

Contents

1 Basic	1
1.1 Basic codeblock setting	1
1.2 Basic vim setting	1
1.3 Code Template	1
1.4 Python	1
1.5 Range data	1
1.6 Some Function	2
1.7 Time	2
2 DP	2
2.1 3 維 DP 思路	2
2.2 Knapsack Bounded	2
2.3 Knapsack sample	2
2.4 Knapsack Unbounded	2
2.5 LCIS	2
2.6 LCS	2
2.7 LIS $O(N\log(N))$	3
2.8 LIS	3
2.9 LPS	3
2.10 Max_subarray	3
2.11 Money problem	3
3 Flow & matching	4
3.1 Dinic	4
3.2 Edmonds_karp	4
3.3 hungarian	4
3.4 Maximum_matching	4
3.5 MFlow Model	5
4 Geometry	5
4.1 Circle Intersect	5
4.2 Closest Pair	6
4.3 Line	6
4.4 max_cover_rectangle	6
4.5 Point	7
4.6 Polygon	7
4.7 Triangle	8
5 Graph	9
5.1 Bellman-Ford	9
5.2 BFS-queue	9
5.3 DFS-rec	9
5.4 Dijkstra	9
5.5 Euler circuit	10
5.6 Floyd-warshall	10
5.7 Hamilton_cycle	10
5.8 Kruskal	10
5.9 Minimum Weight Cycle	11
5.10 Prim	11
5.11 Union_find	11
6 Mathematics	12
6.1 Catalan	12
6.2 Combination	12
6.3 CRT	12
6.4 Extended Euclidean	12
6.5 Fermat	12
6.6 Hex to Dec	12
6.7 Log	13
6.8 Mod 性質	13
6.9 PI	13
6.10 Pow_Mod	13
6.11 Prime table	13
6.12 Prime 判斷	13
6.13 Round(小數)	14
6.14 二分逼近法	14
6.15 公式	14
6.16 四則運算	14
6.17 因數表	14
6.18 數字乘法組合	14
6.19 數字加法組合	14
6.20 羅馬數字	14
6.21 質因數分解	15
6.22 質數數量	15
7 Other	15
7.1 Binary search 三類變化	15
7.2 Heap sort	15
7.3 Josephus	16
7.4 Largest Multi-interval	16
7.5 Merge sort	16
7.6 Quick sort	16
7.7 Sudoku solution	16
7.8 Weighted Job Scheduling	17
8 String	17
8.1 KMP	17
8.2 Min Edit Distance	17
8.3 Sliding window	17
8.4 Split	17

9	data structure	17
9.1	Bigint	17
9.2	DisjointSet	19
9.3	Matirx	19
9.4	分數	19

1 Basic

1.1 Basic codeblock setting

```
Settings -> Editor -> Keyboard shortcuts -> Plugins -> Source
code formatter (AStyle)
Settings -> Source Formatter -> Padding
Delete empty lines within a function or method
Insert space padding around operators
Insert space padding around parentheses on outside
Remove extra space padding around parentheses
```

1.2 Basic vim setting

```
/*at home directory*/
/* vi ~/.vimrc */
syntax enable
set smartindent
set tabstop=4
set shiftwidth=4
set expandtab
set relativenumber
```

1.3 Code Template

```
#include <bits/stdc++.h>
using namespace std;
typedef long long ll;
typedef unsigned long long ull;
#define pb push_back
#define len length()
#define all(p) p.begin(), p.end()
#define endl '\n'
#define x first
#define y second
#define bug(k) cout << "value of " << #k << " is " << k << endl;
;
#define bugp(k) cout << "pair of " << #k << " is " << k.x << '
' << k.y << endl;
#define bugarr(k) for(auto i : k) cout << i << ' '; cout <<
endl;
int main()
{
    ios::sync_with_stdio(0);
    cin.tie(0);
    return 0;
}
```

1.4 Python

```
// 輸入
input()

array = [0] * (N) // N個0
range(0, N) // 0 ~ N-1
line = input().split()
D, R, N = map(int, line) // 分三個 int 變數

// 才是 取除數
// 是 小數運算

pow(a, b, c) // a ^ b % c

print(*objects, sep = ' ', end = '\n')
// objects -- 可以一次輸出多個對象
// sep -- 分開多個objects
// end -- 默認值是\n

// EOF break
try:
    while True:
        //input something
except EOFError:
    pass
```

1.5 Range data

```
int (-2147483648 to 2147483647)
unsigned int (0 to 4294967295)
long (-2147483648 to 2147483647)
unsigned long (0 to 4294967295)
long long (-9223372036854775808 to 9223372036854775807)
unsigned long long (0 to 18446744073709551615)
```

1.6 Some Function

```
round(double f);           // 四捨五入
ceil(double f);           // 進入
floor(double f);          // 捨去
__builtin_popcount(int n); // 32bit有多少 1
to_string(int s);         // int to string

cout << setprecision(位數) // cout 小數位設定
printf 型別
"%lf" // long double
"%lld" // long long int

set_union(all(a), all(b), back_inserter(d)); // 聯集
set_intersection(all(a), all(b), back_inserter(c)); // 交集

/** 全排列要先 sort !!! */
next_permutation(num.begin(), num.end());
prev_permutation(num.begin(), num.end());
//用binary search找第一個大於或等於val的位置
vector<int>::iterator it = lower_bound(v.begin(), v.end(), val)
;
//用binary search找第一個大於val的位置
vector<int>::iterator it = upper_bound(v.begin(), v.end(), val)
;

/*找到範圍裏面的最大元素*/
max_element(n, n + len); // n到n+len範圍內最大值
max_element(v.begin(), v.end()); // vector 中最大值
/*找到範圍裏面的最大元素*/
min_element(n, n + len); // n到n+len範圍內最小值
min_element(v.begin(), v.end()); // vector 中最小值

/*queue*/
queue<datatype> q;
front(); /*取出最前面的值(沒有移除掉)*/
back(); /*取出最後面的值(沒有移除掉)*/
pop(); /*移掉最前面的值*/
push(); /*新增值到最後面*/
empty(); /*回傳bool,檢查是不是空的queue*/
size(); /*queue 的大小*/

/*stack*/
stack<datatype> s;
top(); /*取出最上面的值(沒有移除掉)*/
pop(); /*移掉最上面的值*/
push(); /*新增值到最上面*/
empty(); /*bool 檢查是不是空*/
size(); /*stack 的大小*/

/*unordered_set*/
unordered_set<datatype> s;
unordered_set<datatype> s(arr, arr + n);
/*initial with array*/
insert(); /*插入值*/
erase(); /*刪除值*/
empty(); /*bool 檢查是不是空*/
count(); /*判斷元素存在回傳1 無則回傳0*/

/*tuple*/
tuple<datatype,datatype,datatype> t;
std::get<0>(t) /*Get first element of tuple*/
std::get<1>(t) /*Get second element of tuple*/
std::get<2>(t) /*Get third element of tuple*/
```

1.7 Time

```
cout << 1.0 * clock() / CLOCKS_PER_SEC << endl;
```

2 DP

2.1 3 維 DP 思路

解題思路: $dp[i][j][k]$
 i 跟 j 代表 range $i \sim j$ 的 value
 k 在我的理解裡是視題目的要求而定的
像是 Remove Boxes 當中 k 代表的是在 i 之前還有多少個連續的箱子
所以每次區間消去的值就是 $(k+1) * (k+1)$
換言之, 我認為可以理解成 k 的意義就是題目今天所關注的重點, 就是老師說的題目所規定的運算

2.2 Knapsack Bounded

```
const int N = 100, W = 100000;
int cost[N], weight[N], number[N];
int c[W + 1];
void knapsack(int n, int w)
{
```

```
for (int i = 0; i < n; ++i)
{
    int num = min(number[i], w / weight[i]);
    for (int k = 1; num > 0; k *= 2)
    {
        if (k > num)
            k = num;
        num -= k;
        for (int j = w; j >= weight[i] * k; --j)
            c[j] = max(c[j], c[j - weight[i] * k] + cost[i] * k);
    }
}
cout << "Max Prince" << c[w];
}
```

2.3 Knapsack sample

```
int Knapsack(vector<int> weight, vector<int> value, int bag_weight)
{
    // vector<int> weight = {1, 3, 4};
    // vector<int> value = {15, 20, 30};
    // int bagWeight = 4;
    vector<vector<int>> dp(weight.size(), vector<int>(bag_weight + 1, 0));
    for (int j = weight[0]; j <= bag_weight; j++)
        dp[0][j] = value[0];
    // weight數組的大小就是物品個數
    for (int i = 1; i < weight.size(); i++)
    { // 遍歷物品
        for (int j = 0; j <= bag_weight; j++)
        { // 遍歷背包容量
            if (j < weight[i]) dp[i][j] = dp[i - 1][j];
            else dp[i][j] = max(dp[i - 1][j], dp[i - 1][j - weight[i]] + value[i]);
        }
    }
    cout << dp[weight.size() - 1][bag_weight] << endl;
}
```

2.4 Knapsack Unbounded

```
const int N = 100, W = 100000;
int cost[N], weight[N];
int c[W + 1];
void knapsack(int n, int w)
{
    memset(c, 0, sizeof(c));
    for (int i = 0; i < n; ++i)
        for (int j = weight[i]; j <= w; ++j)
            c[j] = max(c[j], c[j - weight[i]] + cost[i]);
    cout << "最高的價值為" << c[w];
}
```

2.5 LCIS

```
int LCIS_len(vector<int> arr1, vector<int> arr2)
{
    int n = arr1.size(), m = arr2.size();
    vector<int> table(m, 0);
    for (int j = 0; j < m; j++)
        table[j] = 0;
    for (int i = 0; i < n; i++)
    {
        int current = 0;
        for (int j = 0; j < m; j++)
        {
            if (arr1[i] == arr2[j])
                if (current + 1 > table[j])
                    table[j] = current + 1;

            if (arr1[i] > arr2[j])
                if (table[j] > current)
                    current = table[j];
        }
    }
    int result = 0;
    for (int i = 0; i < m; i++)
        if (table[i] > result)
            result = table[i];
    return result;
}
```

2.6 LCS

```
int LCS(vector<string> Ans, vector<string> num)
{
    int N = Ans.size(), M = num.size();
    vector<vector<int>> LCS(N + 1, vector<int>(M + 1, 0));
    for (int i = 1; i <= N; ++i)
    {
        for (int j = 1; j <= M; ++j)
```

```

    {
        if (Ans[i - 1] == num[j - 1])
            LCS[i][j] = LCS[i - 1][j - 1] + 1;
        else
            LCS[i][j] = max(LCS[i - 1][j], LCS[i][j - 1]);
    }
}
cout << LCS[N][M] << '\n';
//列印 LCS
int n = N, m = M;
vector<string> k;
while (n && m)
{
    if (LCS[n][m] != max(LCS[n - 1][m], LCS[n][m - 1]))
    {
        k.push_back(Ans[n - 1]);
        n--;
        m--;
    }
    else if (LCS[n][m] == LCS[n - 1][m])
        n--;
    else if (LCS[n][m] == LCS[n][m - 1])
        m--;
}
reverse(k.begin(), k.end());
for (auto i : k)
    cout << i << " ";
cout << endl;
return LCS[N][M];
}

```

2.7 LIS $O(N \log(N))$

```

int LIS(vector<int> &v) //  $O(n \log(n))$ 
{ // 需要 LDS 請把 array reverse 反過來求 LIS
  // 但必須注意 lower_bound or upper_bound
  if (v.size() == 0)
      return 0;
  vector<int> dp(v.size(), 0);
  int length = 1;
  dp[0] = v[0];
  for (int i = 1; i < v.size(); i++)
  {
      auto b = dp.begin(), e = dp.begin() + length;
      // auto it = lower_bound(b, e, v[i]); // 後面 >= 前面
      auto it = upper_bound(b, e, v[i]); // 後面 > 前面
      if (it == dp.begin() + length)
          dp[length++] = v[i];
      else
          *it = v[i];
  }
  return length;
}

```

2.8 LIS

```

vector<int> ans;
void LIS(vector<int> &arr)
{
    vector<int> dp(arr.size(), 1);
    vector<int> pos(arr.size(), -1);
    int res = INT_MIN, index = 0;
    for (int i = 0; i < arr.size(); ++i)
    {
        for (int j = i + 1; j < arr.size(); ++j)
        {
            if (arr[j] > arr[i])
            {
                if (dp[i] + 1 > dp[j])
                {
                    dp[j] = dp[i] + 1;
                    pos[j] = i;
                }
            }
        }
        if (dp[i] > res)
        {
            res = dp[i];
            index = i;
        }
    }
    cout << res << endl; // length
    printLIS(arr, pos, index);
    for (int i = 0; i < ans.size(); i++)
    {
        cout << ans[i];
        if (i != ans.size() - 1)
            cout << ' ';
    }
    cout << '\n';
}
void printLIS(vector<int> &arr, vector<int> &pos, int index)
{
    if (pos[index] != -1)

