

Student Name: Kevin Alexander Bucio Martinez

Assignment: Robotics

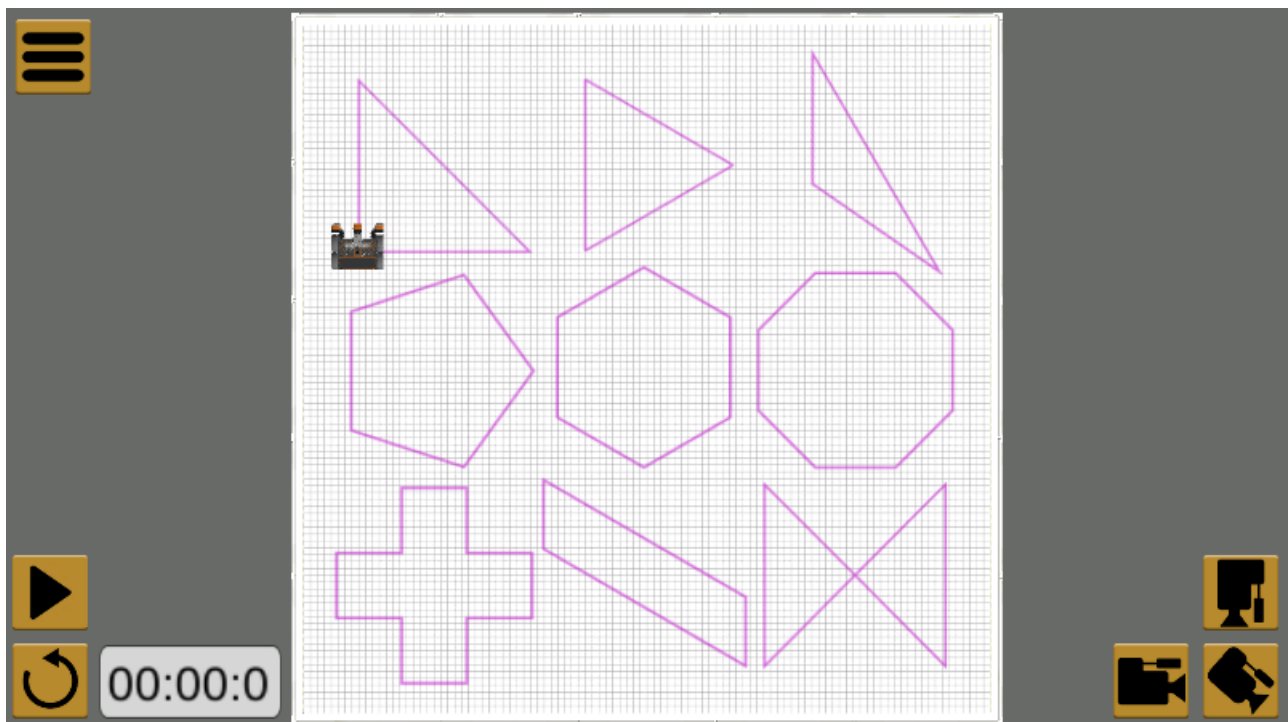
Notes: Shape Trace

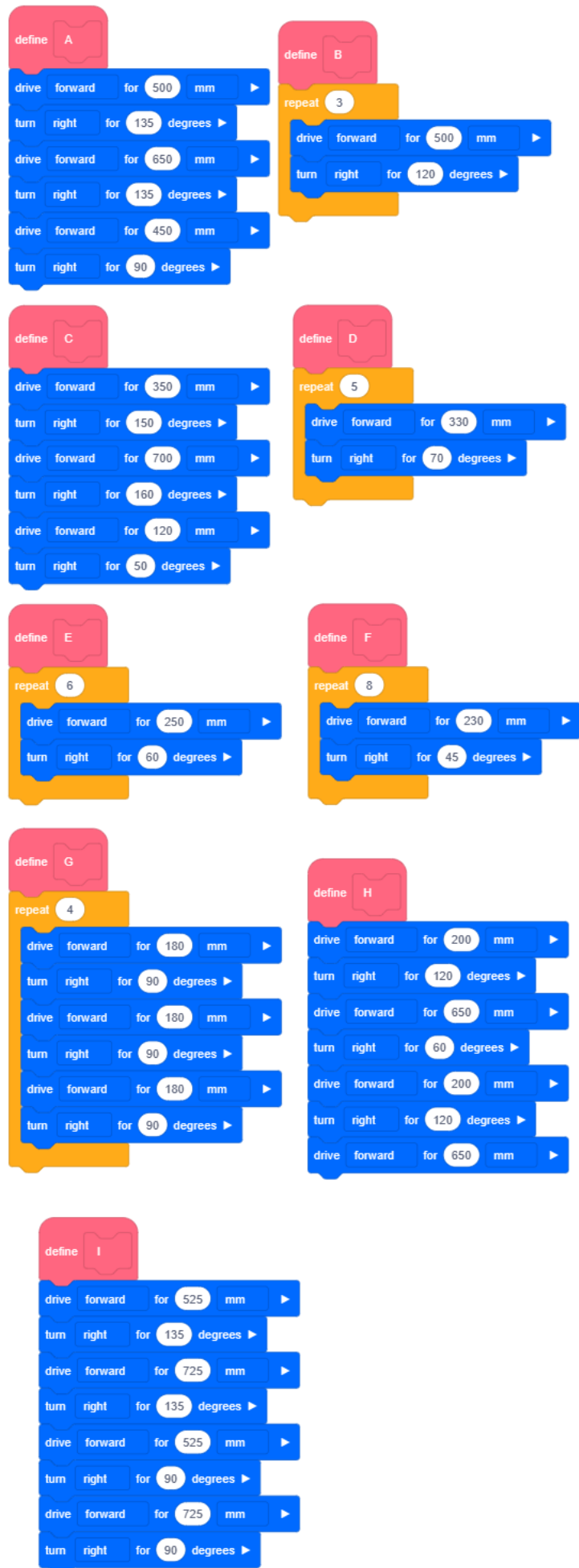
Playground: Shape Tracer

Project Name: KevinRobotics.omegaup#7

