

ICPC Notebook

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template

hash.sh

```
# 使い方: sh hash.sh -> コピー -> Ctrl + D
# コメント・空白・改行を削除して md5 でハッシュする
g++ -dD -E -fpreprocessed - | tr -d '[:space:]' | md5sum | cut
-c-6
```

settings.sh

```
# CLion の設定
Settings -> Build -> CMake -> Reload CMake Project
add_compile_options(-D_GLIBCXX_DEBUG)
# Caps Lock を Ctrl に変更
setxkbmap -option ctrl:nocaps
```

template.hpp

md5: 365d7f

```
#include <bits/stdc++.h>
using namespace std;
using ll = long long;
const ll INF = LLONG_MAX / 4;
#define rep(i, a, b) for (ll i = a; i < (b); i++)
#define all(a) begin(a), end(a)
ll sz(const auto& a) { return size(a); }
bool chmin(auto& a, auto b) {
    if (a <= b) return 0;
    a = b;
    return 1;
}
bool chmax(auto& a, auto b) {
    if (a >= b) return 0;
    a = b;
    return 1;
}

int main() {
    cin.tie(0)->sync_with_stdio(0);
    // your code here...
}
```

data-structure

BIT.hpp

md5: d8ec49

```
struct BIT {
    vector<ll> a;
    BIT(ll n) : a(n + 1) {}
    void add(ll p, ll x) { // A[p] += x
        p++;
        while (p < sz(a)) {
            a[p] += x;
            p += p & -p;
        }
    }
}
```

```
ll sum(ll r) {
    ll s = 0;
    while (r > 0) {
        s += a[r];
        r -= r & -r;
    }
    return s;
}
ll sum(ll l, ll r) { // sum of A[l, r)
    return sum(r) - sum(l);
}
};
```

FastSet.hpp

md5: fbc0ac

math

modint

BarrettReduction.hpp

md5: b4bd2c

```
using u64 = uint64_t;
struct Barrett { // mod < 2^32
    u64 m, im;
    Barrett(u64 mod) : m(mod), im(-1ULL / m + 1) {}
    // input: a * b < 2^64, output: a * b % mod
    u64 mul(u64 a, u64 b) const {
        a *= b;
        u64 x = ((__uint128_t)a * im) >> 64;
        a -= x * m;
        if ((ll)a < 0) a += m;
        return a;
    }
};
```

modint.hpp

md5: ade70b

```
const ll mod = 998244353;
struct mm {
    ll x;
    mm(ll x_ = 0) : x(x_ % mod) {
        if (x < 0) x += mod;
    }
    friend mm operator+(mm a, mm b) { return a.x + b.x; }
    friend mm operator-(mm a, mm b) { return a.x - b.x; }
    friend mm operator*(mm a, mm b) { return a.x * b.x; }
    friend mm operator/(mm a, mm b) { return a * b.inv(); }
    // 4 行コピー Alt + Shift + クリックで複数カーソル
    friend mm& operator+=(mm& a, mm b) { return a = a.x + b.x; }
    friend mm& operator-=(mm& a, mm b) { return a = a.x - b.x; }
    friend mm& operator*=(mm& a, mm b) { return a = a.x * b.x; }
    friend mm& operator/=(mm& a, mm b) { return a = a * b.inv(); }
}
mm inv() const { return pow(mod - 2); }
mm pow(ll b) const {
    mm a = *this, c = 1;
    while (b) {
        if (b & 1) c *= a;
        a *= a;
        b >>= 1;
    }
    return c;
}
};
```