```

```

        printLIS(arr, pos, pos[index]);
    ans.push_back(arr[index]);
}

```

2.9 LPS

```

void LPS(string s)
{
    int maxlen = 0, l, r;
    int n = s.size();
    for (int i = 0; i < n; i++)
    {
        int x = 0;
        while ((s[i - x] == s[i + x]) && (i - x >= 0) && (i + x < n)) //odd length
            x++;
        x--;
        if (2 * x + 1 > maxlen)
        {
            maxlen = 2 * x + 1;
            l = i - x;
            r = i + x;
        }
        x = 0;
        while ((s[i - x] == s[i + 1 + x]) && (i - x >= 0) && (i + 1 + x < n)) //even length
            x++;
        if (2 * x > maxlen)
        {
            maxlen = 2 * x;
            l = i - x + 1;
            r = i + x;
        }
    }
    cout << maxlen << '\n'; // 最後長度
    cout << l + 1 << ' ' << r + 1 << '\n'; // 頭到尾
}

```

2.10 Max_subarray

```

/*Kadane's algorithm*/
int maxSubArray(vector<int> &nums) {
    int local_max = nums[0], global_max = nums[0];
    for (int i = 1; i < nums.size(); i++) {
        local_max = max(nums[i], local_max + nums[i]);
        global_max = max(local_max, global_max);
    }
    return global_max;
}

```

2.11 Money problem

```

//能否湊得某個價位
void change(vector<int> price, int limit)
{
    vector<bool> c(limit + 1, 0);
    c[0] = true;
    for (int i = 0; i < price.size(); ++i) // 依序加入各種面額
        for (int j = price[i]; j <= limit; ++j) // 由低價位逐步到高價位
            c[j] = c[j] | c[j - price[i]]; // 湊、湊、湊
    if (c[limit]) cout << "YES\n";
    else cout << "NO\n";
}
// 湊得某個價位的湊法總共幾種
void change(vector<int> price, int limit)
{
    vector<int> c(limit + 1, 0);
    c[0] = true;
    for (int i = 0; i < price.size(); ++i)
        for (int j = price[i]; j <= limit; ++j)
            c[j] += c[j - price[i]];
    cout << c[limit] << '\n';
}
// 湊得某個價位的最少錢幣用量
void change(vector<int> price, int limit)
{
    vector<int> c(limit + 1, 0);
    c[0] = true;
    for (int i = 0; i < price.size(); ++i)
        for (int j = price[i]; j <= limit; ++j)
            c[j] = min(c[j], c[j - price[i]] + 1);
    cout << c[limit] << '\n';
}
//湊得某個價位的錢幣用量，有哪幾種可能性
void change(vector<int> price, int limit)
{
    vector<int> c(limit + 1, 0);
    c[0] = true;
    for (int i = 0; i < price.size(); ++i)
        for (int j = price[i]; j <= limit; ++j)
            c[j] |= c[j - price[i]] << 1; // 錢幣數量加一，每一種可能性都加一。
}

```

```

for (int i = 1; i <= 63; ++i)
    if (c[m] & (1 << i))
        cout << "用" << i << "個錢幣可湊得價位" << m;
}

```

3 Flow & matching

3.1 Dinic

```

const long long INF = 1LL<<60;
struct Dinic { //O(VVE), with minimum cut
    static const int MAXN = 5003;
    struct Edge{
        int u, v;
        long long cap, rest;
    };
    int n, m, s, t, d[MAXN], cur[MAXN];
    vector<Edge> edges;
    vector<int> G[MAXN];
    void init(){
        edges.clear();
        for (int i = 0; i < n; i++) G[i].clear();
        n = 0;
    }
    // min cut start
    bool side[MAXN];
    void cut(int u) {
        side[u] = 1;
        for (int i : G[u]) {
            if (!side[edges[i].v] && edges[i].rest)
                cut(edges[i].v);
        }
    }
    // min cut end
    int add_node(){
        return n++;
    }
    void add_edge(int u, int v, long long cap){
        edges.push_back({u, v, cap, cap});
        edges.push_back({v, u, 0, 0LL});
        m = edges.size();
        G[u].push_back(m-2);
        G[v].push_back(m-1);
    }
    bool bfs(){
        fill(d,d+n,-1);
        queue<int> que;
        que.push(s); d[s]=0;
        while (!que.empty()){
            int u = que.front(); que.pop();
            for (int ei : G[u]){
                Edge &e = edges[ei];
                if (d[e.v] < 0 && e.rest > 0){
                    d[e.v] = d[u] + 1;
                    que.push(e.v);
                }
            }
        }
        return d[t] >= 0;
    }
    long long dfs(int u, long long a){
        if (u == t || a == 0) return a;
        long long flow = 0, f;
        for (int &i=cur[u]; i < (int)G[u].size(); i++) {
            Edge &e = edges[G[u][i]];
            if (d[u] + 1 != d[e.v]) continue;
            f = dfs(e.v, min(a, e.rest));
            if (f > 0) {
                e.rest -= f;
                edges[G[u][i]^1].rest += f;
                flow += f;
                a -= f;
                if (a == 0) break;
            }
        }
        return flow;
    }
    long long maxflow(int _s, int _t){
        s = _s, t = _t;
        long long flow = 0, mf;
        while (bfs()) {
            fill(cur,cur+n,0);
            while ((mf = dfs(s, INF)) > 0) flow += mf;
        }
        return flow;
    }
} dinic;

```

3.2 Edmonds_karp

```

/*Flow - Edmonds-karp*/
/*Based on UVa820*/
#define inf 1000000

```

```

int getMaxFlow(vector<vector<int>> &capacity, int s, int t, int
n){
    int ans = 0;
    vector<vector<int>> residual(n+1, vector<int>(n+1, 0)); //
    residual network
    while(true){
        vector<int> bottleneck(n+1, 0);
        bottleneck[s] = inf;
        queue<int> q;
        q.push(s);
        vector<int> pre(n+1, 0);
        while(!q.empty() && bottleneck[t] == 0){
            int cur = q.front();
            q.pop();
            for(int i = 1; i <= n; i++){
                if(bottleneck[i] == 0 && capacity[cur][i] > residual[
                    cur][i]){
                    q.push(i);
                    pre[i] = cur;
                    bottleneck[i] = min(bottleneck[cur], capacity[cur][i]
                        - residual[cur][i]);
                }
            }
        }
        if(bottleneck[t] == 0) break;
        for(int cur = t; cur != s; cur = pre[cur]){
            residual[pre[cur]][cur] += bottleneck[t];
            residual[cur][pre[cur]] -= bottleneck[t];
        }
        ans += bottleneck[t];
    }
    return ans;
}

int main(){
    int testcase = 1;
    int n;
    while(cin >> n){
        if(n == 0)
            break;
        vector<vector<int>> capacity(n+1, vector<int>(n+1, 0));
        int s, t, c;
        cin >> s >> t >> c;
        int a, b, bandwidth;
        for(int i = 0; i < c; ++i){
            cin >> a >> b >> bandwidth;
            capacity[a][b] += bandwidth;
            capacity[b][a] += bandwidth;
        }
        cout << "Network " << testcase++ << endl;
        cout << "The bandwidth is " << getMaxFlow(capacity, s, t, n
            ) << "." << endl;
        cout << endl;
    }
    return 0;
}

```

3.3 hungarian

```

/*bipartite - hungarian*/
struct Graph{
    static const int MAXN = 5003;
    vector<int> G[MAXN];
    int n, match[MAXN], vis[MAXN];
    void init(int _n){
        n = _n;
        for (int i=0; i<n; i++) G[i].clear();
    }
    bool dfs(int u){
        for (int v:G[u]){
            if (vis[v]) continue;
            vis[v]=true;
            if (match[v]==-1 || dfs(match[v])){
                match[v] = u;
                match[u] = v;
                return true;
            }
        }
        return false;
    }
    int solve(){
        int res = 0;
        memset(match,-1,sizeof(match));
        for (int i=0; i<n; i++){
            if (match[i]==-1){
                memset(vis,0,sizeof(vis));
                if (dfs(i)) res++;
            }
        }
        return res;
    }
} graph;

```

3.4 Maximum_matching

```

/*bipartite - maximum matching*/

```

```

bool dfs(vector<vector<bool>> res, int node, vector<int>& x,
vector<int>& y, vector<bool> pass){
    for (int i = 0; i < res[0].size(); i++){
        if(res[node][i] && !pass[i]){
            pass[i] = true;
            if(y[i] == -1 || dfs(res, y[i], x, y, pass)){
                x[node] = i;
                y[i] = node;
                return true;
            }
        }
    }
    return false;
}

int main(){
    int n, m, l;
    while (cin >> n >> m >> l){
        vector<vector<bool>> res(n, vector<bool>(m, false));
        for (int i = 0; i < l; i++){
            int a, b;
            cin >> a >> b;
            res[a][b] = true;
        }
        int ans = 0;
        vector<int> x(n, -1);
        vector<int> y(n, -1);
        for (int i = 0; i < n; i++){
            vector<bool> pass(n, false);
            if(dfs(res, i, x, y, pass))
                ans += 1;
        }
        cout << ans << endl;
    }
    return 0;
}
/*
input:
4 3 5 //n matching m, l links
0 0
0 2
1 0
2 1
3 1
answer is 3
*/

```

3.5 MFlow Model

```

typedef long long ll;
struct MF
{
    static const int N = 5000 + 5;
    static const int M = 60000 + 5;
    static const ll oo = 1000000000000LL;

    int n, m, s, t, tot, tim;
    int first[N], next[M];
    int u[M], v[M], cur[N], vi[N];
    ll cap[M], flow[M], dis[N];
    int que[N + N];

    void Clear()
    {
        tot = 0;
        tim = 0;
        for (int i = 1; i <= n; ++i)
            first[i] = -1;
    }

    void Add(int from, int to, ll cp, ll flw)
    {
        u[tot] = from;
        v[tot] = to;
        cap[tot] = cp;
        flow[tot] = flw;
        next[tot] = first[u[tot]];
        first[u[tot]] = tot;
        ++tot;
    }

    bool bfs()
    {
        ++tim;
        dis[s] = 0;
        vi[s] = tim;

        int head, tail;
        head = tail = 1;
        que[head] = s;
        while (head <= tail)
        {
            for (int i = first[que[head]]; i != -1; i = next[i])
            {
                if (vi[v[i]] != tim && cap[i] > flow[i])
                {
                    vi[v[i]] = tim;
                    dis[v[i]] = dis[que[head]] + 1;
                    que[++tail] = v[i];
                }
            }
        }
    }
}

```

```

    }
    ++head;
    return vi[t] == tim;
}

ll dfs(int x, ll a)
{
    if (x == t || a == 0)
        return a;
    ll flw = 0, f;
    int &i = cur[x];
    for (i = first[x]; i != -1; i = next[i])
    {
        if (dis[x] + 1 == dis[v[i]] && (f = dfs(v[i], min(a, cap[i] - flow[i]))) > 0)
        {
            flow[i] += f;
            flow[i ^ 1] -= f;
            a -= f;
            flw += f;
            if (a == 0)
                break;
        }
    }
    return flw;
}

ll MaxFlow(int s, int t)
{
    this->s = s;
    this->t = t;
    ll flw = 0;
    while (bfs())
    {
        for (int i = 1; i <= n; ++i)
            cur[i] = 0;
        flw += dfs(s, oo);
    }
    return flw;
}

// MF Net;
// Net.n = n;
// Net.Clear();
// a 到 b (注意從1開始!!!!)
// Net.Add(a, b, w, 0);
// Net.MaxFlow(s, d)
// s 到 d 的 MF

```

4 Geometry

4.1 Circle Intersect

```

bool same(double a, double b)
{
    return abs(a - b) < 0;
}

struct P
{
    double x, y;
    P() : x(0), y(0) {}
    P(double x, double y) : x(x), y(y) {}
    P operator+(P b) { return P(x + b.x, y + b.y); }
    P operator-(P b) { return P(x - b.x, y - b.y); }
    P operator*(double b) { return P(x * b, y * b); }
    P operator/(double b) { return P(x / b, y / b); }
    double operator*(P b) { return x * b.x + y * b.y; }
    // double operator^(P b) { return x * b.y - y * b.x; }
    double abs() { return hypot(x, y); }
    P unit() { return *this / abs(); }
    P rot(double o)
    {
        double c = cos(o), s = sin(o);
        return P(c * x - s * y, s * x + c * y);
    }
    double angle() { return atan2(y, x); }
};

struct C
{
    P c;
    double r;
    C(P c = P(0, 0), double r = 0) : c(c), r(r) {}
};

vector<P> Intersect(C a, C b)
{
    if (a.r > b.r)
        swap(a, b);
    double d = (a.c - b.c).abs();
    vector<P> p;
    if (same(a.r + b.r, d))
        p.pb(a.c + (b.c - a.c).unit() * a.r);
    else if (a.r + b.r > d && d + a.r >= b.r)
    {
        double o = acos((sqrt(a.r) + sqrt(d) - sqrt(b.r)) / (2 * a.r * d));
    }
}

