



FUDAN SUMMER SCHOOL INTRODUCTION TO AI

Probabilistic Reasoning and Decision Making
Day 4 – Conditional Independence, d-separation

Conditional independence revisited

full joint

$$P(X_1, X_2, \dots, X_n) = \overset{\text{product}}{P(X_1)P(X_2|X_1) \dots P(X_n|X_1, X_2, \dots, X_{n-1})}$$

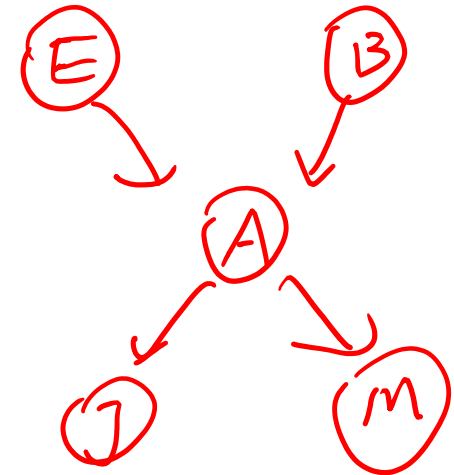
$$= \prod_{i=1}^n P(X_i|X_1, X_2, \dots, X_{i-1})$$

always true

Suppose that in any given domain:

$$P(J|A, E, B)$$

$$= P(J|A)$$



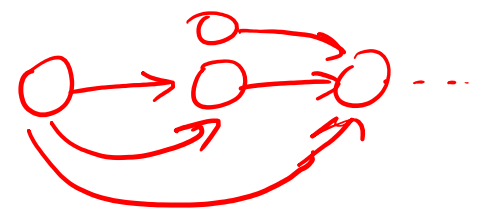
$$P(E, B, A, J, M) = P(E)P(B)P(A|E, B)P(J|A)P(M|A)$$

For Bayes Net

$$P(X_1 \dots X_n) = \prod_{i=1}^n P(X_i | Pa(X_i))$$

How to build a Bayes Net?

: DAG



1. Choose random variables $\{X_1, X_2, \dots, X_n\}$

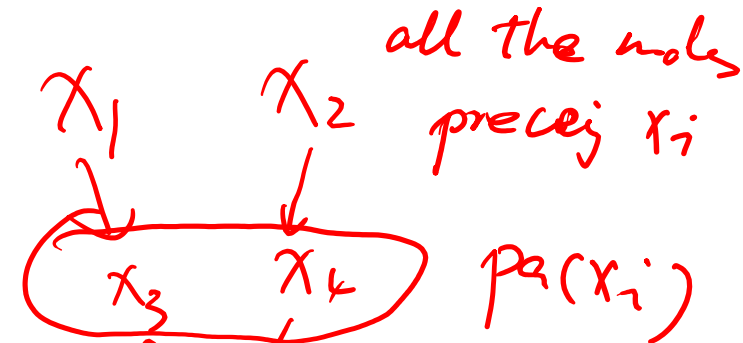
2. Choose an ordering — choose parents & their ordering

3. While there are variables left:

1. Add node X_i to the BN

2. Set parents of X_i to the minimal subset such that X_i is conditionally independent from non-parent nodes preceding i , given its parents.

3. Define $P(X_i | \text{parent}(X_i))$ CPT $\frac{P_i(x_i)}{x_i = 1}$
 combinations prob



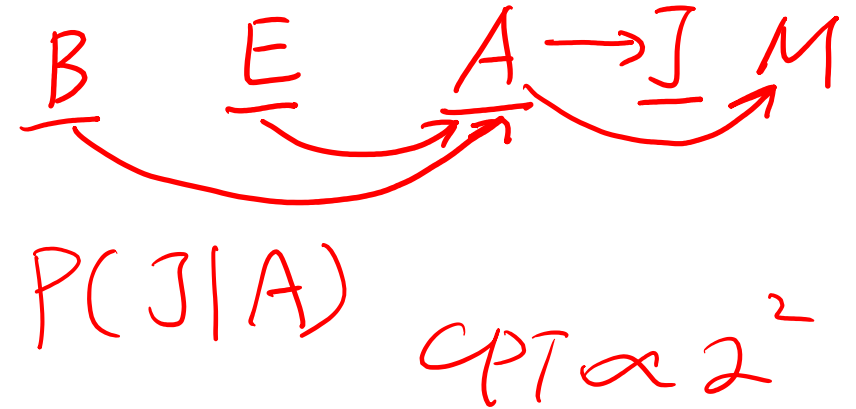
$$P(X_5 | X_1, X_2, X_3, X_4) = P(X_5 | X_3, X_4)$$

How to build a Bayes Net?

