MAT311: Abstract Algebra

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## **Preface**

These lecture notes were taken in the course MAT311: Abstract Algebra taught by Arnab Chakraborty at BRAC University as part of the BSc. in Mathematics program Fall 2024.

These notes are not endorsed by the lecturer, and I often modified them after lectures. They are not accurate representations of what was actually lectured, and in particular, all errors are surely mine. If you find anything that needs to be corrected or improved, please inform me: mh.turjoy@yahoo.com.

— Mahmudul Hasan Turjoy

Lecture 0

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23 Oct 2024

## **0.1** $\mathbb{Z}/n\mathbb{Z}$ : The Integers Modulo n

 $\mathbb{Z} = \text{Set of integers.}$ 

Define a relation on  $\mathbb{Z}$  by -

$$a \sim b$$
 if  $n \mid (a - b)$ .

Properties of this relation:

- $a \sim a$  (Reflexivity)
- $a \sim b \Rightarrow b \sim a$  (Symmetry)
- $a \sim b, b \sim c \Rightarrow a \sim c$  (Transitivity)

Hence, this is an equivalence relation.

If  $a \sim b$ , we say b is congruent to a modulo n and denote as  $a \equiv b \pmod{n}$ .

Let  $\overline{a} := \text{The set of all integers congruent to } a \mod n$ , then  $\overline{a} = \{a + kn : k \in \mathbb{Z}\}$  is called equivalence class / congruence class / residue class of  $a \mod n$ .

There are precisely n distinct equivalence classes mod n, namely

$$\overline{0}, \overline{1}, \overline{2}, ..., \overline{n-1}.$$

**Example.**  $\mathbb{Z}/4\mathbb{Z} = \{\overline{0}, \overline{1}, \overline{2}, \overline{3}\}.$ 

Define an addition on  $\mathbb{Z}/n\mathbb{Z}$  via -

$$\overline{a} \oplus \overline{b} = \overline{a+b}$$

**Example.**  $\mathbb{Z}/3\mathbb{Z} = \{\overline{0}, \overline{1}, \overline{2}\}.$ 

$$\begin{array}{c|cccc} \oplus & \overline{0} & \overline{1} & \overline{2} \\ \hline \overline{0} & \overline{0} & \overline{1} & \overline{2} \\ \overline{1} & \overline{1} & \overline{2} & \overline{0} \\ \overline{2} & \overline{2} & \overline{0} & \overline{1} \\ \end{array}$$

Notice that for all  $a, b \in \mathbb{Z}/3\mathbb{Z}$  the following properties hold:

- $(a \oplus b) \in \mathbb{Z}/3\mathbb{Z}$  (Closure).
- $(a \oplus b) \oplus c = a \oplus (b \oplus c)$  (Associativity).
- $a \oplus \overline{0} = \overline{0} \oplus a = a$  (Identity element).
- For all  $a \in \mathbb{Z}/3\mathbb{Z}$ , there exists  $b \in \mathbb{Z}/3\mathbb{Z}$  such that  $a \oplus b = b \oplus a = \overline{0}$  (Inverse element).

These properties hold for  $\mathbb{Z}/n\mathbb{Z}$  in general.

Now let's move on to a totally different kind of set.

## 0.2 Rotational Symmetries of an Equilateral Triangle

Consider the set of all roational symmetries of an equilateral triangle.

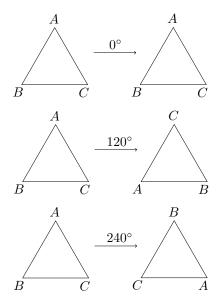


Figure 1: Symmetries of Triangle

A symmetry is something we do to an object that leaves the object intact. In case of the equilateral triangle we have three roational symmetries: roatation by 0°,120° and 240°. The operation here is to compose two symmetries, meaning apply one after another. Notice, composition of two symmetries is again a symmetry (Closure). Composition of three symmetries is associative, because we really applying symmetries from the left to right (Associativity). We consider rotation by 0° or 'do nothing' is also a symmetry. When we compose this with another symmetry, the other symmetry is unchanged (Identity). Finally, given any symmetry, we can undo the symmetry (Inverse elemnet).

Although, our earlier example of  $\mathbb{Z}/3\mathbb{Z}$  and the Symmetries of a triangle is totally different set, both share four common properties.

A set equipped with an operation that follows these four properties is called a *Group*.

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28 Oct 2024

"The axioms for a groups are short and natural... Yet somehow hidden behind these axioms is the monster simple group, a huge and extraordinary mathematical object, which appears to rely on numerous bizzare coincidences to exists. The axioms for groups give no obvious hint that anything like this exits."

— Richard Borcherds, Mathematicians: An Outer View...

"The one thing I would really like to know before I die is why the monster group exists."

— John Conway, in a 2014 interview on Numberphile

## 1.1 Groups

**Definition 1** (Binary Operation). A binary operation \* on a set G is a function  $*: G \times G \longrightarrow G$ . For any  $a, b \in G$ , we will write a\*b for \*(a,b).