```

```

    p.i = (b.c - a.c).unit();
    p.pb(a.c + i.rot(o) * a.r);
    p.pb(a.c + i.rot(-o) * a.r);
}
return p;
}

```

4.2 Closest Pair

```

//最近點對 (距離) //台大
vector<pair<double, double>> p;
double closest_pair(int l, int r)
{
    // p 要對 x 軸做 sort
    if (l == r)
        return 1e9;
    if (r - l == 1)
        return dist(p[l], p[r]); // 兩點距離
    int m = (l + r) >> 1;
    double d = min(closest_pair(l, m), closest_pair(m + 1, r));
    vector<int> vec;
    for (int i = m; i >= l && fabs(p[m].x - p[i].x) < d; --i)
        vec.push_back(i);
    for (int i = m + 1; i <= r && fabs(p[m].x - p[i].x) < d; ++i)
        vec.push_back(i);
    sort(vec.begin(), vec.end(), [&](int a, int b)
        { return p[a].y < p[b].y; });
    for (int i = 0; i < vec.size(); ++i)
        for (int j = i + 1; j < vec.size() && fabs(p[vec[j]].y - p[vec[i]].y) < d; ++j)
            d = min(d, dist(p[vec[i]], p[vec[j]]));
    return d;
}

```

4.3 Line

```

template <typename T>
struct line
{
    line() {}
    point<T> p1, p2;
    T a, b, c; //ax+by+c=0
    line(const point<T> &x, const point<T> &y) : p1(x), p2(y) {}
    void pton()
    { //轉成一般式
        a = p1.y - p2.y;
        b = p2.x - p1.x;
        c = -a * p1.x - b * p1.y;
    }
    T ori(const point<T> &p) const
    { //點和有向直線的關係 · >0左邊 · =0在線上 <0右邊
        return (p2 - p1).cross(p - p1);
    }
    T btw(const point<T> &p) const
    { //點投影落在線段上 <=0
        return (p1 - p).dot(p2 - p);
    }
    bool point_on_segment(const point<T> &p) const
    { //點是否在線段上
        return ori(p) == 0 && btw(p) <= 0;
    }
    T dis2(const point<T> &p, bool is_segment = 0) const
    { //點跟直線/線段的距離平方
        point<T> v = p2 - p1, v1 = p - p1;
        if (is_segment)
        {
            point<T> v2 = p - p2;
            if (v.dot(v1) <= 0)
                return v1.abs2();
            if (v.dot(v2) >= 0)
                return v2.abs2();
        }
        T tmp = v.cross(v1);
        return tmp * tmp / v.abs2();
    }
    T seg_dis2(const line<T> &l) const
    { //兩線段距離平方
        return min({dis2(l.p1, 1), dis2(l.p2, 1), l.dis2(p1, 1), l.dis2(p2, 1)});
    }
    point<T> projection(const point<T> &p) const
    { //點對直線的投影
        point<T> n = (p2 - p1).normal();
        return p - n * (p - p1).dot(n) / n.abs2();
    }
    point<T> mirror(const point<T> &p) const
    {
        //點對直線的鏡射 · 要先呼叫 pton 轉成一般式
        point<T> R;
        T d = a * a + b * b;
        R.x = (b * b * p.x - a * a * p.x - 2 * a * b * p.y - 2 * a * c) / d;

```

```

        R.y = (a * a * p.y - b * b * p.y - 2 * a * b * p.x - 2 * b * c) / d;
        return R;
    }
    bool equal(const line &l) const
    { //直線相等
        return ori(l.p1) == 0 && ori(l.p2) == 0;
    }
    bool parallel(const line &l) const
    {
        return (p1 - p2).cross(l.p1 - l.p2) == 0;
    }
    bool cross_seg(const line &l) const
    {
        return (p2 - p1).cross(l.p1 - p1) * (p2 - p1).cross(l.p2 - p1) <= 0; //直線是否交線段
    }
    int line_intersect(const line &l) const
    { //直線相交情況 · -1無限多點 · 1交於一點 · 0不相交
        return parallel(l) ? (ori(l.p1) == 0 ? -1 : 0) : 1;
    }
    int seg_intersect(const line &l) const
    {
        T c1 = ori(l.p1), c2 = ori(l.p2);
        T c3 = l.ori(p1), c4 = l.ori(p2);
        if (c1 == 0 && c2 == 0)
        { //共線
            bool b1 = btw(l.p1) >= 0, b2 = btw(l.p2) >= 0;
            T a3 = l.btw(p1), a4 = l.btw(p2);
            if (b1 && b2 && a3 == 0 && a4 >= 0)
                return 2;
            if (b1 && b2 && a3 >= 0 && a4 == 0)
                return 3;
            if (b1 && b2 && a3 >= 0 && a4 >= 0)
                return 0;
            return -1; //無限交點
        }
        else if (c1 * c2 <= 0 && c3 * c4 <= 0)
            return 1;
        return 0; //不相交
    }
    point<T> line_intersection(const line &l) const
    { //直線交點*
        point<T> a = p2 - p1, b = l.p2 - l.p1, s = l.p1 - p1;
        // if (a.cross(b) == 0)
        //     return INF;
        return p1 + a * (s.cross(b) / a.cross(b));
    }
    point<T> seg_intersection(const line &l) const
    { //線段交點
        int res = seg_intersect(l);
        if (res <= 0)
            assert(0);
        if (res == 2)
            return p1;
        if (res == 3)
            return p2;
        return line_intersection(l);
    }
};

```

4.4 max_cover_rectangle

```

const double PI = atan2(0.0, -1.0);
const double eps = 1e-10;
typedef point<double> p; // data type 依照題目更改
int mycmp(double a) { return fabs(a) < eps ? 0 : (a < 0 ? -1 : 1); }
double Length(p a) { return sqrt(a.dot(a)); }
p Rotate(p a, double rad) { return p(a.x * cos(rad) - a.y * sin(rad), a.x * sin(rad) + a.y * cos(rad)); }
double angle(p a) { return atan2(a.y, a.x); }
double angle(p a, p b) { return atan2(a.cross(b), a.dot(b)); }
double turnAngle(p a, p b) { return mycmp(a.dot(b)) == 1 ? angle(a, b) : PI + angle(a, b); }
double distanceOfpAndLine(p a, p b, p c) { return fabs((b - a).cross(c - a) / Length(b - c)); }
double Area(int a, int b, int c, int d, p ab, p cd, polygon<double> po)
{
    double h1 = distanceOfpAndLine(po.p[a], po.p[b], po.p[b] + ab);
    double h2 = distanceOfpAndLine(po.p[c], po.p[d], po.p[d] + cd);
    return h1 * h2;
}
double max_cover_rectangle(polygon<double> po)
{
    po.p.pb(po.p[0]);
    int m = po.p.size();
    if (m < 3)
        return 0; // 沒凸包哪來外包矩形
    double Max = -1;
    double Minx = po.p[0].x, Miny = po.p[0].y, Maxx = po.p[0].x, Maxy = po.p[0].y;

```



```

int p1 = 0, p2 = 0, p3 = 0, p4 = 0;
p v1, v2, ori;
ori = v1 = p(1, 0);
v2 = p(0, 1);
for (int i = 1; i < m; i++)
{
    if (mycmp(Minx - po.p[i].x) == 1)
        Minx = po.p[i].x, p3 = i;
    if (mycmp(Maxx - po.p[i].x) == -1)
        Maxx = po.p[i].x, p4 = i;
    if (mycmp(Miny - po.p[i].y) == 1)
        Miny = po.p[i].y, p1 = i;
    if (mycmp(Maxy - po.p[i].y) == -1)
        Maxy = po.p[i].y, p2 = i;
}
while (mycmp(ori.cross(v1)) >= 0)
{
    double minRad = 1e20;
    minRad = min(minRad, turnAngle(v1, po.p[p1 + 1] - po.p[p1]));
    minRad = min(minRad, turnAngle(v1 * (-1), po.p[p2 + 1] - po.p[p2]));
    minRad = min(minRad, turnAngle(v2 * (-1), po.p[p3 + 1] - po.p[p3]));
    minRad = min(minRad, turnAngle(v2, po.p[p4 + 1] - po.p[p4]));
    double l = 0, r = minRad;
    while (mycmp(l - r))
    {
        double len = (r - l) / 3;
        double midl = l + len;
        double midr = r - len;

        if (mycmp(Area(p1, p2, p3, p4, Rotate(v1, midl), Rotate(v2, midl), po) - Area(p1, p2, p3, p4, Rotate(v1, midr), Rotate(v2, midr), po)) == 1)
            r = midr;
        else
            l = midl;
    }
    Max = max(Max, Area(p1, p2, p3, p4, Rotate(v1, l), Rotate(v2, l), po));
    v1 = Rotate(v1, minRad);
    v2 = Rotate(v2, minRad);
    if (mycmp(angle(v1, po.p[p1 + 1] - po.p[p1])) == 0)
        p1 = (p1 + 1) % m;
    if (mycmp(angle(v1 * (-1), po.p[p2 + 1] - po.p[p2])) == 0)
        p2 = (p2 + 1) % m;
    if (mycmp(angle(v2 * (-1), po.p[p3 + 1] - po.p[p3])) == 0)
        p3 = (p3 + 1) % m;
    if (mycmp(angle(v2, po.p[p4 + 1] - po.p[p4])) == 0)
        p4 = (p4 + 1) % m;
}
return Max;
}

```

4.5 Point

```

const double PI = atan2(0.0, -1.0);
template <typename T>
struct point
{
    T x, y;
    point() {}
    point(const T &x, const T &y) : x(x), y(y) {}
    point operator+(const point &b) const
    {
        return point(x + b.x, y + b.y);
    }
    point operator-(const point &b) const
    {
        return point(x - b.x, y - b.y);
    }
    point operator*(const T &b) const
    {
        return point(x * b, y * b);
    }
    point operator/(const T &b) const
    {
        return point(x / b, y / b);
    }
    bool operator==(const point &b) const
    {
        return x == b.x && y == b.y;
    }
    T dot(const point &b) const
    {
        return x * b.x + y * b.y;
    }
    T cross(const point &b) const
    {
        return x * b.y - y * b.x;
    }
    point normal() const

```

```

{ //求法向量
    return point(-y, x);
}
T abs2() const
{ //向量長度的平方
    return dot(*this);
}
T rad(const point &b) const
{ //兩向量的弧度
    return fabs(atan2(fabs(cross(b)), dot(b)));
}
T getA() const
{
    T A = atan2(y, x); //對x軸的弧度
    if (A <= -PI / 2)
        A += PI * 2;
    return A;
}
};

```

4.6 Polygon

```

template <typename T>
struct polygon
{
    polygon() {}
    vector<point<T>> p; //逆時針順序
    T area() const
    { //面積
        T ans = 0;
        for (int i = p.size() - 1, j = 0; j < (int)p.size(); i = j++)
            ans += p[i].cross(p[j]);
        return ans / 2;
    }
    point<T> center_of_mass() const
    { //重心
        T cx = 0, cy = 0, w = 0;
        for (int i = p.size() - 1, j = 0; j < (int)p.size(); i = j++)
        {
            T a = p[i].cross(p[j]);
            cx += (p[i].x + p[j].x) * a;
            cy += (p[i].y + p[j].y) * a;
            w += a;
        }
        return point<T>(cx / 3 / w, cy / 3 / w);
    }
    char ahas(const point<T> &t) const
    { //點是否在簡單多邊形內，是的話回傳1、在邊上回傳-1、否則回傳0
        bool c = 0;
        for (int i = 0, j = p.size() - 1; i < p.size(); j = i++)
            if (line<T>(p[i], p[j]).point_on_segment(t))
                return -1;
            else if ((p[i].y > t.y) != (p[j].y > t.y) && t.x < (p[j].x - p[i].x) * (t.y - p[i].y) / (p[j].y - p[i].y) + p[i].x)
                c = !c;
        return c;
    }
    char point_in_convex(const point<T> &x) const
    {
        int l = 1, r = (int)p.size() - 2;
        while (l <= r)
        { //點是否在凸多邊形內，是的話回傳1、在邊上回傳-1、否則回傳0
            int mid = (l + r) / 2;
            T a1 = (p[mid] - p[0]).cross(x - p[0]);
            T a2 = (p[mid + 1] - p[0]).cross(x - p[0]);
            if (a1 >= 0 && a2 <= 0)
            {
                T res = (p[mid + 1] - p[mid]).cross(x - p[mid]);
                return res > 0 ? 1 : (res >= 0 ? -1 : 0);
            }
            else if (a1 < 0)
                r = mid - 1;
            else
                l = mid + 1;
        }
        return 0;
    }
    vector<T> getA() const
    { //凸包邊對x軸的夾角
        vector<T> res; //一定是遞增的
        for (size_t i = 0; i < p.size(); ++i)
            res.push_back((p[(i + 1) % p.size()] - p[i]).getA());
        return res;
    }
    bool line_intersect(const vector<T> &A, const line<T> &l) const
    { //O(logN)

