

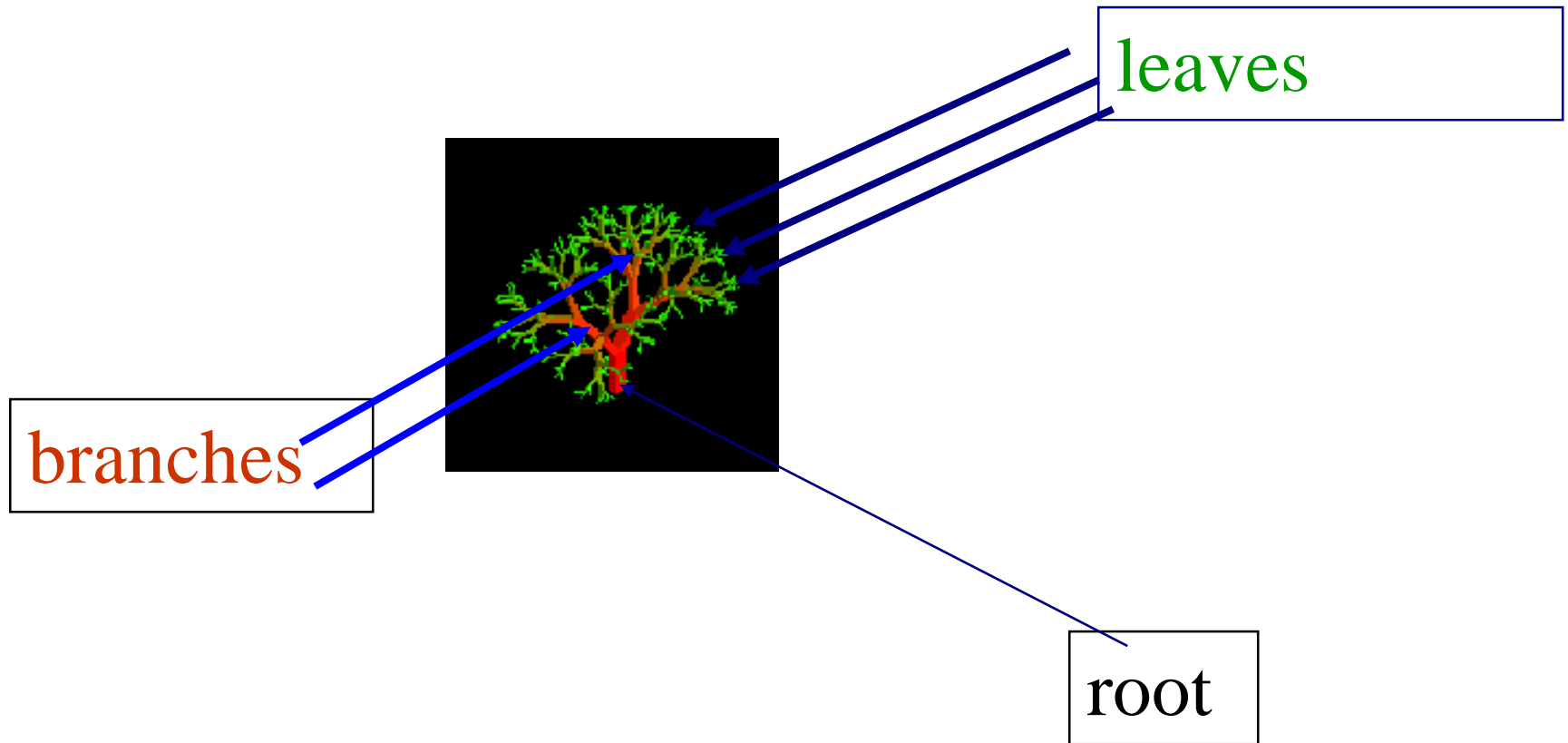
CHAPTER 5

Trees

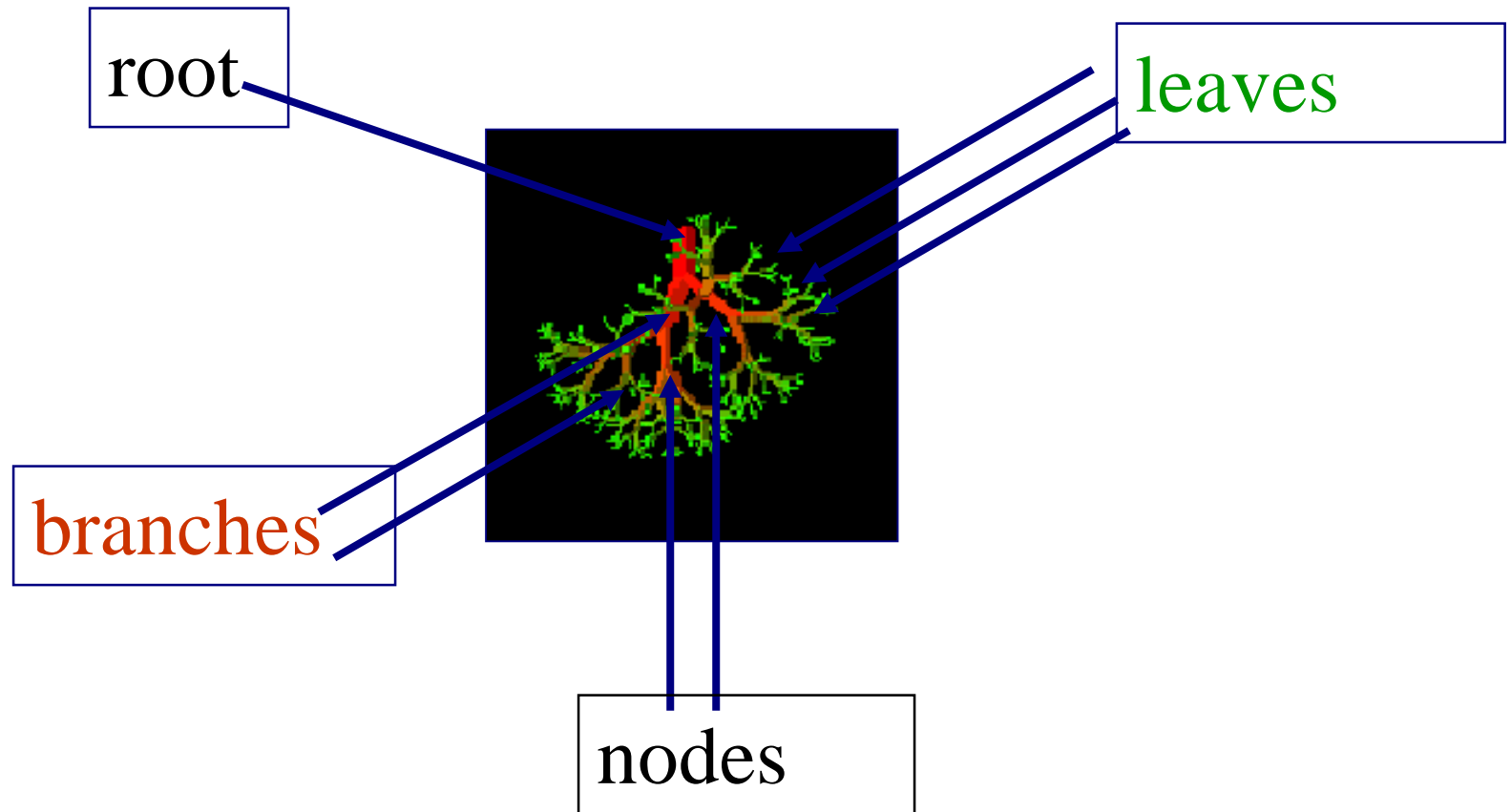
All the programs in this file are selected from

Ellis Horowitz, Sartaj Sahni, and Susan Anderson-Freed
“Fundamentals of Data Structures in C /2nd Edition”,
Silicon Press, 2008.

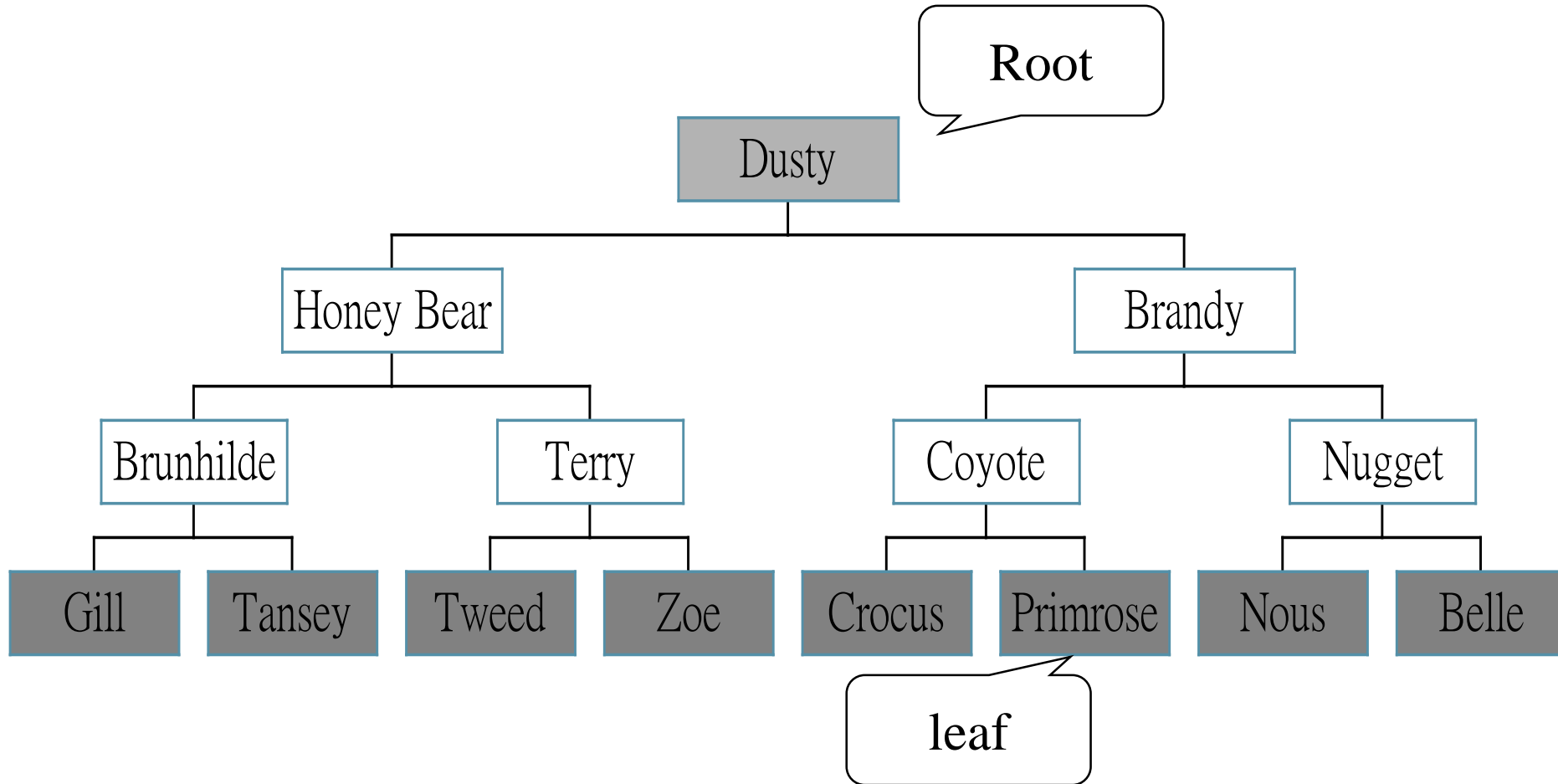
Nature Lover's View Of A Tree



Computer Scientist's View



Trees



Definition of Tree

- A tree is a finite set of one or more nodes such that:
- There is a specially designated node called the root .
- The remaining nodes are partitioned into $n \geq 0$ **disjoint** sets T_1, \dots, T_n , where each of these sets is a tree.
- We call T_1, \dots, T_n the **subtrees** of the root.

