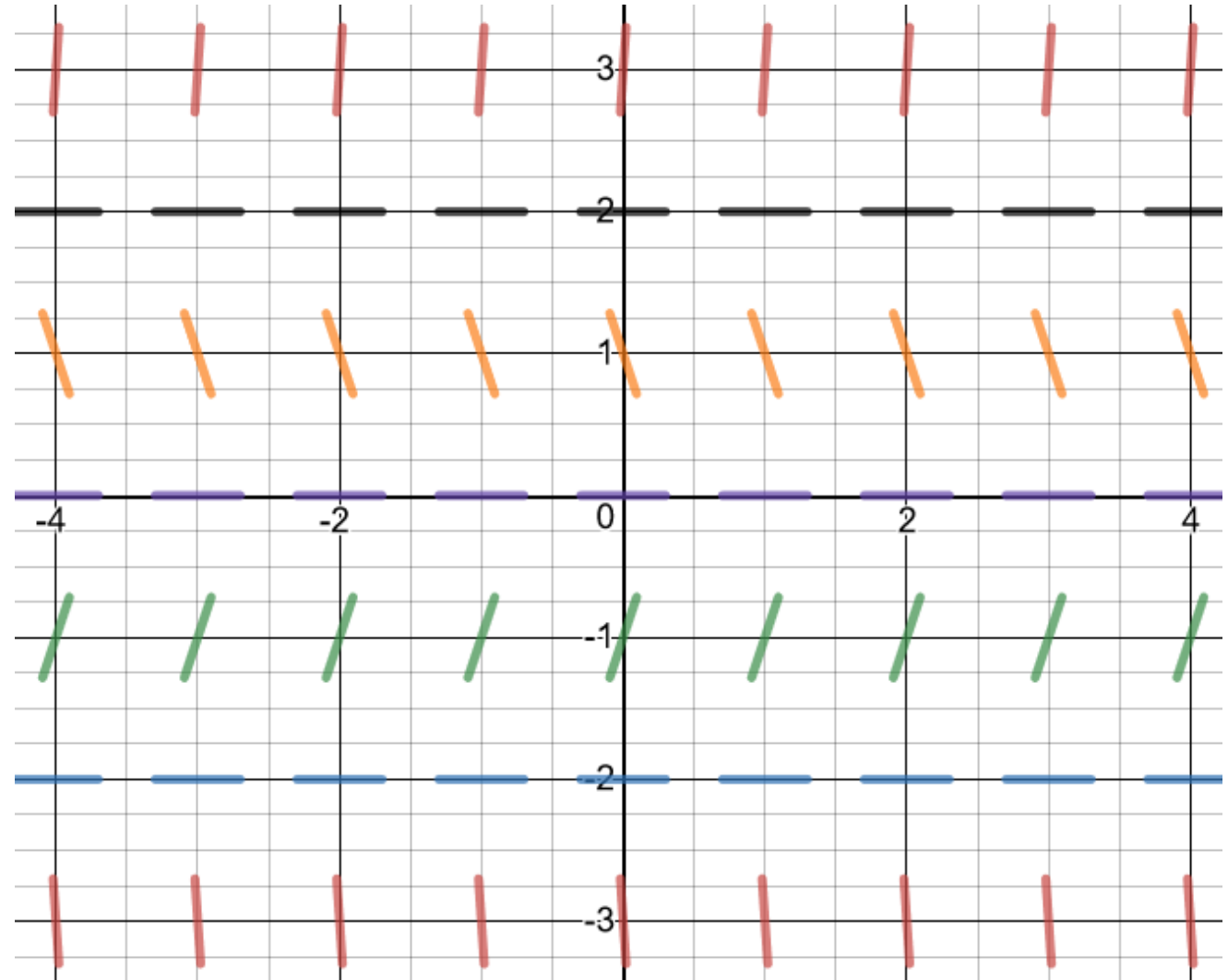
The direction field for

$$y' = y^3 - 4y$$

Note the horizontal slopes when