```

```

    int f1 = upper_bound(A.begin(), A.end(), (l.p1 - l.p2).
        getA()) - A.begin();
    int f2 = upper_bound(A.begin(), A.end(), (l.p2 - l.p1).
        getA()) - A.begin();
    return l.cross_seg(line<T>(p[f1], p[f2]));
}
polygon cut(const line<T> &l) const
{ //凸包對直線切割·得到直線l左側的凸包
    polygon ans;
    for (int n = p.size(), i = n - 1, j = 0; j < n; i = j
        ++){
        if (l.ori(p[i]) >= 0)
        {
            ans.p.push_back(p[i]);
            if (l.ori(p[j]) < 0)
                ans.p.push_back(l.line_intersection(line<T>
                    (p[i], p[j])));
        }
        else if (l.ori(p[j]) > 0)
            ans.p.push_back(l.line_intersection(line<T>(p[i]
                , p[j])));
    }
    return ans;
}
static bool Andrew_Monotone_Chain_angle(const point<T> &a,
    const point<T> &b)
{ //凸包排序函數 // 起始點不同
    return (a.y < b.y) || (a.y == b.y && a.x < b.x); //Y最
        小開始
}
void Andrew_Monotone_Chain(vector<point<T>> &s)
{ //凸包 Convexhull 2D
    sort(s.begin(), s.end(), Andrew_Monotone_Chain_angle);
    p.resize(s.size() + 1);
    int m = 0;
    // cross >= 0 順時針·cross <= 0 逆時針旋轉
    for (size_t i = 0; i < s.size(); ++i)
    {
        while (m >= 2 && (p[m - 1] - p[m - 2]).cross(s[i] -
            p[m - 2]) <= 0)
            --m;
        p[m++] = s[i];
    }
    for (int i = s.size() - 2, t = m + 1; i >= 0; --i)
    {
        while (m >= t && (p[m - 1] - p[m - 2]).cross(s[i] -
            p[m - 2]) <= 0)
            --m;
        p[m++] = s[i];
    }
    if (s.size() > 1) // 重複頭一次需扣掉
        --m;
    p.resize(m);
    // p.pb(s[0]); // 需要頭在 pb 回去!!
}
T diam()
{ //直徑
    int n = p.size(), t = 1;
    T ans = 0;
    p.push_back(p[0]);
    for (int i = 0; i < n; i++)
    {
        point<T> now = p[i + 1] - p[i];
        while (now.cross(p[t + 1] - p[i]) > now.cross(p[t]
            - p[i]))
            t = (t + 1) % n;
        ans = max(ans, (p[i] - p[t]).abs2());
    }
    return p.pop_back(), ans;
}
T min_cover_rectangle()
{ // 先做凸包 //最小覆蓋矩形
    int n = p.size(), t = 1, r = 1, l;
    if (n < 3)
        return 0; //也可以做最小周長矩形
    T ans = 1e99;
    p.push_back(p[0]);
    for (int i = 0; i < n; i++)
    {
        point<T> now = p[i + 1] - p[i];
        while (now.cross(p[t + 1] - p[i]) > now.cross(p[t]
            - p[i]))
            t = (t + 1) % n;
        while (now.dot(p[r + 1] - p[i]) > now.dot(p[r] - p[
            i]))
            r = (r + 1) % n;
        if (!i)
            l = r;
        while (now.dot(p[l + 1] - p[i]) <= now.dot(p[l] - p
            [i]))
            l = (l + 1) % n;
        T d = now.abs2();
        T tmp = now.cross(p[t] - p[i]) * (now.dot(p[r] - p[
            i]) - now.dot(p[l] - p[i])) / d;

```

```

        ans = min(ans, tmp);
    }
    return p.pop_back(), ans;
}
T dis2(polygon &p1)
{ //凸包最近距離平方
    vector<point<T>> &P = p, &Q = p1.p;
    int n = P.size(), m = Q.size(), l = 0, r = 0;
    for (int i = 0; i < n; ++i)
        if (P[i].y < P[l].y)
            l = i;
    for (int i = 0; i < m; ++i)
        if (Q[i].y < Q[r].y)
            r = i;
    P.push_back(P[0]), Q.push_back(Q[0]);
    T ans = 1e99;
    for (int i = 0; i < n; ++i)
    {
        while ((P[l] - P[l + 1]).cross(Q[r + 1] - Q[r]) <
            0)
            r = (r + 1) % m;
        ans = min(ans, line<T>(P[l], P[l + 1]).seg_dis2(
            line<T>(Q[r], Q[r + 1])));
        l = (l + 1) % n;
    }
    return P.pop_back(), Q.pop_back(), ans;
}
static char sign(const point<T> &t)
{
    return (t.y == 0 ? t.x : t.y) < 0;
}
static bool angle_cmp(const line<T> &A, const line<T> &B)
{
    point<T> a = A.p2 - A.p1, b = B.p2 - B.p1;
    return sign(a) < sign(b) || (sign(a) == sign(b) && a.
        cross(b) > 0);
}
int halfplane_intersection(vector<line<T>> &s)
{ //半平面交
    sort(s.begin(), s.end(), angle_cmp); //線段左側為該線段
        半平面
    int L, R, n = s.size();
    vector<point<T>> px(n);
    vector<line<T>> q(n);
    q[L = R = 0] = s[0];
    for (int i = 1; i < n; ++i)
    {
        while (L < R && s[i].ori(px[R - 1]) <= 0)
            --R;
        while (L < R && s[i].ori(px[L]) <= 0)
            ++L;
        q[++R] = s[i];
        if (q[R].parallel(q[R - 1]))
        {
            --R;
            if (q[R].ori(s[i].p1) > 0)
                q[R] = s[i];
        }
        if (L < R)
            px[R - 1] = q[R - 1].line_intersection(q[R]);
    }
    while (L < R && q[L].ori(px[R - 1]) <= 0)
        --L;
    p.clear();
    if (R - L <= 1)
        return 0;
    px[R] = q[R].line_intersection(q[L]);
    for (int i = L; i <= R; ++i)
        p.push_back(px[i]);
    return R - L + 1;
}
};

```

4.7 Triangle

```

template <typename T>
struct triangle
{
    point<T> a, b, c;
    triangle() {}
    triangle(const point<T> &a, const point<T> &b, const point<
        T> &c) : a(a), b(b), c(c) {}
    T area() const
    {
        T t = (b - a).cross(c - a) / 2;
        return t > 0 ? t : -t;
    }
    point<T> barycenter() const
    { //重心
        return (a + b + c) / 3;
    }
    point<T> circumcenter() const
    { //外心
        static line<T> u, v;
        u.p1 = (a + b) / 2;

```



```

    u.p2 = point<T>(u.p1.x - a.y + b.y, u.p1.y + a.x - b.x)
    ;
    v.p1 = (a + c) / 2;
    v.p2 = point<T>(v.p1.x - a.y + c.y, v.p1.y + a.x - c.x)
    ;
    return u.line_intersection(v);
}
point<T> incenter() const
{ //内心
    T A = sqrt((b - c).abs2()), B = sqrt((a - c).abs2()), C
    = sqrt((a - b).abs2());
    return point<T>(A * a.x + B * b.x + C * c.x, A * a.y +
    B * b.y + C * c.y) / (A + B + C);
}
point<T> perpercenter() const
{ //垂心
    return barycenter() * 3 - circumcenter() * 2;
}
};

```

5 Graph

5.1 Bellman-Ford

```

/*SPA - Bellman-Ford*/
#define inf 99999 //define by you maximum edges weight
vector<vector<int>> > edges;
vector<int> dist;
vector<int> ancestor;
void BellmanFord(int start,int node){
    dist[start] = 0;
    for(int it = 0; it < node-1; it++){
        for(int i = 0; i < node; i++){
            for(int j = 0; j < node; j++){
                if(edges[i][j] != -1){
                    if(dist[i] + edges[i][j] < dist[j]){
                        dist[j] = dist[i] + edges[i][j];
                        ancestor[j] = i;
                    }
                }
            }
        }
    }

    for(int i = 0; i < node; i++) //negative cycle detection
        for(int j = 0; j < node; j++){
            if(dist[i] + edges[i][j] < dist[j])
            {
                cout<<"Negative cycle!"<<endl;
                return;
            }
        }
}
int main(){
    int node;
    cin>>node;
    edges.resize(node,vector<int>(node,inf));
    dist.resize(node,inf);
    ancestor.resize(node,-1);
    int a,b,d;
    while(cin>>a>>b>>d){
        /*input: source destination weight*/
        if(a == -1 && b == -1 && d == -1)
            break;
        edges[a][b] = d;
    }
    int start;
    cin>>start;
    BellmanFord(start,node);
    return 0;
}

```

5.2 BFS-queue

```

/*BFS - queue version*/
void BFS(vector<int> &result, vector<pair<int, int>> edges, int
node, int start)
{
    vector<int> pass(node, 0);
    queue<int> q;
    queue<int> p;
    q.push(start);
    int count = 1;
    vector<pair<int, int>> newedges;
    while (!q.empty())
    {
        pass[q.front()] = 1;
        for (int i = 0; i < edges.size(); i++)
        {
            if (edges[i].first == q.front() && pass[edges[i].
                second] == 0)
            {
                p.push(edges[i].second);
                result[edges[i].second] = count;
            }
        }
    }
}

```

```

    else if (edges[i].second == q.front() && pass[edges
        [i].first] == 0)
    {
        p.push(edges[i].first);
        result[edges[i].first] = count;
    }
    else
        newedges.push_back(edges[i]);
}
edges = newedges;
newedges.clear();
q.pop();
if (q.empty() == true)
{
    q = p;
    queue<int> tmp;
    p = tmp;
    count++;
}
}
}
}
int main()
{
    int node;
    cin >> node;
    vector<pair<int, int>> edges;
    int a, b;
    while (cin >> a >> b)
    {
        /*a = b = -1 means input edges ended*/
        if (a == -1 && b == -1)
            break;
        edges.push_back(pair<int, int>(a, b));
    }
    vector<int> result(node, -1);
    BFS(result, edges, node, 0);
}
return 0;
}

```

5.3 DFS-rec

```

/*DFS - Recursive version*/
map<pair<int,int>,int> edges;
vector<int> pass;
vector<int> route;
void DFS(int start){
    pass[start] = 1;
    map<pair<int,int>,int>::iterator iter;
    for(iter = edges.begin(); iter != edges.end(); iter++){
        if((*iter).first.first == start && (*iter).second == 0
            && pass[(*iter).first.second] == 0){
            route.push_back((*iter).first.second);
            DFS((*iter).first.second);
        }
        else if((*iter).first.second == start && (*iter).second
            == 0 && pass[(*iter).first.first] == 0){
            route.push_back((*iter).first.first);
            DFS((*iter).first.first);
        }
    }
}
int main(){
    int node;
    cin>>node;
    pass.resize(node,0);
    int a,b;
    while(cin>>a>>b){
        if(a == -1 && b == -1)
            break;
        edges.insert(pair<pair<int,int>,int>(pair<int,int>(a,b),
            0));
    }
    int start;
    cin>>start;
    route.push_back(start);
    DFS(start);
    return 0;
}

```

5.4 Dijkstra

```

/*SPA - Dijkstra*/
const int MAXN = 1e5 + 3;
const int inf = INT_MAX;
typedef pair<int, int> pii;
vector<vector<pii>> weight(MAXN);
vector<int> isDone(MAXN, false), dist, ancestor;
void dijkstra(int s)
{
    priority_queue<pii, vector<pii>, greater<pii>> pq;
    pq.push(pii(0, s));
    ancestor[s] = -1;
    while (!pq.empty())
    {
        int u = pq.top().second;
    }
}

