

ARINC

MARK 33 DIGITAL INFORMATION TRANSFER SYSTEM (DITS) PART 1 FUNCTIONAL DESCRIPTION, ELECTRICAL INTERFACE, LABEL ASSIGNMENTS AND WORD FORMATS

ARINC SPECIFICATION 429 PART 1-17

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ARINC SPECIFICATION 429 PART 1-17
MARK 33 DIGITAL INFORMATION TRANSFER SYSTEM (DITS)
PART 1
FUNCTIONAL DESCRIPTION, ELECTRICAL INTERFACE,
LABEL ASSIGNMENTS AND WORD FORMATS

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Prepared by the Airlines Electronic Engineering Committee

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A description of the changes introduced by each supplement is included on goldenrod paper at the end of this document.

FOREWORD

Aeronautical Radio, Inc., the AEEC, and ARINC Standards

Aeronautical Radio, Inc. (ARINC) was incorporated in 1929 by four fledgling airlines in the United States as a privately-owned company dedicated to serving the communications needs of the air transport industry. Today, the major U.S. airlines remain the Company's principal shareholders. Other shareholders include a number of non-U.S. airlines and other aircraft operators.

ARINC sponsors aviation industry committees and participates in related industry activities that benefit aviation at large by providing technical leadership and guidance and frequency management. These activities directly support airline goals: promote safety, efficiency, regularity, and cost-effectiveness in aircraft operations.

The Airlines Electronic Engineering Committee (AEEC) is an international body of airline technical professionals that leads the development of technical standards for airborne electronic equipment—including avionics and in-flight entertainment equipment—used in commercial, military, and business aviation. The AEEC establishes consensus-based, voluntary form, fit, function, and interface standards that are published by ARINC and are known as ARINC Standards. The use of ARINC Standards results in substantial benefits to airlines by allowing avionics interchangeability and commonality and reducing avionics cost by promoting competition.

There are three classes of ARINC Standards:

- a) ARINC Characteristics – Define the form, fit, function, and interfaces of avionics and other airline electronic equipment. ARINC Characteristics indicate to prospective manufacturers of airline electronic equipment the considered and coordinated opinion of the airline technical community concerning the requisites of new equipment including standardized physical and electrical characteristics to foster interchangeability and competition.
- b) ARINC Specifications – Are principally used to define either the physical packaging or mounting of avionics equipment, data communication standards, or a high-level computer language.
- c) ARINC Reports – Provide guidelines or general information found by the airlines to be good practices, often related to avionics maintenance and support.

The release of an ARINC Standard does not obligate any airline or ARINC to purchase equipment so described, nor does it establish or indicate recognition or the existence of an operational requirement for such equipment, nor does it constitute endorsement of any manufacturer's product designed or built to meet the ARINC Standard.

In order to facilitate the continuous product improvement of this ARINC Standard, two items are included in the back of this volume:

- a) An Errata Report solicits any corrections to the text or diagrams in this ARINC Standard.
- b) An ARINC IA Project Initiation/Modification (APIM) form solicits any recommendations for addition of substantive material to this volume which would be the subject of a new Supplement.

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ARINC Standard – Errata Report

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1.0 INTRODUCTION

1.1 Purpose of this Document

This document defines the air transport industry's standards for the transfer of digital data between avionics systems elements. Adherence to these standards is desired for all inter-systems communications in which the system line replaceable units are defined as unit interchangeable in the relevant ARINC characteristics. Their use for intra-system communications in systems in which the line replaceable units are defined in the ARINC characteristics as system interchangeable is not essential, although it may be convenient.

1.2 Organization of ARINC Specification 429

ARINC Specification 429 was originally published in a single volume through version 14 (429-14). The size of the document and the need for improved organization dictated the division of the document into three parts. Those three parts include:

Part 1 Functional Description, Electrical Interface, Label Assignments and Word Formats

Part 2 Discrete Word Data Formats

Part 3 File Data Transfer Techniques

c-15 Part 1 provides the basic description of the functions and the supporting physical and electrical interfaces for the data transfer system. Data word formats, standard label and address assignments, and application examples are defined. Part 2 lists discrete word bit assignments in label order. Part 3 describes protocols and message definitions for data transferred in large blocks and/or file format. For convenience of the user, the section and attachment numbering has been retained for the material moved from the original Specification to Part 3.

Updates to each part of future releases of ARINC 429 will be independent of the other parts to accommodate timely revisions as industry needs dictate. The dash numbers for each Part will NOT be synchronized with the other Parts as time passes. Users of ARINC Specification 429 should ensure that the latest version of each Part is used when designing or procuring equipment.

1.3 Relationship to ARINC Specification 419

ARINC Specification 419, "Digital Data System Compendium", is a catalog of the elements of the several digital data transmission systems that have found application during the "emergent" period of digital avionics technology. The maturing of this technology, now evident in the scope of its planned use on aircraft of the 1980s and beyond, has shown the need for a generally applicable digital information transfer system having capabilities not provided by any combination of the elements presently defined in Specification 419. In defining such a system, this document draws on the experience gained in the preparation of Specification 419 but is otherwise separate and distinct from it. Addition of the element specifications of the system defined herein to the Specification 419 catalog is not anticipated.

1.4 "Mark 33 Digital Information Transfer System" - Basic Philosophy

This "Mark 33 Digital Information Transfer System (DITS)" specification describes a system in which an avionics system element having information to transmit does so from a designated output port over a single twisted and shielded pair of wires to all other system elements having need of that information. Bi-directional data flow on a given twisted and shielded pair of wires is not permitted.

1.4.1 Numeric Data Transfer

The Mark 33 DITS numeric data transmission characteristics have been developed from those of successful predecessor air transport industry digital information transfer systems. Data for transmission, encoded in either two's complement fractional binary notation or binary coded decimal notation, is supplied from source systems at rates sufficiently high to ensure small incremental value changes between updates. Transmission is made "open loop", i.e., sinks are not required to inform sources that information has been received. A parity bit is transmitted as part of each data word to permit simple error checks to be performed by the sinks. These, together with data reasonableness checks which may also be performed by the sinks, may be used to prevent the display or other utilization of an erroneous or suspect word. The inherently high integrity of the twisted and shielded wire transmission medium ensures that such drop-outs are few. The low rates of change of the data ensure that when one does occur, it is of no consequence.

1.4.2 ISO Alphabet No. 5 Data Transfer

In addition to the transfer of BNR and BCD numeric data as just described, the Mark 33 DITS handles alpha and numeric data encoded per ISO Alphabet No. 5. The same "broadcast" transmission philosophy is used, although the "housekeeping" aspects of system operation differ in order to accommodate particular needs associated with this type of data. These differences will be addressed individually in this document as they arise.

1.4.3 Graphic Data Transfer

A third type of data which may eventually be handled by the Mark 33 DITS is graphic data, i.e., the lines, circles, randomly positioned alpha/numeric text and other symbols used on CRT map and similar displays. The technique employed for this purpose can be basically similar to that used for ISO Alphabet No. 5 alpha/numeric data transfer. However, because a need for graphic data handling capability has not yet emerged, the air transport industry has decided not to be specific concerning this technique for the moment. When the need for graphic data handling is established, appropriate specification material will be developed.

c-1

c-1

2.0 DIGITAL INFORMATION TRANSFER SYSTEM STANDARDS**2.1 Message Related Elements**

This section describes the digital data transfer system elements considered to be principally related to the message itself or the manner in which it is handled.

2.1.1 Direction of Information Flow

The information output of an avionics system element should be transmitted from a designated port (or ports) to which the receiving ports of other system elements in need of that information are connected. In no case does information flow into a port designated for transmission.

COMMENTARY

A separate data bus (twisted and shielded pair of wires per Section 2.2.1) for each direction is used when data is required to flow both ways between two avionics systems elements.

2.1.2 Information Element

c-2 The basic information element is a digital word containing 32 bits. There are five application groups for such words, BNR data, BCD data, Discrete data, Maintenance data (general) and Acknowledgement, ISO Alphabet Number 5 and Maintenance (ISO Alphabet Number 5) data (AIM). Word formats for these different applications are depicted in Attachment 6 while the relevant data handling rules are set forth in Section 2.3.1. When less than the full data field is needed to accommodate the information conveyed in a word in the desired manner, the unused bit positions should be filled with binary zeros or, in the case of BNR/BCD numeric data, valid data bits. If valid data bits are used, the resolution possible for the information may exceed that called for in this Specification. The Commentary following Section 2.1.6 of this document refers.

COMMENTARY

c-1 To permit the use of identical error-checking hardware elements in the handling of BNR and BCD numeric data words, the format for the Mark 33 DITS BCD word differs from that used formerly for this type of data. Bit Number 32 is assigned to parity, Bit Numbers 31 and 30 to the sign/status matrix, Bit Number 29 is the most significant bit of the data field, and the maximum decimal value of the most significant character is 7. Previously, the BCD word contained no parity bit, the sign/status matrix occupied Bit Numbers 32 and 31, Bit Number 30 was the most significant data bit and the maximum decimal value of the most significant character was 3. This format made the word 8-bit byte oriented with respect to the data. This characteristic is not retained in the Mark 33 system.

c-1 Also, latitude and longitude can only be encoded in the Mark 33 DITS word with the formerly specified resolution of 0.1 minute of arc if Bit Numbers 9 and 10 are used for data rather than the SDI function described in Section 2.1.4 of this document, and the word is structured differently from the standard shown in Attachment 6. Restructuring the word involves limiting the maximum value of the most significant character to 1 and moving the remaining BCD

characters towards the MSB by two bit positions. It is possible, however, that future latitude and longitude displays will not be the simple, dedicated read-out type for which BCD data is intended. More likely is the use of some form of multiple-message display, such as a CRT, which will be backed by its own data processor and prefer inputs of BNR data. If this proves to be the case, these special provisions for BCD-encoding will not be required.

c-1

2.1.3 Information Identifier

The type of information contained in a word is identified by a six-character label. The first three characters are octal characters coded in binary in the first eight bits of the word. The eight bits will:

c-2
c-4

- identify the information contained within BNR and BCD numeric data words (e.g., DME distance, static air temperature, etc.) and
 - identify the word application for Discrete, Maintenance and AIM data.
- c-2

The last three characters of the six-character label are hexadecimal characters used to provide for identification of ARINC 429 bus sources. Each triplet of hexadecimal characters identifies a "black box" with one or more DITS ports. Each three character code (and black box) may have up to 255 eight bit labels assigned to it. The code is used administratively to retain distinction between unlike parameters having like labels assignments.

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COMMENTARY

Some users have expressed a desire to have means for identifying label sets and buses associated with a particular equipment ID code. Octal label 377 has been assigned for this purpose. (The code appears in the 3 LSDs of the BCD Word format). The transmission of the equipment identifier word on a bus will permit receivers attached to the bus to recognize the source of the DITS information. Since the transmission of the equipment identifier word is optional, receivers should not depend on that word for correct operation.

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Label code assignments are set forth in Attachment 1-1 to this document.

c-2

Special Note:

In some ARINC 429 DITS applications, a bus will be dedicated to delivering a single information element from a source to one or more identical sink devices. In such circumstances, the sink device designer might be tempted to assume that decoding the word label is not necessary. Experience has shown, however, that system developments frequently occur that result in the need for additional information elements to appear on the bus. If a sink device designed for service prior to such a development cannot decode the original word label, it cannot differentiate between this word and the new data in the new situation. The message for sink designers should therefore be quite clear - provide label decoding from the outset, no matter how strong the temptation to omit it might be.

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2.0 DIGITAL INFORMATION TRANSFER SYSTEM STANDARDS**COMMENTARY**

Adherence to the label code assignments of Attachment 1-1 is essential in inter-system communications and in intra-system communications where the system elements are defined as “unit interchangeable” per ARINC Report 403. The assignment of label codes for all such communications must be coordinated with the air transport industry if chaos is to be avoided. A manufacturer who finds that Attachment 1-1 does not specify the label he needs for such system application must not simply choose one from those unassigned and *drive on*. The user should contact AEEC Staff for assistance. A web page on the ARINC Website (ARINC.com) has been developed to assist you in contacting the AEEC Staff.

2.1.4 Source/Destination Identifier

c-1 Bit Numbers 9 and 10 of numeric data words should be reserved for a data source/destination identification function. They are not available for this function in alpha/numeric (ISO Alphabet Number 5) data words (see Section 2.3.1.3 of this document) or when the resolution needed for numeric (BNR/BCD) data necessitates their use of valid data. The source/destination identifier function may find application when specific words need to be directed to a specific system of a multi-system installation or when the source system of a multi-system installation needs to be recognizable from the word content. When it is used, a source equipment should encode its aircraft installation number in Bit Numbers 9 and 10 as shown in the table below. A sink equipment should recognize words containing its own installation number code and words containing code “00,” the “all-call” code.

COMMENTARY

c-8 Equipment will fall into the categories of source only, sink only, or both source and sink. Use of the SDI bits by equipment functioning only as a source or only as a sink is described above. Both the source and sink texts above are applicable to equipment functioning as both a source and a sink. Such equipment should recognize the SDI bits on the inputs and should also encode the SDI bits, as applicable, on the outputs. DME, VOR, ILS and other sensors, are examples of source and sink equipment generally considered to be only source equipment. These are actually sinks for their own control panels. Many other types of equipment are also misconstrued as source only or sink only. A simple rule of thumb is: if a unit has a 429 input port and a 429 output port, it is a source and sink! With the increase of equipment consolidation, e.g., centralized control panels, the correct use of the SDI bits cannot be overstressed.

Bit Number		Installation Number
10	9	
0	0	See Note Below
0	1	1
1	0	2
1	1	3

Note: In certain specialized applications of the SDI function the all-call capability may be forfeited so that

code “00” is available as an “installation Number 4” identifier. When the SDI function is not used, binary zeros or valid data should be transmitted in Bit Numbers 9 and 10.

COMMENTARY

This document does not address the practical question of how the SDI bits will be set in those multi-installation systems in which the source/destination function is desired. One way would be to use program pins on the individual installation black boxes which would be wired to set up the appropriate code. The ARINC Characteristics devoted to the individual systems will define the method actually to be used.

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2.1.5 Sign/Status Matrix

This section describes the coding of the Sign/Status Matrix (SSM) field. In all cases the SSM field uses Bits 30 and 31. For BNR data words, the SSM field also includes Bit 29.

The SSM field may be used to report hardware equipment condition (fault/normal), operational mode (functional test), or validity of data word content (verified/no computed data).

The following definitions apply in this Specification:

Invalid Data - is defined as any data generated by a source system whose fundamental characteristic is the inability to convey reliable information for the proper performance of a user system. There are two categories of invalid data, namely, “No Computed Data” and “Failure Warning.”

No Computed Data - is a particular case of data invalidity where the source system is unable to compute reliable data for reasons other than system failure. This inability to compute reliable data is caused exclusively by a definite set of events or conditions whose boundaries are uniquely defined in the system characteristic.

Failure Warning - is a particular case of data invalidity where the system monitors have detected one or more failures. These failures are uniquely characterized by boundaries defined in the system characteristic.

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The system indicators should always be flagged during a “Failure Warning” condition.

When a “No Computed Data” condition exists, the source system should annunciate its outputs to be invalid by setting the sign/status matrix of the affected words to the “No Computed Data” code, as defined in the subsections which follow. The system indicators may or may not be flagged, depending on system requirements.

While the unit is in the functional test mode, all output data words generated within the unit (i.e., pass through words are excluded) should be coded for “Functional Test.” Pass through data words are those words received by the unit and retransmitted without alteration.

When the SSM code is used to transmit status and more than one reportable condition exists, the condition with the highest priority should be encoded in Bit Numbers 30 and 31. The order of condition priorities to be used is shown in the table below.

2.0 DIGITAL INFORMATION TRANSFER SYSTEM STANDARDS**2.1.5 Sign/Status Matrix (cont'd)**

Failure Warning	Priority 1
No Computed Data	Priority 2
Functional Test	Priority 3
Normal Operation	Priority 4

Each data word type has its own unique utilization of the SSM field. These various formats are described in the following subsections.

2.1.5.1 BCD Numeric

When a failure is detected within a system which would cause one or more of the words normally output by that system to be unreliable, the system should stop transmitting the affected word or words on the data bus.

Some avionic systems are capable of detecting a fault condition which results in less than normal accuracy. In these systems, when a fault of this nature (for instance, partial sensor loss) which results in degraded accuracy is detected, each unreliable BCD digit should be encoded "1111" when transmitted on the data bus. For equipments having a display, the "1111" code should, when received, be recognized as representing an inaccurate digit and a "dash" or equivalent symbol should be displayed in place of the inaccurate digit. Parameters for which such a degraded mode of operation is possible are identified in the Note column of the tables in Attachment 2.

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The sign (plus/minus, north/south, etc.) of BCD Numeric Data should be encoded in bit numbers 30 and 31 of the word as shown in the table below. Bit Numbers 30 and 31 of BCD Numeric Data words should be "zero" where no sign is needed.

The "No Computed Data" code should be annunciated in the affected BCD Numeric Data word(s) when a source system is unable to compute reliable data for reasons other than system failure.

When the "Functional Test" code appears in Bits 30 and 31 of an instruction input data word, it should be interpreted as a command to perform a functional test.

COMMENTARY

A typical instruction input to a radio, for example, would be a channel change command word. When this command word is received with the "Functional Test" coding in the SSM field, the radio should exercise its functional test.

When the "Functional Test" code appears as a system output, it should be interpreted as advice that the data in the BCD Numeric Data word contents are the result of the execution of a functional test. A functional test should produce indications of 1/8 of positive full-scale values unless indicated otherwise in the associated ARINC Equipment Characteristic.

BCD NUMERIC SIGN/STATUS MATRIX

Bit Number		Meaning
31	30	
0	0	Plus, North, East, Right, To, Above
0	1	No Computed Data
1	0	Functional Test
1	1	Minus, South, West, Left, From, Below

2.1.5.2 BNR Numeric Data Words

The status of the transmitter hardware should be encoded in the Status Matrix field (Bit Numbers 30 and 31) of BNR Numeric Data words as shown in the table below.

A source system should annunciate any detected failure that causes one or more of the words normally output by that system to be unreliable by setting Bit Numbers 30 and 31 in the affected word(s) to the "Failure Warning" code defined in the table below. Words containing this code should continue to be supplied to the data bus during the failure condition.

The "No Computed Data" code should be annunciated in the affected BNR Numeric Data word(s) when a source system is unable to compute reliable data for reasons other than system failure.

When it appears as a system output, the "Functional Test" code should be interpreted as advice that the data in the word results from the execution of a functional test. A functional test should produce indications of 1/8 of positive full-scale values unless indicated otherwise in an ARINC equipment characteristic.

If, during the execution of a functional test, a source system detects a failure which causes one or more of the words normally output by that system to be unreliable, it should immediately change the states of Bit Numbers 30 and 31 in the affected words such that the "Functional Test" annunciation is replaced with "Failure Warning" annunciation.

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BNR STATUS MATRIX

Bit Number		Meaning
31	30	
0	0	Failure Warning
0	1	No Computed Data
1	0	Functional Test
1	1	Normal Operation

The sign (plus, minus, north, south, etc.) of BNR Numeric Data words should be encoded in the Sign Matrix field (Bit Number 29) as shown in the table below. Bit Number 29 should be "zero" when no sign is needed.

2.0 DIGITAL INFORMATION TRANSFER SYSTEM STANDARDS**SIGN MATRIX**

Bit Number	Meaning
29	
0	Plus, North, East, Right, To, Above
1	Minus, South, West, Left, From, Below

Some avionic systems are capable of detecting a fault condition which results in less than normal accuracy. In these systems, when a fault of this nature (for instance, partial sensor loss) which results in degraded accuracy is detected, the equipment should continue to report "Normal" for the sign status matrix while indicating the degraded performance by coding bit 11 as follows:

ACCURACY STATUS

Bit Number	Meaning
11	
0	Nominal Accuracy
1	Degraded Accuracy

This implies that degraded accuracy can be coded only in BNR words not exceeding 17 bits of data. Parameters for which such a degraded mode of operation is possible are identified in the notes column of the tables in Attachment 2.

2.1.5.3 Discrete Data Words

A source system should annunciate any detected failure that could cause one or more of the words normally output by that system to be unreliable. Three methods are defined. The first method is to set Bit Numbers 30 and 31 in the affected word(s) to the "Failure Warning" code defined in the table below. Words containing the "Failure Warning" code should continue to be supplied to the data bus during the failure condition. When using the second method, the equipment may stop transmitting the affected word or words on the data bus. Designers should use this method when the display or use of the discrete data by a system is undesirable. The third method applies to data words which are defined such that they contain failure information within the data field. For these applications, refer to the associated ARINC equipment characteristic to determine proper SSM reporting. Designers should preclude mixing operational and BITE data in the same word.

The "No Computed Data" code should be annunciated in the affected Discrete Data word(s) when a source system is unable to compute reliable data for reasons other than system failure.

When the "Functional Test" code appears as a system output, it should be interpreted as advice that the data in the Discrete Data word contents are the result of the execution of a functional test.

DISCRETE DATA WORDS

Bit Number		Meaning
31	30	
0	0	Verified Data, Normal Operation
0	1	No Computed Data
1	0	Functional Test
1	1	Failure Warning

2.1.6 Data Standards

The units, ranges, resolutions, refresh rates, number of significant bits, pad bits, etc. for the items of information to be transferred by the Mark 33 DITS are tabulated in Attachment 2 to this document.

COMMENTARY

Note that Section 2.3.1.1 of this document calls for numeric data to be encoded in BCD and binary, the latter using twos complement fractional notation. In this notation, the most significant bit of the data field represents one half of the maximum value chosen for the parameter being defined. Successive bits represent the increments of a binary fraction series. Negative numbers are encoded as the twos complements of positive value and the negative sign is annunciated in the sign/status matrix.

In establishing a given parameter's binary data standards for inclusion in Attachment 2, the units maximum value and resolution are first determined in that order. The least significant bit of the word is then given a value equal to the resolution increment, and the number of significant bits is chosen such that the maximum value of the fractional binary series just exceeds the maximum value of the parameter, i.e., equals the next whole binary number greater than the maximum parameter value less one least significant bit value. For example, if the Mark 33 DITS is required to transfer altitude in units of feet over a range of zero to 100,000 feet with a resolution of one foot, the number of significant bits is 17 and the maximum value of the fractional binary series is 131,071 (i.e., $131,072 - 1$).

Note that because accuracy is a quality of the measurement process and not the data transfer process, it plays no part in the selection of word characteristics. Obviously, the resolution provided in the DITS word should equal or exceed the accuracy in order not to degrade it.

For the binary representation of angular data, the Mark 33 DITS employs "degrees divided by 180°" as the unit of data transfer and ± 1 (semicircle) as the range for twos complement fractional notation encoding (ignoring, for the moment, the subtraction of the least significant bit value). Thus the angular range 0 through 359.XXX degrees is encoded as 0 through $\pm 179.XXX$ degrees, the value of the most significant bit is one half semicircle and there are no discontinuities in the code.

This may be illustrated as follows. Consider encoding the angular range 0° to 360° in 1° increments. Per the general encoding rules above, the positive semicircle will cover the range 0° to 179° (one least significant bit less than full range). All the bits of the code will be "zeros" for 0° and "ones" for 179°, and the sign/status matrix will indicate the positive sign. The negative semicircle will cover the range 180° to 359°. All the bits will be "zeros" for 180°. The codes for angles between 181° to 359° will be determined by taking the twos complements of the fractional binary series for

2.0 DIGITAL INFORMATION TRANSFER SYSTEM STANDARDS

2.1.6 Data Standards (cont'd)

COMMENTARY (cont'd)

c-3 the result of subtracting each value from 360. Thus, the code for 181° is the twos complement of the code for 179°. Throughout the negative semicircle, which includes 180°, the sign/status matrix contains the negative sign.

For convenience, all binary word ranges in Attachment 2 are shown as whole binary numbers rather than such numbers less one least significant bit value. Also, the resolutions shown are approximate only. Accurate resolutions can be determined, if required, by reference to the range values and numbers of significant bits for the words of interest.

It should be noted that in all applications of the twos complement fractional notation, the maximum value of the word, once chosen, cannot be changed by the use of more bits in the data field. The number of bits in the word affects only the resolution of the data, not its range.

Binary Coded Decimal (BCD) data is encoded per the numeric subset of the ISO Alphabet #5 code (see Attachment 5 to this document) using Bit Numbers 1 through 4 of the seven-bit-per-character code. Alpha/numeric data is encoded using all seven bits per character of the ISO Alphabet #5 code and is transmitted using the special word format described in Section 2.3.1.3 of this document.

2.2 Electrically Related Elements

This section describes the digital transfer system elements considered to be principally related to the electrical aspects of the signal circuit.

2.2.1 Transmission System Interconnect

c-5 A data source should be connected to the data sink(s) by means of a single twisted and shielded pair of wires. The shields should be grounded at both ends to an aircraft ground close to the rack connector and at all production breaks in the cable.

COMMENTARY

In practical wire line digital information transmission systems, cable characteristics and electrical mismatches can produce distortion of the digital data pulses. Also, noise due to electrical interference perturbs digital signals.

The performance of a digital receiver depends upon the receiver input signal characteristics (data with distortion and noise) and the receiver design.

Prior to the selection of the voltage and impedance parameters set forth in this section of this document, the pulse distortion likely to be encountered in systems built around them in existing size commercial aircraft was evaluated and judged to be acceptable for a well-designed receiver. No restriction is placed by this specification, therefore, on the number or length of stubs for installations on aircraft no larger than those existing, e.g., B 747. See Appendix A to this document for a report of this investigation.

Tests have shown that some receivers continue decoding data properly when one side of the transmission line is open or shorted to ground. When this condition exists noise immunity decreases and intermittent operation may occur. Users desire protection against non-annunciated system operation in this mode. This protection may consist of additional circuitry to detect and annunciate the fault, or to increase the receiver threshold to above 5.5 volts, which is the maximum signal level under this one-wire fault condition.

Most ARINC Characteristics now contain text specifying that DITS receivers should discontinue operation when the voltage thresholds fall into the undefined regions between "Null" and "Hi" or "Null" and "Lo." Manufacturers building DITS receivers are urged to incorporate this feature in their circuitry whether it is to be used in ARINC 7XX-series equipment or Non-ARINC devices.

2.2.2 Modulation

RZ bipolar modulation should be used. This is tri-level state modulation consisting of "HI," "NULL" and "LO" states.

2.2.3 Voltage Levels

2.2.3.1 Transmitter Voltage Levels

The differential output signal across the specified output terminals (balanced to ground at the transmitter) should be as given in the following table when the transmitter is open circuit:

	HI (V)	NULL (V)	LO (V)
Line A to Line B	+10 ±1.0	0 ±0.5	-10 ±1.0
Line A to Ground	+5 ±0.5	0 ±0.25	-5 ±0.5
Line B to Ground	-5 ±0.5	0 ±0.25	+5 ±0.5

2.0 DIGITAL INFORMATION TRANSFER SYSTEM STANDARDS**2.2.3.2 Receiver Voltage Levels**

The differential voltage presented at the receiver input terminals will be dependent upon line length, stub configuration and the number of receivers connected. In the absence of noise, the normal ranges of voltages presented to the receiver terminals (A and B) would be:

c-5	“HI”	+7.25V to +11V
	“NULL”	+0.5V to -0.5V
	“LO”	-7.25V to -11V

In practice, these nominal voltages will be perturbed by noise and pulse distortion. Thus, receivers should associate the following voltage ranges with the three states indicated:

c-4	“HI”	+6.5V to 13V
	“NULL”	+2.5V to -2.5V
	“LO”	-6.5V to -13V

COMMENTARY

Receiver reaction is currently undefined herein for voltages that fall in the range just above and below the “Null” range. Respective equipment characteristics should be referenced for desired receiver response in this range. However, it is desirable that all DITS receivers will discontinue operation when the voltage levels fall into the undefined regions. Manufacturers are urged, as new equipment is developed, to “design in” the rejection capability.

The opinion is held by some people that conditions on transmission lines will be encountered which will require receivers to operate with less than the above defined minimum difference of 4.0V between the NULL and HI and NULL and LO states. Receiver designers are encouraged to investigate the possibilities and problems of working with a minimum difference of 1 volt between these states and to report their findings.

c-4	Receiver input common mode voltages (terminal A to ground and terminal B to ground) are not specified because of the difficulties of defining ground with any satisfactory degree of precision. Receiver manufacturers are encouraged to work with the differential input voltage (line A to line B) and not line-to-ground voltages.
-----	---

2.2.4 Impedance Levels**2.2.4.1 Transmitter Output Impedance**

c-4	The transmitter output impedance should be 75 ± 5 ohms, divided equally between line A and line B to provide an impedance balanced output. This output impedance should be present for the “HI,” “NULL” and “LO” transmitter output conditions and also during transitions between these levels.
-----	--

COMMENTARY

The output impedance of the transmitter is specified as 75 ± 5 ohms to provide an approximate match to the characteristic impedance of the cable. The match can

only be approximate due to the wide range of characteristic impedances which may be encountered due to the variety of conductor wire gauges and insulation properties. Measurements on a few samples of wire showed a spread of characteristic impedance of 63 to 71 ohms. An extrapolation over the wire gauges 20 to 26 for wrapped and extruded insulation indicate an expected characteristic impedance spread of 60 to 80 ohms approx. Twisted shielded wire specifications do not control the characteristic impedance of the cable, thus future developments in insulation techniques may result in cables having characteristic impedances outside the range estimated.

2.2.4.2 Receiver Input Impedance

The receiver should exhibit the following characteristics, measured at the receiver input terminals:

Differential Input Resistance $R_I = 12,000$ ohms minimum	c-4
Differential Input Capacitance $C_I = 50$ pF maximum	
Resistance to Ground R_H and $R_G \geq 12,000$ ohms	
Capacitance to Ground C_H and $C_G \leq 50$ pF.	

The total receiver input resistance including the effects of R_I , R_H and R_G in parallel should be 8,000 ohms minimum (400 ohms minimum for twenty receiver loads).	c-4
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No more than twenty receivers should be connected on to one digital data bus and each receiver should incorporate isolation provisions to ensure that the occurrence of any reasonably probable failure does not cause loss of data to the others.

See Attachment 4 to this document for a pictorial representation of the input and output circuit standards.

COMMENTARY

The above characteristics apply to differential amplifier receivers. Opto-isolator technology is progressing and may soon find application in digital data receivers. Opto-isolator receivers impose slightly greater loads on data buses than differential amplifier receivers and the way in which they are characterized is different. It is probable, however, that a future revision of this Specification will include material specifically related to their use.

2.2.5 Fault Tolerance**2.2.5.1 Receiver External Fault Voltage Tolerance**

Receivers should withstand without sustaining damage the following steady-state voltages being applied to their terminals, superimposed upon a normally operating bus. Operation within specification limits is not required under these conditions.

- | | |
|---|-----|
| a. 30 Vac RMS applied across terminals A and B, or | c-4 |
| b. ± 29 Vdc applied between terminal A and ground, or | |
| c. ± 29 Vdc applied between terminal B and ground. | |

2.0 DIGITAL INFORMATION TRANSFER SYSTEM STANDARDS**2.2.5.2 Transmitter External Fault Voltage**

Transmitter failures caused by external fault voltages should not cause other transmitters or other circuitry in the unit to function outside of their specification limits or to fail.

2.2.5.3 Transmitter External Fault Load Tolerance

Transmitters should indefinitely withstand without sustaining damage a short circuit applied:

- a. across terminals A and B, or
- b. from terminal A to ground, or
- c. from terminal B to ground, or
- d. b and c above, simultaneously.

2.2.6 Fault Isolation**2.2.6.1 Receiver Fault Isolation**

Each receiver should incorporate isolation provisions to ensure that the occurrence of any reasonably probable internal LRU or bus receiver failure does not cause any input bus to operate outside of its specification limits (both undervoltage or overvoltage).

2.2.6.2 Transmitter Fault Isolation

Each transmitter should incorporate isolation provisions to ensure that it does not under any reasonably probable LRU fault condition provide an output voltage in excess of:

- a. a voltage greater than 30 Vac RMS between terminal A and B, or
- b. greater than ± 29 Vdc between A and ground, or
- c. greater than ± 29 Vdc between B and ground.

2.3 Logic Related Elements

This section describes the digital transfer system elements considered to be principally related to the logic aspects of the signal circuit.

2.3.1 Digital Language**2.3.1.1 Numeric Data**

The Mark 33 DITS should accommodate numeric data encoded in two digital languages, (i) BNR expressed in two complement fractional notation and (ii) BCD per the numerical subset of ISO Alphabet Number 5 (see Attachment 5 to this document). An information item encoded in both languages will be assigned a unique address for each (see Section 2.1.3 and Attachment 1-1). Word formats are illustrated in Attachment 6 to this document.

2.3.1.2 Discretes

In addition to handling numeric data as specified above, the Mark 33 DITS should also be capable of accommodating discrete items of information either in the unused (pad) bits of data words or, when necessary, in dedicated words. Any

discrete information contained in a numeric data word assigned a label in Attachment 1-1 is specified in the definition for that word in Attachment 6.

The rule to be followed in the assignment of soft bits to discrete in numeric data words is to start with the least significant bit of the word and to continue towards the most significant bit available in the word. Attachment 6 shows this against the background of the generalized word structure.

There are two types of discrete words. These are general purpose discrete words, and dedicated discrete words. Seven labels (270 XXX-276 XXX) are assigned to the general purpose words in Attachment 1-1. These words should be used in ascending label order (starting with 270 XXX) when the system receiving the data can identify its source by reference to the port at which it arrives.

2.3.1.3 Maintenance Data (General Purpose)

The general purpose maintenance words are assigned labels in sequential order as are the labels for the general purpose discrete words. The lowest octal value label assigned to the maintenance words should be used when only one maintenance word is transmitted. When more than one word is transmitted the lowest octal value label should be used first and the other labels used sequentially until the message has been completed. The general purpose maintenance words may contain discrete, BCD or BNR numeric data but should never contain ISO Alphabet Number 5 messages. The general purpose maintenance words should be formatted according to the layouts of the corresponding BCD/BNR/discrete data words shown in Attachment 2.

2.3.1.4 AIM Data

The information previously contained in this section is no longer applicable to ARINC Specification 429. For reference purposes, the section header is retained and the original contents of this section are located in Part 3 of this Specification.

2.3.1.5 File Data Transfer

This section previously described a character-oriented file data transfer protocol. This definition was used as guidance for the character-oriented file transfer protocol descriptions incorporated into many ARINC equipment characteristics. The original contents of this section are located in Part 3 of this Specification.

The protocol defined in Part 3 is preferred for new applications. The purpose of this bit-oriented communications protocol is to provide for the transparent transfer of data files using the ARINC 429 data bus.

COMMENTARY

The data transparent protocol described in Part 3 was developed in order to facilitate the communications of the ACARS Management Unit (MU) and the Satellite Data Unit (SDU). Its viability as a universal protocol was recognized by the Systems Architecture and Interfaces (SAI) Subcommittee, which recommended its inclusion herein as the standard means of file data transfer.

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2.0 DIGITAL INFORMATION TRANSFER SYSTEM STANDARDS

c-14 The process for determining the protocol (character-oriented or bit-oriented) to be used in the interaction between two units, where this information is not pre-determined is described in Part 3 of ARINC 429.

2.3.1.5.1 Bit-Oriented Protocol Determination

The ALO word should be sent by any system which supports the bit-oriented Link Layer protocol just after the system powers-up, or performs a re-initialization for any reason. The ALO/ALR protocol process may also be used when a bit-oriented Link Layer protocol system needs to determine if any of its interfaces support the bit-oriented protocol. All systems which support the Link Layer bit-oriented protocol must be able to respond to the initiation of this process. Attachment 11C of Part 3 to ARINC 429, shows the ALO and ALR word formats.

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When a system with a bit-oriented Link Layer protocol has the need to make this determination, it should construct the ALO word and transmit this word to the device in question. The system should then wait for a maximum period of time defined by T_{12} . If the device in question has not responded within T_{12} , the initiating system should initiate another ALO word and again delay up to T_{12} . An initiating system will attempt a maximum of N_6 ALO word operations before declaring the device in question as "Not bit-oriented" or "Not able to respond."

2.3.2 Transmission Order

The Least Significant Bit (LSB) and Least Significant Character (LSC) of each word should be transmitted first. It may be noted that the least significant bit of the word is the most significant bit of the label and that the label is transmitted ahead of the data in each case. This "reversed label" characteristic is a legacy from past systems in which the octal coding of the label field was, apparently, of no significance.

2.3.3 Data Bit Encoding Logic

A "HI" state after the beginning of the bit interval returning to a "NULL" state before the end of the same bit interval signifies a logic "one."

A "LO" state after the beginning of the bit interval returning to a "NULL" state before the end of the same bit interval signifies a logic "zero." This is represented graphically in Attachment 7 to this document.

2.3.4 Error Detection/Correction

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The last bit of each word should be encoded such that word parity is rendered odd to allow error detection in receivers. Note that the parity calculation encompasses all 31 label and information bits of the word.

COMMENTARY

Air transport industry experience with digital information transfer systems pre-dating the Mark 33 DITS has shown that the twisted shielded pair of wires can be regarded as a high integrity link unlikely to introduce bit errors into the data passing through it. It is for this reason that no means for error correction are specified in this document. The error detection

capability specified above may be used as desired in receiving terminals. BNR data, for example, may be checked for parity by reference to the binary state of Bit Number 32 of each word. Also, the data may be submitted to reasonableness checks. BCD may be submitted to reasonableness checks. BCD data intended for human consumption in the cockpit is normally smoothed before transmission to ensure tolerable levels of display jitter. As this process eliminates any obviously wild data points, the need for further error detection is questionable. As pointed out in the Commentary following Section 2.1.2 of this document, the parity bit was added to the BCD word for reasons related to BCD/BNR transmitter hardware commonality, not because a need for it existed for error detection.

2.4 Timing Related Elements

This section describes the digital data transfer system elements considered to be principally related to the timing aspects of the signal circuit.

2.4.1 Bit Rate**2.4.1.1 High Speed Operation**

The bit rate for high speed operation of the system should be 100 kilobits per second $\pm 1\%$.

2.4.1.2 Low Speed Operation

The bit rate for low speed operation of the system should be within the range 12.0 to 14.5 kilobits per second. The selected rate should be maintained within 1%.

NOTE:

High bit rate and low bit rate messages will not be intermixed on the same bus.

COMMENTARY

Although the bit rates specified above should be held within the stated tolerances over the long term, individual bit lengths may fall outside the limits expected from these tolerances. Bit symmetry and jitter should be within the tolerances specified in Attachment 8.

Also, notwithstanding the RFI performance of the ARINC 429 DITS reported in Appendix 1 to this document, system designers are advised to avoid selection of 13.6 kilobits per second for low speed operations and precisely 100 kilobits per second for high speed operations to ensure that the system is not responsible for interference to LORAN C systems with which the aircraft might be equipped.

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2.4.2 Information Rates

The minimum and maximum transmit intervals for each item of information transferred by the Mark 33 DITS are specified in the tables of Attachment 2. Words with like labels but with different SDI codes should be treated as unique items of information. Each and every unique item of information should be transmitted once during an interval bounded in length by the minimum and maximum

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2.0 DIGITAL INFORMATION TRANSFER SYSTEM STANDARDS

2.4.2 Information Rates (cont'd)

c-5 | values specified in Attachment 2. Stated another way, a word having the same label and four different SDI codes should appear on the bus four times (once for each SDI code) during that time interval.

COMMENTARY

There are no values given for refresh rates in this Specification. However, it is desirable that data be refreshed at least once per transmission. Those data actually requiring long processing times or a large number of samples are the only types not expected to be refreshed with every transmission.

Discretes contained within data words should be transferred at the bit rate and repeated at the update rate of the primary data. Words dedicated to discretes should be repeated continuously at the rates defined in Attachment 2.

COMMENTARY

The time intervals between successive transmissions of a given BCD word specified in table 1 of Attachment 2 to this document are, in general, too short for the signal to be of use in driving a display device directly. If the signal was so used the least significant character of the display, would change too rapidly for human perception. Considerations other than human factors demand the time intervals specified. Thus, display designers should incorporate into their devices means for selecting those words to be used for updating the display from the greater quantity delivered.

2.4.3 Clocking Method

Clocking is inherent in the data transmission. The identification of the bit interval is related to the initiation of either a "HI" or "LO" state from a previous "NULL" state in a bipolar RZ code.

2.4.4 Word Synchronization

The digital word should be synchronized by reference to a gap of four bit times (minimum) between the periods of word transmissions. The beginning of the first transmitted bit following this gap signifies the beginning of the new word.

2.4.5 Timing Tolerances

The waveform timing tolerances should be as shown in Attachment 8 to this document.

COMMENTARY

RF interference radiated by the Mark 33 DITS using the waveform characteristics specified in this section has been shown not to exceed that permitted by Figure 21-5 of RTCA Document DO-160, "Environmental Conditions and Test Procedures for Airborne Electronic/Electrical Equipment and Instruments." Also, conducted RF interference is within the limits specified in Figure 21-2 of DO-160. Appendix 1 to this document refers.

3.0 MARK 33 DITS APPLICATIONS NOTES**3.1 Radio Systems Management**

One special application of the Mark 33 DITS is to radio systems frequency selection and function switching. The following paragraphs set forth the rules which should be followed in the application of the DITS to ensure interchangeability of radios and control sources.

3.1.1 Word Format and Digital Language

The standard DITS 32-bit BCD word should be used, of which Bit Numbers 1 through 8 constitute the label, Bit Numbers 9 and 10 are reserved for a source/destination identifier code, bit Numbers 11 through 29 constitute the data, Bit Numbers 30 and 31 form the sign/status matrix and Bit Number 32 is the word parity bit. The data field should contain the frequency to which the radio defined by the label field is to tune encoded in BCD characters, together with the discretes required for function switching for that radio. Attachment 6 shows how the word should be structured for each radio system requiring the DITS management service.

3.1.2 Update Rate

The nominal update rate for all radio systems management words should be five times per second.

3.1.3 Sign/Status Matrix

Since sign is not a characteristic of radio systems management information, the normal states of the sign/status matrix bits will be binary "zeros." However, the radios should recognize the codes for "functional test" and "no computed data," (see Section 2.1.5 of this document). They should interpret the former as an instruction to perform a functional test or functional test sequence. They should regard the latter as an instruction to remain tuned to the frequency contained in the last valid word received until either another valid word is decoded or their primary power is removed.

3.1.4 Frequency Ranges and Switching Functions**3.1.4.1 ADF**

Frequency Range:	190kHz to 1750kHz
Frequency Selection Increment:	0.5kHz
Characters encoded in DITS word:	1000kHz, 100kHz, 10kHz, 1kHz
Switching Functions:	0.5kHz on/off, BFO on/off, ADF/ANT mode selection

3.1.4.2 DME

Frequency Range: (VOR/ILS)	108.00MHz to 135.95MHz
Frequency Selection Increment: (VOR/ILS)	50kHz
Characters encoded in DITS word:	10Mhz, 1Mhz, 0.1MHz 0.05MHz (VOR/ILS only) (100MHz character is 1 for VOR/ILS, 10MHz character is limited to 7)
Switching Functions:	VOR/ILS/MLS Frequency, DME modes, Directed Frequency Numbers, Display Control

3.1.4.3 HF Communications

Frequency Range:	2.8MHz to 24MHz
Frequency Selection Increment:	1kHz or .1kHz
Characters encoded in DITS words:	10MHz, 1MHz, 0.1MHz,
Switching Functions:	USB/LSB mode selection SB/AM mode selection

Note: Two words may be transmitted for HF frequency selection to facilitate frequency resolution of 0.1kHz.

3.1.4.4 ILS

Frequency Range:	108.00MHz to 111.95MHz
Frequency Selection Increment:	50kHz
Characters encoded in DITS words:	10MHz, 1MHz, 0.1MHz, 0.01MHz, (100MHz character is always decimal 1)
Switching Functions:	None

3.1.4.5 VOR/ILS

Frequency Range:	108.00 MHz to 117.95MHz
Frequency Selection Increment:	50kHz
Characters encoded in DITS words:	10MHz, 1MHz, 0.1MHz, 0.01MHz, (100MHz character is always decimal 1)
Switching Functions:	ILS Mode

3.1.4.6 VHF Communications

Frequency Range:	117.975MHz to 137.000MHz
Frequency Selection Increment:	25kHz or 8.33kHz
Characters encoded in DITS words:	10MHz, 1MHz, 0.1MHz, 0.01MHz, (100MHz character is always decimal 1)
Switching Functions:	None

3.1.4.7 ATC Transponder

Note: The ATC Transponder operates on two frequencies (one receive and one transmit) which do not require selection. Reply code selection, however, is required and it is this that the Mark 33 DITS accommodates).

Reply Code Ranges:	0-7 in four independent groups
Code increments:	1 decimal digit per group
Number of characters encoded in DITS words:	ALL
Switching Functions:	Ident. Pulse Select, Altitude Reporting On/Off, Altitude Source Select, X-pulse Select (reserved), VFR/IFR Select (reserved), IRS/FMC Input Select (reserved).

3.0 MARK 33 DITS APPLICATIONS NOTES

3.2 AIM Information Transfer

The information previously contained in this section is no longer applicable to ARINC Specification 429. For reference purposes, the section header is retained and the original contents of this section are located in Part 3.

