

# Team notebook

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## 1 Data Structures

### 1.1 STL PBDS

---

```
// ost = ordered set
// omp = ordered map
#include <ext/pb_ds/assoc_container.hpp>
#include <ext/pb_ds/tree_policy.hpp>

using namespace __gnu_pbds;

template<class T>
using ost = tree<T, null_type, less<T>, rb_tree_tag,
                tree_order_statistics_node_update>;

template<class T, class U>
using omp = tree<T, U, less<T>, rb_tree_tag,
                tree_order_statistics_node_update>;
```

---

## 2 Geometry

### 2.1 Smallest Enclosing Circle

---

```
// Welzl's algorithm to find the smallest circle
```

```

// that encloses a group of points in O(N * ITERS)
// returns {radius, x, y}
const int ITERS = 3e5;
const double INF = 1e12;

tuple<double, double, double> welzl(const vector<pair<int, int>>& points)
{
    double xt = 0, yt = 0;
    for(auto& [x, y] : points)
    {
        xt += x;
        yt += y;
    }
    xt /= points.size();
    yt /= points.size();
    double p = 0.1;
    double mx_d;
    for(int i = 0; i < ITERS; ++i)
    {
        mx_d = -INF;
        int mx_idx = -1;
        for(int j = 0; j < (int) points.size(); ++j)
        {
            double cx = xt - points[j].first;
            double cy = yt - points[j].second;
            double cur = cx * cx + cy * cy;
            if(cur > mx_d)
            {
                mx_d = cur;
                mx_idx = j;
            }
        }
        xt += (points[mx_idx].first - xt) * p;
        yt += (points[mx_idx].second - yt) * p;
        p *= 0.999;
    }
    return {sqrt(mx_d), xt, yt};
}

```

## 3 Graphs

### 3.1 Articulation Point Bridge

```

// gr -> adj list
// vector vis, low -> initialize to -1
// int timer -> initialize to 0
void dfs(int pos, int dad = -1)
{
    vis[pos] = low[pos] = timer++;
    int kids = 0;
    for(auto& i : gr[pos])
    {
        if(i == dad) continue;
        if(vis[i] >= 0)
            low[pos] = min(low[pos], vis[i]);
        else
        {
            dfs(i, pos);
            low[pos] = min(low[pos], low[i]);
            if(low[i] > vis[pos])
                is_bridge(pos, i)
            if(low[i] >= vis[pos] && dad >= 0)
                is_articulation_point(pos)
            ++kids;
        }
    }
    if(dad == -1 && kids > 1)
        is_articulation_point(pos)
}

```

### 3.2 Dinic's Maximum Flow

```

// O(VE log(max_flow)) if scaling == 1
// O((V + E) sqrt(E)) if unit graph (turn scaling off)
// O((V + E) sqrt(V)) if bipartite matching (turn scaling off)
// indices are 0-based
const ll INF = 1e18;

struct Dinic
{

```

```

struct Edge
{
    int v;
    ll cap, flow;
    Edge(int _v, ll _cap) : v(_v), cap(_cap), flow(0) {}
};

int n;
ll lim;
vector<vector<int>> gr;
vector<Edge> e;
vector<int> idx, lv;

bool has_path(int s, int t)
{
    queue<int> q;
    q.push(s);
    lv.assign(n, -1);
    lv[s] = 0;
    while(!q.empty())
    {
        int c = q.front();
        q.pop();
        if(c == t) break;
        for(auto& i : gr[c])
        {
            ll cur_flow = e[i].cap - e[i].flow;
            if(lv[e[i].v] == -1 && cur_flow >= lim)
            {
                lv[e[i].v] = lv[c] + 1;
                q.push(e[i].v);
            }
        }
    }
    return lv[t] != -1;
}

ll get_flow(int s, int t, ll left)
{
    if(!left || s == t) return left;
    while(idx[s] < (int) gr[s].size())
    {
        int i = gr[s][idx[s]];
        if(lv[e[i].v] == lv[s] + 1)