1. Choose random variables
2. Choose an ordering
3. While there are variables left:
 1. Add node X_i to the BN
 2. Set parents of X_i to the minimal subset such that X_i is conditionally independent from non-parent nodes preceding i , given its parents.
 3. Define $P(X_i | \text{parent}(X_i))$ CPT

Which is the better ordering to choose?

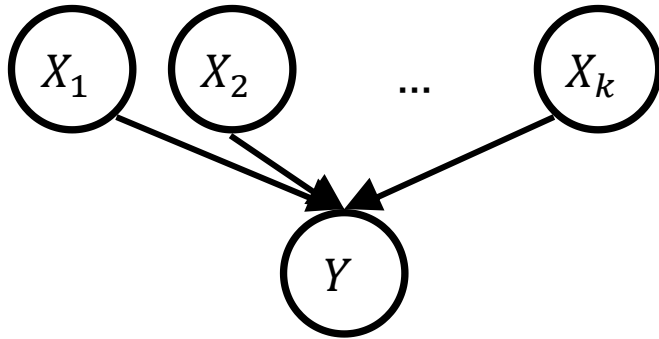
- A. Root events first (i.e. causes), e.g. B, E, A, J, M
- B. Child events first (i.e. consequences), e.g. M, J, A, E, B
- C. It doesn't matter



$$CPT \propto \frac{\text{max \# of parents any node has}}{2}$$

$$\frac{P(J|A, E, B)}{\propto 2^3}$$

Representing CPTs



How do we represent the CPT?

Option 1: CPT

x_1, x_2, \dots, x_k	$P(Y=1)$
0 0 - - - 0	$P(Y=1 \mid x_1=0, x_2=0, \dots, x_k=0)$
0 0 - - - 1	
1 0 - - - 1	
1 1 - - - 1	
1 1 - - - 1	
1 1 1 - - 1	$P(Y=1 \mid x_1=1, x_2=1, \dots, x_k=1)$

Advantage: very easy
to read

disadvantage: size exponential

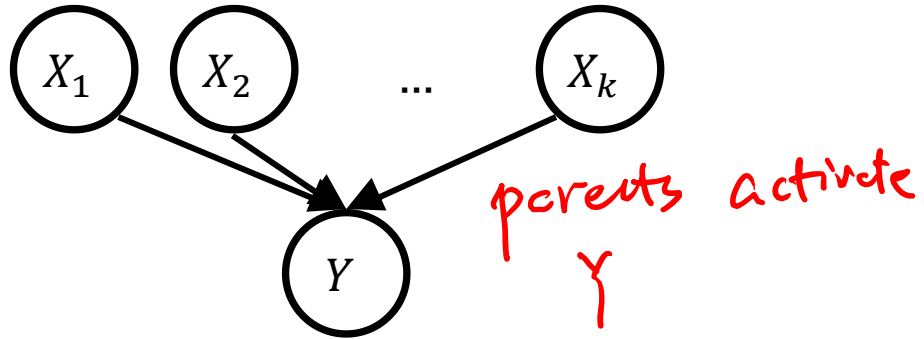
$$k = 20 \text{ or } 2^{20} = \frac{1M}{\text{decim}}$$

X_1	X_2	X_3	$P(Y=1)$
1	0	1	

Index

8 rows

Representing CPTs



advantage: save space (just do calculation)

disadvantage: deterministic

How do we represent the CPT?