FPS

FFT.hpp

md5: 39bb1a

```
#include "test/template.hpp"

constexpr pair<ll, ll> inv_gcd(ll a, ll b) {
    a = safe_mod(a, b);
    if (a == 0) return {b, 0};

    ll s = b, t = a;
    ll m0 = 0, m1 = 1;

    while (t) {
```

```

    ll u = s / t;
    s -= t * u;
    m0 -= m1 * u; // |m1 * u| <= |m1| * s <= b

    auto tmp = s;
    s = t;
    t = tmp;
    tmp = m0;
    m0 = m1;
    m1 = tmp;
}
if (m0 < 0) m0 += b / s;
return {s, m0};
}

using ull = uint64_t;
ull floor_sum_unsigned(ull n, ull m, ull a, ull b) {
    ull ans = 0;
    while (true) {
        if (a >= m) {
            ans += n * (n - 1) / 2 * (a / m);
            a %= m;
        }
        if (b >= m) {
            ans += n * (b / m);
            b %= m;
        }

        ull y_max = a * n + b;
        if (y_max < m) break;
        n = (ull)(y_max / m);
        b = (ull)(y_max % m);
        swap(m, a);
    }
    return ans;
}

struct fft_info {
    static constexpr int rank2 = countr_zero_constexpr(mod - 1);
    array<mm, rank2 + 1> root; // root[i]^(2^i) == 1
    array<mm, rank2 + 1> iroot; // root[i] * iroot[i] == 1

    array<mm, max(0, rank2 - 2 + 1)> rate2;
    array<mm, max(0, rank2 - 2 + 1)> irate2;

    array<mm, max(0, rank2 - 3 + 1)> rate3;
    array<mm, max(0, rank2 - 3 + 1)> irate3;

    fft_info() {
        root[rank2] = mm(g).pow((mod - 1) >> rank2);
        iroot[rank2] = root[rank2].inv();
        for (int i = rank2 - 1; i >= 0; i--) {
            root[i] = root[i + 1] * root[i + 1];
            iroot[i] = iroot[i + 1] * iroot[i + 1];
        }

        {
            mm prod = 1, iprod = 1;
            for (int i = 0; i <= rank2 - 2; i++) {
                rate2[i] = root[i + 2] * prod;
                irate2[i] = iroot[i + 2] * iprod;
                prod *= iroot[i + 2];
                iprod *= root[i + 2];
            }
        }
        {
            mm prod = 1, iprod = 1;
            for (int i = 0; i <= rank2 - 3; i++) {
                rate3[i] = root[i + 3] * prod;
                irate3[i] = iroot[i + 3] * iprod;
                prod *= iroot[i + 3];
                iprod *= root[i + 3];
            }
        }
    }
};

void butterfly(vector<mm>& a) {
    int n = int(a.size());
    int h = internal::countr_zero((uint)n);

    static const fft_info<mm> info;

    int len = 1; // a[i, i+(n>>len), i+2*(n>>len), ..] is
    transformed
    while (len < h) {
        if (h - len == 1) {
            int p = 1 << (h - len - 1);
            mm rot = 1;
            for (int s = 0; s < (1 << len); s++) {
                int offset = s << (h - len);
                for (int i = 0; i < p; i++) {
                    auto l = a[i + offset];
                    auto r = a[i + offset + p] * rot;
                    a[i + offset] = l + r;
                    a[i + offset + p] = l - r;
                }
                if (s + 1 != (1 << len)) rot *=
                    info.rate2[countr_zero(~(uint)(s))];
            }
            len++;
        } else {
            int p = 1 << (h - len - 2);
            mm rot = 1, imag = info.root[2];
            for (int s = 0; s < (1 << len); s++) {
                mm rot2 = rot * rot;
                mm rot3 = rot2 * rot;
                int offset = s << (h - len);
                for (int i = 0; i < p; i++) {
                    auto mod2 = 1ULL * mod * mod;
                    auto a0 = 1ULL * a[i + offset].val();
                    auto a1 = 1ULL * a[i + offset + p].val() *
                        rot.val();
                    auto a2 = 1ULL * a[i + offset + 2 * p].val() *
                        rot2.val();
                    auto a3 = 1ULL * a[i + offset + 3 * p].val() *
                        rot3.val();
                    auto a1na3imag = 1ULL * mm(a1 + mod2 - a3).val() *
                        * imag.val();
                    auto na2 = mod2 - a2;
                    a[i + offset] = a0 + a2 + a1 + a3;
                    a[i + offset + 1 * p] = a0 + a2 + (2 * mod2 -
                        (a1 + a3));
                    a[i + offset + 2 * p] = a0 + na2 + a1na3imag;
                    a[i + offset + 3 * p] = a0 + na2 + (mod2 -
                        a1na3imag);
                }
                if (s + 1 != (1 << len)) rot *=
                    info.rate3[countr_zero(~(uint)(s))];
            }
            len += 2;
        }
    }
}

void butterfly_inv(vector<mm>& a) {
    int n = int(a.size());
    int h = internal::countr_zero((uint)n);

    static const fft_info<mm> info;

    int len = h; // a[i, i+(n>>len), i+2*(n>>len), ..] is
    transformed
    while (len) {
        if (len == 1) {
            int p = 1 << (h - len);
            mm irot = 1;
            for (int s = 0; s < (1 << (len - 1)); s++) {
                int offset = s << (h - len + 1);
                for (int i = 0; i < p; i++) {
                    auto l = a[i + offset];
                    auto r = a[i + offset + p];
                    a[i + offset] = l + r;
                    a[i + offset + p] = (ull)(mod + l.val() -
                        r.val()) * irot.val();
                }
                if (s + 1 != (1 << (len - 1))) irot *=
                    info.irate2[countr_zero(~(uint)(s))];
            }
            len--;
        } else {
            int p = 1 << (h - len);
            mm irot = 1, iimag = info.iroot[2];
            for (int s = 0; s < (1 << (len - 2)); s++) {
                mm irot2 = irot * irot;