```

```

{
    ll add = get_flow(
        e[i].v,
        t,
        min(left, e[i].cap - e[i].flow)
    );
    if(add)
    {
        e[i].flow += add;
        e[i ^ 1].flow -= add;
        return add;
    }
    ++idx[s];
}
return 0;
}

Dinic(int vertices, bool scaling = 1) // toggle scaling here
    : n(vertices), lim(scaling ? 1 << 30 : 1), gr(n) {}

void add_edge(int from, int to, ll cap, bool directed = 1)
{
    gr[from].push_back(e.size());
    e.emplace_back(to, cap);
    gr[to].push_back(e.size());
    e.emplace_back(from, directed ? 0 : cap);
}

ll get_max_flow(int s, int t) // call this
{
    ll res = 0;
    while(lim) // scaling
    {
        while(has_path(s, t))
        {
            idx.assign(n, 0);
            while(ll add = get_flow(s, t, INF)) res += add;
        }
        lim >>= 1;
    }
    return res;
}
};

```

### 3.3 Edmonds' Blossom

// Maximum matching on general graphs in  $O(V^2 E)$   
 // Indices are 1-based  
 // Stolen from ko\_osaga's cheatsheet

```
struct Blossom
{
    vector<int> vis, dad, orig, match, aux;
    vector<vector<int>> conn;
    int t, N;
    queue<int> Q;

    void augment(int u, int v)
    {
        int pv = v;
        do
        {
            pv = dad[v];
            int nv = match[pv];
            match[v] = pv;
            match[pv] = v;
            v = nv;
        } while(u != pv);
    }

    int lca(int v, int w)
    {
        ++t;
        while(true)
        {
            if(v)
            {
                if(aux[v] == t) return v;
                aux[v] = t;
                v = orig[dad[match[v]]];
            }
            swap(v, w);
        }
    }
}
```

```
void blossom(int v, int w, int a)
{
    while(orig[v] != a)
    {
        dad[v] = w;
        w = match[v];
        if(vis[w] == 1)
        {
            Q.push(w);
            vis[w] = 0;
        }
        orig[v] = orig[w] = a;
        v = dad[w];
    }
}

bool bfs(int u)
{
    fill(vis.begin(), vis.end(), -1);
    iota(orig.begin(), orig.end(), 0);
    Q = queue<int>();
    Q.push(u);
    vis[u] = 0;
    while(!Q.empty())
    {
        int v = Q.front(); Q.pop();
        for(int x : conn[v])
        {
            if(vis[x] == -1)
            {
                dad[x] = v; vis[x] = 1;
                if(!match[x])
                {
                    augment(u, x);
                    return 1;
                }
                Q.push(match[x]);
                vis[match[x]] = 0;
            }
            else if(vis[x] == 0 && orig[v] != orig[x])
            {
                int a = lca(orig[v], orig[x]);
                blossom(x, v, a);
                blossom(v, x, a);
            }
        }
    }
}
```

```

    }
}
}
return false;
}

Blossom(int n) : // n = vertices
    vis(n + 1), dad(n + 1), orig(n + 1), match(n + 1),
    aux(n + 1), conn(n + 1), t(0), N(n)
{
    for(int i = 0; i <= n; ++i)
    {
        conn[i].clear();
        match[i] = aux[i] = dad[i] = 0;
    }
}

void add_edge(int u, int v)
{
    conn[u].push_back(v);
    conn[v].push_back(u);
}

int solve() // call this for answer
{
    int ans = 0;
    vector<int> V(N - 1);
    iota(V.begin(), V.end(), 1);
    shuffle(V.begin(), V.end(), mt19937(0x94949));
    for(auto x : V)
    {
        if(!match[x])
        {
            for(auto y : conn[x])
            {
                if(!match[y])
                {
                    match[x] = y, match[y] = x;
                    ++ans;
                    break;
                }
            }
        }
    }
}

```

```

        for(int i = 1; i <= N; ++i)
        {
            if(!match[i] && bfs(i)) ++ans;
        }
        return ans;
    }
};

```

### 3.4 Eulerian Path or Cycle

---

```

// finds a eulerian path / cycle
// visits each edge only once
// properties:
// - cycle: degrees are even
// - path: degrees are even OR degrees are even except for 2 vertices
// how to use: g = adjacency list g[n] = connected to n, undirected
// if there is a vertex u with an odd degree, call dfs(u)
// else call on any vertex
// ans = path result

```

```

vector<set<int>> g;
vector<int> ans;

```

```

void dfs(int u)
{
    while(g[u].size())
    {
        int v = *g[u].begin();
        g[u].erase(v);
        g[v].erase(u);
        dfs(v);
    }
    ans.push_back(u);
}