option 2: OR logic

make $P(Y=1)$ deterministic of its parents

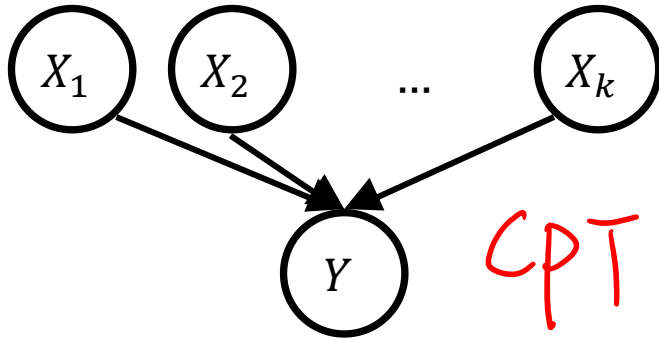
$$P(Y=1 \mid X_1 \dots X_k) = \text{OR}(X_1 \dots X_k)$$

$$\text{OR}(X_1 \dots X_k) = \begin{cases} 1 & \text{if any } x_i = 1 \\ 0 & \text{otherwise} \end{cases}$$

$$P(Y=0 \mid X \dots X_k) = 1 - \text{OR}(X_1 \dots X_k)$$

Representing CPTs

How do we represent the CPT?



CPT: 2^k entries

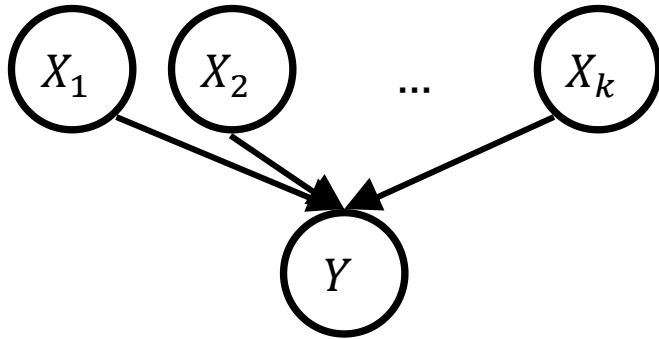
noisy-or: k -params
(reduce the
size a lot)

option 3: middle ground: noisy-or
use k -parameters to model the
relationship $p_i \in [0, 1], 1 \leq i \leq k$

$$P(Y=0 | x_1 \dots x_k) = \frac{1}{Pa(Y)} \prod_{i=1}^k (1 - p_i)^{x_i} \text{ assuming } x_i \text{ is } \{0, 1\}$$

$$P(Y=1 | x_1 \dots x_k) = 1 - \prod_{i=1}^k (1 - p_i)^{x_i}$$

Noisy-OR



if all parents are inactive, the child is guaranteed to be inactive

What is the value of $P(Y = 1 | X_1 = 0, X_2 = 0, \dots, X_k = 0)$?

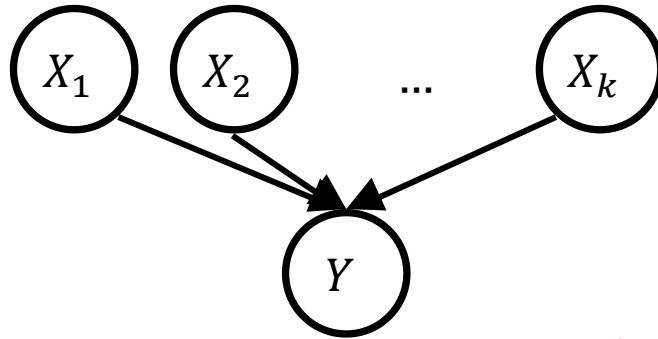
- A. 0
- B. p_i
- C. 1
- D. None of these
- E. Not enough information given

$$P(Y=1 | X_1 \dots X_k) = 1 - \prod_{i=1}^k (1 - p_i)^{x_i}$$

$$P(Y=1 | X_1=0, X_2=0, \dots, X_k=0)$$

$$= 1 - \prod_{i=1}^k \underbrace{(1 - p_i)^0}_1 = 1 - 1 = 0$$

Noisy-OR



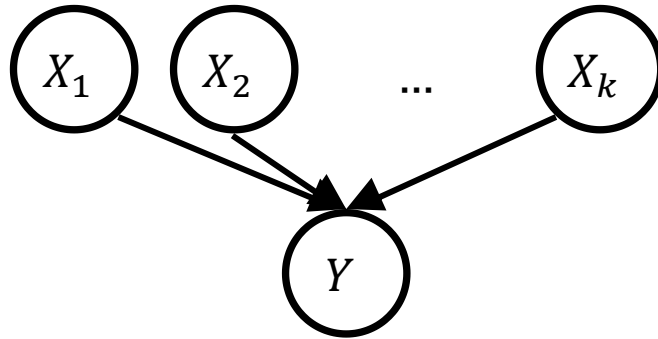
What is the value of $P(Y = 1 | X_1 = 0, X_2 = 0, \dots, X_i = 1, \dots, X_k = 0)$?

