- Short answer questions. Each part below is independent of the others.
 - (a) (3 marks) True or False: If A is an invertible matrix, then $||A^{-1}|| = ||A||^{-1}$. Justify your answer.

$$||A|| = \max_{\|\vec{A}\vec{x}\|} ||A\vec{x}\|| \Rightarrow ||A||^{-1} = \frac{1}{\max_{\|\vec{x}\|=1}} ||A||^{-1} || = \frac{1}{\min_{\|\vec{x}\|=1}} ||A\vec{x}|| \neq \frac{1}{\max_{\|\vec{x}\|=1}} ||A||^{-1} = ||A||^{-1} =$$

(b) (3 marks) True or False: There exists a unique polynomial p(t) of degree 2 (or less) such that

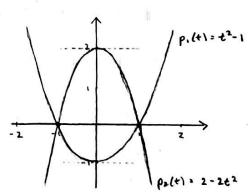
$$p(-1) = p'(0) = p(1) = 0$$

Justify your answer.

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There are infinitely many polynomials of degree <2 satisfying the given conditions.

$$\begin{cases} a-b+c=0\\ b=0\\ a+b+c=0 \end{cases}$$



(c) (3 marks) Determine (approximately) the condition number of the matrix

$$A = \begin{bmatrix} c & 1 & & & \\ 1 & c & 1 & & & \\ & \ddots & \ddots & \ddots & \\ & & 1 & c & 1 \\ & & & 1 & c \end{bmatrix}$$

where c is very large positive number. Justify your answer.

(d) (3 marks) Consider 11 data points $(t_0, y_0), \ldots, (t_{10}, y_{10})$ such that $t_k - t_{k-1} = 1$ for each $k = 1, \ldots, 10$. Suppose the coefficient matrix of the corresponding natural cubic spline is given by

$$\begin{bmatrix} -1 & 2 & 6 & -9 & -1 & 3 & 2 & 8 & 3 & -13 \\ 0 & -3 & 3 & 21 & -6 & -9 & 0 & 6 & 30 & 39 \\ 2 & -1 & -1 & 23 & 38 & 23 & \Box & 20 & 56 & 125 \\ -7 & -6 & -8 & 0 & 35 & 66 & 83 & 99 & 133 & 222 \end{bmatrix}$$

Determine the missing value \square .

=> 2+0+ \(\pi + 83 = 99 \) \(\pi > \(\pi = 14 \)

$$\rho_{k}(t) = a_{k} (t - t_{k-1})^{3} + b_{k} (t - t_{k-1})^{2} + C_{k} (t - t_{k-1}) + d_{k}$$

$$\Rightarrow \rho_{k}'(t) = 3a_{k} (t - t_{k-1})^{2} + 2b_{k} (t - t_{k-1}) + C_{k} , t \in [t_{k-1}, t_{k}]$$
Since $\rho'(t)$ should be continuous, $\rho_{k}'(t_{k}) = \rho_{k+1}(t_{k}) , k=1,...,9$

$$\Rightarrow 3a_{k} (t_{k} - t_{k-1})^{2} + 2b_{k} (t_{k} - t_{k-1}) + C_{k} = C_{k+1}$$

$$= 1$$

$$= 1$$

$$k = 7 : 3a_{7} + 2b_{7} + C_{7} = C_{8} \implies 3 \cdot 2 + 2 \cdot 0 + \Box = 20 \implies \Box = 14$$
or from $\rho_{k}(t_{k}) = \rho_{k+1}(t_{k})$ with $t_{k} - t_{k-1} = 1$, we get: $a_{k} + b_{k} + C_{k} + d_{k} = d_{k+1}$

2. (5 marks) Determine all values c such that the vectors

$$u_1 = \begin{bmatrix} -1 \\ -2 \\ 5 \end{bmatrix} \qquad u_2 = \begin{bmatrix} 2 \\ 3 \\ -6 \end{bmatrix} \qquad u_3 = \begin{bmatrix} 4 \\ 5 \\ c-1 \end{bmatrix}$$

are linearly independent.