Level and Depth

node (13)

degree of a node

leaf (terminal)

nonterminal

parent

children

sibling

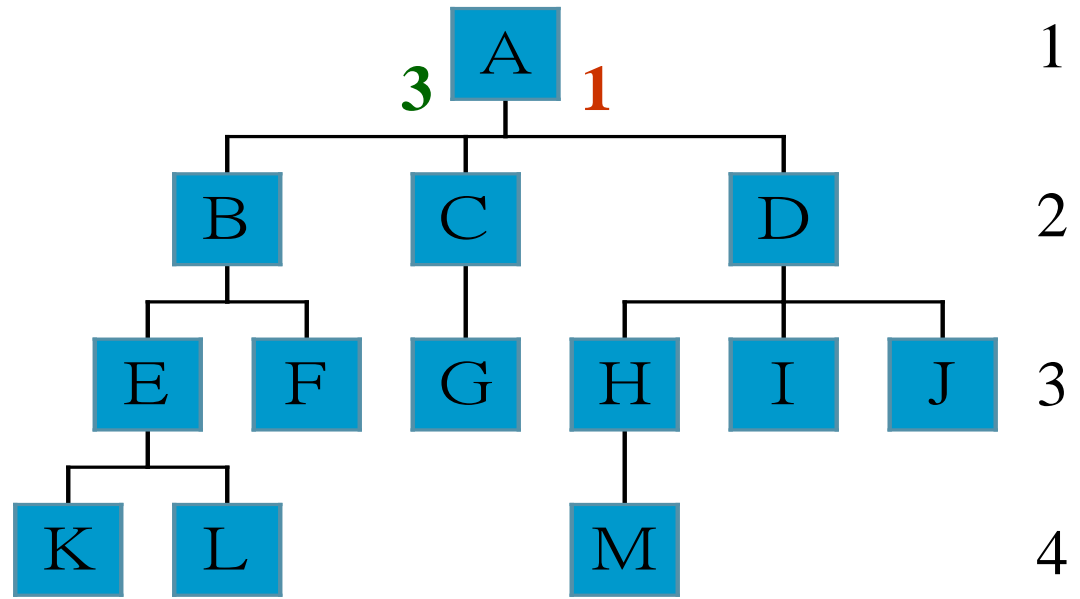
degree of a tree (3)

Ancestor

descendant

level of a node

height of a tree (4)



Terminology(1/2)

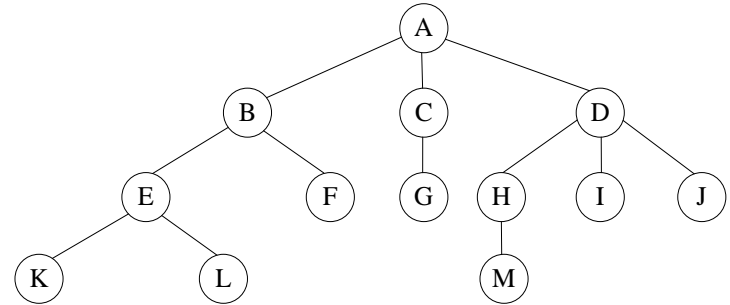
- The **degree** of a node is the number of subtrees of the node
 - The degree of A is 3; the degree of C is 1.
- The node with degree 0 is **leaf** or terminal node.
- A node that has subtrees is the **parent** of the roots of the subtrees.

Terminology(2/2)

- The roots of these subtrees are the of
the node.
- Children of the same parent are **siblings**.
- The **ancestors** of a node are all the nodes
along the path from the root to the node.

Representation of Trees

■ List Representation

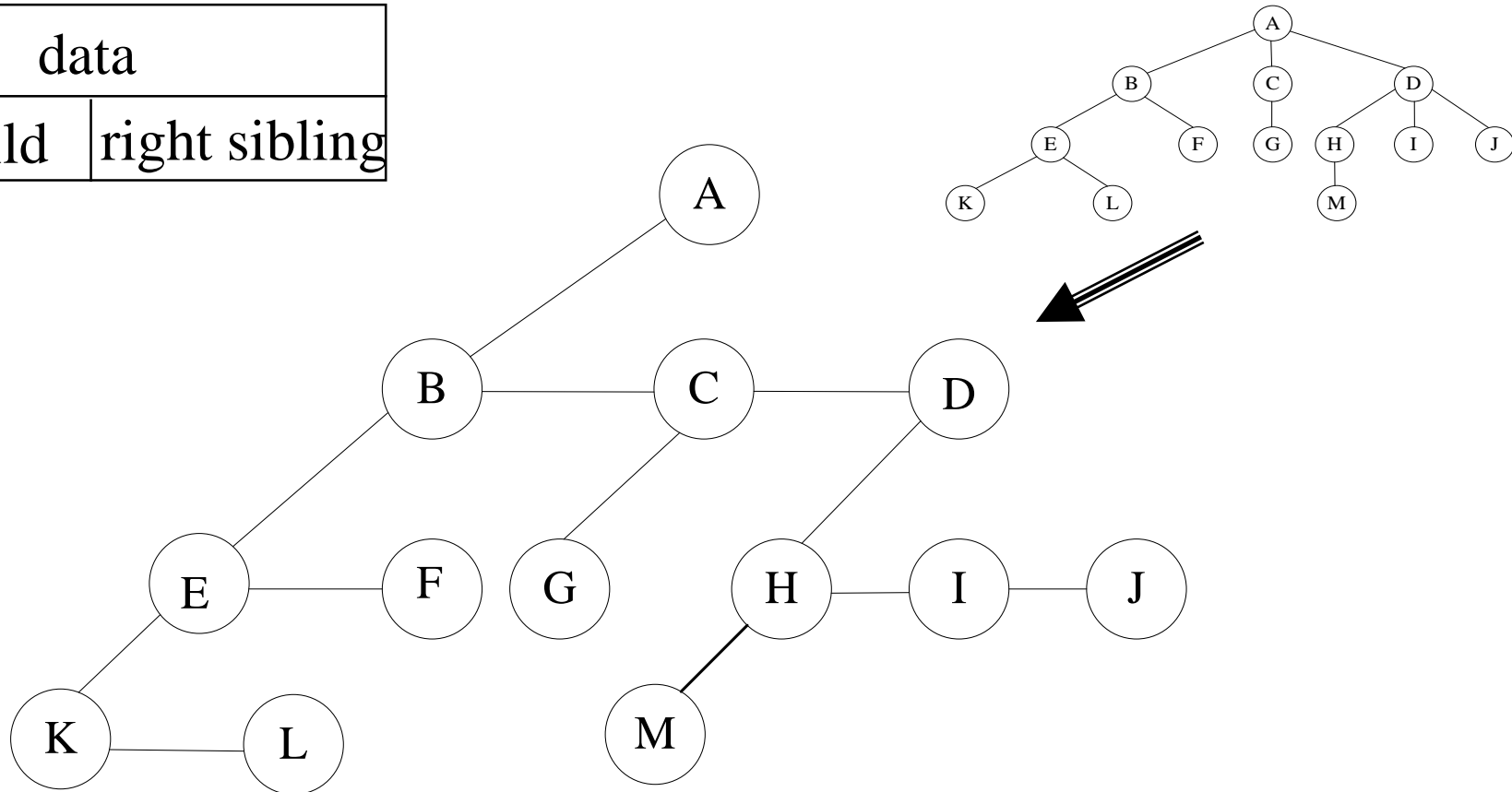


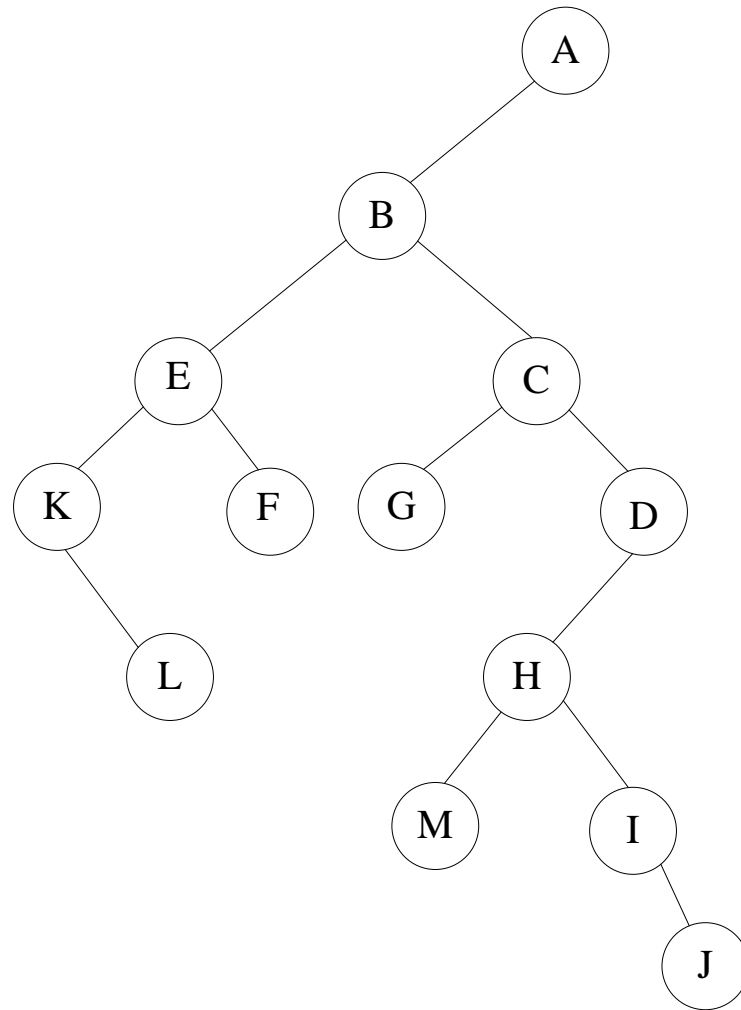
- $(A (B (E (K, L), F), C (G), D (H (M), I, J)))$
- The root comes first, followed by a list of sub-trees

data	link 1	link 2	...	link n
------	--------	--------	-----	--------

Left Child - Right Sibling

data	
left child	right sibling





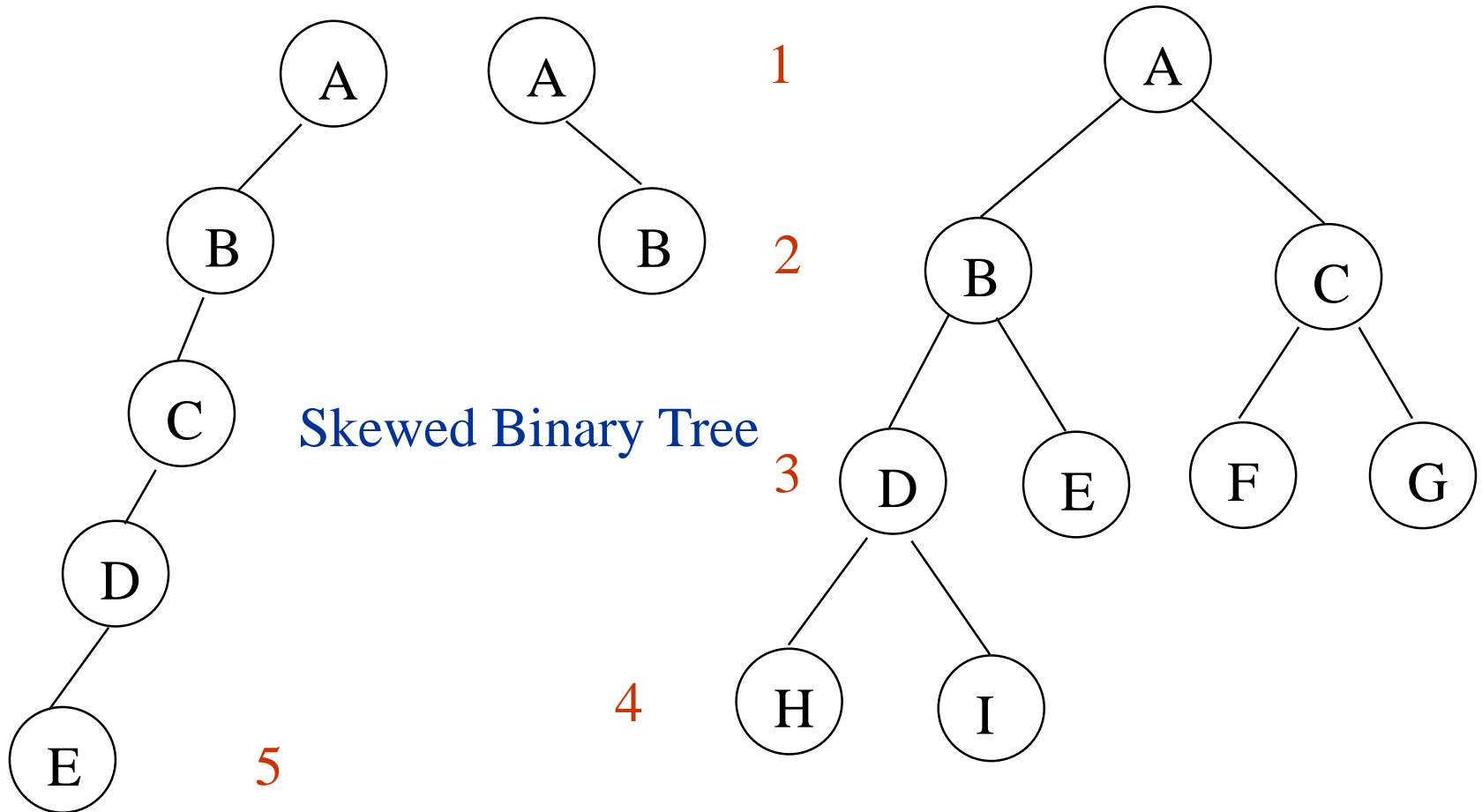
***Figure 5.7:** Left child-right child tree representation of a tree (p.197)

Binary Trees

- A binary tree is a finite set of nodes that is either empty or consists of a root and two disjoint binary trees called *left subtree* and *right subtree*.
- Any tree can be transformed into binary tree.
 - by *preorder* representation
- The left subtree and the right subtree are distinguished.

Samples of Trees

Binary Tree



Maximum Number of Nodes in BT

- The maximum number of nodes on level i of a binary tree is 2^{i-1} , $i \geq 1$.
- The maximum number of nodes in a binary tree of depth k is $2^k - 1$, $k \geq 1$.