- A. 0
- B. p_i
- C. 1
- D. None of these
- E. Not enough information given

p_i : the probability that X_i alone will activate Y .

$$P(Y=1 | X_1, X_2, \dots, X_k) = 1 - \prod_{i=1}^k (1 - p_i)^{X_i}$$
$$P(Y=1 | X_1=0 \dots X_{i-1}=0, X_i=1, X_{i+1}=0 \dots X_k=0)$$
$$= 1 - (1 - p_i)^1 = p_i$$

Noisy-OR



Let $P(Y = 1 | X_1 = 0, \dots, X_i = 1, X_j = 1, \dots, X_k = 0) = \frac{1}{3}$ if only 3 parents

and $p_i = \frac{1}{5}$

What is p_j ?

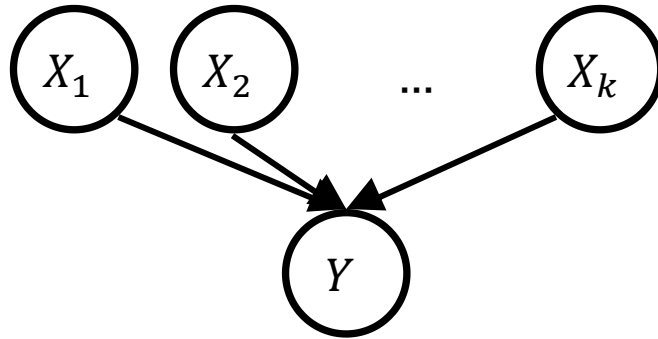
- A. $\frac{1}{6}$
- B. $\frac{2}{5}$
- C. $\frac{1}{15}$
- D. $\frac{2}{3}$
- E. I have no idea

CPT : $\boxed{p_1, p_2, p_3}$ noisy or

X_1	X_2	X_3	$P(Y=1)$
0	0	0	0
0	0	1	p_3
0	1	0	p_2
0	1	1	$1 - (1 - p_2)(1 - p_3)$
1	0	0	p_1
1	0	1	$1 - (1 - p_1)(1 - p_3)$
1	1	0	$1 - (1 - p_1)(1 - p_2)$
1	1	1	$1 - (1 - p_1)(1 - p_2)(1 - p_3)$

CPT

Noisy-OR



Let $P(Y = 1|X_1 = 0, \dots, X_i = 1, X_j = 1, \dots, X_k = 0) = \frac{1}{3}$

and $p_i = \frac{1}{5}$

What is p_j ?