ATTACHMENT 1-1
LABEL CODES

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Code No. (Octal)	Eqpt. ID (Hex)	Transmission Order Bit Position								Parameter	Data				Notes & Cross Ref. to Tables in Att. 6
		1	2	3	4	5	6	7	8		BNR	BCD	DISC	SAL	
0 0 0	0 X X	0 0	0 0	0 0	0 0	0 0	0 0	0 0	0 0	Not Used					
0 0 1	0 0 2	0 0	0 0	0 0	0 0	0 0	0 0	0 0	0 1	Distance to Go		X			6-25
	0 5 6	0 0	0 0	0 0	0 0	0 0	0 0	0 0	0 1	Distance to Go		X			
	0 6 0	0 0	0 0	0 0	0 0	0 0	0 0	0 0	0 1	Distance to Go		X			
0 0 2	0 0 2	0 0	0 0	0 0	0 0	0 0	0 0	0 1	0 0	Time to Go		X			6-25
	0 5 6	0 0	0 0	0 0	0 0	0 0	0 0	0 1	0 0	Time to Go		X			
	0 6 0	0 0	0 0	0 0	0 0	0 0	0 0	0 1	0 0	Time to Go		X			
	1 1 5	0 0	0 0	0 0	0 0	0 0	0 0	0 1	0 0	Time to Station		X			
0 0 3	0 0 2	0 0	0 0	0 0	0 0	0 0	0 0	0 1	1 0	Cross Track Distance		X			6-25
0 0 4	0 0 1	0 0	0 0	0 0	0 0	0 0	0 0	1 0	0 0	Runway Distance to Go		X			
0 0 5	0 D 0	0 0	0 0	0 0	0 0	0 0	0 0	1 0	1 0	Engine Discrete			X		
0 0 6	0 D 0	0 0	0 0	0 0	0 0	0 0	0 0	1 1	1 0	Engine Discrete			X		
0 0 7	0	0 0	0 0	0 0	0 0	0 0	0 0	1 1	1 1	Spare					
0 1 0	0 0 2	0 0	0 0	0 0	0 0	0 0	0 0	0 0	0 0	Present Position - Latitude		X			6-25-1
	0 0 4	0 0	0 0	0 0	0 0	0 0	0 0	0 0	0 0	Present Position - Latitude		X			
	0 3 8	0 0	0 0	0 0	0 0	0 0	0 0	0 0	0 0	Present Position - Latitude		X			
0 1 1	0 0 2	0 0	0 0	0 0	0 0	0 0	0 0	0 0	0 1	Present Position - Longitude		X			6-25-1
	0 0 4	0 0	0 0	0 0	0 0	0 0	0 0	0 0	0 1	Present Position - Longitude		X			
	0 3 8	0 0	0 0	0 0	0 0	0 0	0 0	0 0	0 1	Present Position - Longitude		X			
0 1 2	0 0 2	0 0	0 0	0 0	0 0	0 0	0 0	0 1	0 0	Ground Speed		X			6-25
	0 0 4	0 0	0 0	0 0	0 0	0 0	0 0	0 1	0 0	Ground Speed		X			
	0 0 5	0 0	0 0	0 0	0 0	0 0	0 0	0 1	0 0	Ground Speed		X			
	0 2 5	0 0	0 0	0 0	0 0	0 0	0 0	0 1	0 0	Ground Speed		X			
	0 3 8	0 0	0 0	0 0	0 0	0 0	0 0	0 1	0 0	Ground Speed		X			
	0 4 D	0 0	0 0	0 0	0 0	0 0	0 0	0 1	0 0	QTY-LD SEL (LB)		X			
	0 5 6	0 0	0 0	0 0	0 0	0 0	0 0	0 1	0 0	Ground Speed		X			
	0 6 0	0 0	0 0	0 0	0 0	0 0	0 0	0 1	0 0	Ground Speed		X			
0 1 3	0 0 2	0 0	0 0	0 0	0 0	0 0	0 0	0 1	1 0	Track Angle - True		X			6-25
	0 0 4	0 0	0 0	0 0	0 0	0 0	0 0	0 1	1 0	Track Angle - True		X			
	0 3 8	0 0	0 0	0 0	0 0	0 0	0 0	0 1	1 0	Track Angle - True		X			
	0 4 D	0 0	0 0	0 0	0 0	0 0	0 0	0 1	1 0	QTY-FLT Deck (LB)		X			
	0 B 8	0 0	0 0	0 0	0 0	0 0	0 0	0 1	1 0	Control Word for TCAS/Mode S			X		
0 1 4	0 0 4	0 0	0 0	0 0	0 0	0 0	0 0	1 0	0 0	Magnetic Heading		X			
	0 0 5	0 0	0 0	0 0	0 0	0 0	0 0	1 0	0 0	Magnetic Heading		X			
	0 3 8	0 0	0 0	0 0	0 0	0 0	0 0	1 0	0 0	Magnetic Heading		X			
0 1 5	0 0 2	0 0	0 0	0 0	0 0	0 0	0 0	1 0	0 1	Wind Speed		X			
	0 0 4	0 0	0 0	0 0	0 0	0 0	0 0	1 0	0 1	Wind Speed		X			
	0 0 5	0 0	0 0	0 0	0 0	0 0	0 0	1 0	0 1	Wind Speed		X			
	0 3 8	0 0	0 0	0 0	0 0	0 0	0 0	1 0	0 1	Wind Speed		X			
0 1 6	0 0 4	0 0	0 0	0 0	0 0	0 0	0 0	1 1	1 0	Wind Direction - True		X			
	0 3 8	0 0	0 0	0 0	0 0	0 0	0 0	1 1	1 0	Wind Direction - True		X			
	0 B 8	0 0	0 0	0 0	0 0	0 0	0 0	1 1	1 0	Control Word for TCAS/Mode S			X		
0 1 7	0 1 0	0 0	0 0	0 0	0 0	0 0	0 0	1 1	1 1	Selected Runway - True		X			
	0 4 D	0 0	0 0	0 0	0 0	0 0	0 0	1 1	1 1	Total-FLT Deck (LB)		X			
	0 5 5	0 0	0 0	0 0	0 0	0 0	0 0	1 1	1 1	Selected Runway Heading		X			
	0 A 0	0 0	0 0	0 0	0 0	0 0	0 0	1 1	1 1	Selected Runway Heading		X			
	0 B 0	0 0	0 0	0 0	0 0	0 0	0 0	1 1	1 1	Selected Runway Heading		X			
0 2 0	0 2 0	0 0	0 0	0 0	0 1	0 0	0 0	0 0	0 0	Selected Vertical Speed		X			6-25
	0 4 D	0 0	0 0	0 0	0 1	0 0	0 0	0 0	0 0	TNK-LD SEL (LB)		X			
	0 6 D	0 0	0 0	0 0	0 1	0 0	0 0	0 0	0 0	Landing Gear Position Infor & System Status			X		
	0 A 1	0 0	0 0	0 0	0 1	0 0	0 0	0 0	0 0	Selected Vertical Speed		X			
0 2 1	0 0 2	0 0	0 0	0 0	0 1	0 0	0 0	0 0	0 1	Selected EPR		X			6-25
	0 0 2	0 0	0 0	0 0	0 1	0 0	0 0	0 0	0 1	Selected N1		X			6-25
	0 2 0	0 0	0 0	0 0	0 1	0 0	0 0	0 0	0 1	Selected EPR		X			
	0 2 0	0 0	0 0	0 0	0 1	0 0	0 0	0 0	0 1	Selected N1		X			
	0 6 D	0 0	0 0	0 0	0 1	0 0	0 0	0 0	0 1	Landing Gear Position Infor & System Status			X		
	0 A 1	0 0	0 0	0 0	0 1	0 0	0 0	0 0	0 1	Selected EPR		X			
	0 A 1	0 0	0 0	0 0	0 1	0 0	0 0	0 0	0 1	Selected N1		X			
0 2 2	0 2 0	0 0	0 0	0 0	0 1	0 0	0 0	0 1	0 0	Selected Mach		X			6-25
	0 4 D	0 0	0 0	0 0	0 1	0 0	0 0	0 1	0 0	QTY-LD SEL (KG)		X			
	0 6 D	0 0	0 0	0 0	0 1	0 0	0 0	0 1	0 0	Landing Gear Position Infor & System Status			X		
	0 A 1	0 0	0 0	0 0	0 1	0 0	0 0	0 1	0 0	Selected Mach		X			
0 2 3	0 2 0	0 0	0 0	0 0	0 1	0 0	0 0	0 1	1 0	Selected Heading		X			6-25
	0 4 D	0 0	0 0	0 0	0 1	0 0	0 0	0 1	1 0	QTY-LD SEL (KG)		X			
	0 6 D	0 0	0 0	0 0	0 1	0 0	0 0	0 1	1 0	Landing Gear Position Infor & System Status			X		
	0 A 1	0 0	0 0	0 0	0 1	0 0	0 0	0 1	1 0	Selected Heading		X			

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Code No. (Octal)	Eqpt. ID (Hex)	Transmission Order Bit Position								Parameter	Data				Notes & Cross Ref. to Tables in Att. 6
		1	2	3	4	5	6	7	8		BNR	BCD	DISC	SAL	
0 2 4	0 1 1	0 0	0 1	0 1	0 0	1 0	0 0			Selected Course #1		X			6-25
	0 2 0	0 0	0 1	0 1	0 0	1 0	0 0			Selected Course #1		X			
	0 6 D	0 0	0 1	0 1	0 0	1 0	0 0			Landing Gear Position Infor & System Status			X		
	0 A 1	0 0	0 1	0 1	0 0	1 0	0 0			Selected Course #1		X			
	0 B 1	0 0	0 1	0 1	0 0	1 0	0 0			Selected Course #1		X			
0 2 5	0 2 0	0 0	0 1	0 1	0 0	1 0	0 1			Selected Altitude		X			6-25
	0 4 D	0 0	0 1	0 1	0 0	1 0	0 1			Load SEL Control	X				
	0 A 1	0 0	0 1	0 1	0 0	1 0	0 1			Selected Altitude		X			
0 2 6	0 0 3	0 0	0 1	0 1	0 0	1 1	0 0			Selected Airspeed		X			6-25
	0 2 0	0 0	0 1	0 1	0 0	1 1	0 0			Selected Airspeed	X				
	0 A 1	0 0	0 1	0 1	0 0	1 1	0 0			Selected Airspeed		X			
0 2 7	0 0 2	0 0	0 1	0 1	0 0	1 1	1 1			TACAN Selected Course		X			
	0 1 1	0 0	0 1	0 1	0 0	1 1	1 1			Selected Course # 2		X			
	0 2 0	0 0	0 1	0 1	0 0	1 1	1 1			Selected Course # 2		X			
	0 4 D	0 0	0 1	0 1	0 0	1 1	1 1			Total-FLT Deck (KG)		X			
	0 5 6	0 0	0 1	0 1	0 0	1 1	1 1			TACAN Selected Course		X			
	0 6 0	0 0	0 1	0 1	0 0	1 1	1 1			TACAN Selected Course		X			
	0 A 1	0 0	0 1	0 1	0 0	1 1	1 1			Selected Course # 2		X			
	0 B 1	0 0	0 1	0 1	0 0	1 1	1 1			Selected Course # 2		X			
0 3 0	0 2 0	0 0	0 1	1 1	0 0	0 0	0 0			VHF COM Frequency		X			6-45
	0 2 4	0 0	0 1	1 1	0 0	0 0	0 0			VHF COM Frequency		X			
	0 4 D	0 0	0 1	1 1	0 0	0 0	0 0			TNK-LD SEL (KG)		X			6-45
	0 B 6	0 0	0 1	1 1	0 0	0 0	0 0			VHF COM Frequency		X			
0 3 1	0 2 0	0 0	0 1	1 1	0 0	0 0	0 1			Beacon Transponder Code			X		6-46
	0 B 8	0 0	0 1	1 1	0 0	0 0	0 1			Beacon Transponder Code			X		
0 3 2	0 1 2	0 0	0 1	1 1	0 1	0 1	0 0			ADF Frequency		X			6-40
	0 2 0	0 0	0 1	1 1	0 1	0 1	0 0			ADF Frequency		X			6-40
	0 B 2	0 0	0 1	1 1	0 1	0 1	0 0			ADF Frequency		X			6-40
0 3 3	0 0 2	0 0	0 1	1 1	0 1	0 1	1 1			ILS Frequency		X			6-44
	0 1 0	0 0	0 1	1 1	0 1	0 1	1 1			ILS Frequency		X			
	0 2 0	0 0	0 1	1 1	0 1	0 1	1 1			ILS Frequency		X			
	0 5 5	0 0	0 1	1 1	0 1	0 1	1 1			Landing System Mode/Frequency		X			
	0 5 6	0 0	0 1	1 1	0 1	0 1	1 1			ILS Frequency		X			
	0 6 0	0 0	0 1	1 1	0 1	0 1	1 1			ILS Frequency		X			
	0 B 0	0 0	0 1	1 1	0 1	0 1	1 1			ILS Frequency		X			
0 3 4	0 0 2	0 0	0 1	1 1	1 0	0 0	0 0			VOR/ILS Frequency		X			6-44-1
	0 0 6	0 0	0 1	1 1	1 0	0 0	0 0			Baro Correction (mb) #3		X			
	0 1 1	0 0	0 1	1 1	1 0	0 0	0 0			VOR/ILS Frequency		X			
	0 2 0	0 0	0 1	1 1	1 0	0 0	0 0			VOR/ILS Frequency		X			
	0 2 5	0 0	0 1	1 1	1 0	0 0	0 0			VOR/ILS Frequency		X			
	0 5 6	0 0	0 1	1 1	1 0	0 0	0 0			VOR/ILS Frequency		X			
	0 6 0	0 0	0 1	1 1	1 0	0 0	0 0			VOR/ILS Frequency #1		X			
	0 B 0	0 0	0 1	1 1	1 0	0 0	0 0			VOR/ILS Frequency		X			
0 3 5	0 0 2	0 0	0 1	1 1	1 0	0 1	0 1			DME Frequency		X			6-41
	0 0 6	0 0	0 1	1 1	1 0	0 1	0 1			Baro Correction (ins of Hg) #3		X			
	0 0 9	0 0	0 1	1 1	1 0	0 1	0 1			DME Frequency		X			6-41
	0 2 0	0 0	0 1	1 1	1 0	0 1	0 1			DME Frequency		X			
	0 2 5	0 0	0 1	1 1	1 0	0 1	0 1			DME Frequency		X			
	0 5 5	0 0	0 1	1 1	1 0	0 1	0 1			Paired DME Frequency		X			
	0 5 6	0 0	0 1	1 1	1 0	0 1	0 1			DME Frequency		X			
	0 6 0	0 0	0 1	1 1	1 0	0 1	0 1			DME Frequency #1		X			
	0 A 9	0 0	0 1	1 1	1 0	0 1	0 1			DME Frequency		X			
0 3 6	0 0 2	0 0	0 1	1 1	1 1	0 0	0 0			MLS Frequency		X			
	0 2 0	0 0	0 1	1 1	1 1	0 0	0 0			MLS Frequency		X			
	0 5 5	0 0	0 1	1 1	1 1	0 0	0 0			MLS Channel Selection		X			
	0 5 6	0 0	0 1	1 1	1 1	0 0	0 0			MLS Frequency Channel		X			
	0 6 0	0 0	0 1	1 1	1 1	0 0	0 0			MLS Frequency Channel		X			
	0 C 7	0 0	0 1	1 1	1 1	0 0	0 0			MLS Frequency		X			
0 3 7	0 0 2	0 0	0 1	1 1	1 1	1 1	1 1			HF COM Frequency		X			6-42
	0 B 9	0 0	0 1	1 1	1 1	1 1	1 1			HF COM Frequency		X			
0 4 0	0	0 0	1 0	0 0	0 0	0 0	0 0			Spare					
0 4 1	0 0 2	0 0	1 0	0 0	0 0	0 0	0 1			Set Latitude		X			
	0 0 4	0 0	1 0	0 0	0 0	0 0	0 1			Set Latitude		X			
	0 2 0	0 0	1 0	0 0	0 0	0 0	0 1			Set Latitude		X			
	0 5 6	0 0	1 0	0 0	0 0	0 0	0 1			Set Latitude		X			
	0 6 0	0 0	1 0	0 0	0 0	0 0	0 1			Set Latitude		X			
	0 A 4	0 0	1 0	0 0	0 0	0 0	0 1			Set Latitude		X			

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Code No. (Octal)	Eqpt. ID (Hex)	Transmission Order Bit Position								Parameter	Data				Notes & Cross Ref. to Tables in Att. 6
		1	2	3	4	5	6	7	8		BNR	BCD	DISC	SAL	
0 4 2	0 0 2	0 0	1 0	0	0	1 0	0	0	1 0	Set Longitude		X			
	0 0 4	0 0	1 0	0	0	0	1 0	0	0	Set Longitude		X			
	0 2 0	0 0	1 0	0	0	0	1 0	0	0	Set Longitude		X			
	0 5 6	0 0	1 0	0	0	0	1 0	0	0	Set Longitude		X			
	0 6 0	0 0	1 0	0	0	0	1 0	0	0	Set Longitude		X			
	0 A 4	0 0	1 0	0	0	0	1 0	0	0	Set Longitude		X			
0 4 3	0 0 2	0 0	1 0	0	0	0	1 1	1	0	Set Magnetic Heading		X			
	0 0 4	0 0	1 0	0	0	0	1 1	1	0	Set Magnetic Heading		X			
	0 2 0	0 0	1 0	0	0	0	1 1	1	0	Set Magnetic Heading		X			
	0 5 6	0 0	1 0	0	0	0	1 1	1	0	Set Magnetic Heading		X			
	0 6 0	0 0	1 0	0	0	0	1 1	1	0	Set Magnetic Heading		X			
	0 A 4	0 0	1 0	0	0	0	1 1	1	0	Set Magnetic Heading		X			
0 4 4	0 0 4	0 0	1 0	0	0	1 0	0	0	0	True Heading		X			
	0 3 8	0 0	1 0	0	0	1 0	0	0	0	True Heading		X			
0 4 5	0 0 3	0 0	1 0	0	0	1 0	0	1	0	Minimum Airspeed		X			
0 4 6	0 3 3	0 0	1 0	0	0	1 1	1	0	0	Engine Serial No. (LSDs)		X			6-15
	1 0 A	0 0	1 0	0	0	1 1	1	0	0	Engine Serial No. (LSDs)		X			6-15
	1 0 B	0 0	1 0	0	0	1 1	1	0	0	Engine Serial No. (LSDs)		X			6-15
0 4 7	0 2 0	0 0	1 0	0	0	1 1	1	1	0	VHF COM Frequency		X			
	0 2 4	0 0	1 0	0	0	1 1	1	1	0	VHF COM Frequency		X			
	0 3 3	0 0	1 0	0	0	1 1	1	1	0	Engine Serial No. (MSDs)		X			6-16
	0 B 6	0 0	1 0	0	0	1 1	1	1	0	VHF COM Frequency		X			
	1 0 A	0 0	1 0	0	0	1 1	1	1	0	Engine Serial No. (MSDs)		X			6-16
	1 0 B	0 0	1 0	0	0	1 1	1	1	0	Engine Serial No. (MSDs)		X			6-16
0 5 0	0	0 0	1 0	1	0	0	0	0	0	Spare					
0 5 1	0	0 0	1 0	1	0	0	0	0	1	Spare					
0 5 2	0 0 4	0 0	1 0	1	0	1	0	1	0	Body Pitch Acceleration	X				
	0 3 7	0 0	1 0	1	0	1	0	1	0	Longitude Zero Fuel CG		X			
	0 3 8	0 0	1 0	1	0	1	0	1	0	Body Pitch Acceleration	X				
0 5 3	0 0 4	0 0	1 0	1	0	1	0	1	1	Body Roll Acceleration	X				
	0 0 5	0 0	1 0	1	0	1	0	1	1	Track Angle - Magnetic		X			
	0 3 8	0 0	1 0	1	0	1	0	1	1	Body Roll Acceleration	X				
0 5 4	0 0 4	0 0	1 0	1	0	1	0	0	0	Body Yaw Acceleration	X				
	0 3 7	0 0	1 0	1	0	1	0	0	0	Zero Fuel Weight (KG)	X				
	0 3 8	0 0	1 0	1	0	1	0	0	0	Body Yaw Acceleration	X				
0 5 5	0	0 0	1 0	1	0	1	0	1	1	Spare					
0 5 6	0 0 2	0 0	1 0	1	0	1	1	0	0	Estimated Time of Arrival		X			
	0 0 5	0 0	1 0	1	0	1	1	0	0	Wind Direction - Magnetic		X			
	0 3 7	0 0	1 0	1	0	1	1	0	0	Gross Weight (KG)		X			
	0 5 6	0 0	1 0	1	0	1	1	0	0	ETA (Active Waypoint)		X			
	0 6 0	0 0	1 0	1	0	1	1	0	0	ETA (Active Waypoint)		X			
0 5 7	0	0 0	1 0	1	0	1	1	1	1	Spare					
0 6 0	0 2 5	0 0	1 1	1	0	0	0	0	0	S/G Hardware Part No		X			6-36
	0 3 7	0 0	1 1	1	0	0	0	0	0	Tire Loading (Left Body Main)		X			
	0 3 C	0 0	1 1	1	0	0	0	0	0	Tire Pressure (Left Inner)	X				
0 6 1	0 0 2	0 0	1 1	1	0	0	0	1	0	ACMS Information	X				6-29
	0 0 B	0 0	1 1	1	0	0	0	1	0	Pseudo Range	X				
	0 2 5	0 0	1 1	1	0	0	0	1	0	S/G Software Configuration Part No.		X			6-37
	0 3 7	0 0	1 1	1	0	0	0	1	0	Tire Loading (Right Body Main)		X			
	0 3 C	0 0	1 1	1	0	0	0	1	0	Tire Pressure (Left Outer)	X				
	0 5 6	0 0	1 1	1	0	0	0	1	0	ACMS Information	X				
0 6 2	0 6 0	0 0	1 1	1	0	0	0	1	0	ACMS Information	X				
	0 0 2	0 0	1 1	1	0	0	1	0	0	ACMS Information	X				6-29
	0 0 B	0 0	1 1	1	0	0	1	0	0	Pseudo Range Fine	X				
	0 3 7	0 0	1 1	1	0	0	1	0	0	Tire Loading (Left Wing Main)		X			
	0 3 C	0 0	1 1	1	0	0	1	0	0	Tire Pressure (Right Inner)	X				
	0 5 6	0 0	1 1	1	0	0	1	0	0	ACMS Information	X				
0 6 3	0 6 0	0 0	1 1	1	0	0	1	0	0	ACMS Information	X				
	0 0 2	0 0	1 1	1	0	0	1	1	0	ACMS Information	X				6-29
	0 0 B	0 0	1 1	1	0	0	1	1	0	Range Rate	X				
	0 3 7	0 0	1 1	1	0	0	1	1	0	Tire Loading (Right Wing Main)		X			
	0 3 C	0 0	1 1	1	0	0	1	1	0	Tire Pressure (Right Outer)	X				
	0 5 6	0 0	1 1	1	0	0	1	1	0	ACMS Information	X				
0 6 4	0 6 0	0 0	1 1	1	0	0	1	1	0	ACMS Information	X				
	0 0 B	0 0	1 1	1	0	1	0	0	0	Delta Range	X				
	0 3 7	0 0	1 1	1	0	1	0	0	0	Tire Loading (Nose)		X			
	0 3 C	0 0	1 1	1	0	1	0	0	0	Tire Pressure (Nose)	X				

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Code No. (Octal)	Eqpt. ID (Hex)	Transmission Order Bit Position								Parameter	Data				Notes & Cross Ref. to Tables in Att. 6
		1	2	3	4	5	6	7	8		BNR	BCD	DISC	SAL	
0 6 5	0 0 3	0 0		1 1	0		1 0	1		Gross Weight		X			
	0 0 B	0 0		1 1	0		1 0	1		SV Position X	X				
	0 3 7	0 0		1 1	0		1 0	1		Gross Weight		X			
0 6 6	0 0 2	0 0		1 1	0		1 1	0		Longitudinal Center of Gravity		X			
	0 0 B	0 0		1 1	0		1 1	0		SV Position X Fine	X				
	0 3 7	0 0		1 1	0		1 1	0		Longitudinal Center of Gravity		X			
0 6 7	0 3 7	0 0		1 1	0		1 1	1		Lateral Center of Gravity		X			
0 7 0	0 0 2	0 0		1 1	1		0 0	0		Reference Airspeed (Vref)	X				
	0 0 B	0 0		1 1	1		0 0	0		SV Position Y	X				
	0 2 9	0 0		1 1	1		0 0	0		AC Frequency (Engine)	X				
	0 3 7	0 0		1 1	1		0 0	0		Hard landing Magnitude #1	X				
	0 5 6	0 0		1 1	1		0 0	0		Reference Airspeed (Vref)	X				
	0 6 0	0 0		1 1	1		0 0	0		Reference Airspeed (Vref)	X				
	0 C C	0 0		1 1	1		0 0	0		Brakes - Metered Hydraulic Pressure L (Normal)	X				
0 7 1	0 0 2	0 0		1 1	1		0 0	1		Take-Off Climb Airspeed (V2)	X				
	0 0 B	0 0		1 1	1		0 0	1		SV Position Y Fine	X				
	0 2 9	0 0		1 1	1		0 0	1		AC Frequency (Alt. Sources)	X				
	0 3 3	0 0		1 1	1		0 0	1		VBV	X				
	0 3 7	0 0		1 1	1		0 0	1		Hard Landing Magnitude #2	X				
	0 C C	0 0		1 1	1		0 0	1		Brakes - Metered Hydraulic Pressure L (Alt)	X				
0 7 2	0 0 2	0 0		1 1	1		0 1	0		VR (Rotation Speed)	X				
	0 0 B	0 0		1 1	1		0 1	0		SV Position Z	X				
	0 1 C	0 0		1 1	1		0 1	0		Stator Vane Angle	X				
	0 2 9	0 0		1 1	1		0 1	0		AC Voltage (Engine)	X				
	0 2 F	0 0		1 1	1		0 1	0		Stator Vane Angle	X				
	0 3 3	0 0		1 1	1		0 1	0		Stator Vane Angle	X				
	0 C C	0 0		1 1	1		0 1	0		Brakes - Metered Hydraulic Pressure R (Normal)	X				
0 7 3	0 0 2	0 0		1 1	1		0 1	1		V1 (Critical Engine Failure Speed)	X				
	0 0 B	0 0		1 1	1		0 1	1		SV Position Z Fine	X				
	0 1 C	0 0		1 1	1		0 1	1		Oil Quantity	X				
	0 2 9	0 0		1 1	1		0 1	1		Oil Quantity	X				
	0 A 2	0 0		1 1	1		0 1	1		V2 (Critical Engine Failure Speed)	X				
	0 C C	0 0		1 1	1		0 1	1		Brakes - Metered Hydraulic Pressure R (Alt.)	X				
	0 D 0	0 0		1 1	1		0 1	1		Engine Oil Quantity	X				
0 7 4	0 0 2	0 0		1 1	1		1 0	0		Zero Fuel Weight	X				
	0 0 B	0 0		1 1	1		1 0	0		UTC Measure Time	X				
	0 2 C	0 0		1 1	1		1 0	0		Zero Fuel Weight	X				
	0 3 3	0 0		1 1	1		1 0	0		LP Compressor Bleed Position (3.0)	X				
	0 3 7	0 0		1 1	1		1 0	0		Zero Fuel Weight (lb)	X				
	0 5 6	0 0		1 1	1		1 0	0		Zero Fuel Weight	X				
	0 6 0	0 0		1 1	1		1 0	0		Zero Fuel Weight	X				
	1 1 4	0 0		1 1	1		1 0	0		Zero Fuel Weight	X				
0 7 5	0 0 2	0 0		1 1	1		1 0	1		Gross Weight	X				
	0 0 3	0 0		1 1	1		1 0	1		Gross Weight	X				
	0 0 8	0 0		1 1	1		1 0	1		Maximum Hazard Alert Level Output			X		
	0 0 B	0 0		1 1	1		1 0	1		Geodetic Altitude	X				
	0 2 9	0 0		1 1	1		1 0	1		AC Voltage (Alt. Sources)	X				
	0 2 C	0 0		1 1	1		1 0	1		Gross Weight	X				
	0 3 7	0 0		1 1	1		1 0	1		Gross Weight	X				
	0 3 E	0 0		1 1	1		1 0	1		Gross Weight	X				
	1 1 4	0 0		1 1	1		1 0	1		Aircraft Gross Weight	X				
0 7 6	0 0 8	0 0		1 1	1		1 1	0		Hazard Azimuth Output			X		
	0 0 B	0 0		1 1	1		1 1	0		GNSS Altitude (MSL)	X				
	0 2 9	0 0		1 1	1		1 1	0		AC Voltage (Bus Bar)	X				
	0 3 7	0 0		1 1	1		1 1	0		Longitudinal Center of Gravity	X				
	0 3 E	0 0		1 1	1		1 1	0		Longitudinal Center of Gravity	X				
	1 1 4	0 0		1 1	1		1 1	0		Aircraft Longitudinal Center of Gravity	X				

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Code No. (Octal)	Eqpt. ID (Hex)	Transmission Order Bit Position								Parameter	Data				Notes & Cross Ref. to Tables in Att. 6
		1	2	3	4	5	6	7	8		BNR	BCD	DISC	SAL	
0 7 7	0 0 2	0 0	1 1 1	1 1 1	1 1 1	1 1 1	Target Airspeed			X					
	0 0 8	0 0	1 1 1	1 1 1	1 1 1	1 1 1	Hazard Azimuth Output						X		
	0 0 B	0 0	1 1 1	1 1 1	1 1 1	1 1 1	GPS Hor/Vert Deviation			X					
	0 2 9	0 0	1 1 1	1 1 1	1 1 1	1 1 1	AC Load (Engine)			X					
	0 3 7	0 0	1 1 1	1 1 1	1 1 1	1 1 1	Lateral Center of Gravity			X					
	0 5 6	0 0	1 1 1	1 1 1	1 1 1	1 1 1	Target Airspeed			X					
	0 6 0	0 0	1 1 1	1 1 1	1 1 1	1 1 1	Target Airspeed			X					
	1 1 4	0 0	1 1 1	1 1 1	1 1 1	1 1 1	Zero Fuel Center of Gravity			X					
1 0 0	0 0 1	0 1	0 0 0	0 0 0	0 0 0	0 0 0	Selected Course #1			X					6-27
	0 0 2	0 1	0 0 0	0 0 0	0 0 0	0 0 0	Selected Course #1			X					
	0 1 1	0 1	0 0 0	0 0 0	0 0 0	0 0 0	Selected Course #1			X					
	0 2 0	0 1	0 0 0	0 0 0	0 0 0	0 0 0	Selected Course #1			X					
	0 2 9	0 1	0 0 0	0 0 0	0 0 0	0 0 0	AC Load (Alt. Source)			X					
	0 3 7	0 1	0 0 0	0 0 0	0 0 0	0 0 0	Gross Weight (Kilogram)			X					
	0 5 6	0 1	0 0 0	0 0 0	0 0 0	0 0 0	Selected Course #1			X					
	0 6 0	0 1	0 0 0	0 0 0	0 0 0	0 0 0	Selected Course #1			X					
	0 A 1	0 1	0 0 0	0 0 0	0 0 0	0 0 0	Selected Course #1			X					
	0 B 1	0 1	0 0 0	0 0 0	0 0 0	0 0 0	Selected Course #1			X					
	0 B B	0 1	0 0 0	0 0 0	0 0 0	0 0 0	Outbound Flaps - PDU			X					
1 0 1	0 0 2	0 1	0 0 0	0 0 0	0 0 0	0 0 1	Selected Heading			X					6-27
	0 0 B	0 1	0 0 0	0 0 0	0 0 0	0 0 1	HDOP			X					
	0 2 0	0 1	0 0 0	0 0 0	0 0 0	0 0 1	Selected Heading			X					
	0 2 5	0 1	0 0 0	0 0 0	0 0 0	0 0 1	Selected Heading			X					
	0 2 9	0 1	0 0 0	0 0 0	0 0 0	0 0 1	DC Current (TRU)			X					
	0 5 A	0 1	0 0 0	0 0 0	0 0 0	0 0 1	FQIC			X					
	0 A 1	0 1	0 0 0	0 0 0	0 0 0	0 0 1	Selected Heading			X					
	0 B B	0 1	0 0 0	0 0 0	0 0 0	0 0 1	Inboard Flaps - PDU			X					
	1 1 4	0 1	0 0 0	0 0 0	0 0 0	0 0 1	C/G Target			X					
1 0 2	0 0 2	0 1	0 0 0	0 0 0	0 0 0	0 1 0	Selected Altitude			X					6-27
	0 0 B	0 1	0 0 0	0 0 0	0 0 0	0 1 0	VDOP			X					
	0 2 0	0 1	0 0 0	0 0 0	0 0 0	0 1 0	Selected Altitude			X					
	0 2 9	0 1	0 0 0	0 0 0	0 0 0	0 1 0	DC Current (Battery)			X					
	0 5 6	0 1	0 0 0	0 0 0	0 0 0	0 1 0	Selected Altitude			X					
	0 6 0	0 1	0 0 0	0 0 0	0 0 0	0 1 0	Selected Altitude			X					
	0 A 1	0 1	0 0 0	0 0 0	0 0 0	0 1 0	Selected Altitude			X					
1 0 3	0 0 1	0 1	0 0 0	0 0 0	0 0 0	0 1 1	Selected Airspeed			X					6-27
	0 0 2	0 1	0 0 0	0 0 0	0 0 0	0 1 1	Selected Airspeed			X					
	0 0 3	0 1	0 0 0	0 0 0	0 0 0	0 1 1	Selected Airspeed			X					
	0 0 B	0 1	0 0 0	0 0 0	0 0 0	0 1 1	GNSS Track Angle			X					
	0 1 B	0 1	0 0 0	0 0 0	0 0 0	0 1 1	Left/PDU Flap			X					
	0 2 0	0 1	0 0 0	0 0 0	0 0 0	0 1 1	Selected Airspeed			X					
	0 2 9	0 1	0 0 0	0 0 0	0 0 0	0 1 1	DC Voltage (TRU)			X					
	0 5 6	0 1	0 0 0	0 0 0	0 0 0	0 1 1	Selected Airspeed			X					
	0 6 0	0 1	0 0 0	0 0 0	0 0 0	0 1 1	Selected Airspeed			X					
	0 A 1	0 1	0 0 0	0 0 0	0 0 0	0 1 1	Selected Airspeed			X					
	0 B B	0 1	0 0 0	0 0 0	0 0 0	0 1 1	Left Outboard Flap Position			X					
1 0 4	0 0 1	0 1	0 0 0	0 0 0	0 0 0	1 0 0	Selected Vertical Speed			X					6-27
	0 0 2	0 1	0 0 0	0 0 0	0 0 0	1 0 0	Selected Vertical Speed			X					
	0 1 B	0 1	0 0 0	0 0 0	0 0 0	1 0 0	Right/PDU Flap			X					
	0 2 0	0 1	0 0 0	0 0 0	0 0 0	1 0 0	Selected Vertical Speed			X					
	0 2 9	0 1	0 0 0	0 0 0	0 0 0	1 0 0	DC Voltage (Battery)			X					
	0 2 B	0 1	0 0 0	0 0 0	0 0 0	1 0 0	Selected Vertical Speed			X					
	0 5 6	0 1	0 0 0	0 0 0	0 0 0	1 0 0	Selected Vertical Speed			X					
	0 6 0	0 1	0 0 0	0 0 0	0 0 0	1 0 0	Selected Vertical Speed			X					
	0 A 1	0 1	0 0 0	0 0 0	0 0 0	1 0 0	Selected Vertical Speed			X					
	0 B B	0 1	0 0 0	0 0 0	0 0 0	1 0 0	Right Outboard Flap Position			X					

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Code No. (Octal)	Eqpt. ID (Hex)	Transmission Order Bit Position								Parameter	Data				Notes & Cross Ref. to Tables in Att. 6
		1	2	3	4	5	6	7	8		BNR	BCD	DISC	SAL	
1 0 5	0 0 2	0 1	0 0 0	1 0 1	Selected Runway Heading						X				
	0 1 0	0 1	0 0 0	1 0 1	Selected Runway Heading						X				
	0 1 B	0 1	0 0 0	1 0 1	Left/PDU Slat						X				
	0 2 0	0 1	0 0 0	1 0 1	Selected Runway Heading						X				
	0 2 9	0 1	0 0 0	1 0 1	Oil Temperature Input (IDG/CSD)						X				
	0 5 5	0 1	0 0 0	1 0 1	Selected Runway Heading						X				
	0 5 6	0 1	0 0 0	1 0 1	Selected Runway Heading						X				
	0 6 0	0 1	0 0 0	1 0 1	Selected Runway Heading						X				
	0 A 1	0 1	0 0 0	1 0 1	Selected Runway Heading						X				
	0 B 0	0 1	0 0 0	1 0 1	Selected Runway Heading						X				
1 0 6	0 B B	0 1	0 0 0	1 0 1	Left Inboard Flap Position						X				6-27
	0 0 2	0 1	0 0 0	1 1 0	Selected Mach						X				
	0 1 B	0 1	0 0 0	1 1 0	Right/PDU Slat						X				
	0 2 0	0 1	0 0 0	1 1 0	Selected Mach						X				
	0 2 9	0 1	0 0 0	1 1 0	Oil Temperature Input (IDG/CSD)						X				
	0 5 6	0 1	0 0 0	1 1 0	Selected Mach						X				
	0 6 0	0 1	0 0 0	1 1 0	Selected Mach						X				
	0 A 1	0 1	0 0 0	1 1 0	Selected Mach						X				
1 0 7	0 B B	0 1	0 0 0	1 1 0	Right Inboard Flap Position						X				
	0 0 2	0 1	0 0 0	1 1 1	Selected Cruise Altitude						X				
	0 1 B	0 1	0 0 0	1 1 1	Flap/Slat Lever						X				
	0 3 7	0 1	0 0 0	1 1 1	Longitude Zero Fuel C/G						X				
	0 5 6	0 1	0 0 0	1 1 1	Selected Cruise Altitude						X				
	0 6 0	0 1	0 0 0	1 1 1	Selected Cruise Altitude						X				
1 1 0	0 B B	0 1	0 0 0	1 1 1	Flap Lever Position - Median Value						X				
	0 0 1	0 1	0 0 1	0 0 0	Selected Course #2						X				
	0 0 2	0 1	0 0 1	0 0 0	Selected Course #2						X				
	0 0 B	0 1	0 0 1	0 0 0	GNSS Latitude						X				
	0 1 0	0 1	0 0 1	0 0 0	Selected Course #2						X				
	0 1 1	0 1	0 0 1	0 0 0	Selected Course #2						X				
	0 2 0	0 1	0 0 1	0 0 0	Selected Course #2						X				
	0 A 1	0 1	0 0 1	0 0 0	Selected Course #2						X				
1 1 1	0 B 1	0 1	0 0 1	0 0 0	Selected Course #2						X				
	0 B B	0 1	0 0 1	0 0 0	Flap Lever Position - Center						X				
	0 0 1	0 1	0 0 1	0 0 1	Test Word A						X		X		
1 1 2	0 0 B	0 1	0 0 1	0 0 1	GNSS Longitude						X				
	0 1 D	0 1	0 0 1	0 0 1	Test Word A								X		
	0 0 2	0 1	0 0 1	0 1 0	Runway Length						X				
	0 0 B	0 1	0 0 1	0 1 0	GNSS Ground Speed						X				
	0 A 1	0 1	0 0 1	0 1 0	Selected EPR						X				
1 1 3	0 A 1	0 1	0 0 1	0 1 0	Selected N1						X				
	0 B B	0 1	0 0 1	0 1 0	Flap Lever Position - Left										
	0	0 1	0 0 1	0 1 1	Spare										
	0 0 2	0 1	0 0 1	1 0 0	Desired Track						X				6-27
	0 2 9	0 1	0 0 1	1 0 0	Brake Temperature (Left Inner L/G)						X				
1 1 4	0 2 F	0 1	0 0 1	1 0 0	Ambient Pressure						X				
	0 3 F	0 1	0 0 1	1 0 0	Pamb Sensor						X				
	0 5 6	0 1	0 0 1	1 0 0	Desired Track						X				
	0 6 0	0 1	0 0 1	1 0 0	Desired Track						X				
	0 B B	0 1	0 0 1	1 0 0	Flap Lever Position - Right						X				
	0 C C	0 1	0 0 1	1 0 0	Wheel Torque Output						X				
	1 0 A	0 1	0 0 1	1 0 0	Selected Ambient Static Pressure						X				
	1 0 B	0 1	0 0 1	1 0 0	Selected Ambient Static Pressure						X				
	1 3 A	0 1	0 0 1	1 0 0	Ambient Pressure						X				
1 1 5	0 0 2	0 1	0 0 1	1 0 1	Waypoint Bearing						X				
	0 2 9	0 1	0 0 1	1 0 1	Brake Temperature (Left Outer L/G)						X				
	0 2 F	0 1	0 0 1	1 0 1	Fuel Temperature						X				
	0 3 F	0 1	0 0 1	1 0 1	Fuel Temperature						X				
	0 5 6	0 1	0 0 1	1 0 1	Waypoint Bearing						X				
	0 6 0	0 1	0 0 1	1 0 1	Waypoint Bearing						X				
	0 B C	0 1	0 0 1	1 0 1	Fuel Temperature						X				
	0 C C	0 1	0 0 1	1 0 1	Wheel Torque Output						X				
1 1 6	0 0 2	0 1	0 0 1	1 1 0	Cross Track Distance						X				6-27
	0 0 B	0 1	0 0 1	1 1 0	Horizontal GLS Deviation Rectilinear						X				
	0 2 9	0 1	0 0 1	1 1 0	Brake Temperature (Right Inner L/G)						X				
	0 5 5	0 1	0 0 1	1 1 0	Horizontal GLS Deviation Rectilinear						X				
	0 5 6	0 1	0 0 1	1 1 0	Cross Track Distance						X				
	0 6 0	0 1	0 0 1	1 1 0	Cross Track Distance						X				
	0 C C	0 1	0 0 1	1 1 0	Wheel Torque Output						X				
															6-26

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Code No. (Octal)	Eqpt. ID (Hex)	Transmission Order Bit Position								Parameter	Data				Notes & Cross Ref. to Tables in Att. 6
		1	2	3	4	5	6	7	8		BNR	BCD	DISC	SAL	
1 1 7	0 0 2	0	1	0	0	1	1	1	1	Vertical Deviation	X				6-27
	0 0 B	0	1	0	0	1	1	1	1	Vertical GLS Deviation Rectilinear	X				
	0 2 9	0	1	0	0	1	1	1	1	Brake Temperature (Right Inner L/G)	X				
	0 5 5	0	1	0	0	1	1	1	1	Vertical GLS Deviation Rectilinear	X				
	0 5 6	0	1	0	0	1	1	1	1	Vertical Deviation	X				
	0 6 0	0	1	0	0	1	1	1	1	Vertical Deviation	X				
	0 C C	0	1	0	0	1	1	1	1	Wheel Torque Output	X				6-26
1 2 0	0 0 2	0	1	0	1	0	0	0	0	Range to Altitude	X				
	0 0 B	0	1	0	1	0	0	0	0	GNSS Latitude Fine	X				
	0 2 9	0	1	0	1	0	0	0	0	Pack Bypass Turbine Position	X				
	0 5 6	0	1	0	1	0	0	0	0	Range to Altitude	X				
	0 6 0	0	1	0	1	0	0	0	0	Range to Altitude	X				
1 2 1	0 0 2	0	1	0	1	0	0	0	1	Horizontal Command Signal	X				
	0 0 B	0	1	0	1	0	0	0	1	GNSS Longitude Fine	X				
	0 2 5	0	1	0	1	0	0	0	1	Pitch Limit	X				
	0 2 9	0	1	0	1	0	0	0	1	Pack Outlet Temperature	X				
	0 5 6	0	1	0	1	0	0	0	1	Horizontal Command Signal	X				
	0 6 0	0	1	0	1	0	0	0	1	Horizontal Command Signal	X				
1 2 2	0 0 2	0	1	0	1	0	0	1	0	Vertical Command Signal	X				
	0 2 9	0	1	0	1	0	0	1	0	Pack Turbine Inlet Temperature	X				
	0 5 6	0	1	0	1	0	0	1	0	Vertical Command Signal	X				
	0 6 0	0	1	0	1	0	0	1	0	Vertical Command Signal	X				
1 2 3	0 0 2	0	1	0	1	0	0	1	1	Throttle Command	X				
1 2 4	0 0 B	0	1	0	1	0	0	1	1	Digital Time Mark			X		6-49
	0 A 5	0	1	0	1	0	0	1	1	Client Device for GNSS Receiver	X				
	1 E 2	0	1	0	1	0	1	0	0	Horizontal Alarm Limit	X				
1 2 5	0 0 2	0	1	0	1	0	1	0	1	Universal Time Coordinated (UTC)		X			6-25
	0 0 B	0	1	0	1	0	1	0	1	Universal Time Coordinated (UTC)		X			6-25
	0 3 1	0	1	0	1	0	1	0	1	Universal Time Coordinated (UTC)		X			
	0 5 6	0	1	0	1	0	1	0	1	Universal Time Coordinated (UTC)		X			
	0 6 0	0	1	0	1	0	1	0	1	Universal Time Coordinated (UTC)		X			
1 2 6	0 0 2	0	1	0	1	0	1	1	0	Vertical Deviation (wide)	X				
	0 2 6	0	1	0	1	0	1	1	0	FWC Word	X				
	0 2 9	0	1	0	1	0	1	1	0	Pack Flow	X				
	0 5 6	0	1	0	1	0	1	1	0	Vertical Deviation (Wide)	X				
	0 6 0	0	1	0	1	0	1	1	0	Vertical Deviation (Wide)	X				
1 2 7	0 0 2	0	1	0	1	0	1	1	1	Selected Landing Altitude	X				6-11
	0 1 B	0	1	0	1	0	1	1	1	Slat Angle	X				
	0 3 3	0	1	0	1	0	1	1	1	P14	X				
	1 0 A	0	1	0	1	0	1	1	1	Fan Discharge Static Pressure	X				6-50
	1 0 B	0	1	0	1	0	1	1	1	Fan Discharge Static Pressure	X				
	1 E 2	0	1	0	1	0	1	1	1	Vertical Alarm Limit	X				
1 3 0	0 0 B	0	1	0	1	1	0	0	0	Aut Horiz Integ Limit	X				6-21
	0 1 A	0	1	0	1	1	0	0	0	Fan Inlet Total Temperature	X				
	0 1 C	0	1	0	1	1	0	0	0	Fan Inlet Total Temperature	X				
	0 2 F	0	1	0	1	1	0	0	0	Fan Inlet Total Temperature	X				
	0 3 5	0	1	0	1	1	0	0	0	Intruder Range	X				
	0 3 F	0	1	0	1	1	0	0	0	Fan Inlet Total Temperature	X				
	1 0 A	0	1	0	1	1	0	0	0	Selected Total Air Temperature	X				
	1 0 B	0	1	0	1	1	0	0	0	Selected Total Air Temperature	X				
	1 3 A	0	1	0	1	1	0	0	0	Inlet Temperature	X				
1 3 1	0 1 A	0	1	0	1	1	0	0	1	Fan Inlet Total Pressure	X				6-22
	0 1 C	0	1	0	1	1	0	0	1	Fan Inlet Total Pressure	X				
	0 2 D	0	1	0	1	1	0	0	1	Fan Inlet Total Pressure	X				
	0 2 F	0	1	0	1	1	0	0	1	Fan Inlet Total Pressure	X				
	0 3 3	0	1	0	1	1	0	0	1	Fan Inlet Total Pressure	X				
	0 3 5	0	1	0	1	1	0	0	1	Intruder Altitude	X				
	1 3 A	0	1	0	1	1	0	0	1	Inlet Pressure	X				
1 3 2	0 1 A	0	1	0	1	1	0	1	0	Exhaust Gas Total Pressure	X				6-23
	0 1 C	0	1	0	1	1	0	1	0	Exhaust Gas Total Pressure	X				
	0 3 3	0	1	0	1	1	0	1	0	Exhaust Gas Total Pressure	X				
	0 3 5	0	1	0	1	1	0	1	0	Intruder Bearing	X				
1 3 3	0 0 B	0	1	0	1	1	0	1	1	Aut Horiz Integ Limit	X				
	0 1 A	0	1	0	1	1	0	1	1	Thrust Lever Angle	X				
	0 2 F	0	1	0	1	1	0	1	1	Thrust Lever Angle	X				
	0 3 F	0	1	0	1	1	0	1	1	Thrust Lever Angle	X				
	1 0 A	0	1	0	1	1	0	1	1	Selected Throttle Lever Angle	X				
	1 0 B	0	1	0	1	1	0	1	1	Selected Throttle Lever Angle	X				

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Code No. (Octal)	Eqpt. ID (Hex)	Transmission Order Bit Position								Parameter	Data				Notes & Cross Ref. to Tables in Att. 6
		1	2	3	4	5	6	7	8		BNR	BCD	DISC	SAL	
1 3 4	0 1 C	0	1	0	1	1	1	0	0	Power Lever Angle	X				
	1 0 A	0	1	0	1	1	1	0	0	Throttle Lever Angle	X				
	1 0 B	0	1	0	1	1	1	0	0	Throttle Lever Angle	X				
	1 3 A	0	1	0	1	1	1	0	0	Throttle Lever Angle	X				
1 3 5	0 1 C	0	1	0	1	1	1	0	1	Engine Vibration #1	X				
	0 2 9	0	1	0	1	1	1	0	1	Engine Fan Vibration	X				
	0 5 A	0	1	0	1	1	1	0	1	ACT 1 Fuel Quantity Display		X			
1 3 6	0 0 B	0	1	0	1	1	1	1	0	Vertical Figure of Merit	X				
	0 1 C	0	1	0	1	1	1	1	0	Engine Vibration #2	X				
	0 2 9	0	1	0	1	1	1	1	0	Engine Turbine Vibration	X				
	0 5 A	0	1	0	1	1	1	1	0	ACT 2 Fuel Quantity Display		X			
1 3 7	0 1 B	0	1	0	1	1	1	1	1	Flap Angle	X				6-11
	0 2 A	0	1	0	1	1	1	1	1	Flap Angle	X				6-11
	0 2 F	0	1	0	1	1	1	1	1	Thrust Reverser Position Feedback	X				
	0 3 F	0	1	0	1	1	1	1	1	Thrust Reverser Position Feedback	X				
	0 5 A	0	1	0	1	1	1	1	1	Center+ACT1+ACT2 FQ Display		X			
	1 0 A	0	1	0	1	1	1	1	1	Selected Thrust Reverser Position	X				
	1 0 B	0	1	0	1	1	1	1	1	Selected Thrust Reverser Position	X				
	1 4 0	0	1	0	1	1	1	1	1	Flap Angle	X				6-11
1 4 0	0 0 1	0	1	1	0	0	0	0	0	Flight Director - Roll	X				6-27
	0 0 B	0	1	1	0	0	0	0	0	UTC Fine	X				
	0 2 5	0	1	1	0	0	0	0	0	Flight Director - Roll	X				
	0 2 9	0	1	1	0	0	0	0	0	Precooler Output Temperature	X				
	0 5 A	0	1	1	0	0	0	0	0	Actual Fuel Quantity Display		X			
	1 1 4	0	1	1	0	0	0	0	0	Pump Contactor States			X		
1 4 1	0 0 1	0	1	1	0	0	0	0	1	Flight Director - Pitch	X				6-27
	0 0 B	0	1	1	0	0	0	0	1	UTC Fine Fractions	X				
	0 2 5	0	1	1	0	0	0	0	1	Flight Director - Pitch	X				
	0 2 9	0	1	1	0	0	0	0	1	Precooler Input Temperature	X				
	0 5 A	0	1	1	0	0	0	0	1	Preselected Fuel Quantity Display		X			
	1 1 4	0	1	1	0	0	0	0	1	Pump Contactor and Pushbutton States			X		
1 4 2	0 0 2	0	1	1	0	0	0	1	0	Flight Director - Fast/Slow	X				6-27
	0 0 3	0	1	1	0	0	0	1	0	Flight Director - Fast/Slow	X				
	0 0 B	0	1	1	0	0	0	1	0	UTC Fine Fractions	X				
	0 2 5	0	1	1	0	0	0	1	0	Flight Director - Fast/Slow	X				
	0 5 A	0	1	1	0	0	0	1	0	Left Wing Fuel Quantity Display		X			
	1 1 4	0	1	1	0	0	0	1	0	Pump Push Button and LP Switch State			X		
1 4 3	0 0 1	0	1	1	0	0	0	1	1	Flight Director - Yaw	X				
	0 4 1	0	1	1	0	0	0	1	1	HPA Command Word	X				
	0 5 A	0	1	1	0	0	0	1	1	Center Wing Fuel Quantity Display		X			
	1 1 4	0	1	1	0	0	0	1	1	Pump LP Switch State and FCMC Commands			X		
1 4 4	2 4 1	0	1	1	0	0	0	1	1	HPA Response Word	X				
	0 2 B	0	1	1	0	0	1	0	0	Altitude Error	X				
	0 4 1	0	1	1	0	0	1	0	0	ACU/BSU Control Word	X				
	0 5 A	0	1	1	0	0	1	0	0	Right Wing Fuel Quantity Display		X			
	1 1 4	0	1	1	0	0	1	0	0	Valve Feedback			X		
1 4 5	3 4 1	0	1	1	0	0	1	0	0	ACU/BSU Control Word	X				
	0 0 2	0	1	1	0	0	1	0	1	TACAN Control	X				6-30
	0 2 5	0	1	1	0	0	1	0	1	Discrete Status 2 EFIS			X		
	0 2 9	0	1	1	0	0	1	0	1	Discrete Status 2 EFIS			X		
	0 A 1	0	1	1	0	0	1	0	1	AFS DFDR Discretes #1			X		
1 4 6	1 1 4	0	1	1	0	0	1	0	1	Valve Feedback			X		
	0 2 5	0	1	1	0	0	1	1	0	Discrete Status 3 EFIS			X		
	0 2 9	0	1	1	0	0	1	1	0	Discrete Data #9			X		
	0 A 1	0	1	1	0	0	1	1	0	AFS DFDR Discretes #2			X		
	1 1 2	0	1	1	0	0	1	1	0	TACAN Control	X				6-47
1 4 7	1 1 4	0	1	1	0	0	1	1	0	Valve Feedback			X		
	1 1 5	0	1	1	0	0	1	1	1	TACAN Control Word			X		
	0 2 5	0	1	1	0	0	1	1	1	Discrete Status 4 EFIS			X		
	0 2 9	0	1	1	0	0	1	1	1	Discrete Data #10			X		
	0 A 1	0	1	1	0	0	1	1	1	AFS DFDR Discretes #3			X		
1 5 0	1 1 4	0	1	1	0	0	1	1	1	Valve Feedback			X		
	0 0 2	0	1	1	0	1	0	0	0	Universal Time Constant (UTC)	X				6-48/Note 1
	0 0 B	0	1	1	0	1	0	0	0	Universal Time Constant (UTC)	X				6-12/6-27
	0 2 9	0	1	1	0	1	0	0	0	Cabin Altitude Rate	X				
	0 3 1	0	1	1	0	1	0	0	0	Universal Time Constant (UTC)	X				6-12/6-27
	0 5 6	0	1	1	0	1	0	0	0	Universal Time Coordinate	X				
	0 6 0	0	1	1	0	1	0	0	0	Universal Time Coordinate	X				
	1 1 4	0	1	1	0	1	0	0	0	FCMC Valve Commands			X		

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Code No. (Octal)	Eqpt. ID (Hex)	Transmission Order Bit Position						Parameter	Data				Notes & Cross Ref. to Tables in Att. 6		
		1	2	3	4	5	6		7	8	BNR	BCD		DISC	SAL
1 5 1	0 0 2	0	1	1	0	1	0	0	1	Localizer Bearing (True)	X				
	0 2 7	0	1	1	0	1	0	0	1	MLS Azimuth Deviation	X				
	0 2 9	0	1	1	0	1	0	0	1	Cabin Altitude	X				
	0 5 5	0	1	1	0	1	0	0	1	MLS Azimuth Deviation	X				
	0 5 6	0	1	1	0	1	0	0	1	Localizer Bearing (True)	X				
	0 5 A	0	1	1	0	1	0	0	1	LB/KG Control Word		X			
	0 6 0	0	1	1	0	1	0	0	1	Localizer Bearing (True)	X				
	1 1 4	0	1	1	0	1	0	0	1	FCMC Valve Commands			X		
1 5 2	0 2 7	0	1	1	0	1	0	1	0	MLS Elevation Deviation	X				
	0 2 9	0	1	1	0	1	0	1	0	Cabin Pressure	X				
	0 3 8	0	1	1	0	1	0	1	0	Cabin Pressure	X				
	0 4 1	0	1	1	0	1	0	1	0	Open Loop Steering	X				
	0 5 5	0	1	1	0	1	0	1	0	MLS GP Deviation	X				
	0 A D	0	1	1	0	1	0	1	0	Cabin Pressure	X				
	1 1 4	0	1	1	0	1	0	1	0	Overhead Panel Switch/Pushbutton & Refuel Panel Battery Power Supply Switch States			X		
		0	1	1	0	1	0	1	0	777 Cabin Interphone System - System Address Label				X	See Attachment 11
1 5 3	0 0 2	0	1	1	0	1	0	1	1	Maximum Altitude	X				
	0 2 7	0	1	1	0	1	0	1	1	Flare	X				
	0 2 9	0	1	1	0	1	0	1	1	Pressurization Valve Position (Gr. #1)	X				
	0 4 1	0	1	1	0	1	0	1	1	Closed Loop Steering	X				
	0 5 5	0	1	1	0	1	0	1	1	MLS Selected Azimuth	X				
	1 1 4	0	1	1	0	1	0	1	1	Level States			X		
1 5 4	0 0 2	0	1	1	0	1	1	0	0	Runway Heading (True)	X				
	0 2 7	0	1	1	0	1	1	0	0	MLS Auxilliary Data	X				
	0 2 9	0	1	1	0	1	1	0	0	Pressurization Valve Position (Gr. #2)	X				
	0 5 5	0	1	1	0	1	1	0	0	MLS Max Selectable GP	X				
	0 5 6	0	1	1	0	1	1	0	0	Runway Heading (True)	X				
	0 6 0	0	1	1	0	1	1	0	0	Runway Heading (True)	X				
	1 1 4	0	1	1	0	1	1	0	0	Level States and Low Warning and Transfer Indications			X		
1 5 5	0 1 C	0	1	1	0	1	1	0	1	Maintenance Data #6			X		
	0 2 5	0	1	1	0	1	1	0	1	Discrete Status 5 EFIS		X		X	
	0 2 7	0	1	1	0	1	1	0	1	MLS Selected GP Angle					
	0 2 9	0	1	1	0	1	1	0	1	Discrete #1			X		
	0 3 3	0	1	1	0	1	1	0	1	Maintenance Data #6			X		
	0 5 5	0	1	1	0	1	1	0	1	MLS Selected Glide Path	X				
	0 5 A	0	1	1	0	1	1	0	1	FQIC			X		
	0 B B	0	1	1	0	1	1	0	1	Maintenance Data #6			X		
	1 0 A	0	1	1	0	1	1	0	1	Maintenance Data #6			X		
	1 0 B	0	1	1	0	1	1	0	1	Maintenance Data #6			X		
1 1 4	0	1	1	0	1	1	0	1	XFR Pump Faults & Wing Imbalance Warning			X			
1 5 6	0 1 C	0	1	1	0	1	1	1	0	Maintnance Data #7			X		
	0 2 7	0	1	1	0	1	1	1	0	MLS Dataword 1	X				
	0 2 9	0	1	1	0	1	1	1	0	Discrete #12			X		
	0 3 3	0	1	1	0	1	1	1	0	Maintenance Data #7			X		
	0 4 D	0	1	1	0	1	1	1	0	L Tank Faults			X		
	0 5 5	0	1	1	0	1	1	1	0	MLS Basic Data Wd 1	X				
	0 B B	0	1	1	0	1	1	1	0	Maintenance Data #7			X		
	1 0 A	0	1	1	0	1	1	1	0	Maintenance Data #7			X		
	1 0 B	0	1	1	0	1	1	1	0	Maintenance Data #7			X		
	1 1 4	0	1	1	0	1	1	1	0	Refuel Panel Switch States			X		
	0	1	1	0	1	1	1	0	CVR #2 - System Address Label				X	See Attachment 11	
1 5 7	0 1 C	0	1	1	0	1	1	1	1	Maintenance Data #8	X				
	0 2 7	0	1	1	0	1	1	1	1	MLS Dataword 2			X		
	0 3 3	0	1	1	0	1	1	1	1	Maintenance Data #8			X		
	0 4 D	0	1	1	0	1	1	1	1	R Tank Faults			X		
	0 5 5	0	1	1	0	1	1	1	1	MLS Basic Data Wd 2	X				
	0 B B	0	1	1	0	1	1	1	1	Maintenance Data #8			X		
	1 0 A	0	1	1	0	1	1	1	1	Maintenance Data #8			X		
	1 0 B	0	1	1	0	1	1	1	1	Maintenance Data #8			X		
	1 1 4	0	1	1	0	1	1	1	1	Trim Tank Probe Capacitance		X			
		0	1	1	0	1	1	1	1	CVR #1 - System Address Label				X	See Attachment 11

