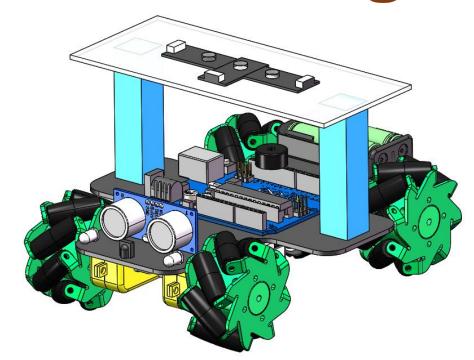


A Laser Tracing Rover

Group Members:

Kaiqi Zhu
Linghui Zhou
Lubing Han
Tianle Jiang
Xiang Li





A remote control rover that can trace lasers and help to carry things, as well as avoiding obstacles

In the Mars Base...

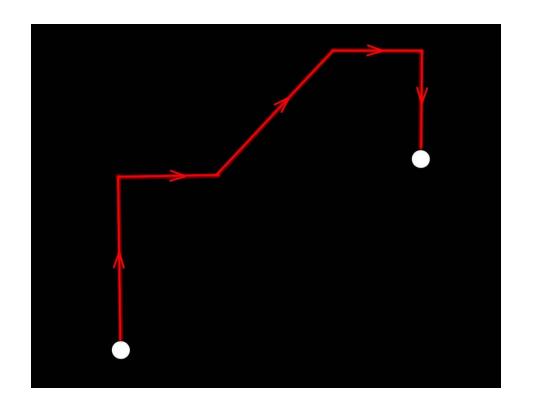
- Huge labor in transporting
- Hard to redirect motion
- Obstacles in predetermined routes
- Certain emergencies happen





Our Solution

- Utilize laser beams as signals
- Automatically follow the visible trace of lasers
- Detect obstacles and alert by beeping
- Be manually controlled by infrared remote control