A. $\frac{1}{6}$

B. $\frac{2}{5}$

C. $\frac{1}{15}$

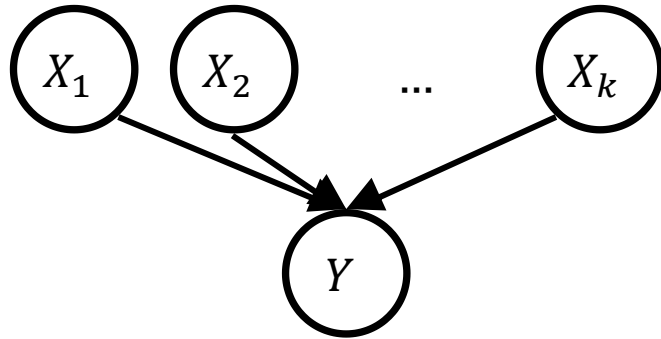
D. $\frac{2}{3}$

E. I have no idea

$$P(Y = 1|X_1, \dots, X_k) = 1 - \prod_{i=1}^k (1 - p_i)^{X_i}$$

$$1 - \left(1 - \frac{1}{5}\right)(1 - p_j) = \frac{1}{3}$$

Noisy-OR



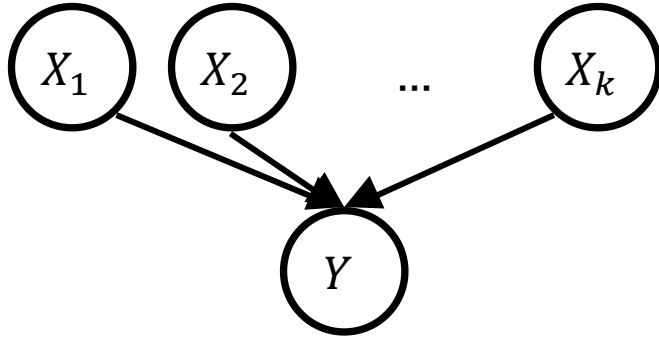
Is it true that $P(X_i=1) = p_i$

- A. Yes
- ☒ B. NO

$p_i = P(X_i=1, \text{ other } X=0)$

$$P(Y = 1 | X_1, \dots, X_k) = 1 - \prod_{i=1}^k (1 - p_i)^{X_i}$$

Noisy-OR: Intuition



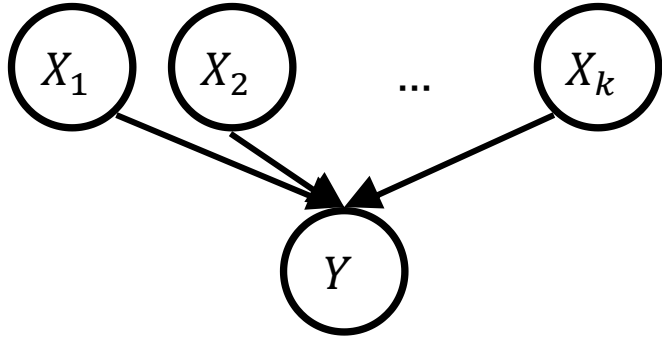
$$P(Y = 1 | X_1, \dots, X_k) = 1 - \prod_{i=1}^k (1 - p_i)^{X_i}$$

Let $P(Y = 1 | X_1 = 1, X_2 = 1, \dots, X_{i-1} = 1, X_i = 0, \dots, X_k = 0) = a$
and $P(Y = 1 | X_1 = 1, X_2 = 1, \dots, X_{i-1} = 1, \textcircled{X_i = 1}, X_{i+1} = 0, \dots, X_k = 0) = b$
What is the relationship between a and b ?

- ☒ A. $a \leq b$
- ☐ B. $a = b$
- ☐ C. $a \geq b$
- ☐ D. There is not enough information to determine the relationship

$$\begin{aligned} &= 1 - \prod_{j=1}^{i-1} (1 - p_j) \\ &= 1 - \prod_{j=1}^i (1 - p_j) \\ &= 1 - \frac{(1 - p_i) \prod_{j=1}^{i-1} (1 - p_j)}{1} \end{aligned}$$

Noisy-OR: Intuition



$$\underline{P(Y = 1 | X_1, \dots, X_k)} = 1 - \prod_{i=1}^k (1 - p_i)^{X_i}$$

max of probability is when all $x_i = 1$

- When all parents are off, child is off with certainty (just like OR).
- Each parent that turns on increases (or at least does not decrease) the probability that the child will turn on.
- When all the parents are on, it still might not be certain that the child is on, but it is probably very likely.

Bayesian Networks: Network structure and conditional independence

- By our construction of a Bayes' net, we know that a node is conditionally independent of its non-parent ancestors given its parents:

$$\begin{aligned} P(X_1, X_2, \dots, X_n) &= P(X_1)P(X_2|X_1) \dots P(X_n|X_1, X_2, \dots, X_{n-1}) \\ &= \prod_{i=1}^n P(X_i|X_1, X_2, \dots, X_{i-1}) \\ &= \prod_{i=1}^n P(X_i|\text{parents}(X_i)) \end{aligned}$$

But what about more general assertions of independence?