Prove by induction.

$$\sum_{i=1}^k 2^{i-1} = 2^k - 1$$

Relations between Number of Leaf Nodes and Nodes of Degree 2

For any nonempty binary tree, T , if n_0 is the number of leaf nodes and n_2 the number of nodes of degree 2, then

proof:

Let n and B denote the total number of nodes & branches in T .

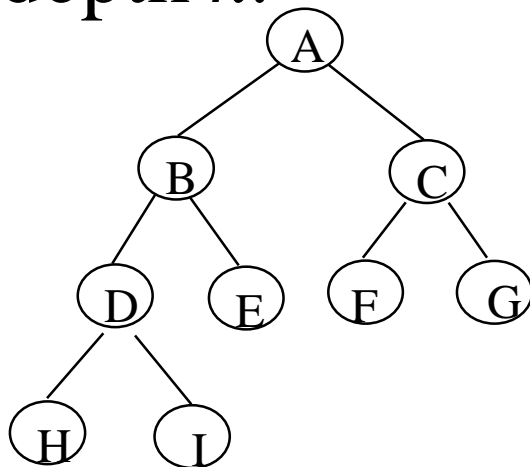
Let n_0 , n_1 , n_2 represent the nodes with no children, single child, and two children respectively.

$$n = n_0 + n_1 + n_2, \quad B + 1 = n, \quad B = n_1 + 2n_2 \implies n_1 + 2n_2 + 1 = n, \\ n_1 + 2n_2 + 1 = n_0 + n_1 + n_2 \implies$$

BT VS

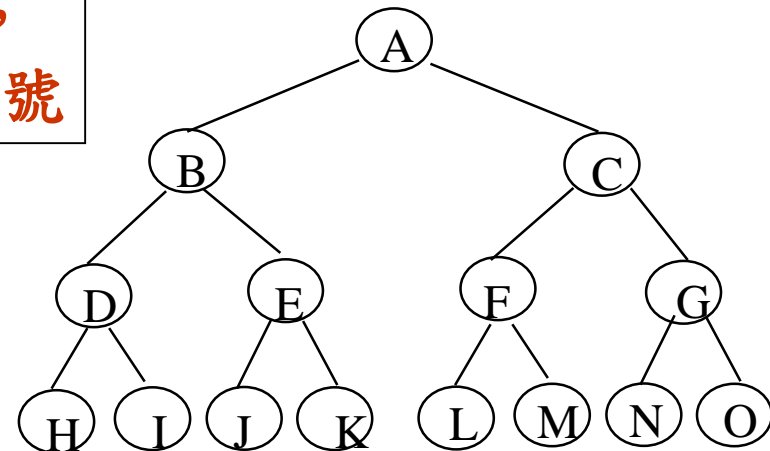
BT

- A full binary tree of depth k is a binary tree of depth k having $2^k - 1$ nodes, $k \geq 0$.
- A binary tree with n nodes and depth k is complete *iff* its nodes correspond to the nodes numbered from 1 to n in the full binary tree of depth k .



Complete binary tree

由上至下，
由左至右編號

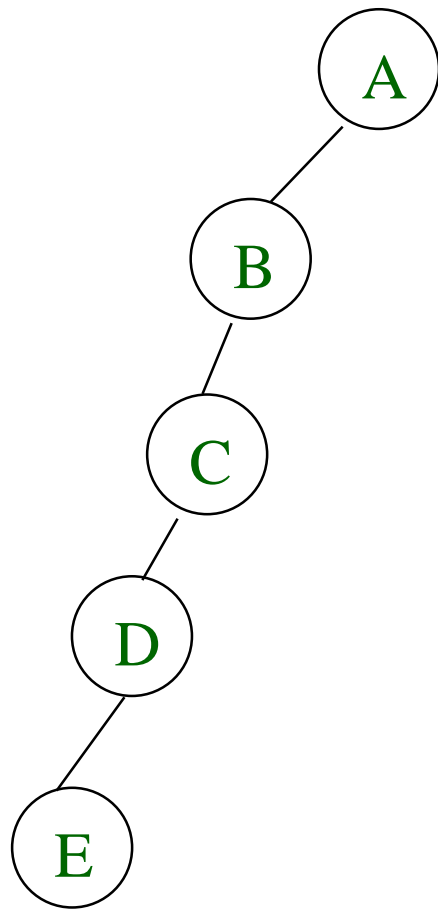


Full binary tree of depth 4

Binary Tree Representations

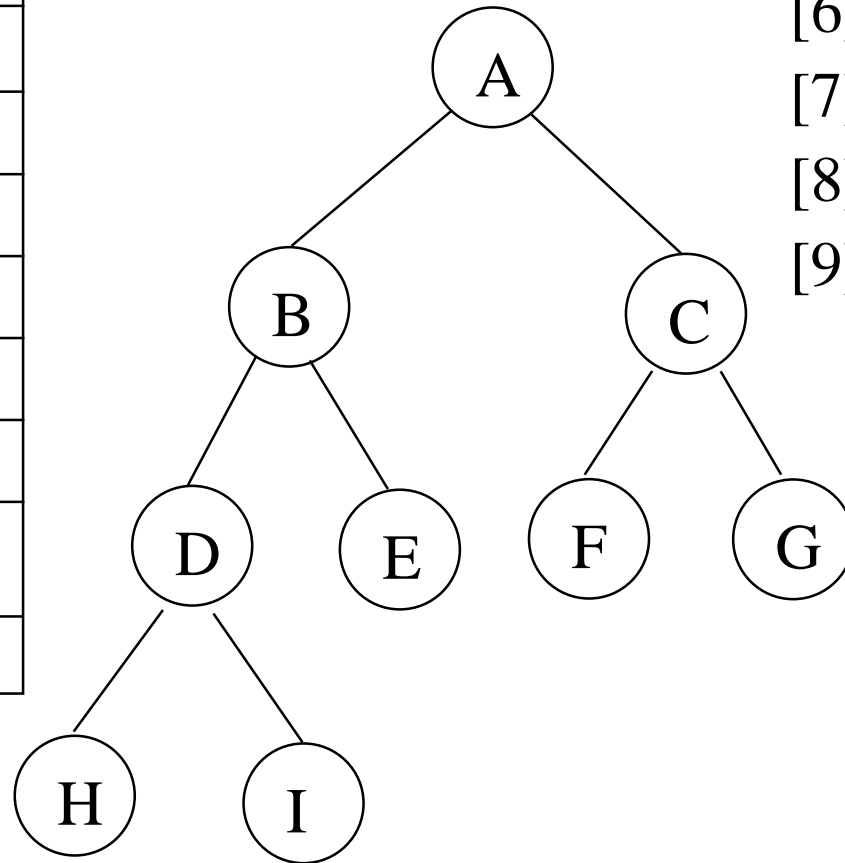
- If a complete binary tree with n nodes (depth = $\log n + 1$) is represented sequentially, then for any node with index i , $1 \leq i \leq n$, we have:
 - $parent(i)$ is at $\lfloor i/2 \rfloor$ if $i \neq 1$. If $i=1$, i is at the root and has no parent.
 - $left_child(i)$ is at $2i$ if $2i \leq n$. If $2i > n$, then i has no left child.
 - $right_child(i)$ is at $2i+1$ if $2i+1 \leq n$. If $2i+1 > n$, then i has no right child.

Sequential Representation



[1]	A
[2]	B
[3]	--
[4]	C
[5]	--
[6]	--
[7]	--
[8]	D
[9]	--
.	.
[16]	E

(1) waste space
(2) insertion/deletion problem

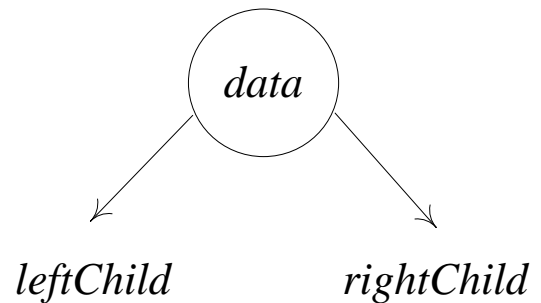
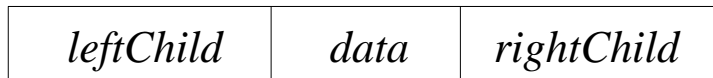


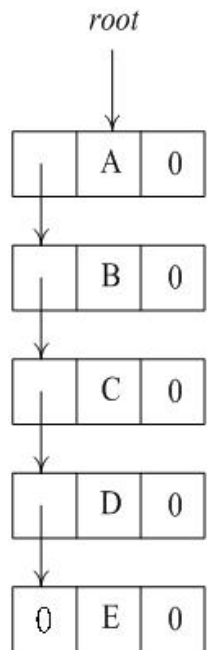
[1]
[2]
[3]
[4]
[5]
[6]
[7]
[8]
[9]

A
B
C
D
E
F
G
H
I

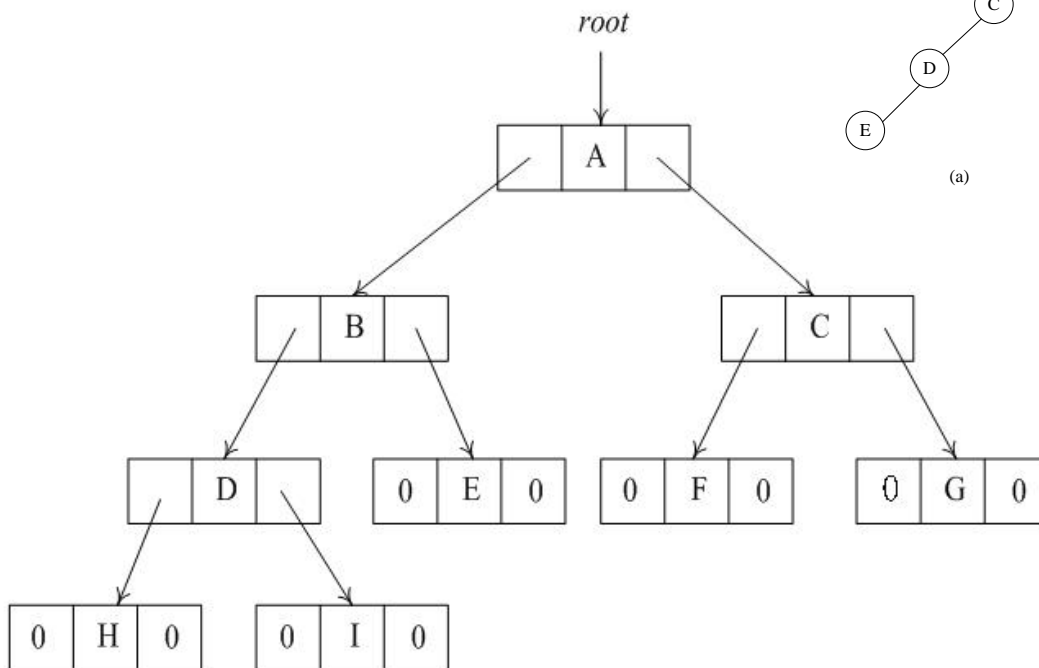
Linked Representation

```
typedef struct node *tree_pointer;  
typedef struct node {  
    int data;  
    tree_pointer left_child, right_child;  
};
```

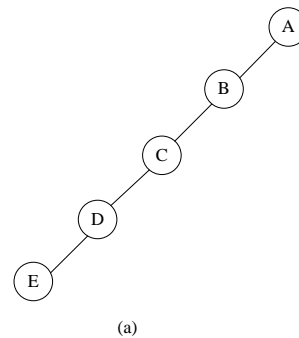




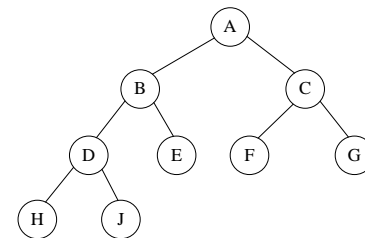
(a)



(b)



(a)

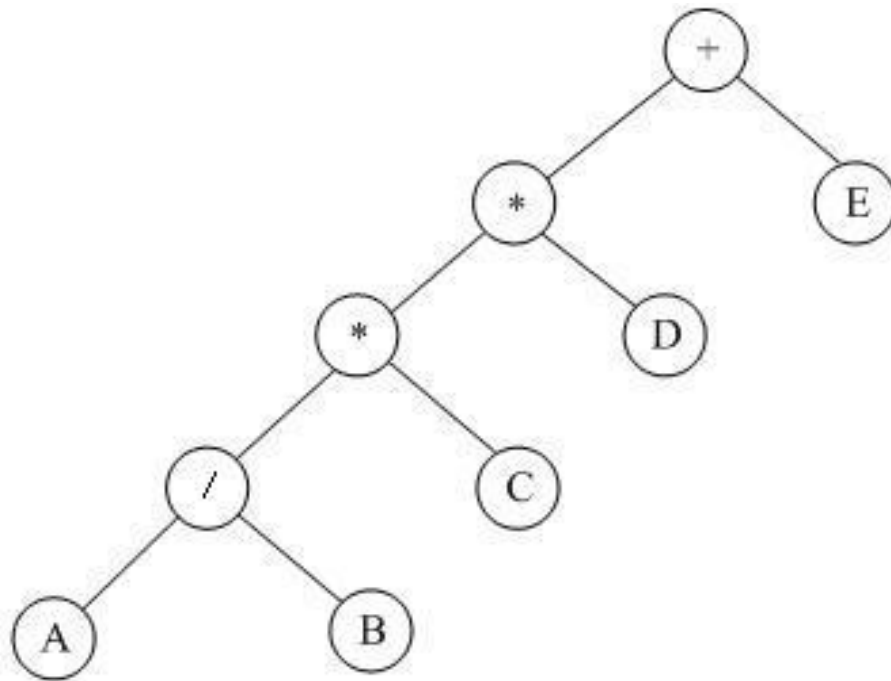


(b)

