KEVIN SCHMIDT

M.Sc. Student in Autonomous Systems

Södertälje, Sweden





https://kevs272.github.io/



https://www.linkedin.com/in/kevin-schmidt-61894b171



https://github.com/KevS272

SKILLS

Programming

Presentation Skills

Scientific Writing

Attention to Detail

Creativity

PROGRAMMING LANGUAGES

Python

C++

lava

HTML & CSS

Javascript

FRAMEWORKS, LIBRARIES & OTHERS

ROS (2)

OpenCV

CUDA

TensorRT

Docker

PyTorch

Linux

LANGUAGES

German - Native speaker

English - Advanced, C1 TOEFL IBT: 110/120

HOBBIES

Cooking

Exploring

Guitar

Concerts

Piano

EDUCATION BACKGROUND

Eötvös Loránd University Budapest, Hungary

2023 - 2024

M.Sc. Autonomous Systems - CS for Autonomous Driving EIT Digital Master School - Exit year

KTH Royal Institute of Technology Stockholm, Sweden 2

2022 - 2023

M.Sc. Autonomous Systems

EIT Digital Master School - Entry year

Baden-Wuerttemberg Cooperative State University Mannheim, Germany

2017 - 2020

B.Sc. Business Information Systems - Grade: 1.5 (excellent)
Integrated study program with Atos Information Technology GmbH

WORK EXPERIENCE

Master Thesis Worker

02/2024 - 05/2024

Scania CV AB, Södertälje, Sweden

- Research on combining probabilistic and ML dynamic occupancy grid mapping methods
- Creation of a fully self-supervised data annotation and training pipeline for RNN-based dynamic occupancy grid mapping system
- Evaluation of the approach under real-world conditions of autonomous hub-to-hub trucks

Digital Business & Innovation Manager

10/2020 - 12/2023*

Eviden Germany GmbH, Frankfurt, Germany (Until 04/2023: Atos Information Technology GmbH)

- Sales expert for IT services for manufacturing, sustainability and automated driving development
- Responsible for startup and partner collaborations, customer events, industry fairs, client meetings and workshops

Cooperative Student Intern

10/2020 - 09/2017

Atos Information Technology GmbH, Frankfurt, Germany

Six consecutive internships in different departments:
 IT Service delivery management, SAP consulting, Project and transition management, Digital Business and Innovation

^{*}long-term leave during master study periods

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AWARDS & CERTIFICATES

2023 Best Entrepreneurial Team

EIT Digital Summer School 2023, Vilnius, Lithuania Pitch competition winner

2022 Best Entrepreneurial Team

EIT Digital Master School 2022, Tallin, Estonia Pitch competition winner

2020 Apprentice instructor certificate

IHK Rhein-Neckar

2019 ITIL Foundation certificate AXELOS Global

PUBLICATIONS

Towards Environment-Dependent Model Switching for Performance and Accuracy Conscious Object Detection in Dayand Nighttime Urban Traffic Environments

IEEE 47th Annual Computers, Software, and Applications Conference (COMPSAC) 2023, co-author

Signal processing pipeline for an autonomous electrical race car

IMAGE PROCESSING FORUM 2022, co-author

OTHER NOTEWORTHY EXPERIENCE

Driverless Perception Group Leader

KTH Formula Student, Stockholm, Sweden

- Management of perception-related projects inside the team
- Supervision of the teams' Engineering Design documentation
- Representation of the team at Formula Student Germany 2023, including the Engineering Design Presentation
- Implementation of camera and lidar-based object detection algorithms for a Formula Student Driverless race car

Driverless Perception Software Engineer

09/2022 - 04/2023

05/2023 - 08/2023

KTH Formula Student, Stockholm, Sweden

- Implementation of camera and lidar-based object detection algorithms for a Formula Student Driverless race car
- Collaboration on modularizing and containerizing a large ROS project

Alumni Autonomous System Advisor

10/2021 - Current

CURE Mannheim e.V., Mannheim, Germany

 Support and consulting of club members in the areas of camera-based object detection, ROS, Docker, sensor and compute hardware selection on request

Lead Software Engineer Perception

09/2019 - 09/2021

CURE Mannheim e.V., Mannheim, Germany

- Establishment of the Driverless division inside the club
- Implementation of camera and lidar-based object detection algorithms for a Formula Student Driverless race car
- Sensor and compute hardware selection
- Containerization of a large ROS project
- Representation of the team at Formula Student East 2021, including the Engineering Design Presentation