Bayesian Networks: Network structure and conditional independence

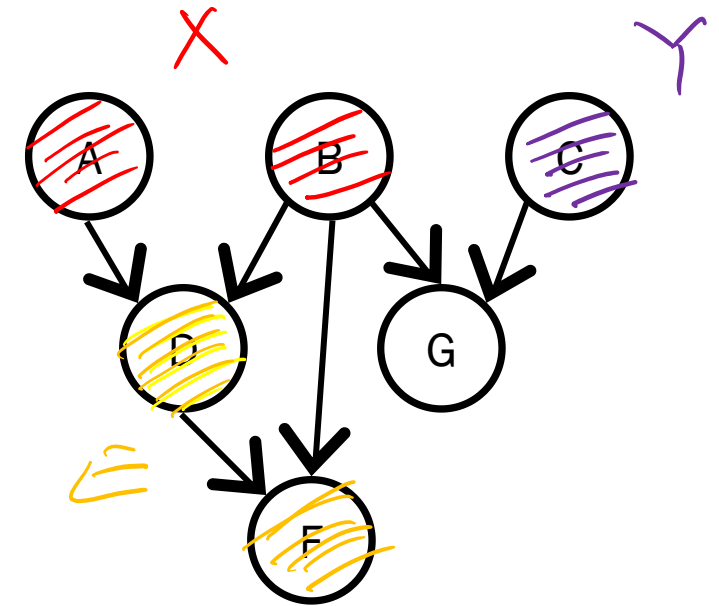
$X = \{A, B\}$
 $Y = \{C\}$
 $E = \{D, F\}$

$\Rightarrow X, Y, E$ have no common nodes

- Let X , Y and E refer to disjoint sets of nodes. When is X conditionally independent of Y given E (evidence)?

Write three equalities using $P(X|Y, E)$, $P(Y|X, E)$, $P(X, Y|E)$, etc, that indicate this conditional independence.

$$\left\{ \begin{array}{l} P(X|Y, E) = P(X|E) \\ P(Y|X, E) = P(Y|E) \\ P(X, Y|E) = P(X|E)P(Y|E) \end{array} \right.$$



Bayesian Networks: Network structure and conditional independence

- Let X , Y and E refer to disjoint sets of nodes. When is X conditionally independent of Y given E (evidence)?

Theorem: $P(X, Y|E) = P(X|E)P(Y|E)$ if and only if every UNDIRECTED path from a node in X to a node in Y is "d-separated" ("blocked") by E .

(we will not prove this)

~~X~~ undirected path:
ignore edge direction

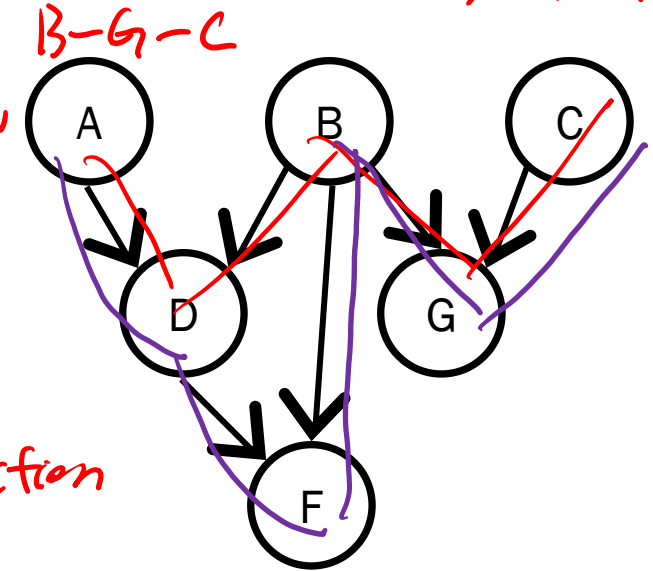
undirected path from A to C

A - D - B - G - C

A - D - F - B - G - C

every undirected path:
all possible undirected path
from any node in X to nodes in Y
 $X: \{A, B\}$, $Y: \{C\}$

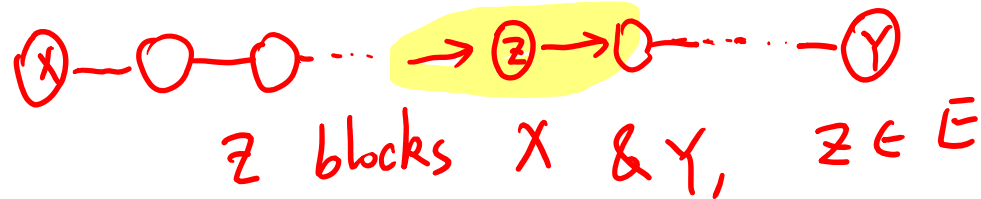
all possible path
A - D - B - G - C,
A - D - F - B - G - C,