```

```

pq.pop();

isDone[u] = true;

for (auto &pr : weight[u])
{
    int v = pr.first, w = pr.second;

    if (!isDone[v] && dist[u] + w < dist[v])
    {
        dist[v] = dist[u] + w;
        pq.push(pii(dist[v], v));
        ancestor[v] = u;
    }
}

// weight[a - 1].push_back(pii(b - 1, w));
// weight[b - 1].push_back(pii(a - 1, w));
// dist.resize(n, inf);
// ancestor.resize(n, -1);
// dist[0] = 0;
// dijkstra(0);

```

5.5 Euler circuit

```

/*Euler circuit*/
/*From NTU kiseki*/
/*G is graph, vis is visited, la is path*/
bool vis[N];
size_t la[K];
void dfs(int u, vector<int> &vec)
{
    while (la[u] < G[u].size())
    {
        if (vis[G[u][la[u]].second])
        {
            ++la[u];
            continue;
        }
        int v = G[u][la[u]].first;
        vis[G[u][la[u]].second] = true;
        ++la[u];
        dfs(v, vec);
        vec.push_back(v);
    }
}

```

5.6 Floyd-warshall

```

/*SPA - Floyd-Warshall*/
// 有向圖 · 正邊 O(V³)
// 有向圖 · 無負環 O(V³)
// 有向圖 · 有負環 不適用

// 無向圖 · 正邊 O(V³)
// 無向圖 · 無負環 不適用
// 無向圖 · 有負環 不適用
/*Find min weight cycle*/
#define inf 99999
void floyd_warshall(vector<vector<int>> &distance, vector<
vector<int>> &ancestor, int n)
{
    for (int k = 0; k < n; k++)
    {
        for (int i = 0; i < n; i++)
        {
            for (int j = 0; j < n; j++)
            {
                if (distance[i][k] + distance[k][j] < distance[
i][j])
                {
                    distance[i][j] = distance[i][k] + distance[
k][j];
                    ancestor[i][j] = ancestor[k][j];
                }
            }
        }
    }

    vector<vector<int>> distance(n, vector<int>(n, inf));
    vector<vector<int>> ancestor(n, vector<int>(n, -1));
    distance[a][b] = w;
    ancestor[a][b] = w;
    floyd_warshall(distance, ancestor, n);
    /*Negative cycle detection*/
    for (int i = 0; i < n; i++)
    {
        if (distance[i][i] < 0)
        {
            cout << "Negative cycle!" << endl;
            break;
        }
    }
}

```

5.7 Hamilton_cycle

```

/*find hamilton cycle*/
void hamilton(vector<vector<int>> gp, int k, int cur, vector<
int>& solution, vector<bool> pass, bool& flag){
    if(k == gp.size()-1){
        if(gp[cur][1] == 1){
            cout << 1 << " ";
            while(cur != 1){
                cout << cur << " ";
                cur = solution[cur];
            }
            cout << cur << endl;
            flag = true;
            return;
        }
    }
    for (int i = 0; i < gp[cur].size() && !flag; i++){
        if(gp[cur][i] == 1 && !pass[i]){
            pass[i] = true;
            solution[i] = cur;
            hamilton(gp, k + 1, i, solution, pass, flag);
            pass[i] = false;
        }
    }
}

int main(){
    int n;
    while(cin>>n){
        int a,b;
        bool end = false;
        vector<vector<int>> gp(n+1, vector<int>(n+1, 0));
        while(cin>>a>>b){
            if(a == 0 && b == 0)
                break;
            gp[a][b] = 1;
            gp[b][a] = 1;
        }
        vector<int> solution(n + 1, -1);
        vector<bool> pass(n + 1, false);
        solution[1] = 0;
        pass[1] = true;
        bool flag = false;
        hamilton(gp, 1, 1, solution, pass, flag);
        if(!flag)
            cout << "N" << endl;
    }
    return 0;
}

/*
4
1 2
2 3
2 4
3 4
3 1
0 0
output: 1 3 4 2 1
*/

```

5.8 Kruskal

```

/*mst - Kruskal*/
struct edges{
    int from;
    int to;
    int weight;
    friend bool operator < (edges a, edges b){
        return a.weight > b.weight;
    }
};

int find(int x, vector<int>& union_set){
    if(x != union_set[x])
        union_set[x] = find(union_set[x], union_set);
    return union_set[x];
}

void merge(int a, int b, vector<int>& union_set){
    int pa = find(a, union_set);
    int pb = find(b, union_set);
    if(pa != pb)
        union_set[pa] = pb;
}

void kruskal(priority_queue<edges> pq, int n){
    vector<int> union_set(n, 0);
    for (int i = 0; i < n; i++)
        union_set[i] = i;
    int edge = 0;
    int cost = 0; //evaluate cost of mst
    while(!pq.empty() && edge < n - 1){
        edges cur = pq.top();
        int from = find(cur.from, union_set);
        int to = find(cur.to, union_set);
        if(from != to){
            merge(from, to, union_set);
            edge += 1;
            cost += cur.weight;
        }
    }
}

```

```

        pq.pop();
    }
    if(edge < n-1)
        cout << "No mst" << endl;
    else
        cout << cost << endl;
}
int main(){
    int n;
    cin >> n;
    int a, b, d;
    priority_queue<edges> pq;
    while(cin>>a>>b>>d){
        if(a == -1 && b == -1 && d == -1)
            break;
        edges tmp;
        tmp.from = a;
        tmp.to = b;
        tmp.weight = d;
        pq.push(tmp);
    }
    kruskal(pq, n);
    return 0;
}

```

5.9 Minimum Weight Cycle

```

// 最小環
// 圖上無負環 !!!!
#define INF 99999
vector<vector<int>>> w, d, p;
vector<int> cycle;
int c = 0;
void trace(int i, int j)
{
    cycle[c++] = i;
    if (i != j)
        trace(p[i][j], j);
}
void init(int n)
{
    for (int i = 0; i < n; ++i)
        d[i][i] = 0;
}
void minimum_cycle(int n)
{
    int weight = 1e9;
    for (int k = 0; k < n; ++k)
    {
        for (int i = 0; i < k; ++i)
            for (int j = 0; j < k; ++j)
                if (i != j)
                    if (w[k][i] + d[i][j] + w[j][k] < weight)
                    {
                        weight = w[k][i] + d[i][j] + w[j][k];
                        c = 0;
                        trace(i, j);
                        cycle[c++] = k;
                    }

        for (int i = 0; i < n; ++i)
        {
            for (int j = 0; j < n; ++j)
            {
                if (d[i][k] + d[k][j] < d[i][j])
                {
                    d[i][j] = d[i][k] + d[k][j];
                    p[i][j] = p[i][k];
                }
            }
        }
    }
    if (weight == 1e9)
        cout << "No exist";
    else
    {
        bug(weight);
        bug(c);
        bugarr(cycle);
    }
}
void simple_minimum_cycle(int n) // No use vector p
{
    int weight = INF;
    for (int k = 0; k < n; ++k)
    {
        for (int i = 0; i < k; ++i)
            for (int j = 0; j < k; ++j)
                if (i != j)
                    weight = min(mp[k][i] + d[i][j] + mp[j][k],
                                weight);

        for (int i = 0; i < n; ++i)
            for (int j = 0; j < n; ++j)
                d[i][j] = min(d[i][k] + d[k][j], d[i][j]);
    }
}

```

```

    if (weight == INF)
        cout << "Back to jail\n";
    else
        cout << weight << endl;
}
w.resize(n, vector<int>(n, INF));
d.resize(n, vector<int>(n, INF));
p.resize(n, vector<int>(n));
cycle.resize(n);
//Edge input
w[a][b] = w;
d[a][b] = w;
p[a][b] = b;
init(n);
minimum_cycle(n);

```

5.10 Prim

```

/*mst - Prim*/
#define inf 99999
struct edges
{
    int from;
    int to;
    int weight;
    friend bool operator<(edges a, edges b)
    {
        return a.weight > b.weight;
    }
};
void Prim(vector<vector<int>>> gp, int n, int start)
{
    vector<bool> pass(n, false);
    int edge = 0;
    int cost = 0; //evaluate cost of mst
    priority_queue<edges> pq;
    for (int i = 0; i < n; i++)
    {
        if (gp[start][i] != inf)
        {
            edges tmp;
            tmp.from = start;
            tmp.to = i;
            tmp.weight = gp[start][i];
            pq.push(tmp);
        }
    }
    pass[start] = true;
    while (!pq.empty() && edge < n - 1)
    {
        edges cur = pq.top();
        pq.pop();
        if (!pass[cur.to])
        {
            for (int i = 0; i < n; i++)
            {
                if (gp[cur.to][i] != inf)
                {
                    edges tmp;
                    tmp.from = cur.to;
                    tmp.to = i;
                    tmp.weight = gp[cur.to][i];
                    pq.push(tmp);
                }
            }
            pass[cur.to] = true;
            edge += 1;
            cost += cur.weight;
        }
    }
    if (edge < n - 1)
        cout << "No mst" << endl;
    else
        cout << cost << endl;
}
int main()
{
    int n;
    cin >> n;
    int a, b, d;
    vector<vector<int>>> gp(n, vector<int>(n, inf));
    while (cin >> a >> b >> d)
    {
        if (a == -1 && b == -1 && d == -1)
            break;
        if (gp[a][b] > d)
            gp[a][b] = d;
    }
    Prim(gp, n, 0);
    return 0;
}

```

5.11 Union_find

```

// union_find from 台大
vector<int> father;

```

```
vector<int> people;
void init(int n)
{
    for (int i = 0; i < n; i++)
    {
        father[i] = i;
        people[i] = 1;
    }
}
int Find(int x)
{
    if (x != father[x])
        father[x] = Find(father[x]);
    return father[x];
}
void Union(int x, int y)
{
    int m = Find(x);
    int n = Find(y);
    if (m != n)
    {
        father[n] = m;
        people[m] += people[n];
    }
}
```

6 Mathematics

6.1 Catalan

Catalan number

- 0~19項的catalan number
 - 1, 1, 2, 5, 14, 42, 132, 429, 1430, 4862, 16796, 58786, 208012, 742900, 2674440, 9694845, 35357670, 129644790, 477638700, 1767263190
 - 公式: $C_n = \frac{1}{n+1} \binom{2n}{n} = \frac{(2n)!}{(n+1)!n!}$

6.2 Combination

```
/*input type string or vector*/
for (int i = 0; i < (1 << input.size()); ++i)
{
    string testCase = "";
    for (int j = 0; j < input.size(); ++j)
        if (i & (1 << j))
            testCase += input[j];
}
```

6.3 CRT

```
// 中國剩餘定理
template <typename T>
tuple<T, T, T> extgcd(T a, T b)
{
    if (!b)
        return make_tuple(a, 1, 0);
    T d, x, y;
    tie(d, x, y) = extgcd(b, a % b);
    return make_tuple(d, y, x - (a / b) * y);
}
long long crt(vector<int> mod, vector<int> a)
{
    // x % mod[i] = a[i]
    long long mult = mod[0];
    int n = (int)mod.size();
    long long res = a[0];
    for (int i = 1; i < n; ++i)
    {
        long long d, x, y;
        tie(d, x, y) = extgcd(mult, mod[i] * 1ll);
        if ((a[i] - res) % d)
            return -1;
        long long new_mult = mult / __gcd(mult, 1ll * mod[i]) * mod[i];
        res += x * ((a[i] - res) / d) % new_mult * mult % new_mult;
        mult = new_mult;
        ((res %= mult) += mult) %= mult;
    }
    return res;
}
```

6.4 Extended Euclidean

```
// ax + by = gcd(a,b)
pair<long long, long long> extgcd(long long a, long long b)
{
    if (b == 0)
```

```
        return {1, 0};
    long long k = a / b;
    pair<long long, long long> p = extgcd(b, a - k * b);
    //cout << p.first << " " << p.second << endl;
    //cout << "商數(k)= " << k << endl << endl;
    return {p.second, p.first - k * p.second};
}
int main()
{
    int a, b;
    cin >> a >> b;
    pair<long long, long long> xy = extgcd(a, b); //(x0,y0)
    cout << xy.first << " " << xy.second << endl;
    cout << xy.first << " * " << a << " + " << xy.second << " * " << b << endl;
    return 0;
}
// ax + by = gcd(a,b) * r
/*find |x|+|y| -> min*/
int main()
{
    long long r, p, q; /*px+qy = r*/
    int cases;
    cin >> cases;
    while (cases--)
    {
        cin >> r >> p >> q;
        pair<long long, long long> xy = extgcd(q, p); //(x0,y0)
        long long ans = 0, tmp = 0;
        double k, k1;
        long long s, s1;
        k = 1 - (double)(r * xy.first) / p;
        s = round(k);
        ans = llabs(r * xy.first + s * p) + llabs(r * xy.second - s * q);
        k1 = -(double)(r * xy.first) / p;
        s1 = round(k1);
        /*cout << k << endl << k1 << endl;
        cout << s << endl << s1 << endl;*/
        tmp = llabs(r * xy.first + s1 * p) + llabs(r * xy.second - s1 * q);
        ans = min(ans, tmp);

        cout << ans << endl;
    }
    return 0;
}
```