Project Type: Blocks

Date: Mon Mar 06 2023







when started



A

define

A

drive

forward

for

500

mm



turn

right

for

135

degrees



drive

forward

for

650

mm



turn

right

for

135

degrees



drive

forward

for

450

mm



turn

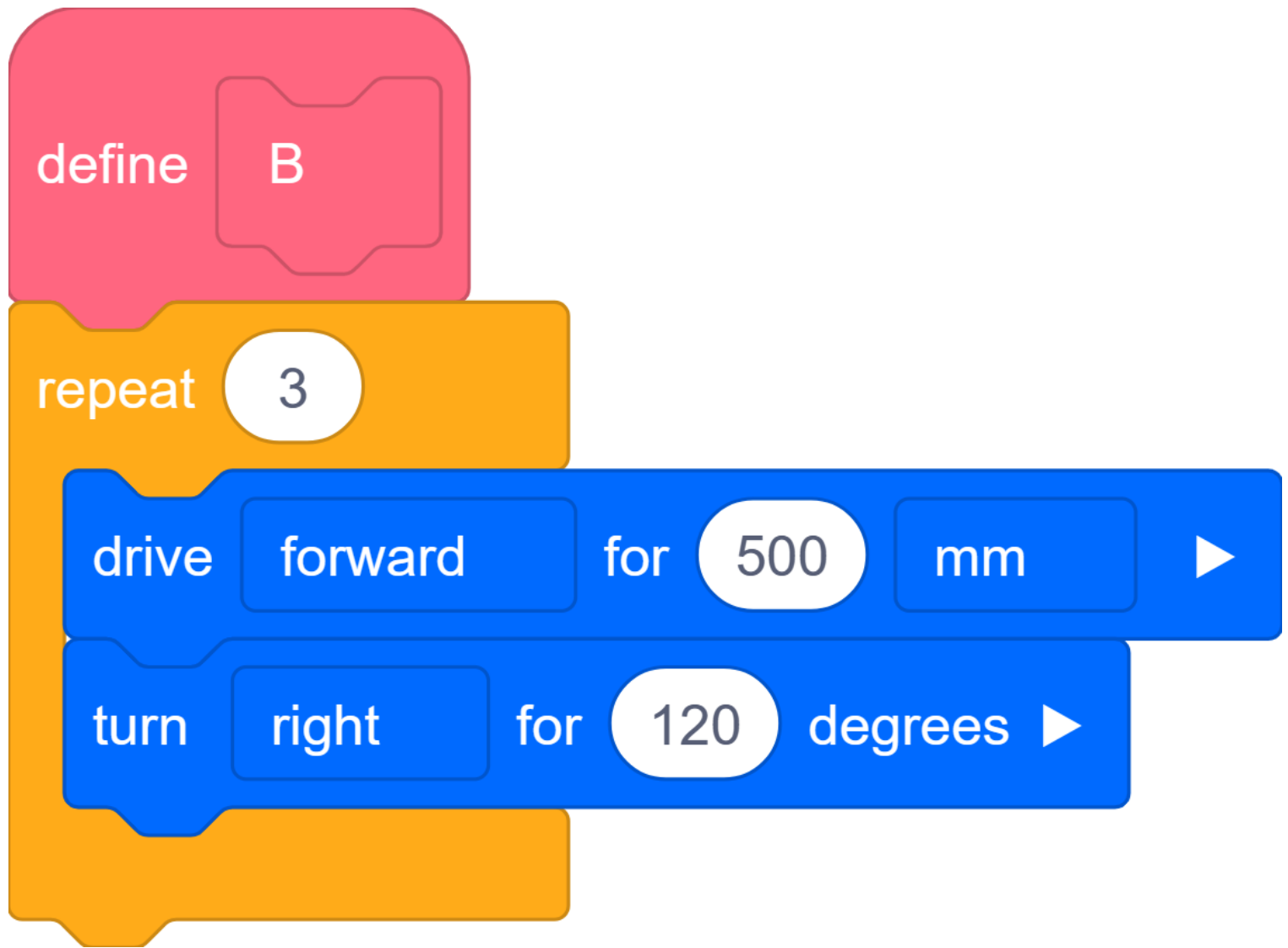
right

for

90

degrees





define

C

drive

forward

for

350

mm



turn

right

for

150

degrees



drive

forward

for

700

mm



turn

right

for

160

degrees



drive

forward

for

120