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Code No. (Octal)	Eqpt. ID (Hex)	Transmission Order Bit Position								Parameter	Data				Notes & Cross Ref. to Tables in Att. 6
		1	2	3	4	5	6	7	8		BNR	BCD	DISC	SAL	
1 7 4	0 0 3	0	1	1	1	1	1	0	0	Delayed Flap Approach Speed (DFA)	X				6-6/6-27 6-6/6-27 See Attachment 11
	0 0 B	0	1	1	1	1	1	0	0	East/West Velocity	X				
	0 1 0	0	1	1	1	1	1	0	0	Glideslope Deviation	X				
	0 2 9	0	1	1	1	1	1	0	0	Hydraulic Pressure	X				
	0 3 B	0	1	1	1	1	1	0	0	Glideslope Deviation	X				
	0 5 5	0	1	1	1	1	1	0	0	Glideslope Deviation	X				
	0 D 0	0	1	1	1	1	1	0	0	Hydraulic Oil Pressure	X				
		0	1	1	1	1	1	0	0	RFU - System Address Label				X	
1 7 5	0 0 3	0	1	1	1	1	1	0	1	Economical Speed	X				See Attachment 11
	0 2 9	0	1	1	1	1	1	0	1	EGT (APU)	X				
	0 3 3	0	1	1	1	1	1	0	1	Hydraulic Pump Case Drain Temperature	X				
		0	1	1	1	1	1	0	1	HGA/IGA HPA - System Address Label				X	
1 7 6	0 0 3	0	1	1	1	1	1	1	0	Economical Mach	X				
	0 2 9	0	1	1	1	1	1	1	0	RPM (APU)	X				
	0 3 8	0	1	1	1	1	1	1	0	Left Static Pressure Uncorrected, mb	X				
	0 5 A	0	1	1	1	1	1	1	0	Fuel Temperature - Set to Zero	X				
	0 A D	0	1	1	1	1	1	1	0	Static Pressure Left, Uncorrected, mb	X				
	1 1 4	0	1	1	1	1	1	1	0	Left Outer Tank Fuel Temp & Advisory Warning	X				
1 7 7	0 0 3	0	1	1	1	1	1	1	1	Economical Flight Level	X				See Attachment 11
	0 2 9	0	1	1	1	1	1	1	1	Oil Quantity (APU)	X				
	0 3 8	0	1	1	1	1	1	1	1	Right Static Pressure Uncorrected, mb	X				
	0 5 5	0	1	1	1	1	1	1	1	Distance to LTP/FTP	X				
	0 5 A	0	1	1	1	1	1	1	1	Fuel Temperature Left Wing Tank	X				
	0 A D	0	1	1	1	1	1	1	1	Static Pressure Right, Uncorrected, mb	X				
	1 1 4	0	1	1	1	1	1	1	1	Inner Tank 1 Fuel Temp & Advisory Warning	X			X	
		0	1	1	1	1	1	1	1	LGA/HPA - System Address Label					
2 0 0	0 0 2	1	0	0	0	0	0	0	0	Drift Angle		X			
	0 0 4	1	0	0	0	0	0	0	0	Drift Angle		X			
	0 5 6	1	0	0	0	0	0	0	0	Drift Angle		X			
	0 6 0	1	0	0	0	0	0	0	0	Drift Angle		X			
	1 1 4	1	0	0	0	0	0	0	0	Inner Tank 2 Fuel Temp & Advisory Warning	X				
2 0 1	0 0 9	1	0	0	0	0	0	0	1	DME Distance		X			6-1-1 6-25 See Attachment 11
	0 5 A	1	0	0	0	0	0	0	1	Fuel Temperature Right Wing Tank	X				
	1 1 2	1	0	0	0	0	0	0	1	TACAN Distance		X			
	1 1 4	1	0	0	0	0	0	0	1	Inner Tank 3 Fuel Temp & Advisory Warning	X				
	1 1 5	1	0	0	0	0	0	0	1	DME		X			
	1 4 0	1	0	0	0	0	0	0	1	Mach Maximum Operation (Mmo)	X				
	1 4 2	1	0	0	0	0	0	0	1	Projected Future Latitude	X				
		1	0	0	0	0	0	0	1	GPS/GNSS Sensor - System Address Label				X	
2 0 2	0 0 2	1	0	0	0	0	0	1	0	Energy Management (clean)	X				6-7/6-27
	0 0 9	1	0	0	0	0	0	1	0	DME Distance	X				
	0 2 9	1	0	0	0	0	0	1	0	Cabin Compartment Temperature (Group #1)	X				
	0 5 A	1	0	0	0	0	0	1	0	Fuel Temperature - Set to Zero	X				
	1 1 4	1	0	0	0	0	0	1	0	Inner Tank 4 Fuel Temp & Advisory Warning	X				
	1 4 0	1	0	0	0	0	0	1	0	Mach Rate	X				
	1 4 2	1	0	0	0	0	0	1	0	Projected Future Latitude Fine	X				
2 0 3	0 0 2	1	0	0	0	0	0	1	1	Energy Management Speed Brakes	X				6-24/6-27
	0 0 6	1	0	0	0	0	0	1	1	Altitude (1013.25mB)	X				
	0 1 8	1	0	0	0	0	0	1	1	Altitude	X				
	0 2 9	1	0	0	0	0	0	1	1	Cabin Compartment Temperature (Group #2)	X				
	0 3 5	1	0	0	0	0	0	1	1	Own A/C Altitude	X				
	0 3 8	1	0	0	0	0	0	1	1	Altitude (1013.25mB)	X				
	0 5 A	1	0	0	0	0	0	1	1	Fuel Tank #6 Temperature	X				
	1 0 A	1	0	0	0	0	0	1	1	Ambient Static Pressure	X				
	1 0 B	1	0	0	0	0	0	1	1	Ambient Static Pressure	X				
	1 1 4	1	0	0	0	0	0	1	1	Trim Tank Fuel Temp & Advisory Warning	X				
	1 4 0	1	0	0	0	0	0	1	1	Altitude	X				
2 0 4	0 0 2	1	0	0	0	0	0	1	0	Utility Airspeed	X				
	0 0 6	1	0	0	0	0	0	1	0	Baro Corrected Altitude #1	X				
	0 2 9	1	0	0	0	0	0	1	0	Cabin Duct Temperature (Group #1)	X				
	0 3 8	1	0	0	0	0	0	1	0	Baro Corrected Altitude #1	X				
	0 5 6	1	0	0	0	0	0	1	0	Baro Altitude	X				
	0 5 A	1	0	0	0	0	0	1	0	Fuel Tank #7 Temperature	X				
	0 6 0	1	0	0	0	0	0	1	0	Baro Altitude	X				
	1 1 4	1	0	0	0	0	0	1	0	Right Outer Tank Fuel Temp & Advisory Warning	X				
	1 4 0	1	0	0	0	0	0	1	0	Baro Corrected Altitude	X				

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LABEL CODES

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Code No. (Octal)	Eqpt. ID (Hex)	Transmission Order Bit Position								Parameter	Data				Notes & Cross Ref. to Tables in Att. 6
		1	2	3	4	5	6	7	8		BNR	BCD	DISC	SAL	
2 0 5	0 0 2	1	0	0	0	0	1	0	1	HF COM Frequency (New Format)		X			6-43
	0 0 6	1	0	0	0	0	1	0	1	Mach	X				6-27
	0 1 A	1	0	0	0	0	1	0	1	Mach	X				6-27
	0 2 9	1	0	0	0	0	1	0	1	Cabin Duct Temperature (Group #2)	X				
	0 3 8	1	0	0	0	0	1	0	1	Mach	X				
	0 5 A	1	0	0	0	0	1	0	1	Fuel Tank #8 Temperature	X				
	0 B 9	1	0	0	0	0	1	0	1	HF COM Frequency (New Format)		X			
	1 0 A	1	0	0	0	0	1	0	1	Mach Number	X				
	1 0 B	1	0	0	0	0	1	0	1	Mach Number	X				
	1 4 0	1	0	0	0	0	1	0	1	Mach	X				
2 0 6	0 0 6	1	0	0	0	0	1	1	0	Computed Airspeed	X				6-27
	0 1 8	1	0	0	0	0	1	1	0	Altitude (Variable Resolution)	X				6-20
	0 2 9	1	0	0	0	0	1	1	0	Cabin Temp. Reg. Valve Position (Group #1)	X				
	0 3 8	1	0	0	0	0	1	1	0	Computed Airspeed	X				6-27
	0 5 6	1	0	0	0	0	1	1	0	Computed Airspeed	X				
	0 6 0	1	0	0	0	0	1	1	0	Computed Airspeed	X				
	0 C C	1	0	0	0	0	1	1	0	Taxi Speed	X				
	1 4 0	1	0	0	0	0	1	1	0	Computed Airspeed (CAS)	X				
2 0 7	0 0 2	1	0	0	0	0	1	1	1	HF Control Word			X		
	0 0 6	1	0	0	0	0	1	1	1	Max. Allowable Airspeed	X				
	0 0 A	1	0	0	0	0	1	1	1	Max. Allowable Airspeed	X				
	0 2 5	1	0	0	0	0	1	1	1	Operational Software Part Number		X			6-37
	0 2 9	1	0	0	0	0	1	1	1	Cabin Temp. Reg. Valve Position (Group #2)	X				
	0 3 8	1	0	0	0	0	1	1	1	Max. Allowable Airspeed	X				
	0 B 9	1	0	0	0	0	1	1	1	HF Control Word			X		
	1 4 0	1	0	0	0	0	1	1	1	Airspeed Maximum Operating (VMO)	X				
2 1 0	0 0 6	1	0	0	0	1	0	0	0	True Airspeed	X				6-27
	0 2 9	1	0	0	0	1	0	0	0	Cargo Compartment Temperature	X				
	0 3 8	1	0	0	0	1	0	0	0	True Airspeed	X				6-27
	1 4 0	1	0	0	0	1	0	0	0	True Airspeed	X				
		1	0	0	0	1	0	0	0	FCMC Com A340-500/600 - System Address Label				X	See Attachment 11
2 1 1	0 0 2	1	0	0	0	1	0	0	1	Total Air Temperature	X				6-27
	0 0 3	1	0	0	0	1	0	0	1	Total Air Temperature	X				
	0 0 6	1	0	0	0	1	0	0	1	Total Air Temperature	X				
	0 1 A	1	0	0	0	1	0	0	1	Total Air Temperature	X				
	0 2 9	1	0	0	0	1	0	0	1	Cargo Duct Temperature	X				
	0 3 8	1	0	0	0	1	0	0	1	Total Air Temperature	X				
	0 A D	1	0	0	0	1	0	0	1	Total Air Temperature Indicated	X				
	1 0 A	1	0	0	0	1	0	0	1	Total Fan Inlet Temperature	X				
	1 0 B	1	0	0	0	1	0	0	1	Total Fan Inlet Temperature	X				
	1 4 0	1	0	0	0	1	0	0	1	Total Air Temp (TAT)	X				
	1 4 2	1	0	0	0	1	0	0	1	Projected Future Longitude	X				
		1	0	0	0	1	0	0	1	FCMC Mon A340-500/600 - System Address Label				X	See Attachment 11
2 1 2	0 0 4	1	0	0	0	1	0	1	0	Altitude Rate	X				6-27
	0 0 5	1	0	0	0	1	0	1	0	Altitude Rate	X				
	0 0 6	1	0	0	0	1	0	1	0	Altitude Rate	X				
	0 2 9	1	0	0	0	1	0	1	0	Cargo Temp. Reg. Valve Position	X				
	0 3 8	1	0	0	0	1	0	1	0	Altitude Rate	X				
	0 3 B	1	0	0	0	1	0	1	0	Altitude Rate	X				
	0 5 6	1	0	0	0	1	0	1	0	Altitude Rate	X				
	0 6 0	1	0	0	0	1	0	1	0	Altitude Rate	X				
	1 4 0	1	0	0	0	1	0	1	0	Altitude Rate	X				
	1 4 2	1	0	0	0	1	0	1	0	Projected Future Longitude Fine	X				
		1	0	0	0	1	0	1	0	FCMC Int A340-500/600 - System Address Label				X	See Attachment 11
2 1 3	0 0 2	1	0	0	0	1	0	1	1	Static Air Temperature	X				6-27
	0 0 6	1	0	0	0	1	0	1	1	Static Air Temperature	X				6-27
	0 3 8	1	0	0	0	1	0	1	1	Static Air Temperature	X				
	0 8 D	1	0	0	0	1	0	1	1	Fuel Used	X				6-27
	1 4 0	1	0	0	0	1	0	1	1	Static Air Temp (SAT)	X				
	1 4 2	1	0	0	0	1	0	1	1	Vertical Time Interval	X				
2 1 4	X X X	1	0	0	0	1	1	0	0	ICAO Aircraft Address (Part 1)			X		Note 1
2 1 5	0 0 6	1	0	0	0	1	1	0	1	Impacted Pressure, Uncorrected, mb	X				
	0 1 A	1	0	0	0	1	1	0	1	Impact Pressure	X				
	0 2 9	1	0	0	0	1	1	0	1	N1 Actual (EEC)	X				
	0 2 9	1	0	0	0	1	1	0	1	EPR Actual (EEC)	X				
	0 3 8	1	0	0	0	1	1	0	1	Impacted Pressure, Uncorrected, mb	X				
	0 A D	1	0	0	0	1	1	0	1	Impacted Pressure, Uncorrected, mb	X				
	1 4 0	1	0	0	0	1	1	1	1	Impact Pressure Subsonic	X				
2 1 6	X X X	1	0	0	0	1	1	1	0	ICAO Aircraft Address (Part 2)			X		Note 1

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Code No. (Octal)	Eqpt. ID (Hex)	Transmission Order Bit Position								Parameter	Data				Notes & Cross Ref. to Tables in Att. 6
		1	2	3	4	5	6	7	8		BNR	BCD	DISC	SAL	
2 1 7	0 0 2	1	0	0	0	1	1	1	1	Geometric Vertical Rate	X				
	0 0 6	1	0	0	0	1	1	1	1	Static Pressure, Corrected (In. Hg)	X				
	0 2 9	1	0	0	0	1	1	1	1	N1 Limit (EEC)	X				
	0 2 9	1	0	0	0	1	1	1	1	EPR Actual (EEC)	X				
	0 3 8	1	0	0	0	1	1	1	1	Static Pressure, Average, Corrected (In. Hg)	X				
	1 4 0	1	0	0	0	1	1	1	1	Static Pressure Corrected (In. Hg)	X				
2 2 0	0 0 6	1	0	0	1	0	0	0	0	Baro Corrected Altitude #2	X				
	0 3 8	1	0	0	1	0	0	0	0	Baro Corrected Altitude #2	X				
	1 4 0	1	0	0	1	0	0	0	0	Baro Corrected Altitude #2	X				
		1	0	0	1	0	0	0	0	MCDU #1 - System Address label (Recipient)				X	See Attachment 11
2 2 1	0 0 6	1	0	0	1	0	0	0	1	Indicated Angle of Attack (Average)	X				
	0 3 8	1	0	0	1	0	0	0	1	Indicated Angle of Attack (Average)	X				
	0 A D	1	0	0	1	0	0	0	1	Indicated Angle of Attack (Average)	X				
	1 2 C	1	0	0	1	0	0	0	1	Indicated Angle of Attack (Average)					
	1 4 0	1	0	0	1	0	0	0	1	Angle of Attack Indicated Average	X				
		1	0	0	1	0	0	0	1	MCDU #2 - System Address label (Recipient)				X	See Attachment 11
2 2 2	0 0 6	1	0	0	1	0	0	1	0	Indicated Angle of Attack (#1 Left)	X				
	0 1 1	1	0	0	1	0	0	1	0	VOR Omnibearing	X				
	1 1 2	1	0	0	1	0	0	1	0	TACAN Bearing	X				
	1 1 5	1	0	0	1	0	0	1	0	Bearing	X				
	1 2 C	1	0	0	1	0	0	1	0	Indicated Angle of Attack (#1 Left)	X				
	1 4 0	1	0	0	1	0	0	1	0	Angle of Attack, Indicated (#1 Left)	X				
		1	0	0	1	0	0	1	0	MCDU #3 - System Address Label				X	See Attachment 11
2 2 3	0 0 6	1	0	0	1	0	0	1	1	Indicated Angle of Attack (#1 Right)	X				
	1 2 C	1	0	0	1	0	0	1	1	Indicated Angle of Attack (#1 Right)	X				
	1 4 0	1	0	0	1	0	0	1	1	Angle of Attack, Indicated (#1 Right)	X				
		1	0	0	1	0	0	1	1	Printer #1 - System Address Label				X	See Attachment 11
2 2 4	0 0 6	1	0	0	1	0	1	0	0	Indicated Angle of Attack (#2 Left)	X				
	1 2 C	1	0	0	1	0	1	0	0	Indicated Angle of Attack (#2 Left)	X				
	1 4 0	1	0	0	1	0	1	0	0	Angle of Attack, Indicated (#2 Left)	X				
		1	0	0	1	0	1	0	0	Printer #2 - System Address Label				X	See Attachment 11
2 2 5	0 0 2	1	0	0	1	0	1	0	1	Min. Maneuvering Airspeed	X				
	0 0 6	1	0	0	1	0	1	0	1	Indicated Angle of Attack (#2 Right)	X				
	0 2 B	1	0	0	1	0	1	0	1	Compensated Altitude Rate	X				
	0 5 6	1	0	0	1	0	1	0	1	Minimum Maneuvering Airspeed	X				
	0 6 0	1	0	0	1	0	1	0	1	Minimum Maneuvering Airspeed	X				
	1 2 C	1	0	0	1	0	1	0	1	Indicated Angle of Attack (#2 Right)	X				
	1 4 0	1	0	0	1	0	1	0	1	Angle of Attack, Indicated (#2 Right)	X				
		1	0	0	1	0	1	0	1	HUD - System Address Label				X	See Attachment 11
2 2 6	0 0 2	1	0	0	1	0	1	1	0	Min. Op. Fuel Temp (non-conflicting)	X				
		1	0	0	1	0	1	1	0	Data Loader - System Address Label (High Speed)				X	See Attachment 11
2 2 7	0 1 9	1	0	0	1	0	1	1	1	CFDS Bite Command Summary for HFDR			X		
	0 3 D	1	0	0	1	0	1	1	1	AVM Command	X				
	0 5 3	1	0	0	1	0	1	1	1	CFDS Bite Command Summary for HFDR			X		
	0 7 E	1	0	0	1	0	1	1	1	BITE Command Word	X				
2 3 0	0 0 6	1	0	0	1	1	0	0	0	True Airspeed		X			6-25
	0 3 8	1	0	0	1	1	0	0	0	True Airspeed		X			6-25
	1 1 4	1	0	0	1	1	0	0	0	Left Outer Probes Capacitance		X			
		1	0	0	1	1	0	0	0	MCDU #4 - System Address Label				X	See Attachment 11
2 3 1	0 0 6	1	0	0	1	1	0	0	1	Total Air Temperature		X			6-25
	0 3 8	1	0	0	1	1	0	0	1	Total Air Temperature		X			
	1 1 4	1	0	0	1	1	0	0	1	Inner 2 Tank Probe Capacitance		X			
2 3 2	0 0 4	1	0	0	1	1	0	1	0	Altitude Rate		X			
	0 0 5	1	0	0	1	1	0	1	0	Altitude Rate		X			
	0 0 6	1	0	0	1	1	0	1	0	Altitude Rate		X			
	0 5 5	1	0	0	1	1	0	1	0	GLS Airport ID			X		
	1 1 4	1	0	0	1	1	0	1	0	Inner 4 Tank Probe Capacitance		X			
2 3 3	0 0 2	1	0	0	1	1	0	1	1	ACMS Information	X				6-31
	0 0 6	1	0	0	1	1	0	1	1	Static Air Temperature		X			6-25
	0 3 8	1	0	0	1	1	0	1	1	Static Air Temperature		X			6-25
	0 5 6	1	0	0	1	1	0	1	1	ACMS Information	X				
	0 6 0	1	0	0	1	1	0	1	1	ACMS Information	X				
	1 1 4	1	0	0	1	1	0	1	1	Right Outer Probe Capacitance		X			
2 3 4	0 0 2	1	0	0	1	1	1	0	0	ACMS Information	X				6-31
	0 0 6	1	0	0	1	1	1	0	0	Baro Correction (mb) #1		X			
	0 3 8	1	0	0	1	1	1	0	0	Baro Correction (mb) #1		X			
	0 5 6	1	0	0	1	1	1	0	0	ACMS Information	X				
	0 6 0	1	0	0	1	1	1	0	0	ACMS Information	X				
		1	0	0	1	1	1	0	0	EIVMU 1 - System Address Label				X	See Attachment 11

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Code No. (Octal)	Eqpt. ID (Hex)	Transmission Order Bit Position						Parameter	Data				Notes & Cross Ref. to Tables in Att. 6		
		1	2	3	4	5	6		7	8	BNR	BCD		DISC	SAL
2 3 5	0 0 2	1	0	0	1	1	1	0	1	ACMS Information	X				6-31
	0 0 6	1	0	0	1	1	1	0	1	Baro Correction (ins. Hg) #1		X			6-25
	0 3 8	1	0	0	1	1	1	0	1	Baro Correction (ins. Hg) #1		X			6-25
	0 5 6	1	0	0	1	1	1	0	1	ACMS Information	X				
	0 6 0	1	0	0	1	1	1	0	1	ACMS Information	X				
		1	0	0	1	1	1	0	1	EIVMU 2 - System Address Label				X	See Attachment 11
2 3 6	0 0 2	1	0	0	1	1	1	1	0	ACMS Information	X				6-31
	0 0 6	1	0	0	1	1	1	1	0	Baro Correction (mb) #2		X			
	0 3 8	1	0	0	1	1	1	1	0	Baro Correction (mb) #2		X			
	0 5 6	1	0	0	1	1	1	1	0	ACMS Information	X				
	0 6 0	1	0	0	1	1	1	1	0	ACMS Information	X				
		1	0	0	1	1	1	1	0	EIVMU 3 - System Address Label				X	See Attachment 11
2 3 7	0 0 2	1	0	0	1	1	1	1	1	ACMS Information	X				
	0 0 6	1	0	0	1	1	1	1	1	Baro Correction (ins. Hg) #2		X			
	0 0 B	1	0	0	1	1	1	1	1	Horizontal Uncertainty Level	X				
	0 3 8	1	0	0	1	1	1	1	1	Baro Correction (ins. Hg) #2		X			
	0 5 6	1	0	0	1	1	1	1	1	ACMS Information	X				
	0 6 0	1	0	0	1	1	1	1	1	ACMS Information	X				
	1	0	0	1	1	1	1	1	EIVMU 4 - System Address Label				X	See Attachment 11	
2 4 0	0								Spare						
2 4 1	0 0 2	1	0	1	0	0	0	0	1	Min. Airspeed for Flap Extension	X				
	0 0 6	1	0	1	0	0	0	0	1	Corrected Angle of Attack	X				
	0 2 C	1	0	1	0	0	0	0	1	Reserved (Special Use)			X		
	0 3 8	1	0	1	0	0	0	0	1	Corrected Angle of Attack	X				
	0 4 D	1	0	1	0	0	0	0	1	FQIS System Data	X				
	0 5 6	1	0	1	0	0	0	0	1	Min. Airspeed for Flap Extension	X				
	0 6 0	1	0	1	0	0	0	0	1	Min. Airspeed for Flap Extension	X				
	1 4 0	1	0	1	0	0	0	0	1	Angle of Attack, Corrected	X				
	1 6 0	1	0	1	0	0	0	0	1	Tank Unit Data	X				
		1	0	1	0	0	0	0	1	APM-MMR - System Address Label				X	See Attachment 11
2 4 2	0 0 6	1	0	1	0	0	0	1	0	Total Pressure	X				
	0 0 9	1	0	1	0	0	0	1	0	Ground Station ID (Word #1)			X		
	0 1 0	1	0	1	0	0	0	1	0	Ground Station ID (Word #1)			X		
	0 1 1	1	0	1	0	0	0	1	0	Ground Station ID (Word #1)			X		
	1 1 2	1	0	1	0	0	0	1	0	Ground Station ID (Word #1)			X		
	0 1 A	1	0	1	0	0	0	1	0	Total Pressure	X				
	0 3 8	1	0	1	0	0	0	1	0	Total Pressure	X				
	0 3 B	1	0	1	0	0	0	1	0	Speed Deviation	X				
	0 A D	1	0	1	0	0	0	1	0	Total Pressure, Uncorrected, mb	X				
	1 4 0	1	0	1	0	0	0	1	0	Total Pressure	X				
	1	0	1	0	0	0	1	0	MMR - System Address Label				X	See Attachment 11	
2 4 3	0 3 7	1	0	1	0	0	0	1	1	Zero Fuel Weight (kg)		X			
	0 5 5	1	0	1	0	0	0	1	1	GLS Runway Selection			X		
	X X X	1	0	1	0	0	0	1	1	Simulator to Avionics Control Word	X				Note 1
2 4 4	0 0 9	1	0	1	0	0	1	0	0	Ground Station ID (Word #2)			X		
	0 1 0	1	0	1	0	0	1	0	0	Ground Station ID (Word #2)			X		
	0 1 1	1	0	1	0	0	1	0	0	VOR Ground Station Ident Word #2			X		
	0 1 2	1	0	1	0	0	1	0	0	Ground Station ID (Word #2)			X		
	0 1 C	1	0	1	0	0	1	0	0	Fuel Flow (Engine Direct)	X				
	0 3 3	1	0	1	0	0	1	0	0	Fuel Flow (Wf)	X				
	0 3 B	1	0	1	0	0	1	0	0	Mach Error	X				
	0 8 D	1	0	1	0	0	1	0	0	Fuel Flow Rate	X				
	1 0 A	1	0	1	0	0	1	0	0	Fuel Mass Flow	X				
	1 0 B	1	0	1	0	0	1	0	0	Fuel Mass Flow	X				
	1 4 0	1	0	1	0	0	1	0	0	Angle of Attack, Normalized	X				
		1	0	1	0	0	1	0	0	ILS - System Address Label				X	See Attachment 11

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LABEL CODES

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Code No. (Octal)	Eqpt. ID (Hex)	Transmission Order Bit Position								Parameter	Data				Notes & Cross Ref. to Tables in Att. 6
		1	2	3	4	5	6	7	8		BNR	BCD	DISC	SAL	
2 4 5	0 0 2	1	0	1	0	0	1	0	1	Minimum Airspeed	X				See Attachment 11
	0 0 3	1	0	1	0	0	1	0	1	Minimum Airspeed	X				
	0 0 A	1	0	1	0	0	1	0	1	Minimum Airspeed	X				
	0 2 9	1	0	1	0	0	1	0	1	N3 (Engine)	X				
	0 3 8	1	0	1	0	0	1	0	1	Average Static Pressure mb, Uncorrected	X				
	0 3 B	1	0	1	0	0	1	0	1	EPR Error	X				
	0 5 6	1	0	1	0	0	1	0	1	Minimum Airspeed	X				
	0 6 0	1	0	1	0	0	1	0	1	Minimum Airspeed	X				
	0 A D	1	0	1	0	0	1	0	1	Average Static Pressure mb, Uncorrected	X				
	1 4 0	1	0	1	0	0	1	0	1	Static Pressure, Uncorrected	X				
		1	0	1	0	0	1	0	1	MLS - System Address Label				X	
2 4 6	0 0 2	1	0	1	0	0	1	1	0	General Maximum Speed (VCMAX)	X				See Attachment 11
	0 0 6	1	0	1	0	0	1	1	0	Average Static Pressure	X				
	0 0 9	1	0	1	0	0	1	1	0	DME Ground Station Ident Word #1			X		
	0 1 C	1	0	1	0	0	1	1	0	N1 (Engine Direct)	X				
	0 2 9	1	0	1	0	0	1	1	0	N1 (Engine Direct)	X				
	0 3 8	1	0	1	0	0	1	1	0	Average Static Pressure mb, Corrected	X				
	0 3 B	1	0	1	0	0	1	1	0	Angle of Attack Error	X				
		1	0	1	0	0	1	1	0	AHRS - System Address Label				X	
2 4 7	0 0 2	1	0	1	0	0	1	1	1	Control Minimum Speed (VCMIN)	X				See Attachment 11
	0 0 9	1	0	1	0	0	1	1	1	DME Ground Station Ident Word #1			X		
	0 0 B	1	0	1	0	0	1	1	1	Horizontal Figure of Merit	X				
	0 1 F	1	0	1	0	0	1	1	1	Total Fuel	X				
	0 2 C	1	0	1	0	0	1	1	1	Total Fuel	X				
	0 3 B	1	0	1	0	0	1	1	1	Speed Error	X				
	0 4 D	1	0	1	0	0	1	1	1	Total Fuel	X				
	0 5 6	1	0	1	0	0	1	1	1	Control Minimum Speed (VCMIN)	X				
	0 5 A	1	0	1	0	0	1	1	1	Total Fuel	X				
	0 6 0	1	0	1	0	0	1	1	1	Control Minimum Speed (VCMIN)	X				
	0 E B	1	0	1	0	0	1	1	1	Fuel to Remain	X				
	1 1 4	1	0	1	0	0	1	1	1	Fuel on Board	X				
	1 4 0	1	0	1	0	0	1	1	1	Airspeed Minimum Vmc	X				
		1	0	1	0	0	1	1	1	High-Speed Data Unit #1 (HSDU #1) - SAL				X	
2 5 0	0 0 2	1	0	1	0	1	0	0	0	Continuous N1 Limit	X				See Attachment 11
	0 2 B	1	0	1	0	1	0	0	0	Maximum Continuous EPR Limit	X				
	0 2 C	1	0	1	0	1	0	0	0	Preselected Fuel Quantity	X				
	0 3 8	1	0	1	0	1	0	0	0	Indicated Side Slip Angle	X				
	0 5 A	1	0	1	0	1	0	0	0	Preselected Fuel Quantity	X				
	0 A D	1	0	1	0	1	0	0	0	Indicated Side Slip Angle or AOS	X				
	1 1 4	1	0	1	0	1	0	0	0	Preselected Fuel Quantity	X				
	1 2 B	1	0	1	0	1	0	0	0	Temperature Rate of Change	X				
		1	0	1	0	1	0	0	0	High-Speed Data Unit #1 (HSDU #2) - SAL				X	
2 5 1	0 0 1	1	0	1	0	1	0	0	1	Distance to Go	X				6-19 See Attachment 11
	0 0 2	1	0	1	0	1	0	0	1	Distance to Go	X				
	0 0 6	1	0	1	0	1	0	0	1	Baro Corrected Altitude #3	X				
	0 1 A	1	0	1	0	1	0	0	1	Flight Leg Counter	X				
	0 3 8	1	0	1	0	1	0	0	1	Baro Corrected Altitude #3	X				
		1	0	1	0	1	0	0	1	VDR #1 - System Address Label				X	
2 5 2	0 0 1	1	0	1	0	1	0	1	0	Time to Go	X				See Attachment 11
	0 0 2	1	0	1	0	1	0	1	0	Time to Go	X				
	0 0 6	1	0	1	0	1	0	1	0	Baro Corrected Altitude #4	X				
	0 1 A	1	0	1	0	1	0	1	0	EPR Idle	X				
	0 2 F	1	0	1	0	1	0	1	0	EPR Idle Reference	X				
	0 3 8	1	0	1	0	1	0	1	0	Baro Corrected Altitude #4	X				
	0 3 F	1	0	1	0	1	0	1	0	EPR Idle Reference	X				
	0 E B	1	0	1	0	1	0	1	0	Time Until Jettison Complete	X				
		1	0	1	0	1	0	1	0	VDR #2 - System Address Label				X	
2 5 3	0 0 2	1	0	1	0	1	0	1	1	Go-Around N1 Limit	X				See Attachment 11
	0 1 E	1	0	1	0	1	0	1	1	Go-Around EPR Limit	X				
	0 3 8	1	0	1	0	1	0	1	1	Corrected Side Slip Angle	X				
		1	0	1	0	1	0	1	1	VDR #3 - System Address Label				X	
2 5 4	0 0 2	1	0	1	0	1	1	0	0	Cruise N1 Limit	X				See Attachment 11
	0 1 2	1	0	1	0	1	1	0	0	ADF Ground Station Ident Word #1			X		
	0 1 E	1	0	1	0	1	1	0	0	Cruise EPR Limit	X				
	0 4 D	1	0	1	0	1	1	0	0	Actual Fuel Quantity (test)	X				
	0 5 5	1	0	1	0	1	1	0	0	GBAS ID			X		
	1 3 A	1	0	1	0	1	1	0	0	N1 Cruise	X				
	1 4 0	1	0	1	0	1	1	0	0	Altitude Rate	X				
		1	0	1	0	1	1	0	0	Network Server System (NSS) - System Address Label				X	

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Code No. (Octal)	Eqpt. ID (Hex)	Transmission Order Bit Position						Parameter	Data				Notes & Cross Ref. to Tables in Att. 6
		1 2	3 4 5	6 7 8	BNR	BCD	DISC		SAL				
2 5 5	0 0 2	1 0	1 0 1	1 0 1	Climb N1 Limit	X							
	0 1 2	1 0	1 0 1	1 0 1	ADF Ground Station Ident Word #2			X					
	0 1 E	1 0	1 0 1	1 0 1	Climb EPR Limit	X							
	0 2 F	1 0	1 0 1	1 0 1	Max. Climb EPR Rating	X							
	0 3 F	1 0	1 0 1	1 0 1	Max. Climb EPR Rating	X							
	0 4 D	1 0	1 0 1	1 0 1	Fuel Quantity (gal)	X							
	0 5 5	1 0	1 0 1	1 0 1	GBAS ID/ Airport ID			X					
	0 8 E	1 0	1 0 1	1 0 1	Spoiler Position	X							
	1 3 A	1 0	1 0 1	1 0 1	N1 Climb	X							
	1 4 0	1 0	1 0 1	1 0 1	Impact Pressure	X							
		1 0	1 0 1	1 0 1	Electronic Flight Bag - Left - System Address Label				X	See Attachment 11			
2 5 6	0 0 2	1 0	1 0 1	1 1 0	Time for Climb	X							
	0 0 A	1 0	1 0 1	1 1 0	V Stick Shaker	X							
	0 2 7	1 0	1 0 1	1 1 0	MLS Ground Station Ident Word #1			X					
	0 2 C	1 0	1 0 1	1 1 0	Fuel Quantity (Tanks) #1	X							
	0 4 D	1 0	1 0 1	1 1 0	Fuel Discretes			X					
	0 5 5	1 0	1 0 1	1 1 0	MLS Station ID #1			X					
	0 5 6	1 0	1 0 1	1 1 0	Time for Climb	X							
	0 5 A	1 0	1 0 1	1 1 0	Fuel Quantity - Left Outer Cell	X							
	0 6 0	1 0	1 0 1	1 1 0	Time for Climb	X							
	1 1 4	1 0	1 0 1	1 1 0	Left Outer Tank Fuel Quantity	X							
	1 4 0	1 0	1 0 1	1 1 0	Equivalent Airspeed	X							
	1 0	1 0 1	1 1 0	Electronic Flight Bag -Right - System Address Label					See Attachment 11				
2 5 7	0 0 2	1 0	1 0 1	1 1 1	Time for Descent	X							
	0 2 7	1 0	1 0 1	1 1 1	MLS Ground Station Ident Word #2			X					
	0 2 C	1 0	1 0 1	1 1 1	Fuel Quantity (Tanks) #2	X							
	0 5 5	1 0	1 0 1	1 1 1	MLS Station ID #2								
	0 5 6	1 0	1 0 1	1 1 1	Time for Descent	X							
	0 5 A	1 0	1 0 1	1 1 1	Fuel Quantity Left W/T Tank	X							
	0 6 0	1 0	1 0 1	1 1 1	Time for Descent	X							
	1 1 4	1 0	1 0 1	1 1 1	Inner Tank 1 Fuel Quantity	X							
1 4 0	1 0	1 0 1	1 1 1	Total Pressure (High Range)	X								
2 6 0	0 0 2	1 0	1 1 0	0 0 0	Date/Flight Leg		X			6-8			
	0 0 B	1 0	1 1 0	0 0 0	Date		X						
	0 2 C	1 0	1 1 0	0 0 0	Fuel Quantity (Tanks) #3	X							
	0 3 1	1 0	1 1 0	0 0 0	Date (No Flight Leg)		X			6-18			
	0 3 3	1 0	1 1 0	0 0 0	T5	X							
	0 5 6	1 0	1 1 0	0 0 0	Date/Flight Leg		X						
	0 5 A	1 0	1 1 0	0 0 0	Fuel Quantity Center Tank	X							
	0 6 0	1 0	1 1 0	0 0 0	Date/Flight Leg		X			6-8			
	0 A 2	1 0	1 1 0	0 0 0	Date/Flight Leg		X			6-8			
	1 0 A	1 0	1 1 0	0 0 0	LP Turbine Discharge Temperature	X							
	1 0 B	1 0	1 1 0	0 0 0	LP Turbine Discharge Temperature	X							
1 1 4	1 0	1 1 0	0 0 0	Collector Cell 1 and 2 Fuel Quantity	X								
2 6 1	0 0 2	1 0	1 1 0	0 0 1	Flight Number	X	X			6-9			
	0 2 C	1 0	1 1 0	0 0 1	Fuel Quantity (Tanks) #4	X							
	0 3 3	1 0	1 1 0	0 0 1	P49		X						
	0 5 6	1 0	1 1 0	0 0 1	Flight Number (BCD)								
	0 5 A	1 0	1 1 0	0 0 1	Fuel Quantity Right I/C or W/T Tank	X							
	0 6 0	1 0	1 1 0	0 0 1	Flight Number (BCD)		X						
	0 A 2	1 0	1 1 0	0 0 1	Flight Number		X			6-9			
	1 0 A	1 0	1 1 0	0 0 1	LP Turbine Inlet Pressure	X							
	1 0 B	1 0	1 1 0	0 0 1	LP Turbine Inlet Pressure	X							
1 1 4	1 0	1 1 0	0 0 1	Fuel On Board At Engine Start	X								
1 4 4	1 0	1 1 0	0 0 1	Range Ring Radius	X				6-52				

ATTACHMENT 1-1
LABEL CODES

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Code No. (Octal)	Eqpt. ID (Hex)	Transmission Order Bit Position						Parameter	Data				Notes & Cross Ref. to Tables in Att. 6		
		1	2	3	4	5	6		7	8	BNR	BCD		DISC	SAL
2 6 2	0 0 2	1	0	1	1	0	0	1	0	Documentary Data	X				6-14
	0 0 A	1	0	1	1	0	0	1	0	Predictive Airspeed Variation	X				
	0 1 C	1	0	1	1	0	0	1	0	LP Compressor Exist Pressure (PT3)	X				
	0 2 C	1	0	1	1	0	0	1	0	Fuel Quantity (Tanks) #5	X				
	0 3 3	1	0	1	1	0	0	1	0	LP Compressor Exist Pressure	X				
	0 4 D	1	0	1	1	0	0	1	0	T/U CAP-L Tank 1-4	X				
	0 5 6	1	0	1	1	0	0	1	0	Documentary Data	X				
	0 5 A	1	0	1	1	0	0	1	0	Fuel Quantity - Right Outer Cell	X				
	0 6 0	1	0	1	1	0	0	1	0	Documentary Data	X				
	1 0 A	1	0	1	1	0	0	1	0	HP Compressor Inlet Total Pressure	X				
	1 0 B	1	0	1	1	0	0	1	0	HP Compressor Inlet Total Pressure	X				
	1 1 4	1	0	1	1	0	0	1	0	Center Tank Fuel Quantity	X				
1 4 4	1	0	1	1	0	0	1	0	Display Range	X				6-51	
2 6 3	0 0 2	1	0	1	1	0	0	1	1	Minimum Airspeed for Flap Retraction	X				
	0 0 A	1	0	1	1	0	0	1	1	Minimum Airspeed for Flap Retraction	X				
	0 1 0	1	0	1	1	0	0	1	1	ILS Ground Station Ident Word #1		X			
	0 1 C	1	0	1	1	0	0	1	1	LP Compressor Exit Temperature	X				
	0 2 C	1	0	1	1	0	0	1	1	Fuel Quantity (Tanks) #6	X				
	0 3 3	1	0	1	1	0	0	1	1	LP Compressor Exit Temperature	X				
	0 4 D	1	0	1	1	0	0	1	1	T/U CAP-L Tank 5-8	X				
	0 5 5	1	0	1	1	0	0	1	1	Ground Station/Approach		X			
	0 5 6	1	0	1	1	0	0	1	1	Minimum Airspeed For Flap Retraction	X				
	0 6 0	1	0	1	1	0	0	1	1	Minimum Airspeed For Flap Retraction	X				
	1 0 A	1	0	1	1	0	0	1	1	Selected Compressor Inlet Temperature (Total)	X				
	1 0 B	1	0	1	1	0	0	1	1	Selected Compressor Inlet Temperature (Total)	X				
1 1 4	1	0	1	1	0	0	1	1	Collector Cell 3 and 4 Fuel Quantity	X					
2 6 4	0 0 2	1	0	1	1	0	1	0	0	Time to Touchdown	X				
	0 0 A	1	0	1	1	0	1	0	0	Minimum Airspeed for Slats Retraction	X				
	0 1 0	1	0	1	1	0	1	0	0	ILS Ground Station Ident Word #2		X			
	0 1 C	1	0	1	1	0	1	0	0	HP Compressor Exit Pressure	X				
	0 2 C	1	0	1	1	0	1	0	0	Fuel Quantity (Tanks) #7	X				
	0 2 F	1	0	1	1	0	1	0	0	Burner Pressure	X				
	0 3 3	1	0	1	1	0	1	0	0	HP Compressor Exit Pressure	X				
	0 3 F	1	0	1	1	0	1	0	0	Burner Pressure	X				
	0 4 D	1	0	1	1	0	1	0	0	T/U CAP-L Tank 9-12	X				
	0 5 5	1	0	1	1	0	1	0	0	Ground Station/Approach		X			
	0 5 6	1	0	1	1	0	1	0	0	Time to Touchdown	X				
	0 6 0	1	0	1	1	0	1	0	0	Time to Touchdown	X				
	1 0 A	1	0	1	1	0	1	0	0	Selected Compressor Discharge Temperature	X				
	1 0 B	1	0	1	1	0	1	0	0	Selected Compressor Discharge Temperature	X				
	1 1 4	1	0	1	1	0	1	0	0	Fuel Quantity (Tanks) #7	X				
	1 3 A	1	0	1	1	0	1	0	0	Burner Pressure	X				
2 6 5	0 0 2	1	0	1	1	0	1	0	1	Minimum Buffet Airspeed	X				
	0 0 4	1	0	1	1	0	1	0	1	Integrated Vertical Acceleration	X				
	0 0 A	1	0	1	1	0	1	0	1	Maneuvering Airspeed	X				
	0 1 C	1	0	1	1	0	1	0	1	HP Compressor Exit Temperature (TT4.5)	X				
	0 2 C	1	0	1	1	0	1	0	1	Fuel Quantity (Tanks) #8	X				
	0 3 3	1	0	1	1	0	1	0	1	HP Compressor Exit Temperature	X				
	0 3 8	1	0	1	1	0	1	0	1	Integrated Vertical Acceleration	X				
	0 4 D	1	0	1	1	0	1	0	1	T/U CAP-L Tank 13-14	X				
	0 5 6	1	0	1	1	0	1	0	1	Minimum Buffet Airspeed	X				
	0 6 0	1	0	1	1	0	1	0	1	Minimum Buffet Airspeed	X				
	1 0 A	1	0	1	1	0	1	0	1	Selected Compressor Discharge Temperature	X				
	1 0 B	1	0	1	1	0	1	0	1	Selected Compressor Discharge Temperature	X				
	1 1 4	1	0	1	1	0	1	0	1	Inner Tank 3 Fuel Quantity	X				
	2 6 6	0 0 1	1	0	1	1	0	1	1	0	Test Word B			X	
0 1 D		1	0	1	1	0	1	1	0	Test Word B			X		
0 4 D		1	0	1	1	0	1	1	0	T/U CAP-C Tank 1-4	X				
1 1 4		1	0	1	1	0	1	1	0	Inner Tank 2 Fuel Quantity	X				
		1	0	1	1	0	1	1	0	Cabin Video System - System Address Label				X	See Attachment 11

See Attachment 11

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Code No. (Octal)	Eqpt. ID (Hex)	Transmission Order Bit Position								Parameter	Data				Notes & Cross Ref. to Tables in Att. 6
		1	2	3	4	5	6	7	8		BNR	BCD	DISC	SAL	
2 6 7	0 0 2	1	0	1	1	0	1	1	1	Maximum Maneuver Airspeed	X				
	0 0 A	1	0	1	1	0	1	1	1	Predictive Maximum Maneuver Speed	X				
	0 2 B	1	0	1	1	0	1	1	1	Throttle Position Command	X				
	0 3 3	1	0	1	1	0	1	1	1	Spare T/C	X				
	0 4 D	1	0	1	1	0	1	1	1	T/U CAP-C Tank 5-8	X				
	0 5 6	1	0	1	1	0	1	1	1	Maximum Maneuver Airspeed	X				
	0 6 0	1	0	1	1	0	1	1	1	Maximum Maneuver Airspeed	X				
	1 0 A	1	0	1	1	0	1	1	1	HP Compressor Inlet Temperature (Total)	X				
	1 0 B	1	0	1	1	0	1	1	1	HP Compressor Inlet Temperature (Total)	X				
	1 1 4	1	0	1	1	0	1	1	1	Inner Tank 4 Fuel Quantity	X				
2 7 0	0 0 1	1	0	1	1	1	0	0	0	Discrete Data #1			X		
	0 0 2	1	0	1	1	1	0	0	0	Discrete Data #1			X		
	0 0 4	1	0	1	1	1	0	0	0	Discrete Data #1			X		
	0 0 5	1	0	1	1	1	0	0	0	Discrete Data #1			X		
	0 0 6	1	0	1	1	1	0	0	0	Discrete Data #1			X		
	0 0 B	1	0	1	1	1	0	0	0	Discrete Data #1			X		
	0 1 A	1	0	1	1	1	0	0	0	Discrete Data #1			X		
	0 1 B	1	0	1	1	1	0	0	0	Discrete Data #1			X		
	0 1 C	1	0	1	1	1	0	0	0	Discrete Data #1			X		
	0 1 E	1	0	1	1	1	0	0	0	Discrete Data #1			X		
	0 2 3	1	0	1	1	1	0	0	0	GPWS Discrete			X		
	0 2 4	1	0	1	1	1	0	0	0	MU Output Data Word, Communication Link Status			X		
	0 2 5	1	0	1	1	1	0	0	0	Discrete Data #1			X		
	0 2 7	1	0	1	1	1	0	0	0	Discrete Data #1			X		
	0 2 9	1	0	1	1	1	0	0	0	Discrete Data #1			X		
	0 2 F	1	0	1	1	1	0	0	0	Discrete Data #1			X		
	0 3 1	1	0	1	1	1	0	0	0	Discrete Data #1			X		
	0 3 3	1	0	1	1	1	0	0	0	Discrete Data #1			X		
	0 3 5	1	0	1	1	1	0	0	0	Discrete Data #1			X		
	0 3 7	1	0	1	1	1	0	0	0	Discrete Data #1			X		
	0 3 8	1	0	1	1	1	0	0	0	Discrete Data #1			X		
	0 3 9	1	0	1	1	1	0	0	0	MCDU Normal Discrete Word			X		
	0 3 A	1	0	1	1	1	0	0	0	Discrete Data #1			X		
	0 3 B	1	0	1	1	1	0	0	0	Discrete Data #1			X		
	0 3 D	1	0	1	1	1	0	0	0	Discrete Data #1			X		
	0 3 E	1	0	1	1	1	0	0	0	Discrete Data #1			X		
	0 3 F	1	0	1	1	1	0	0	0	Discrete Data #1			X		
	0 4 1	1	0	1	1	1	0	0	0	SDU To ACARS MU/CMU Status Word			X		
	0 4 A	1	0	1	1	1	0	0	0	Discrete Data #1			X		
	0 4 D	1	0	1	1	1	0	0	0	T/U CAP-C Tank 9	X				
	0 5 0	1	0	1	1	1	0	0	0	VDR Status Word			X		
	0 5 3	1	0	1	1	1	0	0	0	HFDL Status Word			X		
	0 5 5	1	0	1	1	1	0	0	0	MLS Discrete			X		
	0 5 6	1	0	1	1	1	0	0	0	Status Discretes			X		
	0 5 A	1	0	1	1	1	0	0	0	Discrete Data #1			X		
	0 6 0	1	0	1	1	1	0	0	0	Intent Status			X		
	0 6 0	1	0	1	1	1	0	0	0	Status Discretes			X		
	0 6 0	1	0	1	1	1	0	0	0	Discrete Data #1			X		
	0 A 2	1	0	1	1	1	0	0	0	Discrete Data #1			X		
	0 A 8	1	0	1	1	1	0	0	0	Discrete Data #1			X		
	0 A D	1	0	1	1	1	0	0	0	Discrete Data #1			X		
	0 C 5	1	0	1	1	1	0	0	0	Discrete Data #1			X		
	1 0 A	1	0	1	1	1	0	0	0	Discrete Data #1			X		
	1 0 B	1	0	1	1	1	0	0	0	Discrete Data #1			X		
	1 1 4	1	0	1	1	1	0	0	0	Unusable, and Empty Warning			X		
	1 1 5	1	0	1	1	1	0	0	0	Stored TACAN Control Word			X		
	1 4 0	1	0	1	1	1	0	0	0	Discrete Data #1			X		
	1 4 2	1	0	1	1	1	0	0	0	Aircraft Category (Disc Data 1)			X		
	1 4 4	1	0	1	1	1	0	0	0	Display Mode			X		

