

Q18

$$a) \quad p(\text{inlier}) = \frac{4}{10} = \frac{2}{5}$$

$$\underline{p(2 \text{ inliers}) = \frac{2}{5} \times \frac{2}{5} = \frac{4}{25}}$$

$$\frac{4}{10} \times \frac{3}{10} \quad \leftarrow \text{different points}$$

$$= \frac{3}{25}$$

$$b) \quad p(\text{incorrect sample}) = 1 - \frac{4}{25} = \frac{21}{25}$$

$$p(\text{all incorrect in } k) = \frac{21^k}{25^k}$$

$$\frac{21^k}{25^k} < 0.05$$

$$k \log \frac{21}{25} < \log 0.05$$

$$k > \frac{\log 0.05}{\log \frac{21}{25}}$$

(note div by -ve,
reverse sign)

Q19

$$\begin{array}{ccc} & t & \\ 0 & 7 & 4 \\ 3 & \boxed{3} & \boxed{3} \\ 0 & \boxed{10} & 8 \end{array}$$

$$\begin{array}{ccc} & t+1 & \\ 10 & 3 & 5 \\ 3 & \boxed{5} & 1 \\ 6 & 7 & 1 \end{array}$$

$$I_x = 3 - 3 = 0$$

$$I_y = 10 - 3 = 7$$

$$I_t = 5 - 3 = 2$$

$$0u + 7v + 2 = 0$$

$$\underline{v = -2/7}$$

u is undefined \rightarrow could be any value

Q21

$$\hat{y}_0 = \text{sign}(w_0 \cdot x_0)$$

$$= \text{sign}\left(\begin{bmatrix} 1 \\ 0 \end{bmatrix} \cdot \begin{bmatrix} -1 \\ -1 \end{bmatrix}\right) = -1, \quad y_0 = -1, \quad w_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \quad \text{correct class, do nothing}$$

$$\hat{y}_1 = \text{sign}(w_1 \cdot x_1)$$

$$= \text{sign}\left(\begin{bmatrix} 1 \\ 0 \end{bmatrix} \cdot \begin{bmatrix} -1 \\ 1 \end{bmatrix}\right) = -1, \quad y_1 = +1, \quad w_2 = w_1 + y_1 x_1 \\ = \begin{bmatrix} 1 \\ 0 \end{bmatrix} + \begin{bmatrix} -1 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$\hat{y}_2 = \text{sign}(w_2 \cdot x_2)$$

$$= \text{sign}\left(\begin{bmatrix} 0 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 1 \end{bmatrix}\right) = 1, \quad y_2 = +1, \quad w_3 = \begin{bmatrix} 0 \\ 1 \end{bmatrix} \quad \text{correct class, do nothing}$$

$$\hat{y}_3 = \text{sign}(w_3 \cdot x_3)$$

$$= \text{sign}\left(\begin{bmatrix} 0 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} -0.5 \\ 0.1 \end{bmatrix}\right) = \text{sign}(0.1) = 1, \quad y_3 = -1, \quad w_4 = w_3 + y_3 x_3 \\ = \begin{bmatrix} 0 \\ 1 \end{bmatrix} - \begin{bmatrix} -0.5 \\ 0.1 \end{bmatrix} \\ = \begin{bmatrix} 0.5 \\ 0.9 \end{bmatrix}$$

$$\text{check } \text{sign}(w_4^T x_i) = y_i ?$$

Perceptron rule would fail if data are not linearly separable from the origin.