$y = -2$, $y = 0$ or $y = 2$. These are

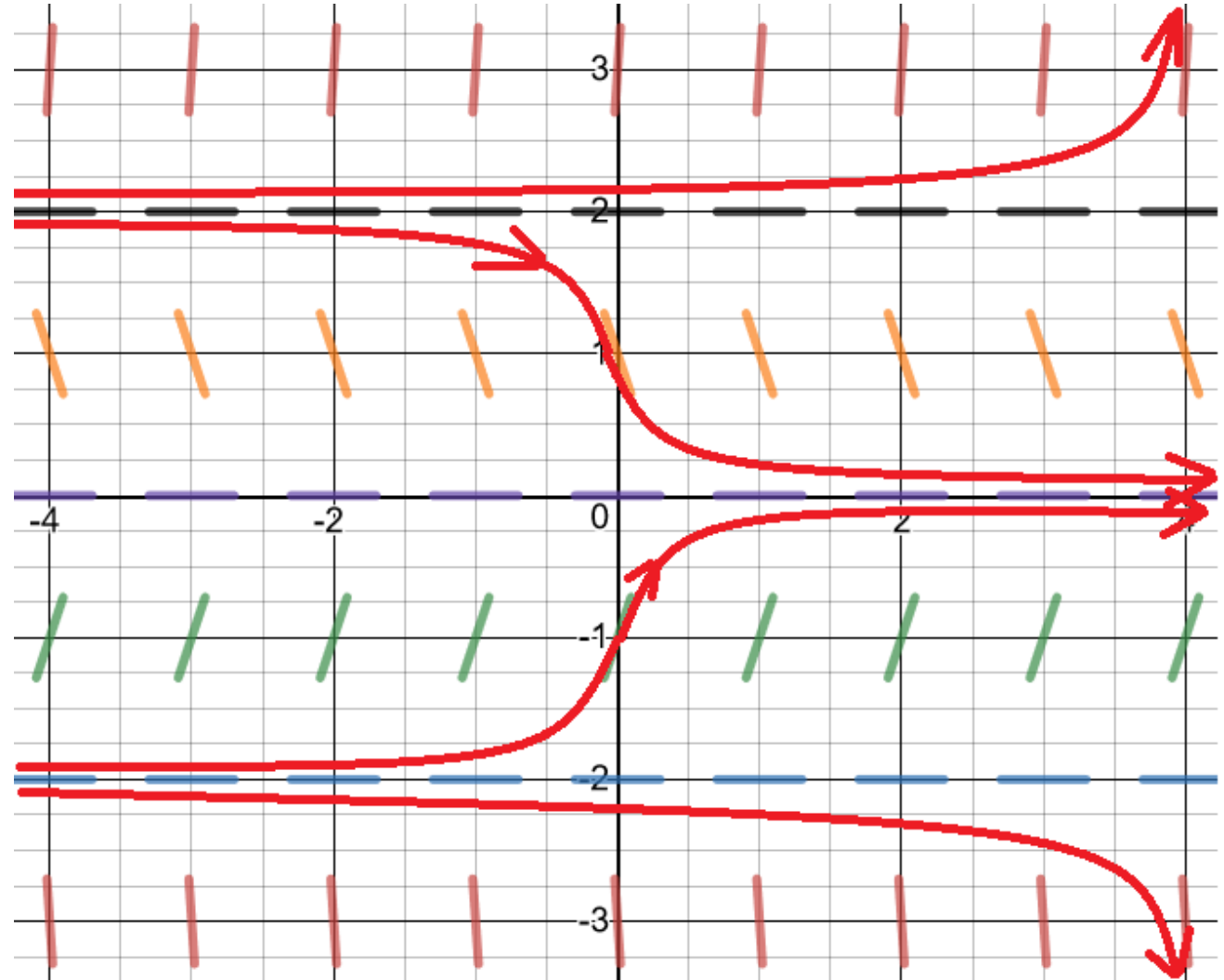
equilibrium solutions.