**Example.** Modular addition on  $\mathbb{Z}/n\mathbb{Z}$ , composition of symmetries of equilateral triangle.

**Definition 2** (Group). A group is an ordered pair (G, \*), where G is a set and \* is a binary operation on G satisfying the following axioms:

- Associativity: (a \* b) \* c = a \* (b \* c); for all  $a, b, c \in G$ .
- **Identity:** There exists an element  $e \in G$ , called identity of G, such that for all  $a \in G, a * e = e * a = a$ .
- Inverse: For all  $a \in G, a \neq e$ , there exists  $b \in G$  such that a \* b = b \* a = e. We call b is the inverse of a and write  $b = a^{-1}$ .

**Example.**  $(\mathbb{Q}, +), (\mathbb{Z}, +), (\mathbb{R}, +), (\mathbb{Q} \setminus 0, \times).$ 

**Definition 3.** A group G is called *abelian* (Or *commutative*) if a \* b = b \* a, for all  $a, b \in G$ . Otherwise, it is called *non-abelian* (Or *non-commutative*).

**Example.** • (R, +) is an abelian group.

• Group of the symmetries of an equilateral triangle is a non-abelian group.

Informally, we say G is a group under \* if (G,\*) is a group, or just G is a group when the operation \* is clear from the context.

**Example.** Consider  $G = \{x \in \mathbb{R} : 0 \le x < 1\}$ . For all  $x, y \in G$  define \* via -

• x \* y = x + y - [x + y].

•  $x + y \pmod{1}$ .

Prove that (G,\*) is an abelian group.

**Proof.** For all  $x, y \in G$ ,

$$0 \le x + y \pmod{1} < 1 \Rightarrow 0 \le x * y < 1$$
 (Closure).

For all  $x, y, z \in G$ ,

$$(x*y)*z = (x + y \pmod{1})*z$$
  
=  $(x + y \pmod{1}) + z \pmod{1}$   
=  $(x + y) + z \pmod{1}$   
=  $x + (y + z) \pmod{1}$   
=  $x + (y + z \pmod{1}) \pmod{1}$   
=  $x + y*z \pmod{1}$   
=  $x*(y*z)$  (Associativity).

For all  $x \in G$ ,

$$x * 0 = x + 0 \pmod{1} = x.$$

Similarly, 0 \* x = x (Identity).

For all  $x \neq 0 \in G$ ,  $(1-x) \in G$  and

$$x * (1 - x) = x + 1 - x \text{ Mod } 1 = 1 \text{ Mod } 1 = 0 \text{ &}$$
  
$$(1 - x) * x = 1 - x + x \text{ Mod } 1 = 1 \text{ Mod } 1 = 0$$

And for  $0 \in G, 0 * 0 = 0 + 0 \pmod{1} = 0$  (Inverse) For all  $x, y \in G$ 

$$x * y = x + y \pmod{1}$$
$$= y + x \pmod{1}$$
$$= y * x$$

Hence, G is an Abelian group.

## 1.2 Matrix Groups

**Example.**  $GL_n(R) = \{x \in \mathbb{R}^{n \times n} : x \text{ is invertible}\}$  under matrix multiplication forms a group.

**Proof.** For all  $A, B \in GL_n(R), AB$  is an  $n \times n$  matrix. If A and B is invertible,  $(AB)^{-1} = B^{-1}A^{-1} \in GL_n(R)$  (Closure).

Matrix multiplication is associative (Associativity).

Identity matrix  $I_n \in GL_n(R)$  since it is invertible (**Identity**).

Inverse exists by defintion (Inverse).

**Example.**  $SL_n(R) = \{x \in \mathbb{R}^{n \times n} : det(x) = 1\}$  under matrix multiplication forms a group.

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**Proof.** For all  $A, B \in GL_n(R)$ , AB is an  $n \times n$  matrix. If det(A) = det(B) = 1, then  $det(AB) = det(A) \times det(B) = 1 \times 1 = 1$  (Closure).

Matrix multiplication is associative (Associativity).

Identity matrix  $I_n \in GL_n(R)$  since  $\det(I_n) = 1$ . For all  $A \in GL_n(R)$ , inverse exists as  $\det(A) \neq 0$  and  $\det(A^{-1}) = \frac{1}{\det(A)} = 1$  (Inverse)

7 Lecture 1

30 Oct 2024

#### 2.1 **Group Propositions**

**Proposition 1.** If (G, \*) is a group, then

- 1. The identity e is unique.
- 2. For all  $a \in G$ ,  $a^{-1}$  is unique.
- 3. For all  $a \in G$ ,  $(a^{-1})^{-1} = a$ .
- 4. For all  $a, b \in G$ ,  $(a * b)^{-1} = b^{-1}a^{-1}$ .
- 5. For all  $a_1, a_2, ... a_n \in G$ , the value of  $a_1 * a_2 * ... * a_n$  is independent of how the expression is bracketed (Generalized associative law).