```

## 4 Math

### 4.1 Euler's Totient

---

```
// Precompute up to n in O(n log log n)
vector<int> phi_1_to_n(int n)
{
    vector<int> phi(n + 1);
    phi[0] = 0;
    phi[1] = 1;
    for(int i = 2; i <= n; i++)
        phi[i] = i;
    for(int i = 2; i <= n; i++)
        if(phi[i] == i)
            for(int j = i; j <= n; j += i)
                phi[j] -= phi[j] / i;
    return phi;
}

// Calculate for a single n in O(sqrt(n))
ll totient(ll n)
{
    ll res = 1;
    for(ll i = 2; i * i <= n; ++i)
    {
        if(n % i == 0)
        {
            res *= i - 1;
            n /= i;
        }
        while(n % i == 0)
        {
            res *= i;
            n /= i;
        }
    }
    if(n > 1) res *= n - 1;
    return res;
}
```

## 4.2 Extended Euclidean GCD

```
// computes x and y such that ax + by = gcd(a, b) in O(log (min(a, b)))
// returns {gcd(a, b), x, y}
tuple<int, int, int> gcd(int a, int b)
{
```

```
    if(b == 0) return {a, 1, 0};
    auto [d, x1, y1] = gcd(b, a % b);
    return {d, y1, x1 - y1 * (a / b)};
}
```

## 4.3 Fibonacci Check

```
bool is_fibonacci(int n)
{
    return is_perfect_square(5 * n * n + 4)
        || is_perfect_square(5 * n * n - 4);
}
```

## 4.4 Matrix Multiplication

```
using Mat = vector<vector<ll>>;

Mat multiply(const Mat& a, const Mat& b)
{
    assert(a[0].size() == b.size());
    int y = a.size(), x = b[0].size(), n = b.size();
    Mat res(y, vector<ll>(x));
    for(int i = 0; i < y; ++i)
        for(int k = 0; k < n; ++k)
            for(int j = 0; j < x; ++j)
                res[i][j] += a[i][k] * b[k][j];
    return res;
}
```

## 4.5 Miller-Rabin Pollard's Rho

```
namespace MillerRabin
{
    const vector<ll> primes = { // deterministic up to 2^64 - 1
        2, 3, 5, 7, 11, 13, 17, 19, 23, 29, 31, 37
    };
    ll gcd(ll a, ll b)
```

```

{
    return b ? gcd(b, a % b) : a;
}
ll powa(ll x, ll y, ll p) // (x ^ y) % p
{
    if(!y) return 1;
    if(y & 1) return ((__int128) x * powa(x, y - 1, p)) % p;
    ll temp = powa(x, y >> 1, p);
    return ((__int128) temp * temp) % p;
}
bool miller_rabin(ll n, ll a, ll d, int s)
{
    ll x = powa(a, d, n);
    if(x == 1 || x == n - 1) return 0;
    for(int i = 0; i < s; ++i)
    {
        x = ((__int128) x * x) % n;
        if(x == n - 1) return 0;
    }
    return 1;
}
bool is_prime(ll x) // use this
{
    if(x < 2) return 0;
    int r = 0;
    ll d = x - 1;
    while((d & 1) == 0)
    {
        d >>= 1;
        ++r;
    }
    for(auto& i : primes)
    {
        if(x == i) return 1;
        if(miller_rabin(x, i, d, r)) return 0;
    }
    return 1;
}

namespace PollardRho
{
    mt19937_64 generator(chrono::steady_clock::now()
        .time_since_epoch().count());

```

```

uniform_int_distribution<ll> rand_ll(0, LLONG_MAX);
ll f(ll x, ll b, ll n) // (x^2 + b) % n
{
    return (((__int128) x * x) % n + b) % n;
}
ll rho(ll n)
{
    if(n % 2 == 0) return 2;
    ll b = rand_ll(generator);
    ll x = rand_ll(generator);
    ll y = x;
    while(1)
    {
        x = f(x, b, n);
        y = f(f(y, b, n), b, n);
        ll d = MillerRabin::gcd(abs(x - y), n);
        if(d != 1) return d;
    }
}
void pollard_rho(ll n, vector<ll>& res)
{
    if(n == 1) return;
    if(MillerRabin::is_prime(n))
    {
        res.push_back(n);
        return;
    }
    ll d = rho(n);
    pollard_rho(d, res);
    pollard_rho(n / d, res);
}
vector<ll> factorize(ll n, bool sorted = 1) // use this
{
    vector<ll> res;
    pollard_rho(n, res);
    if(sorted) sort(res.begin(), res.end());
    return res;
}
}