```

```

    int len = 0; // a[i, i+(n>>len), i+2*(n>>len), ..] is
    transformed
    while (len < h) {
        if (h - len == 1) {
            int p = 1 << (h - len - 1);
            mm rot = 1;
            for (int s = 0; s < (1 << len); s++) {
                int offset = s << (h - len);
                for (int i = 0; i < p; i++) {
                    auto l = a[i + offset];
                    auto r = a[i + offset + p] * rot;
                    a[i + offset] = l + r;
                    a[i + offset + p] = l - r;
                }
                if (s + 1 != (1 << len)) rot *=
                    info.rate2[countr_zero(~(uint)(s))];
            }
            len++;
        } else {
            int p = 1 << (h - len - 2);
            mm rot = 1, imag = info.root[2];
            for (int s = 0; s < (1 << len); s++) {
                mm rot2 = rot * rot;
                mm rot3 = rot2 * rot;
                int offset = s << (h - len);
                for (int i = 0; i < p; i++) {
                    auto mod2 = 1ULL * mod * mod;
                    auto a0 = 1ULL * a[i + offset].val();
                    auto a1 = 1ULL * a[i + offset + p].val() *
                        rot.val();
                    auto a2 = 1ULL * a[i + offset + 2 * p].val() *
                        rot2.val();
                    auto a3 = 1ULL * a[i + offset + 3 * p].val() *
                        rot3.val();
                    auto a1na3imag = 1ULL * mm(a1 + mod2 - a3).val() *
                        * imag.val();
                    auto na2 = mod2 - a2;
                    a[i + offset] = a0 + a2 + a1 + a3;
                    a[i + offset + 1 * p] = a0 + a2 + (2 * mod2 -
                        (a1 + a3));
                    a[i + offset + 2 * p] = a0 + na2 + a1na3imag;
                    a[i + offset + 3 * p] = a0 + na2 + (mod2 -
                        a1na3imag);
                }
                if (s + 1 != (1 << len)) rot *=
                    info.rate3[countr_zero(~(uint)(s))];
            }
            len += 2;
        }
    }
}

void butterfly_inv(vector<mm>& a) {
    int n = int(a.size());
    int h = internal::countr_zero((uint)n);

    static const fft_info<mm> info;

    int len = h; // a[i, i+(n>>len), i+2*(n>>len), ..] is
    transformed
    while (len) {
        if (len == 1) {
            int p = 1 << (h - len);
            mm irot = 1;
            for (int s = 0; s < (1 << (len - 1)); s++) {
                int offset = s << (h - len + 1);
                for (int i = 0; i < p; i++) {
                    auto l = a[i + offset];
                    auto r = a[i + offset + p];
                    a[i + offset] = l + r;
                    a[i + offset + p] = (ull)(mod + l.val() -
                        r.val()) * irot.val();
                }
                if (s + 1 != (1 << (len - 1))) irot *=
                    info.irate2[countr_zero(~(uint)(s))];
            }
            len--;
        } else {
            int p = 1 << (h - len);
            mm irot = 1, iimag = info.iroot[2];
            for (int s = 0; s < (1 << (len - 2)); s++) {
                mm irot2 = irot * irot;