**Proof.** 1. If there were two distinct identity say e' and e'', then for all  $a \in G$ ,

$$a * e' = e' * a = a$$

also

$$a * e'' = e'' * a = a$$

$$\Rightarrow a * e'' = a * e'$$

$$\Rightarrow a^{-1} * a * e'' = a^{-1} * a * e'$$

$$\Rightarrow e'' = e' \text{ (Contradiction!)}$$

Hence, indentity is unique.

2. Let for all  $a \in G$ , there exists two distinct inverse b, c,

$$a*b=b*a=e$$

also

$$a*c=c*a=e$$

Now, b = b \* e = b \* (a \* c) = (b \* a) \* c = e \* c = c (Contradiction!)

Hence, inverse is unique for each element of a group. 3. According to the defintion,  $a * a^{-1} = a^{-1} * a = e$ . By mentally interchanging the roles of a and  $a^{-1}$ , we can see that a satisfies the defining property for the inverse of  $a^{-1}$ , hence,  $(a^{-1})^{-1} = a$ .

4.  $(a * b) * (b^{-1} * a^{-1}) = a * (b * b^{-1}) * a^{-1} = a * e * a^{-1} = a * a^{-1} = e$ .

Since, G is a group, only inverse can have such property. Hence,  $(a*b)^{-1} = b^{-1}*a^{-1}$ .

5. Left as exercise.

**Lemma 1** (Cancellation Lemma). For all a, u, w

- $a * u = a * w \Rightarrow u = w$
- $u * a = w * a \Rightarrow u = w$

## 2.2 Subgroups

**Definition 4** (Subgroup). A subset of H of G is a subgroup if H is non-empty and is closed under products and inverses. We write  $H \leq G$ .