Structure Details

Light Sensor

Acrylic Board

Battery Holder

Buzzer

Mechanum Wheel

Arduino Board

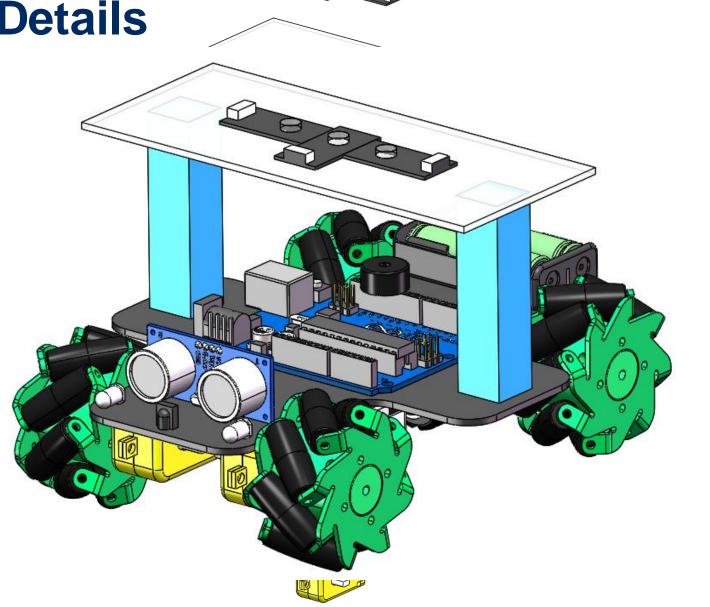
Motors

Pillars IR Sensor

Led Lights

Ultrasonic Sensor

Main Board

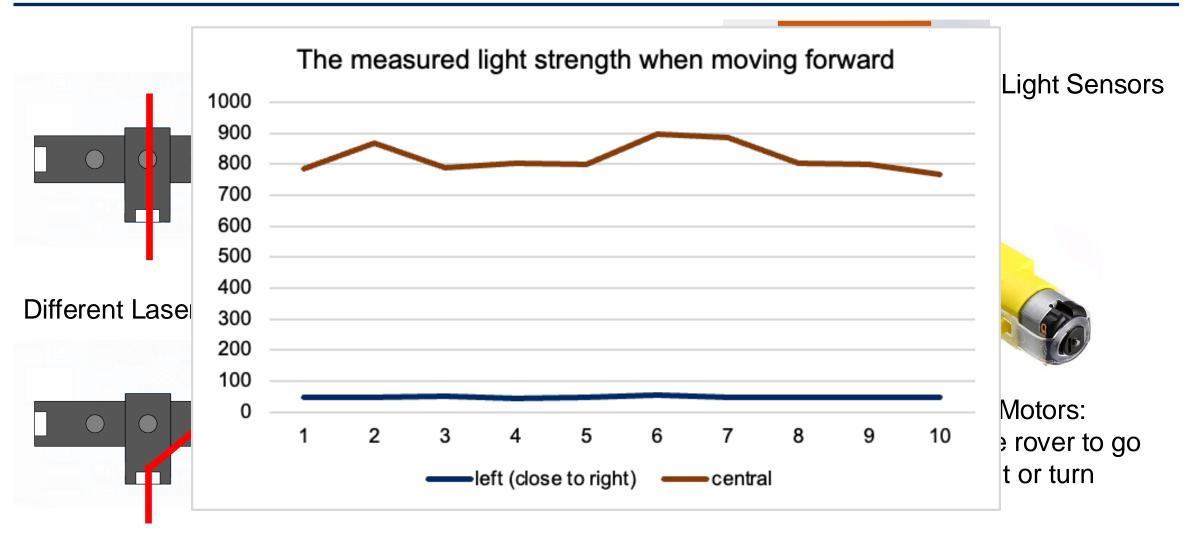




Demo Video



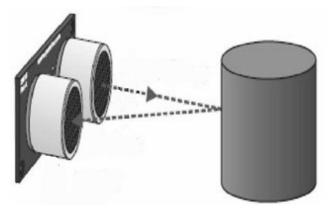
Function 1: Laser Tracing



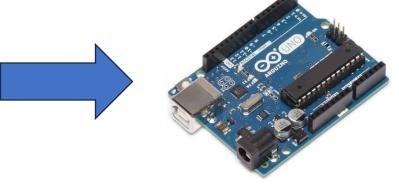
Function 2: Avoid Obstacles



Ultrasonic Sensor



Ultrasonic Reflection



Receive and transform



Arduino Board: the signals



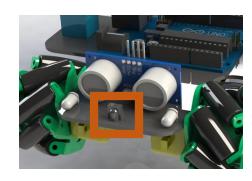
Buzzer: Alarming



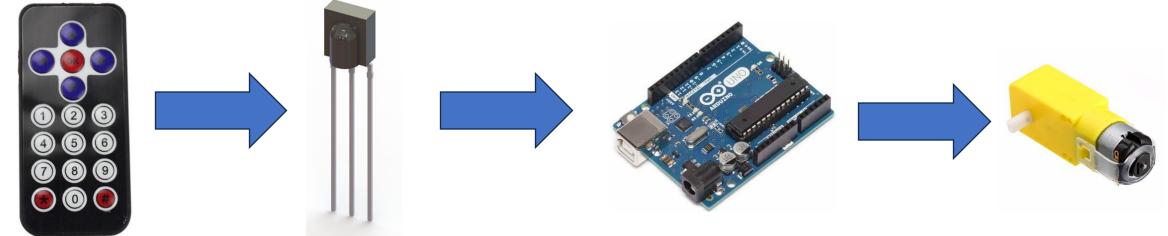
Motors: Stop



Function 3: Remote Control



Infrared sensor



Remote Control

Infrared Sensor: Receive signals

Arduino Board: Receive and transform the signals

Gear Motors: Adjust the route



