## AAG1 Domáci úkol II.

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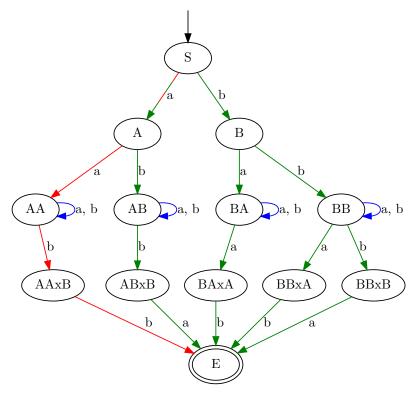
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$$L = \{w : w \in \{a, b\}^* \land w = uvz \land |u| = |z| = 2 \land \land u \neq z \land (z \in \{ab, ba\} \Leftrightarrow |u|_a < 2)\}$$

We can break equivalence from last condition into:

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L = \\ \{w: w \in \{a,b\}^* \land w = uvz \land |u| = |z| = 2 \land u \neq z \land \\ \land ((z \in \{ab,ba\} \land |u|_a < 2) \lor (z \notin \{ab,ba\} \land |u|_a \geqslant 2))\} \\ = \\ \{w: w \in \{a,b\}^* \land w = uvz \land |u| = |z| = 2 \land u \neq z \land \\ \land z \in \{ab,ba\} \land |u|_a < 2\} \cup \\ \lor \{w: w \in \{a,b\}^* \land w = uvz \land |u| = |z| = 2 \land u \neq z \land \\ \land z \notin \{ab,ba\} \land |u|_a \geqslant 2\} \\ = \\ \{w: w \in \{a,b\}^* \land w = uvz \land |u| = |z| = 2 \land u \neq z \land \\ \land z \notin \{ab,ba\} \land u \in \{ab,ba,bb\}\} \cup \\ \lor \{w: w \in \{a,b\}^* \land w = uvz \land |u| = |z| = 2 \land u \neq z \land \\ \land z \in \{aa,b\} \land u = aa\} \\ = \\ \{w: w \in \{a,b\}^* \land w = uvz \land \\ \land (u,z) \in \{(ba,ab),(bb,ab),(ab,ba),(bb,ba)\}\} \cup \\ \cup \{w: w \in \{a,b\}^* \land w = aavbb\}
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We can create nondeterministic finite automaton from this description:



Of course we could join states  $\{ABxB,BBxB\}$  and  $\{AAxB,BAxA,BBxA\}.$ 

Formal definition of this automaton:

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M = (\{S, A, B, AA, BB, AB, BA, BB, AAx, ABx, BAx, BBx, E\},
                       \{a,b\},\
                 \{\delta(S, a) = \{A\},\
                  \delta(S, b) = \{B\},\
                  \delta(A, a) = \{AA\},\
                  \delta(A, b) = \{AB\},\
                  \delta(B, a) = \{BA\},\
                  \delta(B, b) = \{BB\},\
                \delta(AA, a) = \{AA\},\
                \delta(AA, b) = \{AA, AAxB\},\
               \delta(AB, a) = \{AB\},\
                \delta(AB, b) = \{AB, ABxB\},\
               \delta(BA, a) = \{BA, BAxA\},\
                \delta(BA, b) = \{BA\},\
               \delta(BB, a) = \{BB, BBxA\},\
                \delta(BB, b) = \{BB, BBxB\},\
            \delta(AAxB, b) = \{E\},\
            \delta(ABxB, a) = \{E\},\
            \delta(BAxA, b) = \{E\},\
            \delta(BBxA, b) = \{E\},\
           \delta(BBxB, a) = \{E\}\},\
                           S,
                         \{E\})
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We can create deterministic finite automaton with states that keep track of original states. Each state of new automaton keeps information about subset of original automaton. For example deterministic state  $\{A, B, C\}$  would mean that we are in states A, B, C of nondeterministic automaton at the same time. We start from states  $\{A\}$ ,  $\{B\}$ . From state  $\{A\}$  we can get to states  $\{A, C, F\}$  in single a-transition  $(\delta(\{A\}, a) = \{A, B, F\})$ . This way we can create transition table:

Q	a	b	$\varepsilon$
$\leftrightarrow \{A\}$	$\{A,C,F\}$	$\{B\}$	$\{C\}$
<i>{B}</i>	$\{B,D\}$	Ø	Ø
$\leftarrow \{C\}$	Ø	Ø	Ø
$\rightarrow \{D\}$	$\{A,F\}$	$\{C,D\}$	$\{A\}$
$\{B,D\}$	$\{A,B,D,F\}$	$\{C,D\}$	$\{A\}$
$\leftarrow \{C, D\}$	$\{A,F\}$	$\{C,D\}$	$\{A\}$
$\leftarrow \{A, F\}$	$\{A,C,F\}$	$\{B\}$	$\{C\}$
$\leftarrow \{A, C, F\}$	$\{A,C,F\}$	$\{B\}$	$\{C\}$
$\leftarrow \{A, B, D, F\}$	$\{A, B, C, D, F\}$	$\{B,C,D\}$	$\{A,C\}$
$\leftarrow \{A,C\}$	$\{A,C,F\}$	$\{B\}$	$\{C\}$
$\leftarrow \{B, C, D\}$	$\{A,B,D,F\}$	$\{C,D\}$	$\{A\}$
$\leftarrow \{A, B, C, D, F\}$	$\{A, B, C, D, F\}$	$\{B,C,D\}$	$\{A,C\}$

New states of automaton:

$$Q' = \{\{A\}, \{B\}, \{C\}, \{D\}, \{A, C\}, \{A, F\}, \{B, D\}, \{C, D\}, \{A, C, F\}, \{B, C, D\}$$
$$\{A, B, D, F\}, \{A, B, C, D, F\}\}$$

Finite automaton accept states that contain at least one accept state of original automaton:

$$F' = \{\{A\}, \{C\}, \{A, C\}, \{A, F\}, \{C, D\}, \\ \{A, C, F\}, \{B, C, D\} \\ \{A, B, D, F\}, \{A, B, C, D, F\}\}$$

Final deterministic automaton:

$$M' = (Q', \{a, b\}, \delta', \{\{A\}, \{D\}\}, F')$$

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We can easily transform automaton M into nondeterministic automaton with  $\varepsilon$ -transitions with single start-state. We can introduce new start-state S with  $\varepsilon$ -transitions into original start-states A,D.

Q	a	b	$\varepsilon$
$\rightarrow S$	Ø	Ø	$\{A,D\}$
$\leftarrow A$	$\{A,C,F\}$	$\{B\}$	$\{C\}$
B	$\{B,D\}$	Ø	Ø
$\leftarrow C$	Ø	Ø	Ø
D	$\{A,F\}$	$\{C,D\}$	$\{A\}$
E	$\{B,C\}$	Ø	$\{A, B, C, D, E, F\}$
F	Ø	Ø	Ø