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Example. (\mathbb{Z},+) \leq (Q,+) \leq (\mathbb{R},+) \leq (\mathbb{C},+).
```

For an equilateral triangle, the group of rotational symmetries is a subgroup of the group of all symmetries (rotation and reflection).

Any group G has at least two subgroups: trivial group  $\{e\}$  and the group itself (aka. improper subgroup).

When we say that H is a subgroup of G we shall always mean that the operation for the group H is the operation on G restricted to H. In general, it is possible that the subset H has the structure of a group with respect to some operation other than the operation on G restricted to H.

**Example.**  $\mathbb{Q} \setminus 0$  under multiplication is not a subgroup of  $\mathbb{R}$  under addition even though both are groups and  $\mathbb{Q} \setminus 0$  is indeed a subset of  $\mathbb{R}$ .

**Lemma 2** (The Subgroup Criterion).  $H \leq G$  is a subgroup if and only if  $H \neq \emptyset$  and for all  $x, y \in H, xy^{-1} \in H$ .

**Proof.** The forward direction is trivial.

For backward direction,

Since,  $H \neq \emptyset$ , there exists  $x, x \in H$ , which means  $xx^{-1} = e \in H$  (Identity).

For all  $x \in H$ ,  $ex^{-1} = x^{-1} \in H$  (Inverse).

Associativity holds inherently (Associativity).

For all  $x, y \in H, y^{-1} \in H$ , and so is  $x(y^{-1})^{-1} = xy \in H$  (Closure).

**Lemma 3.** If H is a nonempty finite subset of a group G and H is closed under multiplication, then H is a subgroup of G.

**Proof.** Here, we just have to prove **inverse** property. Suppose  $a \in H$ . Since is H is closed under multiplication, the infinte collection of elements  $a, a^2, a^3, ..., a^m, ...$  must all fit into H, which is a finite subset of G. Thus there must be repetations in this collection of elements; that is, for some integers r, s with  $r > s > 0, a^r = a^s \Rightarrow a^{r-s} = e$ . Since,  $r - s - 1 \ge 0, a^{r-s-1} \in H$  and since  $aa^{r-s-1} = a^{r-s} = e, a^{-1} = a^{r-s-1}$ . Thus,  $a^{-1} \in H$ , completes the proof of the lemma.

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04 Nov 2024

### 3.1 Order of Group and its elements

Order of a group G, denoted as |G| is the number of its element. If |G| is a finite, then G is finite group; otherwise it is infinite group which has infinite order. (R, +) has infinite order; whereas symmetries of a triangle,  $\mathbb{Z}/n\mathbb{Z}$  or  $(\mathbb{Z}/n\mathbb{Z})^{\times}$  has finite order.

**Note.**  $\mathbb{Z}/n\mathbb{Z}$  is a group under addition and  $(\mathbb{Z}/n\mathbb{Z})^{\times}$  is a group under multiplication, consists of the elements of  $\mathbb{Z}/n\mathbb{Z}$  that do have multiplicative inverse. Former is called **additive group** and the latter is called **multiplicative group**.

**Example.**  $|(\mathbb{Z}/n\mathbb{Z})^{\times}| = \{a \in \mathbb{Z}/n\mathbb{Z} : \gcd(a, n) = 1\} = \varphi(n).$  The function is called **Euler's totient function**.

**Definition 5.** For a group G and  $x \in G$ , the *order* of x is the smallest positive integer n such that  $x^n = e$ , and is denoted by |x|. In this case, x is said to be order of n. If no positive power x is the identity, the order of x is defined to be infinity and x is said to be of infinite order.

**Example.**  $\mathbb{Z}/n\mathbb{Z}$  has order 6. Elements of  $\mathbb{Z}/n\mathbb{Z}$  has following orders:  $|\overline{0}| = 1, |\overline{1}| = 6, |\overline{2}| = 3, |\overline{3}| = 2, |\overline{4}| = 3, |\overline{5}| = 6$ . Notice, order of any element is less than or equals to the order of the group.

**Example.** In additive groups  $\mathbb{Z}$ ,  $\mathbb{Q}$ ,  $\mathbb{R}$  or  $\mathbb{C}$ , every nonzero element has infinte order. whereas, in the multiplicative groups  $\mathbb{R}^{\times}$  or  $\mathbb{Q}^{\times}$  the element -1 has order 2 and all other nonidentity elements have infinite order.

**Example.** In the group  $GL_n(R)$ , order of  $\begin{pmatrix} -1 & 0 \\ 0 & -1 \end{pmatrix}$  is 2 because  $\begin{pmatrix} -1 & 0 \\ 0 & -1 \end{pmatrix}^2 = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$ .

# 3.2 Cyclic Groups

**Definition 6.** A group H is cyclic if H can be generated by a single element, i.e., there is some element  $x \in H$  such that  $H = \{x^n : n \in \mathbb{Z}\}$  (where as usual the operation is multiplication).

In additive notion H is cyclic if  $H = \{nx : n \in \mathbb{Z}\}$ . In both cases we will write  $H = \langle x \rangle$  and say H is generated by x.