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Code No. (Octal)	Eqpt. ID (Hex)	Transmission Order Bit Position								Parameter	Data				Notes & Cross Ref. to Tables in Att. 6
		1	2	3	4	5	6	7	8		BNR	BCD	DISC	SAL	
2 7 1	0 0 2	1	0	1	1	1	0	0	1	Discrete Data #2			X		
	0 0 5	1	0	1	1	1	0	0	1	AHRS Discrete			X		
	0 0 6	1	0	1	1	1	0	0	1	Discrete Data #2			X		
	0 1 8	1	0	1	1	1	0	0	1	Discrete Data #2			X		
	0 1 A	1	0	1	1	1	0	0	1	Discrete Data #2			X		
	0 1 C	1	0	1	1	1	0	0	1	Discrete Data #2			X		
	0 1 E	1	0	1	1	1	0	0	1	Discrete Data #2			X		
	0 2 9	1	0	1	1	1	0	0	1	Discrete Data #2			X		
	0 2 F	1	0	1	1	1	0	0	1	Discrete Data #2			X		
	0 3 1	1	0	1	1	1	0	0	1	Discrete Data #2			X		
	0 3 3	1	0	1	1	1	0	0	1	Discrete Data #2			X		
	0 3 5	1	0	1	1	1	0	0	1	Discrete Data #2			X		
	0 3 8	1	0	1	1	1	0	0	1	Discrete Data #2			X		
	0 3 A	1	0	1	1	1	0	0	1	Discrete Data #2			X		
	0 3 B	1	0	1	1	1	0	0	1	Discrete Data #2			X		
	0 3 F	1	0	1	1	1	0	0	1	Discrete Data #2			X		
	0 4 1	1	0	1	1	1	0	0	1	SDU To ACARS MU/CMU Join/Leave Message			X		
	0 4 D	1	0	1	1	1	0	0	1	T/U CAP-A Tank 1-4	X				
	0 5 5	1	0	1	1	1	0	0	1	MMR Discrete			X		
	0 5 6	1	0	1	1	1	0	0	1	Discrete Data #2			X		
	0 5 A	1	0	1	1	1	0	0	1	Fuel Density			X		
	0 6 0	1	0	1	1	1	0	0	1	Discrete Data #2			X		
	0 A 2	1	0	1	1	1	0	0	1	Discrete Data #2			X		
	0 A 8	1	0	1	1	1	0	0	1	Discrete Data #2			X		
	0 A D	1	0	1	1	1	0	0	1	Discrete Data #2			X		
	0 C 5	1	0	1	1	1	0	0	1	Discrete Data #2			X		
	1 0 A	1	0	1	1	1	0	0	1	Discrete Data #2			X		
	1 0 B	1	0	1	1	1	0	0	1	Discrete Data #2			X		
	1 1 4	1	0	1	1	1	0	0	1	Fuel Transfer Indication			X		
	1 4 0	1	0	1	1	1	0	0	1	Discrete Data #2			X		
	1 4 2	1	0	1	1	1	0	0	1	Altitude Filter Limits (Disc Data 2)			X		
	1 4 4	1	0	1	1	1	0	0	1	Altitude Filter Setting			X		
2 7 2	0 0 1	1	0	1	1	1	0	1	0	Discrete Data #3			X		
	0 0 2	1	0	1	1	1	0	1	0	Discrete Data #3			X		
	0 0 3	1	0	1	1	1	0	1	0	Discrete Data #3			X		
	0 0 5	1	0	1	1	1	0	1	0	Air Data AHARS					
	0 1 8	1	0	1	1	1	0	1	0	Discrete Data #3			X		
	0 1 A	1	0	1	1	1	0	1	0	Discrete Data #3					
	0 1 C	1	0	1	1	1	0	1	0	Discrete Data #3			X		
	0 2 5	1	0	1	1	1	0	1	0	Discrete Data #3			X		
	0 2 9	1	0	1	1	1	0	1	0	Discrete Data #3			X		
	0 2 F	1	0	1	1	1	0	1	0	Discrete Data #3			X		
	0 3 5	1	0	1	1	1	0	1	0	Discrete Data #3			X		
	0 3 8	1	0	1	1	1	0	1	0	Discrete Data #3			X		
	0 3 A	1	0	1	1	1	0	1	0	Discrete Data #3			X		
	0 3 B	1	0	1	1	1	0	1	0	Discrete Data #3			X		
	0 3 F	1	0	1	1	1	0	1	0	Discrete Data #3			X		
	0 4 D	1	0	1	1	1	0	1	0	T/U CAP-A Tank 5-8	X				
	0 5 3	1	0	1	1	1	0	1	0	HFDL Slave (Disc Data 2)			X		
	0 5 6	1	0	1	1	1	0	1	0	Discrete Data #3			X		
	0 5 A	1	0	1	1	1	0	1	0	Fuel Density		X			
	0 6 0	1	0	1	1	1	0	1	0	Discrete Data #3			X		
	0 A D	1	0	1	1	1	0	1	0	Discrete Data #3			X		
	0 C 5	1	0	1	1	1	0	1	0	Discrete Data #3			X		
	1 0 A	1	0	1	1	1	0	1	0	Discrete Data #3			X		
	1 0 B	1	0	1	1	1	0	1	0	Discrete Data #3			X		
	1 1 4	1	0	1	1	1	0	1	0	Fuel Transfer Indication			X		
	1 4 0	1	0	1	1	1	0	1	0	Discrete Data #3			X		
	1 4 4	1	0	1	1	1	0	1	0	Target Selection Word			X		

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Code No. (Octal)	Eqpt. ID (Hex)	Transmission Order Bit Position						Parameter	Data				Notes & Cross Ref. to Tables in Att. 6				
		1	2	3	4	5	6		7	8	BNR	BCD		DISC	SAL		
2 7 3	0 0 1	1	0	1	1	1	0	1	1	Discrete Data #4	X		X				
	0 0 3	1	0	1	1	1	0	1	1	Discrete Data #4			X				
	0 0 B	1	0	1	1	1	0	1	1	GNSS Sensor Status			X				
	0 1 8	1	0	1	1	1	0	1	1	Discrete Data #4			X				
	0 1 C	1	0	1	1	1	0	1	1	Discrete Data #4			X				
	0 2 5	1	0	1	1	1	0	1	1	Discrete Data #4			X				
	0 2 9	1	0	1	1	1	0	1	1	Discrete Data #4			X				
	0 2 F	1	0	1	1	1	0	1	1	Discrete Data #4			X				
	0 3 3	1	0	1	1	1	0	1	1	Discrete Data #4			X				
	0 3 5	1	0	1	1	1	0	1	1	Discrete Data #4			X				
	0 3 B	1	0	1	1	1	0	1	1	Discrete Data #4			X				
	0 3 F	1	0	1	1	1	0	1	1	Discrete Data #4			X				
	0 4 D	1	0	1	1	1	0	1	1	T/U CAP-A Tank 9-11			X				
	0 5 5	1	0	1	1	1	0	1	1	GNSS Status							X
	0 5 A	1	0	1	1	1	0	1	1	Sensor Valves Left Wing Tank							X
	0 C 5	1	0	1	1	1	0	1	1	Discrete Data #4							X
1 0 A	1	0	1	1	1	0	1	1	Discrete Data #4	X							
1 0 B	1	0	1	1	1	0	1	1	Discrete Data #4	X							
1 1 4	1	0	1	1	1	0	1	1	Memos and Status	X							
2 7 4	0 0 1	1	0	1	1	1	1	0	0	Discrete Data #5	X		X				
	0 0 3	1	0	1	1	1	1	0	0	Discrete Data #5			X				
	0 0 A	1	0	1	1	1	1	0	0	Discrete Data #5			X				
	0 1 8	1	0	1	1	1	1	0	0	Discrete Data #5			X				
	0 1 C	1	0	1	1	1	1	0	0	Discrete Data #5			X				
	0 2 5	1	0	1	1	1	1	0	0	Discrete Data #5			X				
	0 2 9	1	0	1	1	1	1	0	0	Discrete Data #5			X				
	0 2 F	1	0	1	1	1	1	0	0	Discrete Data #5			X				
	0 3 3	1	0	1	1	1	1	0	0	Discrete Data #5			X				
	0 3 5	1	0	1	1	1	1	0	0	Discrete Data #5			X				
	0 3 B	1	0	1	1	1	1	0	0	Discrete Data #5			X				
	0 3 F	1	0	1	1	1	1	0	0	Discrete Data #5			X				
	0 4 D	1	0	1	1	1	1	0	0	T/U CAP-R Tank 1-4			X				
	0 5 A	1	0	1	1	1	1	0	0	Sensor Valves Center Wing Tank							X
	0 C 5	1	0	1	1	1	1	0	0	Discrete Data #5							X
	1 0 A	1	0	1	1	1	1	0	0	Discrete Data #5							X
1 0 B	1	0	1	1	1	1	0	0	Discrete Data #5	X							
1 1 4	1	0	1	1	1	1	0	0	Fuel Transfer Indications	X							
2 7 5	0 0 1	1	0	1	1	1	1	0	1	Discrete Data #6	X		X				
	0 0 2	1	0	1	1	1	1	0	1	Discrete Data #6			X				
	0 0 3	1	0	1	1	1	1	0	1	Discrete Data #6			X				
	0 1 8	1	0	1	1	1	1	0	1	Discrete Data #6			X				
	0 1 C	1	0	1	1	1	1	0	1	Discrete Data #6			X				
	0 2 5	1	0	1	1	1	1	0	1	Discrete Data #6			X				
	0 2 9	1	0	1	1	1	1	0	1	Discrete Data #6			X				
	0 2 B	1	0	1	1	1	1	0	1	Discrete Data #6			X				
	0 2 F	1	0	1	1	1	1	0	1	Discrete Data #6			X				
	0 3 5	1	0	1	1	1	1	0	1	Discrete Data #6			X				
	0 3 8	1	0	1	1	1	1	0	1	IR Discrete Word #2			X				
	0 3 B	1	0	1	1	1	1	0	1	Discrete Data #6			X				
	0 3 F	1	0	1	1	1	1	0	1	Discrete Data #6			X				
	0 4 A	1	0	1	1	1	1	0	1	T/U CAP-R Tank 5-8			X				
	0 4 D	1	0	1	1	1	1	0	1	Discrete Data #6							X
	0 5 A	1	0	1	1	1	1	0	1	Sensor Valves Right Wing Tank							X
	0 5 6	1	0	1	1	1	1	0	1	Discrete Data #6							X
	0 6 0	1	0	1	1	1	1	0	1	Discrete Data #6			X				
	1 0 A	1	0	1	1	1	1	0	1	Discrete Data #6			X				
1 0 B	1	0	1	1	1	1	0	1	Discrete Data #6	X							
1 1 4	1	0	1	1	1	1	0	1	Miscellaneous Warning	X							

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Code No. (Octal)	Eqpt. ID (Hex)	Transmission Order Bit Position								Parameter	Data				Notes & Cross Ref. to Tables in Att. 6	
		1	2	3	4	5	6	7	8		BNR	BCD	DISC	SAL		
2 7 6	0 0 2	1	0	1	1	1	1	1	0	Discrete Data #7	X			X		
	0 1 8	1	0	1	1	1	1	1	0	Discrete Data #7				X		
	0 1 C	1	0	1	1	1	1	1	0	Discrete Data #7				X		
	0 2 5	1	0	1	1	1	1	1	0	Discrete Status 8 EFIS				X		
	0 2 9	1	0	1	1	1	1	1	0	Discrete Data #7				X		
	0 2 F	1	0	1	1	1	1	1	0	Discrete Data #7				X		
	0 3 F	1	0	1	1	1	1	1	0	Discrete Data #7				X		
	0 4 D	1	0	1	1	1	1	1	0	T/U CAP-R Tank 9-12						
	0 5 0	1	0	1	1	1	1	1	0	VDR Mode				X		
	0 5 6	1	0	1	1	1	1	1	0	Discrete Data #7				X		
	0 5 8	1	0	1	1	1	1	1	0	Output Status Word #2				X		
	0 5 A	1	0	1	1	1	1	1	0	Discrete Data #7				X		
	0 6 0	1	0	1	1	1	1	1	0	Discrete Data #7			X			
	0 B B	1	0	1	1	1	1	1	0	Discrete Data #7			X			
	1 1 4	1	0	1	1	1	1	1	0	Discrete Data #7			X			
	0 0 1	1	0	1	1	1	1	1	0	FCC to Simulator Control Word - Simulator Use Only	X					
	0 0 2	1	0	1	1	1	1	1	0	FMC to Simulator Control Word - Simulator Use Only	X					
	0 0 3	1	0	1	1	1	1	1	0	TCC to Simulator Control Word - Simulator Use Only	X					
2 7 7	X X X	1	0	1	1	1	1	1	1	General Test Word	X			X		Note 1
	0 0 4	1	0	1	1	1	1	1	1	IRS Maintenance Discrete				X		
	0 1 8	1	0	1	1	1	1	1	1	Discrete Data #8				X		
	0 3 8	1	0	1	1	1	1	1	1	IR Test				X		
	0 4 D	1	0	1	1	1	1	1	1	T/U CAP-R Tank 13-14						
	1 1 4	1	0	1	1	1	1	1	1	Fuel Transfer and CG Status				X		
3 0 0	0 0 1	1	1	0	0	0	0	0	0	Application Dependent	X			X		
	0 1 A	1	1	0	0	0	0	0	0	Application Dependent				X		
	0 3 D	1	1	0	0	0	0	0	0	Application Dependent				X		
	0 5 A	1	1	0	0	0	0	0	0	Internal Parameter for SPATIAAL						
	1 0 A	1	1	0	0	0	0	0	0	ECU Internal Temperature		X				
	1 0 B	1	1	0	0	0	0	0	0	ECU Internal Temperature		X				
	T B D	1	1	0	0	0	0	0	0	Data Loader Address Label (Low Speed)				X		
	1	1	0	0	0	0	0	0	FMC 1 - System Address Label				X	See Attachment 11		
3 0 1	0 0 1	1	1	0	0	0	0	0	1	Application Dependent	X			X		
	0 0 2	1	1	0	0	0	0	0	1	Application Dependent				X		
	0 1 A	1	1	0	0	0	0	0	1	Application Dependent				X		
	0 5 6	1	1	0	0	0	0	0	1	Application Dependent				X		
	0 5 A	1	1	0	0	0	0	0	1	Internal Parameter for SPATIAAL						
	0 6 0	1	1	0	0	0	0	0	1	Application Dependent				X		
	1 0 A	1	1	0	0	0	0	0	1	Demanded Fuel Metering Valve Position		X				
	1 0 B	1	1	0	0	0	0	0	1	Demanded Fuel Metering Valve Position		X				
	1	1	0	0	0	0	0	1	FMC 2 - System Address Label				X	See Attachment 11		
3 0 2	0 0 1	1	1	0	0	0	0	1	0	Application Dependent	X			X		
	0 0 2	1	1	0	0	0	0	1	0	Application Dependent				X		
	0 1 A	1	1	0	0	0	0	1	0	Application Dependent				X		
	0 5 6	1	1	0	0	0	0	1	0	Application Dependent				X		
	0 5 A	1	1	0	0	0	0	1	0	Internal Parameter for SPATIAAL						
	0 6 0	1	1	0	0	0	0	1	0	Application Dependent				X		
	1 0 A	1	1	0	0	0	0	1	0	Demanded Variable Stator Vane Position		X				
	1 0 B	1	1	0	0	0	0	1	0	Demanded Variable Stator Vane Position		X				
		1	1	0	0	0	0	1	0	AIDS (DFDAU) - System Address Label					X	
3 0 3	0 0 1	1	1	0	0	0	0	1	1	Application Dependent	X			X		
	0 0 2	1	1	0	0	0	0	1	1	Application Dependent				X		
	0 1 A	1	1	0	0	0	0	1	1	Application Dependent				X		
	0 5 6	1	1	0	0	0	0	1	1	Application Dependent				X		
	0 5 A	1	1	0	0	0	0	1	1	Internal Parameter for SPATIAAL						
	0 6 0	1	1	0	0	0	0	1	1	Application Dependent				X		
	1 0 A	1	1	0	0	0	0	1	1	Demanded Variable Bleed Valve Position		X				
	1 0 B	1	1	0	0	0	0	1	1	Demanded Variable Bleed Valve Position		X				
		1	1	0	0	0	0	1	1	CFDIU - System Address Label					X	
3 0 4	0 0 1	1	1	0	0	0	1	0	0	Application Dependent	X			X		
	0 1 A	1	1	0	0	0	1	0	0	Application Dependent				X		
	0 5 A	1	1	0	0	0	1	0	0	Internal Parameter for SPATIAAL						
	1 0 A	1	1	0	0	0	1	0	0	Demanded HPT Clearance Valve Position		X				
	1 0 B	1	1	0	0	0	1	0	0	Demanded HPT Clearance Valve Position		X				
		1	1	0	0	0	1	0	0	ACARS - System Address Label					X	

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Code No. (Octal)	Eqpt. ID (Hex)	Transmission Order Bit Position								Parameter	Data				Notes & Cross Ref. to Tables in Att. 6
		1	2	3	4	5	6	7	8		BNR	BCD	DISC	SAL	
3 0 5	0 0 1	1	1	0	0	0	1	0	1	Application Dependent			X		See Attachment 11
	0 1 A	1	1	0	0	0	1	0	1	Application Dependent			X		
	0 5 A	1	1	0	0	0	1	0	1	Internal Parameter for SPATIAAL	X				
	1 0 A	1	1	0	0	0	1	0	1	Demanded LPT Clearance Valve Position	X				
	1 0 B	1	1	0	0	0	1	0	1	Demanded LPT Clearance Valve Position	X				
		1	1	0	0	0	1	0	1	Weight/Balance System - System Address Label				X	
3 0 6	0 0 1	1	1	0	0	0	1	1	0	Application Dependent			X		See Attachment 11
	0 1 A	1	1	0	0	0	1	1	0	Application Dependent			X		
	0 5 A	1	1	0	0	0	1	1	0	Internal Parameter for SPATIAAL	X				
		1	1	0	0	0	1	1	0	TCAS - System Address Label				X	
3 0 7	0 0 1	1	1	0	0	0	1	1	1	Application Dependent			X		See Attachment 11
	0 1 A	1	1	0	0	0	1	1	1	Application Dependent			X		
	0 5 A	1	1	0	0	0	1	1	1	Internal Parameter for SPATIAAL	X				
		1	1	0	0	0	1	1	1	Satellite Data Unit (SDU) - System Address Label				X	
3 1 0	0 0 2	1	1	0	0	1	0	0	0	Present Position - Latitude	X				6-27 See Attachment 11
	0 0 4	1	1	0	0	1	0	0	0	Present Position - Latitude	X				
	0 2 9	1	1	0	0	1	0	0	0	Aileron Position	X				
	0 3 8	1	1	0	0	1	0	0	0	Present Position - Latitude	X				
	0 4 D	1	1	0	0	1	0	0	0	COMP CAP - TANK	X				
	0 5 6	1	1	0	0	1	0	0	0	Present Position Latitude	X				
	0 5 A	1	1	0	0	1	0	0	0	Internal Parameter for SPATIAAL	X				
	0 6 0	1	1	0	0	1	0	0	0	Present Postion Latitude	X				
	1 1 4	1	1	0	0	1	0	0	0	Right Outer Tank Fuel Quantity	X				
		1	1	0	0	1	0	0	0	GPWS - System Address Label				X	
3 1 1	0 0 2	1	1	0	0	1	0	0	1	Present Position - Longitude	X				6-27 See Attachment 11
	0 0 4	1	1	0	0	1	0	0	1	Present Position - Longitude	X				
	0 2 9	1	1	0	0	1	0	0	1	Aileron Trim	X				
	0 3 8	1	1	0	0	1	0	0	1	Present Position - Longitude	X				
	0 3 B	1	1	0	0	1	0	0	1	Control Wheel Roll Force	X				
	0 5 6	1	1	0	0	1	0	0	1	Present Postion Longitude	X				
	0 5 A	1	1	0	0	1	0	0	1	Internal Parameter for SPATIAAL	X				
	0 6 0	1	1	0	0	1	0	0	1	Present Position Longitude	X				
	1 1 4	1	1	0	0	1	0	0	1	Right Outer Tank Fuel Quantity	X				
		1	1	0	0	1	0	0	1	GNLU 1 - System Address Label				X	
3 1 2	0 0 2	1	1	0	0	1	0	1	0	Ground Speed	X				6-27 See Attachment 11
	0 0 4	1	1	0	0	1	0	1	0	Ground Speed	X				
	0 0 5	1	1	0	0	1	0	1	0	Ground Speed	X				
	0 2 9	1	1	0	0	1	0	1	0	Rudder Position	X				
	0 3 8	1	1	0	0	1	0	1	0	Ground Speed	X				
	0 5 6	1	1	0	0	1	0	1	0	Ground Speed	X				
	0 5 A	1	1	0	0	1	0	1	0	Fuel Quantity ACT 1	X				
	0 6 0	1	1	0	0	1	0	1	0	Ground Speed	X				
	1 1 4	1	1	0	0	1	0	1	0	Additional Center Tank (Act 1) Fuel Quantity	X				
		1	1	0	0	1	0	1	0	GNLU 2 - System Address Label				X	
3 1 3	0 0 2	1	1	0	0	1	0	1	1	Track Angle - True	X				See Attachment 11
	0 0 4	1	1	0	0	1	0	1	1	Track Angle - True	X				
	0 2 5	1	1	0	0	1	0	1	1	Track Angle - True	X				
	0 2 9	1	1	0	0	1	0	1	1	Rudder Trim	X				
	0 3 8	1	1	0	0	1	0	1	1	Track Angle - True	X				
	0 5 6	1	1	0	0	1	0	1	1	Track Angle - True	X				
	0 5 A	1	1	0	0	1	0	1	1	Fuel Quantity ACT 2	X				
	0 6 0	1	1	0	0	1	0	1	1	Track Angle - True	X				
	1 1 4	1	1	0	0	1	0	1	1	Additional Center Tank (Act 2) Fuel Quantity	X				
		1	1	0	0	1	0	1	1	GNLU 3 - System Address Label				X	
3 1 4	0 0 2	1	1	0	0	1	1	0	0	Stabilizer Position Indication (B747-400)	X				See Attachment 11
	0 0 4	1	1	0	0	1	1	0	0	True Heading	X				
	0 2 5	1	1	0	0	1	1	0	0	True Heading	X				
	0 2 9	1	1	0	0	1	1	0	0	Elevator Position	X				
	0 3 8	1	1	0	0	1	1	0	0	True Heading	X				
	0 3 B	1	1	0	0	1	1	0	0	Control Wheel Pitch Force	X				
	0 5 A	1	1	0	0	1	1	0	0	Internal Parameter for SPATIAAL	X				
	1 1 4	1	1	0	0	1	1	0	0	Rear Center Tank (RCT) Fuel Quantity	X				
		1	1	0	0	1	1	0	0	GNU 1 - System Address Label				X	
		1	1	0	0	1	1	0	0					X	

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Code No. (Octal)	Eqpt. ID (Hex)	Transmission Order Bit Position								Parameter	Data				Notes & Cross Ref. to Tables in Att. 6
		1	2	3	4	5	6	7	8		BNR	BCD	DISC	SAL	
3 1 5	0 0 1	1	1	0	0	1	1	0	1	Stabilizer Position	X				
	0 0 2	1	1	0	0	1	1	0	1	Wind Speed	X				
	0 0 4	1	1	0	0	1	1	0	1	Wind Speed	X				
	0 0 5	1	1	0	0	1	1	0	1	Wind Speed	X				
	0 2 9	1	1	0	0	1	1	0	1	Stabilizer Position	X				
	0 3 8	1	1	0	0	1	1	0	1	Wind Speed	X				
	0 5 6	1	1	0	0	1	1	0	1	Wind Speed	X				
	0 5 A	1	1	0	0	1	1	0	1	Internal Parameter for SPATIAAL	X				
	0 6 0	1	1	0	0	1	1	0	1	Wind Speed	X				
	0 A 1	1	1	0	0	1	1	0	1	Stabilizer Position	X				
		1	1	0	0	1	1	0	1	GNU 2 - System Address Label				X	See Attachment 11
3 1 6	0 0 2	1	1	0	0	1	1	1	0	Wind Direction (True)	X				
	0 0 4	1	1	0	0	1	1	1	0	Wind Angle	X				
	0 2 9	1	1	0	0	1	1	1	0	Oil Temperature (Engine)	X				
	0 3 8	1	1	0	0	1	1	1	0	Wind Angle	X				
	0 5 6	1	1	0	0	1	1	1	0	Wind Direction (True)	X				
	0 5 A	1	1	0	0	1	1	1	0	Internal Parameter for SPATIAAL	X				
	0 6 0	1	1	0	0	1	1	1	0	Wind Direction (True)	X				
	0 D 0	1	1	0	0	1	1	1	0	Engine Oil Temperature	X				
	1 0 A	1	1	0	0	1	1	1	0	Engine Oil Temperature	X				
	1 0 B	1	1	0	0	1	1	1	0	Engine Oil Temperature	X				
		1	1	0	0	1	1	1	0	GNU 3 - System Address Label				X	See Attachment 11
3 1 7	0 0 2	1	1	0	0	1	1	1	1	Track Angle - Magnetic	X				
	0 0 4	1	1	0	0	1	1	1	1	Track Angle - Magnetic	X				
	0 0 5	1	1	0	0	1	1	1	1	Track Angle - Magnetic	X				
	0 2 5	1	1	0	0	1	1	1	1	Track Angle - Magnetic	X				
	0 2 9	1	1	0	0	1	1	1	1	Oil Pressure (Engine)	X				
	0 3 8	1	1	0	0	1	1	1	1	Track Angle - Magnetic	X				
	0 5 6	1	1	0	0	1	1	1	1	Track Angle - Magnetic	X				
	0 5 A	1	1	0	0	1	1	1	1	Internal Parameter for SPATIAAL	X				
	0 6 0	1	1	0	0	1	1	1	1	Track Angle - Magnetic	X				
	0 D 0	1	1	0	0	1	1	1	1	Oil Pressure (Engine)	X				
3 2 0	0 0 4	1	1	0	1	0	0	0	0	Magnetic Heading	X				
	0 0 5	1	1	0	1	0	0	0	0	Magnetic Heading	X				
	0 2 5	1	1	0	1	0	0	0	0	Magnetic Heading	X				
	0 2 9	1	1	0	1	0	0	0	0	Engine Fuel Pressure	X				
	0 3 5	1	1	0	1	0	0	0	0	Own Aircraft Magnetic Heading	X				
	0 3 8	1	1	0	1	0	0	0	0	Magnetic Heading	X				
	0 4 D	1	1	0	1	0	0	0	0	Density - Tank	X				
	0 5 6	1	1	0	1	0	0	0	0	Magnetic Heading	X				
	0 6 0	1	1	0	1	0	0	0	0	Magnetic Heading	X				
3 2 1	0 0 2	1	1	0	1	0	0	0	1	Drift Angle	X				
	0 0 4	1	1	0	1	0	0	0	1	Drift Angle	X				
	0 0 5	1	1	0	1	0	0	0	1	Drift Angle	X				
	0 2 9	1	1	0	1	0	0	0	1	Engine Fuel Temperature	X				
	0 3 8	1	1	0	1	0	0	0	1	Drift Angle	X				
	0 5 6	1	1	0	1	0	0	0	1	Drift Angle	X				
	0 6 0	1	1	0	1	0	0	0	1	Drift Angle	X				
	1 0 A	1	1	0	1	0	0	0	1	Exhaust gas Temperature (Total)	X				
	1 0 B	1	1	0	1	0	0	0	1	Exhaust gas Temperature (Total)	X				
		1	1	0	1	0	0	0	1	Autothrottle Computer - System Address Label				X	See Attachment 11
3 2 2	0 0 2	1	1	0	1	0	0	1	0	Flight Path Angle	X				
	0 0 4	1	1	0	1	0	0	1	0	Flight Path Angle	X				
	0 0 5	1	1	0	1	0	0	1	0	Flight Path Angle	X				
	0 2 9	1	1	0	1	0	0	1	0	Engine Nacelle Temperature	X				
	0 3 8	1	1	0	1	0	0	1	0	Flight Path Angle	X				
	0 5 6	1	1	0	1	0	0	1	0	Flight Path Angle	X				
	0 6 0	1	1	0	1	0	0	1	0	Flight Path Angle	X				
	1 0 A	1	1	0	1	0	0	1	0	Total Compressor Discharge Temperature	X				
	1 0 B	1	1	0	1	0	0	1	0	Total Compressor Discharge Temperature	X				
		1	1	0	1	0	0	1	0	FCC 1 - System Address Label				X	See Attachment 11

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Code No. (Octal)	Eqpt. ID (Hex)	Transmission Order Bit Position								Parameter	Data				Notes & Cross Ref. to Tables in Att. 6
		1	2	3	4	5	6	7	8		BNR	BCD	DISC	SAL	
3 2 3	0 0 2	1	1	0	1	0	0	1	1	Geometric Altitude	X				6-27
	0 0 4	1	1	0	1	0	0	1	1	Flight Path Acceleration	X				
	0 0 5	1	1	0	1	0	0	1	1	Flight Path Acceleration	X				
	0 3 8	1	1	0	1	0	0	1	1	Flight Path Acceleration	X				
	0 5 6	1	1	0	1	0	0	1	1	Geometric Altitude	X				
	0 6 0	1	1	0	1	0	0	1	1	Geometric Altitude	X				
	1 0 A	1	1	0	1	0	0	1	1	Variable Stator Vane Position	X				
	1 0 B	1	1	0	1	0	0	1	1	Variable Stator Vane Position	X				
		1	1	0	1	0	0	1	1	FCC 2 - System Address Label				X	
3 2 4	0 0 4	1	1	0	1	0	1	0	0	Pitch Angle	X				
	0 0 5	1	1	0	1	0	1	0	0	Pitch Angle	X				
	0 2 5	1	1	0	1	0	1	0	0	Pitch Angle	X				
	0 3 8	1	1	0	1	0	1	0	0	Pitch Angle	X				
	0 4 D	1	1	0	1	0	1	0	0	Tank VSO Quantity	X				
	0 5 A	1	1	0	1	0	1	0	0	Effective Pitch Angle	X				
	1 0 A	1	1	0	1	0	1	0	0	Selected Fuel Metering Valve Position	X				
	1 0 B	1	1	0	1	0	1	0	0	Selected Fuel Metering Valve Position	X				
	1 1 4	1	1	0	1	0	1	0	0	Effective Pitch Angle	X				
		1	1	0	1	0	1	0	0	FCC 3 - System Address Label				X	See Attachment 11
3 2 5	0 0 4	1	1	0	1	0	1	0	1	Roll Angle	X				
	0 0 5	1	1	0	1	0	1	0	1	Roll Angle	X				
	0 1 A	1	1	0	1	0	1	0	1	Engine Control Trim Feedback	X				
	0 2 5	1	1	0	1	0	1	0	1	Roll Angle	X				
	0 2 F	1	1	0	1	0	1	0	1	Stator Vane Feedback	X				
	0 3 8	1	1	0	1	0	1	0	1	Roll Angle	X				
	0 3 F	1	1	0	1	0	1	0	1	Stator Vane Feedback	X				
	0 5 A	1	1	0	1	0	1	0	1	Effective Roll Angle	X				
	1 0 A	1	1	0	1	0	1	0	1	Selected Fuel Metering Vane Position	X				
		1	1	0	1	0	1	0	1	Selected Fuel Metering Vane Position	X				See Attachment 11
	1 1 4	1	1	0	1	0	1	0	1	Effective Roll Angle	X				
		1	1	0	1	0	1	0	1	APU - System Address Label				X	
3 2 6	0 0 4	1	1	0	1	0	1	1	0	Body Pitch Rate	X				
	0 0 5	1	1	0	1	0	1	1	0	Body Pitch Rate	X				
	0 3 8	1	1	0	1	0	1	1	0	Body Pitch Rate	X				
	0 4 D	1	1	0	1	0	1	1	0	Uplift Quantity	X				
	0 5 A	1	1	0	1	0	1	1	0	Maintenance Word	X				
	1 0 A	1	1	0	1	0	1	1	0	Compressor Discharge Static Pressure	X				
	1 0 B	1	1	0	1	0	1	1	0	Compressor Discharge Static Pressure	X				
		1	1	0	1	0	1	1	0	APU Controller - System Address Label				X	See Attachment 11
3 2 7	0 0 4	1	1	0	1	0	1	1	1	Body Roll Rate	X				
	0 0 5	1	1	0	1	0	1	1	1	Body Roll Rate	X				
	0 3 8	1	1	0	1	0	1	1	1	Body Roll Rate	X				
	0 4 D	1	1	0	1	0	1	1	1	Uplift Density	X				
	1 0 A	1	1	0	1	0	1	1	1	Fuel Metering Valve Position	X				
	1 0 B	1	1	0	1	0	1	1	1	Fuel Metering Valve Position	X				
		1	1	0	1	0	1	1	1	Mode Control Panel (MCP) - System Address Label				X	See Attachment 11
3 3 0	0 0 4	1	1	0	1	1	0	0	0	Body Yaw Rate	X				
	0 0 5	1	1	0	1	1	0	0	0	Body Yaw Rate	X				
	0 2 F	1	1	0	1	1	0	0	0	HC/TC Cooling Valve Position Feedback	X				
	0 3 8	1	1	0	1	1	0	0	0	Body Yaw Rate	X				
	0 3 F	1	1	0	1	1	0	0	0	HC/TC Cooling Valve Position Feedback	X				
	1 0 A	1	1	0	1	1	0	0	0	Selected HPT Clearance Valve Position	X				
	1 0 B	1	1	0	1	1	0	0	0	Selected HPT Clearance Valve Position	X				
		1	1	0	1	1	0	0	0	FMC 3 - System Address Label				X	See Attachment 11
3 3 1	0 0 4	1	1	0	1	1	0	0	1	Body Longitudinal Acceleration	X				
	0 0 5	1	1	0	1	1	0	0	1	Body Longitudinal Acceleration	X				
	0 2 F	1	1	0	1	1	0	0	1	LTC Cooling Valve Position Feedback	X				
	0 3 8	1	1	0	1	1	0	0	1	Body Longitudinal Acceleration	X				
	0 3 F	1	1	0	1	1	0	0	1	LTC Cooling Valve Position Feedback	X				
	1 0 A	1	1	0	1	1	0	0	1	Selected LPT Clearance Valve Position	X				
	1 0 B	1	1	0	1	1	0	0	1	Selected LPT Clearance Valve Position	X				
		1	1	0	1	1	0	0	1	ATC Transponder - System Address Label				X	See Attachment 11

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Code No. (Octal)	Eqpt. ID (Hex)	Transmission Order Bit Position						Parameter	Data				Notes & Cross Ref. to Tables in Att. 6		
		1	2	3	4	5	6		7	8	BNR	BCD		DISC	SAL
3 3 2	0 0 4	1	1	0	1	1	0	1	0	Body Lateral Acceleration	X				
	0 0 5	1	1	0	1	1	0	1	0	Body Lateral Acceleration	X				
	0 2 F	1	1	0	1	1	0	1	0	A/O Heat Exchanger Valve Postion Feedback	X				
	0 3 8	1	1	0	1	1	0	1	0	Body Lateral Acceleration	X				
	0 3 F	1	1	0	1	1	0	1	0	A/O Heat Exchanger Valve Postion Feedback	X				
		1 1	0	1	1	0	1	0		DADC - System Address Label			X	See Attachment 11	
3 3 3	0 0 4	1	1	0	1	1	0	1	1	Body Normal Acceleration	X				
	0 0 5	1	1	0	1	1	0	1	1	Body Normal Acceleration	X				
	0 2 F	1	1	0	1	1	0	1	1	Acceleration Fuel Flow Limit	X				
	0 3 8	1	1	0	1	1	0	1	1	Body Normal Acceleration	X				
	0 3 F	1	1	0	1	1	0	1	1	Acceleration Fuel Flow Limit	X				
3 3 4	0 0 4	1	1	0	1	1	1	0	0	Platform Heading	X				
	0 0 5	1	1	0	1	1	1	0	0	Platform Heading	X				
	0 2 F	1	1	0	1	1	1	0	0	Fuel Flow Command	X				
	0 3 8	1	1	0	1	1	1	0	0	Platform Heading	X				
	0 3 F	1	1	0	1	1	1	0	0	Fuel Flow Command	X				
		1 1	0	1	1	1	0	0		CTU - System Address Label			X	See Attachment 11	
3 3 5	0 0 2	1	1	0	1	1	1	0	1	Track Angle Rate	X				
	0 0 4	1	1	0	1	1	1	0	1	Track Angle Rate	X				
	0 0 5	1	1	0	1	1	1	0	1	Track Angle Rate	X				
	0 2 F	1	1	0	1	1	1	0	1	2.5 Bld Actuator Postion	X				
	0 3 8	1	1	0	1	1	1	0	1	Track Angle Rate	X				
	0 3 F	1	1	0	1	1	1	0	1	2.5 Bld Actuator Postion	X				
	0 5 6	1	1	0	1	1	1	0	1	Track Angle Rate	X				
	0 6 0	1	1	0	1	1	1	0	1	Track Angle Rate	X				
	1 0 A	1	1	0	1	1	1	0	1	Selected Variable Bleed Valve Position	X				
	1 0 B	1	1	0	1	1	1	0	1	Selected Variable Bleed Valve Position	X				
3 3 6	0 0 2	1	1	0	1	1	1	1	0	Maximum Climb Angle	X				
	0 0 4	1	1	0	1	1	1	1	0	Inertial Pitch Rate	X				
	0 0 5	1	1	0	1	1	1	1	0	Inertial Pitch Rate	X				
	0 1 A	1	1	0	1	1	1	1	0	Engine Torque	X				
	0 2 F	1	1	0	1	1	1	1	0	N2 Corrected to Sta. 2.5	X				
	0 3 8	1	1	0	1	1	1	1	0	Inertial Pitch Rate	X				
	0 3 F	1	1	0	1	1	1	1	0	N2 Corrected to Sta. 2.5	X				
	1 0 A	1	1	0	1	1	1	1	0	Variable Bleed Value Position	X				
	1 0 B	1	1	0	1	1	1	1	0	Variable Bleed Value Position	X				
3 3 7	0 0 2	1	1	0	1	1	1	1	1	EPR - Required for Level Flight	X				
	0 0 2	1	1	0	1	1	1	1	1	N1 - Required for Level Flight	X				
	0 0 4	1	1	0	1	1	1	1	1	Inertial Roll Rate	X				
	0 0 5	1	1	0	1	1	1	1	1	Inertial Roll Rate	X				
	0 1 A	1	1	0	1	1	1	1	1	Engine Rating	X				
	0 3 8	1	1	0	1	1	1	1	1	Inertial Roll Rate	X				
	1 0 A	1	1	0	1	1	1	1	1	HPT Clearance Valve Position	X				
	1 0 B	1	1	0	1	1	1	1	1	HPT Clearance Valve Position	X				
3 4 0	0 0 3	1	1	1	0	0	0	0	0	EPR Actual	X				
	0 0 4	1	1	1	0	0	0	0	0	Inertial Yaw Rate	X				
	0 0 4	1	1	1	0	0	0	0	0	Track Angle Rate	X				
	0 0 5	1	1	1	0	0	0	0	0	Inertial Yaw Rate	X				
	0 1 A	1	1	1	0	0	0	0	0	EPR Actual	X				
	0 2 9	1	1	1	0	0	0	0	0	EPR Actual (Engine Direct)	X				
	0 2 D	1	1	1	0	0	0	0	0	EPR Actual	X				
	0 2 F	1	1	1	0	0	0	0	0	EPR Actual	X				
	0 3 3	1	1	1	0	0	0	0	0	EPR Actual	X				
	0 3 F	1	1	1	0	0	0	0	0	EPR Actual	X				
	1 3 A	1	1	1	0	0	0	0	0	N1 Take Off	X				
	1 4 0	1	1	1	0	0	0	0	0	Pressure Ratio (Pt/Ps)	X				
		1 1	1	0	0	0	0	0	0	HF DATA Radio/Data #1 - System Address Label			X	See Attachment 11	

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Code No. (Octal)	Eqpt. ID (Hex)	Transmission Order Bit Position								Parameter	Data				Notes & Cross Ref. to Tables in Att. 6
		1	2	3	4	5	6	7	8		BNR	BCD	DISC	SAL	
3 4 1	0 0 2	1	1	1	0	0	0	0	1	Target N1	X				
	0 0 3	1	1	1	0	0	0	0	1	N1 Command	X				
	0 0 3	1	1	1	0	0	0	0	1	EPR Command	X				
	0 0 4	1	1	1	0	0	0	0	1	Grid Heading	X				
	0 1 A	1	1	1	0	0	0	0	1	N1 Command	X				
	0 1 A	1	1	1	0	0	0	0	1	EPR Command	X				
	0 2 9	1	1	1	0	0	0	0	1	N1 Command (Engine)	X				
	0 2 9	1	1	1	0	0	0	0	1	EPR Command (Engine)	X				
	0 2 F	1	1	1	0	0	0	0	1	N1 Command	X				
	0 2 F	1	1	1	0	0	0	0	1	EPR Command	X				
	0 3 8	1	1	1	0	0	0	0	1	Grid Heading	X				
	0 3 F	1	1	1	0	0	0	0	1	EPR Command	X				
	0 4 D	1	1	1	0	0	0	0	1	I/O S/W REV 1&2	X				
	1 0 A	1	1	1	0	0	0	0	1	Command Fan Speed	X				
	1 0 B	1	1	1	0	0	0	0	1	Command Fan Speed	X				
	1 3 A	1	1	1	0	0	0	0	1	N1 Reference	X				
3 4 2	1 4 0	1	1	1	0	0	0	0	1	Pressure Ratio (Ps/Pso)	X				
	0 0 2	1	1	1	0	0	0	1	0	N1 Bug Drive	X				
	0 0 3	1	1	1	0	0	0	1	0	N1 Limit	X				
	0 0 3	1	1	1	0	0	0	1	0	EPR Limit	X				
	0 1 A	1	1	1	0	0	0	1	0	N1 Maximum	X				
	0 1 A	1	1	1	0	0	0	1	0	EPR Maximum	X				
	0 2 9	1	1	1	0	0	0	1	0	N1 Limit (TCC)	X				
	0 2 9	1	1	1	0	0	0	1	0	EPR Limit (TOC)	X				
	0 2 F	1	1	1	0	0	0	1	0	Maximum Available EPR	X				
	0 3 B	1	1	1	0	0	0	1	0	N1 Limit	X				
	0 3 B	1	1	1	0	0	0	1	0	EPR Limit	X				
	0 3 F	1	1	1	0	0	0	1	0	Maximum Available EPR	X				
	0 4 D	1	1	1	0	0	0	1	0	S/W Rev-Tank	X				
	1 0 A	1	1	1	0	0	0	1	0	Maximum Allowed Fan Speed	X				
	1 0 B	1	1	1	0	0	0	1	0	Maximum Allowed Fan Speed	X				
	1 4 0	1	1	1	0	0	0	1	0	Air Density Ratio	X				
3 4 3	0 0 3	1	1	1	0	0	0	1	1	N1 Derate	X				
	0 0 3	1	1	1	0	0	0	1	1	EPR Rate	X				
	0 1 A	1	1	1	0	0	0	1	1	N1 Demand	X				
	1 0 A	1	1	1	0	0	0	1	1	N1 Command vs. TLA	X				
	1 0 B	1	1	1	0	0	0	1	1	N1 Command vs. TLA	X				
3 4 4	0 1 A	1	1	1	0	0	1	0	0	N2	X				
	0 1 C	1	1	1	0	0	1	0	0	N2	X				
	0 2 9	1	1	1	0	0	1	0	0	N2	X				
	0 2 F	1	1	1	0	0	1	0	0	N2	X				
	0 3 3	1	1	1	0	0	1	0	0	N2	X				
	0 3 F	1	1	1	0	0	1	0	0	N2	X				
	0 4 D	1	1	1	0	0	1	0	0	Fuel Discretes			X		
	0 D 0	1	1	1	0	0	1	0	0	N2	X				
	1 0 A	1	1	1	0	0	1	0	0	Selected Actual Core Speed	X				
	1 0 B	1	1	1	0	0	1	0	0	Selected Actual Core Speed	X				
	1 3 A	1	1	1	0	0	1	0	0	N2 Speed	X				
	1 1	1	1	1	0	0	1	0	0	HF DATA Radio/Data #2 - System Address Label				X	See Attachment 11
3 4 5	0 0 2	1	1	1	0	0	1	0	1	NDB Effectivity		X			
	0 1 A	1	1	1	0	0	1	0	1	Exhaust Gas Temperature	X				
	0 1 C	1	1	1	0	0	1	0	1	Exhaust Gas Temperature	X				
	0 2 9	1	1	1	0	0	1	0	1	Exhaust Gas Temperature	X				
	0 2 F	1	1	1	0	0	1	0	1	Exhaust Gas Temperature	X				
	0 3 3	1	1	1	0	0	1	0	1	Exhaust Gas Temperature	X				
	0 3 F	1	1	1	0	0	1	0	1	Exhaust Gas Temperature	X				
	0 4 D	1	1	1	0	0	1	0	1	Discretes Status 1&3			X		
	0 D 0	1	1	1	0	0	1	0	1	EGT	X				
	1 0 A	1	1	1	0	0	1	0	1	Selected Exhaust Gas Temperature (Total)	X				
	1 0 B	1	1	1	0	0	1	0	1	Selected Exhaust Gas Temperature (Total)	X				
	1 3 A	1	1	1	0	0	1	0	1	EGT Trimmed	X				
	1 1	1	1	1	0	0	1	0	1	Remote Data Concentrator - System Address Label				X	

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Code No. (Octal)	Eqpt. ID (Hex)	Transmission Order Bit Position						Parameter	Data				Notes & Cross Ref. to Tables in Att. 6		
		1	2	3	4	5	6		7	8	BNR	BCD		DISC	SAL
3 4 6	0 0 3	1	1	1	0	0	1	1	0	N1 Actual	X				
	0 1 A	1	1	1	0	0	1	1	0	N1 Actual	X				
	0 2 F	1	1	1	0	0	1	1	0	N1 Actual	X				
	0 3 3	1	1	1	0	0	1	1	0	N1 Actual	X				
	0 3 F	1	1	1	0	0	1	1	0	N1 Actual	X				
	0 4 D	1	1	1	0	0	1	1	0	Cable Cap-Hi-Z	X				
	0 D 0	1	1	1	0	0	1	1	0	N1	X				
	1 0 A	1	1	1	0	0	1	1	0	Selected Actual Fan Speed	X				
	1 0 B	1	1	1	0	0	1	1	0	Selected Actual Fan Speed	X				
	1 3 A	1	1	1	0	0	1	1	0	N1 Speed Actual	X				
3 4 7	0 1 8	1	1	1	0	0	1	1	1	Antenna Control	X				
	0 2 9	1	1	1	0	0	1	1	1	Fuel Flow (Engine)	X				
	0 3 0	1	1	1	0	0	1	1	1	Sector Control	X				
	0 3 5	1	1	1	0	0	1	1	1	Antenna Control	X				
	0 D 0	1	1	1	0	0	1	1	1	Fuel Flow	X				
	1 0 A	1	1	1	0	0	1	1	1	LPT Clearance Valve Position	X				
	1 0 B	1	1	1	0	0	1	1	1	LPT Clearance Valve Position	X				
	1 3 A	1	1	1	0	0	1	1	1	Fuel Flow	X				
3 5 0	0 0 3	1	1	1	0	1	0	0	0	Maintenance Data #1			X		
	0 0 4	1	1	1	0	1	0	0	0	IRS Maintenance Discrete			X		
	0 0 6	1	1	1	0	1	0	0	0	Maintenance Data #1			X		
	0 0 B	1	1	1	0	1	0	0	0	GPS Test Word (manufacturer specific)			X		
	0 1 8	1	1	1	0	1	0	0	0	Maintenance Data #1			X		
	0 1 9	1	1	1	0	1	0	0	0	CFDS Bite Fault Summary Word for HFDR			X		
	0 1 A	1	1	1	0	1	0	0	0	Maintenance Data #1			X		
	0 1 C	1	1	1	0	1	0	0	0	Maintenance Data #1			X		
	0 2 3	1	1	1	0	1	0	0	0	Maintenance Data #1			X		
	0 2 4	1	1	1	0	1	0	0	0	MU Output Data Word Failure Status			X		
	0 2 5	1	1	1	0	1	0	0	0	Maintenance Data #1			X		
	0 2 7	1	1	1	0	1	0	0	0	Maintenance Data #1			X		
	0 2 9	1	1	1	0	1	0	0	0	Maintenance Data #1			X		
	0 2 F	1	1	1	0	1	0	0	0	Maintenance Data #1			X		
	0 3 2	1	1	1	0	1	0	0	0	Maintenance Data #1			X		
	0 3 5	1	1	1	0	1	0	0	0	Maintenance Data #1			X		
	0 3 8	1	1	1	0	1	0	0	0	IRS Maintenance Word #1			X		
	0 3 D	1	1	1	0	1	0	0	0	Maintenance Data #1			X		
	0 3 E	1	1	1	0	1	0	0	0	Maintenance Data #1			X		
	0 3 F	1	1	1	0	1	0	0	0	Maintenance Data #1			X		
	0 4 0	1	1	1	0	1	0	0	0	Maintenance Data #1			X		
	0 4 D	1	1	1	0	1	0	0	0	Maintenance Data FQIS 1-3			X		
	0 5 0	1	1	1	0	1	0	0	0	VDR Fault Summary Word			X		
	0 5 3	1	1	1	0	1	0	0	0	CFDS Bite Fault Summary Word for HFDR			X		
	0 5 5	1	1	1	0	1	0	0	0	ILS Maintenance Word			X		
	1 0 A	1	1	1	0	1	0	0	0	Maintenance Data #1			X		
	1 0 B	1	1	1	0	1	0	0	0	Maintenance Data #1			X		
	1 1 4	1	1	1	0	1	0	0	0	Fuel Density	X				
	1 1 5	1	1	1	0	1	0	0	0	Maintenance Data #1			X		
	1 4 0	1	1	1	0	1	0	0	0	Maintenance Data #1			X		
	1 4 4	1	1	1	0	1	0	0	0	CDTI Fault Summary Word			X		
	2 4 1	1	1	1	0	1	0	0	0	Maintenance Data #1			X		
	3 4 1	1	1	1	0	1	0	0	0	Maintenance Data #1			X		

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Code No. (Octal)	Eqpt. ID (Hex)	Transmission Order Bit Position								Parameter	Data				Notes & Cross Ref. to Tables in Att. 6
		1	2	3	4	5	6	7	8		BNR	BCD	DISC	SAL	
3 5 1	0 0 6	1	1	1	0	1	0	0	1	Maintenance Data #2			X		
	0 0 B	1	1	1	0	1	0	0	1	SRU Test Word (manufacturer specific)			X		
	0 1 A	1	1	1	0	1	0	0	1	Maintenance Data #2			X		
	0 1 C	1	1	1	0	1	0	0	1	Maintenance Data #2			X		
	0 2 4	1	1	1	0	1	0	0	1	MU Output Data Word Failure Status			X		
	0 2 5	1	1	1	0	1	0	0	1	Maintenance Data #2			X		
	0 2 9	1	1	1	0	1	0	0	1	Maintenance Data #2			X		
	0 2 E	1	1	1	0	1	0	0	1	Maintenance Data #2			X		
	0 2 F	1	1	1	0	1	0	0	1	Maintenance Data #2			X		
	0 3 1	1	1	1	0	1	0	0	1	Maintenance Data #2			X		
	0 3 8	1	1	1	0	1	0	0	1	IRS Maintenance Word #2			X		
	0 3 F	1	1	1	0	1	0	0	1	Maintenance Data #2			X		
	0 4 D	1	1	1	0	1	0	0	1	Maintenance Data FQIS 1&3			X		
	0 5 5	1	1	1	0	1	0	0	1	MMR Maintenance Word			X		
	1 0 A	1	1	1	0	1	0	0	1	Maintenance Data #2			X		
	1 0 B	1	1	1	0	1	0	0	1	Maintenance Data #2			X		
	1 1 4	1	1	1	0	1	0	0	1	Inner Tank 1 Probe Capacitance		X			
	1 4 0	1	1	1	0	1	0	0	1	Maintenance Data #2			X		
3 5 2	0 1 A	1	1	1	0	1	0	1	0	Maintenance Data #3			X		
	0 1 C	1	1	1	0	1	0	1	0	Maintenance Data #2			X		
	0 2 4	1	1	1	0	1	0	1	0	Maintenance Word			X		
	0 2 5	1	1	1	0	1	0	1	0	Maintenance Data #2			X		
	0 2 E	1	1	1	0	1	0	1	0	Maintenance Data #2			X		
	0 2 F	1	1	1	0	1	0	1	0	Maintenance Data #2			X		
	0 3 F	1	1	1	0	1	0	1	0	Maintenance Data #2			X		
	0 4 D	1	1	1	0	1	0	1	0	Maintenance Data FQIS 1-4			X		
	0 5 5	1	1	1	0	1	0	1	0	MLS Bite Status			X		
	1 0 A	1	1	1	0	1	0	1	0	Maintenance Data #2			X		
	1 0 B	1	1	1	0	1	0	1	0	Maintenance Data #2			X		
	1 1 4	1	1	1	0	1	0	1	0	Center, ACT & RCT Probe Capacitance		X			
	1 4 0	1	1	1	0	1	0	1	0	Maintenance Data #3 Flight Count	X				
3 5 3	0 1 A	1	1	1	0	1	0	1	1	Maintenance Data #4			X		
	0 1 C	1	1	1	0	1	0	1	1	Maintenance Data #4			X		
	0 2 5	1	1	1	0	1	0	1	1	Maintenance Data #4			X		
	0 2 F	1	1	1	0	1	0	1	1	Maintenance Data #4			X		
	0 3 8	1	1	1	0	1	0	1	1	IRS Maintenance Word #3			X		
	0 3 D	1	1	1	0	1	0	1	1	Maintenance Data #4			X		
	0 3 F	1	1	1	0	1	0	1	1	Maintenance Data #4			X		
	0 4 D	1	1	1	0	1	0	1	1	Maintenance Data FQIS 1-4			X		
	0 D 0	1	1	1	0	1	0	1	1	Vibration	X				
	1 0 A	1	1	1	0	1	0	1	1	Maintenance Data #4			X		
	1 0 B	1	1	1	0	1	0	1	1	Maintenance Data #4			X		
	1 1 4	1	1	1	0	1	0	1	1	Inner Tank 1 Probe Capacitance		X			
3 5 4	0 0 2	1	1	1	0	1	1	0	0	Maintenance Data #5			X		
	0 1 A	1	1	1	0	1	1	0	0	Maintenance Data #5			X		
	0 1 C	1	1	1	0	1	1	0	0	Maintenance Data #5			X		
	0 2 F	1	1	1	0	1	1	0	0	Maintenance Data #5			X		
	0 3 D	1	1	1	0	1	1	0	0	N1 Vibration	X				
	0 3 F	1	1	1	0	1	1	0	0	Maintenance Data #5			X		
	0 4 D	1	1	1	0	1	1	0	0	FQIS Tank ID			X		
	0 5 6	1	1	1	0	1	1	0	0	Maintenance Data #5					
	0 6 0	1	1	1	0	1	1	0	0	Maintenance Data #5					
	0 B B	1	1	1	0	1	1	0	0	Maintenance Data #5			X		
	1 0 A	1	1	1	0	1	1	0	0	Maintenance Data #5			X		
	1 0 B	1	1	1	0	1	1	0	0	Maintenance Data #5			X		
3 5 5	0 0 B	1	1	1	0	1	1	0	1	GNSS Fault Summary			X		
	0 2 7	1	1	1	0	1	1	0	1	MLS Maintenance Data			X		
	0 3 8	1	1	1	0	1	1	0	1	IRS Maintenance Word #4			X		
	0 3 D	1	1	1	0	1	1	0	1	N2 Vibration	X				
	0 4 D	1	1	1	0	1	1	0	1	Maintenance Data FQIS 2-4			X		
	X X X	1	1	1	0	1	1	0	1	Acknowledgement			X		6-5/Note 1