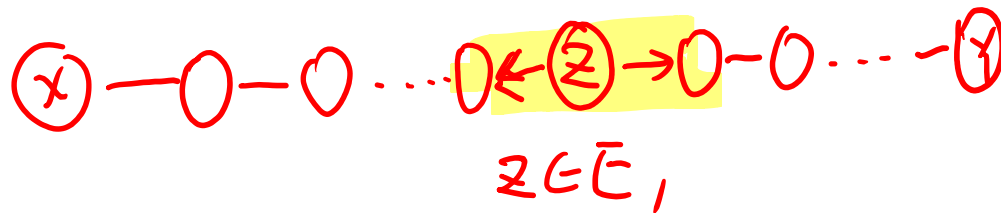
d-separation ("dependence" separation)

Definition: A path π (sequence of nodes connected by edges) is d-separated if there exists some node $z \in \pi$ for which one of the following three conditions hold:

Condition 1:

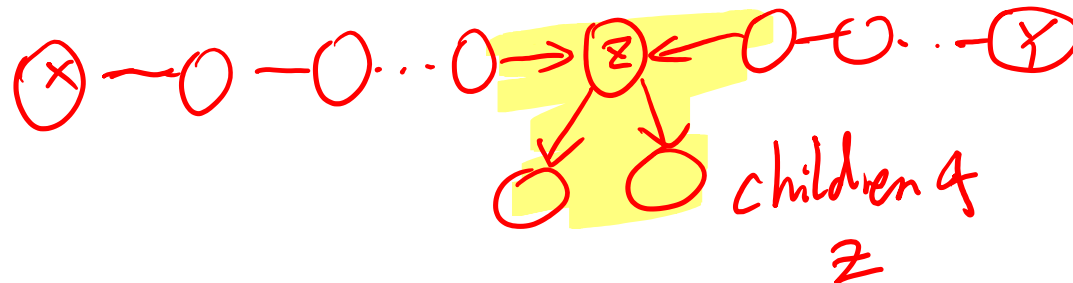


Condition 2:

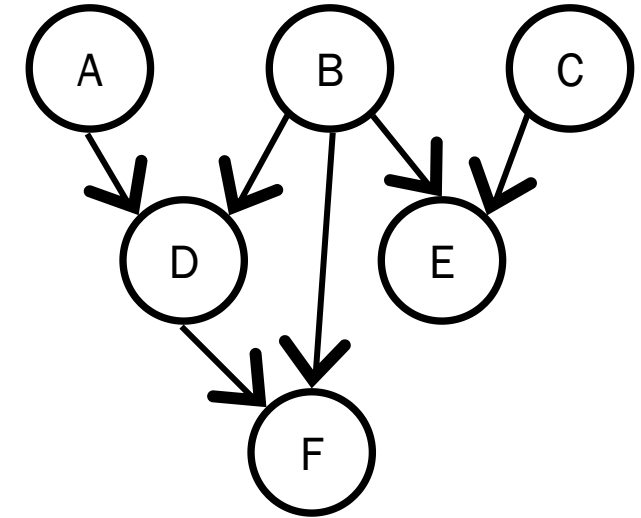


z is the common cause

Condition 3:



z is the common consequence, $z \notin E$, children of $z \notin E$




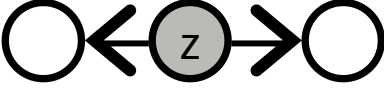
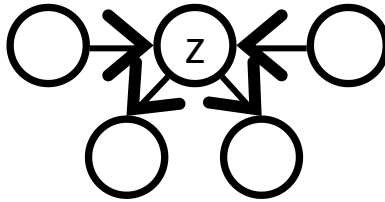
Conditional Independence

$$P(B|A, M) = P(B|A)$$

A. True
B. False

Theorem: $P(X, Y|E) = P(X|E)P(Y|E)$ if and only if **every** UNDIRECTED path from a node in X to a node in Y is "d-separated" ("blocked") by E .

Definition: A path π (sequence of nodes connected by edges) is d-separated if there exists some node $z \in \pi$ for which **one** of the following three conditions hold:

1.  $z \in E$ (observed event in causal chain)
2.  $z \in E$ (observed common explanation)
3.  $z \notin E, \text{descendants}(z) \notin E$ (no observed common effect)

Steps: ① list X, Y, E

② ignore all directions on edges, list all paths from X to Y

③ highlight evidence nodes, put back the direction of edges, check if all paths are d-sep