6.5 Fermat

- $a^{(p-1)} \equiv 1 \pmod{p} \Leftrightarrow a * a^{(p-2)} \equiv 1$
 - $a^{(p-2)} \equiv 1/a$
- 同餘因數定理
 - $a \equiv b \pmod{p} \Leftrightarrow k|a - b$
- 同餘加法性質
 - $a \equiv b \pmod{p}$ and $c \equiv d \pmod{p}$
 $\Leftrightarrow a + c \equiv b + d \pmod{p}$
- 同餘相乘性質
 - $a \equiv b \pmod{p}$ and $c \equiv d \pmod{p}$
 $\Leftrightarrow ac \equiv bd \pmod{p}$
- 同餘次方性質
 - $a \equiv b \pmod{p} \Leftrightarrow a^n \equiv b^n \pmod{p}$
- 同餘倍方性質
 - $a \equiv b \pmod{p} \Leftrightarrow am \equiv bm \pmod{p}$

6.6 Hex to Dec

```
int HextoDec(string num) //16 to 10
{
    int base = 1;
    int temp = 0;
    for (int i = num.length() - 1; i >= 0; i--)
    {
        if (num[i] >= '0' && num[i] <= '9')
        {
            temp += (num[i] - 48) * base;
            base = base * 16;
        }
        else if (num[i] >= 'A' && num[i] <= 'F')
        {
            temp += (num[i] - 55) * base;
            base = base * 16;
        }
    }
}
```

```

    }
    return temp;
}
void DecToHex(int p) //10 to 16
{
    char *l = new (char);
    sprintf(l, "%X", p);
    //int l_intResult = stoi(l);
    cout << l << "\n";
    //return l_intResult;
}

```

6.7 Log

```

double mylog(double a, double base)
{
    //a 的對數底數 b = 自然對數 (a) / 自然對數 (b) 。
    return log(a) / log(base);
}

```

6.8 Mod 性質

加法： $(a + b) \bmod p = (a \bmod p + b \bmod p) \bmod p$

減法： $(a - b) \bmod p = (a \bmod p - b \bmod p + p) \bmod p$

乘法： $(a * b) \bmod p = (a \bmod p * b \bmod p) \bmod p$

次方： $(a^b) \bmod p = ((a \bmod p)^b) \bmod p$

加法結合律： $((a + b) \bmod p + c) \bmod p = (a + (b + c)) \bmod p$

乘法結合律： $((a * b) \bmod p * c) \bmod p = (a * (b * c)) \bmod p$

加法交換律： $(a + b) \bmod p = (b + a) \bmod p$

乘法交換律： $(a * b) \bmod p = (b * a) \bmod p$

結合律： $((a + b) \bmod p * c) = ((a * c) \bmod p + (b * c) \bmod p) \bmod p$

如果 $a \equiv b \pmod{m}$ ，我們會說 a, b 在模 m 下同餘。

以下為性質：

- 整除性： $a \equiv b \pmod{m} \Rightarrow c * m = a - b, c \in \mathbb{Z}$
 $\Rightarrow a \equiv b \pmod{m} \Rightarrow m \mid a - b$

- 遞移性：若 $a \equiv b \pmod{c}, b \equiv d \pmod{c}$
 則 $a \equiv d \pmod{c}$

- 保持基本運算：

$$\begin{cases} a \equiv b \pmod{m} \\ c \equiv d \pmod{m} \end{cases} \Rightarrow \begin{cases} a \pm c \equiv b \pm d \pmod{m} \\ a * c \equiv b * d \pmod{m} \end{cases}$$

- 放大縮小模數：

$$k \in \mathbb{Z}^+, a \equiv b \pmod{m} \Leftrightarrow k * a \equiv k * b \pmod{k * m}$$

模逆元是取模下的反元素，即為找到 a^{-1} 使得 $aa^{-1} \equiv 1 \pmod{c}$ 。

整數 a 在模 c 下要有模反元素的充分必要條件為 a, c 互質。

模逆元如果存在會有無限個，任意兩相鄰模逆元相差 c 。

費馬小定理

給定一個質數 p 及一個整數 a ，那麼： $a^p \equiv a \pmod{p}$ 如果 $\gcd(a, p) = 1$ ，則： $a^{p-1} \equiv 1 \pmod{p}$

歐拉定理

歐拉定理是比較 general 版本的費馬小定理，給定兩個整數 n 和 a ，如果 $\gcd(a, n) = 1$ ，則： $a^{\Phi(n)} \equiv 1 \pmod{n}$ 如果 n 是質數， $\Phi(n) = n - 1$ ，也就是費馬小定理。

Wilson's theorem

給定一個質數 p ，則： $(p-1)! \equiv -1 \pmod{p}$

6.9 PI

```

#define PI acos(-1)
#define PI M_PI

```

6.10 Pow_Mod

```

int pow_mod(int a, int n, int m) // a ^ n mod m;
{
    // a, n, m < 10 ^ 9
    if (n == 0)
        return 1;
    int x = pow_mid(a, n / 2, m);
    long long ans = (long long)x * x % m;
    if (n % 2 == 1)
        ans = ans * a % m;
    return (int)ans;
}
int inv(int a, int n, int p) // n = p-2
{
    long long res = 1;
    for (; n >= 1, (a *= a) %= p)
        if (n & 1)
            (res *= a) %= p;
    return res;
}

```

6.11 Prime table

```

const int maxn = sqrt(INT_MAX);
vector<int> p;
bitset<maxn> is_notp;
void PrimeTable()
{
    is_notp.reset();
    is_notp[0] = is_notp[1] = 1;
    for (int i = 2; i <= maxn; ++i)
    {
        if (!is_notp[i])
            p.push_back(i);
        for (int j = 0; j < (int)p.size(); ++j)
        {
            if (i * p[j] > maxn)
                break;
            is_notp[i * p[j]] = 1;
            if (i % p[j] == 0)
                break;
        }
    }
}

```

6.12 Prime 判斷

```

typedef long long ll;
ll modmul(ll a, ll b, ll mod)
{
    ll ret = 0;
    for (; b >= 1, a = (a + a) % mod)
        if (b & 1)
            ret = (ret + a) % mod;
    return ret;
}
ll qpow(ll x, ll u, ll mod)
{
    ll ret = 1ll;
    for (; u >= 1, x = modmul(x, x, mod))
        if (u & 1)
            ret = modmul(ret, x, mod);
    return ret;
}
ll gcd(ll a, ll b)
{
    return b ? gcd(b, a % b) : a;
}
ll Pollard_Rho(ll n, ll c)
{
    ll i = 1, j = 2, x = rand() % (n - 1) + 1, y = x;
    while (1)
    {
        i++;
        x = (modmul(x, x, n) + c) % n;
        ll p = gcd((y - x + n) % n, n);
        if (p != 1 && p != n)
            return p;
        if (y == x)
            return n;
        if (i == j)
        {
            y = x;
            j <<= 1;
        }
    }
}
bool Miller_Rabin(ll n)
{
    ll x, pre, u = n - 1;
    int i, j, k = 0;
    if (n == 2 || n == 3 || n == 5 || n == 7 || n == 11)
        return 1;
    if (n == 1 || !(n % 2) || !(n % 3) || !(n % 5) || !(n % 7) || !(n % 11))
        return 0;
    while (!(u & 1))
    {
        k++;
        u >>= 1;
    }
    srand((long long)12234336);
    for (i = 1; i <= 50; i++)
    {
        x = rand() % (n - 2) + 2;
        if (!(n % x))
            return 0;
        x = qpow(x, u, n);
        pre = x;
        for (j = 1; j <= k; j++)
        {
            x = modmul(x, x, n);
            if (x == 1 && pre != 1 && pre != n - 1)
                return 0;
            pre = x;
        }
        if (x != 1)
            return 0;
    }
}

```

```

    }
    return 1;
}
// if (Miller_Rabin(n)) puts("Prime");

```

6.13 Round(小數)

```

double myround(double number, unsigned int bits)
{
    LL integerPart = number;
    number -= integerPart;
    for (unsigned int i = 0; i < bits; ++i)
        number *= 10;
    number = (LL)(number + 0.5);
    for (unsigned int i = 0; i < bits; ++i)
        number /= 10;
    return integerPart + number;
}
//printf("%.1f\n", round(3.4515239, 1));

```

6.14 二分逼近法

```

#define eps 1e-14
void half_interval()
{
    double L = 0, R = /*區間*/, M;
    while (R - L >= eps)
    {
        M = (R + L) / 2;
        if (/*函數*/ > /*方程式目標*/)
            L = M;
        else
            R = M;
    }
    printf("%.3lf\n", R);
}

```

6.15 公式

$$S_n = \frac{a(1-r^n)}{1-r} \quad a_n = \frac{a_1 + a_n}{2} \quad \sum_{k=1}^n k = \frac{n(n+1)}{2} \quad \sum_{k=1}^n k^2 = \frac{n(n+1)(2n+1)}{6}$$

$$\sum_{k=1}^n k^3 = \left[\frac{n(n+1)}{2} \right]^2$$

6.16 四則運算

```

string s = ""; //開頭是負號要補0
long long int DFS(int le, int ri) // (0, string final index)
{
    int c = 0;
    for (int i = ri; i >= le; i--)
    {
        if (s[i] == '+')
            c++;
        if (s[i] == '(')
            c--;
        if (s[i] == '+' && c == 0)
            return DFS(le, i - 1) + DFS(i + 1, ri);
        if (s[i] == '-' && c == 0)
            return DFS(le, i - 1) - DFS(i + 1, ri);
    }
    for (int i = ri; i >= le; i--)
    {
        if (s[i] == '+')
            c++;
        if (s[i] == '(')
            c--;
        if (s[i] == '*' && c == 0)
            return DFS(le, i - 1) * DFS(i + 1, ri);
        if (s[i] == '/' && c == 0)
            return DFS(le, i - 1) / DFS(i + 1, ri);
        if (s[i] == '%' && c == 0)
            return DFS(le, i - 1) % DFS(i + 1, ri);
    }
    if ((s[le] == '(' && (s[ri] == ')'))
        return DFS(le + 1, ri - 1); //去除刮號
    if (s[le] == ' ' && s[ri] == ' ')
        return DFS(le + 1, ri - 1); //去除左右兩邊空格
    if (s[le] == ' ')
        return DFS(le + 1, ri); //去除左邊空格
    if (s[ri] == ' ')
        return DFS(le, ri - 1); //去除右邊空格
    long long int num = 0;
    for (int i = le; i <= ri; i++)
        num = num * 10 + s[i] - '0';
    return num;
}

```

6.17 因數表

```

const int limit = 10000000;
vector<vector<int>> arr(limit);
for (int i = 1; i <= limit; i++)
{
    for (int j = i; j <= limit; j += i)
        arr[j].pb(i); // i 為因數
}

```

6.18 數字乘法組合

```

void dfs(int j, int old, int num, vector<int> com, vector<vector<int>> &ans)
{
    for (int i = j; i <= sqrt(num); i++)
    {
        if (old == num)
            com.clear();
        if (num % i == 0)
        {
            vector<int> a;
            a = com;
            a.push_back(i);
            finds(i, old, num / i, a, ans);
            a.push_back(num / i);
            ans.push_back(a);
        }
    }
}
vector<vector<int>> ans;
vector<int> zero;
dfs(2, num, num, zero, ans);
/*num 為 input 數字*/
for (int i = 0; i < ans.size(); i++)
{
    for (int j = 0; j < ans[i].size() - 1; j++)
        cout << ans[i][j] << " ";
    cout << ans[i][ans[i].size() - 1] << endl;
}

```

6.19 數字加法組合

```

void recur(int i, int n, int m, vector<int> &out, vector<vector<int>> &ans)
{
    if (n == 0)
    {
        for (int i : out)
            if (i > m)
                return;
        ans.push_back(out);
    }
    for (int j = i; j <= n; j++)
    {
        out.push_back(j);
        recur(j, n - j, m, out, ans);
        out.pop_back();
    }
}
vector<vector<int>> ans;
vector<int> zero;
recur(1, num, num, zero, ans);
// num 為 input 數字
for (int i = 0; i < ans.size(); i++)
{
    for (int j = 0; j < ans[i].size() - 1; j++)
        cout << ans[i][j] << " ";
    cout << ans[i][ans[i].size() - 1] << endl;
}