Binary Tree Traversals

- Let L, V, and R stand for moving left, visiting the node, and moving right.
- There are six possible combinations of traversal
 - LVR, LRV, VLR, VRL, RVL, RLV
- Adopt convention that we traverse left before right, only 3 traversals remain

Arithmetic Expression Using BT



inorder traversal

$A / B * C * D + E$

infix expression

preorder traversal

$+ * * / A B C D E$

prefix expression

postorder traversal

$A B / C * D * E +$

postfix expression

level order traversal

$+ * E * D / C A B$

Inorder Traversal (recursive version)

```
void inorder(tree_pointer ptr)
```

```
/* inorder tree traversal */
```

```
{
```

```
    if (ptr) {
```

$A / B * C * D + E$

```
        inorder(ptr->left_child);
```

```
        printf("%d", ptr->data);
```

```
        indorder(ptr->right_child);
```

```
    }
```

```
}
```

Preorder Traversal (recursive version)

```
void preorder(tree_pointer ptr)
/* preorder tree traversal */
{
    if (ptr) {
        printf("%d", ptr->data);
        preorder(ptr->left_child);
        preorder(ptr->right_child);
    }
}
```

+ * * / A B C D E

Postorder Traversal (recursive version)

```
void postorder(tree_pointer ptr)
/* postorder tree traversal */
{
    if (ptr) {
        

A B / C * D * E +


        postorder(ptr->left_child);
        postdorder(ptr->right_child);
        printf("%d", ptr->data);
    }
}
```

Iterative Inorder Traversal

(using stack)

```
void iter_inorder(tree_pointer node)
{
    int top= -1; /* initialize stack */
    tree_pointer stack[MAX_STACK_SIZE];
    for (;;) {
        for (; node; node=node->left_child)
            add(&top, node); /* add to stack */
        node= delete(&top);
                        /* delete from stack */
        if (!node) break; /* empty stack */
        printf("%D", node->data);
        node = node->right_child;
    }
}
```

$O(n)$

Trace Operations of Inorder Traversal

Call of inorder	Value in root	Action	Call of inorder	Value in root	Action
1	+		11	C	
2	*		12	NULL	
3	*		11	C	printf
4	/		13	NULL	
5	A		2	*	printf
6	NULL		14	D	
5	A	printf	15	NULL	
7	NULL		14	D	printf
4	/	printf	16	NULL	
8	B		1	+	printf
9	NULL		17	E	
8	B	printf	18	NULL	
10	NULL		17	E	printf
3	*	printf	19	NULL	

Threaded Binary Trees

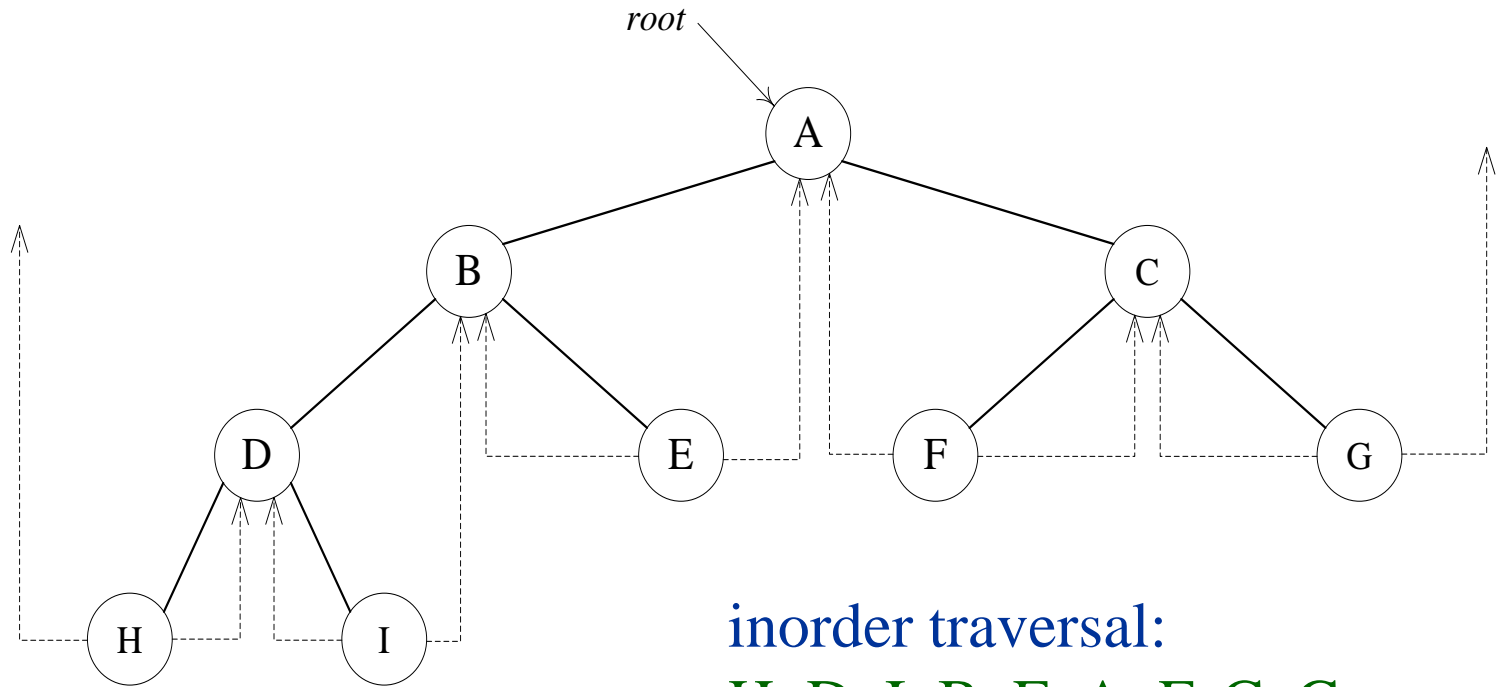
- Two many null pointers in current representation of binary trees
 - n: number of nodes
 - number of non-null links: $n-1$
 - total links: $2n$
 - null links: $2n-(n-1)=n+1$
- Replace these null pointers with some useful “threads”.

Threaded Binary Trees *(Continued)*

If `ptr->left_child` is null,
replace it with a pointer to the node that would be
visited *before* `ptr` in an *inorder traversal*

If `ptr->right_child` is null,
replace it with a pointer to the node that would be
visited *after* `ptr` in an *inorder traversal*

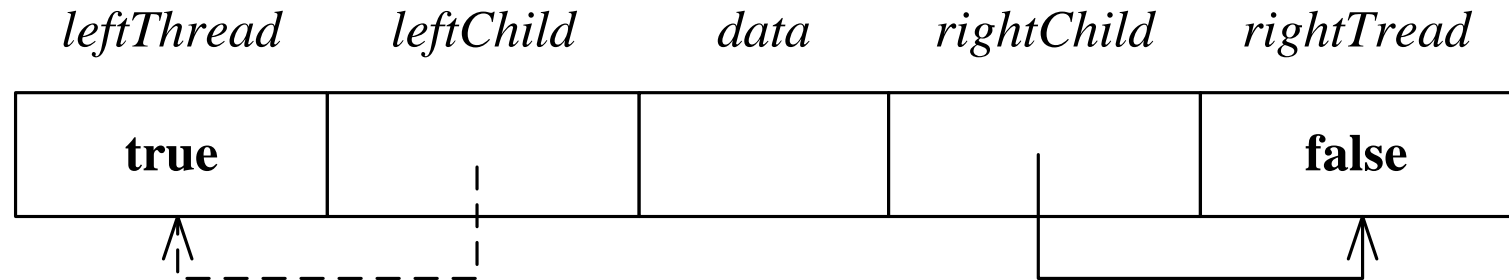
A Threaded Binary Tree



inorder traversal:

H, D, I, B, E, A, F, C, G

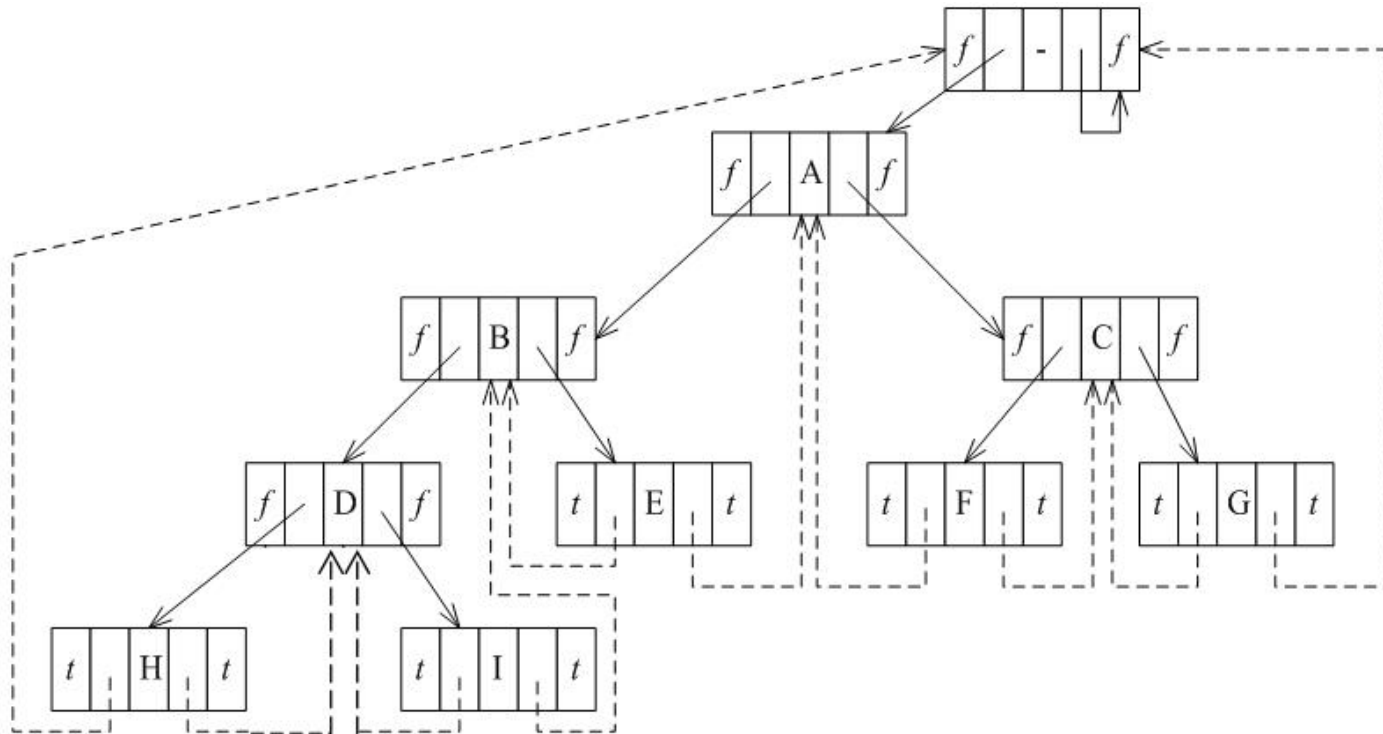
Data Structures for Threaded BT



```
typedef struct threaded_tree
    *threaded_pointer;
typedef struct threaded_tree {
    short int left_thread;
    threaded_pointer left_child;
    char data;
    threaded_pointer right_child;
    short int right_thread;  };

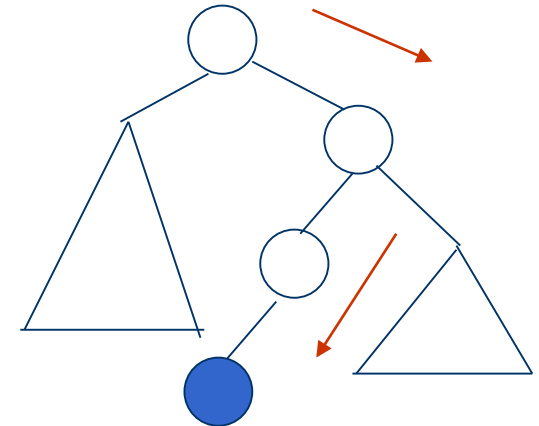
```

Memory Representation of A Threaded BT



Next Node in Threaded BT

```
threaded_pointer insucc(threaded_pointer
tree)
{
    threaded_pointer temp;
    temp = tree->right_child;
    if (!tree->right_thread)
        while (!temp->left_thread)
            temp = temp->left_child;
    return temp;
}
```