Project Management

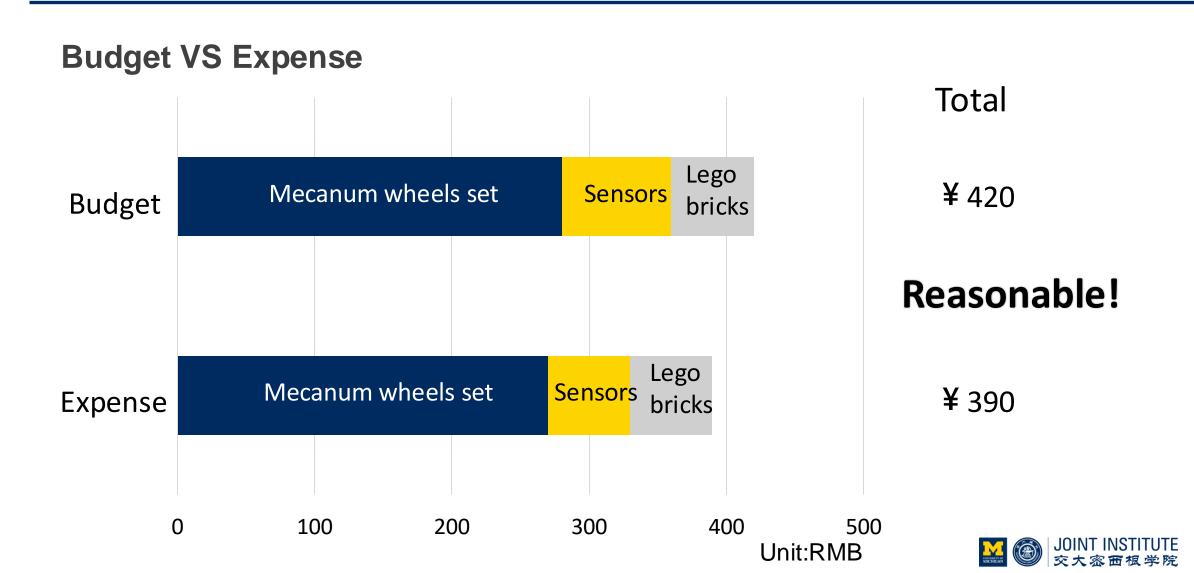
Gantt Chart for Timeline

Main Events	Week 1	Week 2	Week 3	Week 4	Week 5
Constructing the basic structure	jtl, lx, zkq				
Adjusting and fitting laser sensors			zlh, zkq		
Programming and debugging codes		jtl, lx, hlb			
Constructing the laser-covered area		hlb, zlh			
Modifying the prototype in the display area			All		
Designing the aluminum profile platform		All			

Productive!



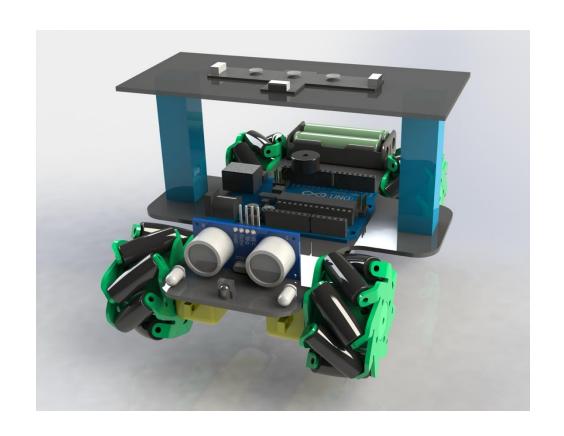
Project Management



Conclusion

- Achieve all goals
- Satisfy the basic needs
- Solve the problem on the Mars basis

Made it!



Further Direction

- Wider laser beam and larger light sensor for better detection.
- The rover can be larger to carry more things with higher efficiency.





Thank you for your attention!

Q&A