ex. 2: Continuation

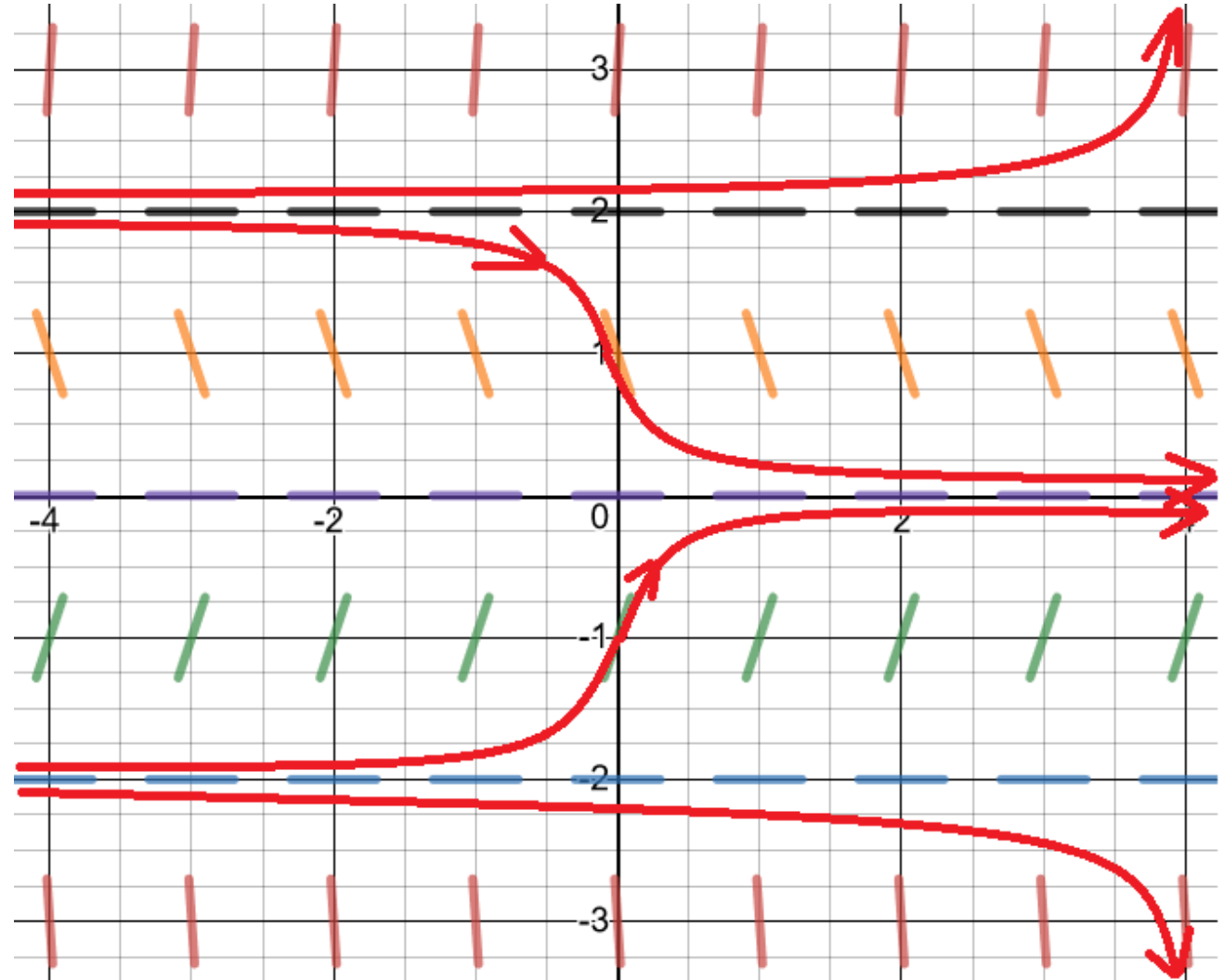
Note how the flow lines (representing possible solution curves) veer towards the equilibrium solution $y = 0$.