```

6.20 羅馬數字

```

int romanToInt(string s)
{
    unordered_map<char, int> T;
    T['I'] = 1;
    T['V'] = 5;
    T['X'] = 10;
    T['L'] = 50;
    T['C'] = 100;
    T['D'] = 500;
    T['M'] = 1000;

    int sum = T[s.back()];
    for (int i = s.length() - 2; i >= 0; --i)
    {
        if (T[s[i]] < T[s[i + 1]])
            sum -= T[s[i]];
        else
            sum += T[s[i]];
    }
    return sum;
}

```


6.21 質因數分解

```
LL ans;
void find(LL n, LL c) // 配合質數判斷
{
    if (n == 1)
        return;
    if (Miller_Rabin(n))
    {
        ans = min(ans, n);
        // bug(ans); // 質因數
        return;
    }
    LL x = n, k = c;
    while (x == n)
        x = Pollard_Rho(x, c--);
    find(n / x, k);
    find(x, k);
}
```

6.22 質數數量

```
// 10 ^ 11 左右
#define LL long long
const int N = 5e6 + 2;
bool np[N];
int prime[N], pi[N];
int getprime()
{
    int cnt = 0;
    np[0] = np[1] = true;
    pi[0] = pi[1] = 0;
    for (int i = 2; i < N; ++i)
    {
        if (!np[i])
            prime[++cnt] = i;
        pi[i] = cnt;
        for (int j = 1; j <= cnt && i * prime[j] < N; ++j)
        {
            np[i * prime[j]] = true;
            if (i % prime[j] == 0)
                break;
        }
    }
    return cnt;
}
const int M = 7;
const int PM = 2 * 3 * 5 * 7 * 11 * 13 * 17;
int phi[PM + 1][M + 1], sz[M + 1];
void init()
{
    getprime();
    sz[0] = 1;
    for (int i = 0; i <= PM; ++i)
        phi[i][0] = i;
    for (int i = 1; i <= M; ++i)
    {
        sz[i] = prime[i] * sz[i - 1];
        for (int j = 1; j <= PM; ++j)
            phi[j][i] = phi[j][i - 1] - phi[j / prime[i]][i - 1];
    }
}
int sqrt2(LL x)
{
    LL r = (LL)sqrt(x - 0.1);
    while (r * r <= x)
        ++r;
    return int(r - 1);
}
int sqrt3(LL x)
{
    LL r = (LL)cbrt(x - 0.1);
    while (r * r * r <= x)
        ++r;
    return int(r - 1);
}
LL getphi(LL x, int s)
{
    if (s == 0)
        return x;
    if (s <= M)
        return phi[x % sz[s]][s] + (x / sz[s]) * phi[sz[s]][s];
    if (x <= prime[s] * prime[s])
        return pi[x] - s + 1;
    if (x <= prime[s] * prime[s] * prime[s] && x < N)
    {
        int s2x = pi[sqrt2(x)];
        LL ans = pi[x] - (s2x + s - 2) * (s2x - s + 1) / 2;
        for (int i = s + 1; i <= s2x; ++i)
            ans += pi[x / prime[i]];
        return ans;
    }
    return getphi(x, s - 1) - getphi(x / prime[s], s - 1);
}
LL getpi(LL x)
```

```
{
    if (x < N)
        return pi[x];
    LL ans = getphi(x, pi[sqrt3(x)]) + pi[sqrt3(x)] - 1;
    for (int i = pi[sqrt3(x)] + 1, ed = pi[sqrt2(x)]; i <= ed; ++i)
        ans -= getpi(x / prime[i]) - i + 1;
    return ans;
}
LL lehmer_pi(LL x)
{
    if (x < N)
        return pi[x];
    int a = (int)lehmer_pi(sqrt2(sqrt2(x)));
    int b = (int)lehmer_pi(sqrt2(x));
    int c = (int)lehmer_pi(sqrt3(x));
    LL sum = getphi(x, a) + (LL)(b + a - 2) * (b - a + 1) / 2;
    for (int i = a + 1; i <= b; ++i)
    {
        LL w = x / prime[i];
        sum -= lehmer_pi(w);
        if (i > c)
            continue;
        LL lim = lehmer_pi(sqrt2(w));
        for (int j = i; j <= lim; j++)
            sum -= lehmer_pi(w / prime[j]) - (j - 1);
    }
    return sum;
}
// lehmer_pi(n)
```

7 Other

7.1 Binary search 三類變化

```
// 查找和目標值完全相等的數
int find(vector<int> &nums, int target)
{
    int left = 0, right = nums.size() - 1;
    while (left < right)
    {
        int mid = left + (right - left) / 2;
        if (nums[mid] == target)
            return mid;
        else if (nums[mid] < target)
            left = mid + 1;
        else
            right = mid;
    }
    return -1;
}
// 找第一個不小於目標值的數 == 找最後一個小於目標值的數
/*(lower_bound)*/
int find(vector<int> &nums, int target)
{
    int left = 0, right = nums.size() - 1;
    while (left < right)
    {
        int mid = left + (right - left) / 2;
        if (nums[mid] < target)
            left = mid + 1;
        else
            right = mid;
    }
    return right;
}
// 找第一個大於目標值的數 == 找最後一個不大於目標值的數
/*(upper_bound)*/
int find(vector<int> &nums, int target)
{
    int left = 0, right = nums.size() - 1;
    while (left < right)
    {
        int mid = left + (right - left) / 2;
        if (nums[mid] <= target)
            left = mid + 1;
        else
            right = mid;
    }
    return right;
}
```

7.2 Heap sort

```
void MaxHeapify(vector<int> &array, int root, int length)
{
    int left = 2 * root, right = 2 * root + 1, largest;
    if (left <= length && array[left] > array[root])
        largest = left;
    else
        largest = root;
    if (right <= length && array[right] > array[largest])
        largest = right;
    if (largest != root)
```

```

    {
        swap(array[largest], array[root]);
        MaxHeapify(array, largest, length);
    }
}
void HeapSort(vector<int> &array)
{
    array.insert(array.begin(), 0);
    for (int i = (int)array.size() / 2; i >= 1; i--)
        MaxHeapify(array, i, (int)array.size() - 1);
    int size = (int)array.size() - 1;
    for (int i = (int)array.size() - 1; i >= 2; i--)
    {
        swap(array[1], array[i]);
        size--;
        MaxHeapify(array, 1, size);
    }
    array.erase(array.begin());
}

```

7.3 Josephus

```

/*n people kill k for each turn*/
int josephus(int n, int k)
{
    int s = 0;
    for (int i = 2; i <= n; i++)
    {
        s = (s + k) % i;
    }
    /*index start from 1 -> s+1*/
    return s + 1;
}
/*died at kth*/
int kth(int n, int m, int k)
{
    if (m == 1)
        return n - 1;
    for (k = k * m + m - 1; k >= n; k = k - n + (k - n) / (m - 1))
        ;
    return k;
}

```

7.4 Largest Multi-interval

```

/*多區間算最大值*/
bool name(pii a, pii b)
{ return b.first > a.first; }
vector<pii> data;
data.pb(pii(a, c)); // 區間 a 到 c
sort(data.begin(), data.end(), name); // pair first 從小到大
int l = data[0].x, r = data[0].y, res = 0;
for (int i = 1; i < data.size(); i++)
{
    if (data[i].x <= r)
    {
        if (r < data[i].y)
            r = data[i].y;
    }
    else
    {
        res += r - l;
        l = data[i].x;
        r = data[i].y;
    }
}
res += r - l; // 最大段落不重疊

```

7.5 Merge sort

```

long long merge(vector<int> &arr, int left, int mid, int right)
{
    int *tmp = new int[right - left + 1];
    long long sum = 0;
    int l = left, r = mid + 1, m = 0;
    while (l <= mid && r <= right)
    {
        if (arr[l] <= arr[r])
            tmp[m++] = arr[l++];
        else
        {
            tmp[m++] = arr[r++];
            sum += mid - l + 1;
        }
    }
    while (l <= mid)
        tmp[m++] = arr[l++];
    while (r <= right)
        tmp[m++] = arr[r++];
    for (int i = left; i <= right; ++i)
        arr[i] = tmp[i - left];
    delete[] tmp;
    return sum;
}

```

```

long long mergesort(vector<int> &arr, int left, int right)
{
    long long sum = 0;
    // left = 0, right = P.size() - 1
    if (left < right)
    {
        int mid = (left + right) / 2;
        sum = mergesort(arr, left, mid);
        sum += mergesort(arr, mid + 1, right);
        sum += merge(arr, left, mid, right);
    }
    return sum; // 回傳為 swap 次數
}

```

7.6 Quick sort

```

int Partition(vector<int> &arr, int front, int end)
{
    int pivot = arr[end];
    int i = front - 1;
    for (int j = front; j < end; j++)
    {
        if (arr[j] < pivot)
        {
            i++;
            swap(arr[i], arr[j]);
        }
    }
    i++;
    swap(arr[i], arr[end]);
    return i;
}
void QuickSort(vector<int> &arr, int front, int end)
{
    // front = 0, end = arr.size() - 1
    if (front < end)
    {
        int pivot = Partition(arr, front, end);
        QuickSort(arr, front, pivot - 1);
        QuickSort(arr, pivot + 1, end);
    }
}

```

7.7 Sudoku solution

```

/*數獨解法*/
int getSquareIndex(int row, int column, int n)
{
    return row / n * n + column / n;
}

bool backtracking(vector<vector<int>> &board, vector<vector<bool>> &rows, vector<vector<bool>> &cols, vector<vector<bool>> &boxes, int index, int n)
{
    int n2 = n * n;
    int rowNum = index / n2, colNum = index % n2;
    if (index >= n2 * n2)
        return true;

    if (board[rowNum][colNum] != 0)
        return backtracking(board, rows, cols, boxes, index + 1, n);

    for (int i = 1; i <= n2; i++)
    {
        if (!rows[rowNum][i] && !cols[colNum][i] && !boxes[getSquareIndex(rowNum, colNum, n)][i])
        {
            rows[rowNum][i] = true;
            cols[colNum][i] = true;
            boxes[getSquareIndex(rowNum, colNum, n)][i] = true;
            board[rowNum][colNum] = i;
            if (backtracking(board, rows, cols, boxes, index + 1, n))
                return true;
            board[rowNum][colNum] = 0;
            rows[rowNum][i] = false;
            cols[colNum][i] = false;
            boxes[getSquareIndex(rowNum, colNum, n)][i] = false;
        }
    }
    return false;
}

/*用法 main*/
int n = sqrt(數獨邊長大小) /*e.g. 9*9 n=3*/
vector<vector<int>> board(n * n + 1, vector<int>(n * n + 1, 0));
vector<vector<bool>> isRow(n * n + 1, vector<bool>(n * n + 1, false));
vector<vector<bool>> isColumn(n * n + 1, vector<bool>(n * n + 1, false));
vector<vector<bool>> isSquare(n * n + 1, vector<bool>(n * n + 1, false));

for (int i = 0; i < n * n; ++i)

```

```

{
    for (int j = 0; j < n * n; ++j)
    {
        int number;
        cin >> number;
        board[i][j] = number;
        if (number == 0)
            continue;
        isRow[i][number] = true;
        isColumn[j][number] = true;
        isSquare[getSquareIndex(i, j, n)][number] = true;
    }
}
if (backtracking(board, isRow, isColumn, isSquare, 0, n))
    /*有解答*/
else
    /*解答*/

```

7.8 Weighted Job Scheduling

```

struct Job
{
    int start, finish, profit;
};
bool jobComparataor(Job s1, Job s2)
{
    return (s1.finish < s2.finish);
}
int latestNonConflict(Job arr[], int i)
{
    for (int j = i - 1; j >= 0; j--)
    {
        if (arr[j].finish <= arr[i].start)
            return j;
    }
    return -1;
}
int findMaxProfit(Job arr[], int n)
{
    sort(arr, arr + n, jobComparataor);
    int *table = new int[n];
    table[0] = arr[0].profit;
    for (int i = 1; i < n; i++)
    {
        int inclProf = arr[i].profit;
        int l = latestNonConflict(arr, i);
        if (l != -1)
            inclProf += table[l];
        table[i] = max(inclProf, table[i - 1]);
    }
    int result = table[n - 1];
    delete[] table;
    return result;
}

```

8 String

8.1 KMP

```

// 用在在一個 s 內查找一個詞 w 的出現位置
void ComputePrefix(string s, int next[])
{
    int n = s.length();
    int q, k;
    next[0] = 0;
    for (k = 0, q = 1; q < n; q++)
    {
        while (k > 0 && s[k] != s[q])
            k = next[k];
        if (s[k] == s[q])
            k++;
        next[q] = k;
    }
}
void KMPMatcher(string text, string pattern)
{
    int n = text.length();
    int m = pattern.length();
    int next[pattern.length()];
    ComputePrefix(pattern, next);

    for (int i = 0, q = 0; i < n; i++)
    {
        while (q > 0 && pattern[q] != text[i])
            q = next[q];
        if (pattern[q] == text[i])
            q++;
        if (q == m)
        {
            cout << "Pattern occurs with shift " << i - m + 1
                  << endl;
            q = 0;
        }
    }
}