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LABEL CODES

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Code No. (Octal)	Eqpt. ID (Hex)	Transmission Order Bit Position								Parameter	Data				Notes & Cross Ref. to Tables in Att. 6	
		1	2	3	4	5	6	7	8		BNR	BCD	DISC	SAL		
3 5 6	0 3 D	1	1	1	0	1	1	1	0	N3 Vibration	X				6-3/Note 1 Note 1	
	X X X	1	1	1	0	1	1	1	0	Maintenance ISO #5 Message			X			
	Y Y Y	1	1	1	0	1	1	1	0	BITE Status Word	X					
3 5 7	0 0 2	1	1	1	0	1	1	1	1	ISO Alphabet #5 Message	X		X		6-3	
	0 1 7	1	1	1	0	1	1	1	1	ISO Alphabet #5 Message						
	0 2 4	1	1	1	0	1	1	1	1	ISO Alphabet #5 Message						
	0 3 5	1	1	1	0	1	1	1	1	TCAS Intruder Data File						
	0 3 7	1	1	1	0	1	1	1	1	ISO Alphabet #5 Message						
	0 3 D	1	1	1	0	1	1	1	1	BB Vibration						
	0 4 D	1	1	1	0	1	1	1	1	Maintenance Data FQIS 2-3						
	0 5 6	1	1	1	0	1	1	1	1	ISO Alphabet #5 Message						
	0 5 A	1	1	1	0	1	1	1	1	Part Number (Manufacturer - Specific)						
0 6 0	1	1	1	0	1	1	1	1	ISO Alphabet #5 Message			X				
3 6 0	0 0 2	1	1	1	1	0	0	0	0	Flight Information	X				6-33	
	0 0 4	1	1	1	1	0	0	0	0	Potential Vertical Speed	X					
	0 0 5	1	1	1	1	0	0	0	0	Potential Vertical Speed	X					
	0 3 8	1	1	1	1	0	0	0	0	Potential Vertical Speed	X					
	0 3 D	1	1	1	1	0	0	0	0	N1 Rotor Imbalance Angle	X					
	0 5 6	1	1	1	1	0	0	0	0	Flight Information	X					
	0 6 0	1	1	1	1	0	0	0	0	Flight Information	X					
	1 0 A	1	1	1	1	0	0	0	0	Throttle Rate of Change	X					
	1 0 B	1	1	1	1	0	0	0	0	Throttle Rate of Change	X					
	1 4 2	1	1	1	1	0	0	0	0	RAIM Status Word	X					
		1	1	1	1	0	0	0	0	ACCESS - System Address Label				X		See Attachment 11
3 6 1	0 0 4	1	1	1	1	0	0	0	1	Altitude (Inertial)	X					
	0 0 5	1	1	1	1	0	0	0	1	Altitude (Inertial)	X					
	0 3 8	1	1	1	1	0	0	0	1	Altitude (Inertial)	X					
	0 3 D	1	1	1	1	0	0	0	1	LPT Rotor Imbalance Angle (737 only)	X					
	1 0 A	1	1	1	1	0	0	0	1	Derivative of Thrust vs. N1	X					
	1 0 B	1	1	1	1	0	0	0	1	Derivative of Thrust vs. N1	X					
	1	1	1	1	0	0	0	1	EFIS - System Address Label				X	See Attachment 11		
3 6 2	0 0 4	1	1	1	1	0	0	1	0	Along Track Horizontal Acceleration	X					
	0 3 8	1	1	1	1	0	0	1	0	Along Track Horizontal Acceleration	X					
	1 0 A	1	1	1	1	0	0	1	0	Derivative of Thrust vs. TLA	X					
	1 0 B	1	1	1	1	0	0	1	0	Derivative of Thrust vs. TLA	X					
	1 1 5	1	1	1	1	0	0	1	0	Range Rate	X					
		1	1	1	1	0	0	1	0	PSS - System Address Label				X		See Attachment 11
3 6 3	0 0 4	1	1	1	1	0	0	1	1	Cross Track Acceleration	X					
	0 3 8	1	1	1	1	0	0	1	1	Cross Track Acceleration	X					
	1 0 A	1	1	1	1	0	0	1	1	Corrected Thrust	X					
	1 0 B	1	1	1	1	0	0	1	1	Corrected Thrust	X					
		1	1	1	1	0	0	1	1	System Address Label for CSS				X		See Attachment 11
3 6 4	0 0 4	1	1	1	1	0	1	0	0	Vertical Acceleration	X					
	0 0 5	1	1	1	1	0	1	0	0	Vertical Acceleration	X					
	0 3 8	1	1	1	1	0	1	0	0	Vertical Acceleration	X					
	1 3 A	1	1	1	1	0	1	0	0	N1 APR Rating	X					
		1	1	1	1	0	1	0	0	AES - System Address Label				X		See Attachment 11
3 6 5	0 0 4	1	1	1	1	0	1	0	1	Inertial Vertical Velocity (EFI)	X					
	0 0 5	1	1	1	1	0	1	0	1	Inertial Vertical Velocity (EFI)	X					
	0 3 8	1	1	1	1	0	1	0	1	Inertial Vertical Velocity (EFI)	X					
	1 3 A	1	1	1	1	0	1	0	1	N1 Max Reverse	X					
		1	1	1	1	0	1	0	1	Engine Indication Unit - System Address Label				X		See Attachment 11
3 6 6	0 0 4	1	1	1	1	0	1	1	0	North-South Velocity	X				6-2-1	
	0 3 8	1	1	1	1	0	1	1	0	North-South Velocity	X					
	1 3 A	1	1	1	1	0	1	1	0	IGV Position	X					
		1	1	1	1	0	1	1	0	Multicast - System Address Label				X		See Attachment 11
3 6 7	0 0 4	1	1	1	1	0	1	1	1	East-West Velocity	X					
	0 3 8	1	1	1	1	0	1	1	1	East-West Velocity	X					
	1 3 A	1	1	1	1	0	1	1	1	EGV Request	X					
		1	1	1	1	0	1	1	1	Bridge - System Address Label				X		See Attachment 11
3 7 0	0 0 4	1	1	1	1	1	0	0	0	g	X					
	0 0 5	1	1	1	1	1	0	0	0	g	X					
	0 0 B	1	1	1	1	1	0	0	0	GNSS Height WGS-84 (HAE)	X					
	0 2 5	1	1	1	1	1	0	0	0	Decision Height Selected (EFI)	X					
	0 C 5	1	1	1	1	1	0	0	0	Decision Height Selected (EFI)	X					
3 7 1	0 0 0	1	1	1	1	1	0	0	1	General Aviation Equipment Identifier	X				See Attachment 9B	

ATTACHMENT 1-1
LABEL CODES

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Code No. (Octal)	Eqpt. ID (Hex)	Transmission Order Bit Position								Parameter	Data				Notes & Cross Ref. to Tables in Att. 6
		1	2	3	4	5	6	7	8		BNR	BCD	DISC	SAL	
3 7 2	0 0 5	1	1	1	1	1	0	1	0	Wind Direction - Magnetic	X				See Attachment 11
	1 0 A	1	1	1	1	1	0	1	0	Actual Fan Speed	X				
	1 0 B	1	1	1	1	1	0	1	0	Actual Fan Speed	X				
		1	1	1	1	1	0	1	0	Cabin Terminal #3 - System Address Label				X	
3 7 3	0 0 5	1	1	1	1	1	1	0	0	North-South Velocity - Magnetic	X				See Attachment 11
	1 0 A	1	1	1	1	1	1	0	0	Actual Core Speed	X				
	1 0 B	1	1	1	1	1	1	0	0	Actual Core Speed	X				
		1	1	1	1	1	1	0	0	Cabin Terminal #4 - System Address Label				X	
3 7 4	0 0 5	1	1	1	1	1	1	0	0	East-West Velocity - Magnetic	X				See Attachment 11
	1 0 A	1	1	1	1	1	1	0	0	Left Thrust Reverser Position	X				
	1 0 B	1	1	1	1	1	1	0	0	Left Thrust Reverser Position	X				
		1	1	1	1	1	1	0	0	Cabin Terminal #1 - System Address Label				X	
3 7 5	0 0 4	1	1	1	1	1	1	0	1	Along Heading Acceleration	X				See Attachment 11
	0 0 5	1	1	1	1	1	1	0	1	Along Heading Acceleration	X				
	0 3 3	1	1	1	1	1	1	0	1	Spare DC1	X				
	0 3 8	1	1	1	1	1	1	0	1	Along Heading Acceleration	X				
	1 0 A	1	1	1	1	1	1	0	1	Right Thrust Reverser Position	X				
	1 0 B	1	1	1	1	1	1	0	1	Right Thrust Reverser Position	X				
	X X X	1	1	1	1	1	1	0	1	GPS Differential Correction Word A	X				
		1	1	1	1	1	1	0	1	Cabin Terminal #2 - System Address Label				X	
3 7 6	0 0 4	1	1	1	1	1	1	1	0	Cross Heading Acceleration	X				
	0 0 5	1	1	1	1	1	1	1	0	Cross Heading Acceleration	X				
	0 3 3	1	1	1	1	1	1	1	0	Spare DC2	X				
	0 3 8	1	1	1	1	1	1	1	0	Cross Heading Acceleration	X				
	X X X	1	1	1	1	1	1	1	0	GPS Differential Correction Word B	X				
3 7 7	0 3 0	1	1	1	1	1	1	1	1	Equipment Identification			X		6-17/Note 2
	X X X	1	1	1	1	1	1	1	1	Equipment Identification			X		

[1] XXX or YYY is applicable to all Equipment IDs.

[2] The preferred SSM encoding method for the Equipment Identification Word is according to the Discrete word guidelines. When this label was originally assigned, it was recognized as a non-BNR word. The SSM encoding was according to the BCD and DISC guidelines that were identical at that time. During development of Supplement 4, the SSM for DISC was revised to its current form to provide enhanced failure warning. When the SSM encoding was changed, some systems retained the BCD encoding for the Equipment Identification word and others changed to DISC encoding.

There are ARINC standards that are still active that have the SSM for Equipment Identification designated as BCD. You will need to check with the equipment manufacturer to determine the SSM format.

[3] The Label does not adhere to ARINC 429 Standard Signal Format and contains both BCD and BRN bit encoding depending on the selected mode.

ATTACHMENT 1-2
EQUIPMENT CODES

Equip ID (Hex)	Equipment Type	Equip ID (Hex)	Equipment Type	
000	Not Used	03A	Propulsion Discrete Interface Unit	c-11
001	Flight Control Computer (701)	03B	Autopilot Buffer Unit	c-6
002	Flight Management Computer (702)	03C	Tire Pressure Monitoring System	c-8
003	Thrust Control Computer (703)	03D	Airborne Vibration Monitor (737/757/767)	c-9
004	Inertial Reference System (704)	03E	Center of Gravity Control Computer	
005	Attitude and Heading Ref. System (705)	03F	Full Authority EEC-B	c-7
006	Air Data System (706)	040	Cockpit Printer (740)	c-11
007	Radio Altimeter (707)	041	Satellite Data Unit	
008	Airborne Weather Radar (708)	042		
009	Airborne DME (709)	043		
c-5 00A	FAC (A310)	044		
c-10 00B	Global Positioning System (743)	045		
00C		046	CTU	
c-7 00D	AIDS Data Management Unit	047	Digital Flight Data Recorder	c-14
00E		048		
00F		049		
010	Airborne ILS Receiver (710)	04A	Landing Gear Position Interface Unit	
011	Airborne VOR Receiver (711)	04B	Main Electrical System Controller	c-9
012	Airborne ADF System (712)	04C	Emergency Electrical System Controller	
013		04D	Fuel Qty. Indicating System (757/767)	c-10
014		04E	Fuel Qty. Indicating System (747)	
015		04F		c-14
016	Airborne VHF COM (716)	050	VDR (750)	
017	DEFDARS-AIDS (717)	051		
018	ATC Transponder (718)	052		
019	Airborne HF/SSB System (719)	053	HF Data Unit	
c-5 01A	Electronic Supervisory Control [1]	054		
01B	Digital Slat/Flap Computer (A310)	055	Multi-Mode Receiver (MMR) (755)	
01C	Engine Parameter Digitizer (Engine)	056	GNSS Navigation Landing Unit (GNLU)(756)	c-16
01D	A/P & F/D Mode Control Panel (757/767)	057	Cockpit Voice Recorder (CVR) (757)	
01E	Performance Data Computer (Boeing 737)	058		
01F	Fuel Quantity Totalizer	059		
020	DFS System (720)	05A	Fuel Quan. Indicating System (A320/A321)	
021		05B	Cargo Smoke Detection Unit (A320)	
022		05C	Cabin Pressure Unit (A320)	c-10
023	Ground Prox. Warning System (723)	05D	Zone Controller (A320)	
024	ACARS (724) / CMU Mark 2 (758)	05E	Cargo Heat (A320)	
025	Electronic Flt. Instruments (725)	05F	CIDS (A320)	
026	Flight Warning Computer (726)	060	GNSS Navigation Unit (GNU) (760)	c-16
027	Microwave Landing System (727)	061	High-Speed Data Unit (HSDU)	c-17
028		062		
029	ADDCS (729) and EICAS	063		
02A	Thrust Management Computer	064		
02B	Perf. Nav. Computer System (Boeing 737)	065		
c-6 02C	Digital Fuel Gauging System (A310)	066		
c-5 02D	EPR Indicator (Boeing 757)	067		
c-6 02E	Land Rollout CU/Landing C & LU	068		
c-7 02F	Full Authority EEC-A	069		
030	Airborne Separation Assurance System	06A	AMU (A320)	c-10
031	Chronometer (731)	06B	Battery Charge Limiter (A320)	
032	Pass. Entertainment Tape Reproducer (732)	06C	Flt. Cont. Data Concentrator (A320)	
c-6 033	Propulsion Multiplexer (PMUX)(733)	06D	Landing Gear Prox. Control (A320)	
034	Fault Isolation & Detection System (734)	06E	Brake Steering Unit (A320)	
035	TCAS (735)	06F	Bleed Air (A320)	
036	Radio Management System (736)	070		
c-10 037	Weight and Balance System (737)	071		
038	ADIRS (738)	072		
039	MCDU (739)	073		

c-5 [1] "Electronic Engine Control" and "Power Management Control" are two other names for equipment identified by "1A".

ATTACHMENT 1-2
EQUIPMENT CODES

Equip ID (Hex)	Equipment Type	Equip ID (Hex)	Equipment Type	
074		0B0	Airborne ILS Controller (710)	
075		0B1	Airborne VOR Controller (711)	
076		0B2	Airborne ADF Controller (712)	
077		0B3		
079		0B4		
07A	APU Engine Control Unit (A320)	0B5		
07B	Engine Interface Unit (A320)	0B6	VHF COM Controller (716)	
07C	FADEC Channel A (A320)	0B7		
07D	FADEC Channel B (A320)	0B8	ATC Transponder Controller (718)	
07E	Centralized Fault Data Interface Unit	0B9	HF/SSB System Controller (719)	
07F	Fire Detection Unit (A320)	0BA	Power Supply Module (B747-400)	c-11
080		0BB	Flap Control Unit (B747-400)	c-16
081			Flap Slat Electronics Unit (B767-400)	
082		0BC	Fuel System Interface Card (B747-400)	
083		0BD	Hydraulic Quantity Monitor Unit (B747-400)	c-11
084		0BE	Hydraulic Interface Module (B747-400)	
085		0BF	Window Heat Control Unit (B747-400)	
086		0C0		
087		0C1		
088		0C2	PVS Control Unit	c-11
089		0C3	GPWS Controller (723)	c-10
08A	Window Heat Computer (A320)	0C4	A429W SDU Controller	c-17
08B	Probes Heat Computer (A320)	0C5	EFI Controller (725)	
08C	Avionics Cooling Computer (A320)	0C6		
08D	Fuel Flow Indicator (B747)	0C7	MLS Controller (727)	c-14
08E	Surface Position Digitizer (B747-400)	0C8		
08F	Vacuum System Controller	0C9		
090		0CA	Brake Temperature Monitor Unit (B747-400)	
091		0CB	Autostart (B747-400)	
093		0CC	Brake System Control Unit (B747-400)	
094		0CD	Pack Temperature Controller (B747-400)	c-11
095		0CE	EICAS/EFIC Interface Unit (B747-400)	
096		0CF	Para Visual Display Computer (B747-400)	
097		0D0	Engine Instrument System (B737)	
098		0D1		
099		0D2		
09A		0D3	Thermal Monitoring Unit (General)	c-14
09B		0D4		
09C		0D5	TCAS Control Panel	c-14
09D		0D6		
09E		0D7		
09F		0D8		
0A0		0D9		
0A1	FCC Controller (701)	0DA	Prox. Switch Electronics Unit (B747-400)	
0A2	FMC Controller (702)	0DB	APU Controller (B747-400)	
0A3	Thrust Rating Controller (703)	0DC	Zone Temperature Controller (B747-400)	
0A4	IRS Controller (704)	0DD	Cabin Pressure Controller (B747-400)	c-11
0A5		0DE	Windshear Computer (Sperry)	
0A6		0DF	Equipment Cooling Card (B747-400)	
0A7		0E0	Crew Rest Temp. Controller (B747-400)	
0A8	Airborne WXR Controller (708)	0E1		
0A9	Airborne DME Controller (709)	0E2		
0AA	Generator Control Unit (A320)	0E3		
0AB	Air Supply Control & Test Unit (B747-400)	0E4		
0AC	Bus Control Unit (B747-400)	0E5		
0AD	ADIRS Air Data Module	0E6		
0AE	Yaw Damper Module (B747-400)	0E7		
0AF	Stabilizer Trim Module (B747-400)	0E8		

ATTACHMENT 1-2
EQUIPMENT CODES

Equip ID (Hex)	Equipment Type	Equip ID (Hex)	Equipment Type	
	0E9	123	Ground Power Control Unit (A330/A340)	
	0EA Misc. Environment Control (B747)	124	Fuel Management Computer (A330/A340)	
	0EB Fuel Jettison Control Card (B747)	125	Center of Gravity Fuel Control Comp.(A330/A340)	
c-11	0EC Advance Cabin Entertainment Serv. Sys.	126	Circuit breakers Monitoring Unit (A330/A340)	c-12
	0ED Fuel System Controller (MD-11)	127	Electrical Contractor Management Unit (A330/A340)	
	0EE Hydraulic System Controller (MD-11)	128	Hydraulic Electrical Generator Control Unit (A330/A340)	
	0EF Environmental System Controller (MD-11)	129	Hydraulic System Monitoring Unit (A330/A340)	
	0F0	12A	Cargo Bay Conditioning Card (B747)	c-11
	0F1	12B	Predictive Windshear System Sensor	
	0F2	12C	Angle of Attack Sensor	c-14
	0F3	12D	Logic Drive Control Computer (B747/B767)	
	0F4	12E	Cargo Control Logic Unit (B767)	c-16
	0F5	12F	Cargo Electronics Interface Unit (B767)	
	0F6	130	Load Management Unit (LMU) Airbus	
	0F7	131		
	0F8	132		
	0F9	133		
	0FA Misc. System controller (MD-11)	134		
	0FB Anti-Skid System (MD-11)	135		
c-11	0FC Cabin Pressure Control Sys. (MD-11)	136	Audio Management System	c-11
	0FD Air Condition Control System (MD-11)	137		
	0FE Pneumatic Control System (MD-11)	138		
	0FF Manifold Failure Detection System (MD-11)	139		
	100	13A	Full Authority Engine Control (P&W)	c-14
	101	13B	Audio Entertainment System (AES) Controller (Boeing)	c-16
	102	13C	Boarding Music Machine (B777)	
	103	13D	Passenger In Flight Info Unit (Airshow)	c-14
	104	13E	Video Interface Unit (B777)	
	105	13F	Camera Interface Unit (A340/B777)	c-16
	106	140	Supersonic Air Data Computer	
	107	141	Satellite RF Unit	c-11
c-16	108 Electronic Engine Control (EEC) Channel A (B737-700)	142	ADS-B Link Display Processor Unit (LPDU)	c-16
	109 Elect Eng Control (EEC) Channel B (B737-700)	143	Vertical/Horizontal Gyro	
	10A Full Authority Engine Control A (GE)	144	CDTI Display Unit	c-17
	10B Full Authority Engine Control B (GE)	145		
c-11	10C APU Controller	146		
	10D Data Loader	147		
	10E Fire Detection Unit (MD-11)	148		
	10F Auto Brake Unit (MD-11)	149		
	110 Multiplexer PES (A-320)	14A	Slide Slip Angle (SSA)	c-17
	111	14B		
c-14	112 TACAN Adapter Unit (TAU)	14C		
	113 Stall Warning Card (B747-400)	14D		
	114 Fuel Unit Management System (A330/A340)	14E		
	115 TACAN	14F		
c-12	116 Eng Interface Vibration Monitoring Unit (A330/A340)	150	AIMS Gen. Pur. Bus #1 (B777)	
	117 Engine Control Unit Channel A (A330/A340)	151	AIMS Gen. Pur. Bus #2 (B777)	
	118 Engine Control Unit Channel B (A330/A340)	152	AIMS Digital Comm. Mgmt. (B777)	
	119 Centralized Maintenance Computer (A330/A340)	153	AIMS Gen. Pur. Bus #3 (B777)	c-14
	11A Multi-Disk Drive Unit (A330/A340)	154	Central Maintenance Computer (B-777)	
	11B	155	AIMS EFIS Control Panel (B777)	
	11C	156	AIMS Display Unit (B777)	
	11D	157	AIMS Cursor Control Device (B777)	
c-17	11E Integrated Static Probe	158	AIMS General Purpose Bus #4	c-16
	11F	159		
c-17	120 Multifunction Air Data Probe	15A	Flight Data Interface Unit (A330/A340)	
	121	15B	Flight Control Unit (A330/A340)	c-12
c-16	122 Ground Auxiliary Power Unit (A320/319/321)	15C	Flight Control Primary Computer (A330/A340)	

ATTACHMENT 1-2
EQUIPMENT CODES

	Equip ID (Hex)	Equipment Type	Equip ID (Hex)	Equipment Type	
c-12	15D	Flight Control Secondary Computer (A330/A340)	19F	Cade Environment System	c-16
	15E	Flight Mgmt Guidance Env Comp (A330/A340)	1E2	ADS-B LDPU Controller	c-17
	15F		200	Versatile Integrated Avionics Unit (B717/MD-10)	
	160	Special Fuel Quan. Sys. (Boeing)	201	Electronic Spoiler Control Unit (B717)	
	161		202	Brake Control Unit (B717)	
	162		203	Pneumatic Overheat Detection Unit (B717)	c-16
	163		204	Proximity Switch Electronics Unit (B717)	
	164		205	APU Electronic Control Unit (B717)	
	165		206	Aircraft Interface Unit (MD-10)	
	166		207	Fuel Quantity Gauging Unit (MD-10)	
c-16	167	Air Traffic Service Unit (Airbus)			
	168	Integ Standby Instr System (A340/330,A320/319/321)			
	169	Data Link Control and Display Unit (A340/330)			
	16A	Display Unit (A330/A340)			
c-12	16B	Display Management Computer (A330/A340)			
	16C	Head-Up Display Computer (A330/A340)	241	High Power Amplifier	c-11
	16D	ECAM Control Panel (A330/A340)			
c-14	16E	Clock (A330/A340)			
	16F	Cabin Interphone System (B777)			
c-17	170	Radio Tuning Panel (B777)			
	171	Electronic Flight Bag			
	172				
	173		341	Satellite ACU	c-11
	174				
	175				
	176				
	177				
	178				
	179				
c-12	17A	Cabin Ventilation Controller (A330/A340)			
	17B	Smoke Detection Control Unit (A330/A340)			
	17C	Proximity Sensor Control Unit (A330/A340)			
	17D				
	17E				
	17F				
	180				
	181				
	182				
	183				
c-11	184				
	185				
	186				
	187				
	188				
	189				
	18A	Audio Control Panel (A330/A340)			
	18B	Cockpit Voice recorder (A330/A340)			
	18C	Passenger Entertainment Sys Main MUX (A330/A340)			
	18D	Passenger Entertainment Sys Audio Repro.(A330/A340)			
c-11	18E	Pre-recorded Announcement Music Repro (A330/A340)			
	18F	Video Control Unit (A330/A340)			

ATTACHMENT 2
DATA STANDARDS

TABLE 1 - BCD DATA

Label	Eqpt ID (Hex)	Parameter Name	Units	Range (Scale)	Sig Bits	Pos Sense	Resolution	Min Transit Interval (msec) 2	Max Transit Interval (msec) 2	Max Transport Delay (msec) 3	Notes & Cross Ref. to Tables and Attachments
0 0 1	0 0 2	Distance to Go	N.M.	±3999.9	5		0.1	100	200		6-25
	0 5 6	Distance to Go	N.M.	±3999.9	5		0.1	100	200		
	0 6 0	Distance to Go	N.M.	±3999.9	5		0.1	100	200		
0 0 2	0 0 2	Time to Go	Min	0-399.9	4		0.1	100	200		6-25
	0 5 6	Time to Go	Min	0-399.9	4		0.1	100	200		
	0 6 0	Time to Go	Min	0-399.9	4		0.1	100	200		
	1 1 5	Time to Station	Min	0-399.9	4		0.1	50	50		
0 0 3	0 0 2	Cross Track Distance	N.M.	0-399.9	4		0.1	100	200		6-25
0 0 4	0 0 1	Runway Distance to Go	Feet	0-79900	3		100.0	100	200		
0 1 0	0 0 2	Present Position - Latitude	Deg:Min	180N-180S	6	N	0.1	250	500		Section 2.1.2
	0 0 4	Present Position - Latitude	Deg:Min	180N-180S	6	N	0.1	250	500		Section 2.1.2
	0 3 8	Present Position - Latitude	Deg:Min	180N-180S	6	N	0.1	250	500		
0 1 1	0 0 2	Present Position - Longitude	Deg:Min	180E-180W	6	E	0.1	250	500		
	0 0 4	Present Position - Longitude	Deg:Min	180E-180W	6	E	0.1	250	500		
	0 3 8	Present Position - Longitude	Deg:Min	180E-180W	6	E	0.1	250	500		
0 1 2	0 0 2	Ground Speed	Knots	0-7000	4		1.0	250	500		6-25
	0 0 4	Ground Speed	Knots	0-7000	4		1.0	250	500		
	0 4 D	Qty-LD SEL (LB)	Lbs.	0-79999	5		1.0				
	0 0 5	Ground Speed	Knots	0-7000	4		1.0	250	500		
	0 2 5	Ground Speed	Knots	0-7000	4		1.0	125	250		
	0 3 8	Ground Speed	Knots	0-7000	4		1.0	250	500		
	0 5 6	Ground Speed	Knots	0-7000	4		1.0	250	500		
	0 6 0	Ground Speed	Knots	0-7000	4		1.0	250	500		
0 1 3	0 0 2	Track Angle - True	Deg	0-359.9	4		0.1	250	500		6-25
	0 0 4	Track Angle - True	Deg	0-359.9	4		0.1	250	500		
	0 4 D	Qty-Flt. Deck (LB)	Lbs.	0-79999	5		1.0				
	0 3 8	Track Angle - True	Deg	0-359.9	4		0.1	250	500		
0 1 4	0 0 4	Magnetic Heading	Deg	0-359.9	4		0.1	250	500		
	0 0 5	Magnetic Heading	Deg	0-359.9	4		0.1	250	500		
	0 3 8	Magnetic Heading	Deg	0-359.9	4		0.1	250	500		
0 1 5	0 0 2	Wind Speed	Knots	0-799	3		1.0	250	500		
	0 0 4	Wind Speed	Knots	0-799	3		1.0	250	500		
	0 0 5	Wind Speed	Knots	0-799	3		1.0	250	500		
	0 3 8	Wind Speed	Knots	0-799	3		1.0	250	500		
0 1 6	0 0 4	Wind Direction - True	Deg	0-359	3		1.0	250	500		
	0 3 8	Wind Direction - True	Deg	0-359	3		1.0	250	500		
0 1 7	0 1 0	Selected Runway Heading	Deg	0-359.9	4		0.1	167	333		
	0 4 D	Total-Flt. Deck (LB)	Lbs.	0-79999	5		1.0				
	0 5 5	Selected Runway Heading	Deg	0-359.9	4		0.1				
	0 A 0	Selected Runway Heading	Deg	0-359.9	4		0.1	167	333		
	0 B 0	Selected Runway Heading	Deg	0-359.9	4		0.1	167	333		
0 2 0	0 2 0	Selected Vertical Speed	Ft/Min	±6000	4		1.0	100	200		6-25
	0 4 D	Tnk-LD SEL (LB)	Lbs.	0-79999	5		1.0				
	0 A 1	Selected Vertical Speed	Ft/Min	±6000	4	Up	1.0	100	200		
0 2 1	0 0 2	Selected EPR	EPR	0-3	4		0.001	100	200		
	0 0 2	Selected N1	RPM	0-3000	4		1	100	200		
	0 2 0	Selected EPR	EPR	0-3	4		0.001	100	200		
	0 2 0	Selected N1	RPM	0-3000	4		1	100	200		
	0 A 1	Selected EPR	EPR	0-3	3		0.001	100	200		

ATTACHMENT 2
DATA STANDARDS

TABLE 1 - BCD DATA

Label	Eqpt ID (Hex)	Parameter Name	Units	Range (Scale)	Sig Bits	Pos Sense	Resolution	Min Transit Interval (msec) 2	Max Transit Interval (msec) 2	Max Transport Delay (msec) 3	Notes & Cross Ref. to Tables and Attachments
	0 A 1	Selected N1	RPM	0-3000	4		1	100	200		
0 2 2	0 2 0	Selected Mach	Mach	0-4	4		0.001	100	200		
	0 4 D	Qty-LD SEL (KG)	Kg	0-79999	5		1.0				
	0 A 1	Selected Mach	Mach	0-4	4		0.001	100	200		
0 2 3	0 2 0	Selected Heading	Deg	0-359	3		1.0	100	200		6-25
	0 4 D	Qty-Flt Deck (KG)	Kg	0-79999	5		1.0				
	0 A 1	Selected Heading	Deg	0-359	3		1.0	100	200		
0 2 4	0 1 1	Selected Course #1	Deg	0-359	3		1.0	167	333		6-25
	0 2 0	Selected Course #1	Deg	0-359	3		1.0	167	333		
	0 A 1	Selected Course #1	Deg	0-359	3		1.0	167	333		
	0 B 1	Selected Course #1	Deg	0-359	3		1.0	167	333		
0 2 5	0 2 0	Selected Altitude	Feet	0-50000	5		1.0	100	200		6-25
	0 A 1	Selected Altitude	Feet	0-50000	5		1.0	100	200		
0 2 6	0 0 3	Selected Airspeed	Knots	30-450	3		1.0	100	200		6-25
	0 2 0	Selected Airspeed	Knots	30-450	3		1.0	100	200		
	0 A 1	Selected Airspeed	Knots	30-450	3		1.0	100	200		
0 2 7	0 0 2	TACAN Selected Course	Deg	0-359	3		1.0	167	333		
	0 1 1	Selected Course #2	Deg	0-359	3		1.0	167	333		
	0 2 0	Selected Course #2	Deg	0-359	3		1.0	167	333		
	0 4 D	Total-Flt Deck (KG)	Kg	0-79999	5		1.0				
	0 5 6	TACAN Selected Course	Deg	0-359	3		1.0	167	333		
	0 6 0	TACAN Selected Course (BCD)	Deg	0-359	3		1.0	167	333		
	0 A 1	Selected Course #2	Deg	0-359	3		1.0	167	333		
	0 B 1	Selected Course #2	Deg	0-359	3		1.0	167	333		
0 3 0	0 2 0	VHF COM Frequency		See Chapter 3				100	200		6-45
	0 2 4	VHF COM Frequency		See Chapter 3				100	200		
	0 4 D	TNK-LD SEL (KG)	Kg	0-79999	5		1.0				
	0 B 6	VHF COM Frequency		See Chapter 3				100	200		
0 3 1	0 2 0	Beacon Transponder Code		See Chapter 3				100	200		6-46
	0 B 8	Beacon Transponder Code		See Chapter 3				100	200		
0 3 2	0 1 2	ADF Frequency		See Chapter 3				100	200		6-40
	0 2 0	ADF Frequency		See Chapter 3				100	200		
	0 B 2	ADF Frequency		See Chapter 3				100	200		
0 3 3	0 0 2	ILS Frequency		See Chapter 3				167	333		6-44
	0 1 0	ILS Frequency		See Chapter 3				167	333		
	0 2 0	ILS Frequency		See Chapter 3				167	333		
	0 5 6	ILS Frequency		See Chapter 3				167	333		
	0 6 0	ILS Frequency		See Chapter 3				167	333		
	0 B 0	ILS Frequency		See Chapter 3				167	333		
0 3 4	0 0 2	VOR/ILS Frequency		See Chapter 3				167	333		6-44-1
	0 0 6	Baro Correction (mb) #3	mb	745-1050	5		0.1	62.5	125		
	0 1 1	VOR/ILS Frequency		See Chapter 3				167	333		
	0 2 0	VOR/ILS Frequency		See Chapter 3				167	333		
	0 5 6	VOR/ILS Frequency		See Chapter 3				167	333		
	0 6 0	VOR/ILS Frequency #1		See Chapter 3				167	333		
	0 B 0	VOR/ILS Frequency		See Chapter 3				167	333		
0 3 5	0 0 2	DME Frequency		See Chapter 3				100	200		6-41
	0 0 6	Baro Correction (ins of Hg) #3	ins Hg	22-31	5		0.001	62.5	125		
	0 0 9	DME Frequency		See Chapter 3				100	200		
	0 2 0	DME Frequency		See Chapter 3				100	200		

ATTACHMENT 2 **DATA STANDARDS**

TABLE 1 - BCD DATA

Label	Eqpt ID (Hex)	Parameter Name	Units	Range (Scale)	Sig Bits	Pos Sense	Resolution	Min Transist Interval (msec) 2	Max Transist Interval (msec) 2	Max Transport Delay (msec) 3	Notes & Cross Ref. to Tables and Attachments
	0 5 5	Paired DME Frequency	MHz	108-135.9	4		0.05				
	0 5 6	DME Frequency		See Chapter 3				100	200		
	0 6 0	DME Frequency		See Chapter 3				100	200		
	0 A 9	DME Frequency		See Chapter 3				100	200		
0 3 6	0 0 2	MLS Frequency		See Chapter 3				100	200		
	0 2 0	MLS Frequency		See Chapter 3				100	200		
	0 5 5	MLS Channel Selection		500-600	3		1				
	0 5 6	MLS Frequency Channel		See Chapter 3				100	200		
	0 6 0	MLS Frequency Channel		See Chapter 3				100	200		
	0 C 7	MLS Frequency		See Chapter 3				100	200		
0 3 7	0 2 0	HF COM Frequency		See Chapter 3				100	200		6-42
	0 B 9	HF COM Frequency		See Chapter 3				100	200		
0 4 1	0 0 2	Set Latitude	Deg/Min	180N/180S	6	N	0.1	250	500		
	0 0 4	Set Latitude	Deg/Min	180N/180S	6	N	0.1	250	500		
	0 2 0	Set Latitude	Deg/Min	180N/180S	6	N	0.1	250	500		
	0 5 6	Set Latitude	Deg/Min	180N/180S	6	N	0.1	250	500		
	0 6 0	Set Latitude	Deg/Min	180N/180S	6	N	0.1	250	500		
	0 A 4	Set Latitude	Deg/Min	180N/180S	6	N	0.1	250	500		
0 4 2	0 0 2	Set Longitude	Deg/Min	180E/180W	6	E	0.1	250	500		
	0 0 4	Set Longitude	Deg/Min	180E/180W	6	E	0.1	250	500		
	0 2 0	Set Longitude	Deg/Min	180E/180W	6	E	0.1	250	500		
	0 5 6	Set Longitude	Deg/Min	180E/180W	6	E	0.1	250	500		
	0 6 0	Set Longitude	Deg/Min	180E/180W	6	E	0.1	250	500		
	0 A 4	Set Longitude	Deg/Min	180E/180W	6	E	0.1	250	500		
0 4 3	0 0 2	Set Magnetic Heading	Deg	0-359	3		1.0	250	500		
	0 0 4	Set Magnetic Heading	Deg	0-359	3		1.0	250	500		
	0 2 0	Set Magnetic Heading	Deg	0-359	3		1.0	250	500		
	0 5 6	Set Magnetic Heading	Deg	0-359	3		1.0	250	500		
	0 6 0	Set Magnetic Heading	Deg	0-359	3		1.0	250	500		
	0 A 4	Set Magnetic Heading	Deg	0-359	3		1.0	250	500		
0 4 4	0 0 4	True Heading	Deg	0-359.9	4		0.1	250	500		
	0 3 8	True Heading	Deg	0-359.9	4		0.1	250	500		
0 4 5	0 0 3	Minimum Airspeed	Knots	0-259.9	4		0.1	62.5	125		
0 4 6	0 3 3	Engine Serial No. (LSDs)						500	1000		6-15
	1 0 A	Engine Serial No. (LSDs)						500	1000		6-15
	1 0 B	Engine Serial No. (LSDs)						500	1000		6-15
0 4 7	0 2 0	VHF Com Frequency	See Chap. 3					100	200		
	0 2 4	VHF Com Frequency	See Chap. 3					100	200		
	0 3 3	Engine Serial No. (MSDs)						500	1000		6-16
	1 0 A	Engine Serial No. (MSDs)						500	1000		6-16
	1 0 B	Engine Serial No. (MSDs)						500	1000		6-17
	0 B 6	VHF Com Frequency	See Chap. 3					100	200		
0 5 2	0 3 7	Long. Zero Fuel CG	% MAC	0-100.00	5		0.01	100	200		
0 5 3	0 0 5	Track Angle-Magnetic	Deg	0-359	3		1.0	250	500		
0 5 6	0 0 2	Estimated Time of Arrival	Hr:Min	0-23.59.9	5		0.1	250	500		
	0 0 5	Wind Direction - Magnetic	Deg	0-359	3		1.0	250	500		
	0 3 7	Gross Weight (Kilograms)	100 kg	0-19999	5		1.0	100	200		
	0 5 6	ETA (Active Waypoint)	Hr:Min	0-23.59.9	5		0.1	250	500		
	0 6 0	ETA (Active Waypoint)	Hr:Min	0-23.59.9	5		0.1	250	500		

ATTACHMENT 2
DATA STANDARDS

TABLE 1 - BCD DATA

Label	Eqpt ID (Hex)	Parameter Name	Units	Range (Scale)	Sig Bits	Pos Sense	Resolution	Min Transit Interval (msec) 2	Max Transit Interval (msec) 2	Max Transport Delay (msec) 3	Notes & Cross Ref. to Tables and Attachments
0 6 0	0 2 5	S/G Hardware Part Number			4						6-36
	0 3 7	Tire Loading (Left Body Main)	%	0-299.9	4		0.1	100	200		
0 6 1	0 2 5	S/G Software Config. Part No.			4						6-37
	0 3 7	Tire Loading (Right Body Main)	%	0-299.9	4		0.1	100	200		
0 6 2	0 3 7	Tire Loading (Left Wing Main)	%	0-299.9	4		0.1	100	200		
0 6 3	0 3 7	Tire Loading (Right Wing Main)	%	0-299.9	4		0.1	100	200		
0 6 4	0 3 7	Tire Loading (Nose)	%	0-299.9	4		0.1	100	200		
0 6 5	0 0 3	Gross Weight	100 lb.	0-12000	5		1.0	100	200		
	0 3 7	Gross Weight	100 lb.	0-19999	5		1.0	100	200		
0 6 6	0 0 2	Longitudinal Center of Gravity	% MAC	0-100.00	5		0.01	500	1000		
	0 3 7	Longitudinal Center of Gravity	% MAC	0-100.00	5		0.01	100	200		
0 6 7	0 3 7	Lateral Center of Gravity	% MAC	0-100.00	5		0.01	100	200		
1 2 5	0 0 2	Universal Time Coordinate	Hr-Min	0-23.59.9	4		0.1	100	200		6-25
	0 0 B	UTC	Hr:Min	0-23.59.9	5		0.1	200	1200		
	0 3 1	Universal Time Coordinate	Hr:Min	0-23.59.9	5		0.1	100	200		
	0 5 6	Universal Time Coordinate	Hr-Min	0-23.59.9	4		0.1	100	200		
	0 6 0	Universal Time Coordinate (UTC)	Hr-Min	0-23.59.9	4		0.1	100	200		
1 3 5	0 5 A	ACT 1 Fuel Quan. Display	Kg/Lb	0-9999	4		100	100	200		
1 3 6	0 5 A	ACT 2 Fuel Quan. Display	Kg/Lb	0-9999	4		100	100	200		
1 3 7	0 5 A	Center+Act1+Act2 FQ Display	Kg/Lb	0-9999	4		100	100	200		
1 4 0	0 5 A	Actual Fuel Quan. Display	Kg/Lb	0-9999	4		100	100	200		
1 4 1	0 5 A	Preselect Fuel Quan. Display	Kg/Lb	0-9999	4		100	100	200		
1 4 2	0 5 A	Left Wing Fuel Quan. Display	Kg/Lb	0-9999	4		100	100	200		
1 4 3	0 5 A	Center Wing Fuel Quan. Display	Kg/Lb	0-9999	4		100	100	200		
1 4 4	0 5 A	Right Wing Fuel Quan. Display	Kg/Lb	0-9999	4		100	100	200		
1 5 5	0 2 7	MLS Selected GP Angle	Deg	0-359.9	4		0.1	100	200		
1 5 7	1 1 4	Trim Tank Probe Capacitance	pf	0-400	4		1.0				
1 6 3	0 3 7	Zero Fuel Weight (lb)	Lbs.	0-19999	5		1.0	100	200		
1 6 5	0 0 7	Radio Height	Feet	±7999.9	5		0.1	25	200		6-25
1 7 0	0 2 5	Decision Height Selected (EFL)	Feet	±7000	4		1.0	100	200		6-25
	0 C 5	Decision Height Selected (EFL)	Feet	±7000	4		1.0	100	200		6-25
2 0 0	0 0 2	Drift Angle	Deg	±180	4		0.1	100	200		
	0 0 4	Drift Angle	Deg	±180	4		0.1	100	200		
	0 5 6	Drift Angle	Deg	±180	4		0.1	100	200		
	0 6 0	Drift Angle	Deg	±180	4		0.1	100	200		

ATTACHMENT 2
DATA STANDARDS

TABLE 1 - BCD DATA

Label	Eqpt ID (Hex)	Parameter Name	Units	Range (Scale)	Sig Bits	Pos Sense	Resolution	Min Transit Interval (msec) 2	Max Transit Interval (msec) 2	Max Transport Delay (msec) 3	Notes & Cross Ref. to Tables and Attachments
2 0 1	0 0 9	DME Distance	N.M.	-1-399.99	5		0.01	83.3	167		6-1-1
	1 1 2	TACAN Distance	N.M.	0-399.99	5		0.01	190	210		
	1 1 5	DME Distance	N.M.	0-399.99	5		0.01	50	50		
2 0 5	0 0 2	HF COM Freq (New Format)									
	0 B 9	HF COM Freq (New Format)									
2 0 7	0 2 5	Operational Software Parts			4						6-37
2 3 0	0 0 6	True Airspeed	Knots	100-599	3		1.0	250	500		6-25
	0 3 8	True Airspeed	Knots	100-599	3		1.0	250	500		
2 3 1	0 0 6	Total Air Temperature	Deg C	-060+099	3		1.0	250	500		
	0 3 8	Total Air Temperature	Deg C	-060+099	3		1.0	250	500		
	1 1 4	Inner 2 Tank Probe Capacitance	pf	0-400	4		1.0				
2 3 2	0 0 4	Altitude Rate	Ft/Min	±20000	4	Up	10.0	31.3	62.5		6-25
	0 0 5	Altitude Rate	Ft/Min	±20000	4	Up	10.0	31.3	62.5		
	0 0 6	Altitude Rate	Ft/Min	±20000	4	Up	10.0	31.3	62.5		
	1 1 4	Inner 4 Tank Probe Capacitance	pf	0-400	4		1.0				
2 3 3	0 0 6	Static Air Temperature	Deg C	-099 to +060	3		1.0	250	500		6-25
	0 3 8	Static Air Temperature	Deg C	-099 to +060	3		1.0	250	500		
	1 1 4	Right Outer Probe Capacitance	pf	0-400	4		1.0				
2 3 4	0 0 6	Baro Correction (mb) #1	mb	745-1050	5		0.1	62.5	125		
	0 3 8	Baro Correction (mb) #1	mb	745-1050	5		0.1	62.5	125		
2 3 5	0 0 6	Baro Correction (ins of Hg) #1	ins Hg	22-31	5		0.001	62.5	125		6-25
	0 3 8	Baro Correction (ins of Hg) #1	ins Hg	22-31	5		0.001	62.5	125		6-25
2 3 6	0 0 6	Baro Correction (mb) #2	mb	745-1050	5		0.1	62.5	125		
	0 3 8	Baro Correction (mb) #2	mb	745-1050	5		0.1	62.5	125		
2 3 7	0 0 6	Baro Correction (ins of Hg) #2	ins Hg	22-31	5		0.001	62.5	125		
	0 3 8	Baro Correction (ins of Hg) #2	ins Hg	22-31	5		0.001	62.5	125		
2 4 3	0 3 7	Zero Fuel Weight (kg)	Kg	0-19999	5		1.0	100	200		
2 6 0	0 0 2	Date/Flight Leg	N/A					500	1000		
	0 0 B	Date	dd:mo:yr	dd:mm:yr	6		4				
	0 3 1	Date	N/A					100	200		6-18
	0 5 6	Date/Flight Leg	N/A					500	1000		
	0 6 0	Date/Flight Leg	N/A					500	1000		
	0 A 2	Date/Flight Leg	N/A					500	1000		
2 6 1	0 0 2	Flight Number	N/A	0-9999	4		1.0	500	1000		6-9
	0 A 2	Flight Number	N/A	0-9999	4		1.0	500	1000		
	0 5 6	Flight Number	N/A	0-9999	4		1.0	500	1000		
	0 6 0	Flight Number	N/A	0-9999	4		1.0	500	1000		
2 7 2	0 5 A	Fuel Density	Kg/cu.m.	0-9999	4		0.0001	100	200		ARINC 429 P2
2 7 3	0 5 A	Sensor Values Left Wing Tank	pF	0-100	3		100	200			
2 7 4	0 5 A	Sensor Values Center Wing Tank	pF	0-100	3		0.1	100	200		
2 7 5	0 5 A	Sensor Values Right Wing Tank	pF	0-100	3		0.1	100	200		
3 4 5	0 0 2	NDB Effectivity							1000		
3 5 0	1 1 4	Fuel Density	kg/l	0-.999	4		0.01				ARINC 429 P2

ATTACHMENT 2 **DATA STANDARDS**

TABLE 1 - BCD DATA

Label	Eqpt ID (Hex)	Parameter Name	Units	Range (Scale)	Sig Bits	Pos Sense	Resolution	Min Transit Interval (msec) 2	Max Transit Interval (msec) 2	Max Transport Delay (msec) 3	Notes & Cross Ref. to Tables and Attachments
3 5 1	1 1 4	Inner Tank 1 Probe Capacitance	pf	0-400	3		0.1				ARINC 429 P2
3 5 2	1 1 4	Center, ACT & RCT Probe Capac.	pf	0-400	3		0.1				ARINC 429 P2
3 5 3	1 1 4	Inner Tank 3 Probe Capacitance	pf	0-400	3		0.1				ARINC 429 P2

ATTACHMENT 2
DATA STANDARDS

TABLE 2 - BNR DATA

Label	Eqpt ID (Hex)	Parameter Name	Units	Range (Scale)	Sig Bits	Pos Sense	Resolution	Min Transit Interval (msec) ²	Max Transit Interval (msec) ²	Max Transport Delay (msec) ³	Notes & Cross Ref. to Tables and Attachments
0 0 5	0 D 0	Engine Discrete									Bit 11-Chan. A/ Bit 12-Chan. B
0 2 5	0 4 D	Load SEL Control	NA	204700	11		100				
0 3 4	0 2 5	VOR/ILS Frequency						125	250		
0 3 5	0 2 5	DME Frequency						125	250		
0 5 2	0 0 4	Body Pitch Acceleration	Deg/Sec ²	± 64	15		0.002	50 Hz	117 Hz		
	0 3 8	Body Pitch Acceleration	Deg/Sec ²	± 64	15		0.002	50 Hz	117 Hz		
0 5 3	0 0 4	Body Roll Acceleration	Deg/Sec ²	± 64	15		0.002	50 Hz	117 Hz		
	0 3 8	Body Roll Acceleration	Deg/Sec ²	± 64	15		0.002	50 Hz	117 Hz		
0 5 4	0 0 4	Body Yaw Acceleration	Deg/Sec ²	± 64	15		0.002	50 Hz	117 Hz		
	0 3 7	Zero Fuel Weight (Kg)	Kg	655360	15		20	100	200		
	0 3 8	Body Yaw Acceleration	Deg/Sec ²	± 64	15		0.002	50 Hz	117 Hz		
0 6 0	0 3 C	Tire Pressure (Left Outer)	PSIA	1024	10		1.0	50	250		
0 6 1	0 0 2	ACMS Information									6-29
	0 0 B	Pseudo Range	Meters	± 268435456	20		256	200	1200		
	0 3 C	Tire Pressure (Left Inner)	PSIA	1024	10		1.0	50	250		
	0 5 6	ACMS Information									
	0 6 0	ACMS Information									
0 6 2	0 0 2	ACMS Information									6-29
	0 0 B	Pseudo Rang Fine	Meters	256	11		0.125	200	1200		
	0 3 C	Tire Pressure (Right Inner)	PSIA	1024	10		1.0	50	250		
	0 5 6	ACMS Information									
	0 6 0	ACMS Information									
0 6 3	0 0 2	ACMS Information									6-29
	0 0 B	Range Rate	M/S	± 4096	20		0.0039	200	1200		
	0 3 C	Tire Pressure (Right Outer)	PSIA	1024	10		1.0	50	250		
	0 5 6	ACMS Information									
	0 6 0	ACMS Information									
0 6 4	0 0 B	Delta Range	Meters	± 4096	20		0.0039	200	1200		
	0 3 C	Tire Pressure (Nose)	PSIA	1024	10		1.0	50	250		
0 6 5	0 0 B	SV Position X	Meters	±67108864	20		64	200	1200		
0 6 6	0 0 B	SV Position X Fine	Meters	64	14		0.0039	200	1200		
0 7 0	0 0 2	Reference Airspeed (Vref)	Knots	512	11		0.25	500	1000	1000	
	0 0 B	SV Position X	Meters	±67108864	20		64	200	1200		
	0 2 9	AC Frequency (Engine)	Hz	512	11		0.25	100	200		
	0 3 7	Hard Landing Magnitude #1	Lbs.		12		-	100	200		
	0 5 6	Reference Airspeed (Vref)	Knots	512	11		0.25	500	1000	1000	
	0 6 0	Reference Airspeed (Vref)	Knots	512	11		0.25	500	1000	1000	
	0 C C	Brakes - Metered Hyd. Pres. L (Normal)	PSIG	4096	12		1	50	100		#1 & 2 coded in SDI
0 7 1	0 0 2	Take-Off Climb Airspeed (V2)	Knots	512	11		0.25	500	1000	50	
	0 0 B	SV Position Y Fine	Meters	64	14		0.0039	200	1200		
	0 2 9	AC Frequency (Engine)	Hz	512	11		0.25	100	200		
	0 3 3	VBV	Deg	64	12		0.016	150	250		
	0 3 7	Hard Landing Magnitude #2	Lbs.		12		-	100	200		
	0 C C	Brakes-Metered Hyd.Pres.L (alt.)	PSIG	4096	12		1	50	100		#1 & 2 coded in SDI