Thus, $y = 0$ is a stable equilibrium.



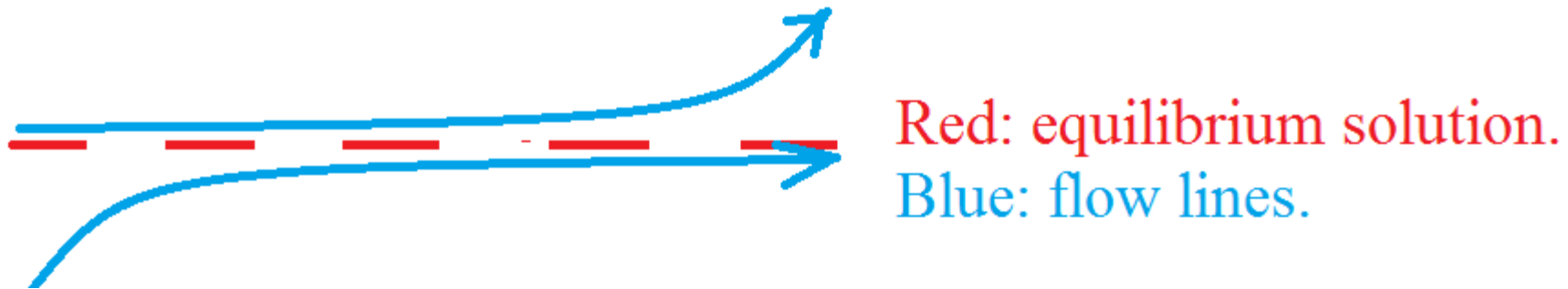
ex. 2: Continuation

The flow lines veer away from the equilibria $y = 2$ and $y = -2$. These are unstable equilibria.



