view_frames Result

Recorded at time: 1582657011.189

world

Broadcaster: /kuka/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1582657011.189 sec old)
Buffer length: 0.000 sec

base_link

Broadcaster: /my_stp
Average rate: 10.185 Hz
Most recent transform: 1582657011.240 (-0.052 sec old)
Buffer length: 4.811 sec

Broadcaster: /kuka/robot_state_publisher
Average rate: 10.201 Hz
Most recent transform: 1582657011.185 (0.004 sec old)
Buffer length: 4.901 sec

base_link_kinect

link_1

Broadcaster: /robot_state_publisher_kinect
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1582657011.189 sec old)
Buffer length: 0.000 sec

Broadcaster: /kuka/robot_state_publisher
Average rate: 10.201 Hz
Most recent transform: 1582657011.185 (0.004 sec old)
Buffer length: 4.901 sec

torso_link

link_2

Broadcaster: /robot_state_publisher_kinect
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1582657011.189 sec old)
Buffer length: 0.000 sec

Broadcaster: /kuka/robot_state_publisher
Average rate: 10.201 Hz
Most recent transform: 1582657011.185 (0.004 sec old)
Buffer length: 4.901 sec

head_link1

link_3

Broadcaster: /robot_state_publisher_kinect
Average rate: 30.201 Hz
Most recent transform: 1582657011.155 (0.034 sec old)
Buffer length: 4.901 sec

Broadcaster: /kuka/robot_state_publisher
Average rate: 10.201 Hz
Most recent transform: 1582657011.185 (0.004 sec old)
Buffer length: 4.901 sec

head_link2

link_4

Broadcaster: /robot_state_publisher_kinect
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1582657011.189 sec old)
Buffer length: 0.000 sec

Broadcaster: /kuka/robot_state_publisher
Average rate: 10.201 Hz
Most recent transform: 1582657011.185 (0.004 sec old)
Buffer length: 4.901 sec

kinect2_ir_optical_frame

link_5

Broadcaster: /robot_state_publisher_kinect
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1582657011.189 sec old)
Buffer length: 0.000 sec

Broadcaster: /kuka/robot_state_publisher
Average rate: 10.201 Hz
Most recent transform: 1582657011.185 (0.004 sec old)
Buffer length: 4.901 sec

kinect2_rgb_optical_frame

link_6

Broadcaster: /kuka/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1582657011.189 sec old)
Buffer length: 0.000 sec

base_link_grp

Broadcaster: /kuka/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1582657011.189 sec old)
Buffer length: 0.000 sec

structure_grp

Broadcaster: /kuka/robot_state_publisher
Average rate: 10.201 Hz
Most recent transform: 1582657011.185 (0.004 sec old)
Buffer length: 4.901 sec

Broadcaster: /kuka/robot_state_publisher
Average rate: 10.201 Hz
Most recent transform: 1582657011.185 (0.004 sec old)
Buffer length: 4.901 sec

Broadcaster: /kuka/robot_state_publisher
Average rate: 10.201 Hz
Most recent transform: 1582657011.185 (0.004 sec old)
Buffer length: 4.901 sec

guide_1_grp

guide_2_grp

guide_3_grp

Broadcaster: /kuka/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1582657011.189 sec old)
Buffer length: 0.000 sec

Broadcaster: /kuka/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1582657011.189 sec old)
Buffer length: 0.000 sec

Broadcaster: /kuka/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1582657011.189 sec old)
Buffer length: 0.000 sec

finger1_grp

finger2_grp

finger3_grp