ATTACHMENT 2
DATA STANDARDS

TABLE 2 - BNR DATA

Label	Eqpt ID (Hex)	Parameter Name	Units	Range (Scale)	Sig Bits	Pos Sense	Resolution	Min Transit Interval (msec) 2	Max Transit Interval (msec) 2	Max Trans- port Delay (msec) 3	Notes & Cross Ref. to Tables and Attachments
0 7 2	0 0 2	Rotation Speed (VR)	Knots	512	11		0.25	500	1000	1000	Revised by Supp 11
	0 0 B	SV Position Z	Meters	±67108864	20		64	200	1200		
	0 1 C	Stator Vane Angle	Deg/180	±180	11		0.1	100	200		
	0 2 9	AC Voltage (Engine)	Volts	256	10		0.25	100	200		
	0 2 F	Stator Vane Angle	Deg/180	±180	11		0.1	100	200		
	0 3 3	Stator Vane Angle	Deg	64	12		0.016	150	250		See Note [4]
	0 C C	Brakes-Metered Hyd.Pres.R (normal)	PSIG	4096	12		1	50	100		#1 & 2 coded in SDI
0 7 3	0 0 2	V1 (critical engine failure speed)	Knots	512	11		0.25	100	200		
	0 0 B	SV Position Z Fine	Meters	64	14		0.0039	200	1200		
	0 1 C	Oil Quantity	cc	32768	8		128	100	200		
	0 2 9	Oil Quantity	US Pint	128	9		0.25	100	200		
	0 A 2	V2 (critical engine failure speed)	Knots	512	11		0.25	100	200		
	0 C C	Brakes-Metered Hyd.Pres.R (alt.)	PSIG	4096	12		1	50	100		#1 & 2 coded in SDI
	0 D 0	Engine Oil Quantity	US Pint	128	9		0.25				SDI 1=L/SDI 2=R
0 7 4	0 0 2	Zero Fuel Weight	Lbs.	1310720	15		40	500	1000	1000	
	0 0 B	UTC Measure Time	Seconds	10.0	20		9.536743μs	200	1200		
	0 2 C	Zero Fuel Weight	Lbs.	1310720	15		40	100	400		
	0 3 3	LP Compressor Bleed Pos. (3.0)	Inches	4	10		0.004	100	200		See Note [5]
	0 3 7	Zero Fuel Weight (lb)	Lbs.	1310720	15		40	100	200		
	0 5 6	Zero Fuel Weight	Lbs.	1310720	15		40	500	1000	1000	
	0 6 0	Zero Fuel Weight	Lbs.	1310720	15		40	500	1000	1000	
	1 1 4	Zero Fuel Weight	Lbs.	1310720	15		40	100	400		
0 7 5	0 0 2	Gross Weight	Lbs.	1310720	15		40	100	200		
	0 0 3	Gross Weight	Lbs.	1310720	15		40	100	200		
	0 0 B	Geodetic Altitude	Feet	131072	17		1.0	500	1000		
	0 2 9	AC Voltage (Alt. Sources)	Volts	256	10		0.25	100	200		
	0 2 C	Gross Weight	Lbs.	1310720	15		40	100	200		
	0 3 7	Gross Weight	Lbs.	1310720	15		40	100	200		
	0 3 E	Gross Weight	Lbs.	1310720	15		40	100	200		
	1 1 4	Aircraft Gross Weight	Lbs.	1310720	15		40	100	400		
0 7 6	0 0 B	GPS Height Above Ref.Ellipsoid	Feet	131072	17		1.0	25	50		
	0 0 B	GNSS Altitude (Msl)	Feet	±131072	20		0.125	200	1200		
	0 2 9	AC Voltage (Bus Bar)	Volts	256	10		0.25	100	200		
	0 3 7	Longitudinal Center of Gravity	% MAC	163.84	14		0.01	100	200		
	0 3 E	Longitudinal Center of Gravity	%	164	14		0.01	100	200		
	1 1 4	Aircraft Longitudinal Center of Gravity	Percent	163.84	14		0.01	100	200		
0 7 7	0 - -	Lateral Center of Gravity	MLb-in	128	17		0.001	100	200		
	0 0 2	Target Airspeed	Knots	512	11		0.25	100	200		
	0 0 B	GPS Hor/Vert Deviation	% F.S.	128	8		0.8	25	50		Revised by Supp 11
	0 2 9	AC Load (Engine)	%	256	8		1.0	100	200		
	0 3 7	Lateral Center of Gravity	% MAC	131.072	17		0.01	100	200		
	0 5 6	Target Airspeed	Knots	512	11		0.25	100	200		
	0 6 0	Target Airspeed	Knots	512	11		0.25	100	200		
	1 1 4	Zero Fuel Center of Gravity	Percent	163.84	14		0.01	100	200		
1 0 0	0 0 1	Selected Course #1	Deg/180	±180	12		0.05	167	333		6-27
	0 0 2	Selected Course #1	Deg/180	±180	12		0.05	167	333		
	0 1 1	Selected Course #1	Deg/180	±180	12		0.05	167	333		
	0 2 0	Slected Course #1	Deg/180	±180	12		0.05	167	333		
	0 2 9	AC Load (Alt. Source)	%	128	8		1.0	100	200		
	0 5 6	Selected Course #1	Deg/180	±180	12		0.05	167	333		
	0 6 0	Selected Course #1	Deg/180	±180	12		0.05	167	333		
	0 3 7	Gross Weight (Kilogram)	Kilograms	655360	15		20	100	200		
	0 A 1	Selected Course #1	Deg/180	±180	12		0.05	167	333		
	0 B 1	Selected Course #1	Deg/180	±180	12		0.05	167	333		
	0 B B	Outboard Flaps - PDU	Deg/180	±180	12		0.05	20	100		
1 0 1	0 0 2	Selected Heading	Deg/180	±180	12		0.05	31.3	62.5		

ATTACHMENT 2
DATA STANDARDS

TABLE 2 - BNR DATA

Label	Eqpt ID (Hex)	Parameter Name	Units	Range (Scale)	Sig Bits	Pos Sense	Resolution	Min Transit Interval (msec) 2	Max Transit Interval (msec) 2	Max Trans- port Delay (msec) 3	Notes & Cross Ref. to Tables and Attachments
	0 0 B	HDOP	N/A	1024	15		0.031	200	1200		
	0 2 0	Selected Heading	Deg/180	±180	12		0.05	31.3	62.5		
	0 2 5	Selected Heading	Deg/180	±180	12		0.05	125	250		
	0 2 9	DC Current (TRU)	Amperes	256	8		1.0	100	200		
	0 5 A	FQIC	Lbs	4-65532	14		4	900	1100		
	0 A 1	Selected Heading	Deg/180	±180	12		0.05	31.3	62.5		
	0 B B	Inboard Flaps - PDU	Deg/180	±180	12		0.05	20	100		
	1 1 4	C/G Target	%	164	8		0.01	100	200		
1 0 2	0 0 2	Selected Altitude	Feet	65536	16		1.0	100	200		6-27
	0 0 B	VDOP	N/A	1024	15		0.031	200	1200		
	0 2 0	Selected Altitude	Feet	65536	16		1.0	100	200		
	0 2 9	DC Current (Battery)	Amperes	256	8		1.0	100	200		
	0 5 6	Selected Altitude	Feet	65536	16		1.0	100	200		
	0 6 0	Selected Altitude	Feet	65536	16		1.0	100	200		
	0 A 1	Selected Altitude	Feet	65536	16		1.0	100	200		
1 0 3	0 0 1	Selected Airspeed	Knots	512	11		0.25	100	200		6-27
	0 0 2	Selected Airspeed	Knots	512	11		0.25	100	200		
	0 0 3	Selected Airspeed	Knots	512	11		0.25	100	200		
	0 0 B	GNSS Track Angle	Deg	±108	15		0.0055	200	1200		
	0 1 B	Left/PDU Flap	Deg/180	±180	18		0.000687	100	200		
	0 2 0	Selected Airspeed	Knots	512	11		0.25	100	200		
	0 2 9	DC Voltage (TRU)	Volts	128	9		0.25	100	200		
	0 5 6	Selected Airspeed	Knots	512	11		0.25	100	200		
	0 6 0	Selected Airspeed	Knots	512	11		0.25	100	200		
	0 A 1	Selected Airspeed	Knots	512	11		0.25	100	200		
	0 B B	Left Outboard Flap Position	Deg/180	±180	12		0.05	20	100		
1 0 4	0 0 1	Selected Vertical Speed	Ft/Min	16384	10	UP	16	100	200		6-27
	0 0 2	Selected Vertical Speed	Ft/Min	16384	10	UP	16	100	200		
	0 1 B	Right/PDU Flap	Deg/180	±180	18		0.000687	100	200		
	0 2 0	Selected Vertical Speed	Ft/Min	16384	10	UP	16	100	200		
	0 2 9	DC Voltage (Battery)	Volts	128	9		0.25	100	200		
	0 2 B	Selected Vertical Speed	Ft/Min	16384	14	UP	1	100	200		
	0 5 6	Selected Vertical Speed	Ft/Min	16384	10	UP	16	100	200		
	0 6 0	Selected Vertical Speed	Ft/Min	16384	10	UP	16	100	200		
	0 A 1	Selected Vertical Speed	Ft/Min	16384	10	UP	16	100	200		
	0 B B	Right Outboard Flap Position	Deg/180	±180	12		0.05	20	100		
1 0 5	0 0 2	Selected Runway Heading	Deg/180	±180	11		0.1	167	333		
	0 1 0	Selected Runway Heading	Deg/180	±180	11		0.1	167	333		
	0 1 B	Left/PDU Slat	Deg/180	±180	18		0.000687	100	200		
	0 2 0	Selected Runway Heading	Deg/180	±180	11		0.1	167	333		
	0 2 9	Oil Temp. Input (IDG/CSD)	Deg C	2048	12		0.5	100	200		
	0 5 5	Selected Runway Heading	Deg	±180	11		0.1				
	0 5 6	Selected Runway Heading	Deg/180	±180	11		0.1	167	333		
	0 6 0	Selected Runway Heading	Deg/180	±180	11		0.1	167	333		
	0 A 1	Selected Runway Heading	Deg/180	±180	11		0.1	167	333		
	0 B 0	Selected Runway Heading	Deg/180	±180	11		0.1	167	333		
	0 B B	Left Inboard Flap Position	Deg/180	±180	12		0.05	20	100		
1 0 6	0 0 2	Selected Mach	Mach	4096	12		1	31.3	200		6-27
	0 1 B	Right/PDU Slat	Deg/180	±180	18		0.000687	100	200		
	0 2 0	Selected Mach	Mach	4096	12		0.5	100	200		
	0 2 9	Oil Temp. Input (IDG/CSD)	Deg C	2048	12		0.5	100	200		
	0 5 6	Selected Mach	Mach	4096	12		1	31.3	200		
	0 6 0	Selected Mach	Mach	4096	12		1	31.3	200		
	0 A 1	Selected Mach	Mach	4096	12		1	31.3	62.5		
	0 B B	Right Inboard Flap Position	Deg/180	±180	12		0.05	20	100		
1 0 7	0 0 2	Selected Cruise Altitude	Feet	65536	16	UP	1	100	200		
	0 1 B	Flap/Slat Lever	Deg/180	±180	18		0.000687	100	200		
	0 B B	Flap Lever Position-median value	Deg/180	±180	18		0.000687	100	200		

ATTACHMENT 2 **DATA STANDARDS**

TABLE 2 - BNR DATA

Label	Eqpt ID (Hex)	Parameter Name	Units	Range (Scale)	Sig Bits	Pos Sense	Resolution	Min Transit Interval (msec) 2	Max Transit Interval (msec) 2	Max Transport Delay (msec) 3	Notes & Cross Ref. to Tables and Attachments
	0 3 7	Long. Zero Fuel Ctr of Gravity	% MAC	163.84	14		0.01	100	200		
	0 5 6	Selected Cruise Altitude	Feet	65536	16	UP	1	100	200		
	0 6 0	Selected Cruise Altitude	Feet	65536	16	UP	1	100	200		
1 1 0	0 0 1	Selected Course #2	Deg/180	±180	12		0.05	167	333		
	0 0 2	Selected Course #2	Deg/180	±180	12		0.05	167	333		
	0 0 B	GNSS Latitude	Deg	±180	20		0.000172	200	1200		
	0 1 0	Selected Course #2	Deg/180	±180	12		0.05	167	333		
	0 1 1	Selected Course #2	Deg/180	±180	12		0.05	167	333		
	0 2 0	Selected Course #2	Deg/180	±180	12		0.05	167	333		
	0 A 1	Selected Course #2	Deg/180	±180	12		0.05	167	333		
	0 B 1	Selected Course #2	Deg/180	±180	12		0.05	167	333		
	0 B B	Flap Lever Position - Center	Deg/180	180	18		0.000687	80	160		
1 1 1	0 0 B	GNSS Longitude	Deg	±180	20		0.000172	200	1200		
1 1 2	0 0 2	Runway Length	Feet	20480	11		10	250	500		
	0 0 B	GNSS Ground Speed	Knots	4096	15		0.125	200	1200		
	0 A 1	Selected EPR		4	12		0.001	100	200		
	0 A 1	Selected N1	RPM	4096	12		1	100	200		
	0 B B	Flap Lever Position - Left	Deg/180	±180	18		0.000687	80	160		
1 1 4	0 0 2	Desired Track	Deg/180	±180	12		0.05	100	200		6-27
	0 2 9	Brake Temp. (Left Inner L/G)	Deg C	2048	11		1	100	200		
	0 2 F	Ambient Pressure	PSIA	32	14		0.002	100	200		
	0 3 F	Pamb Sensor	PSIA	32	14		0.002	100	200		
	0 5 6	Desired Track	Deg/180	±180	12		0.05	100	200		
	0 6 0	Desired Track	Deg/180	±180	12		0.05	100	200		
	0 B B	Flap Lever Position - Right	Deg/180	±180	18		0.000687	80	160		
	0 C C	Wheel Torque Output	Lb./Ft.	16384	12		4	50	100		No. 5 to 8 in SDI
	1 0 A	Selected Ambient Static Pressure	PSIA	1.5-20.0	11		0.016	100	500		
	1 0 B	Selected Ambient Static Pressure	PSIA	1.5-20.0	11		0.016	100	500		
	1 3 A	Ambient Pressure	PSIA	32	14		0.002	100	200		
1 1 5	0 0 2	Waypoint Bearing	Deg/180	±180	12		0.05	31.3	62.5		
	0 2 9	Brake Temp. (Left Outer L/G)	Deg C	2048	11		1	100	200		
	0 2 F	Fuel Temperature	Deg C	512	11		0.25	100	200		
	0 3 F	Fuel Temperature	Deg C	512	11		0.25	100	200		
	0 5 6	Waypoint Bearing	Deg/180	±180	12		0.05	31.3	62.5		
	0 6 0	Waypoint Bearing	Deg/180	±180	12		0.05	31.3	62.5		
	0 B C	Fuel Temperature	Deg C	256	8		1	500	1000		
	0 C C	Wheel Torque Output	Lb./Ft.	16384	12		4	50	100		No. 1 to 4 in SDI – 6-26
1 1 6	0 0 2	Cross Track Distance	N.M.	128	15		0.004	31.3	62.5		6-27
	0 0 B	Horizontal GLS Deviation Rectilinear	Feet	24000	18		0.00915		100		
	0 2 9	Brake Temp. (Right Inner L/G)	Deg C	2048	11		1	100	200		
	0 5 5	Horizontal GLS Deviation Rectilinear	Feet	24000	18		0.00915		100		
	0 5 6	Cross Track Deviation	N.M.	128	15		0.004	31.3	62.5		
	0 6 0	Cross Track Deviation	N.M.	128	15		0.004	31.3	62.5		
	0 C C	Wheel Torque Output	Lb./Ft.	16384	12		4	50	100		No. 9 to 12 in SDI – 6-26
1 1 7	0 0 2	Vertical Deviation	Feet	2048	11		1.0	31.3	62.5		6-27
	0 0 B	Vertical GLS Deviation Rectilinear	Feet	1024	14		0.0625		100		
	0 2 9	Brake Temp. (Right Outer L/G)	Deg C	2048	11		1	100	200		
	0 5 5	Vertical GLS Deviation Rectilinear	Feet	1024	14		0.0625		100		
	0 5 6	Vertical Deviation	Feet	2048	11		1.0	31.3	62.5		
	0 6 0	Vertical Deviation	Feet	2048	11		1.0	31.3	62.5		
	0 C C	Wheel Torque Output	Lb./Ft.	16384	12		4	50	100		No. 13 to 16 in SDI – 6-26
1 2 0	0 0 2	Range to Altitude	N.M.	512	15		0.016	25	50		
	0 0 B	GNSS Latitude Fine	Deg	0.000172	11		8.38-E-8	200	1200		
	0 5 6	Range to Altitude	N.M.	512	15		0.016	25	50		
	0 6 0	Range to Altitude	N.M.	512	15		0.016	25	50		

ATTACHMENT 2
DATA STANDARDS

TABLE 2 - BNR DATA

Label	Eqpt ID (Hex)	Parameter Name	Units	Range (Scale)	Sig Bits	Pos Sense	Resolution	Min Transit Interval (msec) 2	Max Transit Interval (msec) 2	Max Trans- port Delay (msec) 3	Notes & Cross Ref. to Tables and Attachments
1 2 1	0 0 2	Horizontal Command Signal	Deg/180	±180	14		0.01	50	100		
	0 0 B	GNSS Longitude Fine	Degrees	0.000172	11		8.38-E-8 °	200	1200		
	0 2 5	Pitch Limit	Deg/180	±180	14		0.01	125	250		
	0 5 6	Horizontal Command Signal	Deg/180	±180	14		0.01	50	100		
	0 6 0	Horizontal Command Signal	Deg/180	±180	14		0.01	50	100		
1 2 2	0 0 2	Vertical Command Signal	Deg/180	±180	12		0.05	500	100		
	0 5 6	Vertical Command Signal	Deg/180	±180	12		0.05	500	100		
	0 6 0	Vertical Command Signal	Deg/180	±180	12		0.05	500	100		
1 2 3	0 0 2	Throttle Command	Deg/Sec	256	18		0.001	50	100		
1 2 4	0 A 5	Client Device for GNSS Receiver	Meters	8192	13		1		200		6-49
	1 E 2	Horizontal Alarm Limit	Meters	0-8190	13		1	800	1200		
1 2 6	0 0 2	Vertical Deviation (wide)	Feet	32768	15	above sel alt	1.0	31.3	62.5		
	0 5 6	Vertical Deviation	Feet	32768	15	above sel alt	1.0	31.3	62.5		
	0 6 0	Vertical Deviation	Feet	32768	15	above sel alt	1.0	31.3	62.5		
1 2 7	0 0 2	Selected Landing Altitude	Feet	65536	16	UP	1	100	200		
	0 1 B	Slat Angle	Deg/180	±180	12		0.05	100	200		6-11
	0 3 3	P14	PSIA	32	14		0.002	100	200		
	1 0 A	Fan Discharge Static Pressure	PSIA	1.5 - 30.0	11		0.016	100	500		
	1 0 B	Fan Discharge Static Pressure	PSIA	1.5 - 30.0	11		0.016	100	500		
	1 E 2	Vertical Alarm Limit	Meters	0-255	8		1	800	1200		6-50
1 3 0	0 0 B	Aut Horiz Integ Limit	N.M.	16	17		1.2E-4	200	1200		
	0 1 A	Fan Inlet Total Temperature	Deg C	128	11		0.06	100	200		
	0 1 C	Fan Inlet Total Temperature	Deg C	128	11		0.06	100	200		
	0 2 F	Fan Inlet Total Temperature	Deg C	128	11		0.06	100	200		
	0 3 5	Intruder Range							500		6-21 and ARINC 735
	0 3 F	Fan Inlet Total Temperature	Deg C	128	11		0.06	100	200		
	1 0 A	Selected Total Air Temperature	Deg C	-80 to 90	10		0.125	100	500		
	1 0 B	Selected Total Air Temperature	Deg C	-80 to 90	10		0.125	100	500		
	1 3 A	Inlet Temperature	Deg C	128	11		0.0625	100	200		
1 3 1	0 1 A	Fan Inlet Total Pressure	PSIA	32	13		0.004	100	200		
	0 1 C	Fan Inlet Total Pressure	PSIA	32	13		0.004	100	200		
	0 2 D	Fan Inlet Total Pressure	PSIA	32	13		0.004	100	200		
	0 2 F	Fan Inlet Total Pressure	PSIA	32	13		0.004	100	200		
	0 3 3	Fan Inlet Total Pressure	PSIA	32	13		0.004	100	200		
	0 3 5	Intruder Altitude							500		6-22 and ARINC 735
	1 3 A	Inlet Pressure	PSIA	32	13		0.004	100	200		
1 3 2	0 1 A	Exhaust Gas Total Pressure	PSIA	32	13		0.004	100	200		
	0 1 C	Exhaust Gas Total Pressure	PSIA	32	13		0.004	100	200		
	0 3 3	Exhaust Gas Total Pressure	PSIA	32	14		0.002	100	250		
	0 3 5	Intruder Bearing							500		6-23 and ARINC 735
1 3 3	0 0 B	Aut Vert Integ Limit	Feet	32,768	18		0.125	200	1200		
	0 1 A	Thrust Lever Angle	Deg/180	±180	12		0.05	100	250		
	0 2 F	Thrust Lever Angle	Deg/180	±180	12		0.05	25	50		
	0 3 F	Thrust Lever Angle	Deg/180	±180	12		0.05	25	50		
	1 0 A	Selected Throttle Lever Angle	Deg	90	11		0.088	31.3	100		
	1 0 B	Selected Throttle Lever Angle	Deg	90	11		0.088	31.3	100		
1 3 4	0 1 C	Power Lever Angle	Deg/180	±180	12		0.05	100	200		
	1 0 A	Throttle Lever Angle	Deg	±128	11		0.088	500	1000		
	1 0 B	Throttle Lever Angle	Deg	±128	11		0.088	500	1000		

ATTACHMENT 2
DATA STANDARDS

TABLE 2 - BNR DATA

Label	Eqpt ID (Hex)	Parameter Name	Units	Range (Scale)	Sig Bits	Pos Sense	Resolution	Min Transit Interval (msec) 2	Max Transit Interval (msec) 2	Max Trans- port Delay (msec) 3	Notes & Cross Ref. to Tables and Attachments
	1 3 A	Throttle Lever Angle	Deg/180	±180	12		0.05	25	50		
1 3 5	0 1 C	Engine Vibration #1	in/sec	8	12		0.002	100	200		
	0 2 9	Engine Fan Vibration	% FS	128	7		1	100	200		
1 3 6	0 0 B	Vertical Figure of Merit	Feet	32,768	18		0.125	200	1200		
	0 1 C	Engine Vibration #2	in/sec	8	12		0.002	100	200		
1 3 7	0 1 B	Flap Angle	Deg/180	±180	12		0.05	100	200		6-11
	0 2 A	Flap Angle	Deg/180	±180	12		0.05	100	200		6-11
	0 2 F	Thrust Reverser Position Feedback	%	128	12		0.03	100	200		
	0 3 F	Thrust Reverser Position Feedback	%	128	12		0.03	100	200		
	1 0 A	Selected Thrust Reverser Position	%	-5 to 105	11		0.063	62.5	250		
	1 0 B	Selected Thrust Reverser Position	%	-5 to 105	11		0.063	62.5	250		
	1 4 0	Flap Angle	Deg	180	12		0.05	62.5	200		6-11
1 4 0	0 0 1	Flight Director - Roll	Deg/180	±180	12		0.05	50	100		6-27
	0 0 B	UTC Fine	Seconds	1	20		0.953674μs	200	1200		
	0 2 5	Flight Director - Roll	Deg/180	±180	10		0.02	125	250		
1 4 1	0 0 1	Flight Director - Pitch	Deg/180	±180	12		0.05	50	100		
	0 0 B	UTC Fine Fractions	Seconds	0.9536743μs	10		0.931225ns	200	1200		
	0 2 5	Flight Director - Pitch	Deg/180	±180	10		0.02	125	250		
1 4 2	0 0 2	Flight Director - Fast/Slow	Knots	32	12		0.008	31.3	62.5		6-27
	0 0 3	Flight Director - Fast/Slow	Knots	32	12		0.008	31.3	62.5		
	0 2 5	Flight Director - Fast/Slow	Knots	32	8		0.125	125	250		
1 4 3	0 0 1	Flight Director - Yaw	Deg/180	±180	12		0.05	50	100		
	0 4 1	HPA Command Word									See ARINC 741
	2 4 1	HPA Response Word									See ARINC 741
1 4 4	0 2 B	Altitude Error	Feet	8192	14	Above Cmd Alt	1.0	25	50		
	0 4 1	ACU/BSU Control Word									See ARINC 741
	3 4 1	ACU/BSU Response Word									See ARINC 741
1 4 5	0 0 2	TACAN Control	See Sec. 3.1.4					180	220		6-30
1 4 6	1 1 2	TACAN Control	See Sec. 3.1.4					180	220		
1 4 7	X X X	TACAN Control Word						100	200		
1 5 0	0 0 2	Universal Time Coordinate									6-12
	0 0 B	UTC	Hr:Min:S	±23:59:59	17		1.0sec	200	1200		
	0 3 1	Universal Time Coordinate						100	200		6-12
	0 5 6	Universal Time Coordinate									6-12
	0 6 0	Universal Time Coordinate									6-12
1 5 1	0 0 2	Localizer Bearing (True)	Deg/180	±180	11		0.1	167	333		
	0 2 7	MLS Azimuth Deviation									
	0 5 5	MLS AZ Deviation	mV	± 2400	15		0.0732				
	0 5 6	Localizer Bearing (True)	Deg/180	±180	11		0.1	167	333		
	0 6 0	Localizer Bearing (True)	Deg/180	±180	11		0.1	167	333		
1 5 2	0 2 7	MLS Elevation Deviation									
	0 3 8	Cabin Pressure	mB	2048	16		0.03125	62.5	125		
	0 4 1	Open Loop Steering									See ARINC 741
	0 5 5	MLS GP Deviation	mV	± 2400	15		0.0732				
	0 A D	Cabin Pressure	mB	2048	18		0.008	20	200		

ATTACHMENT 2
DATA STANDARDS

TABLE 2 - BNR DATA

Label	Eqpt ID (Hex)	Parameter Name	Units	Range (Scale)	Sig Bits	Pos Sense	Resolution	Min Transit Interval (msec) 2	Max Transit Interval (msec) 2	Max Trans- port Delay (msec) 3	Notes & Cross Ref. to Tables and Attachments
1 5 3	0 0 2	Maximum Altitude	Feet	65536	16	Above S.L.	1	500	1000	100	
	0 4 1	Closed Loop Steering									See ARINC 741
	0 5 5	MLS Selected Azimuth	Deg	0-359	9		1				
1 5 4	0 0 2	Runway Heading (True)	N.M.	512	16		0.008	83.3	167		
	0 2 7	MLS Auxiliary Data									
	0 5 5	MLS Max Selectable GP	Deg	± 51.1	9		1				
	0 5 6	Runway Heading (True)	N.M.	512	16		0.008	83.3	167		
	0 6 0	Runway Heading (True)	N.M.	512	16		0.008	83.3	167		
1 5 5	0 5 5	MLS Selected Glide Path	Deg	± 51.1	9		0.01				
1 6 2	0 1 2	ADF Bearing	Deg/180	±180	12		0.05	31.3	62.5		
	0 2 5	ADF brg left/right	Deg/180	±180	12		0.05	125	250		SDI-01=left/SDI-10=right
	0 2 9	Crew Oxygen Pressure	PSI	4096	12		1	100	200		
	0 5 5	MLS Basic Data Word 5	N/A	N/A	N/A		N/A				
	1 4 0	Density Altitude	Feet	1131072	16		2	250	500		
1 6 4	0 0 2	Minimum Descent Altitude (MDA)	Feet	8192	16		0.125	500	1000		
	0 0 3	Target Height	Feet	8192	16		0.125	500	1000		
	0 0 7	Radio Height	Feet	8192	16		0.125	25	50		6-13/6-27
	0 2 5	Radio Height	Feet	8192	12		2.0	125	250		
	0 3 B	Radio Height	VDC	32	11		0.015	150	250		Per ARINC 522A
	0 5 5	MLS ABS GP Angle	Deg	± 41	15		0.00125				
1 6 5	0 0 B	Vertical Velocity	Feet/Min	± 32768	15		1.0	200	1200		
	0 5 5	MLS ABS Azimuth Angle	Deg	± 82	16		0.00125				
1 6 6	0 0 7	RALT Check Point Dev	Feet	512	10		0.5	*	*		
	0 0 B	North/South Velocity	Knots	± 4096	15		0.125	200			
1 6 7	0 0 2	EPU Estimate Position Uncertainty (ANP) Actual Navigation Perf.	N.M.	0-128	16		0.00195				
1 7 1	0 0 2	Required Navigation Performance (RNP)	N.M.	0-128	16		0.001953				
	0 A 5	Vertical Alarm Limit (VAL) and SBAS System Identifier	Meters	256	8		1		200		
	X X X	Manu. Specific Status Word									See Attachment 10
1 7 3	0 1 0	Localizer Deviation	DDM	0.4	12		0.0001	33.3	66.6		6-6/6-27
	0 2 5	Localizer Deviation	DDM	0.4	10		0.0004	125	250		
	0 2 9	Hydraulic Quantity	%	128	7		1	100	200		
	0 3 B	Localizer Deviation	Dots	4	11		0.002	150	250		
	0 5 5	Localizer Deviation	DDM	± 0.4	12		0.0001				
	0 B D	Hydraulic Quantity	%	128	7		1	500	1000		
	0 D 0	Hydraulic Oil Quantity	US Pint	128	9		0.25				SDI 1= A/SDI 2= B
1 7 4	0 0 3	Delayed Flap Approach Speed (DFA)	Knots	512	11		0.25	100	200		
	0 0 B	East/West Velocity	Knots	± 4096	15		0.125	200	1200		
	0 1 0	Glideslope Deviation	DDM	0.8	12		0.0002	33.3	66.6		6-6/6-27
	0 2 9	Hydraulic Pressure	PSI	4096	12		1	100	200		
	0 3 B	Glideslope Deviation	Dots	4	11		0.0002	150	250		6-6/6-27
	0 5 5	Glide Slope Deviation	DDM	± 0.8	12		0.0002				
	0 D 0	Hydraulic Oil Pressure	PSI	4096	12		1.0				SDI 1= A/SDI 2= B
1 7 5	0 0 3	Economical Speed	Knots	1024	14		0.06	62.5	125		
	0 2 9	EGT (APU)	Deg C	2048	11		1	100	200		
	0 3 3	Hydraulic Pump Case Drain Temp	Deg C	256	12		0.06	100	200		
1 7 6	0 0 3	Economical Mach	Mach	4096	13		0.5	62.5	125		
	0 2 9	RPM (APU)	% RPM	256	9		0.5	100	200		

ATTACHMENT 2
DATA STANDARDS

TABLE 2 - BNR DATA

Label	Eqpt ID (Hex)	Parameter Name	Units	Range (Scale)	Sig Bits	Pos Sense	Resolution	Min Transit Interval (msec) ²	Max Transit Interval (msec) ²	Max Trans- port Delay (msec) ³	Notes & Cross Ref. to Tables and Attachments
	0 3 8	Left Static Pressure Uncorrected, mb	mb	2048	18		0.008	20	200		
	0 5 A	Fuel Temperature - Set to Zero	Deg. C	512	11		0.25	100	200		
	0 A D	Static Pressure Left, Uncorrected, mb	mb	2048	18		0.008	20	200		
	1 1 4	Left Outer Tank Fuel Temp & Advisory Warning	Deg	± 512	11		0.25				
1 7 7	0 0 3	Economical Flight Level	Feet	131072	17		1.0	31.3	62.5		
	0 2 9	Oil Quantity (APU)	US Pint	128	9		0.25	100	200		
	0 3 8	Right Static Pressure, Uncorrected, mb	mb	2048	18		0.008	20	200		
	0 5 5	Distance to LTP/FTP	Nmiles	± 512	16		0.007812				
	0 5 A	Fuel Temp. Left Wing Tank	Deg C	512	11		0.25	100	200		
	0 A D	Static Pressure Right, Uncorrected, mb	mb	2048	18		0.008	20	200		
	1 1 4	Inner Tank 1 Fuel Temp & Advisory Warning	Deg C	± 512	11		0.25				
2 0 0	1 1 4	Inner Tank 2 Fuel Temp & Advisory Warning	Deg C	± 512	11		0.25				
2 0 1	0 5 A	Fuel Temp. Right Wing Tank	Deg C	512	11		0.25	100	200		
	1 1 4	Inner Tank 3 Fuel Temp & Advisory Warning	Deg C	± 512	11		0.25				
	1 4 0	Mach Maximum Operation (Mmo)	Mach	4.096	12		0.001	62.5	125		
	1 4 2	Projected Future Latitude	Deg	± 180	20		0.000172	150	400		
2 0 2	0 0 2	Energy Management (clean)	N.M.	512	15		0.016	100	200		
	0 0 9	DME Distance	N.M.	512	16		0.008	83.3	167		6-7/6-27
	0 5 A	Fuel Temperature - Set to Zero	Deg C	512	11		0.25	100	200		
	1 1 4	Inner Tank 4 Fuel Temp & Advisory Warning	Deg C	± 512	11		0.025				
	1 4 0	Mach Rate	M/minute	4.096	12		0.001	62.5	125		
	1 4 2	Projected Future Latitude Fine	Deg	0.000172	11		2E-32	150	400		
2 0 3	0 0 2	Energy Management Speed Brakes	N.M.	512	15		0.016	100	200		
	0 0 6	Altitude (1013.25 mb)	Feet	131072	17		1.0	31.3	62.5		6-24/6-27
	0 1 8	Altitude	Feet	131072	17		1.0	20	40		
	0 3 5	Own A/C Altitude	Feet	131072	17		1.0	20	500		
	0 3 8	Altitude (1013.25 mb)	Feet	131072	17		1.0	31.3	62.5		
	0 5 A	Fuel Tank #6 Temperature	Deg C	512	11		0.25	100	200		
	1 0 A	Ambient Static Pressure	PSIA	1.5 to 20.0	11		0.016	500	1000		
	1 0 B	Ambient Static Pressure	PSIA	1.5 to 20.0	11		0.016	500	1000		
	1 1 4	Trim Tank Fuel Temp & Advisory Warning	Deg C	± 512	11		0.25				
	1 4 0	Altitude	Feet	131072	17		1	31.25	62.5		
2 0 4	0 0 2	Utility Airspeed	Knots	512	11		0.25	500	1000	50	
	0 0 6	Baro Corrected Altitude #1	Feet	131072	17		1.0	31.3	62.5		
	0 3 8	Baro Corrected Altitude #1	Feet	131072	17		1.0	31.3	62.5		
	0 5 6	Baro Altitude	Knots	512	11		0.25	500	1000	50	
	0 5 A	Fuel Tank #7 Temperature	Deg C	512	11		0.25	100	200		
	0 6 0	Baro Altitude	Knots	512	11		0.25	500	1000	50	
	1 1 4	Right Outer Tank Fuel Temp & Advisory Warning	Deg C	± 512	11		0.25				
	1 4 0	Baro Corrected Altitude	Feet	131072	17		1	31.25	62.5		
2 0 5	0 0 6	Mach	Mach	4.096	16		0.0000625	62.5	125		6-27
	0 1 A	Mach	Mach	4.096	16		0.0000625	62.5	125		6-27
	0 3 8	Mach	Mach	4.096	16		0.0000625	62.5	125		6-27
	0 5 A	Fuel Tank #8 Temperature	Deg C	512	11		0.25	100	200		
	1 0 A	Mach Number	Mach	1	11		0.002	100	500		
	1 0 B	Mach Number	Mach	1	11		0.002	100	500		
	1 4 0	Mach	Mach	4.096	16		0.00000625	62.5	125		

ATTACHMENT 2
DATA STANDARDS

TABLE 2 - BNR DATA

Label	Eqpt ID (Hex)	Parameter Name	Units	Range (Scale)	Sig Bits	Pos Sense	Resolution	Min Transit Interval (msec) 2	Max Transit Interval (msec) 2	Max Trans- port Delay (msec) 3	Notes & Cross Ref. to Tables and Attachments
2 0 6	0 0 6	Computed Airspeed	Knots	1024	14		0.0625	62.5	125		6-27
	0 1 8	Altitude (Variable Resolution)	Feet	Variable	15		Variable	31.3	62.5		6-20
	0 3 8	Computed Airspeed	Knots	1024	14		0.0625	62.5	125		
	0 C C	Taxi Speed	Knots	512	11		0.25	50	100		
	1 4 0	Computed Airspeed (CAS)	Knots	1024	14		0.0625	62.5	125		
2 0 7	0 0 6	Maximum Allowable Airspeed	Knots	1024	12		0.25	62.5	125		
	0 0 A	Maximum Allowable Airspeed	Knots	512	11		0.25	100	200		
	0 3 8	Maximum Allowable Airspeed	Knots	1024	12		0.25	62.5	125		
	1 4 0	Airspeed Maximum Operating (VMO)	Knots	1024	12		0.25	62.56	125		
2 1 0	0 0 6	True Airspeed	Knots	2048	15		0.0625	62.5	125		6-27
	0 3 8	True Airspeed	Knots	2048	15		0.0625	62.5	125		
	1 4 0	True Airspeed	Knots	2048	15		0.0625	62.5	125		
2 1 1	0 0 2	Total Air Temperature	Deg C	512	11		0.25	250	500		6-27
	0 0 3	Total Air Temperature	Deg C	512	11		0.25	250	500		
	0 0 6	Total Air Temperature	Deg C	512	11		0.25	250	500		
	0 1 A	Total Air Temperature	Deg C	512	11		0.25	250	500		
	0 3 8	Total Air Temperature	Deg C	512	11		0.25	250	500		
	0 A D	Total Air Temperature Indicated	Deg C	512	12		0.125	250	500		
	1 0 A	Total Fan Inlet Temperature	Deg C	-80 to 90	10		0.125	500	1000		
	1 0 B	Total Fan Inlet Temperature	Deg C	-80 to 90	10		0.125	500	1000		
	1 4 0	Total Air Temperature (TAT)	Deg C	512	12		0.125	250	500		
	1 4 2	Projected Future Longitude	Deg	± 180	20		0.000172	250	500		
2 1 2	0 0 4	Altitude Rate	Ft/Min	32768	11		16	31.3	62.5		6-27
	0 0 5	Altitude Rate	Ft/Min	32768	11		16	31.3	62.5		
	0 0 6	Altitude Rate	Ft/Min	32768	11		16	31.3	62.5		
	0 3 8	Altitude Rate	Ft/Min	32768	11		16	31.3	62.5		
	0 3 B	Altitude Rate	Ft/Min	32768	11		16	150	250		
	1 4 0	Altitude Rate	Ft/Min	32768	11		16	31.25	62.5		
	1 4 2	Projected Future Longitude Fine	Deg	0.000172	11		2E-32 Cir	150	400		
2 1 3	0 0 2	Static Air Temperature	Deg C	512	11		0.25	250	500		6-27
	0 0 6	Static Air Temperature	Deg C	512	11		0.25	250	500		
	0 3 8	Static Air Temperature	Deg C	512	11		0.25	250	500		
	0 8 D	Fuel Used	Lbs.	262144	18		1	75	125		
	1 4 0	Static Air Temperature (SAT)	Deg C	512	11		0.25	250	500		
	1 4 2	Vertical Time Interval	Minute	265 min	10		0.25 min	500	2000		
2 1 5	0 0 6	Impacted Pressure	mb	512	14		0.03125	62.5	125		
	0 1 A	Impact Pressure	mb	512	14		0.03125	62.5	125		
	0 2 9	N1 Actual (EEC)	% RPM	256	14		0.015	50	100		
	0 2 9	EPR Actual (EEC)		4	12		0.001	50	100		
	0 3 8	Impacted Pressure, Uncorrected, mb	mb	512	14		0.03125	62.5	125		
	0 A D	Impacted Pressure, Uncorrected, mb	mb	512	16		0.008	20	40		
	1 4 0	Impact Pressure Subsonic	mb	512	14		0.03125	62.5	125		
2 1 7	0 0 2	Geometric Vertical Rate	Ft/Min	20000	11		16				
	0 0 6	Static Pressure, Corrected (In.Hg.)	in. Hg	64	16		0.001	62.5	125		
	0 2 9	N1 Limit (EEC)	% RPM	256	14		0.015	100	200		
	0 2 9	EPR Limit (EEC)		4	12		0.001	100	200		
	0 3 8	Static Pressure, Average, Corrected (In. Hg.)	in. Hg	64	16		0.001	62.5	125		
	1 4 0	Static Pressure Corrected (In. Hg.)	in. Hg	64	16		0.001	62.5	125		
2 2 0	0 0 6	Baro Corrected Altitude #2	Feet	131072	17		1.0	31.3	62.5		
	0 3 8	Baro Corrected Altitude #2	Feet	131072	17		1.0	31.3	62.5		
	1 4 0	Baro Corrected Altitude #2	Feet	131072	17		1	31.25	62.5		

ATTACHMENT 2
DATA STANDARDS

TABLE 2 - BNR DATA

Label	Eqpt ID (Hex)	Parameter Name	Units	Range (Scale)	Sig Bits	Pos Sense	Resolution	Min Transit Interval (msec) 2	Max Transit Interval (msec) 2	Max Trans- port Delay (msec) 3	Notes & Cross Ref. to Tables and Attachments
2 2 1	0 0 6	Indicated Angle of Attack (Avg)	Deg/180	±180	12		0.05	31.3	62.5		
	0 3 8	Indicated Angle of Attack (Average)	Deg/180	±180	12		0.05	31.3	62.5		
	0 A D	Indicated Angle of Attack	Deg/180	±180	14		0.01	31.3	200		
	1 2 C	Indicated Angle of Attack (Avg.)	Deg/180	±180	12		0.05	31.3	62.5		
	1 4 0	Angle of Attack Indicated Average	Deg	±180	12		0.05	31.25	62.5		
2 2 2	0 0 6	Indicated Angle of Attack (#1 Left)	Deg/180	±180	12		0.05	31.3	62.5		
	0 1 1	VOR Omnibearing	Deg/180	±180	12		0.05	50	100		
	1 1 2	TACAN Bearing	Deg/180	±180	12		0.05	180	220		
	1 1 5	Bearing	Deg/180	±180	11		0.1	50	50		
	1 2 C	Indicated Angle of Attack (#1 Left)	Deg/180	±180	12		0.05	31.3	62.5		
	1 4 0	Angle of Attack, Indicated #1 Left	Deg	±180	12		0.05	31.5	62.5		
2 2 3	0 0 6	Indicated Angle of Attack (#1 Right)	Deg/180	±180	12		0.05	31.3	62.5		
	1 2 C	Indicated Angle of Attack (#1 Right)	Deg/180	±180	12		0.05	31.3	62.5		
	1 4 0	Angle of Attack, Indicated #1 Right	Deg	±180	12		0.05	31.5	62.5		
2 2 4	0 0 6	Indicated Angle of Attack (#2 Left)	Deg/180	±180	12		0.05	31.3	62.5		
	1 2 C	Indicated Angle of Attack (#2 Left)	Deg/180	±180	12		0.05	31.3	62.5		
	1 4 0	Angle of Attack, Indicated #2 Left	Deg	±180	12		0.05	31.5	62.5		
2 2 5	0 0 2	Minimum Maneuvering Airspeed	Knots	512	11		0.25	500	1000	50	
	0 0 6	Indicated Angle of Attack (#2 Right)	Deg/180	±180	12		0.05	31.3	62.5		
	0 2 B	Compensated Altitude Rate	Ft/Min	32768	11	Increas- -ing alt	16.0	31.3	62.5		
	0 5 6	Minimum Maneuvering Air Speed	Knots	512	11		0.25	500	1000		
	0 6 0	Minimum Maneuvering Air Speed	Knots	512	11		0.25	500	1000		
	1 2 C	Indicated Angle of Attack (#2 Right)	Deg/180	±180	12		0.05	31.3	62.5		
	1 4 0	Angle of Attack, Indicated #2 Right	Deg	±180	12		0.05	31.5	62.5		
2 2 7	0 3 D	AVM Command									6-28
	0 7 E	BITE Command Word									See ARINC 604
2 3 1	0 A D	Total Air Temperature	Deg C	512	12		0.125	20	200		
2 3 3	0 0 2	ACMS Information									6-31
	0 5 6	ACMS Information									
	0 6 0	ACMS Information									
2 3 4	0 0 2	ACMS Information									6-31
	0 5 6	ACMS Information									
	0 6 0	ACMS Information									
2 3 5	0 0 2	ACMS Information									6-31
	0 5 6	ACMS Information									
	0 6 0	ACMS Information									
2 3 6	0 0 2	ACMS Information									6-31
	0 5 6	ACMS Information									
	0 6 0	ACMS Information									
2 3 7	0 0 2	ACMS Information									
	0 0 B	Horizontal Uncertainty Level	N.M.	16	17		0.000122		1200		See ARINC 743A
	0 5 6	ACMS Information									
	0 6 0	ACMS Information									
2 4 1	0 0 2	Min. Airspeed for Flap Extension	Knots	512	11		0.25	500	1000	50	
	0 0 6	Corrected Angle of Attack	Deg/180	±180	12		0.05	31.3	62.5		
	0 3 8	Corrected Angle of Attack	Deg/180	±180	12		0.05	31.3	62.5		
	0 4 D	FQIS System Data						500	1024		6-35
	0 5 6	Min. Airspeed for Flap Extension	Knots	512	11		0.25	500	1000		
	0 6 0	Min. Airspeed for Flap Extension	Knots	512	11		0.25	500	1000		
	1 4 0	Angle of Attack, Corrected	Deg	±180	12		0.05	31.5	62.5		

ATTACHMENT 2
DATA STANDARDS

TABLE 2 - BNR DATA

Label	Eqpt ID (Hex)	Parameter Name	Units	Range (Scale)	Sig Bits	Pos Sense	Resolution	Min Transit Interval (msec) 2	Max Transit Interval (msec) 2	Max Trans- port Delay (msec) 3	Notes & Cross Ref. to Tables and Attachments
2 4 2	0 0 6	Total Pressure	mb	2048	16		0.03125	62.5	125		
	0 1 A	Total Pressure	mb	2048	16		0.03125	62.5	125		
	0 3 8	Total Pressure	mb	2048	16		0.03125	62.5	125		
	0 3 B	Speed Deviation	Dots	4	11		0.002	150	250		
	0 A D	Total Pressure, Uncorrected, mb	mb	2048	18		0.008	20	200		
	1 4 0	Total Pressure	mb	2048	16		0.03125	62.5	125		
2 4 3	X X X	Simulator to Avcs Control Word						33	100		See ARINC Rpt 610
2 4 4	0 1 C	Fuel Flow (Engine Direct)	Lbs/hr	32768	8		128.0	100	200		
	0 3 3	Fuel Flow (Wf)	pph	32768	16		0.5	150	250		
	0 3 B	Mach Error	Mach	0.064	11		0.00003	150	250		
	0 8 D	Fuel Flow Rate	PPH	32768	16		0.5	75	125		
	1 0 A	Fuel Mass Flow	MSEC	256	15		0.008	31.3	100		
	1 0 B	Fuel Mass Flow	MSEC	256	15		0.008	31.3	100		
	1 4 0	Angle of Attack, Normalized	Ratio	2	11		0.001	62.5	125		
2 4 5	0 0 2	Minimum Airspeed	Knots	256	12		0.0625	62.5	125		
	0 0 3	Minimum Airspeed	Knots	256	12		0.0625	62.5	125		
	0 0 A	Minimum Airspeed	Knots	512	13		0.0625	62.5	125		
	0 2 9	N3 (Engine)	% RPM	256	14		0.015	50	100		
	0 3 8	Avg. Static Pres. mb uncorrected	mb	2048	16		0.03125	62.5	125		
	0 3 B	EPR Error		4	12		0.001	150	250		
	0 A D	Average Static Pressure mb Uncorrected	mb	2048	16		0.03125	62.5	125		
	0 5 6	Minimum Airspeed	Knots	256	12		0.0625	62.5	125		
	0 6 0	Minimum Airspeed	Knots	256	12		0.0625	62.5	125		
	1 4 0	Static Pressure, Uncorrected	mb	2048	16		0.03125	62.5	125		
2 4 6	0 0 2	Control Maximum Speed (VCMAX)	Knots	512	11		0.25	50	100	50	
	0 0 6	Average Static Pressure	mb	2048	16		0.03	62.5	125		
	0 1 C	N1 (Engine Direct)	RPM	4096	12		1.0	100	200		
	0 2 9	N1 (Engine Direct)	% RPM	256	14		0.015	50	100		
	0 3 8	Avg Static Pres mb Corrected	mb	2048	16		0.03125	62.5	125		
	0 3 B	Angle of Attack Error	Deg/180	±180	14		0.01	150	250		
2 4 7	0 0 2	Control Min. Speed (VCMIN)	Knots	512	11		0.25	50	100	50	
	0 0 B	Horizontal Figure of Merit	N.M.	16	18		6.1 E-5	200	1200		
	0 1 F	Total Fuel	Lbs.	655360	14		40	500	1000		
	0 2 C	Total Fuel	Lbs.	655360	14		40	500	1000		
	0 3 B	Speed Error	Knots	256	12		0.06	150	250		
	0 4 D	Total Fuel	Lbs.	655360	14		40	500	1000		
	0 5 6	Control Minimum Speed (Vcmin)	Knots	512	11		0.25	50	100		
	0 5 A	Total Fuel	Lbs.	655360	14		40	100	200		
	0 6 0	Control Minimum Speed (Vcmin)	Knots	512	11		0.25	50	100		
	0 E B	Fuel to Remain	Lbs.	1638400	14		100	100	125		
	1 1 4	Fuel on Board	Lbs.	655320	13		40				
	1 4 0	Airspeed Minimum Vmc	Knots	512	11		0.25	62.5	125		
2 5 0	0 0 2	Continuous N1 Limit	% RPM	256	14		0.015	50	200	200	
	0 2 B	Maximum Continuous EPR Limit		4	12		0.001	100	200		
	0 2 C	Preselected Fuel Quantity	Lbs.	655360	14		40	100	400		
	0 5 A	Preselected Fuel Quantity	Lbs.	655360	14		40	100	200		
	0 3 8	Indicated Side Slip Angle	Deg/180	±180	12		0.05	31.3	62.5		
	0 A D	Indicated Side Slip Angle or AOS	Deg/180	±180	14		0.01	31.3	200		
	1 1 4	Preselected Fuel Quantity	Lbs.	655320	13		40				
2 5 1	0 0 1	Distance to Go	N.M.	4096	15		0.125	100	200		
	0 0 2	Distance to Go	N.M.	4096	15		0.125	100	200		
	0 0 6	Baro Corrected Altitude #3	Feet	131072	17		1.0	31.3	62.5		
	0 1 A	Flight Leg Counter						75	175		6-19
	0 3 8	Baro Corrected Altitude #3	Feet	131072	17		1.0	31.3	62.5		
2 5 2	0 0 1	Time to Go	Min.	512	9		1.0	100	200		
	0 0 2	Time to Go	Min.	512	9		1.0	100	200		