**Example** (A cyclic group may have more than one generator). •  $\mathbb{Z}/n\mathbb{Z} = \langle \overline{1} \rangle = \langle \overline{2} \rangle$ 

- $\mathbb{Z}/p\mathbb{Z} = \langle \overline{1} \rangle = \dots = \langle \overline{p-1} \rangle$
- $(\mathbb{Z},+)=\langle \overline{-1}\rangle=\langle \overline{1}\rangle$

**Example.** The 6th complex roots of unity form a cyclic group under multiplication. Here, z is a generator, but  $z^2$  is not, because its power fail to produce the odd powers of z.

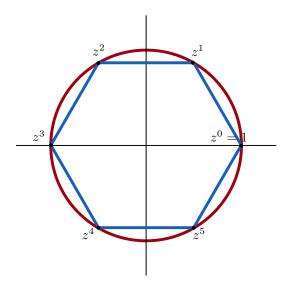


Figure 3.1: The 6th complex roots of unity form a cylic group under multiplication

#### 3.3 Centralizers and Normalizers

**Definition 7** (Centralizer). The *centralizer* of a subset A of group G is the set  $C_G(A) = \{g \in G : gag^{-1} = a \text{ for all } a \in A\}$ . Since  $gag^{-1} = a$  if and only if  $ga = ag, C_G(A)$  is the set of elements of G which commute with every element of A.

We show  $C_G(A)$  is a subgroup of G. First of all,  $C_G(A) \neq \emptyset$  as  $e \in C_G(A)$  because the identity commutes with every element of G, in particular for all  $a \in A$ . Let  $x, y \in C_G(A)$ , that is, for all  $a \in A$ 

$$xax^{-1} = a \text{ and } yay^{-1} = a.$$

We have to prove  $xy^{-1}$  also exits in  $C_G(A)$ .

$$(xy^{-1})a(xy^{-1})^{-1} = (xy^{-1})a(yx^{-1})$$
$$= x(yay^{-1})x^{-1}$$
$$= xax^{-1}$$
$$= a$$

In special case when A = a we will write simply  $C_G(a)$  instead of  $C_G(a)$ . In this case  $a^n \in C_G(a)$  for all  $n \in \mathbb{Z}$ .

To be continued...

Lecture 3

06 Nov 2024

**Note.**  $x, y \in C_G(A)$  does not necessarily mean xy = yx.

**Definition 8** (Center). Define  $Z(G) = \{g \in G : gx = xg \text{ for all } x \in G\}$ , the set of elements commuting with all the elements of G. This subset of G is called the *center* of G.

**Note.**  $Z(G) = C_G(G)$ , so the argument above proves  $Z(G) \leq G$  as a special case.

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Definition 9 (Normalizer). Let gAg^{-1} := \{gag^{-1} : a \in A\}. The normalizer of A \in G is the set N_g(A) = \{g \in G : gAg^{-1} = A\}.
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 $N_G(A)$  is a subgroup of G (follows from the same steps which demonstrated that  $C_G(A) \leq G$  with appropriate modifications).

## 4.1 Caylay's Table

To be written...

11 Nov 2024

### 5.1 Congruence Modulo Subgroup H

**Definition 10.** Let G be a group, H a subgroup of G; for  $a, b \in G$  we say a is congruent to  $b \pmod{H}$ , written as  $a \equiv b \pmod{H}$  if  $ab^{-1} \in H$ .

**Lemma 4.** The relation  $a \equiv b \pmod{H}$  is an equivalence relation.

**Proof.** 1. Since H is a subgroup, for all  $a \in H, aa^{-1} = e \in H$ . Hence,  $a \equiv a \pmod{H}$  (reflexivity).

2. Let  $a \equiv b \pmod{H}$ , equivalently,  $ab^{-1} \in H$ . So,  $(ab^{-1})^{-1} \in H$ . But  $(ab^{-1})^{-1} = (b^{-1})^{-1}a^{-1} = ba^{-1}$ . Hence,  $ba^{-1} \in H$  equivalently,  $b \equiv a \pmod{H}$  (symmetry).

3. Let  $a \equiv b \pmod{H}$  and  $b \equiv c \pmod{H}$ , which are equivalent to  $ab^{-1} \in H$  and  $bc^{-1} \in H$  respectively. But together they imply  $(ab^{-1})(bc^{-1}) \in H$ .  $(ab^{-1})(bc^{-1}) = ac^{-1} \in H$ . From which it follows  $a \equiv c \pmod{H}$ . (Transitivity).

Hence,  $a \equiv b \pmod{H}$  is an equivalence relation.

**Remark.** The  $a \equiv b \pmod{H}$  is a generalization of the "mod" we see in integers. Recall that  $(\mathbb{Z},+)$  is a group. So  $ab^{-1}$  is the generalization of a-b=a+(-b). Now,  $a \equiv b \pmod{n}$  means  $n \mid a-b$ . This can be interpreted as  $a-b \in n\mathbb{Z}$ , where  $n\mathbb{Z} = \{nk \mid k \in \mathbb{Z}\}$ . Observe that all subgroups of  $\mathbb{Z}$  are of the form  $n\mathbb{Z}$ . So to generalize this for any group G and any subgroup H, we interpret  $a \equiv b \pmod{H}$  as  $ab^{-1} \in H$ .

#### 5.2 Cosets

**Definition 11** (Cosets). If H is a subgroup of  $G, a \in G$ , then  $Ha = \{ha : h \in H\}$ . Ha is called a right coset of H in G. Similarly,  $aH = \{ah : h \in H\}$  is a left coset in G.

Is Ha a subgroup of G? Not in general. Let  $a \notin Ha$ . Then identity  $e \notin H$ . Because otherwise  $e * a = a \in Ha$  (contradiction).