Inorder Traversal of Threaded BT

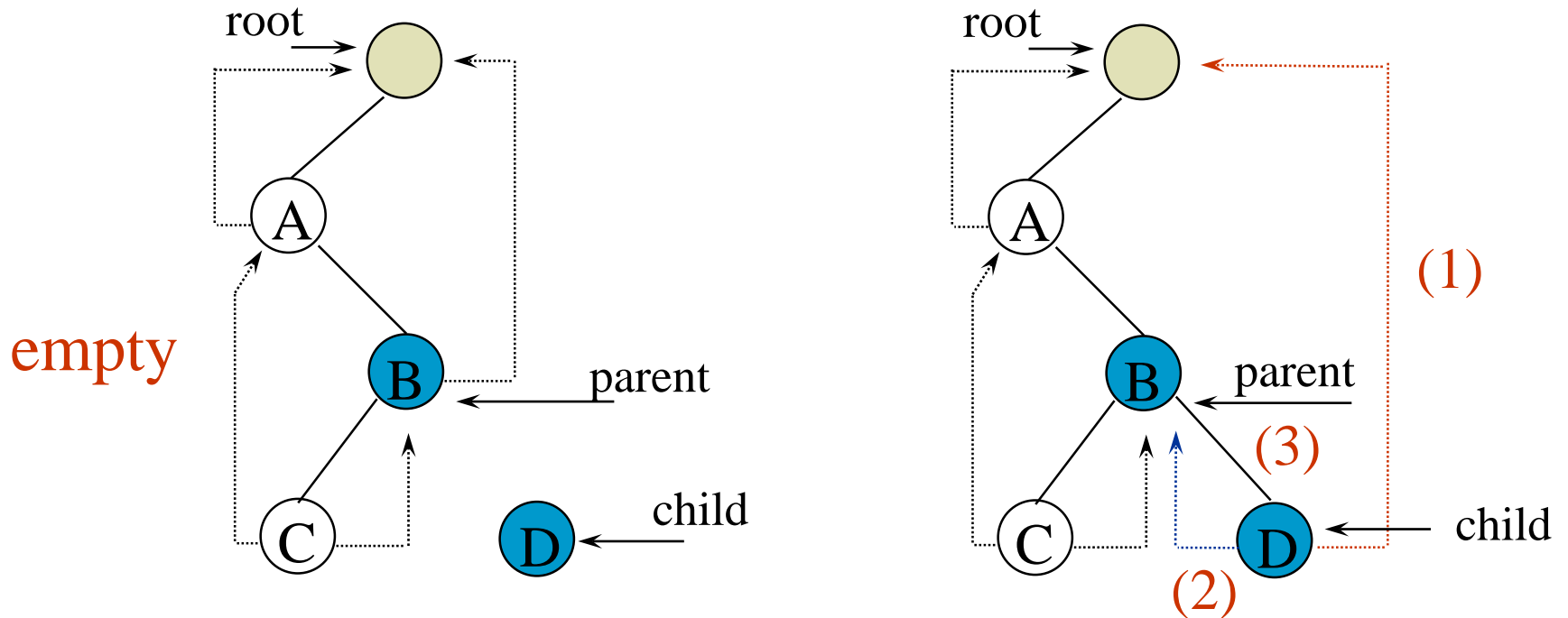
```
void tinorder(threaded_pointer tree)
{
    /* traverse the threaded binary tree
       inorder */
    threaded_pointer temp = tree;
    for (;;) {
        temp = insucc(temp);
        O(n) if (temp==tree) break;
        printf("%3c", temp->data);
    }
}
```

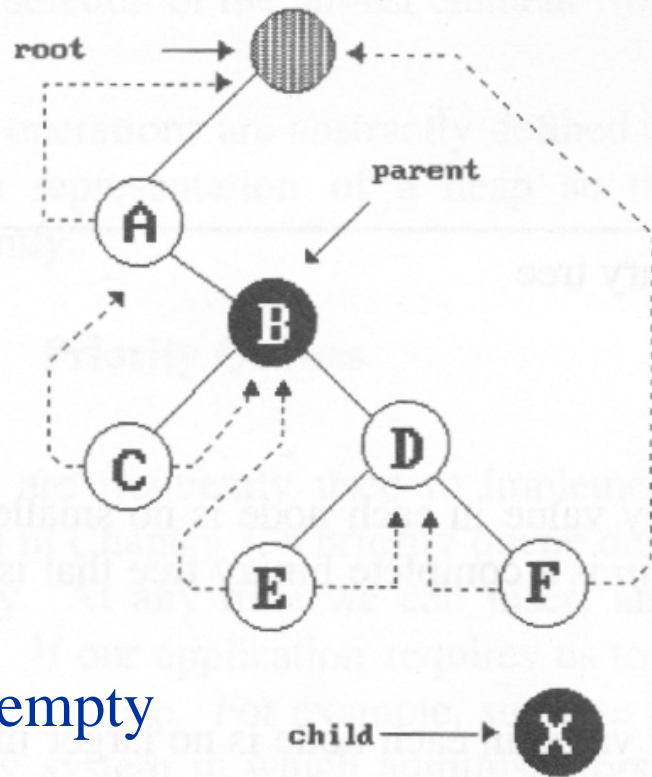
Inserting Nodes into Threaded BTs

- Insert `child` as the right child of node `parent`
 - change `parent->right_thread` to `FALSE`
 - set `child->left_thread` and `child->right_thread` to `TRUE`
 - set `child->left_child` to point to `parent`
 - set `child->right_child` to `parent->right_child`
 - change `parent->right_child` to point to `child`

Examples

Insert a node D as a right child of B.

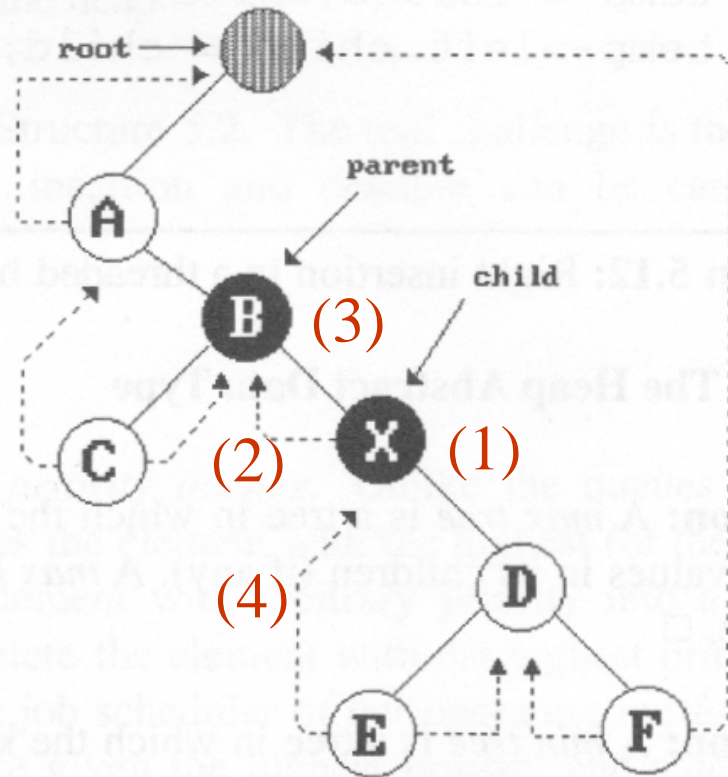




nonempty

before

(b)



after

Right Insertion in Threaded BTs

```
void insert_right(threaded_pointer parent,
                  threaded_pointer child)
{
    threaded_pointer temp;
    (1) child->right_child = parent->right_child;
    child->right_thread = parent->right_thread;
    (2) child->left_child = parent;  case (a)
    child->left_thread = TRUE;
    (3) parent->right_child = child;
    parent->right_thread = FALSE;
    if (!child->right_thread) { case (b)
    (4) temp = insucc(child);
        temp->left_child = child;
    }
}
```

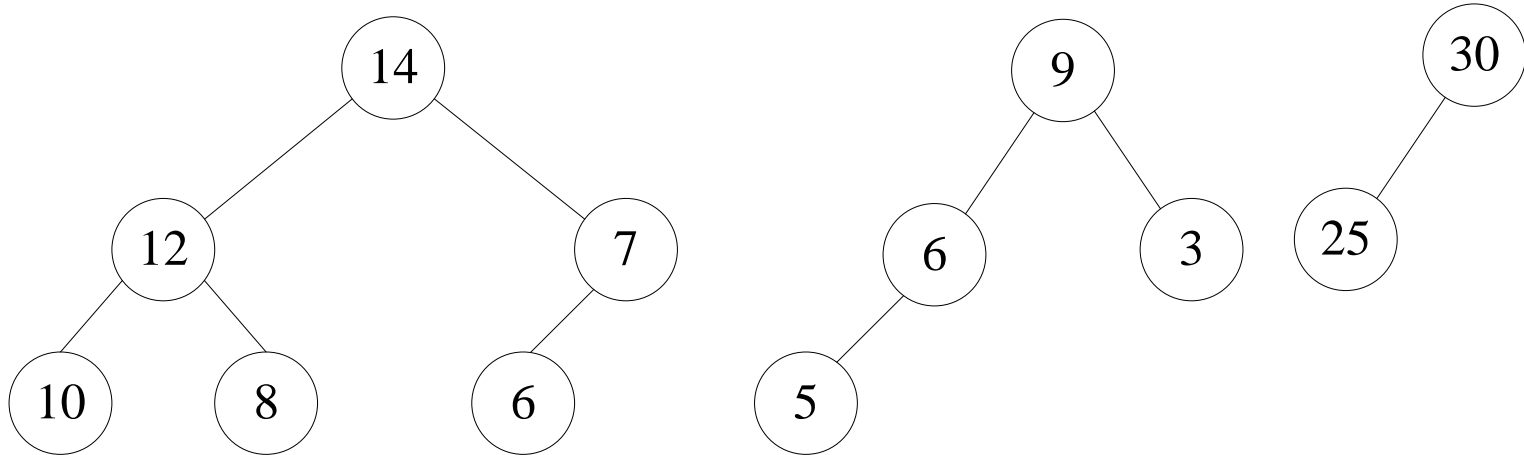
Heap(1/4)

- A **max heap** is a tree in which the key value in each node is **no smaller than** the key values in its children. A **max heap** is a **complete binary tree** that is also a max tree.
- A **min heap** is a tree in which the key value in each node is **no larger than** the key values in its children. A **min heap** is a **complete binary tree** that is also a min tree.

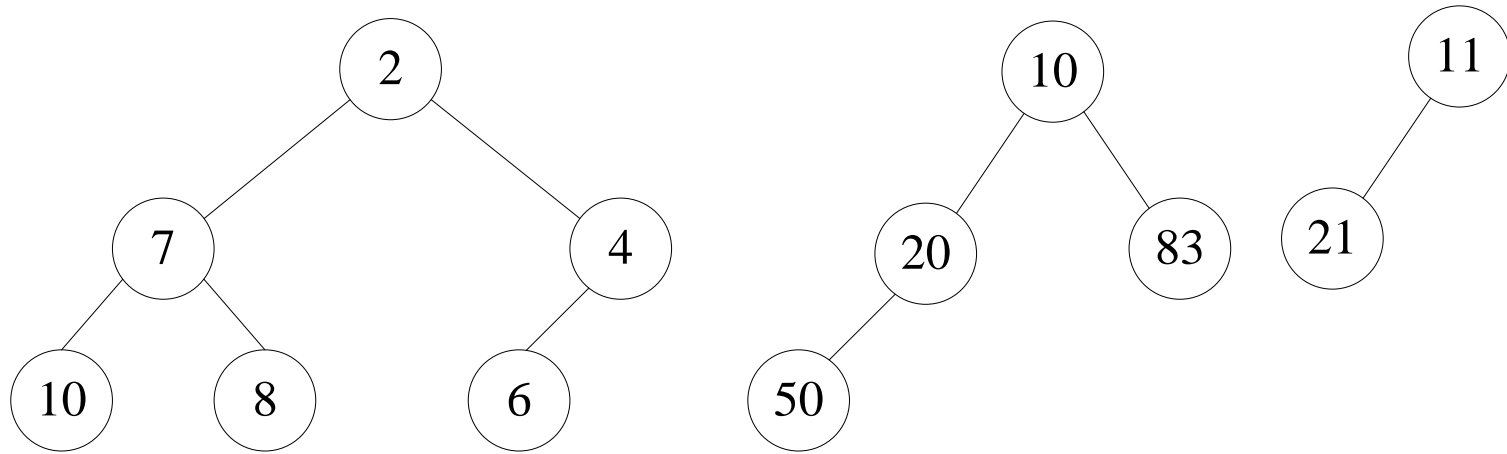
Heap(2/4)

- Property:
 - The root of max heap (min heap) contains the largest (smallest) element.
- Operations on heaps
 - creation of an empty heap
 - insertion of a new element into the heap
 - deletion of the largest (smallest) element from the max (min) heap

Heap(3/4)-max heap



Heap(4/4)-min heap



ADT for Max Heap

structure MaxHeap

objects: a complete binary tree of $n > 0$ elements organized so that the value in each node is at least as large as those in its children

functions:

for all *heap* belong to *MaxHeap*, *item* belong to *Element*, *n*,
max_size belong to integer

MaxHeap Create(max_size)::= create an empty heap that can
hold a maximum of max_size elements

Boolean HeapFull(heap, n)::= if ($n == \text{max_size}$) return TRUE
else return FALSE

MaxHeap Insert(heap, item, n)::= if ($\neg \text{HeapFull}(\text{heap}, n)$) insert
item into heap and return the resulting heap
else return error