ATTACHMENT 2
DATA STANDARDS

TABLE 2 - BNR DATA

Label	Eqpt ID (Hex)	Parameter Name	Units	Range (Scale)	Sig Bits	Pos Sense	Resolution	Min Transit Interval (msec) 2	Max Transit Interval (msec) 2	Max Trans- port Delay (msec) 3	Notes & Cross Ref. to Tables and Attachments
	0 0 6	Baro Corrected Altitude #4	Feet	131072	17		1.0	31.3	62.5		
	0 1 A	EPR Idle		4	12		0.001	100	200		
	0 2 F	EPR Idle Reference		4	12		0.001	100	200		
	0 3 8	Baro Corrected Altitude #4	Feet	131072	17		1.0	31.3	62.5		
	0 3 F	EPR Idle Reference		4	12		0.001	100	200		
	0 E B	Time Until Jettison Complete	Minutes	64	6		1	500	1000		
2 5 3	0 0 2	Go-Around N1 Limit	% RPM	256	14		0.015	50	200	200	
	0 1 E	Go-Around EPR Limit		4	12		0.001	100	200		
	0 3 8	Corrected Side Slip Angle	Deg/180	±180	12		0.05	31.3	62.5		
2 5 4	0 0 2	Cruise N1 Limit	% RPM	256	14		0.015	50	200	200	
	0 1 E	Cruise EPR Limit		4	12		0.001	100	200		
	0 4 D	Actual Fuel Quan (test)	Lbs	262144	15		8	500	1000		
	1 3 A	N1 Cruise	% N1 Nom	256	14		0.015	100	200		
	1 4 0	Altitude Rate	Ft/Min	131072	13		16	31.25	62.5		
2 5 5	0 0 2	Climb N1 Limit	% RPM	256	14		0.015	50	200	200	
	0 1 E	Climb EPR Limit		4	12		0.001	100	200		
	0 2 F	Maximum Climb EPR Rating	N/A	4	12		0.001	100	200		
	0 3 F	Maximum Climb EPR Rating	N/A	4	12		0.001	100	200		
	0 4 D	Fuel Quantity (gal)	Gallons	32768	15		1.0	500	1000		
	0 8 E	Spoiler Position	Deg/180	+180	11		0.1	50	100		
	1 3 A	N1 Climb	% N1 Nom	256	14		0.015	100	200		
	1 4 0	Impact Pressure	mb	4096	17		0.03125	62.5	125		
2 5 6	0 0 2	Time For Climb	Min.	512	9		1	100	200		
	0 0 A	V Stick Shaker	Knots	512	11		0.25	100	200		
	0 2 C	Fuel Quantity (Tanks) #1	Lbs.	131072	15		4	500	1000		
	0 5 6	Time for Climb	Min.	512	9		1	100	200		
	0 5 A	Fuel Quantity-Left Outer Cell	Lbs.	131072	15		4	100	200		Zero for A-321
	0 6 0	Time for Climb	Min.	512	9		1	100	200		
	1 1 4	Left Outer Tank Fuel Quantity	Lbs.	131072	15		4				
	1 4 0	Equivalent Airspeed	Knots	1024	14		0.0625	62.5	125		
2 5 7	0 0 2	Time For Descent	Min.	512	9		1	100	200		
	0 2 C	Fuel Quantity (Tanks) #2	Lbs.	131072	15		4	500	1000		
	0 5 6	Time for Descent	Min.	512	9		1	100	200		
	0 5 A	Fuel Quantity Left W/T Tank	Lbs.	131072	15		4	100	200		
	0 6 0	Time for Descent	Min.	512	9		1	100	200		
	1 1 4	Fuel Quantity (Tanks) #2	Lbs.	131072	15		4	500	1000		
	1 4 0	Total Pressure (High Range)	mb	4096	17		0.03125	62.5	125		
2 6 0	0 2 C	Fuel Quantity (Tanks) #3	Lbs.	131072	15		4	500	1000		
	0 5 A	Fuel Quantity Center Tank	Lbs.	131072	15		4	100	200		
	0 3 3	T5	Deg C	1024	12		0.25	150	250		See Note [5]
	1 0 A	LP Turbine Discharge Temp	Deg C	-55 to 850	11		0.50	100	500		
	1 0 B	LP Turbine Discharge Temperature	Deg C	-55 to 850	11		0.50	100	500		
	1 1 4	Collector Cell 1 and 2 Fuel Quantity	Lbs.	131072	15		4				
2 6 1	0 2 C	Fuel Quantity (Tanks) #4	Lbs.	131072	15		4	500	1000		
	0 3 3	P49	PSIA	128	14		0.008	150	250		
	0 5 A	Fuel Qty Right I/C or W/T Tank	Lbs.	131072	15		4	100	200		
	1 0 A	LP Turbine Inlet Pressure	PSIA	2-120	11		0.125	100	500		
	1 0 B	LP Turbine Inlet Pressure	PSIA	2-120	11		0.125	100	500		
	1 1 4	Fuel on Board at Engine Start	Lbs.	131072	15		4				
	1 4 4	Range Ring Radius	NM	512	15		1/64	800	1200		6-52
2 6 2	0 0 2	Documentary Data						500	1000		6-14
	0 0 A	Predictive Airspeed Variation	Knots	256	10		0.25	100	200		
	0 1 C	LP Compressor Exist Pres. (PT3)	PSIA	64	13		0.008	100	200		
	0 2 C	Fuel Quantity (Tanks) #5	Lbs.	131072	15		4	500	1000		
	0 3 3	LP Compressor Exist Pressure	PSIA	64	14		0.004	150	250		
	0 4 D	T/U Cap-L Tank 1-4	PF	655.35	16		0.01	TBD	TBD		

ATTACHMENT 2
DATA STANDARDS

TABLE 2 - BNR DATA

Label	Eqpt ID (Hex)	Parameter Name	Units	Range (Scale)	Sig Bits	Pos Sense	Resolution	Min Transit Interval (msec) 2	Max Transit Interval (msec) 2	Max Transport Delay (msec) 3	Notes & Cross Ref. to Tables and Attachments
	0 5 A	Fuel Quantity-Right Outer Cell	Lbs.	131072	15		4	100	200		
	1 0 A	HP Compressor Inlet Total Pres.	PSIA	2-50	11		0.032	100	500		
	1 0 B	HP Compressor Inlet Total Pres.	PSIA	2-50	11		0.032	100	500		
	1 1 4	Center Tank Fuel Quantity	Lbs.	131072	15		4				
	1 4 4	Display Range	NM	512	14		1/32	800	1200		6-51
2 6 3	0 0 2	Min. Airspeed for Flap Retraction	Knots	512	11		0.25	500	1000	50	
	0 0 A	Min. Airspeed for Flap Retraction	Knots	512	11		0.25	100	200		
	0 1 C	LP Compressor Exit Temperature		256	12		0.06	100	200		
	0 2 C	Fuel Quantity (Tanks) #6	Lbs	131072	15		4	500	1000		
	0 3 3	LP Compressor Exit Temperature	Deg C	256	12		0.063	150	250		
	0 4 D	T/U Cap-L Tank 5-8	PF	655.35	16		0.01	TBD	TBD		
	0 5 6	Min. Airspeed for Flap Retraction	Knots	512	11		0.25	500	1000		
	0 6 0	Min. Airspeed for Flap Retraction	Knots	512	11		0.25	500	1000		
	1 0 A	Selected Compressor Inlet Temperature (Total)	Deg C	-55 to 160	11		0.125	100	500		
	1 0 B	Selected Compressor Inlet Temp (Total)	Deg C	-55 to 160	11		0.125	100	500		
	1 1 4	Collector Cell 3 and 4 Fuel Quantity	Lbs.	131072	15		4				
2 6 4	0 0 2	Time To Touchdown	Min.	2048	11		1	100	200	145	
	0 0 A	Min. Airspeed for Slats Retraction	Knots	512	11		0.25	100	200		
	0 1 C	HP Compressor Exit Pressure		512	14		0.03	100	200		
	0 2 C	Fuel Quantity (Tanks) #7	Lbs.	131072	15		4	500	1000		
	0 2 F	Burner Pressure	PSIA	512	14		0.03	100	200		
	0 4 D	T/U Cap-L Tank 9-12	PF	655.35	16		0.01	TBD	TBD		
	0 3 3	HP Compressor Exit Pressure	PSIA	512	14		0.03	150	250		
	0 3 F	Burner Pressure	PSIA	512	14		0.03	100	200		
	0 5 6	Time to Touchdown	Min.	2048	11		1	100	200		
	0 6 0	Time to Touchdown	Min.	2048	11		1	100	200		
	1 0 A	Selected Compressor Dischg Pres.	PSIA	5-600	11		1.00	62.5	250		
	1 0 B	Selected Compressor Dischg Pres.	PSIA	5-600	11		1.00	62.5	250		
	1 3 A	Burner Pressure	PSIA	512	14		0.031	100	200		
2 6 5	0 0 2	Min. Buffet Airspeed	Knots	512	11		0.25	50	100	50	
	0 0 4	Integrated Vertical Acceleration	Ft/Sec	±256	20	UP	0.000244		20		
	0 0 A	Maneuvering Airspeed	Knots	512	11		0.25	100	200		
	0 1 C	HP Compressor Exit Temp (TT4.5)		1024	12		0.25	100	200		
	0 2 C	Fuel Quantity (Tanks) #8	Lbs.	131072	15		4	500	1000		
	0 3 3	HP Compressor Exit Temperature	Deg C	1024	12		0.25	150	250		
	0 3 8	Integrated Vertical Acceleration	Ft/Sec	±256	20	UP	0.000244		20		
	0 4 D	T/U Cap-L Tank 13-14	PF	655.35	16		0.01	TBD	TBD		
	0 5 6	Min. Buffet Airspeed	Knots	512	11		0.25	50	100		
	0 6 0	Min. Buffet Airspeed	Knots	512	11		0.25	50	100		
	1 0 A	Selected Compressor Dischg Temp	Deg C	-55 to 650	11		0.50	100	500		
	1 0 B	Selected Compressor Dischg Temp	Deg C	-55 to 650	11		0.50	100	500		
	1 1 4	Inner Tank 3 Fuel Quantity	Lbs.	131072	15		4				
2 6 6	0 4 D	T/U Cap-C Tank 1-4	PF	655.35	16		0.01	TBD	TBD		
	1 1 4	Inner Tank 2 Fuel Quantity	Lbs.	131072	15		4				
2 6 7	0 0 2	Maximum Maneuver Airspeed	Knots	512	11		0.25	500	1000	50	
	0 0 A	Predictive Max. Maneuver Speed	Knots	512	11		0.25	100	200		
	0 2 B	Throttle Position Command	Deg/180	±180	12		0.05	50	100		
	0 4 D	T/U Cap-C Tank 5-8	PF	655.35	16		0.01	TBD	TBD		
	0 3 3	Spare T/C	Deg C	256	12		0.063	150	250		
	0 5 6	Max. Maneuver Airspeed	Knots	512	11		0.25	500	1000		
	0 6 0	Max. Maneuver Airspeed	Knots	512	11		0.25	500	1000		
	1 0 A	HP Compressor Inlet Temp. (total)	Deg C	-55 to 160	11		0.125	500	1000		
	1 0 B	HP Compressor Inlet Temperature	Deg C	-55 to 160	11		0.125	500	1000		
	1 1 4	Inner Tank 4 Fuel Quantity	Lbs.	131072	15		4				
2 7 0	0 4 D	T/U Cap-C Tank 9	PF	655.35	16		0.01	TBD	TBD		
	1 1 5	Stored TACAN Control Word						25	50		See ARINC 429P2

ATTACHMENT 2
DATA STANDARDS

TABLE 2 - BNR DATA

Label	Eqpt ID (Hex)	Parameter Name	Units	Range (Scale)	Sig Bits	Pos Sense	Resolution	Min Transit Interval (msec) 2	Max Transit Interval (msec) 2	Max Trans- port Delay (msec) 3	Notes & Cross Ref. to Tables and Attachments
2 7 1	0 4 D	T/U Cap-A Tank 1-4	PF	655.35	16		0.01	TBD	TBD		
2 7 2	0 4 D	T/U Cap Tank 5-8	PF	655.35	16		0.01	TBD	TBD		
2 7 3	0 4 D	T/U Cap-A Tank 9-11	PF	655.35	16		0.01	TBD	TBD		
2 7 4	0 4 D	T/U Cap-R Tank 1-4	PF	655.35	16		0.01	TBD	TBD		
2 7 5	0 4 D	T/U Cap-R Tank 5-8	PF	655.35	16		0.01	TBD	TBD		
2 7 6	0 0 1	FCC to Simulator Control Word						50	150		Used only in simulator
	0 0 2	FMC to Simulator Control Word						33	100		Used only in simulator
	0 0 3	TCC to Simulator Control Word						50	150		Used only in simulator
	0 4 D	T/U Cap-R Tank 9-12	PF	655.35	16		0.01	TBD	TBD		
2 7 7	0 4 D	T/U Cap-R Tank 13-14	PF	655.35	16		0.01	TBD	TBD		
3 0 0	1 0 A	ECU Internal Temperature	Deg C	-55 to 125	11		0.125	500	1000		
	1 0 B	ECU Internal Temperature	Deg C	-55 to 125	11		0.125	500	1000		
3 0 1	1 0 A	Demanded Fuel Metering Valve Pos	%	100	11		0.063	62.5	250		
	1 0 B	Demanded Fuel Metering Valve Pos	%	100	11		0.063	62.5	250		
3 0 2	1 0 A	Demanded Variable Stator Vane Pos	%	100	11		0.063	100	500		
	1 0 B	Demanded Variable Stator Vane Pos	%	100	11		0.063	100	500		
3 0 3	1 0 A	Demanded Variable Bleed Valve Pos	%	100	11		0.063	100	500		
	1 0 B	Demanded Variable Bleed Valve Pos	%	100	11		0.063	100	500		
3 0 4	1 0 A	Demanded HPT Clearance Valve Pos	%	100	11		0.063	250	1000		
	1 0 B	Demanded HPT Clearance Valve Pos	%	100	11		0.063	250	1000		
3 0 5	1 0 A	Demanded LPT Clearance Valve Pos	%	100	11		0.063	250	1000		
	1 0 B	Demanded LPT Clearance Valve Pos	%	100	11		0.063	250	1000		
3 1 0	0 0 2	Present Position - Latitude	Deg/180	0-180N/ 0-180S	20		0.000172	100	200		6-27
	0 0 4	Present Position - Latitude	Deg/180	0-180N/ 0-180S	20		0.000172	100	200		
	0 2 9	Aileron Position	Deg/180	±180	11		0.088	50	100		
	0 3 8	Present Position - Latitude	Deg/180	0-180N/ 0-180S	20		0.000172	100	200		
	0 4 D	Comp Cap-Tank	PF	327.67	15		0.01	TBD	TBD		
	0 5 6	Present Position Latitude	Deg/180	0-180N/ 0-180S	20		0.000172	100	200		
	0 6 0	Present Position Latitude	Deg/180	0-180N/ 0-180S	20		0.000172	100	200		
	1 1 4	Right Outer Tank Fuel Quantity	Lbs.	131068	15		4				
3 1 1	0 0 2	Present Position - Longitude	Deg/180	0-180E/ 0-180W	20		0.000172	100	200		
	0 0 4	Present Position - Longitude	Deg/180	0-180E/ 0-180W	20		0.000172	100	200		
	0 2 9	Aileron Trim	Deg/180	±180	11		0.088	50	100		
	0 3 8	Present Position - Longitude	Deg/180	0-180E/ 0-180W	20		0.000172	100	200		
	0 3 B	Control Wheel Roll Force	Lbs.	64	10		0.0625	150	250		

ATTACHMENT 2
DATA STANDARDS

TABLE 2 - BNR DATA

Label	Eqpt ID (Hex)	Parameter Name	Units	Range (Scale)	Sig Bits	Pos Sense	Resolution	Min Transit Interval (msec) ²	Max Transit Interval (msec) ²	Max Transport Delay (msec) ³	Notes & Cross Ref. to Tables and Attachments
	0 5 6	Present Position Longitude	Deg/180	0-180E/ 0-180W	20		0.000172	100	200		
	0 6 0	Present Position Longitude	Deg/180	0-180E/ 0-180W	20		0.000172	100	200		
	1 1 4	Trim Tank Fuel Quantity	Lbs.	131072	15		4				
3 1 2	0 0 2	Ground Speed	Knots	4096	15		0.125	25	50		
	0 0 4	Ground Speed	Knots	4096	15		0.125	25	50		
	0 0 5	Ground Speed	Knots	4096	15		0.125	25	50		
	0 2 9	Rudder Position	Deg/180	±180	11		0.088	50	100		
	0 3 8	Ground Speed	Knots	4096	15		0.125	25	50		
	0 5 6	Ground Speed	Knots	4096	15		0.125	25	50		
	0 5 A	Fuel Quantity ACT 1	Lbs.	131072	15		4	100	200		
	0 6 0	Ground Speed	Knots	4096	15		0.125	25	50		
	1 1 4	Additional Center Tank (Act 1) Fuel Quantity	Lbs.	131072	15		4				
3 1 3	0 0 2	Track Angle - True	Deg/180	±180	12		0.05	25	50		
	0 0 4	Track Angle - True	Deg/180	±180	15		0.0055	25	50		
	0 2 5	Track Angle - True	Deg/180	±180	10		0.2	125	250		
	0 2 9	Rudder Trim	Deg/180	±180	11		0.088	50	100		
	0 3 8	Track Angle - True	Deg/180	±180	15		0.0055	25	50		
	0 5 6	Track Angle - True	Deg/180	±180	12		0.05	25	50		
	0 5 A	Fuel Quantity ACT 2	Lbs.	131072	15		4	100	200		
	0 6 0	Track Angle - True	Deg/180	±180	12		0.05	25	50		
	1 1 4	Additional Center Tank (Act 2) Fuel Quantity	Lbs.	131072	15		4				
3 1 4	0 0 2	Stabilizer Pos Indication (B747-400)	Deg/180	±180	12	TE Down	0.05	25	50	50	
	0 0 4	True Heading	Deg/180	±180	15		0.0055	25	50		
	0 2 5	True Heading	Deg/180	±180	10		0.2	125	250		
	0 2 9	Elevator Position	Deg/180	±180	11		0.088	50	100		
	0 3 8	True Heading	Deg/180	±180	15		0.0055	25	50		
	0 3 B	Control Wheel Pitch Force	Lbs.	64	10		0.0625	150	250		
	1 1 4	Rear Center tank (RCT) Fuel Quantity	Lbs.	131072	15		4				
3 1 5	0 0 1	Stabilizer Position	Deg/180	±180	12	TE Down	0.05	25	50		
	0 0 2	Wind Speed	Knots	256	8		1.0	50	100		
	0 0 4	Wind Speed	Knots	256	8		1.0	50	100		
	0 0 5	Wind Speed	Knots	256	8		1.0	50	100		
	0 2 9	Stabilizer Position	Deg/180	±180	11	TE Down	0.088	50	100		
	0 3 8	Wind Speed	Knots	256	8		1.0	50	100		
	0 5 6	Wind Speed	Knots	256	8		1.0	50	100		
	0 6 0	Wind Speed	Knots	256	8		1.0	50	100		
	0 A 1	Stabilizer Position	Deg/180	±180	12	TE Down	0.05	25	50		
3 1 6	0 0 2	Wind Direction (True)	Deg/180	+180	12	CW from north	0.05	25	50	50	
	0 0 4	Wind Angle	Deg/180	±180	8		0.7	50	100		
	0 2 9	Oil Temperature (Engine)	Deg C	2048	12		0.5	100	200		
	0 3 8	Wind Angle	Deg/180	±180	8		0.7	50	100		
	0 5 6	Wind Direction (True)	Deg/180	+180	12	CW from north	0.05	25	50	50	

ATTACHMENT 2
DATA STANDARDS

TABLE 2 - BNR DATA

Label	Eqpt ID (Hex)	Parameter Name	Units	Range (Scale)	Sig Bits	Pos Sense	Resolution	Min Transit Interval (msec) ²	Max Transit Interval (msec) ²	Max Transport Delay (msec) ³	Notes & Cross Ref. to Tables and Attachments
	0 6 0	Wind Direction (True)	Deg/180	+180	12	CW from north	0.05	25	50	50	
	1 0 A	Engine Oil Temperature	Deg C	-55 to 170	11		1.00	250	1000		
	1 0 B	Engine Oil Temperature	Deg C	-55 to 170	11		1.00	250	1000		
	0 D 0	Engine Oil Temperature	Deg C	2048	12		0.5				SDI 1=L SDI 2 =R
3 1 7	0 0 2	Track Angle - Magnetic	Deg/180	±180	12		0.05	25	50		
	0 0 4	Track Angle - Magnetic	Deg/180	±180	15		0.0055	25	50		
	0 0 5	Track Angle - Magnetic	Deg/180	±180	15		0.0055	25	50		
	0 2 5	Track Angle - Magnetic	Deg/180	±180	10		0.2	125	250		
	0 2 9	Oil Pressure (Engine)	PSI	4096	12		1	50	100		
	0 3 8	Track Angle - Magnetic	Deg/180	±180	15		0.0055	25	50		
	0 5 6	Track Angle Magnetic	Deg/180	±180	12		0.05	25	50		
	0 6 0	Track Angle Magnetic	Deg/180	±180	12		0.05	25	50		
	0 D 0	Engine Oil Pressure	PSI	4096	14		0.25				SDI 1 = L/SDI 2 = R
3 2 0	0 0 4	Magnetic Heading	Deg/180	±180	15		0.0055	25	50		
	0 0 5	Magnetic Heading	Deg/180	±180	15		0.0055	25	50		
	0 2 5	Magnetic Heading	Deg/180	±180	10		0.2	125	250		
	0 3 5	Own A/C Magnetic Heading	Deg/180	±180	15		0.0055	25	500		See ARINC 735
	0 3 8	Magnetic Heading	Deg/180	±180	15		0.0055	25	50		
	0 4 D	Density-Tank	Lb/Gal	8.191	13		0.001	TBD	TBD		
3 2 1	0 0 2	Drift Angle	Deg/180	±180	12		0.05	25	50		
	0 0 4	Drift Angle	Deg/180	±180	11		0.09	25	50		
	0 0 5	Drift Angle	Deg/180	±180	11		0.09	25	50		
	0 3 8	Drift Angle	Deg/180	±180	12		0.05	25	50		
	0 5 6	Drift Angle	Deg/180	±180	12		0.05	25	50		
	0 6 0	Drift Angle	Deg/180	±180	12		0.05	25	50		
	1 0 A	Exhaust Gas Temperature (Total)	Deg C	-55 to 1100	11		1.00	500	1000		
	1 0 B	Exhaust Gas Temperature (Total)	Deg C	-55 to 1100	11		1.00	500	1000		
3 2 2	0 0 2	Flight Path Angle	Deg/180	+180	12		0.05	25	50		
	0 0 4	Flight Path Angle	Deg/180	±180	12		0.05	25	50		
	0 0 5	Flight Path Angle	Deg/180	±180	12		0.05	25	50		
	0 3 8	Flight Path Angle	Deg/180	±180	12		0.05	25	50		
	0 5 6	Flight Path Angle	Deg/180	+180	12		0.05	25	50		
	0 6 0	Flight Path Angle	Deg/180	+180	12		0.05	25	50		
	1 0 A	Total Compressor Discharge Temp	Deg C	-55 to 650	11		0.50	500	1000		
	1 0 B	Total Compressor Discharge Temp	Deg C	-55 to 650	11		0.50	500	1000		
3 2 3	0 0 2	Geometric Altitude	Feet	50000	17		1				
	0 0 4	Flight Path Acceleration	g	4	12		0.001	10	20		6-27
	0 0 5	Flight Path Acceleration	g	4	12		0.001	10	20		
	0 3 8	Flight Path Acceleration	g	4	12		0.001	10	20		
	0 5 6	Geometric Altitude	Feet	50000	17		1				
	0 6 0	Geometric Altitude	Feet	50000	17		1				
	1 0 A	Variable Stator Vane Position	%	-5 to 105	11		0.063	500	1000		
	1 0 B	Variable Stator Vane Position	%	-5 to 105	11		0.063	500	1000		
3 2 4	0 0 4	Pitch Angle	Deg/180	±180	14		0.01	10	20		
	0 0 5	Pitch Angle	Deg/180	±180	14		0.01	10	20		
	0 2 5	Pitch Angle	Deg/180	±180	10		0.2	125	250		
	0 3 8	Pitch Angle	Deg/180	±180	14		0.01	10	20		
	0 4 D	Tank VSO Quantity	Gal.	32768	15		1.0	TBD	TBD		See Att. 6 for SDI encoding
	0 5 A	Effective Pitch Angle	Deg./180	±180	14		0.01				
	1 0 A	Selected Fuel Metering Valve Pos	%	-5 to 105	11		0.063	62.5	250		
	1 0 B	Selected Fuel Metering Valve Pos	%	-5 to 105	11		0.063	62.5	250		

ATTACHMENT 2
DATA STANDARDS

TABLE 2 - BNR DATA

Label	Eqpt ID (Hex)	Parameter Name	Units	Range (Scale)	Sig Bits	Pos Sense	Resolution	Min Transit Interval (msec) 2	Max Transit Interval (msec) 2	Max Trans- port Delay (msec) 3	Notes & Cross Ref. to Tables and Attachments
	1 1 4	Effective Pitch Angle	Deg	±180	13		0.02				
3 2 5	0 0 4	Roll Angle	Deg/180	±180	14		0.01	10	20		
	0 0 5	Roll Angle	Deg/180	±180	14		0.01	10	20		
	0 1 A	Engine Control Trim Feedback									
	0 2 5	Roll Angle	Deg/180	±180	10		0.2	125	250		
	0 2 F	Stator Vane Feedback	Inches	4	12		0.001	100	200		
	0 3 8	Roll Angle	Deg/180	±180	14		0.01	10	20		
	0 3 F	Stator Vane Feedback	Inches	4	12		0.001	100	200		
	0 5 A	Effective Roll Angle	Deg/180	±180	14		0.01				
	1 0 A	Selected Variable Stator Vane Pos	%	-5 to 105	11		0.063	62.5	250		
	1 0 B	Selected Variable Stator Vane Pos	%	-5 to 105	11		0.063	62.5	250		
	1 1 4	Effective Roll Angle	Deg	±180	13		0.02				
3 2 6	0 0 4	Body Pitch Rate	Deg/Sec	128	13		0.015	10	20		
	0 0 5	Body Pitch Rate	Deg/Sec	128	13		0.015	10	20		
	0 3 8	Body Pitch Rate	Deg/Sec	128	13		0.015	10	20		
	0 4 D	Uplift Quantity	Lbs	1638400	14		100	TBD	TBD		
	1 0 A	Compressor Discharge Static Press	PSIA	5-600	11		1.00	500	1000		
	1 0 B	Compressor Discharge Static Press	PSIA	5-600	11		1.00	500	1000		
3 2 7	0 0 4	Body Roll Rate	Deg/Sec	128	13		0.015	10	20		
	0 0 5	Body Roll Rate	Deg/Sec	128	13		0.015	10	20		
	0 3 8	Body Roll Rate	Deg/Sec	128	13		0.015	10	20		
	0 4 D	Uplift Density	Lbs/Gal	8.181	13		0.001	TBD	TBD		
	1 0 A	Fuel Metering Valve Position	%	-5 to 105	11		0.063	500	1000		
	1 0 B	Fuel Metering Valve Position	%	-5 to 105	11		0.063	500	1000		
3 3 0	0 0 4	Body Yaw Rate	Deg/Sec	128	13		0.015	10	20		
	0 0 5	Body Yaw Rate	Deg/Sec	128	13		0.015	10	20		
	0 2 F	HC/TC Cooling Valve Pos. Feedback	%	128	12	OPEN	0.03	100	200		
	0 3 8	Body Yaw Rate	Deg/Sec	128	13		0.015	10	20		
	0 3 F	HC/TC Cooling Valve Pos. Feedback	%	128	12	OPEN	0.03	100	200		
	1 0 A	Selected HPT Clearance Valve Position	%	-5 to 105	11		0.063	250	1000		
	1 0 B	Selected HPT Clearance Valve Pos	%	-5 to 105	11		0.063	250	1000		
3 3 1	0 0 4	Body Longitudinal Acceleration	g	4	12		0.001	10	20		
	0 0 5	Body Longitudinal Acceleration	g	4	12		0.001	10	20		
	0 2 F	LTC Cooling Valve Pos. Feedback	%	128	12	OPEN	0.03	100	200		
	0 3 8	Body Longitudinal Acceleration	g	4	12		0.001	10	20		
	0 3 F	LTC Cooling Valve Pos. Feedback	%	128	12	OPEN	0.03	100	200		
	1 0 A	Selected LPT Clearance Valve Pos	%	-5 to 105	11		0.063	250	1000		
	1 0 B	Selected LPT Clearance Valve	%	-5 to 105	11		0.063	250	1000		
3 3 2	0 0 4	Body Lateral Acceleration	g	4	12		0.001	10	20		
	0 0 5	Body Lateral Acceleration	g	4	12		0.001	10	20		
	0 2 F	A/O Heat Xchr Valve Pos. Feedback	%	128	12	OPEN	0.03	100	200		
	0 3 8	Body Lateral Acceleration	g	4	12		0.001	10	20		
	0 3 F	A/O Heat Xchr Valve Pos. Feedback	%	128	12	OPEN	0.03	100	200		
3 3 3	0 0 4	Body Normal Acceleration	g	4	12		0.001	10	20		
	0 0 5	Body Normal Acceleration	g	4	12		0.001	10	20		
	0 2 F	Acceleration Fuel Flow Limit	Lb/Hr	32768	12		8	100	200		
	0 3 8	Body Normal Acceleration	g	4	12		0.001	10	20		
	0 3 F	Acceleration Fuel Flow Limit	Lb/Hr	32768	12		8	100	200		
3 3 4	0 0 4	Platform Heading	Deg/180	±180	11		0.09	20	40		
	0 0 5	Platform Heading	Deg/180	±180	11		0.09	20	40		
	0 2 F	Fuel Flow Command	Lb/Hr	32768	12		8	100	200		

ATTACHMENT 2
DATA STANDARDS

TABLE 2 - BNR DATA

Label	Eqpt ID (Hex)	Parameter Name	Units	Range (Scale)	Sig Bits	Pos Sense	Resolution	Min Transit Interval (msec) 2	Max Transit Interval (msec) 2	Max Trans- port Delay (msec) 3	Notes & Cross Ref. to Tables and Attachments
	0 3 8	Platform Heading	Deg/180	±180	11		0.09	20	40		
	0 3 F	Fuel Flow Command	Lb/Hr	32768	12		8	100	200		
3 3 5	0 0 2	Track Angle Rate	Deg/Sec	32	11		0.015	10	20		
	0 0 4	Track Angle Rate	Deg/Sec	32	11		0.015	10	20		
	0 0 5	Track Angle Rate	Deg/Sec	32	11		0.015	10	20		
	0 2 F	2.5 BLD Actuator Position	%	128	12		0.031	100	200		
	0 3 8	Track Angle Rate	Deg/Sec	32	11		0.015	10	20		
	0 3 F	2.5 BLD Actuator Position	%	128	12		0.031	100	200		
	0 5 6	Track Angle Rate	Deg/Sec	32	11		0.015	10	20		
	0 6 0	Track Angle Rate	Deg/Sec	32	11		0.015	10	20		
	1 0 A	Selected Variable Bleed Valve Pos	%	-5 to 105	11		0.063	100	500		
	1 0 B	Selected Variable Bleed Valve Pos	%	-5 to 105	11		0.063	100	500		
3 3 6	0 0 2	Max Climb Angle	Deg	32	15	Climb	0.001	100	200		
	0 0 4	Inertial Pitch Rate	Deg/Sec	128	13		0.015	10	20		
	0 0 5	Inertial Pitch Rate	Deg/Sec	128	13		0.015	10	20		
	0 1 A	Engine Torque	%	256	12		0.063	100	200		
	0 2 F	N2 Corrected to Sta 2.5	%	128	12		0.031	100	200		
	0 3 8	Inertial Pitch Rate	Deg/Sec	128	13		0.015	10	20		
	0 3 F	N2 Corrected to Sta 2.5	%	128	12		0.031	100	200		
	1 0 A	Variable Bleed Valve Position	%	-5 to 105	11		0.063	500	1000		
	1 0 B	Variable Bleed Valve Position	%	-5 to 105	11		0.063	500	1000		
3 3 7	0 0 2	EPR - Required For Level Flight	Ratio	±4	12		0.001	100	200		Engine Types: P&W
	0 0 2	N1 - Required For Level Flight	% RPM	±256	15		0.015				Engine Types: GE
	0 0 4	Inertial Roll Rate	Deg/Sec	128	13		0.015	10	20		
	0 0 5	Inertial Roll Rate	Deg/Sec	128	13		0.015	10	20		
	0 1 A	Engine Rating	%	0-256	12		0.063	100	200		
	0 3 8	Inertial Roll Rate	Deg/Sec	128	13		0.015	10	20		
	1 0 A	HPT Clearance Valve Position	%	-5 to 105	11		0.063	500	1000		
	1 0 B	HPT Clearance Valve Position	%	-5 to 105	11		0.063	500	1000		
3 4 0	0 0 3	EPR Actual		4	12		0.001	100	200		
	0 0 4	Inertial Yaw Rate	Deg/Sec	128	13		0.015	10	20		
	0 0 4	Track Angle Grid	Deg	± 180	15		0.0055	20	110		
	0 0 5	Inertial Yaw Rate	Deg/Sec	128	13		0.015	10	20		
	0 1 A	EPR Actual		4	12		0.001	100	200		
	0 2 9	EPR Actual (Engine Direct)		4	12		0.001	50	100		
	0 2 D	EPR Actual		4	12		0.001	100	200		
	0 2 F	EPR Actual		4	12		0.001	25	50		
	0 3 3	EPR Actual		4	12		0.001	100	200		
	0 3 F	EPR Actual		4	12		0.001	25	50		
	1 3 A	N1 Take Off	% N1Nom	256	14		0.015	25	50		
	1 4 0	Pressure Ratio (Pt/Ps)	Ratio	16	14		0.001	62.5	125		
3 4 1	0 0 2	Target N1	% RPM	256	14		0.015	100	200		
	0 0 3	N1 Command	% RPM	256	14		0.015	100	200		
	0 0 3	EPR Command		4	12		0.001	100	200		
	0 0 4	Grid Heading	Deg	± 180	15		0.0055	20	110		
	0 1 A	N1 Command	% RPM	256	14		0.015	100	200		
	0 1 A	EPR Command		4	12		0.001	100	200		
	0 2 9	N1 Command (Engine)	% RPM	256	14		0.015	50	100		
	0 2 9	EPR Command (Engine)		4	12		0.001	50	100		
	0 2 F	N1 Command	% RPM	256	14		0.015	25	50		
	0 2 F	EPR Command		4	12		0.001	25	50		
	0 3 8	Grid Heading	Deg	± 180	15		0.0055	20	110		
	0 3 F	EPR Command		4	12		0.001	100	200		
	0 4 D	I/O S/W REV 1&2		(1)	16		N/A	TBD	TBD		
	1 0 A	Command Fan Speed	%	117.5	13		0.032	31.3	100		

ATTACHMENT 2
DATA STANDARDS

TABLE 2 - BNR DATA

Label	Eqpt ID (Hex)	Parameter Name	Units	Range (Scale)	Sig Bits	Pos Sense	Resolution	Min Transit Interval (msec) 2	Max Transit Interval (msec) 2	Max Trans- port Delay (msec) 3	Notes & Cross Ref. to Tables and Attachments
	1 0 B	Command Fan Speed	%	117.5	13		0.032	31.3	100		
	1 3 A	N1 Reference	% N1Nom	256	14		0.015	25	50		
	1 4 0	Pressure Ratio (Ps/Pso)	Ratio	4	12		0.001	62.5	125		
3 4 2	0 0 2	N1 Bug Drive	% RPM	256	14		0.015	100	200		
	0 0 3	N1 Limit	% RPM	256	14		0.015	100	200		
	0 0 3	EPR Limit		4	12		0.001	100	200		
	0 1 A	N1 Maximum	% RPM	256	14		0.015	100	200		
	0 1 A	EPR Maximum		4	12		0.001	100	200		
	0 2 9	N1 Limit (TCC)	% RPM	256	14		0.015	100	200		
	0 2 9	EPR Limit (TOC)		4	12		0.001	100	200		
	0 2 F	Maximum Available EPR		4	12		0.001	100	200		
	0 3 B	EPR Limit		4	12		0.001	150	250		
	0 3 B	N1 Limit	% RPM	256	14		0.015	150	250		
	0 3 F	Maximum Available EPR		4	12		0.001	100	200		
	0 4 D	S/W REV-Tank		(1)	16		N/A	TBD	TBD		
	1 0 A	Max Allowed Fan Speed	%	117.5	13		0.032	100	500		
	1 0 B	Max Allowed Fan Speed	%	117.5	13		0.032	100	500		
	1 4 0	Air Density Ratio	Ratio	4	12		0.001	250	500		
3 4 3	0 0 3	N1 Derate	% RPM	256	14		0.015	100	200		
	0 0 3	EPR Rate		4	12		0.001	100	200		
	0 1 A	N1 Demand	% RPM	256	12		0.063	20	50		
	1 0 A	N1 Command vs. TLA	%	117.5	13		0.032	31.3	100		
	1 0 B	N1 Command vs. TLA	%	117.5	13		0.032	31.3	100		
3 4 4	0 1 A	N2	% RPM	256	14		0.015	50	100		
	0 1 C	N2	% RPM	256	14		0.015	50	100		
	0 2 9	N2	% RPM	256	14		0.015	50	100		
	0 2 F	N2	% RPM	256	14		0.015	25	50		
	0 3 3	N2	% RPM	256	14		0.015	50	200		
	0 3 F	N2	% RPM	256	14		0.015	25	50		
	1 0 A	Selected Actual Core Speed	%	128	12		0.063	31.3	100		
	1 0 B	Selected Actual Core Speed	%	128	12		0.063	31.3	100		
	1 3 A	N2 Speed	% RPM	256	14		0.015	25	50		
	0 D 0	N2	% RPM	256	13		0.03				SDI 1 = L/SDI 2 = R
3 4 5	0 1 A	Exhaust Gas Temperature	Deg C	2048	12		0.5	100	200		
	0 1 C	Exhaust Gas Temperature	Deg C	2048	12		0.5	100	200		
	0 2 9	Exhaust Gas Temperature	Deg C	2048	12		0.5	50	100		
	0 2 F	Exhaust Gas Temperature	Deg C	2048	12		0.5	25	50		
	0 3 3	Exhaust Gas Temperature	Deg C	2048	12		0.5	100	200		
	0 3 F	Exhaust Gas Temperature	Deg C	2048	12		0.5	25	50		
	1 0 A	Selected Exhaust Gas Temp (Total)	Deg C	-55 to 1100	11		1.00	62.5	250		
	1 0 B	Selected Exhaust Gas Temp (Total)	Deg C	-55 to 1100	11		1.00	62.5	250		
	1 3 A	EGT Trimmed	Deg C	2048	12		0.5	25	50		
	0 D 0	EGT	Deg C	2048	12		0.5				SDI 1 = L/SDI 2 = R
3 4 6	0 0 3	N1 Actual	% RPM	256	14		0.015	100	200		
	0 1 A	N1 Actual	% RPM	256	14		0.015	100	200		
	0 2 F	N1 Actual	% RPM	256	14		0.015	25	50		
	0 3 3	N1 Actual	% RPM	256	14		0.015	50	200		
	0 3 F	N1 Actual	% RPM	256	14		0.015	25	50		
	0 4 D	Cable Cap-Hi-Z	PF	65535	15		2.0	100	200		
	1 0 A	Selected Actual Fan Speed	%	128	12		0.063	31.3	100		
	1 0 B	Selected Actual Fan Speed	%	128	12		0.063	31.3	100		
	1 3 A	N1 Speed Actual	% N1Nom	256	14		0.015	25	50		
	0 D 0	N1	% RPM	256	13		0.03				SDI 1 = L/SDI 2 = R
3 4 7	0 2 9	Fuel Flow (Engine)	Lbs/Hr	32768	12		8	50	100		
	1 0 A	LPT Clearance Valve Position	%	-5 to 105	11		0.063	500	1000		

ATTACHMENT 2 DATA STANDARDS

TABLE 2 - BNR DATA

Label	Eqpt ID (Hex)	Parameter Name	Units	Range (Scale)	Sig Bits	Pos Sense	Resolution	Min Transit Interval (msec) 2	Max Transit Interval (msec) 2	Max Transport Delay (msec) 3	Notes & Cross Ref. to Tables and Attachments
	1 0 B	LPT Clearance Valve Position	%	-5 to 105	11		0.063	500	1000		
	1 3 A	Fuel Flow	Lbs/Hr	32768	14		2	50	100		
	0 D 0	Fuel Flow	Lbs/Hr	32768	12		8				SDI 1 = L/SDI 2 = R
3 5 2	1 4 0	Maintenance Flight Controller	Flights	524, 287	19		1				
3 5 3	0 D 0	Vibration	Scalar	5.12	8		0.02				SDI 1 = L/SDI 2 = R
3 5 4	0 3 D	N1 Vibration	Scalar	5.12	9		0.01				Bit 11-Chan. A Bit 12-Chan. B
3 5 5	0 3 D	N2 Vibration	Scalar	5.12	9		0.01				Bit 11-Chan. A Bit 12-Chan. B
3 5 6	0 3 D	N2 Vibration	Scalar	5.12	9		0.01				Bit 11-Chan. A Bit 12-Chan. B
3 5 7	0 3 D	BB Vibration	Scalar	5.12	9		0.01				Bit 11-Chan. A Bit 12-Chan. B
3 6 0	0 0 2	Flight Information									6-33
	0 0 4	Potential Vertical Speed	Ft/Min	32768	15		1.0	10	20		
	0 0 5	Potential Vertical Speed	Ft/Min	32768	15		1.0	25	50		
	0 3 8	Potential Vertical Speed	Ft/Min	32768	15		1.0	10	20		
	0 3 D	N1 Rotor Imbalance Angle	Deg.	±180	9		1.0				Bit 11-Chan. A Bit 12-Chan. B
	0 5 6	Flight Information									6-33
	0 6 0	Flight Information									6-33
	1 0 A	Throttle Rate of Change	Deg/Sec	±16	9/9		1.00	31.3	100		See Notes [6] & [7]
	1 0 B	Throttle Rate of Change	Deg/Sec	±16	9/9		1.00	31.3	100		See Notes [6] & [7]
	1 4 2	RAIM Status Word	N.M.	16	13		0.00195				
3 6 1	0 0 4	Altitude (Inertial)	Feet	131072	20		0.125	20	40		
	0 0 5	Altitude (Inertial)	Feet	131072	18		0.5	20	40		
	0 3 8	Altitude (Inertial)	Feet	131072	20		0.125	20	40		
	0 3 D	LPT Rotor Imbalance Angle (737 only)	Deg.	±180	9		1.0				Bit 11-Chan. A Bit 12-Chan. B
	1 0 A	Derivative of Thrust vs. N1	DFN/%N1	2000	11		2.0	62.5	250		See Note [6]
	1 0 B	Derivative of Thrust vs. N1	DFN/%N1	2000	11		2.0	62.5	250		See Note [6]
3 6 2	0 0 4	Along Track Horizontal Acceleration	g	4	12		0.001	10	20		
	0 3 8	Along Track Horizontal Acceleration	g	4	12		0.001	10	20		
	1 0 A	Derivative of N1 vs. TLA	% N1/Deg	12	11		0.008	62.5	250		See Note [6]
	1 0 B	Derivative of N1 vs. TLA	% N1/Deg	12	11		0.008	62.5	250		See Note [6]
	1 1 5	Range Rate	Knots	±8192	13		1.0	50	50		
3 6 3	0 0 4	Cross Track Acceleration	g	4	12		0.001	10	20		
	0 3 8	Cross Track Acceleration	g	4	12		0.001	10	20		
	1 0 A	Corrected Thrust	LBF	64000	11		64.0	62.5	250		See Note [6]
	1 0 B	Corrected Thrust	LBF	64000	11		64.0	62.5	250		See Note [6]
3 6 4	0 0 4	Vertical Acceleration	g	4	12		0.001	10	20		
	0 0 5	Vertical Acceleration	g	4	12		0.001	10	20		
	1 3 A	N1 APR Rating	% N1Nom	256	14		0.015	100	200		
	0 3 8	Vertical Acceleration	g	4	12		0.001	10	20		
3 6 5	0 0 4	Inertial Vertical Velocity (EFI)	Ft/Min	32768	15		1.0	20	40		
	0 0 5	Inertial Vertical Velocity (EFI)	Ft/Min	32768	15		1.0	20	40		
	1 3 A	N1 Max Reverse	% N1Nom	256	14		0.015	100	200		
	0 3 8	Inertial Vertical Velocity (EFI)	Ft/Min	32768	15		1.0	20	40		

ATTACHMENT 2 **DATA STANDARDS**

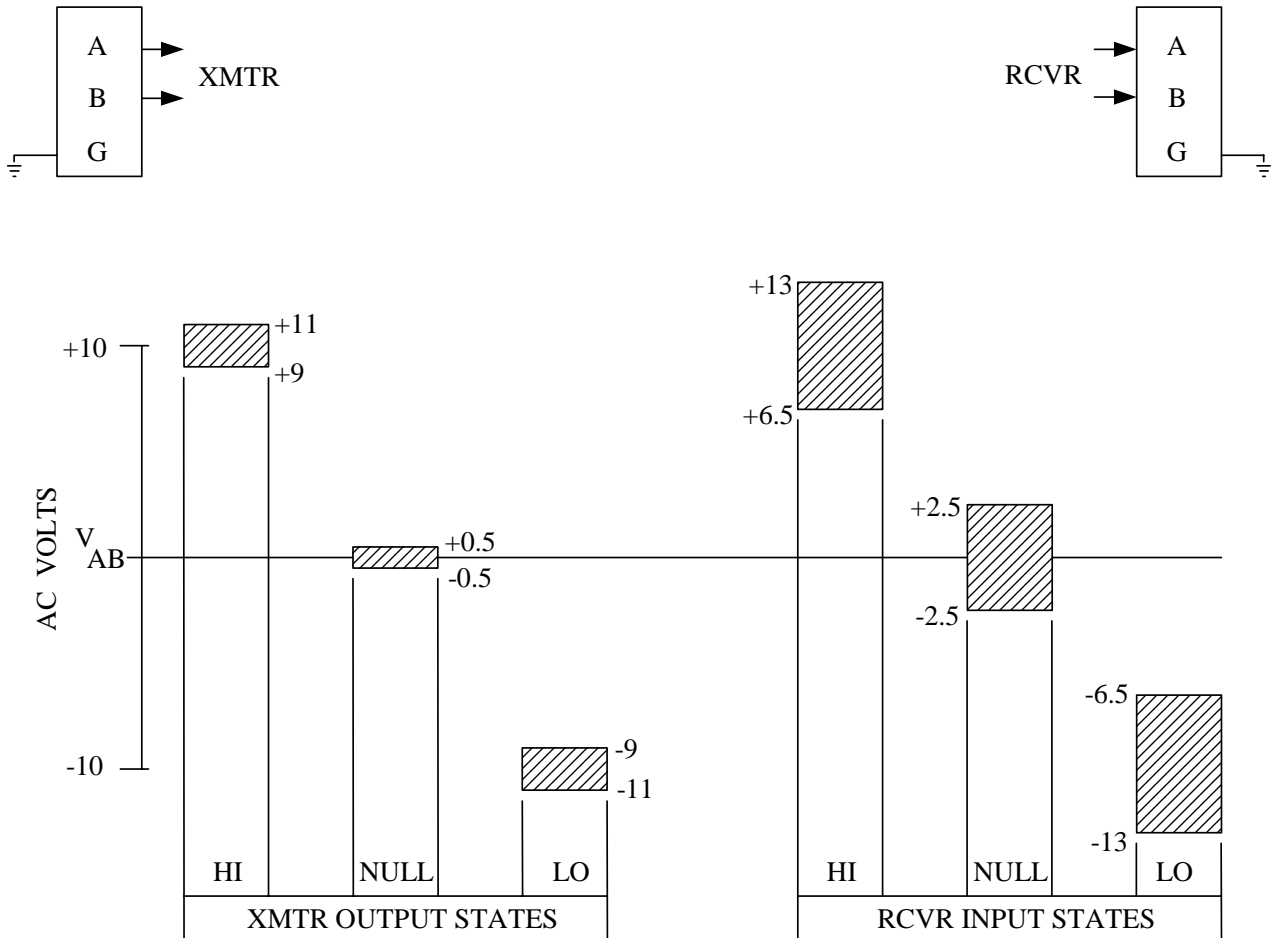
TABLE 2 - BNR DATA

[illegible]

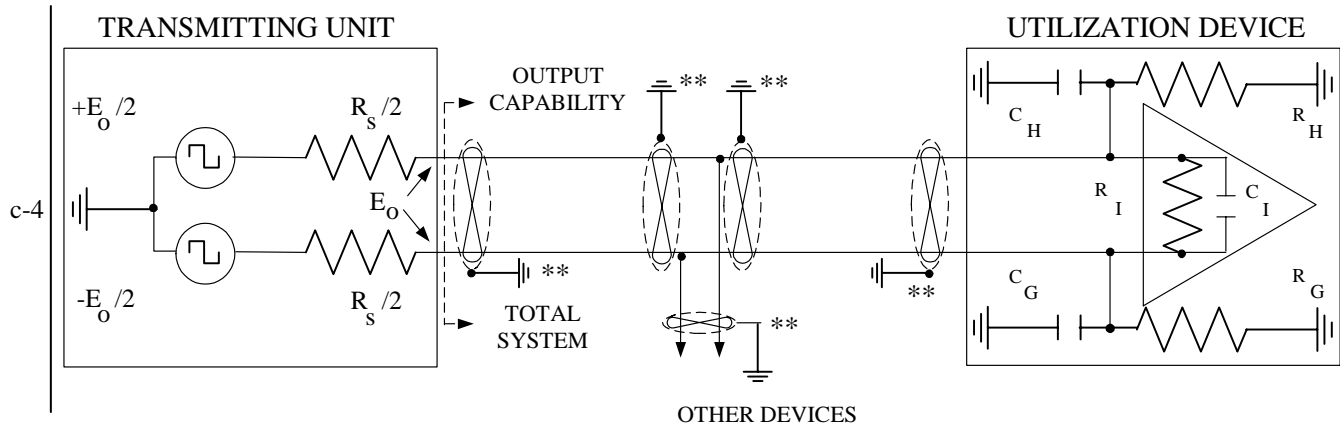
ATTACHMENT 2
DATA STANDARDS**TABLE 2 - BNR DATA**

	[1]	The number entered into the Range Column for each parameter that is not angular in nature is the nearest whole binary number greater than the parameter range required. As explained in the Commentary following Section 2.1.6 of this document, the weight of the most significant bit of the twos complement fractional notation binary word will be one half this value, and the actual maximum value of the parameter capable of being encoded will be the number in the range column less one least significant bit value. The numbers entered in the RANGE column for angular parameters are the actual degree ranges required. The way in which these parameters are encoded is also explained in the Commentary following Section 2.1.6.
c-4	[2]	Transmit intervals and the number of parameters to be transmitted are prime factors in bus loading. The interval for transmission of parameters should fall between the minimum and maximum specified intervals and nominally should be near the center of the range at equal intervals between transmissions. When heavy bus loading dictates a shift from the center of the range, the shift should be toward the maximum transmit interval.
c-5		When words with like labels and with different SDI codes are transmitted, each of those words is considered a unique item of information. The guidance given in this document for transmit intervals should be applied to those words as if each word were identified by a different label.
	[3]	Maximum transport delay is the worst case total delay between an input function and the output response.
		<u>COMMENTARY</u>
c-4		Since the nature of the data varies, the definition of transport delay will differ depending on the application. In the case of a sampling system, a sample is complete when the 32-bit word constituting the output data is complete. In the case of a system involving filtering, transport delay is the phase slope of the transfer function across the frequency band of interest.
		There can be situations in which it is necessary to define which portions of an equipment are included in the transport delay term. Such definitions should appear in individual equipment Characteristics when needed.
c-7	[4]	The values shown in parentheses are the preferred data standards for stator vane angle. However, a considerable portion of existing equipment use the other (non-parenthesized) values. Users should verify the data standards of the equipment they are or will be using.
	[5]	These labels can provide data in a degraded accuracy mode. See Section 2.1.5.1 and 2.1.5.2.
	[6]	Optionally transmitted.
c-12	[7]	Binary packed word consisting of: Word 1 = Bits 11-19 (Range = 16) Word 2 = Bits 20-28 (Range = 16)

ATTACHMENT 3
VOLTAGE LEVELS



ATTACHMENT 4
INPUT/OUTPUT CIRCUIT STANDARDS



**OUTPUT (SYSTEM)
CAPABILITY**

**UTILIZATION DEVICE
STANDARDS**

c-4	Total System *Resistance	400 to 8,000 ohms	$R_I \geq 12,000$ ohms
	Total System *Capacitance	1,000 to 30,000 pF	$C_I \leq 50$ pF
	System Capacitance Unbalance	Not defined but unbalance due to aircraft interwiring should be held to a minimum	R_H or $R_G \geq 12,000$ ohms C_H and $C_G \leq 50$ pF

The total differential input impedance of the receiver should be limited to the values specified in Section 2.2.4.2.

c-16 This drawing describes total system characteristics rather than individual component parameters.

