

Vidyavardhini's College of Engineering and Technology

Department of Artificial Intelligence & Data Science

Experiment No. 6	
Prim's Algorithm	
Date of Performance:	
Date of Submission:	

Experiment No. 6

Title: Prim's Algorithm.

Aim: To study and implement Prim's Minimum Cost Spanning Tree Algorithm.

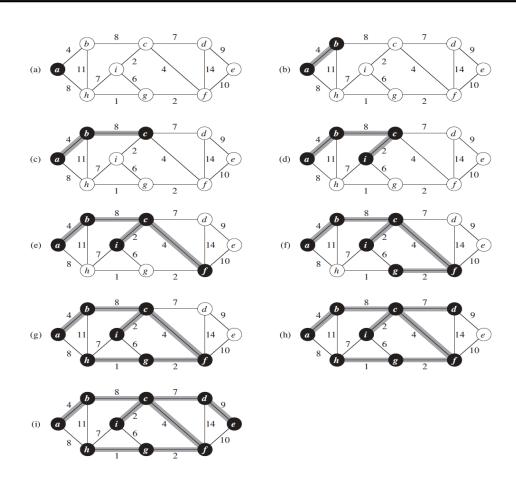
Objective: To introduce Greedy based algorithms

Theory:

Prim's algorithm is a greedy algorithm that finds a minimum spanning tree for a weighted undirected graph. This means it finds a subset of the edges that forms a tree that includes every vertex, where the total weight of all the edges in the tree is minimized. The algorithm operates by building this tree one vertex at a time, from an arbitrary starting vertex, at each step adding the cheapest possible connection from the tree to another vertex.

Example:





Algorithm and Complexity:



```
Algorithm Prim(E, cost, n, t)
2
    // E is the set of edges in G. cost[1:n,1:n] is the cost
3
    // adjacency matrix of an n vertex graph such that cost[i, j] is
4
    // either a positive real number or \infty if no edge (i, j) exists.
5
    // A minimum spanning tree is computed and stored as a set of
6
7
    // edges in the array t[1:n-1,1:2]. (t[i,1],t[i,2]) is an edge in
    // the minimum-cost spanning tree. The final cost is returned.
8
9
         Let (k, l) be an edge of minimum cost in E;
10
         mincost := cost[k, l];
11
         t[1,1] := k; t[1,2] := l;
         for i := 1 to n do // Initialize near.
12
             if (cost[i, l] < cost[i, k]) then near[i] := l;
13
14
              else near[i] := k;
         near[k] := near[l] := 0;
15
         for i := 2 to n-1 do
16
         \{ // \text{ Find } n-2 \text{ additional edges for } t. \}
17
18
              Let j be an index such that near[j] \neq 0 and
19
              cost[j, near[j]] is minimum;
20
             t[i,1] := j; t[i,2] := near[j];
21
             mincost := mincost + cost[j, near[j]];
22
             near[j] := 0;
23
             for k := 1 to n do // Update near[].
^{24}
                  if ((near[k] \neq 0) and (cost[k, near[k]] > cost[k, j]))
25
                       then near[k] := j;
26
27
         return mincost;
28
    }
```

Time Complexity is O(n2), Where, n = number of vertices**Theory:**

Implemenation:

#include <stdio.h>
#include <stdlib.h>
#include <limits.h>

#define V 5 // Number of vertices in the graph

// Function to find the vertex with minimum key value,



```
// from the set of vertices not yet included in MST
int minKey(int key[], int mstSet[]) {
  int min = INT MAX, min index;
  for (int v = 0; v < V; v++)
    if (mstSet[v] == 0 \&\& key[v] < min)
       min = key[v], min_index = v;
  return min index;
}
// Function to print the constructed MST stored in parent[]
void printMST(int parent[], int graph[V][V]) {
  printf("Edge Weight\n");
  for (int i = 1; i < V; i++)
    printf("%d - %d %d \n", parent[i], i, graph[i][parent[i]]);
}
// Function to construct and print MST for a graph represented
// using adjacency matrix representation
void primMST(int graph[V][V]) {
  int parent[V]; // Array to store constructed MST
  int key[V]; // Key values used to pick minimum weight edge in cut
```



int mstSet[V]; // To represent set of vertices not yet included in MST

```
// Initialize all keys as INFINITE
for (int i = 0; i < V; i++)
  key[i] = INT MAX, mstSet[i] = 0;
// Always include first vertex in MST.
// Make key 0 so that this vertex is picked as first vertex.
key[0] = 0;
parent[0] = -1; // First node is always root of MST
// The MST will have V vertices
for (int count = 0; count < V - 1; count++) {
  // Pick the minimum key vertex from the set of vertices
  // not yet included in MST
  int u = minKey(key, mstSet);
  // Add the picked vertex to the MST set
  mstSet[u] = 1;
  // Update key value and parent index of the adjacent vertices
  // of the picked vertex. Consider only those vertices which are
  // not yet included in MST
```



}

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```
for (int v = 0; v < V; v++)
       // graph[u][v] is non-zero only for adjacent vertices of m
       // mstSet[v] is false for vertices not yet included in MST
       // Update the key only if graph[u][v] is smaller than key[v]
       if (graph[u][v] \&\& mstSet[v] == 0 \&\& graph[u][v] < key[v])
          parent[v] = u, key[v] = graph[u][v];
  }
  // Print the constructed MST
  printMST(parent, graph);
// Driver code
int main() {
  // Graph representation using adjacency matrix
  int graph[V][V] = {
     \{0, 2, 0, 6, 0\},\
     \{2, 0, 3, 8, 5\},\
     \{0, 3, 0, 0, 7\},\
     \{6, 8, 0, 0, 9\},\
     \{0, 5, 7, 9, 0\}
  };
```



```
// Print the MST
primMST(graph);
return 0;
}
```

Conclusion: Prim's algorithm has been successfully implemented.