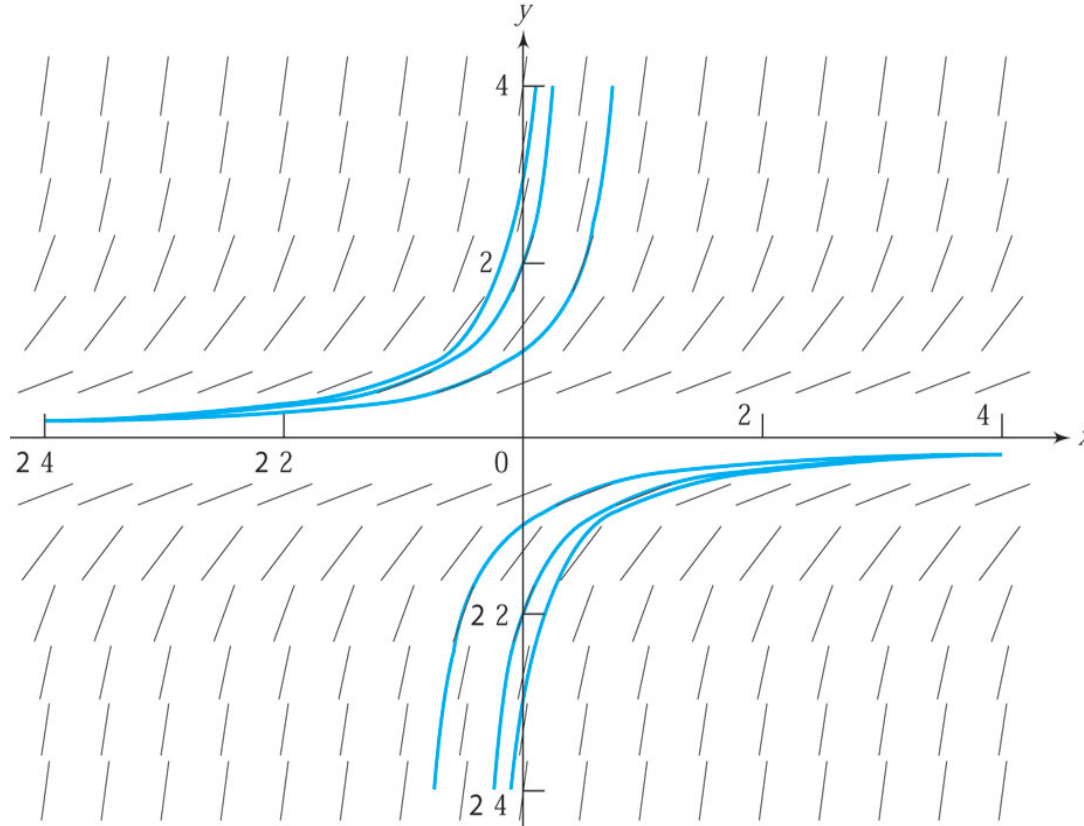
Direction Field

A third type of equilibrium is *semi-stable*, in which the solution curves approach the equilibrium asymptotically from one side, yet veer away from the other.



Direction Field

ex. 3:
 $y' = y^2$



Direction field for $y' = y^2$ and integral curves through $(0, 1)$, $(0, 2)$, $(0, 3)$, $(0, -1)$, $(0, -2)$, and $(0, -3)$.

Slope: y^2
General Solution: $y = -\frac{1}{x + k}$

$$y' = \frac{dy}{dx} = y^2$$

$$y^{-2} dy = dx$$

$$-y^{-1} = x + c$$

$$y = \frac{-1}{x + c}$$

Worksheet 1

Equation	ind. var.	dep. var.	Order	Degree	Linearity	Type
$\left(\frac{dy}{dz}\right)^3 + 2y = 0$						
$\frac{d^2y}{dx^2} + \frac{dy}{dx} = e^x$						
$z^{(iv)} + z'' = 2$						
$p' + ap = bt$						
$f'' + f + g(t) = h(t)$						
$\frac{d^4y}{dt^4} - t\frac{d^2y}{dt^2} + 1 = t^2$						
$u_{xx} + uu_{yy} = \sin t$						
$u_{xx} + \sin u u_{yy} = \cos t$						
$y'' + 3e^y y' - 2t = 0$						
$y'' + 3y' - 2t^2 = 0$						

Worksheet 2

Equation	ind. var.	dep. var.	Order	Degree	Linearity	Type
$\frac{dy}{dx} + x^2y = xe^x$						
$\frac{d^3y}{dt^3} = \sqrt{x+y}$						
$\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = 0$						
$\frac{d^2y}{dx^2} + x \sin y = 0$						
$\frac{d^2y}{dx^2} + y \sin x = 0$						
$\left(\frac{dr}{ds}\right)^3 = \sqrt{\frac{d^2r}{ds^2} + 1}$						
$\frac{\partial^4 u}{\partial x^2 \partial y^2} + \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + u = 0$						
$u_{xx} + \sin u u_{yy} = \cos t$						
$x'' + tx^2 = t$						
$y'' + 3y' + 5x = 0$						

Verification of a solution by substitution

ex. 4: $y'' - 2y' + y = 0; \quad y = xe^x$

$$y' = (x + 1)e^x, \quad y'' = (x + 2)e^x$$

left hand side:

$$y'' - 2y' + y = (xe^x + 2e^x) - 2(xe^x + e^x) + xe^x = 0$$

right-hand side: 0

The DE possesses the constant $y=0 \Rightarrow$ **trivial solution**

Worksheet 2

Check whether the given expression a solution of the corresponding equation?