mm



turn

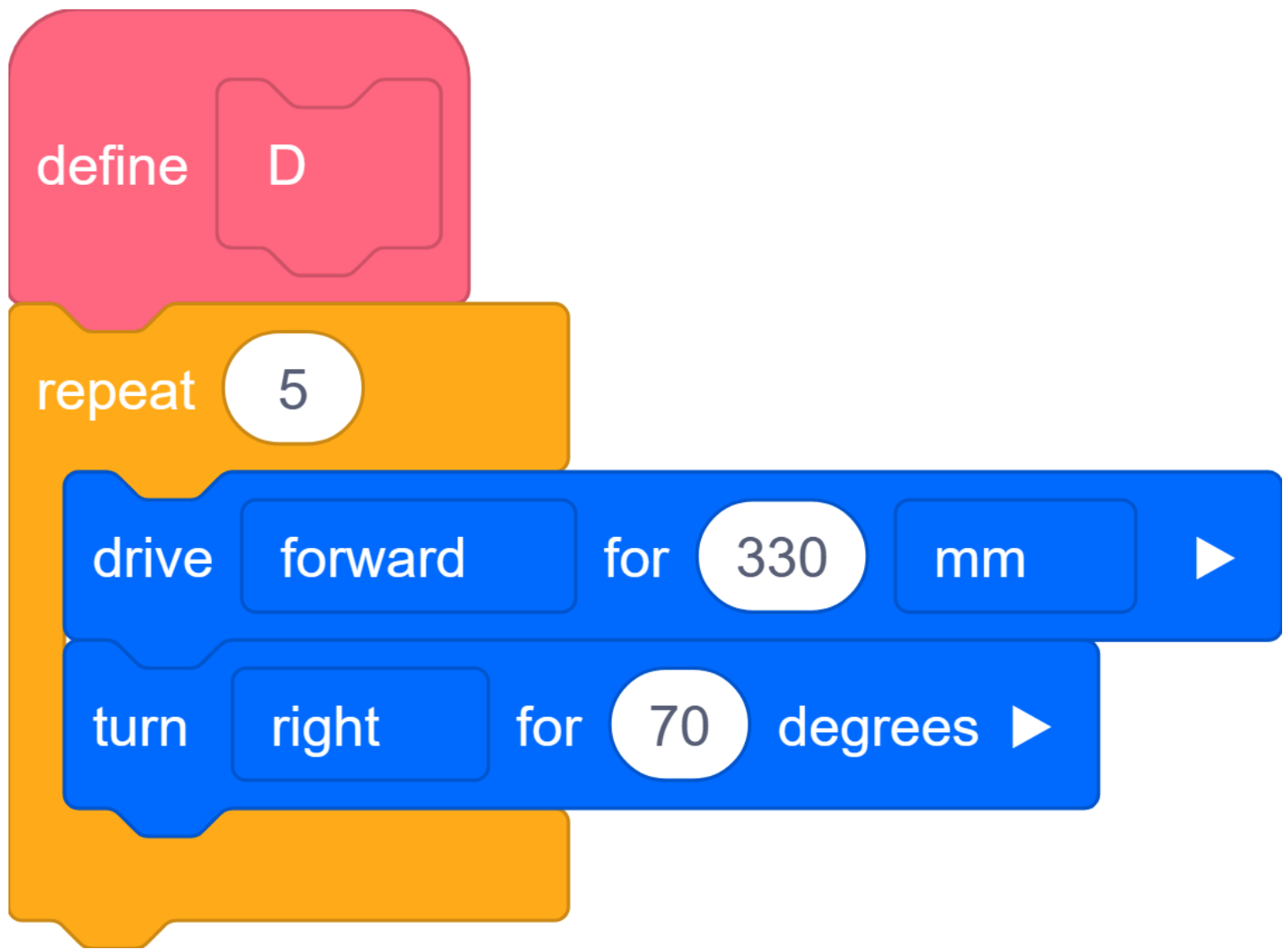
right

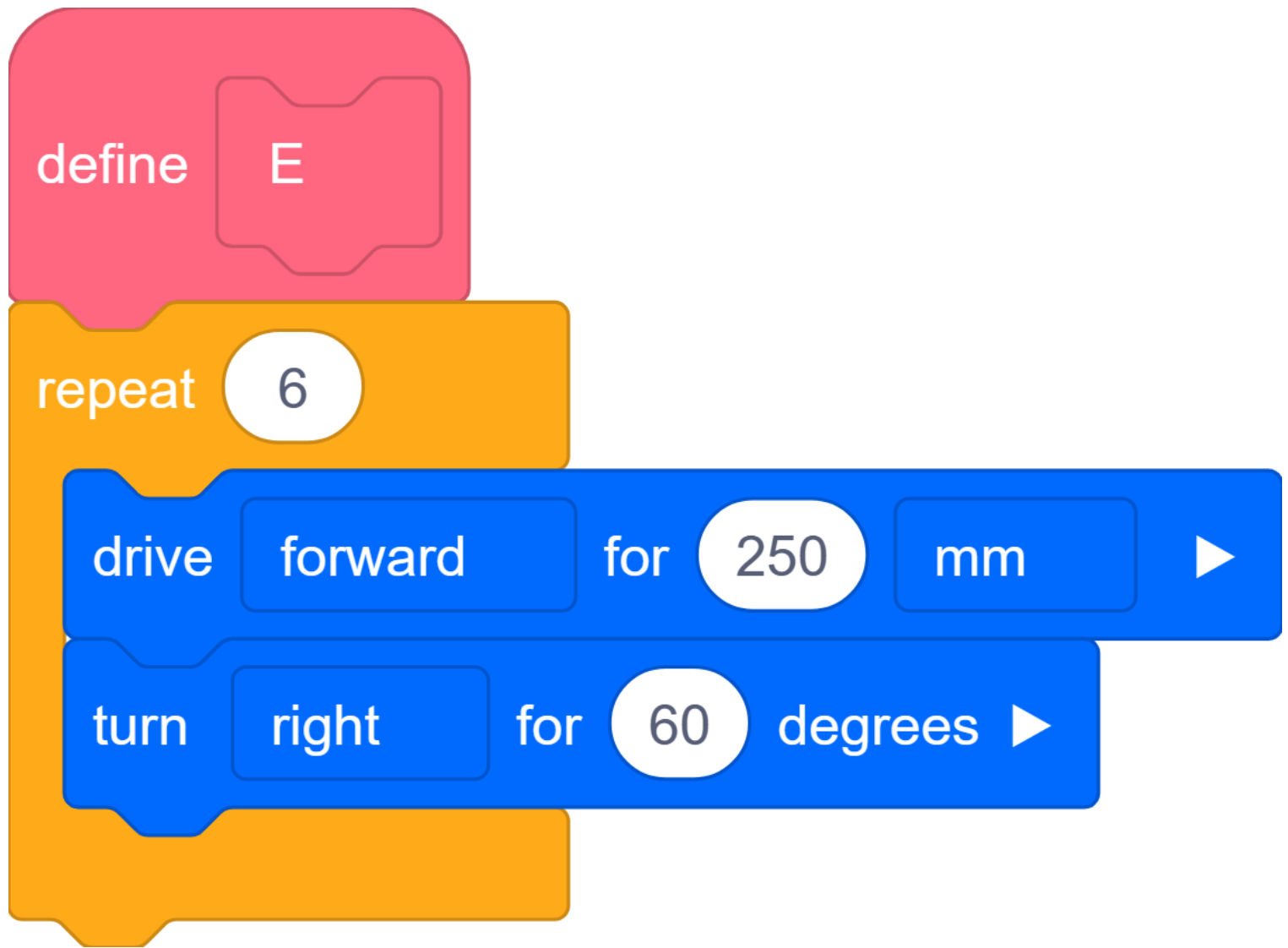
for

50

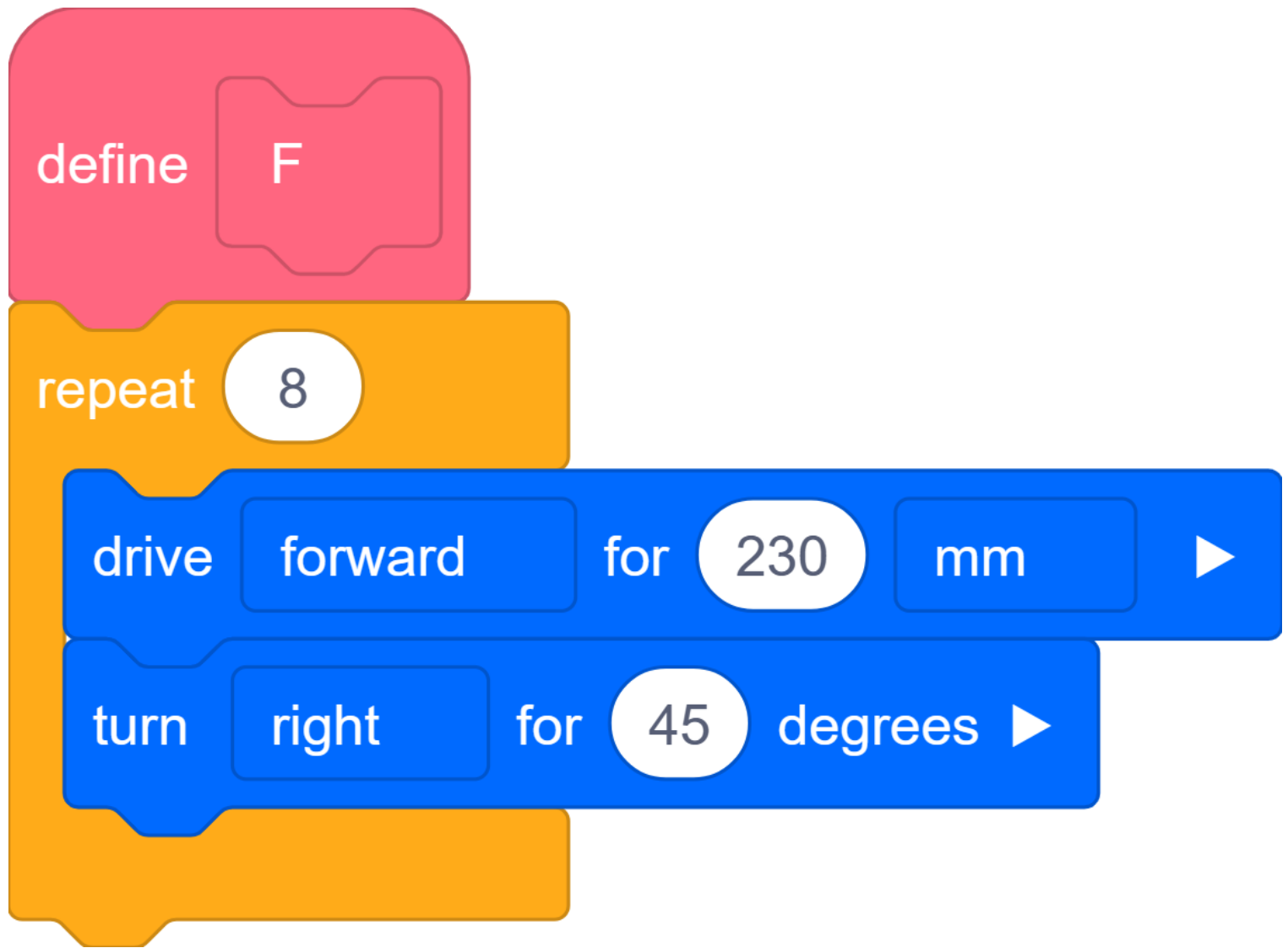
degrees

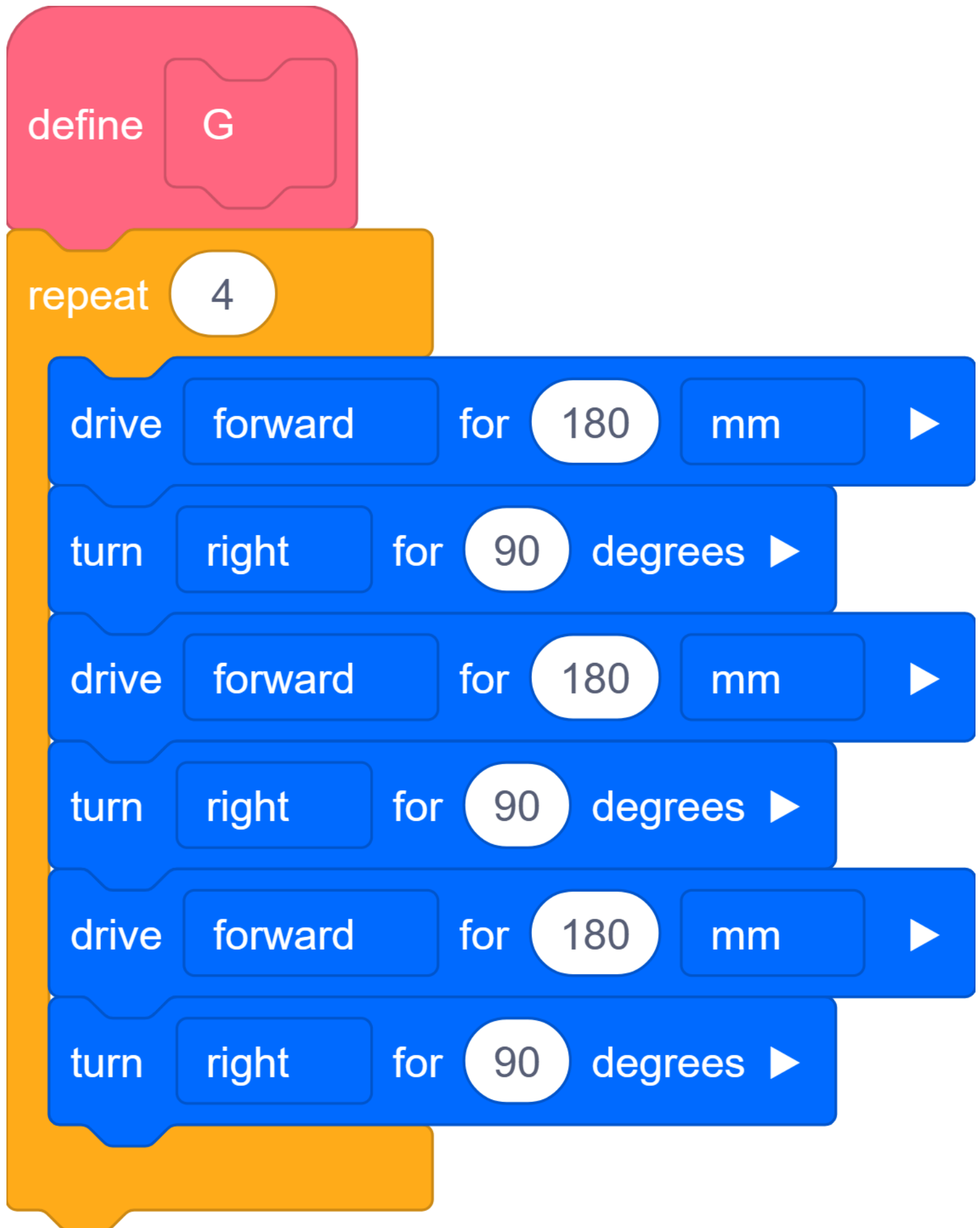












define

H

drive

forward

for

200

mm



turn

right

for

120

degrees



drive

forward

for

650

mm



turn

right

for

60

degrees



drive

forward

for

200

mm



turn

right

for

120

degrees



drive

forward

for

650

mm



define

I

drive

forward

for

525

mm



turn

right

for

135

degrees



drive

forward

for

725

mm



turn

right

for

135

degrees



drive

forward

for

525

mm



turn

right

for

90

degrees



drive

forward

for

725

mm



turn

right

for

90

degrees