The vectors
$$\vec{u_1}$$
, $\vec{u_2}$ and $\vec{u_3}$ are linearly independent if $a_1 \vec{u_1} + a_2 \vec{u_2} + a_3 \vec{u_3} = \vec{0}$ if and only if $a_1 = a_2 = a_3 = 0$

We want to find a such that the system

$$\begin{bmatrix} \vec{u_1} & \vec{u_2} & \vec{u_3} \end{bmatrix} \begin{bmatrix} a_1 \\ a_2 \\ a_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \text{ has a unique solution } \left(a_1 = a_2 = a_3 = 0 \right).$$

Gaussian elimination:

$$\begin{bmatrix} -1 & 2 & 4 & | & 0 \\ -2 & 3 & 5 & | & 0 \\ 5 & -6 & 2 - 1 & | & 0 \end{bmatrix} \rightarrow \begin{bmatrix} -1 & 2 & 4 & | & 0 \\ 0 & -1 & -3 & | & 0 \\ 0 & 4 & 2 + 19 & | & 0 \end{bmatrix}$$

$$\rightarrow \begin{bmatrix} -1 & 2 & 4 & 0 \\ 0 & -1 & -3 & 0 \\ 0 & 0 & c+7 & 0 \end{bmatrix}$$

We see that the system has a unique solution if $C \neq -7$ and infinitely many solutions if C = -7

3. Consider the matrix

$$A = \begin{bmatrix} 2 & 1 & 1 & 0 \\ 8 & 3 & 8 & 2 \\ -4 & -3 & 5 & -1 \\ 2 & -2 & 7 & 11 \end{bmatrix}$$

- (a) (4 marks) Find the LU decomposition of A.
- (b) (2 mark) Compute $\det(A)$.

$$\begin{pmatrix} a \end{pmatrix} \begin{bmatrix} 2 & 1 & 1 & 0 \\ 8 & 3 & 8 & 2 \\ -4 & -3 & 5 & -1 \\ 2 & -2 & 7 & 11 \end{bmatrix}
\xrightarrow{R_3 - 2R_1}
\begin{bmatrix} 2 & 1 & 1 & 0 \\ 0 & -1 & 4 & 2 \\ 0 & -1 & 7 & -1 \\ 0 & -3 & 6 & 11 \end{bmatrix}
\xrightarrow{R_3 - R_2}
\begin{bmatrix} 2 & 1 & 1 & 0 \\ 0 & -1 & 4 & 2 \\ 0 & 0 & 3 & -3 \\ 0 & 0 & -6 & 5 \end{bmatrix}$$

$$\Rightarrow A = LU \text{ where } L = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 4 & 1 & 0 & 0 \\ -2 & 1 & 1 & 0 \\ 1 & 3 & -2 & 1 \end{bmatrix}, U = \begin{bmatrix} 2 & 1 & 1 & 0 \\ 0 & -1 & 4 & 2 \\ 0 & 0 & 3 & -3 \\ 0 & 0 & 0 & -1 \end{bmatrix}$$

(b)
$$det(A) = det(U) = picduct of elements on diagonal$$

= $2 \cdot (-1) \cdot 3 \cdot (-1) = (6)$

4. (6 marks) Setup (but do not solve) a linear system Ax = b such that the solution

$$oldsymbol{x} = egin{bmatrix} a \ b \ c \ d \end{bmatrix}$$

determines the unique function of the form

$$f(t) = a\sin(\pi t) + b\cos(\pi t) + c\sin(2\pi t) + d\cos(2\pi t)$$

which interpolates the data $(0, y_0)$, $(1/4, y_1)$, $(1/2, y_2)$, $(3/4, y_3)$. The system depends on y_0, y_1, y_2, y_3 .

