Keshav Bagri

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EDUCATION

Indian Institute of Technology, Kharagpur   **Kharagpur, India**
*B.Tech (Hons.) in Mechanical Engineering [CGPA: **9.21/10** (upto 6 semesters)]*   *July'18 – May'22*
*Micro Specialization in Embedded Control, Software, Modelling and Design [CGPA: **9.64/10**]*

Aditya Academy Secondary   **Kolkata, India**
*AISSCE (Grade: **93.6%**) | CBSE Class X (CGPA: **9.21/10**)*   *2016 – 2018*

RESEARCH INTERESTS

ADAS | Localization & Mapping | Motion/path Planning | Autonomous Vehicles | Automotive Engineering | Controls

RESEARCH EXPERIENCE

Performance assessment of Driver-in-Loop Simulators   **The Ohio State University**
Supervisor: Dr. Jeffrey P. Chrstos | CAR   *Feb'20 – Present*
- ◇ Reviewed literature for absolute and relative validity of medium fidelity D-i-L simulators for physical validation
- ◇ Proposed the testing methodology for the simulator's platform's motion and analysed the results in essence of the OMCT

Memory footprint and inference time reduction for DL models   **KPIT Technologies Ltd, Pune**
Summer Intern   *May'21 – Present*
- ◇ Currently working on the comparison between compilers & DL frameworks using pre-trained models for performance review
- ◇ Generated deployable executables using AI compilers like TVM leading to a substantial reduction in memory & inference time

SLAM for autonomous cargo delivery vehicles   **Ati Motors, Bengaluru**
Winter Intern | [Description]   *Nov'20 – Jan'21*
- ◇ Studied the **OctoMap** mapping and implemented open-source datasets to facilitate better visualization of 3D maps
- ◇ Explored multiple **SLAM algorithms** like IMLS, EKF, Gmapping, etc. to select an efficient method for implementation
- ◇ Implemented the **Particle Filter** SLAM algorithm to build maps on a 2D grid using lidar and wheel odometry in Python
- ◇ Analysed the effects of multiple **resampling algorithms** and variation in hyperparameters on the map's quality

Applications of ML methods in motion planning of autonomous vehicles   **IIT Bombay**
Supervisors: Prof. Leena Vachhani and Prof. Arpita Sinha | ARMS Lab | [Description]   *July'20 – Oct'20*
- ◇ Formulated the **Markov Decision Process** representation of the scenarios considering different state and action spaces
- ◇ Coded an **automatic controller** in Python to collect real-time client data & images from the CARLA Simulator
- ◇ Generated training datasets for a **RL model** for the safe traversal of an autonomous vehicle in a **campus-like environment**
- ◇ Developed a **Finite State Machine** for lane following & 2-way lane intersection (without traffic signals) management

Autonomous Drone & Rover Prototype development, & automated agriculture   **Kanan Park, Pune**
Research & Development Intern | [Description]   *June'20 – Aug'20*
- ◇ Developed the code for ArUco marker based **autonomous landing of a drone** using image processing in Raspberry Pi
- ◇ Formulated the conceptual model with update algorithm & reward function for the **RL based landing** sequence of the drone
- ◇ Devised the code & components of a GSM-based remotely controlled **motorised water flow system** for use in farms

PROJECTS

TeamKART, Formula SAE | [Description] | [Website]   **IIT Kharagpur**
Supervisor: Dr. Dhananjay Kumar Srivastava | Mechanical Engineering Department   *June'19 – Present*
- ◇ Worked on the designing of a **reactive muffler** for noise reduction from a combustion vehicle, with an insertion loss of **25 dB**
- ◇ Designed the **fuel tank** and the mounting arrangement for the vehicle considering the optimal capacity requirement
- ◇ Designed and analyzed the components of the **transmission** and **cooling system** for a standard FSAE electric vehicle
- ◇ Engineered the **intake manifold** & **downflow radiator** for a single cylinder engine, producing a power output of **35 HP**

Mathematical modelling of Li-ion batteries focusing on Si anode particles   **IIT Kharagpur**
Supervisor: Dr. Jeevanjyoti Chakraborty | Mechanical Engineering Department | [Description]   *Feb'20 – Jan'21*
- ◇ Studied the mechanics behind **crack development** and formation of amorphous lithiated Si with time around the Si anode
- ◇ Solved Ordinary and Partial differential equations, using **Finite Difference & Liebmann's methods**, in Python
- ◇ Established a **two-way coupling** between diffusion & stress, to understand the effect of one parameter on the other

Fault Tolerant Controller for Electric Vehicles   **IIT Kharagpur**
Supervisor: Dr. Somnath Sengupta | Advanced Technology Development Center   *Feb'21 – Present*
- ◇ Currently working on the modelling of integrated ABS & regenerative braking for efficient braking & max energy recuperation
- ◇ Prepared the complete vehicle dynamics model for a RWD EV for analysing the effect of faults & the control strategy
- ◇ Studied various EV and HEV architectures along with powertrain and vehicle dynamics control systems required for modelling