Equation	Solution to Check
$y'' + 4y = 0$	$y(x) = c_1 \sin 2x + c_2 \cos 2x$
$(y')^4 + y^2 = -1$	$y = x^2 - 1$
$y' = ay, \quad y(0) = 1$	$y(t) = e^{at}$
$y' + y = 10$	$y(t) = 10 - ce - t$
$w_t + 3w_x = 0$	$w(x, t) = 1/(1 + (x - 3t)^2)$
$x'' + 4x = 0$	$x = \cos(2t) + \sin(2t) + c$
$y'' + y = 0$	$y_1(t) = \sin t, y_2(t) = -\cos t, y_3(t) = 2\sin t$
$\frac{dy}{dx} = -\frac{(1 + ye^{xy})}{(1 + xe^{xy})}$	$x + y + e^{xy} = 0$

Simple Integrable Forms

$$b_k \frac{d^k y}{dt^k} = f(t)$$

In theory, this equation may be solved by integrating both sides k times. It may be convenient to introduce new variables so that only first derivative forms need be integrated at each step.

ex. 5:

An object is initially at rest and dropped from a height h at $t = 0$. Determine velocity v and displacement y .

$$\frac{dv}{dt} = g$$

$$dv = gdt$$

$$v = gt + C_1 \quad C_1 = 0 \quad v = gt$$

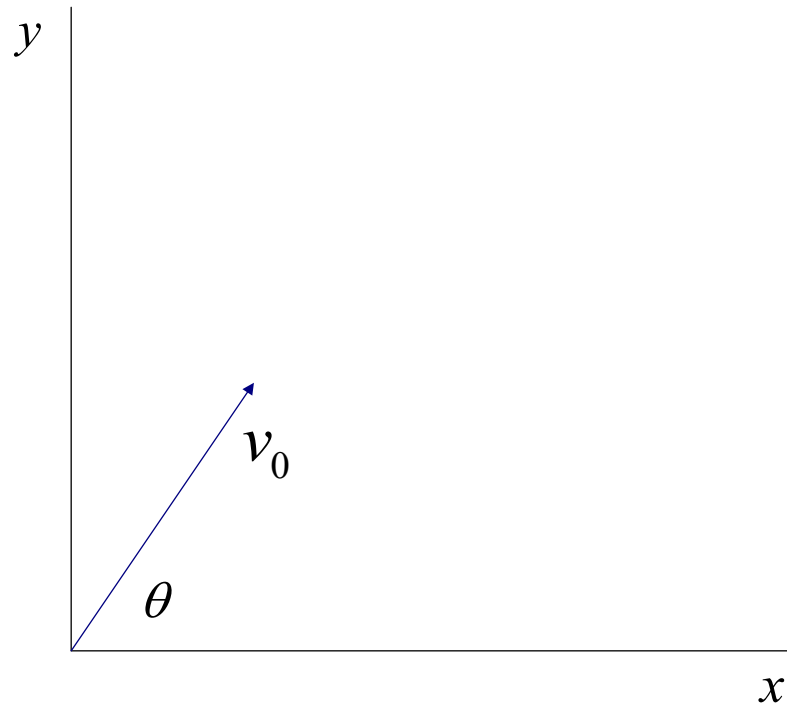
$$\frac{dy}{dt} = gt$$

$$dy = gtdt$$

$$y = \frac{1}{2}gt^2 + C_2 \quad C_2 = 0 \quad y = \frac{1}{2}gt^2$$

ex. 6

Consider situation below and solve for velocity and displacement in both x and y directions.



ex. 6: Continuation

$$\frac{dv_y}{dt} = -g$$

$$v_y = -gt + C_1$$

$$v_y(0) = v_0 \sin \theta \quad C_1 = v_0 \sin \theta \quad v_y = -gt + v_0 \sin \theta$$

$$\frac{dy}{dt} = v_y = -gt + v_0 \sin \theta$$

$$y = -\frac{1}{2}gt^2 + (v_0 \sin \theta)t + C_2$$

$$y(0) = 0$$

$$C_2 = 0 \quad y = -\frac{1}{2}gt^2 + (v_0 \sin \theta)t$$

ex. 6: Continuation

$$\frac{dv_x}{dt} = 0$$

$$v_x = C_3$$

$$v_x(0) = v_0 \cos \theta \quad C_3 = v_0 \cos \theta \quad v_x = v_0 \cos \theta$$

