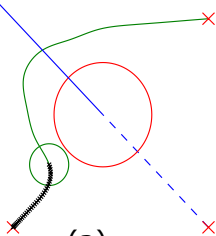
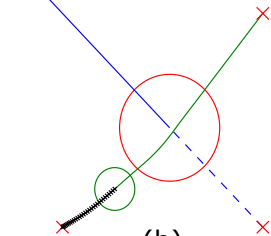


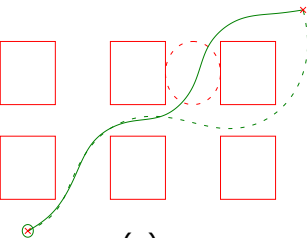
— Motion trajectory
— Linear prediction



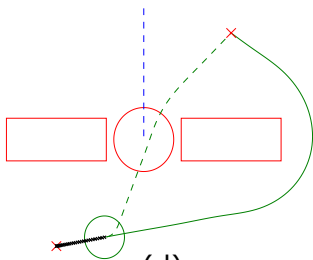
(a)



(b)



(c)



(d)