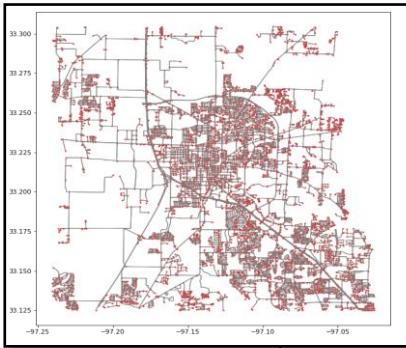
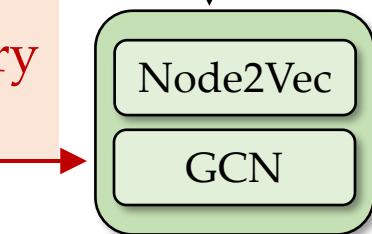


Road network



Input:
Trajectory
 $x_{1:N}$



$$f_{\text{GCN}}(x_{1:N})$$



Positional
encoding

$$+$$

**(a) Location
embedding**

$$\mathbf{H}_{1:N} = [\mathbf{h}_1, \dots, \mathbf{h}_N]$$

Softmax

Fully connected layer

Add & Norm

Feed Forward

Add & Norm

Masked Multi-head Attention

Embedding $f(x_{1:N})$

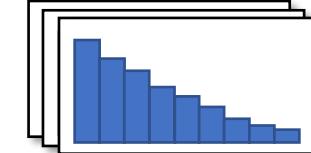
**(b) Location assessment
by transformer encoder**

$$h_{1,n} + \frac{\alpha}{\Delta c_{x_n, v_1}}$$

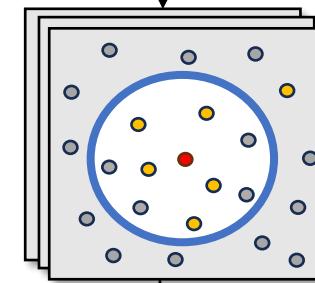
...

$$h_{L,n} + \frac{\alpha}{\Delta c_{x_n, v_L}}$$

Utility loss



Ranking



Location
filtering



Output:
Candidate
locations

**(c) Location ranking
adjusted by utility loss**