We should have:

$$f(0) = y_0 \Rightarrow a \sin(0) + b \cos(0) + c \sin(0) + d \cos(0) = y_0$$

 $\Leftrightarrow b + d = y_0$

$$f\left(\frac{1}{4}\right) = y_1 \implies a \sin\left(\frac{\pi}{4}\right) + b \cos\left(\frac{\pi}{4}\right) + c \sin\left(\frac{\pi}{2}\right) + d \cos\left(\frac{\pi}{2}\right) = y_1$$

$$\iff \frac{2}{12} + \frac{b}{12} + c = y_1$$

$$f(\frac{1}{2}) = \gamma_2 \implies \alpha \sin(\frac{\pi}{2}) + b \cos(\frac{\pi}{2}) + c \sin(\pi) + d \cos(\pi) = \gamma_2$$

$$\Leftrightarrow \alpha - d = \gamma_2$$

$$f(\frac{3}{4}) = y_3 \implies a \sin(\frac{3\pi}{4}) + b \cos(\frac{3\pi}{4}) + c \sin(\frac{3\pi}{4}) + d \cos(\frac{3\pi}{4}) = y_3$$

$$\Rightarrow \frac{a}{\sqrt{2}} - \frac{b}{\sqrt{2}} - c = y_3$$

$$= \Rightarrow \begin{bmatrix} 0 & 1 & 0 & 1 \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} & 1 & 0 \\ 1 & 0 & 0 & -1 \\ \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} & -1 & 0 \end{bmatrix} \begin{bmatrix} q \\ b \\ c \\ d \end{bmatrix} = \begin{bmatrix} \gamma_0 \\ \gamma_1 \\ \gamma_2 \\ \gamma_3 \end{bmatrix}$$

$$A \qquad \overrightarrow{x} \qquad \overrightarrow{b}$$

5. (6 marks) Find all polynomials p(t) of degree 3 (or less) such that

$$p(1) = p(-1) p(-2) = -7p(0) p'(1) = 3p'(-1) 5p''(1) = -7p''(-1)$$

$$\rho(t) = at^{3} + bt^{2} + ct + d$$

$$\rho'(t) = 3at^{2} + 2bt + c$$

$$\rho''(t) = 6at + 2b$$

The conditions give:

$$\Rightarrow \begin{bmatrix} 1 & 0 & 1 & 0 & | & 0 \\ -4 & 2 & -1 & 4 & | & 0 \\ 3 & -4 & 1 & 0 & | & 0 \\ 1 & -2 & 0 & 0 & | & 0 \end{bmatrix} \xrightarrow{R_2 + 4R_1} \begin{bmatrix} 1 & 0 & 1 & 0 & | & 0 \\ R_3 - 3R_1 & | & 0 & | & 0 \\ 0 & 2 & 3 & 4 & | & 0 \\ 0 & -4 & -2 & 0 & | & 0 \end{bmatrix} \xrightarrow{R_3 + 2R_2} \begin{bmatrix} 1 & 0 & 1 & 0 & | & 0 \\ 0 & 2 & 3 & 4 & | & 0 \\ 0 & -4 & -2 & 0 & | & 0 \end{bmatrix} \xrightarrow{R_3 + 2R_2} \begin{bmatrix} 1 & 0 & 1 & 0 & | & 0 \\ 0 & 2 & 3 & 4 & | & 0 \\ 0 & 0 & -4 & -2 & 0 & | & 0 \end{bmatrix}$$

Then,
$$C+2d=0 \Rightarrow C=-2\Gamma$$

 $2b+3c+4d=0 \Rightarrow b=\Gamma$
 $a+c=0 \Rightarrow a=2\Gamma$

$$\Rightarrow \begin{bmatrix} q \\ b \\ c \\ d \end{bmatrix} = \begin{bmatrix} 2 \\ 1 \\ -2 \\ 1 \end{bmatrix}$$

:
$$p(t) = r(2t^3 + t^2 - 2t + 1), r \in \mathbb{R}$$