```

```
mm irot3 = irot2 * irot;
int offset = s << (h - len + 2);
for (int i = 0; i < p; i++) {
    auto a0 = 1ULL * a[i + offset + 0 * p].val();
    auto a1 = 1ULL * a[i + offset + 1 * p].val();
    auto a2 = 1ULL * a[i + offset + 2 * p].val();
    auto a3 = 1ULL * a[i + offset + 3 * p].val();

    auto a2na3iimag = 1ULL * mm((mod + a2 - a3) *
iimag.val()).val();

    a[i + offset] = a0 + a1 + a2 + a3;
    a[i + offset + 1 * p] = (a0 + (mod - a1) +
a2na3iimag) * irot.val();
    a[i + offset + 2 * p] = (a0 + a1 + (mod - a2) +
(mod - a3)) * irot2.val();
    a[i + offset + 3 * p] = (a0 + (mod - a1) + (mod
- a2na3iimag)) * irot3.val();
}
if (s + 1 != (1 << (len - 2))) irot *=
info.irate3[countr_zero(~(uint)(s))];
}
len -= 2;
}
}
}

vector<mm> convolution_naive(const vector<mm>& a, const
vector<mm>& b) {
    int n = int(a.size()), m = int(b.size());
    vector<mm> ans(n + m - 1);
    if (n < m) {
        for (int j = 0; j < m; j++) {
            for (int i = 0; i < n; i++) { ans[i + j] += a[i] *
b[j]; }
        }
    } else {
        for (int i = 0; i < n; i++) {
            for (int j = 0; j < m; j++) { ans[i + j] += a[i] *
b[j]; }
        }
    }
    return ans;
}

vector<mm> convolution_fft(vector<mm> a, vector<mm> b) {
    int n = int(a.size()), m = int(b.size());
    int z = (int)internal::bit_ceil((uint)(n + m - 1));
    a.resize(z);
    internal::butterfly(a);
    b.resize(z);
    internal::butterfly(b);
```

```
for (int i = 0; i < z; i++) { a[i] *= b[i]; }
internal::butterfly_inv(a);
a.resize(n + m - 1);
mm iz = mm(z).inv();
for (int i = 0; i < n + m - 1; i++) a[i] *= iz;
return a;
}

vector<mm> convolution(const vector<mm>& a, const vector<mm>&
b) {
    int n = int(a.size()), m = int(b.size());
    if (!n || !m) return {};

    int z = (int)internal::bit_ceil((uint)(n + m - 1));
    assert((mod - 1) % z == 0);

    if (min(n, m) <= 60) return convolution_naive(a, b);
    return internal::convolution_fft(a, b);
}
```

graph
flow

ProjectSelectionProblem.md

変形前の制約	変形後の制約
x が 0 のとき z 失う	(x, T, z)
x が 0 のとき z 得る	無条件で z 得る; (S, x, z)
x が 1 のとき z 失う	(S, x, z)
x が 1 のとき z 得る	無条件で z 得る; (x, T, z)
x, y, \dots がすべて 0 のとき z 得る	無条件で z 得る; $(S, w, z), (w, x, \infty), (w, y, \infty)$
x, y, \dots がすべて 1 のとき z 得る	無条件で z 得る; $(w, T, z), (x, w, \infty), (y, w, \infty)$

string
geometry
memo