```

```

}
}
// string s = "abcdabcdebcd";
// string p = "bcd";
// KMPMatcher(s, p);
// cout << endl;

```

8.2 Min Edit Distance

```

int EditDistance(string a, string b)
{
    vector<vector<int>> dp(a.size() + 1, vector<int>(b.size() + 1, 0));
    int m = a.length(), n = b.length();
    for (int i = 0; i < m + 1; i++)
    {
        for (int j = 0; j < n + 1; j++)
        {
            if (i == 0)
                dp[i][j] = j;
            else if (j == 0)
                dp[i][j] = i;
            else if (a[i - 1] == b[j - 1])
                dp[i][j] = dp[i - 1][j - 1];
            else
                dp[i][j] = 1 + min(min(dp[i - 1][j], dp[i][j - 1]), dp[i - 1][j - 1]);
        }
    }
    return dp[m][n];
}

```

8.3 Sliding window

```

string minWindow(string s, string t)
{
    unordered_map<char, int> letterCnt;
    for (int i = 0; i < t.length(); i++)
        letterCnt[t[i]]++;
    int minLength = INT_MAX, minStart = -1;
    int left = 0, matchCnt = 0;
    for (int i = 0; i < s.length(); i++)
    {
        if (--letterCnt[s[i]] >= 0)
            matchCnt++;
        while (matchCnt == t.length())
        {
            if (i - left + 1 < minLength)
            {
                minLength = i - left + 1;
                minStart = left;
            }
            if (++letterCnt[s[left]] > 0)
                matchCnt--;
            left++;
        }
    }
    return minLength == INT_MAX ? "" : s.substr(minStart, minLength);
}

```

8.4 Split

```

vector<string> mysplit(string s, string d)
{
    int ps = 0, pe, dl = d.length();
    string token;
    vector<string> res;
    while ((pe = s.find(d, ps)) != string::npos)
    {
        token = s.substr(ps, pe - ps);
        ps = pe + dl;
        res.push_back(token);
    }
    res.push_back(s.substr(ps));
    return res;
}

```

9 data structure

9.1 BigInt

```

//台大 //非必要請用python
struct BigInt
{
    static const int LEN = 60; // maxLEN
    static const int BIGMOD = 10000; //10為正常位數
    int s;
    int vl, v[LEN];
    // vector<int> v;
    BigInt() : s(1) { vl = 0; }
    BigInt(long long a)
    {

```

```

    s = 1;
    vl = 0;
    if (a < 0)
    {
        s = -1;
        a = -a;
    }
    while (a)
    {
        push_back(a % BIGMOD);
        a /= BIGMOD;
    }
}
Bigint(string str)
{
    s = 1;
    vl = 0;
    int stPos = 0, num = 0;
    if (!str.empty() && str[0] == '-')
    {
        stPos = 1;
        s = -1;
    }
    for (int i = str.length() - 1, q = 1; i >= stPos; i--)
    {
        num += (str[i] - '0') * q;
        if ((q *= 10) >= BIGMOD)
        {
            push_back(num);
            num = 0;
            q = 1;
        }
    }
    if (num)
        push_back(num);
    n();
}
int len() const
{
    return vl; //return SZ(v);
}
bool empty() const { return len() == 0; }
void push_back(int x)
{
    v[vl++] = x; //v.pb(x);
}
void pop_back()
{
    vl--; //v.pop_back();
}
int back() const
{
    return v[vl - 1]; //return v.back();
}
void n()
{
    while (!empty() && !back())
        pop_back();
}
void resize(int nl)
{
    vl = nl; //v.resize(nl);
    fill(v, v + vl, 0); //fill(ALL(v), 0);
}
void print() const
{
    if (empty())
    {
        putchar('0');
        return;
    }
    if (s == -1)
        putchar('-');
    printf("%d", back());
    for (int i = len() - 2; i >= 0; i--)
        printf("%.4d", v[i]);
}
friend std::ostream &operator<<(std::ostream &out, const
    Bigint &a)
{
    if (a.empty())
    {
        out << "0";
        return out;
    }
    if (a.s == -1)
        out << "-";
    out << a.back();
    for (int i = a.len() - 2; i >= 0; i--)
    {
        char str[10];
        snprintf(str, 5, "%.4d", a.v[i]);
        out << str;
    }
    return out;
}
int cp3(const Bigint &b) const

```

```

{
    if (s != b.s)
        return s - b.s;
    if (s == -1)
        return -(*this).cp3(-b);
    if (len() != b.len())
        return len() - b.len(); //int
    for (int i = len() - 1; i >= 0; i--)
        if (v[i] != b.v[i])
            return v[i] - b.v[i];
    return 0;
}
bool operator<(const Bigint &b) const
{
    return cp3(b) < 0;
}
bool operator<=(const Bigint &b) const
{
    return cp3(b) <= 0;
}
bool operator==(const Bigint &b) const
{
    return cp3(b) == 0;
}
bool operator!=(const Bigint &b) const
{
    return cp3(b) != 0;
}
bool operator>(const Bigint &b) const
{
    return cp3(b) > 0;
}
bool operator>=(const Bigint &b) const
{
    return cp3(b) >= 0;
}
Bigint operator-() const
{
    Bigint r = (*this);
    r.s = -r.s;
    return r;
}
Bigint operator+(const Bigint &b) const
{
    if (s == -1)
        return -(-( *this) + (-b));
    if (b.s == -1)
        return (*this) - (-b);
    Bigint r;
    int nl = max(len(), b.len());
    r.resize(nl + 1);
    for (int i = 0; i < nl; i++)
    {
        if (i < len())
            r.v[i] += v[i];
        if (i < b.len())
            r.v[i] += b.v[i];
        if (r.v[i] >= BIGMOD)
        {
            r.v[i + 1] += r.v[i] / BIGMOD;
            r.v[i] %= BIGMOD;
        }
    }
    r.n();
    return r;
}
Bigint operator-(const Bigint &b) const
{
    if (s == -1)
        return -(-( *this) - (-b));
    if (b.s == -1)
        return (*this) + (-b);
    if ((*this) < b)
        return -(b - (*this));
    Bigint r;
    r.resize(len());
    for (int i = 0; i < len(); i++)
    {
        r.v[i] += v[i];
        if (i < b.len())
            r.v[i] -= b.v[i];
        if (r.v[i] < 0)
        {
            r.v[i] += BIGMOD;
            r.v[i + 1]--;
        }
    }
    r.n();
    return r;
}
Bigint operator*(const Bigint &b)
{
    Bigint r;
    r.resize(len() + b.len() + 1);
    r.s = s * b.s;
    for (int i = 0; i < len(); i++)
    {

```

```

        for (int j = 0; j < b.len(); j++)
        {
            r.v[i + j] += v[i] * b.v[j];
            if (r.v[i + j] >= BIGMOD)
            {
                r.v[i + j + 1] += r.v[i + j] / BIGMOD;
                r.v[i + j] %= BIGMOD;
            }
        }
    }
    r.n();
    return r;
}
Bigint operator/(const Bigint &b)
{
    Bigint r;
    r.resize(max(1, len() - b.len() + 1));
    int oriS = s;
    Bigint b2 = b; // b2 = abs(b)
    s = b2.s = r.s = 1;
    for (int i = r.len() - 1; i >= 0; i--)
    {
        int d = 0, u = BIGMOD - 1;
        while (d < u)
        {
            int m = (d + u + 1) >> 1;
            r.v[i] = m;
            if ((r * b2) > (*this))
                u = m - 1;
            else
                d = m;
        }
        r.v[i] = d;
    }
    s = oriS;
    r.s = s * b.s;
    r.n();
    return r;
}
Bigint operator%(const Bigint &b)
{
    return (*this) - (*this) / b * b;
}
};

```

9.2 DisjointSet

```

struct DisjointSet {
    int p[maxn], sz[maxn], n, cc;
    vector<pair<int*, int>> his;
    vector<int> sh;
    void init(int _n) {
        n = _n; cc = n;
        for (int i = 0; i < n; ++i) sz[i] = 1, p[i] = i;
        sh.clear(); his.clear();
    }
    void assign(int *k, int v) {
        his.emplace_back(k, *k);
        *k = v;
    }
    void save() {
        sh.push_back((int)his.size());
    }
    void undo() {
        int last = sh.back(); sh.pop_back();
        while (his.size() != last) {
            int *k, v;
            tie(k, v) = his.back(); his.pop_back();
            *k = v;
        }
    }
    int find(int x) {
        if (x == p[x]) return x;
        return find(p[x]);
    }
    void merge(int x, int y) {
        x = find(x); y = find(y);
        if (x == y) return;
        if (sz[x] > sz[y]) swap(x, y);
        assign(&sz[y], sz[x] + sz[y]);
        assign(&p[x], y);
        assign(&cc, cc - 1);
    }
}
};

```

9.3 Matirx

```

template <typename T>
struct Matrix
{
    using rt = std::vector<T>;
    using mt = std::vector<rt>;
    using matrix = Matrix<T>;
    int r, c; // [r][c]
    mt m;
    Matrix(int r, int c) : r(r), c(c), m(r, rt(c)) {}
}

```

```

Matrix(mt a) { m = a, r = a.size(), c = a[0].size(); }
rt &operator[](int i) { return m[i]; }
matrix operator+(const matrix &a)
{
    matrix rev(r, c);
    for (int i = 0; i < r; ++i)
        for (int j = 0; j < c; ++j)
            rev[i][j] = m[i][j] + a.m[i][j];
    return rev;
}
matrix operator-(const matrix &a)
{
    matrix rev(r, c);
    for (int i = 0; i < r; ++i)
        for (int j = 0; j < c; ++j)
            rev[i][j] = m[i][j] - a.m[i][j];
    return rev;
}
matrix operator*(const matrix &a)
{
    matrix rev(r, a.c);
    matrix tmp(a.c, a.r);
    for (int i = 0; i < a.r; ++i)
        for (int j = 0; j < a.c; ++j)
            tmp[j][i] = a.m[i][j];
    for (int i = 0; i < r; ++i)
        for (int j = 0; j < a.c; ++j)
            for (int k = 0; k < c; ++k)
                rev.m[i][j] += m[i][k] * tmp[j][k];
    return rev;
}
bool inverse() //逆矩陣判斷
{
    Matrix t(r, r + c);
    for (int y = 0; y < r; y++)
    {
        t.m[y][c + y] = 1;
        for (int x = 0; x < c; ++x)
            t.m[y][x] = m[y][x];
    }
    if (!t.gas())
        return false;
    for (int y = 0; y < r; y++)
        for (int x = 0; x < c; ++x)
            m[y][x] = t.m[y][c + x] / t.m[y][y];
    return true;
}
T gas() //行列式
{
    vector<T> lazy(r, 1);
    bool sign = false;
    for (int i = 0; i < r; ++i)
    {
        if (m[i][i] == 0)
        {
            int j = i + 1;
            while (j < r && !m[j][i])
                j++;
            if (j == r)
                continue;
            m[i].swap(m[j]);
            sign = !sign;
        }
        for (int j = 0; j < r; ++j)
        {
            if (i == j)
                continue;
            lazy[j] = lazy[j] * m[i][i];
            T mx = m[j][i];
            for (int k = 0; k < c; ++k)
                m[j][k] = m[j][k] * m[i][i] - m[i][k] * mx;
        }
    }
    T det = sign ? -1 : 1;
    for (int i = 0; i < r; ++i)
    {
        det = det * m[i][i];
        det = det / lazy[i];
        for (auto &j : m[i])
            j /= lazy[i];
    }
    return det;
}
};

```

9.4 分數

```

typedef long long ll;
struct fraction
{
    ll n, d;
    fraction(const ll &n = 0, const ll &d = 1) : n(n), d(d)
    {
        ll t = __gcd(n, d);
        n /= t, d /= t;
        if (d < 0)

```

```
    n = -n, d = -d;
}
fraction operator-() const
{
    return fraction(-n, d);
}
fraction operator+(const fraction &b) const
{
    return fraction(n * b.d + b.n * d, d * b.d);
}
fraction operator-(const fraction &b) const
{
    return fraction(n * b.d - b.n * d, d * b.d);
}
fraction operator*(const fraction &b) const
{
    return fraction(n * b.n, d * b.d);
}
fraction operator/(const fraction &b) const
{
    return fraction(n * b.d, d * b.n);
}
void print()
{
    cout << n;
    if (d != 1)
        cout << "/" << d;
}
};
```