Boolean HeapEmpty(heap, n)::= if ($n > 0$) return FALSE
else return TRUE

Element Delete(heap, n)::= if ($\neg \text{HeapEmpty}(\text{heap}, n)$) return one
instance of the **largest** element in the heap
and remove it from the heap

else return error

Application: priority queue

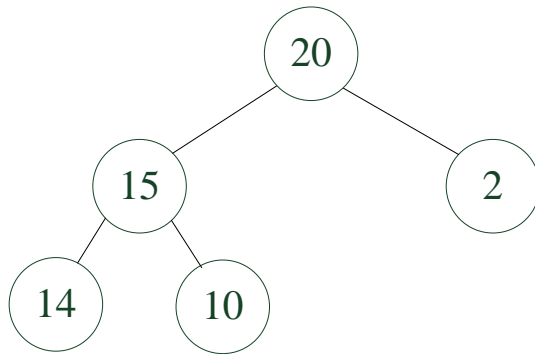
- machine service
 - amount of time (min heap)
 - amount of payment (max heap)
- factory
 - time tag

Data Structures

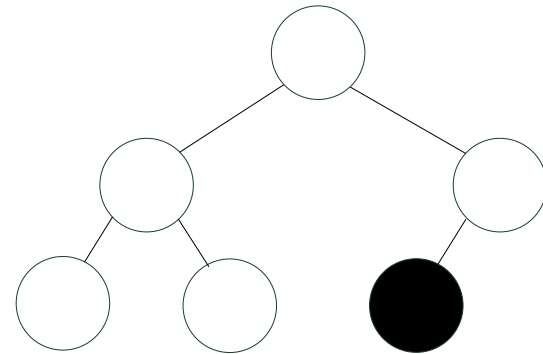
- unordered linked list
- unordered array
- sorted linked list
- sorted array
- heap

Representation	Insertion	Deletion
Unordered array	$\Theta(1)$	$\Theta(n)$
Unordered linked list	$\Theta(1)$	$\Theta(n)$
Sorted array	$O(n)$	$\Theta(1)$
Sorted linked list	$O(n)$	$\Theta(1)$
Max heap	$O(\log_2 n)$	$O(\log_2 n)$

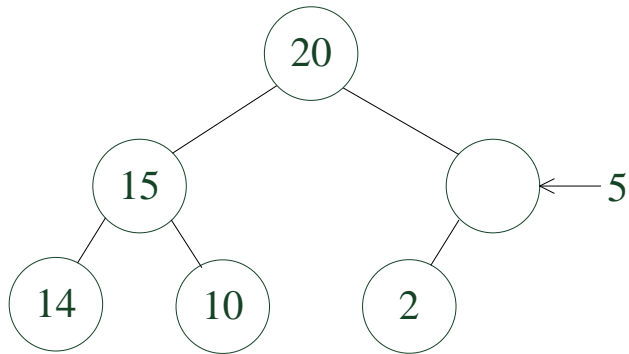
Example of Insertion to Max Heap



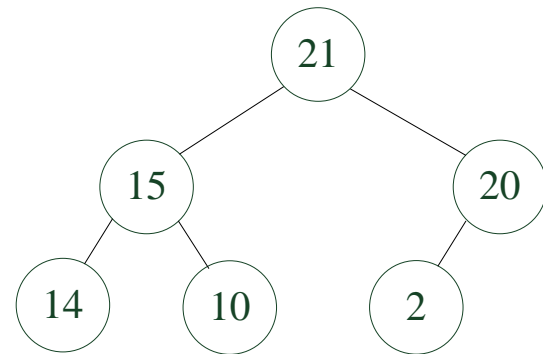
(a)



(b)



(c)



(d)

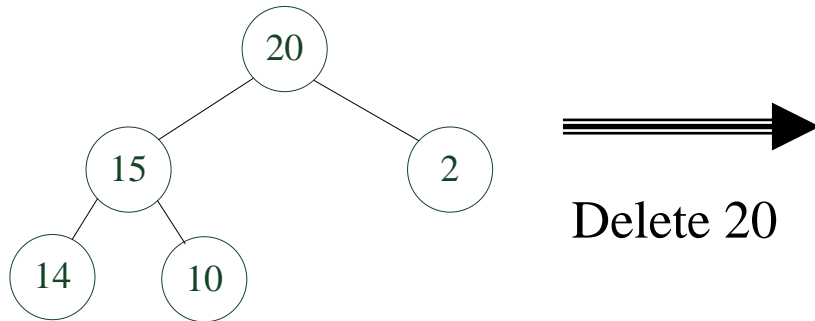
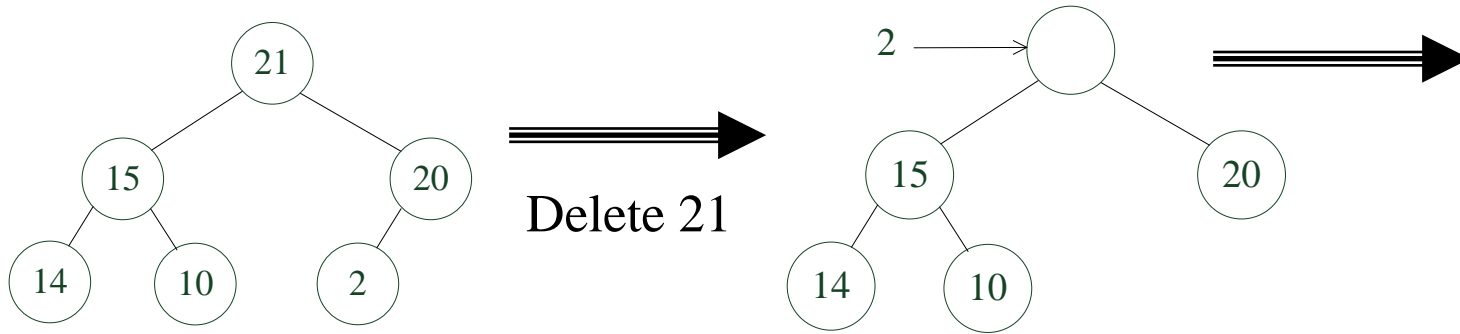
Insertion into a Max Heap

```
void insert_max_heap(element item, int *n)
{
    int i;
    if (HEAP_FULL(*n)) {
        fprintf(stderr, "the heap is full.\n");
        exit(1);
    }
    i = ++(*n);
    while ((i!=1)&&(item.key>heap[i/2].key)) {
        heap[i] = heap[i/2];
        i /= 2;
    }
    heap[i]= item;
}
```

$$2^k-1=n \implies k=\lceil \log_2(n+1) \rceil$$

$$O(\log_2 n)$$

Example of Deletion from Max Heap



Deletion from a Max Heap

```
element delete_max_heap(int *n)
{
    int parent, child;
    element item, temp;
    if (HEAP_EMPTY(*n)) {
        fprintf(stderr, "The heap is empty\n");
        exit(1);
    }
    /* save value of the element with the
       highest key */
    item = heap[1];
    /* use last element in heap to adjust heap */
    temp = heap[(*n)--];
    parent = 1;
    child = 2;
```

```

while (child <= *n) {
    /* find the larger child of the current
       parent */
    if ((child < *n)&&
        (heap[child].key < heap[child+1].key))
        child++;
    if (temp.key >= heap[child].key) break;
    /* move to the next lower level */
    heap[parent] = heap[child];
    child *= 2;
}
heap[parent] = temp;
return item;
}

```

Binary Search Tree(1/2)

■ Heap

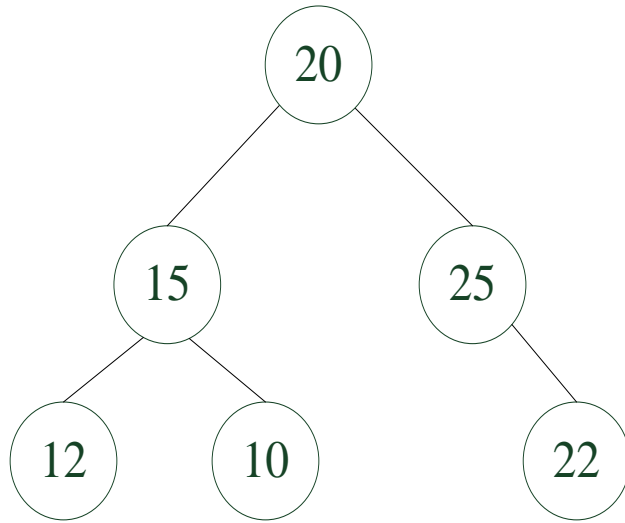
- a min (max) element is deleted.
- deletion of an arbitrary element
- search for an arbitrary element

Binary Search Tree(2/2)

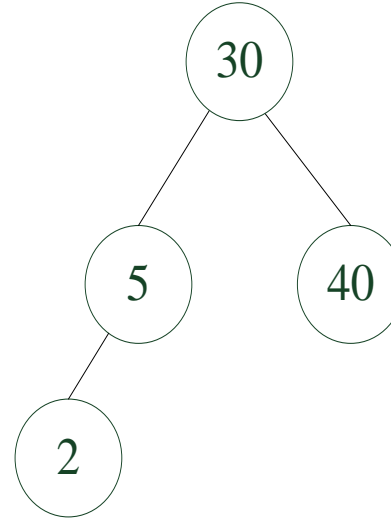
■ Binary search tree

- Each node has exactly one key and the keys in the tree are distinct
- The keys in a the **left subtree** () are **smaller** () than the key in the root
- The left and right subtrees are also binary search trees.

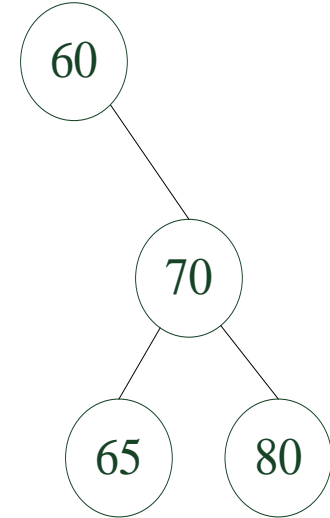
Examples of Binary Search Trees



(a)



(b)



(c)

Searching a Binary Search Tree

```
tree_pointer search(tree_pointer root,
                    int key)
{
    /* return a pointer to the node that
       contains key. If there is no such
       node, return NULL */

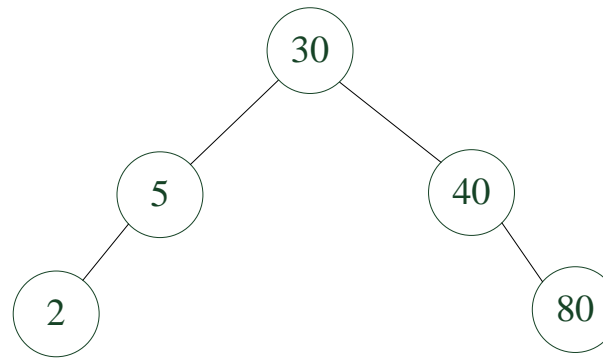
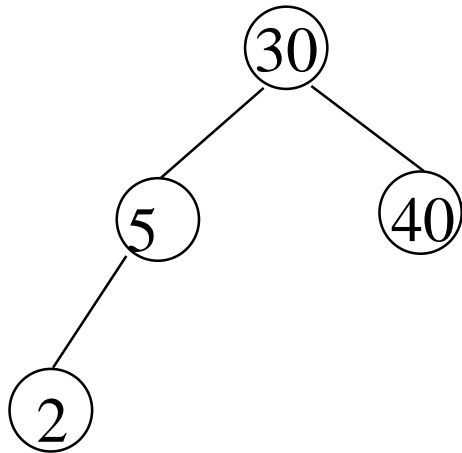
    if (!root) return NULL;
    if (key == root->data) return root;
    if (key < root->data)
        return search(root->left_child,
                       key);
    return search(root->right_child, key);
}
```

Another Searching Algorithm

```
tree_pointer search2(tree_pointer tree,
    int key)
{
    while (tree) {
        if (key == tree->data) return tree;
        if (key < tree->data)
            tree = tree->left_child;
        else tree = tree->right_child;
    }
    return NULL;
}
```

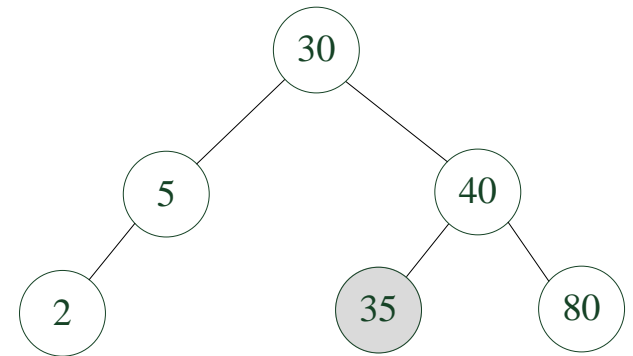
$O(h)$

Insert Node in Binary Search Tree



(a)