$$\frac{dx}{dt} = v_x = v_0 \cos \theta$$

$$x = (v_0 \cos \theta)t + C_4$$

$$x(0) = 0$$

$$C_4 = 0 \quad x = (v_0 \cos \theta)t$$

Standard Integrals

$f(x)$	$\int f(x)dx$	$f(x)$	$\int f(x)dx$
x^n	$\frac{x^{n+1}}{n+1} \quad (n \neq -1)$	$[g(x)]^n g'(x)$	$\frac{[g(x)]^{n+1}}{n+1} \quad (n \neq -1)$
$\frac{1}{x}$	$\ln x $	$\frac{g'(x)}{g(x)}$	$\ln g(x) $
e^x	e^x	a^x	$\frac{a^x}{\ln a} \quad (a > 0)$
$\sin x$	$-\cos x$	$\sinh x$	$\cosh x$
$\cos x$	$\sin x$	$\cosh x$	$\sinh x$
$\tan x$	$-\ln \cos x $	$\tanh x$	$\ln \cosh x$
$\operatorname{cosec} x$	$\ln \left \tan \frac{x}{2} \right $	$\operatorname{cosech} x$	$\ln \left \tanh \frac{x}{2} \right $
$\sec x$	$\ln \sec x + \tan x $	$\operatorname{sech} x$	$2 \tan^{-1} e^x$
$\sec^2 x$	$\tan x$	$\operatorname{sech}^2 x$	$\tanh x$
$\cot x$	$\ln \sin x $	$\coth x$	$\ln \sinh x $
$\sin^2 x$	$\frac{x}{2} - \frac{\sin 2x}{4}$	$\sinh^2 x$	$\frac{\sinh 2x}{4} - \frac{x}{2}$
$\cos^2 x$	$\frac{x}{2} + \frac{\sin 2x}{4}$	$\cosh^2 x$	$\frac{\sinh 2x}{4} + \frac{x}{2}$

Standard Integrals

$f(x)$	$\int f(x) dx$	$f(x)$	$\int f(x) dx$
$\frac{1}{a^2+x^2}$	$\frac{1}{a} \tan^{-1} \frac{x}{a}$ $(a > 0)$	$\frac{1}{a^2-x^2}$ $\frac{1}{x^2-a^2}$	$\frac{1}{2a} \ln \left \frac{a+x}{a-x} \right \quad (0 < x < a)$ $\frac{1}{2a} \ln \left \frac{x-a}{x+a} \right \quad (x > a > 0)$
$\frac{1}{\sqrt{a^2-x^2}}$	$\sin^{-1} \frac{x}{a}$ $(-a < x < a)$	$\frac{1}{\sqrt{a^2+x^2}}$ $\frac{1}{\sqrt{x^2-a^2}}$	$\ln \left \frac{x+\sqrt{a^2+x^2}}{a} \right \quad (a > 0)$ $\ln \left \frac{x+\sqrt{x^2-a^2}}{a} \right \quad (x > a > 0)$
$\sqrt{a^2-x^2}$	$\frac{a^2}{2} \left[\sin^{-1} \left(\frac{x}{a} \right) + \frac{x\sqrt{a^2-x^2}}{a^2} \right]$	$\sqrt{a^2+x^2}$ $\sqrt{x^2-a^2}$	$\frac{a^2}{2} \left[\sinh^{-1} \left(\frac{x}{a} \right) + \frac{x\sqrt{a^2+x^2}}{a^2} \right]$ $\frac{a^2}{2} \left[-\cosh^{-1} \left(\frac{x}{a} \right) + \frac{x\sqrt{x^2-a^2}}{a^2} \right]$