**Lemma 5.** For all  $a \in G$ ,  $Ha = \{x \in G : a \equiv x \pmod{H}\}$ .

**Proof.** Let  $[a] = \{x \in G : a \equiv x \pmod{H}\}$ 

For all  $c \in Ha \Rightarrow c = h_1a$  (for some  $h_1 \in H$ ).  $a(h_1a)^{-1} = aa^{-1}h_1^{-1} = h_1^{-1} \in H$  from which it follows  $h_1a = c \in [a]$ . Hence,  $Ha \subseteq [a]$ .

Conversely, for all  $x \in [a]$ ,  $ax^{-1} \in H \Rightarrow (ax^{-1})^{-1} = xa^{-1} \in H$ . Therefore,  $(xa^{-1})a = x \in Ha$ . Hence,  $[a] \subseteq Ha$ .

Therefore,  $Ha = [a] = \{x \in G : a \equiv x \pmod{H}\}.$ 

Equivalence classes yield a decomposition of G into disjoint subsets. Thus, any two right cosets of H in G either are identical or have no element in common.

**Lemma 6.** There is a one-to-one correspondence between any two right cosets of H in G.

**Proof.** Let  $f: Ha \to Hb$  be a map where f(ha) = hb. Trivially, f is a bijective map.

|H| = |He| = |Hx| for all  $x \in G$ .

All right cosets / left cosets have the same cardinality.

Since any  $a \in G$  is in a unique right coset Ha, the right cosets fill out G. Thus if k represents the number of distinct right cosets of H in G we must have that k|H| = |G|. Which proves the famous Lagrange's Theorem, namely,

**Theorem 1** (Lagrange's Theorem). If G is a finite group and H is a subgroup of G, then order of H is a divisor of order of G.

**Definition 12** (Index of H in G). If  $H \leq G$  then the index of H in G is the number of distinct right cosets of H in G. We denote it by [G:H].

Notice,

$$[G:H] = \frac{|G|}{|H|}.$$

And if K < H < G, then

$$[G:K]=[G:H][H:K]. \\$$

Lecture 5

13 Nov 2024

### 6.1 Dihedral Groups

Consider the set of all symmetries of a regular n-gon. They form a group under composition of transformations. We call this a  $Dihedral\ Group$ . Denoted as  $D_n$  (or  $D_{2n}$  in some texts). Notice  $D_n$  has 2n elements. Let's level n vertices from 1 to n. Then for 1 we have n choices. For 2 we have 2 choices since vertex 2 is adjacent to vertex 1. And since symmetries are rigid motions, once we specify vertex 1 and 2, positions of the remaining vertices are determined automatically. Hence,

$$|D_n|=2n.$$

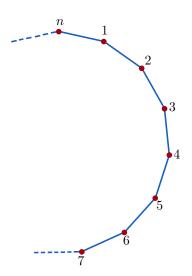


Figure 6.1: A regular n-gon

Now, for  $D_3$  or  $D_4$  we can explicitly exhibit all the symmtries and do computations, but for higher n it becomes complicated. Therefore, viewing  $D_n$  as an abstract group is convenient. Label a regular n-gon consecutively from 1 to n clockwise. Let r be the rotation anti-clockwise about the origin by  $\frac{2\pi}{n}$  radian. Let s be the reflection about the line of symmetry through vertex 1 and the origin. Then, the following properties are true:

- 1.  $1, r, r^2, \dots, r^{n-1}$  are all distinct and  $r^n = 1$ , so |r| = n.
- 2.  $s^2 = 2$ .
- 3.  $r^i s$  has to be a reflection, that is,  $r^i s \neq r^j$  for any i and j.
- 4.  $sr^i \neq sr^j$ , for all  $0 \le i, j \le n-1$  with  $i \ne j$ , so

$$D_n = \{1, r, r^2, \dots, r^{n-1}, s, sr, sr^2, \dots, sr^{n-1}\}\$$

i.e., each element can be written uniquely in the form  $sr^i$  for some k=0 or 1 and  $0 \le i \le n-1$ .

5.  $rs = sr^{-1}$ . Because

$$(rs)^2 = e \Rightarrow rs \cdot rs = e \Rightarrow rs = s^{-1}r^{-1} \Rightarrow rs = sr^{-1}$$
.

6. By induction,  $r^i s = s r^{-i}$ , for all  $0 \le i < n$ .

Using (1), (2), (3), we can compute any finite number of produts of  $D_n$  and represent it in the form  $sr^i$ , where k=0 or 1 and  $0 \le i \le n-1$ . For example, if n=12,

**Example.** 
$$(sr^9)(sr^6) = s(r^9s)r^6 = s(sr^{-9})r^6 = s^2r^{-9+6} = r^{-3} = r^9$$
.

Notice, the set  $\{1, r, r^2, \dots, r^{n-1}\}$  is an abelian subgroup of  $D_n$ .

#### 6.2 Generators, Relations & Presentation of a Group

All the elements of  $D_n$  is generated by r,s. We call them generators of  $D_n$ . r,s satisfy some equations which are called relations. In general, if some group G is generated by some  $S \subseteq G$  and there is some collection of relations, say  $R_1, R_2, ..., R_m$  ( $R_i$  is an equation in the elements from  $S \cup \{1\}$ ) such that any relation among the elements of S can be deduced from these, we shall call these generators and relations a *presentation* of G and write

$$G = \langle S|R_1, R_2, ..., R_m \rangle.$$

