

Keshav Bagri

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EDUCATION

Indian Institute of Technology, Kharagpur

B.Tech (Hons.) in Mechanical Engineering [CGPA: 9.21/10 (upto 6 semesters)]

Micro Specialization in Embedded Control, Software, Modelling and Design [CGPA: 9.64/10]

Kharagpur, India

July'18 – May'22

Aditya Academy Secondary

AISSCE (Grade: 93.6%) | CBSE Class X (CGPA: 9.8/10)

Kolkata, India

2016 – 2018

RESEARCH INTERESTS

ADAS | Localization & Mapping | Automotive Engineering | Motion/path Planning | Autonomous Vehicles | Controls

WORK EXPERIENCE

Performance assessment of Driver-in-Loop Simulators

Supervisor: *Dr. Jeffrey P. Chrstos* | *CAR*

The Ohio State University

Feb'21 – Present

- ◊ Reviewed literature for absolute and relative validity of medium fidelity D-i-L simulators for physical validation
- ◊ Proposed the testing methodology for the simulator's platform's motion and analysed the results in essence of the OMCT

Memory footprint & inference time reduction for Deep Learning models

Summer Intern | Mentors: *Ravish Kumar* and *Rahul Jain*

KPIT Technologies Ltd

May'21 – July'21

- ◊ Worked on the comparison between compilers & DL frameworks using pre-trained models for **performance analysis**
- ◊ Generated **deployable executables** using AI compilers like TVM, Glow to substantially reduce memory & inference time
- ◊ Developed a consolidated method of **hardware-specific** deployment of DL models commonly used in automotive applications

SLAM for autonomous cargo delivery vehicles

Winter Intern | Mentor: *Dr. Naveen Arulselvan* | *[Description]*

Ati Motors, Bengaluru

Nov'20 – Jan'21

- ◊ Studied the **OctoMap** mapping and implemented open-source datasets to facilitate better visualization of 3D maps
- ◊ Explored multiple **SLAM algorithms** like IMLS, EKF, Gmapping, etc. to select an efficient method for implementation
- ◊ Implemented the **Particle Filter** SLAM algorithm to build maps on a 2D grid using lidar and wheel odometry in Python
- ◊ Analysed the effects of multiple **resampling algorithms** and variation in **hyperparameters** on the map's quality

Applications of ML methods in motion planning of autonomous vehicles

Supervisors: *Prof. Leena Vachhani* and *Prof. Arpita Sinha* | *[Description]*

ARMS Lab, IIT Bombay

July'20 – Oct'20

- ◊ Formulated the **Markov Decision Process** representation of the scenarios considering different state and action spaces
- ◊ Coded an **automatic controller** in Python to collect real-time client data & images from the CARLA Simulator
- ◊ Generated training datasets for a **RL model** for the safe traversal of an autonomous vehicle in a **campus-like environment**
- ◊ Developed a **Finite State Machine** for lane following & 2-way lane intersection (without traffic signals) management

PROJECTS

TeamKART, Formula SAE | *[Description]* | *[Website]*

Supervisor: *Dr. Dhananjay Kumar Srivastava* | *Mechanical Engineering Department*

IIT Kharagpur

June'19 – Present

- ◊ Worked on the design of a custom **reactive muffler** for noise reduction from a vehicle, with an insertion loss of **25 dB**
- ◊ Designed the **fuel tank** and the mounting arrangement for the vehicle considering the optimal capacity requirement
- ◊ Designed and analyzed the components of the **transmission** and **cooling system** for a standard FSAE electric vehicle
- ◊ Engineered the **intake manifold & crossflow radiator** for a single cylinder engine, producing a power output of **35 HP**
- ◊ Performed **engine simulations** in Ricardo WAVE and **CFD analysis** using Ansys Fluent for designing the intake manifold

Fault Tolerant Controller for Electric Vehicles | *[Bachelor's Thesis Project]*

Supervisor: *Dr. Somnath Sengupta* | *Advanced Technology Development Center*

IIT Kharagpur

Feb'21 – Present

- ◊ Developed a non-linear **state estimator** using equations for vehicle dynamics to produce reliable estimates of vehicle's states
- ◊ Currently working on the implementation of **E - Limited Slip Differential** for controlled torque transfer to the wheels
- ◊ Worked on the modelling of integrated **ABS & regenerative braking** for efficient braking & max energy recuperation
- ◊ Prepared the complete **electro-mechanical** model for a RWD EV for analysing the effect of faults & the control strategy
- ◊ Studied various EV and HEV architectures along with powertrain and vehicle dynamics control systems required for modelling

Mathematical modelling of Li-ion batteries focusing on Si anode particles

Supervisor: *Dr. Jeevanjyoti Chakraborty* | *Mechanical Engineering Department* | *[Description]*

IIT Kharagpur

Feb'20 – Jan'21

- ◊ Studied the mechanics behind **crack development** and formation of amorphous lithiated Si with time around the Si anode
- ◊ Solved Ordinary and Partial differential equations, using **Finite Difference & Liebmman's methods**, in Python
- ◊ Established a **two-way coupling** relation between diffusion & stress, to understand the effect of one parameter on the other

