# Kevin Galassi, PhD

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 in kevin-galassi
 ♠ KevinGalassi

## Experience

CEO & CO-Founder

Bologna, Italy Jul 2024 -

 $ROBOSECT\ srl$ 

- o Design of a dual-robotic platform for electrical control panel quality control.
- o Deploy of machine learning algorithms for CV applications on GPU and Nvidia jetson.
- Management of funding activities, projects proposal and business development.

#### Postdoctoral Researcher @ INTELLIMAN Z

University of Bologna

Bologna, Italy Jul 2024 – ongoing

- Simulation of a novel gripper for food bin-picking.
- Development of Def. objects perception.

## PhD in Artificial Intelligence for 4.0 Industry

University of Bologna & Polytechnic of Turing

Bologna/Torino, Italy Nov 2021 - Nov2024

- o "Robotic Learning for Perception and Manipulation of Deformable Objects."
- o Perception algorithms for deformable linear objects (DLOs) and wiring harnesses.
- Use of LLM and foundations models for robotics.
- $\circ$  Co-supervisor of > 10 Master Thesis on various robotics topics
- Publication of > 15 articles (8 journals).
- o Tutor of "Autonomous and Mobile Robotics" (2020 Present) and additional tutoring and lecturing...

#### Research Intership

Grenoble, France

Naver Labs Europe

Mar 2023 - Sep. 2023

- Development of a Nvidia IsaacSim-based simulation for cloth-like objects
- Use of attention model for Imitation learning for a robotic cloth-smoothing task

### Visiting PhD student

Munich, Germany

Technical University of Munich (TUM)

Oct. 2022

- Testing simulating environment for Deformable linear objects manipulation.
- Application of Reinforcement Learning (SB3) for DLOs manipulation.

## Research Assistant @ REMODEL Z

University of Bologna

Bologna, Italy Oct 2021 – Oct 2022

- o Machine learning perception of deformable linear objects
- Robotic platform for electrical control panel manufacturing

### Education

# BSc & MSc in Automation Engineering

University of Bologna

Bologna, Italy Oct 2015 – Oct 2020

- MSc Thesis: "Motion and trajectory planning for a robotic manipulation of deformable electrical wires"
   [110/110 cum laude]
- $\circ\,$  UNIBO FSAE Team: Member of the Electronics Team (2018,2019), co-development of control various ETC, LCS, TCS

## Certification, Skills, Interests

Certification: English IELTS C1

**Programming**: Python, C++, **Frameworks**: ROS1/2, PyTorch, **Simulation**: PyBullet, IsaacSim, Omniverse **Tools**: SolidWorks, Creo **Soft Skills**: Grant writing, project leadership.

Interests: Swimming, planning to swim across strait of Sicily. (3.3Km)