One presentation for the dihedral group  $D_n$  is

$$D_n = \langle r, s | r^n = s^2 = e, rs = sr^{-1} \rangle.$$

If G is a finite group then, for  $x, y \in G, \langle x, y \rangle$  is the set of any possible combination of products of x, y.  $\langle x, y \rangle$  forms a subgroup of G. We call it *free group* generated by x, y.

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#### 7.1 Symmetric Groups, Cycle & Cycle Structure

**Definition 13.** Let  $\Omega$  be any nonempty set and let  $S_{\Omega}$  be the set of all bijections from  $\Omega$ to itself. Then  $S_{\Omega}$  forms a group under function composition:  $\circ$ .  $(S, \circ)$  is called *symmetric* group on the set  $\Omega$ .

When  $\Omega = \{1, 2, ..., n\}$ , we write it as  $S_n$ .

**Example.** Let  $\Omega = \{a, b\}$ .

$$S_{\Omega} = \left\{ egin{array}{cccc} a & & b & & a & b \\ & & & & & & , & \\ & & & & & & , & \\ a & & & b & & a & b \end{array} \right\}$$

 $|S_{\Omega}|=2.$ 

**Example.** If  $\Omega = \{a, b, c\}, |S_{\Omega}| = 6.$ 

Order of  $S_n$  is n!. Let  $\sigma \in S_n$ , then

 $\sigma(1)$  has n choices to send 1 to any n element.

 $\sigma(2)$  has (n-1) choices.

 $\sigma(3)$  has (n-2) choices.

 $\sigma(n)$  has (1) choices.

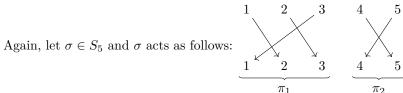
Hence, there is precisely  $n(n-1)(n-2)\cdots 2\cdot 1=n!$  bijections from n to itself.

**Definition 14.** A cycle is a string of integers which represents the element of  $S_n$  which cyclically permutes these integers (and fixes all other integers).

Let

$$\sigma = \begin{pmatrix} 1 & \to & 2 \\ 2 & \to & 3 \\ 3 & \to & 1 \end{pmatrix} \in S_3.$$

 $\sigma^3=e.$   $\sigma$  is called cycle of length  $|\sigma|=3$  generated by  $\sigma.$ 



 $\sigma = \pi_1 \circ \pi_2$ , where  $\pi_1$  has the cycle structure (3+1+1) and  $\pi_2$  has the cycle structure (2+1+1+1).

Two cycles are called disjoint if they have no elements in common.  $\pi_1, \pi_2$  are examples of disjoint cycles. Notice, two dijoint cycles commutes as we can see they do not interact with each other.

**Theorem 2.** Every elements in  $S_n$  can be written as composition of disjoint cycles.

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## 8.1 Cycle Notation

**Cycle Notation:** The cycle which sends  $a_i$  to  $a_{i+1}, 1 \le i \le m-1$  and sends  $a_m$  to  $a_1$  is written as  $(a_1, a_2...a_m)$ .

**Example** (Cycle Decomposition Algorithm). Let n = 13 and let  $\sigma \in S_{13}$  be defined by

$$\sigma(1) = 12, \quad \sigma(2) = 13, \quad \sigma(3) = 3, \quad \sigma(4) = 1, \quad \sigma(5) = 11,$$

$$\sigma(6) = 9$$
,  $\sigma(7) = 5$ ,  $\sigma(8) = 10$ ,  $\sigma(9) = 6$ ,  $\sigma(10) = 4$ ,  $\sigma(11) = 7$ ,  $\sigma(12) = 8$ ,  $\sigma(13) = 2$ .

| Method   | Example  |
|--|--|
| To start a new cycle, pick the smallest element of $\{1, 2, \ldots, n\}$ which has not yet appeared in a previous cycle — call it $a$ (if you are just starting, $a=1$ ); begin the new cycle: ( $a$   | (1   |
| Read off $\sigma(a)$ from the given description of $\sigma$ —call it $b$ . If $b=a$ , close the cycle with a right parenthesis (without writing $b$ down); this completes a cycle—return to step 1. If $b \neq a$ , write $b$ next to $a$ in this cycle: ( $a$ $b$   | $\sigma(1) = 12 = b, 12 \neq 1$ so write: (1 12                  |
| Read off $\sigma(b)$ from the given description of $\sigma$ —call it $c$ . If $c=a$ , close the cycle with a right parenthesis to complete the cycle—return to step 1. If $c \neq a$ , write $c$ next to $b$ in this cycle: $(a \ b \ c)$ . Repeat this step using the number $c$ as the new value for $b$ until the cycle closes. | $\sigma(12) = 8, \ 8 \neq 1 \ \text{ so cycle runs: } (1\ 12\ 8$ |
| Naturally, this process stops when all the numbers from $\{1, 2,, n\}$ have appeared in some cycle.  | $\sigma = (1 \ 12 \ 8 \ 10 \ 4)(2 \ 13)(3)(5 \ 11 \ 7)(6 \ 9)$   |
| Final Step: Remove all cycles of length 1  | $\sigma = (1 \ 12 \ 8 \ 10 \ 4)(2 \ 13)(5 \ 11 \ 7)(6 \ 9)$      |

**Example** (Computing Products in  $S_n$ ). While computing products in  $S_n$  one reads the permutations from *right to left*. Let's compute  $(1\ 2\ 3) \circ (1\ 2)(3\ 4)$ .

Reading off permutations Computing product

$$1 \rightarrow 2 \rightarrow 3 \quad (1 \ 3$$

$$3 \rightarrow 4 \quad (1 \ 3 \ 4)$$

$$4 \to 1 \quad (1 \ 3 \ 4)$$