Self-driving Cars Specialization, Coursera

University of Toronto

Supervisors: *Prof. Steven Waslander and Prof Jonathan Kelly* | [\[Description\]](#) | [GitHub](#)

Apr'20 – June'20

- ◇ Implemented & tested control algorithms like **LQR**, **PID**, **Stanley**, **Pure Pursuit** & **MPC** for autonomous vehicle control
- ◇ Designed an **EKF** for state estimation & localization of an autonomous vehicle using **IMU**, **GPS** & **LIDAR** sensor data
- ◇ Estimated the **drivable space**, **lane** and **distance to obstacles** using the segmented image from a **CNN model**
- ◇ Developed the **behavioral & local planners** to generate a collision-free path, using **conformal lattice planning**

Traffic Sign Classification using CNN

[Self Project]

[\[Description\]](#) | [GitHub](#)

July'20

- ◇ Deployed a CNN model with layers including a dropout rate of **40%** for identifying **43** different classes of **traffic signs**
- ◇ Trained the model for **100 epochs** on a dataset of **32x32 RGB** images with a testing accuracy of **94%** on **12000** images

Deep Reinforcement Learning for Autonomous vehicles

[Self Project]

[\[Description\]](#) | [GitHub](#)

Aug'20 – Sep'20

- ◇ Deployed a **Dueling DNN** to predict discrete action values & mapped them to continuous signals for vehicle control
- ◇ Used **84x84 RGB** images for the environment perception as the state information collected from the camera sensor
- ◇ Accommodated the wheel odometry, collision & lane invasion sensor data to compute **real-time reward** for the agent

TECHNICAL SKILLS

Programming: C/C++, Git, Python, MATLAB, LaTeX, Arduino, ROS, Atmel Studio

Softwares: SOLIDWORKS, Ansys, MATLAB/Simulink, CARLA Simulator, Autodesk Fusion 360, COMSOL, Ricardo WAVE

Libraries: NumPy, SciPy, Pillow, SymPy, Matplotlib, OpenCV, TensorFlow, Keras, CARLA

COMPETITIONS

Inter IIT Tech Meet 9.0

Virtual Event hosted by IIT Guwahati

[\[Problem Statement\]](#) | [\[Design Presentation\]](#)

Mar'21

- ◇ Secured the **Gold** medal in the event, "**Bosch's Electric Vehicle Simulation**" for the proposed solution
- ◇ Proposed the **powertrain architecture** comprising a PMSM motor (self-designed), ABS, VSC, etc.
- ◇ Determined the motor's requirements & battery pack's capacity based on target performance parameters using **Simulink**

4th Annual FSEV Concept Challenge 2020

Virtual Event hosted by Ather Energy

[\[Link\]](#) | [\[Design Presentation\]](#)

July'20

- ◇ Secured an overall **5th place** among **37** teams
- ◇ Received a Notable mention: **Fresher Team Effort - Engineering Design**
- ◇ Stood **2nd** in **EV Presentation** & **4th** in **Powertrain package design** among **37** participant teams internationally

Formula Bharat 2020

Coimbatore, India

Kari Motor Speedway | [\[Link\]](#)

Jan'20

- ◇ Secured an **overall 10th Place** in **Combustion Category**, among **50** teams
- ◇ Secured **6th place** in **Engineering Design Event** & **15th place** in **Cost and Manufacturing Event**
- ◇ 1 of the 3 teams to clear the stringent Technical Inspection including mechanical scrutiny and tilt test on **Day 1**

RELEVANT COURSEWORK

University: Mechanics, Dynamics, Transform Calculus, Probability & Statistics, Embedded Control Systems, Programming & Data Structures, Embedded Sensing, Actuation & Interfacing System, Principles of Automotive Dynamics & Controls

MOOC: Algorithms for Battery Management Systems Spl., Data Structures*, Reinforcement Learning Spl., Self-Driving Cars Spl., Convolutional Neural Networks, Neural Networks and Deep Learning, Machine Learning

POSITIONS OF RESPONSIBILITY

Deputy Team Leader

IIT Kharagpur

TeamKART, Formula SAE

July'20 – Present

- ◇ Leading a dedicated team of **47** students towards the research & development of Formula Student prototype vehicle
- ◇ Responsible for the project management & sponsorship initiatives to ensure the timely completion of the team's preset targets
- ◇ Prepared the design & manufacturing timeline and procurement plan to ensure a smooth & efficient workflow for project **K6**

Powertrain & Corporate Relations Team Member

IIT Kharagpur

TeamKART, Formula SAE

July'19 – July'20

- ◇ Responsible for the design, analysis, and testing of the powertrain components in the FSAE prototype vehicle
- ◇ Involved in the training of **30** freshers in basic automotive engineering, powertrain technology, and aspects of manufacturing
- ◇ Acquired monetary as well as technical sponsorships worth **INR 1,10,000** for the season 2019-20