Insert 80



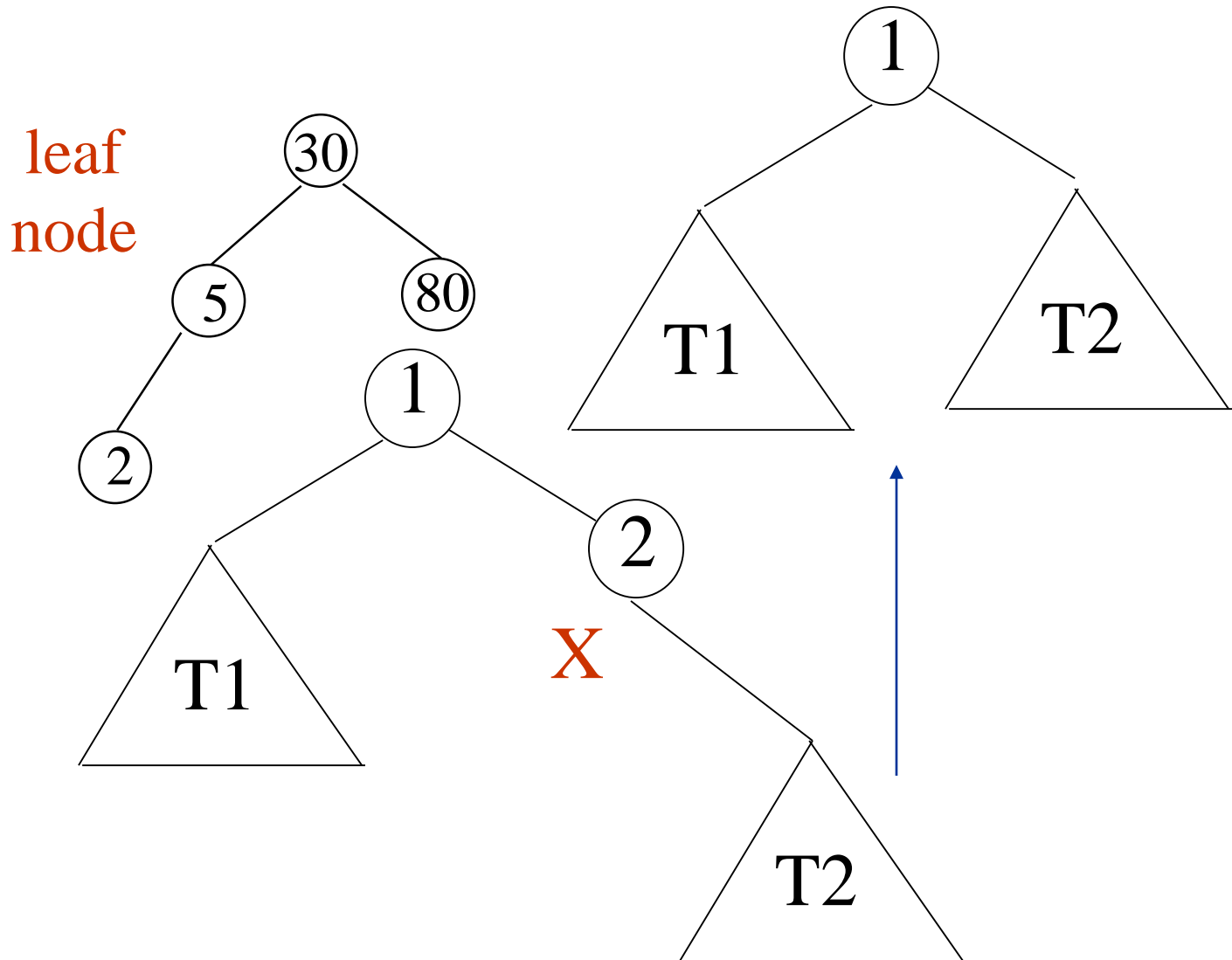
(b)

Insert 35

Insertion into A Binary Search Tree

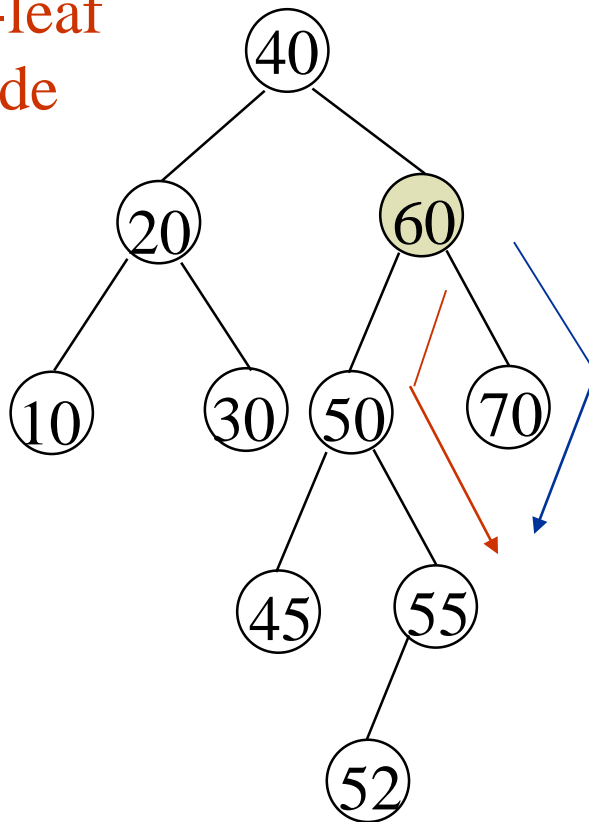
```
void insert_node(tree_pointer *node, int num)
{
    tree_pointer ptr,
        temp = modified_search(*node, num);
    if (temp || !(*node)) {
        ptr = (tree_pointer) malloc(sizeof(node));
        if (IS_FULL(ptr)) {
            fprintf(stderr, "The memory is full\n");
            exit(1);
        }
        ptr->data = num;
        ptr->left_child = ptr->right_child = NULL;
        if (*node)
            if (num < temp->data) temp->left_child = ptr;
            else temp->right_child = ptr;
        else *node = ptr;
    }
}
```

Deletion for A Binary Search Tree

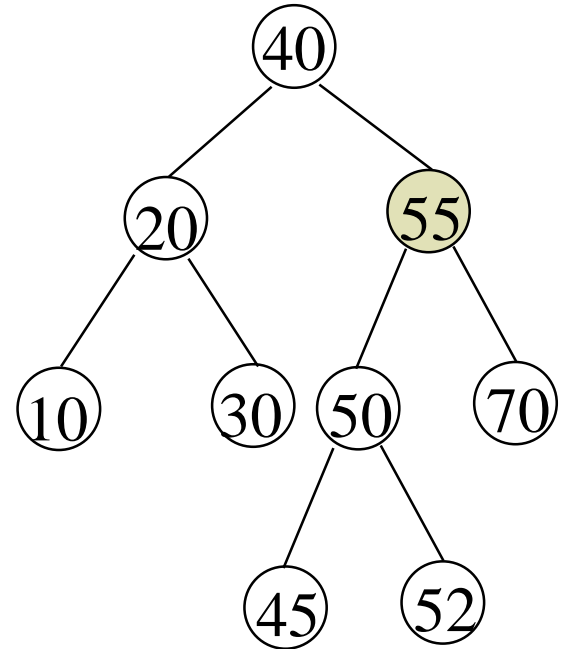


Deletion for A Binary Search Tree

non-leaf
node



Before deleting 60



After deleting 60

Selection Trees

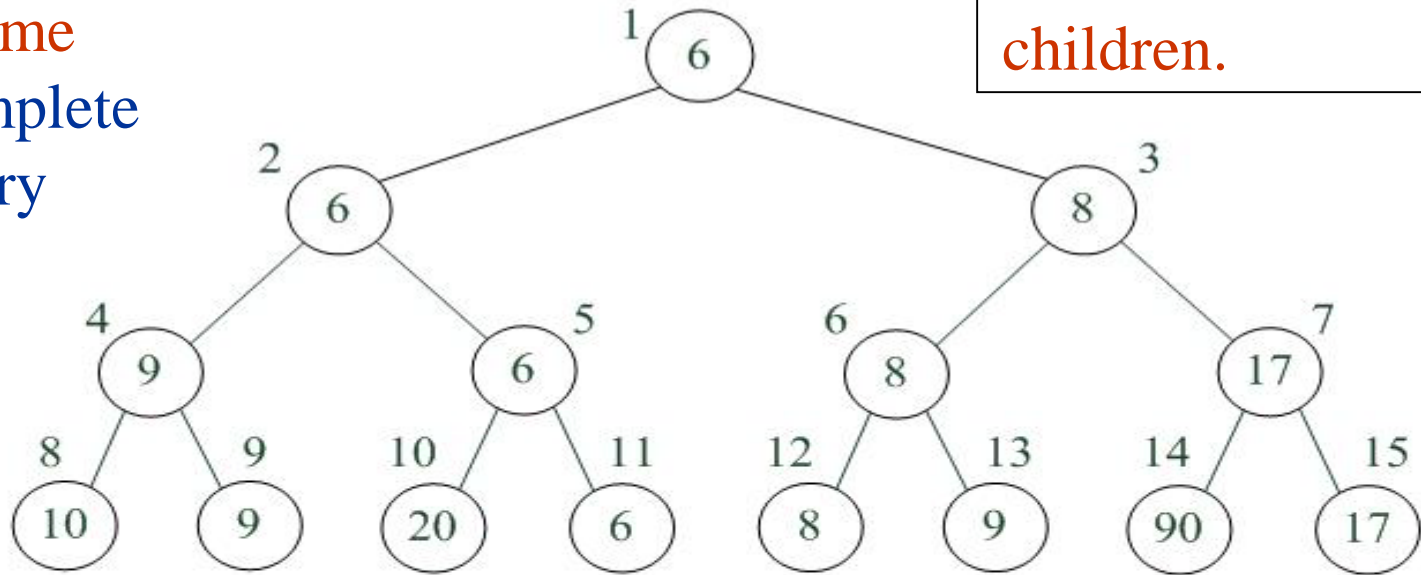
- (1) tree
- (2) tree

sequential
allocation
scheme

(complete
binary
tree)

winner tree

Each node represents
the smaller of its two
children.