```
Hence, (1\ 2\ 3) \circ (1\ 2)(3\ 4) = (1\ 3\ 4).

S_n is non-abelian group for all n \ge 3.
```

## 8.2 Cyclic Permutation, Transposition & Alternating Group

**Definition 15** (Cyclic Permutation).  $\pi \in S_{\Omega}$  has a cycle of length r, and all other cycles are of length 1, then,  $\pi$  is a *cyclic permutation*.

**Definition 16** (Transposition). A cyclic permutation of length 2 is called a transposition.

**Proposition 2.** Any r cycle can be decomposed into a product of (r-1) transpositions.

```
Example. Let \tau = (1\ 3\ 4\ 6\ 7\ 9) \in S_9 Method 1: \tau = (1\ 3\ 4\ 6\ 7\ 9) = (1\ 9)(1\ 7)(1\ 6)(1\ 4)(1\ 3) Method 2: \tau = (1\ 3\ 4\ 6\ 7\ 9) = (1\ 3)(3\ 4)(4\ 6)(6\ 7)(7\ 9)
```

Both products of transpositions method 1 or method 2 represent the same permutation  $\tau$ . Note that the order of the disjoint cycle  $\tau$  is  $\tau$  but in both expressions of  $\tau$  as the product of transpositions,  $\tau$  has 5 (odd number of) permutations. Hence  $\tau$  is an *odd permutation*. Similarly, if a permutation is the product of an even number of transpositions, it is called even permutation.

**Definition 17** (Alternating Group). Let  $A_n$  be the subset of  $S_n$  consisting of all even permutations. Since product of two even permutations is even,  $A_n$  is a subgroup of  $S_n$ .  $A_n$  is called the *alternating group* of degree n.

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#### 9.1 Normal Subgroup

**Definition 18** (Normal Subgroup). Let G be a group. A subgroup N of G is a normal subgroup if gN = Ng, for all  $g \in G$ . Equivalently, a subgroup N is normal in the group G if  $gNg^{-1} = N$ , for all  $g \in G$ . We denote  $N \triangleleft G$ .

**Example.**  $A_3$  is normal in  $S_3$ . Because,  $A_3$  has index 2 in  $S_3$ , meaning  $A_3$  has exactly two cosets:  $A_3$  and its complement in  $S_3$ . Hence, left and right cosets coincide.

In general,  $A_n$  is normal in  $S_n$ . Furthermore, a subgroup of index 2 is always normal because the left and right cosets coincide.

**Example** (Trivial Examples).  $\{e\} \in G$  and the group G itself is normal in G.

**Example** (Center of G). Center of the group G is a normal subgroup.

Remark. Is every abelian subgroup normal? No.

Counter example:  $\{e, s\} \in D_3$  is abelian subgroup. But not normal, since, for intance,  $r\{e, s\} \neq \{e, s\}r$ .

## 9.2 Quotient Group

**Theorem 3.** Let  $N \triangleleft G$ . If  $g_1N = g_1'N$  and  $g_2N = g_2'N$ , then  $g_1g_2N = g_1'g_2'N$ .

**Proof.** Let  $x \in g_1g_2N$ , then  $x = g_1g_2n$ , for some  $n \in N$ . Since,  $g_2N = g_2'N = Ng_2'$ ,  $g_2n = g_2'n_1 = n_2g_2'$  for some  $n_1, n_2 \in N$ . So,  $x = g_1g_2'n_1 = g_1n_2g_2'$ .  $g_1n_2 = g_1'n_3$ , for some  $n_3 \in N$ . Hence,  $x = g_1'n_3g_2' = g_1'g_2'n'$ , for some  $n' \in N$ . Hence,  $x \in g_1'g_2'N$ , which implies  $g_1g_2N \subseteq g_1'g_2'N$ .

Using similar argument, 
$$g_1'g_2'N \subseteq g_1g_2N$$
. Hence,  $g_1g_2N = g_1'g_2'N$ .

Cosets of a subgroup N in a group G naturally partition G. However, not all subgroups allow these cosets to have a meaningful group structure. When N is a normal subgroup (gN = Ng for all  $g \in G$ ), we can define an operation on cosets that mimics the group operation in G. Specifically:

$$(gN) \cdot (hN) = (gh)N.$$

This operation is well-defined only if N is normal, ensuring that the choice of representatives g and h does not affect the result as the previous theorem asserts.

**Definition 19** (Coset Multiplication). Let  $N \triangleleft G$ . Then define a multiplication on two cosets of N via-

$$g_1N \cdot g_2N := g_1g_2N$$

**Theorem 4** (Quotient Group). Under the multiplication operation above, the set of all cosets of the normal subgroup N forms a group, called the quotient group of G modulo N

and denoted as G/N.

**Proof.** To show that G/N forms a group under coset multiplication, we verify the group axioms: closure, associativity, identity, and inverses.

1. Closure: Let  $g_1N, g_2N \in G/N$ . Then their product is defined as:

$$(g_1N)(g_2N) = g_1g_2N.$$

Since  $g_1g_2 \in G$ , it follows that  $g_1g_2N \in G/N$ . Thus, G/N is closed under this operation.

2. Associativity: Let  $g_1N, g_2N, g_3N \in G/N$ . Then:

$$((g_1N)(g_2N))(g_3N) = (g_1g_2N)(g_3N) = (g_1g_2g_3)N.$$

Similarly:

$$(g_1N)((g_2N)(g_3N)) = (g_1N)(g_2g_3N) = (g_1g_2g_3)N.$$

Therefore, coset multiplication is associative.

3. **Identity:** The coset eN, where e is the identity element of G, acts as the identity in G/N. For any  $gN \in G/N$ :

$$(eN)(gN) = egN = gN$$
, and  $(gN)(eN) = geN = gN$ .

Thus, eN is the identity element in G/N.

4. **Inverses:** For any  $gN \in G/N$ , the coset  $g^{-1}N$  serves as its inverse. We verify:

$$(gN)(g^{-1}N) = g(g^{-1})N = eN$$
, and  $(g^{-1}N)(gN) = g^{-1}gN = eN$ .

Hence, every element in G/N has an inverse.

Since G/N satisfies the group axioms, it forms a group under the given multiplication operation.

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