```

## 5 Miscellaneous

### 5.1 Dates

#### 5.1.1 Day of Date

---

```
// 0-based
const vector<int> T = {
    0, 3, 2, 5, 0, 3,
    5, 1, 4, 6, 2, 4
}

int day(int d, int m, int y)
{
    y -= (m < 3);
    return (y + y / 4 - y / 100 + y / 400 + T[m - 1] + d) % 7;
}
```

---

#### 5.1.2 Number of Days since 1-1-1

---

```
int rdn(int d, int m, int y)
{
    if(m < 3) --y, m += 12;
    return 365 * y + y / 4 - y / 100 + y / 400
        + (153 * m - 457) / 5 + d - 306;
}
```

---

### 5.2 Enumerate Subsets of a Bitmask

---

```
int x = 0;
do
{
    // do stuff with the bitmask here
    x = (x + 1 + ~m) & m;
} while(x != 0);
```

---

### 5.3 Int to Roman

---

```
const string R[] = {
    "M", "CM", "D", "CD", "C", "XC", "L",
    "XL", "X", "IX", "V", "IV", "I"
};

const int N[] = {
    1000, 900, 500, 400, 100, 90,
    50, 40, 10, 9, 5, 4, 1
};

string to_roman(int x)
{
    if (x == 0) return "0"; // Not decimal 0!
    string res = "";
    for (int i = 0; i < 13; ++i)
        while (x >= N[i]) x -= N[i], res += R[i];
    return res;
}
```

---

### 5.4 Josephus Problem

---

```
ll josephus(ll n, ll k) // O(k log n)
{
    if(n == 1) return 0;
    if(k == 1) return n - 1;
    if(k > n) return (josephus(n - 1, k) + k) % n;
    ll cnt = n / k;
    ll res = josephus(n - cnt, k);
    res -= n % k;
    if(res < 0) res += n;
    else res += res / (k - 1);
    return res;
}

int josephus(int n, int k) // O(n)
{
    int res = 0;
    for(int i = 1; i <= n; ++i)
        res = (res + k) % i;
    return res + 1;
}
```

---



## 6 Strings

### 6.1 Knuth-Morris-Pratt

---

```
// Constructs KMP failure function in O(n)
vector<int> kmp(const string& s)
{
    vector<int> res(s.length());
    int i = 1, j = 0;
    while(i < (int) s.length())
    {
        if(s[i] == s[j]) res[i++] = ++j;
        else if(j > 0) j = res[j - 1];
        else res[i++] = 0;
    }
    return res;
}
```

---

### 6.2 Suffix Array

---

```
struct SuffixArray
{
    int n;
    vector<int> sa, rnk, cnt;
    vector<pair<int, int>> p;
    SuffixArray(const string& s) :
        n(s.length() + 1), sa(n), rnk(n << 1), cnt(max(n, 256)), p(n)
    {
        for(int i = 0; i < n - 1; ++i) rnk[i] = s[i];
        rnk[n - 1] = 0;
        iota(sa.begin(), sa.end(), 0);
        for(int i = 1; i < n; i <= 1) update(i);
    }
    void update(int len)
    {
        sort_sa(len); sort_sa(0);
```

---

```
        for(int i = 0; i < n; ++i) p[i] = {rnk[i], rnk[i + len]};
        auto lst = p[sa[0]];
        rnk[sa[0]] = 0;
        int cur = 0;
        for(int i = 1; i < n; ++i)
        {
            if(lst != p[sa[i]])
            {
                lst = p[sa[i]];
                ++cur;
            }
            rnk[sa[i]] = cur;
        }
    }
    void sort_sa(int offset)
    {
        fill(cnt.begin(), cnt.end(), 0);
        for(int i = 0; i < n; ++i) ++cnt[rnk[i + offset]];
        int sum = 0;
        for(int i = 0; i < (int) cnt.size(); ++i)
        {
            int temp = cnt[i];
            cnt[i] = sum;
            sum += temp;
        }
        vector<int> temp(n);
        for(int i = 0; i < n; ++i)
        {
            int cur = cnt[rnk[sa[i] + offset]]++;
            temp[cur] = sa[i];
        }
        sa = move(temp);
    }
    const int& operator[](int idx) const
    {
        return sa[idx];
    }
};
```

---