ordered sequence

15
16

run 1

20
38

run 2

20
30

run 3

15
25
28

run 4

15
50

run 5

11
16

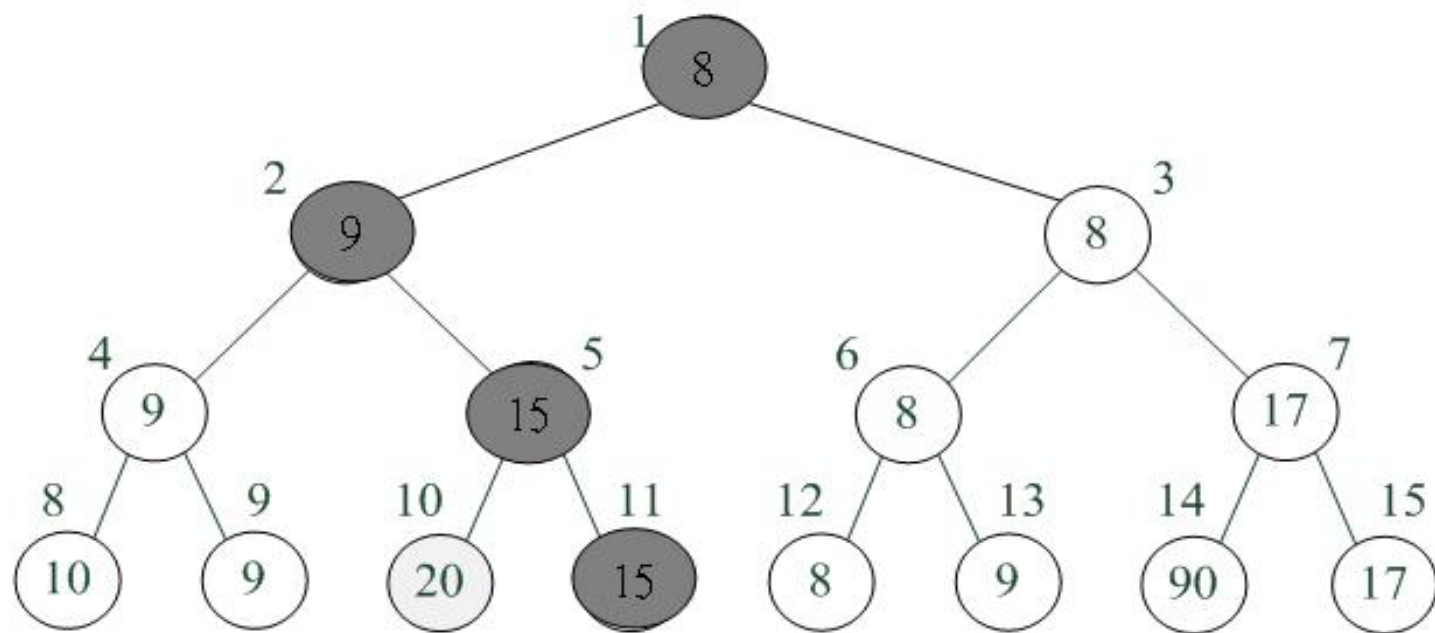
run 6

95
99

run 7

28
20

run 8



15
16

20
38

20
30

25
28

15
50

11
16

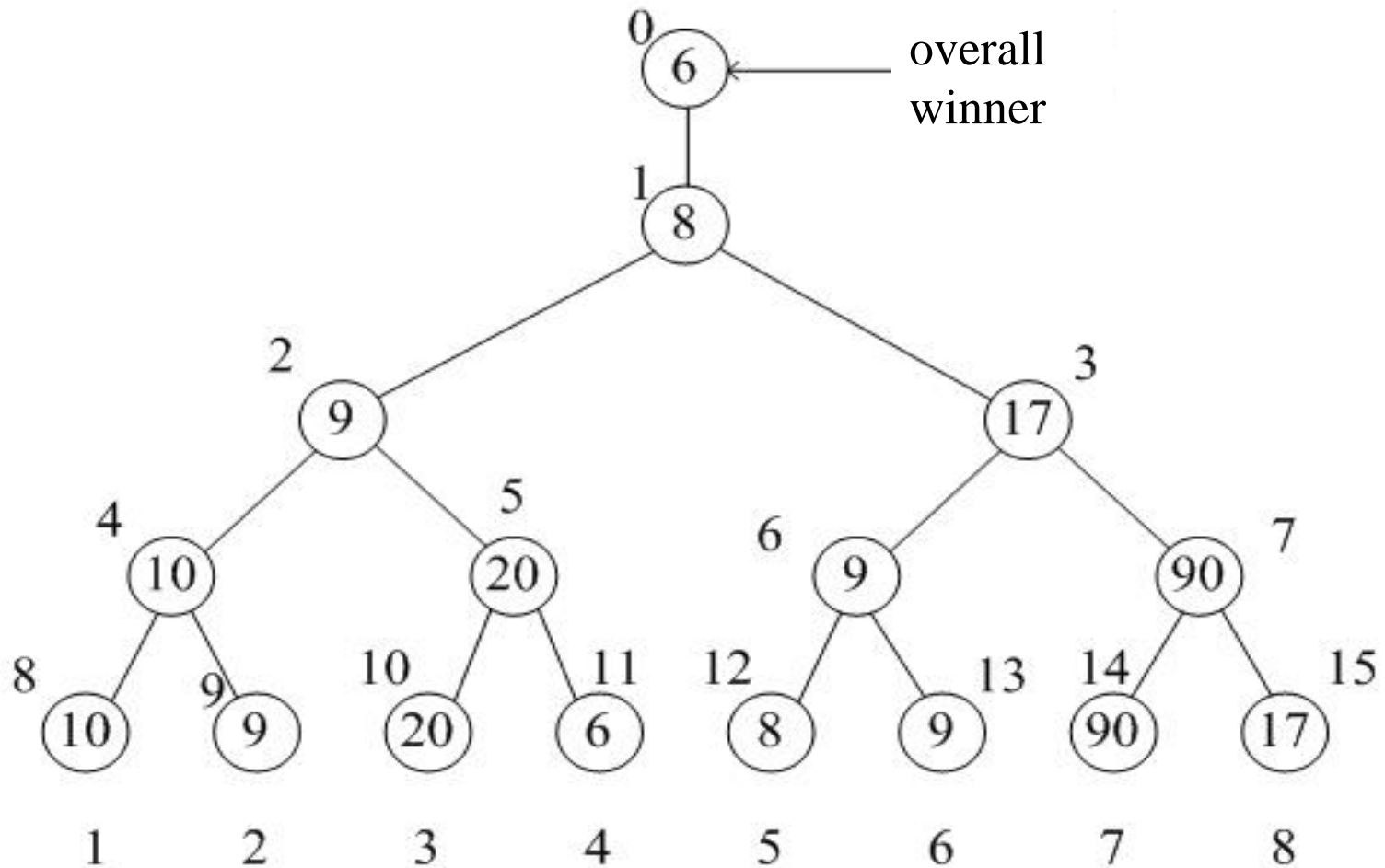
95
99

28
20

Analysis

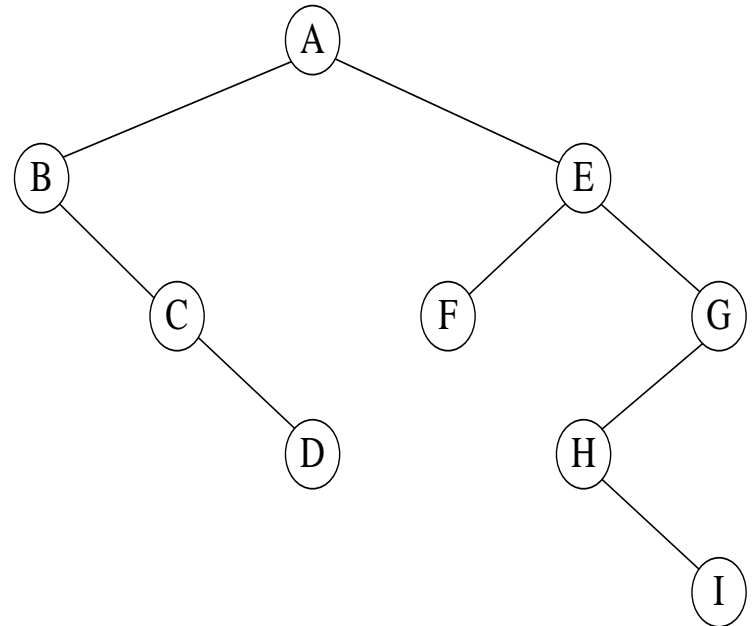
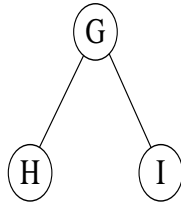
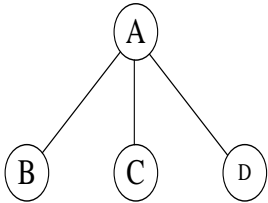
- K : # of runs
- n : # of records
- setup time: $O(K)$ $(K-1)$
- restructure time: $O(\log_2 K)$ $\lceil \log_2(K+1) \rceil$
- merge time: $O(n \log_2 K)$
- slight modification: **loser tree**
 - consider the parent node only (vs. sibling nodes)

Loser tree



Forest

- A forest is a set of $n \geq 0$ disjoint trees



Transform a forest into a binary tree

- T_1, T_2, \dots, T_n : a forest of trees
 $B(T_1, T_2, \dots, T_n)$: a binary tree corresponding to this forest
- algorithm
 - (1) empty, if $n = 0$
 - (2) has root equal to $\text{root}(T_1)$
 - has left subtree equal to $B(T_{11}, T_{12}, \dots, T_{1m})$
 - has right subtree equal to $B(T_2, T_3, \dots, T_n)$

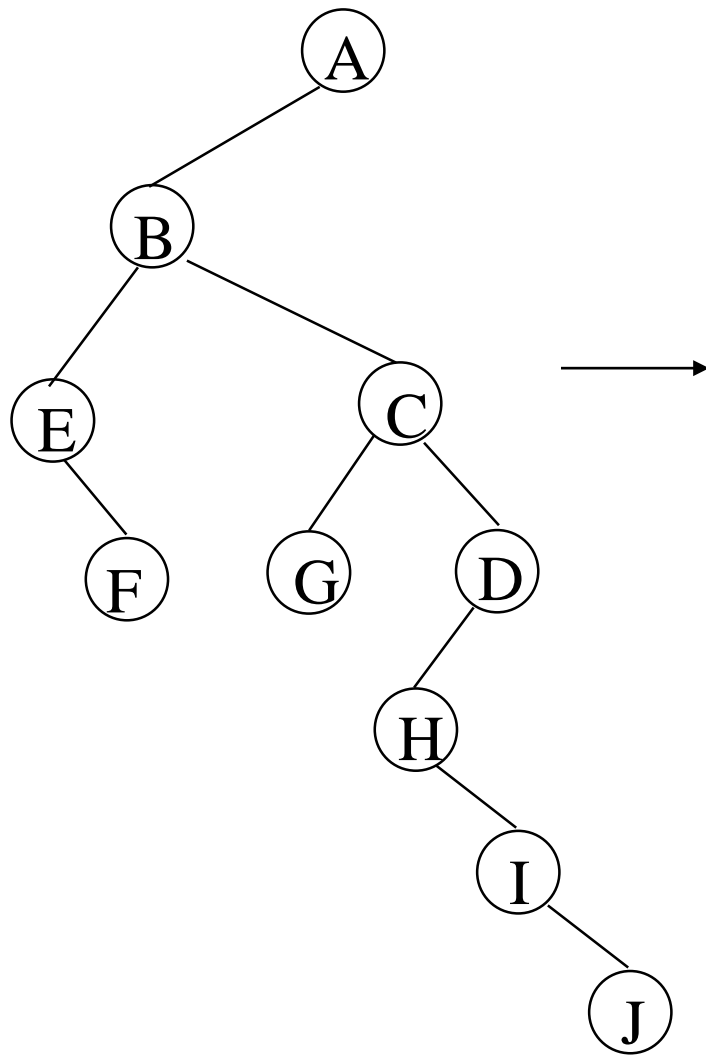
Forest Traversals

■ Preorder

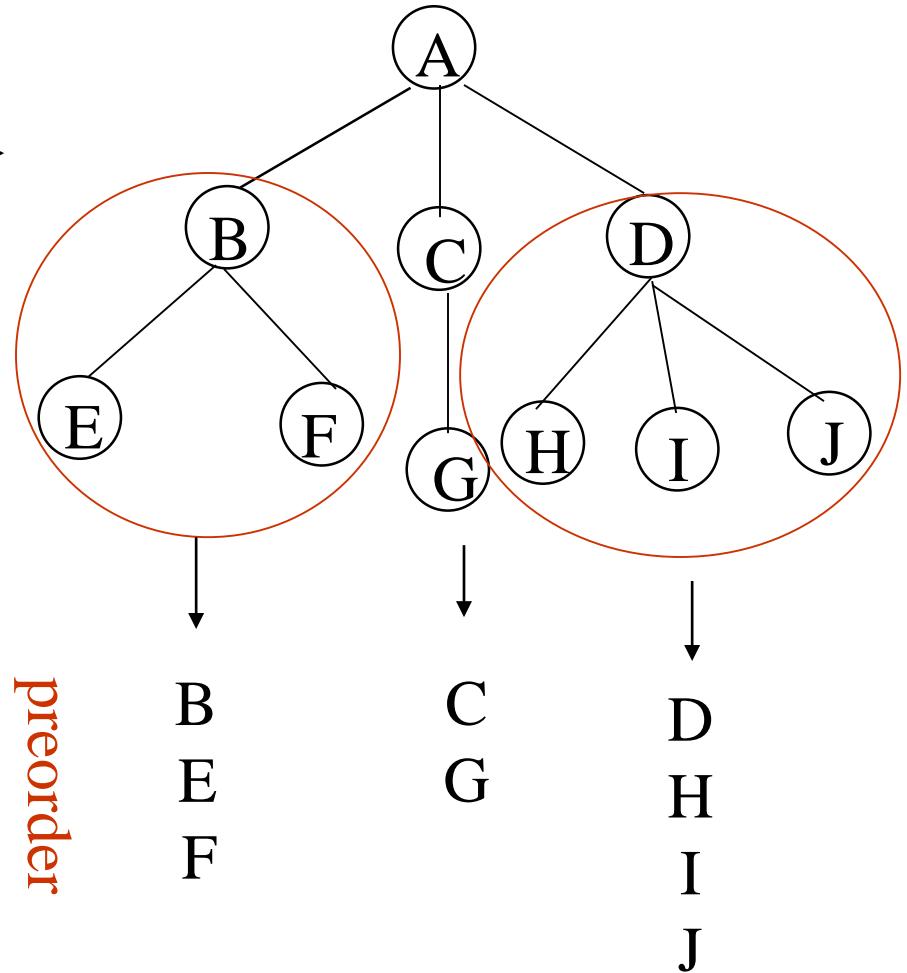
- If F is empty, then return
- Visit the root of the first tree of F
- Traverse the subtrees of the first tree in tree preorder
- Traverse the remaining trees of F in preorder

■ Inorder

- If F is empty, then return
- Traverse the subtrees of the first tree in tree inorder
- Visit the root of the first tree
- Traverse the remaining trees of F in inorder

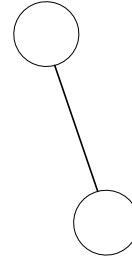
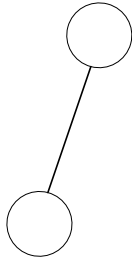


inorder: EFBGCHIJDA
preorder: ABEFCGDHIJ

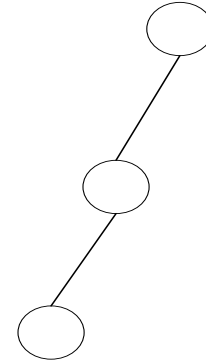
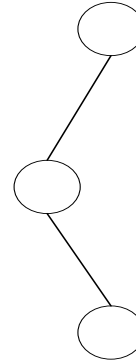
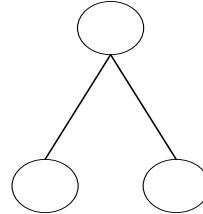
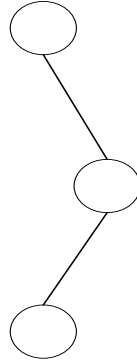
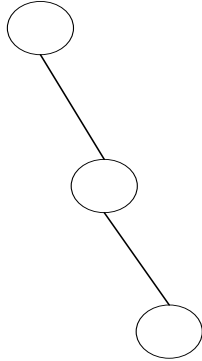


Counting Binary Trees

N=2



N=3



preorder: A B C D E F G H I
inorder: B C A E D G H F I