Self-driving Cars Specialization, Coursera   **University of Toronto**
Supervisors: Prof. Steven Waslander and Prof Jonathan Kelly | [Description] | GitHub   *Apr'20 – June'20*

- ◇ Implemented & tested control algorithms like **LQR, PID, Stanley, Pure Pursuit** & **MPC** for autonomous vehicle control
- ◇ Designed an **EKF** for state estimation & localization of an autonomous vehicle using **IMU, GPS** & **LIDAR** sensor data
- ◇ Estimated the **drivable space**, **lane** and **distance to obstacles** using the segmented image from a **CNN model**
- ◇ Developed the **behavioral & local planners** to generate a collision-free path, using **conformal lattice planning**

Traffic Sign Classification using CNN   **[Self Project]**
[Description] | GitHub   *July'20*

- ◇ Deployed a CNN model with layers including a dropout rate of **40%** for identifying **43** different classes of **traffic signs**
- ◇ Trained the model for **100 epochs** on a dataset of **32x32 RGB** images with a testing accuracy of **94%** on **12000** images

Deep Reinforcement Learning for Autonomous vehicles   **[Self Project]**
[Description] | GitHub   *Aug'20 – Sep'20*

- ◇ Deployed a **Dueling DNN** to predict discrete action values & mapped them to continuous signals for vehicle control
- ◇ Used **84x84 RGB** images for the environment perception as the state information collected from the camera sensor
- ◇ Accommodated the wheel odometry, collision & lane invasion sensor data to compute real-time reward for the agent

TECHNICAL SKILLS

Programming: C/C++, Git, Python, MATLAB, LaTex, Arduino, ROS, Atmel Studio
Softwares: SOLIDWORKS, Ansys, MATLAB/Simulink, CARLA Simulator, Autodesk Fusion 360, COMSOL, Ricardo WAVE
Libraries: NumPy, SciPy, Pillow, SymPy, Matplotlib, OpenCV, TensorFlow, Keras, CARLA

COMPETITIONS

Inter IIT Tech Meet 9.0   **Virtual Event hosted by IIT Guwahati**
[Problem Statement] | [Design Presentation]   *Mar'21*

- ◇ Secured the **Gold** medal in the event, "**Bosch's Electric Vehicle Simulation**" for the proposed solution
- ◇ Proposed the **powertrain architecture** comprising a PMSM motor (self-designed), ABS, VSC, etc.
- ◇ Determined the motor's requirements & battery pack's capacity based on target performance parameters using **Simulink**

4th Annual FSEV Concept Challenge 2020   **Virtual Event hosted by Curiosum Tech**
[Link]   *July'20*

- ◇ Secured an overall **5th place** among **37** teams
- ◇ Received a Notable mention: **Fresher Team Effort - Engineering Design**
- ◇ Stood **2nd** in **EV Presentation** & **4th** in **Powertrain package design** among **37** participant teams internationally

Formula Bharat 2020   **Coimbatore, India**
Kari Motor Speedway | [Link]   *Jan'20*

- ◇ Secured an **overall 10th Place** in **Combustion Category**, among **50 teams**
- ◇ Secured **6th place** in **Engineering Design Event** & **15th place** in **Cost and Manufacturing Event**
- ◇ **1** of the 3 teams to clear the stringent Technical Inspection including mechanical scrutiny and tilt test on **Day 1**

RELEVANT COURSEWORK

University: Mechanics, Dynamics, Transform Calculus, Probability & Statistics, Embedded Control Systems, Programming & Data Structures, Embedded Sensing, Actuation & Interfacing System, Principles of Automotive Dynamics & Controls

MOOC: Algorithms for Battery Management Systems Spl., Data Structures*, Reinforcement Learning Spl., Self-Driving Cars Spl., Convolutional Neural Networks, Neural Networks and Deep Learning, Machine Learning

POSITIONS OF RESPONSIBILITY

Deputy Team Leader   **IIT Kharagpur**
TeamKART, Formula SAE   *July'20 – Present*

- ◇ Leading a dedicated team of **47** students towards the research & development of Formula Student prototype vehicle
- ◇ Responsible for the project management & sponsorship initiatives to ensure the timely completion of the team's preset targets
- ◇ Prepared the design & manufacturing timeline and procurement plan to ensure a smooth & efficient workflow for project **K6**

Powertrain & Corporate Relations Team Member   **IIT Kharagpur**
TeamKART, Formula SAE   *July'19 – July'20*

- ◇ Responsible for the design, analysis, and testing of the powertrain components in the FSAE prototype vehicle
- ◇ Involved in the training of **30** freshers in basic automotive engineering, powertrain technology, and aspects of manufacturing
- ◇ Acquired monetary as well as technical sponsorships worth **INR 1,10,000** for the season 2019-20