NOTES:

* Includes aircraft interwiring

** Shields to be grounded in aircraft at both ends of all "breaks."

ATTACHMENT 5
INTERNATIONAL STANDARDS ORGANIZATION CODE #5

The ISO Alphabet No. 5 seven-unit code set is reproduced in the table below with the BCD subset outlined in column 3:

STANDARD CODE

BIT 7 $\xrightarrow{\hspace{1.5cm}}$ BIT 6 $\xrightarrow{\hspace{1.5cm}}$ BIT 5 $\xrightarrow{\hspace{1.5cm}}$					0 0 0	0 0 1	0 1 0	0 1 1	1 0 0	1 0 1	1 1 0	1 1 1
BIT 4 ↓	BIT 3 ↓	BIT 2 ↓	BIT 1 ↓	Column → Row ↓	0	1	2	3	4	5	6	7
0	0	0	0	0	NUL	DLE	SP	0	@	P	`	p
0	0	0	1	1	SOH	DC1	!	1	A	Q	a	q
0	0	1	0	2	STX	DC2	"	2	B	R	b	r
0	0	1	1	3	ETX	DC3	#	3	C	S	c	s
0	1	0	0	4	EOT	DC4	\$	4	D	T	d	t
0	1	0	1	5	ENQ	NAK	%	5	E	U	e	u
0	1	1	0	6	ACK	SYN	&	6	F	V	f	v
0	1	1	1	7	BEL	ETB	'	7	G	W	g	w
1	0	0	0	8	BS	CAN	(8	H	X	h	x
1	0	0	1	9	HT	EM)	9	I	Y	i	y
1	0	1	0	10	LF	SUB	*	:	J	Z	j	z
1	0	1	1	11	VT	ESC	+	;	K	[k	{
1	1	0	0	12	FF	FS	`	<	L	\	l	
1	1	0	1	13	CR	GS	-	=	M]	m	}
1	1	1	0	14	SO	RS	•	>	N	^	n	~
1	1	1	1	15	SI	US	/	?	O	—	o	DEL

NOTE: b₈ is used as a parity bit.

ATTACHMENT 6
GENERAL WORD FORMATS AND ENCODING EXAMPLES

6.1. General Word Formats

TABLE 6-1

32	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1
P	SSM		DATA										PAD			DISCRETES						SDI		LABEL							
[5]	[4]		MSB										[3]			[2]						[1]		LSB							

Generalized BCD Word Format**TABLE 6-1-1**

P	SSM		BCD CH #2			BCD CH #2			BCD CH #3			BCD CH #4			BCD CH #5			SDI		8	7	6	5	4	3	2	1	
0	0	0	4	2	1	8	4	2	1	8	4	2	1	8	4	2	1	0	0	1	0	0	0	0	0	0	0	1
Example			2			5			7			8			6					DME DISTANCE (201)								

BCD Word Format Example (No Discretes)**TABLE 6-2**

32	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	
P	SSM		DATA		→				←		PAD				←		DISCRETES				SDI		LABEL									
[5]	[4]		MSB								[3]						[2]		LSB		[1]											

Generalized BNR Word Format**TABLE 6-2-1**

P	31 30		29																	11	SDI	8	7	6	5	4	3	2	1				
	SSM		PAD																	LABEL													
0	1	0	1/2	1/4	1/8	1/16	1/32	1/64	1/128	etc	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	0	1	0	1	1	1	1
Example:			512 Knots (i.e., 1/8 x 4096 where 4096 is entry in range column of Table 2, Att. 2)																			N-S VELOCITY (366)											

BNR Word Format Example (No Discretes)**TABLE 6-3**

P		SSM (01)		"STX"				UNIT ADDRESS				WORD COUNT				LABEL (357)					
32	31	30	29				23	22				17	16	BNR EQUIV.	9	8					1

Alpha Numeric (ISO Alphabet No. 5) Message – Initial Word Format

P		SSM (01)		“STX”				SPARES (Zeroes)				WORD COUNT				LABEL (356)			
32	31	30	29			23	22			17	16	BNR EQUIV.		9	8				

Alpha Numeric (ISO Alphabet No. 5) Maintenance Data –Initial Word Format

P	SSM (00)		“DATA CH #3”			DATA CH #2			DATA CH #1			LABEL (356, 357)		
32	31	30	29	P	23	22	L	16	15	A	9	8	1	

Alpha Numeric (ISO Alphabet No. 5) Data – Intermediate Word Format

P	SSM (10)			“DATA CH #3”			DATA CH #2			DATA CH #1			LABEL (356, 357)		
32	31	30	29	(BNR ZEROES)	23	22	A	16	15	H	9	8	1		

Alpha Numeric (ISO Alphabet No. 5) Data – Final Word Format

(Taken together, the following example shows encoding of the word ALPHA into three successive data words)

ATTACHMENT 6
GENERAL WORD FORMATS AND ENCODING EXAMPLE

TABLE 6-4

P	SSM (00)	DISCRETES										SDI	LABEL (See Below)						
32	31	30	29	MSB	[2]					LSB	11	10	9	8	1				

LABEL	USAGE SUBGROUP
155 – 161	Maintenance
270 – 276	Discretes
350 – 354	Maintenance

Discrete Word Format

TABLE 6-5

P	SSM (01)	ACKNOWLEDGEMENT (FORMAT NOT DEFINED)										WORD COUNT			LABEL (355)				
32	31	30	29	17							16	BNR EQUIV.			9	8	1		

Acknowledgement Word – Initial Word Format

TABLE 6-5-1

TABLE 6-1													
P	SSM (00)		ACKNOWLEDGEMENT (FORMAT NOT DEFINED)							LABEL (355)			
32	31	30	29								9	8	1

Acknowledgement Word – Intermediate Word Format

TABLE 6-5-2

ACKNOWLEDGEMENT (FORMAT NOT DEFINED)												LABEL (355)			
32	31	30	29								9	8			1

Acknowledgement Word – Final Word Format

TABLE 6-6

32	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1
P	SSM	DATA →										PADS → *					SDI	LABEL													
[5]	[4]											[3]					[1]	(173/174)													

* Bit No. 11 takes on the binary state “one” to annunciate that the ILS receiver is in the “tune inhibit” condition.

* Bit No. 11 takes on the binary state “one” to annunciate that the ILS receiver is in the “tune inhibit” condition.

ILS Localizer/Glideslope Deviation Word

TABLE 6-7

32	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	
P	SSM	DATA FIELD																			**		*	SDI	LABEL							
[5]	[4]																							[1]	(202)							
* Bit No. 11 is assigned to a memory on/off annunciation function (see Section 4.7 of ARINC 709)																																
** Bit No. 12 is set to “1” when data is for a foreground station in frequency scanning mode.																																
0 1 0 0 0 0 0 0 1																																

DME Distance Word

TABLE 6-8

32	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1
P A R I T Y	SSM	DATE												FLIGHT LEG	PAD [3]	SDI [1]	LABEL (260)														
		Day						Month																							
		x10			x1			x10		x1																					
		2	1	0	8	4	2	1	1	8	4	2	1														8	4	2	1	
	0	0	1	0	0	1	1	0	1	0	0	0	0	0	1	0	1	0	0	0	0	0	0	0	0	0	0	1	1	0	1
Example		2		3				0		8				5									0		6		2				

Date/Flight Leg Word

c-4

c-6

ATTACHMENT 6
GENERAL WORD FORMATS AND ENCODING EXAMPLES

TABLE 6-9

32	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1
P A R I T Y	SSM		FLIGHT NUMBER																PAD			SDI		LABEL (261)							
			x1000				x100				x10				x1																
			8	4	2	1	8	4	2	1	8	4	2	1	8	4	2	1													
	0	0	0	0	0	0	0	0	1	0	0	0	1	0	1	1	1	0	0	0	0	1	1	0	1						
Example			0				1				1				7									1		6		2			

Flight Number Word

TABLE 6-10

32	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1
P	SSM		DATA														PAD					SDI		LABEL							
[5]	[4]		MSB														[3]			[6]		[1]		(222)							

[6] Marker Beacon Output Discrete Bits

Discrete	Bit	Bit State	
		Discrete Grounded	Discrete Open
400 Hz	11	1	0
1300 Hz	12	1	0
3000 Hz	13	1	0

VOR Omnibearing

TABLE 6-11

32	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1
P	SSM			DATA														PAD	LEVER POSITION		SDI	LABEL (127/137)									
[5]	[4]																				[1]										

Lever	Bit				
	11	12	13	14	15
Position 1 (Cruise)	1	0	0	0	0
Position 2	0	1	0	0	0
Position 3	0	0	1	0	0
Position 4	0	0	0	1	0
Position 5 (Landing)	0	0	0	0	1

Slat/Flap Angle Word

TABLE 6-12

32	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1
P	SSM			HOURS				MINUTES				SECONDS				*	SDI		LABEL												
[5]	[4]			0-24				0-60				0-60							(150)												
*Bit 11 of label 150 should be encoded with a “1” when the GNSS system clock is being used as the source of time. Otherwise, bit 11 should be encoded as “0”.																															

UTC Binary Word

TABLE 6-13

32	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1			
P [5]	SSM [4]			DATA																PAD	FTI	SDI [1]	LABEL (164)											
																											0	0	1	0	1	1	1	0
Note: When Bit 11 (Functional Test Inhibit) is a “1”, a functional test should not be performed.																								4		6				1				

Radio Height Word

ATTACHMENT 6
GENERAL WORD FORMATS AND ENCODING EXAMPLE

TABLE 6-14

32	31	30	29	28	27	26	25	24	23	22	21	20	1	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1
P	SSM	DOCUMENTARY DATA																		PAD	SDI	LABEL									
		4 2 1			4 2 1			4 2 1			4 2 1			4 2 1			(262)														
[5]	[4]	Code 1			Code 2			Code 3			Code 4			Code 5			Code 6					[1]	0 1 0			0 1 1			0 1		

Documentary Data Word

[1] Source/Destination Identifier (SDI) Field

The purpose of the SDI field is explained in Section 2.1.4 of this document, as are also the limitations on its use. When the SDI function is not required, this field may be occupied by binary zero or valid data pad bits.

[2] Discretes

As discussed in Section 2.3.1.2 of this document, unused bits in a word may be assigned to discrete functions, one bit per variable. Bit #11 of the word should be the first to be so assigned, followed by bit #12 and so on, in ascending numerical order, until the data field is reached. In the absence of discretes, unused bit positions should be occupied by binary zero or valid data pad bits.

[3] Pad

All bit positions not used for data or discrete should be filled with binary zero or valid data pad bits. Section 2.1.2 of this document refers.

[4] Sign/Status Matrix (SSM)

Section 2.1.5 of this document describes the functions of the sign/status matrix and the ways in which the bits constituting it are encoded.

[5] Parity Bit

This bit is encoded to render word parity odd. Section 2.3.4 of this document refers.

ATTACHMENT 6
GENERAL WORD FORMATS AND ENCODING EXAMPLES

TABLE 6-15

32	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1
P	SSM		PAD			3 rd Digit				2 nd Digit				LSD				PAD				SDI		LABEL (046)							
1	0	0	0	0	0	0	1	1	0	0	1	0	0	1	0	0	0	0	0	0	0	0	0	0	1	1	0	0	1	0	0
Example						6				4				9										6		4			0		

Engine Serial Number (3LDs)

TABLE 6-16

32 31 30			29 28 27			26 25 24 23				22 21 20 19				18 17 16 15				14 13 12 11				10 9		8 7 6 5 4 3 2 1							
P	SSM		PAD			MSD				5 th Digit				4 th Digit				PAD				SDI		LABEL (047)							
0	0	0	0	0	0	0	0	0	0	0	0	1	1	0	0	1	0	0	0	0	0	0	1	1	1	0	0	1	0	0	
Example						0				3				2										7		4			0		

Engine Serial Number (3 MSDs)

TABLE 6-17

32	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1
P	SSM		SPARE						MSD								LSD				SDI		LABEL (377)								
1	0	0	0	0	0	0	0	0	0	0	0	0	1	0	0	0	0	1	1	0	1	0	0	1	1	1	1	1	1	1	1
									1				0				D						7		7			3			

Equipment Identifier Word
 (Example provided for 10D code)

c-17

ATTACHMENT 6
GENERAL WORD FORMATS AND ENCODING EXAMPLE

TABLE 6-18

32	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1
P A R I T Y	SSM		DATE																			SDI	LABEL								
			Day						Month						Year								(260 031)								
			x10		x1				x10	x1				x10				x1			Chronometer										
			2	1	8	4	2	1	1	8	4	2	1	8	4	2	1	8	4	2	1		Output Only								
	0 0		1	0	0	0	1	1	0	1	0	0	0	1	0	0	0	0	1	0	1	0 0	0	0	0	0	1	1	0	1	
Example		2		3				0	8				8				5					0		6			2				

TABLE 6-19

32	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1
P	SSM (00)		D	PRIMARY COUNTER 0-4096 FLIGHT LEGS												4096-65535 LEGS				PAD	SDI	LABEL (251 01A) Electronic Supervisory Control									
				MSB												LSB															

Flight Leg Counter

TABLE 6-20

32	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1
P	SSM (00)			ALTITUDE															SEE BELOW		SDI	LABEL (206 018) Transponder									
				MSB															LSB												

Bits			Range	Bits Used	App. Resolution
13	12	11			
0	0	0	65536	15	4
0	0	1	65536	14	8
0	1	0	65536	13	16
0	1	1	51200	12	25
1	0	0	81920	14	10
1	0	1	51200	10	100

Altitude (Variable Reduction)

ATTACHMENT 6
GENERAL WORD FORMATS AND ENCODING EXAMPLES

TCAS INTRUDER RANGE WORD

TABLE 6-21

32	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1					
P	SSM		INTRUDER RANGE											INTRUDER			INTRUDER				SDI		LABEL													
	[5]		[3] [4]											SENSE LVL[2]			NUMBER [1]						(130)													
0	1	1	0	0	0	0	1	0	1	0	1	0	0	0	1	0	0	0	1	0	1	0	0	0	0	0	1	1	0	1	0					
			MSB										LSB			MSB		LSB		MSB		LSB			LSB										MSB	
			5.25 NM											2			5						0		3		1									

Note 1: Maximum number of intruders is 31.

Note 2: Intruder Sensitivity Level Status

Bits			Meaning
18	17	16	
0	0	0	Not Reported
0	0	1	SL = 1
0	1	0	SL = 2
0	1	1	SL = 3
1	0	0	SL = 4
1	0	1	SL = 5
1	1	0	SL = 6
1	1	1	SL = 7

Note 3: Maximum range is 127-15/16 nautical miles.

Note 4: Intruder range may be reported in the form of horizontal range when intruder is available.

Note 5: Sign Status Matrix (SSM) [BNR]

Bits		Meaning
31	30	
0	0	Failure Warning
0	1	No Computed Data
1	0	Functional Data
1	1	Normal Operation

ATTACHMENT 6
GENERAL WORD FORMATS AND ENCODING EXAMPLE

TCAS INTRUDER ALTITUDE WORD

TABLE 6-22

32	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1		
P	SSM			RELATIVE ALTITUDE							I.V.S.		FUTURE			INTRUDER					SDI		LABEL										
	[5] [4]			[3]							[2]		SPARE			NUMBER [1]							(131)										
0	1	1	0	0	0	1	1	0	0	1	0	0	0	0	0	0	0	0	1	0	1	0	0	1	0	0	1	1	0	1	0		
			S	MSB LSB												MSB LSB							LSB MSB										
				2500 FT							LEVEL					5							1		3			1					

Note 1: Maximum number of intruders is 31.

Note 2: Sense of Intruders VERTICAL RATE (Z SINT)

Bits		Meaning
21	20	
0	0	No Vertical Rate (Level Flight)
0	1	Climbing
1	0	Descending
1	1	No Data

Note 3: Binary, Two's Complement Range = ± 12700 Ft.

Note 4: The No Computed Data Report of the SSM field applies to relative altitude (Bits 29-22) only. See Note 5.

Note 5: Sign Status Matrix (SSM) [BNR]

Bits		Meaning
31	30	
0	0	Failure Warning
0	1	No Computed Data
1	0	Functional Data
1	1	Normal Operation

ATTACHMENT 6
GENERAL WORD FORMATS AND ENCODING EXAMPLES

TCAS INTRUDER BEARING WORD

TABLE 6-23

32	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1
P	SSM			BEARING										DISPLAY MATRIX		[2]	INTRUDER NUMBER				[1]	SDI		LABEL							(132)
	[5]	[4]		[3]										[2]			[1]														
1	1	1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	0	0	0	1	0	1	1	0	1	0
			S	MSB LSB										MSB LSB			MSB LSB							LSB MSB							
				0										NO THREAT			1							2		3			1		

Note 1: Maximum number of intruders is 31.

Note 2: Display Matrix

Bits			Meaning
18	17	16	
0	0	0	No Threat
0	0	1	Traffic Advisory
0	1	0	Resolution Advisory
0	1	1	Proximate Traffic
1	0	0	Not Used
1	0	1	Not Used
1	1	0	Not Used
1	1	1	Not Used

Note 3: Binary, Fractional Binary;
Range = -180 to +180 Degrees

Note 4: The No Computed Data report in the SSM field applies to bearing information (Bits 29-19) only. See Note 5.

Note 5: Sign Status Matrix (SSM) [BNR]

Bits		Meaning
31	30	
0	0	Failure Warning
0	1	No Computed Data
1	0	Functional Data
1	1	Normal Operation

ATTACHMENT 6
GENERAL WORD FORMATS AND ENCODING EXAMPLE

TRANSPONDER ALTITUDE/TCAS OWN AIRCRAFT ALTITUDE

TABLE 6-24

32	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1			
P	SSM [2]		S	ALTITUDE																		ALT [1]	PAD	LABEL (203)										
0	1	1	0	0	0	1	0	1	0	0	1	0	0	1	0	0	0	0	1	1	0	0	0	1	1	0	0	0	0	0	1			
				MSB																					LSB									
				21059																		1			3		0		2					

S = Sign Bit see Section 2.1.5.2 of this Document.

Note 1: Altitude Resolution

Bits	Meaning
11	
0	1 Ft
1	100 Ft

Note 2: Sign Status Matrix (SSM) [BNR]

Bits	Meaning
31 30	
0 0	Failure Warning
0 1	No Computed Data
1 0	Functional Data
1 1	Normal Operation

ATTACHMENT 6
GENERAL WORD FORMATS AND ENCODING EXAMPLES

Table 6-25 BCD DATA ENCODING EXAMPLES

Bit No.	32	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	
PARAMETER (Label)		SSM	DATA FIELD [1]																					SDI	LABEL								
			MSC										LSC																				
			4	2	1	8	4	2	1	8	4	2	1	8	4	2	1	8	4	2	1	1	2		4	1	2	4	1	2			
Distance To Go +2750.4 NM	(001)	1	0	0	0	1	0	0	1	1	1	0	1	0	1	0	0	0	0	0	1	0	0	0	0	1	0	0	0	0	0	0	0
Time To Go +145.3 Min.	(002)	0	0	0	0	0	1	0	1	0	0	0	1	0	1	0	0	1	1	P	P	P	P	0	0	0	1	0	0	0	0	0	0
Cross Track Distance 225.6 NM	(003)	1	0	0	0	1	0	0	0	1	0	0	1	0	1	0	1	1	0	P	P	P	P	0	0	1	1	0	0	0	0	0	0
Ground Speed 650 Knots	(012)	1	0	0	0	0	0	0	1	1	0	0	1	0	1	0	0	0	0	P	P	P	P	0	0	0	1	0	1	0	0	0	0
Track Angle (True) 165.5 Deg.	(013)	1	0	0	0	0	1	0	1	1	0	0	1	0	1	0	1	0	1	P	P	P	P	0	0	1	1	0	1	0	0	0	0
Selected Vertical Speed -2200 Ft/Min	(020)	0	1	1	0	1	0	0	0	1	0	0	0	0	0	0	0	0	0	P	P	P	P	0	0	0	0	0	1	0	0	0	0
Selected EPR 2.05	(021)	0	0	0	0	1	0	0	0	0	0	0	1	0	1	P	P	P	P	P	P	P	P	0	0	1	0	0	0	1	0	0	0
Selected N1 2750 RPM	(021)	1	0	0	0	1	0	0	1	1	1	0	1	0	1	0	0	0	0	P	P	P	P	0	0	1	0	0	0	1	0	0	0
Selected Mach 0.850 Mach	(022)	0	0	0	0	0	0	1	0	0	0	0	1	0	1	0	0	0	0	P	P	P	P	0	0	0	1	0	0	1	0	0	0
Selected Heading 177 Deg.	(023)	1	0	0	0	0	1	0	1	1	1	0	1	1	1	P	P	P	P	P	P	P	P	0	0	1	1	0	0	1	0	0	0
Selected Course 154 Deg.	(024)	1	0	0	0	1	0	0	1	0	1	0	1	0	0	P	P	P	P	P	P	P	P	0		0	0	1	0	1	0	0	0
Selected Altitude 41000 Ft.	(025)	0	0	0	1	0	0	0	0	0	1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	0	1	0	1	0	0	0
Selected Airspeed 423 Knots	(026)	0	0	0	1	0	0	0	0	1	0	0	0	1	1	P	P	P	P	P	P	P	P	0	0	0	1	1	0	1	0	0	0
Universal Time Constant 1545.5 Hr.	(125)	1	0	0	0	0	1	0	1	0	1	0	1	0	0	0	1	0	1	0	1	0	1	0	0	1	0	1	0	1	0	1	0
Radio Height 2450.5 Ft.	(165)	0	0	0	0	1	0	0	0	1	0	0	0	1	1	0	0	0	0	0	1	0	1	0	0	1	0	1	0	1	1	1	0
Decision Height Selected 200 Ft.	(170)	0	0	0	0	1	0	0	0	0	0	0	0	0	0	P	P	P	P	P	P	P	P	0	0	0	0	0	1	1	1	1	0
DME Distance 257.86 NM	(201)	0	0	0	0	1	0	0	0	1	0	1	1	1	1	1	0	0	0	0	0	1	1	0	0	0	1	0	0	0	0	0	1
True Airspeed 565 Knots	(230)	0	0	0	1	0	1	0	1	1	0	0	1	0	1	P	P	P	P	P	P	P	P	0	0	0	0	0	1	1	0	0	1
Total Air Temp. -025 Deg. C [2]	(231)	0	1	1	0	0	0	0	0	1	0	0	1	0	1	P	P	P	P	P	P	P	P	0	0	1	0	0	1	1	0	0	1
Altitude Rate -15250 Ft/Min	(232)	1	1	1	0	0	1	0	1	0	1	0	0	1	0	0	1	0	1	0	0	0	0	0	0	0	1	0	1	1	0	0	1
Static Air Temp. +013 Deg. C [2]	(233)	1	0	0	0	0	0	0	0	0	1	0	0	1	1	P	P	P	P	P	P	P	P	0	0	1	1	0	1	1	0	0	1
Baroset (ins Hg) 29.92 ins Hg	(235)	0	0	0	0	1	0	0	1	0	0	1	0	0	1	0	0	1	0	P	P	P	P	0	0	1	0	1	1	1	0	0	1

NOTES:

- [1] “P” denotes pad “zero” or valid data, see Section 2.1.2. Note possible use of pad bits for discrete functions per Section 2.3.1.2.
- [2] Because of the actual maximum value of the most significant character of these quantities exceeds 7, it cannot be encoded in the most significant character position of the BCD word. For this reason, each quantity has been given an “artificial” MSC of zero and its actual MSC encoded in the next most significant character position of the word.

ATTACHMENT 6
GENERAL WORD FORMATS AND ENCODING EXAMPLE

Table 6-25-1 BCD ENCODING OF LATITUDE AND LONGITUDE

Bit No.	32	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	
PARAMETER (Label)		SSM	DATA FIELD																				LABEL										
			MSC										LSC																				
			1	8	4	2	1	8	4	2	1	8	4	2	1	8	4	2	1	8	4	2	1	1	2	4	1	2	4	1	2		
Present Position (Lat.) N 75 Deg 59.9' (010)	1	0	0	0	0	1	1	1	1	0	1	0	1	0	1	0	1	1	0	0	1	1	0	0	1	0	0	0	1	0	0	0	0
Present Position (Long) W 169 Deg 25.8' (011)	0	1	1	1	1	0	1	1	0	1	0	0	1	0	0	1	0	0	1	0	1	1	0	0	0	1	0	0	1	0	0	0	0

c-4

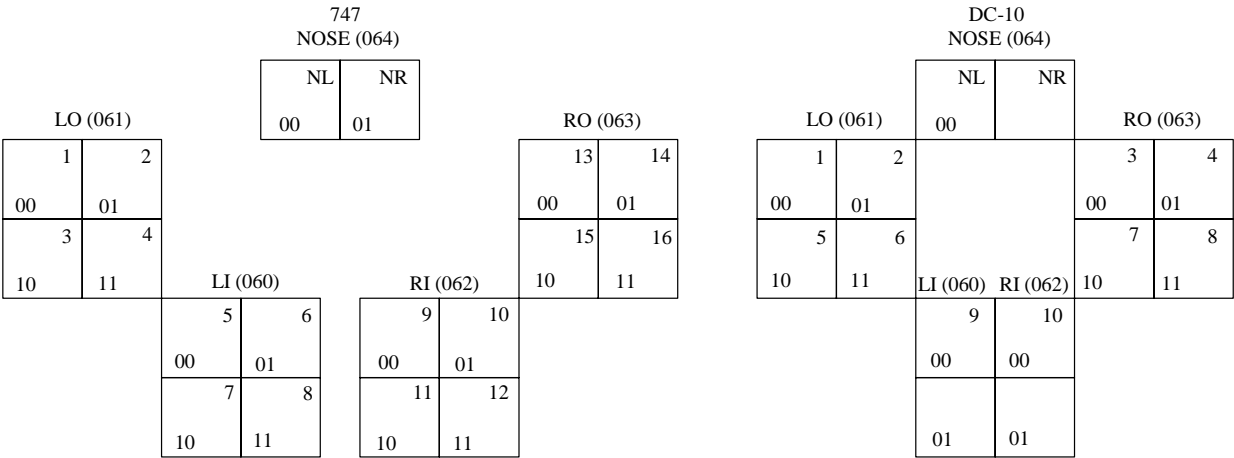
(See Commentary following Section 2.1.2 of this document for further information.)

ATTACHMENT 6
GENERAL WORD FORMATS AND ENCODING EXAMPLES

TABLE 6-26

Wheel 747	Nos. DC-10	32	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	Bit Nos.
		PARITY	BNR	BCD	SPARES	MSB	DATA												LSB	SPARE	SPARE	DIFF. LOW	THRESHOLD LOW	WHEEL FAULT	SYSTEM FAULT	WHEEL LABEL	LABEL	REF. ARINC OCT.						
						512	256	128	64	32	16	8	4	2	1																			
1	1		1	0																				0	0	1	0	1	1	0	0	1	0	115
2	2		1	0																				0	1	1	0	1	1	0	0	1	0	115
13	3		1	0																				0	0	1	1	1	1	0	0	1	0	117
14	4		1	0																				0	1	1	1	1	1	0	0	1	0	117
3	5		1	0																				1	0	1	0	1	1	0	0	1	0	115
4	6		1	0																				1	1	1	0	1	1	0	0	1	0	115
15	7		1	0																				1	0	1	1	1	1	0	0	1	0	117
16	8		1	0																				1	1	1	1	1	1	0	0	1	0	117
5	9		1	0																				0	0	0	0	1	1	0	0	1	0	114
9	10		1	0																				0	0	0	1	1	1	0	0	1	0	116
6			1	0																				0	1	0	0	1	1	0	0	1	0	114
7			1	0																				1	0	0	0	1	1	0	0	1	0	114
8			1	0																				1	1	0	0	1	1	0	0	1	0	114
10			1	0																				0	1	0	1	1	1	0	0	1	0	116
11			1	0																				1	0	0	1	1	1	0	0	1	0	116
12			1	0																				1	1	0	1	1	1	0	0	1	0	116

BITS
10 9



ATTACHMENT 6
GENERAL WORD FORMATS AND ENCODING EXAMPLE

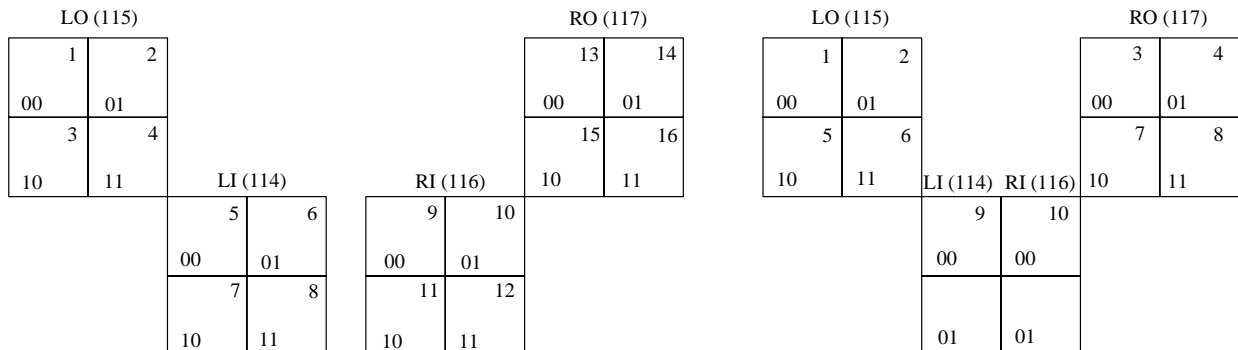
TABLE 6-26-1

Wheel 747	Nos. DC-10	32	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	Bit Nos.	
		PARITY	BNR	BCD	SPARES	MSB	DATA										LSB	PREDICT	DIFF.TEMP.	WARM	HOT	BRAKE FAULT	SYSTEM	WHEEL LABEL	LABEL										REF. ARINC OCT.
							512	256	128	64	32	16	8	4	2	1																			
1	1		1	0																				0	0	1	0	1	1	0	0	0	0	115	
2	2		1	0																				0	1	1	0	1	1	0	0	1	0	115	
13	3		1	0																				0	0	1	1	1	1	0	0	1	0	117	
14	4		1	0																				0	1	1	1	1	1	0	0	1	0	117	
3	5		1	0																				1	0	1	0	1	1	0	0	1	0	115	
4	6		1	0																				1	1	1	0	1	1	0	0	1	0	115	
15	7		1	0																				1	0	1	1	1	1	0	0	1	0	117	
16	8		1	0																				1	1	1	1	1	1	0	0	1	0	117	
5	9		1	0																				0	0	0	0	1	1	0	0	1	0	114	
9	10		1	0																				0	0	0	1	1	1	0	0	1	0	116	
6			1	0																				0	1	0	0	1	1	0	0	1	0	114	
7			1	0																				1	0	0	0	1	1	0	0	1	0	114	
8			1	0																				1	1	0	0	1	1	0	0	1	0	114	
10			1	0																				0	1	0	1	1	1	0	0	1	0	116	
11			1	0																				1	0	0	1	1	1	0	0	1	0	116	
12			1	0																				1	1	0	1	1	1	0	0	1	0	116	

BITS
10 9

747

DC-10



ATTACHMENT 6
GENERAL WORD FORMATS AND ENCODING EXAMPLES

Table 6-27 BNR DATA ENCODING EXAMPLES

Bit No.	32	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1		
PARAMETER (Label)	P	SSM			DATA FIELD [1]																		SDI	LABEL										
																								1	2	4	1	2	4	1	2			
Selected Course 0 Deg. [3]	(100)	0	1	1	0	0	0	0	0	0	0	0	0	0	0	0	P	P	P	P	P	P	P	0	0	0	0	0	0	0	0	1	0	
Selected Heading 150 Deg. [3]	(101)	0	1	1	0	1	1	0	1	0	1	0	1	0	1	P	P	P	P	P	P	P	0	0	1	0	0	0	0	0	0	1	0	
Selected Altitude 41000 Ft.	(102)	1	1	1	0	1	0	1	0	0	0	0	0	0	1	0	1	0	0	0	P	P	0	0	0	1	0	0	0	0	0	1	0	
Selected Airspeed 423.0 Knots	(103)	0	1	1	0	1	1	0	1	0	0	1	1	1	0	0	P	P	P	P	P	P	P	0	0	1	1	0	0	0	0	1	0	
Selected Vertical Speed -2200 Ft/Min [2]	(104)	1	1	1	1	1	1	0	1	1	1	0	1	1	0	P	P	P	P	P	P	P	P	0	0	0	0	1	0	0	0	1	0	
Selected Mach 800 m Mach	(106)	1	1	1	0	0	0	1	1	0	0	1	0	0	0	0	P	P	P	P	P	P	P	0	0	0	1	1	0	0	0	1	0	
Desired Track 275 Deg. [3]	(114)	0	1	1	1	1	0	0	0	0	1	1	1	0	0	1	0	P	P	P	P	P	P	0	0	0	0	1	1	0	0	1	0	
Cross Track Distance 51.0 NM	(116)	1	1	1	0	0	1	1	0	0	1	1	0	0	0	0	0	0	0	0	P	P	P	0	0	0	1	1	1	0	0	1	0	
Vertical Deviation 600 Ft.	(117)	0	1	1	0	0	1	0	1	1	1	0	0	0	0	P	P	P	P	P	P	P	P	0	0	1	1	1	1	0	0	1	0	
Flight Director Roll +30 Deg.	(140)	1	1	1	0	0	0	1	0	1	0	1	0	1	0	1	1	P	P	P	P	P	P	0	0	0	0	0	0	0	1	0	1	
Flight Director Pitch -10 Deg. [2]	(141)	1	1	1	1	1	0	0	0	0	1	1	1	0	0	P	P	P	P	P	P	P	0	0	1	0	0	0	0	0	1	1	0	
Fast/Slow +15 Knots	(142)	0	1	1	0	0	1	1	1	1	0	0	0	0	0	0	P	P	P	P	P	P	P	0	0	0	1	0	0	0	1	1	0	
UTC (18:57:20)	(150)	0	1	1	0	1	0	0	1	0	1	1	1	0	0	1	0	1	0	1	0	0	0	0	0	0	0	0	0	1	0	1	1	0
Radio Height 2450 Ft.	(164)	0	1	1	0	0	1	1	0	0	1	0	0	1	0	0	1	0	0	0	0	P	0	0	0	0	0	1	0	1	1	1	0	
Localizer Deviation +0.021 DDM	(173)	1	1	1	0	0	0	0	1	1	0	1	1	0	0	0	P	P	P	P	P	P	P	0	0	1	1	0	1	1	1	1	0	
Glide Slope Deviation -0.125 DDM [2]	(174)	1	1	1	1	1	1	0	1	1	0	0	0	0	0	0	P	P	P	P	P	P	P	0	0	0	0	1	1	1	1	1	0	
DME Distance 257.86 NM	(202)	0	1	1	0	1	0	0	0	0	0	0	1	1	1	0	1	1	1	1	0	P	0	0	0	0	1	0	0	0	0	0	1	
Altitude (29.92) 45000 Ft.	(203)	0	1	1	0	0	1	0	1	0	1	1	1	1	1	1	0	0	1	0	0	0	P	0	0	0	1	1	0	0	0	0	1	
Mach 0.8325 Mach	(205)	0	1	1	0	0	0	1	1	0	1	0	0	0	0	0	0	1	0	0	0	P	P	0	0	0	1	0	1	0	0	0	1	
Computed Airspeed 425 Knots	(206)	1	1	1	0	0	1	1	0	1	0	0	1	0	0	0	0	0	0	P	P	P	P	0	0	0	1	1	0	0	0	0	1	
True Airspeed 565 Knots	(210)	0	1	1	0	0	0	0	1	1	0	1	0	1	0	0	0	0	0	P	P	P	P	0	0	0	0	0	1	0	0	0	1	
Static Air Temp +13 Deg. C	(213)	0	1	1	0	0	0	0	0	1	1	0	1	0	0	P	P	P	P	P	P	P	P	0	0	1	1	0	1	0	0	0	1	
Total Air Temp -25 Deg. C [2]	(211)	0	1	1	1	1	1	0	0	0	1	1	1	0	0	P	P	P	P	P	P	P	P	0	0	1	0	0	1	0	0	0	1	
Altitude Rate -15250 Ft/Min [2]	(212)	0	1	1	1	1	0	0	1	0	0	0	1	1	1	P	P	P	P	P	P	P	P	0	0	0	1	0	1	0	0	0	1	
Present Pos. Lat. N 81.5 Deg	(310)	1	1	1	0	0	1	1	1	0	0	1	1	1	1	1	0	1	0	1	0	1	0	0	0	0	0	0	1	0	0	1	1	
Present Pos. Long. W 100.25	(311)	0	1	1	1	0	0	0	0	0	1	0	1	1	0	1	1	0	1	0	0	0	0	0	0	0	1	0	0	1	0	0	1	
Ground Speed 650 Knots	(312)	1	1	1	0	0	0	1	0	1	0	0	0	1	0	1	0	0	0	0	P	P	P	0	0	0	1	0	1	0	0	1	1	
Flight Path Accel +2.50 g	(323)	0	1	1	0	1	0	1	0	0	0	0	0	0	1	0	1	0	0	P	P	P	P	0	0	1	1	0	0	1	0	1	1	

NOTES:

- [1] “P” denotes pad “zero” or valid data, see Section 2.1.2. Note possible use of pad bits for discrete functions per Section 2.3.1.2.
- [2] Negative values are encoded as the two’s complements of positive values and the negative sign is annunciated in the sign/status matrix.
- [3] Angles in the range 0 to 180° are encoded as positive numbers. Angles in the range 180° to 360° are subtracted from 360° and the resulting number encoded as a negative value per note 2. Arc minutes and seconds are encoded as decimal degrees.

ATTACHMENT 6
GENERAL WORD FORMATS AND ENCODING EXAMPLE

TABLE 6-28

AVM Command Word – Label 227 03D

32	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1		
P	Command/Control Bits							AVM Hex (Equipment) ID = 03D Hex														PADS	SDI	Label (227)									
								0	0	0	0	0	0	1	1	1	1	0	1							1	1	1	0	1	0	0	1

Bits		Meaning
10	9	
0	0	Engine 4 (or All Call) {not used on 757}
0	1	Engine 1 (or Engine 1 and 2)
1	0	Engine 2
1	1	Engine 3 (or Engine 3 and 4)

Bits							Parameter
31	30	29	28	27	26	25	
0	0	0	0	0	0	0	Not Used
0	0	0	0	0	0	1	Unit Self Test
0	0	0	0	0	1	0	Use Accelerometer A**
0	0	0	0	0	1	1	Use Accelerometer B**
0	0	0	0	1	0	0	PAD
0	0	0	0	1	0	1	Erase Fault History
0	0	0	0	1	1	0	Erase Flight History*
0	0	0	0	1	1	1	Read Fault History
0	0	0	1	0	0	0	Read Flight History*
0	0	1	0	0	1	0	Reserved*

* 737 Only

** 757 Only

ATTACHMENT 6
GENERAL WORD FORMATS AND ENCODING EXAMPLES

ACMS INFORMATION

ORIGIN AND DESTINATION

TABLE 6-29
Label 061 002

32	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1
P	SSM		ORIGIN CHAR #3							ORIGIN CHAR #2							ORIGIN CHAR #1							OCTAL LABEL 061							

Label 062 002

32	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1
P	SSM		DESTINATION CHAR #1							ISO #5 CHAR "SPACE"							ORIGIN CHAR #4							OCTAL LABEL 062							

Label 063 002

32	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1
P	SSM		DESTINATION CHAR #4							DESTINATION CHAR #3							DESTINATION CHAR #2							OCTAL LABEL 063							

NOTE: All characters are expressed in ISO #5 format, as defined in ARINC Specification 429.

ATTACHMENT 6
GENERAL WORD FORMATS AND ENCODING EXAMPLE

TABLE 6-30

TACAN Control - Label 145 002

RANGE 126
 RESOLUTION 1.0
 RATE 5Hz \pm 10%

Bit No.	Description	
1	0	1
2	1	
3	1	
4	0	4
5	0	
6	1	
7	0	5
8	1	
9-10	SDI	
11-13	Pad Zero	
14	VOR/TAC Select (TAC=1, VOR=0)	
15	TACAN Select (TAC 1=1, TAC 2=0)	
16	Pad Zero	
17-20	BCD Units Chan Cont (LSB=17)	
21-24	Hex Tens Chan Cont (LSB=24)	
25	Pad Zero	
26	X/Y Mode (X=1, Y=0)	
27-28	Mode Cont (see Table A)	
29	Pad Zero	
30-31	SSM (see Table B)	
32	Parity (Odd)	

Table A – Mode Control

Bits		Description
27	28	
0	0	
0	1	
1	0	
1	1	A/A T/R

Table B – SSM

Bits		Description
30	31	
0	0	
0	1	
1	0	
1	1	Not Used

ATTACHMENT 6
GENERAL WORD FORMATS AND ENCODING EXAMPLES

ACMS INFORMATION FLIGHT NUMBER

TABLE 6-31

Label 233 EQ ID 002						MSB				LSB				MSB				LSB													
32	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1
P	SSM		PAD ZERO			CHAR #2						PAD ZERO	CHAR #1					SDI			OCTAL LABEL 233										

Label 234 EQ ID 002

32	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1
P	SSM		PAD ZERO			CHAR #4						PAD ZERO	CHAR #3						SDI	OCTAL LABEL 234											

Label 235 EQ ID 002

32	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1
P	SSM		PAD ZERO			CHAR #6					PAD ZERO	CHAR #5					SDI		OCTAL LABEL 235												

Label 236 EQ ID 002

32	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1
P	SSM		PAD ZERO			CHAR #8					PAD ZERO	CHAR #7					SDI	OCTAL LABEL 236													

Sign Matrix for BNR

Bit		Meaning
31	30	
0	0	Failure Warning
0	1	No Computed data
1	0	Functional Test
1	1	Normal Operation

TABLE 6-32

Label 233 EQ ID 018						MSB						LSB						MSB						LSB							
32	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1
P		SSM		PAD ZERO			CHAR #2						PAD ZERO		CHAR #1						SDI		OCTAL LABEL 233								

Label 234 EQ ID 018

32	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1
P	SSM		PAD ZERO			CHAR #4						PAD ZERO	CHAR #3						SDI	OCTAL LABEL 234											

Label 235 EQ ID 018

32	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1
P	SSM		PAD ZERO			CHAR #6						PAD ZERO	CHAR #5						SDI	OCTAL LABEL 235											

Label 236 EQ ID 018

32	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1
P	SSM		PAD ZERO			CHAR #8				PAD ZERO		CHAR #7				SDI		OCTAL LABEL 236													

Sign Matrix for BCD

Bit		Meaning
31	30	
0	0	Valid
0	1	No Computed data
1	0	Functional Test
1	1	Failure Warning

NOTE: The following information is provided in order to clarify the confusion that existed in the Industry in regards to definition of the SSM for Label 233-236. It is expected that Flight ID will be sourced from FMC EQ ID of 002. Alternative implementation may include Mode "S" XPDR EQ ID 018. In this case the user cautioned that the SSM will be BCD format. See ARINC Characteristic 718A, "Mark 4 Air Traffic Control Transponder (ATCRB/MODE S)", Attachment 3A for more detailed information.

ATTACHMENT 6
GENERAL WORD FORMATS AND ENCODING EXAMPLE

TABLE 6-33

Label 360-002

32	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1
P	0	1	“STX”							PAD ZERO							BINARY WORD COUNT							OCTAL LABEL 360							
			0	0	0	0	0	1	0								0	0	0	0	0	1	1	1							

INITIAL WORD

32	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1
P	0	0	FLIGHT NUMBER CHAR #3						FLIGHT NUMBER CHAR #2						FLIGHT NUMBER CHAR #1						OCTAL LABEL 360										

INTERMEDIATE WORD (SECOND)

32	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1
P	0	0	FLIGHT NUMBER CHAR #6						FLIGHT NUMBER CHAR #5						FLIGHT NUMBER CHAR #4						OCTAL LABEL 360										

INTERMEDIATE WORD (THIRD)

32	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1
P	0	0	ORIGIN CHAR #1							FLIGHT NUMBER CHAR #8							FLIGHT NUMBER CHAR #7							OCTAL LABEL 360							

INTERMEDIATE WORD (FOURTH)

32	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1
P	0	0	ORIGIN CHAR #4						ORIGIN CHAR #3						ORIGIN CHAR #2						OCTAL LABEL 360										

INTERMEDIATE WORD (FIFTH)

32	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1
P	0	0	DESTINATION CHAR #3						DESTINATION CHAR #2						DESTINATION CHAR #1						OCTAL LABEL 360										

INTERMEDIATE WORD (SIXTH)

32	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1
P	0	0	PAD ZEROS						PAD ZEROS						DESTINATION CHAR #4						OCTAL LABEL 360										

INTERMEDIATE WORD (SEVENTH)

NOTE: All characters are expressed in ISO #5 format, as defined in Attachment 5.

ATTACHMENT 6

GENERAL WORD FORMATS AND ENCODING EXAMPLES

TABLE 6-34

32	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1
<div style="display: flex; align-items: center; justify-content: space-between;"> <div>P</div> <div> <div style="width: 100%; border-top: 1px solid black; position: relative;"> <div style="position: absolute; left: 0; top: -5px;">←</div> <div style="position: absolute; right: 0; top: -5px;">→</div> <div style="position: absolute; left: 50%; transform: translateX(-50%); top: -10px;">0</div> </div> </div> </div>																SUBSYSTEM SAL <div style="text-align: right;">MSB</div>								SUBSYSTEM ID (LABEL 172)							

ATTACHMENT 6
GENERAL WORD FORMATS AND ENCODING EXAMPLE

TABLE 6-35**FQIS System Data - Label 241 04D**

LABEL:	241
EQPT ID:	04D
PARAMETER NAME:	FQIS System Data
UNITS:	(See Below)
RANGE (SCALE):	(See Below)
SIGNIFICANT DIGITS:	(See Below)
RESOLUTION:	(See Below)
MIN TRANS INTERVAL (msec):	500
MAX TRANS INTERVAL (msec):	1024
SOURCE DESTINATION IDENTIFIER:	01 – LEFT MAIN TANK
	10 – RIGHT MAIN TANK
	11 – CENTER TANK

Label 241 is transmitted approximately once per second. The data encoding depends on the sequence which it is transmitted. Label 241 transmitting sequence, as defined below, starts with the left main tank data followed by the right main tank and then the center tank. Once all the tank data has been transmitted (63 words of data), the sequence will repeat with word number 1, left main tank, and so on. To determine the data that is transmitted at any specific time requires knowing where in the following sequence the word is taken.

LABEL 241 WORD SEQUENCE

<u>Word</u>	<u>Signal</u>	<u>Units</u>	<u>Range</u>	<u>Sig. Dig.</u>	<u>Res</u>	<u>Data</u>
1	LEFT MAIN TANK NO. 1	pF	319.922	12	.078125	BNR
2	LEFT MAIN TANK NO. 2	pF	319.922	12	.078125	BNR
3	LEFT MAIN TANK NO. 3	pF	319.922	12	.078125	BNR
4	LEFT MAIN TANK NO. 4	pF	319.922	12	.078125	BNR
5	LEFT MAIN TANK NO. 5	pF	319.922	12	.078125	BNR
6	LEFT MAIN TANK NO. 6	pF	319.922	12	.078125	BNR
7	LEFT MAIN TANK NO. 7	pF	319.922	12	.078125	BNR
8	LEFT MAIN TANK NO. 8	pF	319.922	12	.078125	BNR
9	LEFT MAIN TANK NO. 9	pF	319.922	12	.078125	BNR
10	LEFT MAIN TANK NO. 10	pF	319.922	12	.078125	BNR
11	LEFT MAIN TANK NO. 11	pF	319.922	12	.078125	BNR
12	LEFT MAIN TANK NO. 12	pF	319.922	12	.078125	BNR
13	LEFT MAIN TANK NO. 13	pF	319.922	12	.078125	BNR
14	LEFT MAIN TANK NO. 14	pF	319.922	12	.078125	BNR
15	LEFT MAIN BITE CAP. NO. 1	pF	319.922	12	.078125	BNR
16	LEFT MAIN COMPENSATOR	pF	319.922	12	.078125	BNR
17	LOAD SELECT 10,000	Lb	0-90000	1	10000	BCD
18	LOAD SELECT 1,000	Lb	0-9000	1	1000	BCD
19	LOAD SELECT 100	Lb	0-900	1	100	BCD
20	NO DATA TRANSMITTED DURING THIS WORD					
21	LEFT MAIN FUEL DENSITY	Lb/Gal	8.000	12	.000977	BNR (1)
22	RIGHT MAIN TANK NO. 1	pF	319.922	12	.078125	BNR
23	RIGHT MAIN TANK NO. 2	pF	319.922	12	.078125	BNR
24	RIGHT MAIN TANK NO. 3	pF	319.922	12	.078125	BNR
25	RIGHT MAIN TANK NO. 4	pF	319.922	12	.078125	BNR
26	RIGHT MAIN TANK NO. 5	pF	319.922	12	.078125	BNR
27	RIGHT MAIN TANK NO. 6	pF	319.922	12	.078125	BNR
28	RIGHT MAIN TANK NO. 7	pF	319.922	12	.078125	BNR
29	RIGHT MAIN TANK NO. 8	pF	319.922	12	.078125	BNR
30	RIGHT MAIN TANK NO. 9	pF	319.922	12	.078125	BNR
31	RIGHT MAIN TANK NO. 10	pF	319.922	12	.078125	BNR
32	RIGHT MAIN TANK NO. 11	pF	319.922	12	.078125	BNR
33	RIGHT MAIN TANK NO. 12	pF	319.922	12	.078125	BNR
34	RIGHT MAIN TANK NO. 13	pF	319.922	12	.078125	BNR
35	RIGHT MAIN TANK NO. 14	pF	319.922	12	.078125	BNR
36	RIGHT MAIN COMPENSATOR	pF	319.922	12	.078125	BNR
37	RIGHT MAIN BITE CAP. NO. 2	pF	319.922	12	.078125	BNR
38	LOAD SELECT 10,000	Lb	0-90000	1	10000	BCD
39	LOAD SELECT 1,000	Lb	0-9000	1	1000	BCD
40	LOAD SELECT 100	Lb	0-900	1	100	BCD
41	NO DATA TRANSMITTED DURING THIS WORD					
42	RIGHT MAIN DENSITY	Lb/Gal	8.000	12	.000977	BNR
43	CENTER TANK NO. 1	pF	319.922	12	.078125	BNR
44	CENTER TANK NO. 2	pF	319.922	12	.078125	BNR
45	CENTER TANK NO. 3	pF	319.922	12	.078125	BNR
46	CENTER TANK NO. 4	pF	319.922	12	.078125	BNR

ATTACHMENT 6
GENERAL WORD FORMATS AND ENCODING EXAMPLES

TABLE 6-35 (cont'd)**LABEL 241 WORD SEQUENCE (cont'd)**

<u>Word</u>	<u>Signal</u>	<u>Units</u>	<u>Range</u>	<u>Sig. Dig.</u>	<u>Res</u>	<u>Data</u>
47	CENTER TANK NO. 5	pF	319.922	12	.078125	BNR
48	CENTER TANK NO. 6	pF	319.922	12	.078125	BNR
49	CENTER TANK NO. 7	pF	319.922	12	.078125	BNR
50	CENTER TANK NO. 8	pF	319.922	12	.078125	BNR
51	CENTER TANK NO. 9	pF	319.922	12	.078125	BNR
52	CENTER COMPENSATOR	pF	319.922	12	.078125	BNR
53	CENTER BITE CAP. NO. 3	pF	319.922	12	.078125	BNR
54	NO DATA TRANSMITTED DURING THIS WORD					
55	NO DATA TRANSMITTED DURING THIS WORD					
56	NO DATA TRANSMITTED DURING THIS WORD					
57	NO DATA TRANSMITTED DURING THIS WORD					
58	NO DATA TRANSMITTED DURING THIS WORD					
59	LOAD SELECT 10,000	Lb	0-90000	1	10000	BCD
60	LOAD SELECT 1,000	Lb	0-9000	1	1000	BCD
61	LOAD SELECT 100	Lb	0-900	1	100	BCD
62	NO DATA TRANSMITTED DURING THIS WORD					
63	CENTER TANK DENSITY	Lb/Gal	8.000	12	.000977	BNR

NOTES:

- (1) Add 4 Lb/Gal adjustment to density data, i.e., 0000 = 4.0 Lb/Gal, FFF = 8.0 Lb/Gal.

FQIS (EQ ID 04D) SDI Encoding for Labels 012, 013, 020, 022, 023, 030, 255, 310, 320, 324, 342, 346, 354

Bits		Data
9	10	Aux Center Left Right
0	0	
1	1	
1	0	
0	1	

FQIS (EQ ID 04D) SDI Encoding for Labels 156, 157, 160

Bits		Data
9	10	#1 #2 #3 #4
0	0	
1	0	
0	1	
1	1	

ATTACHMENT 6
GENERAL WORD FORMATS AND ENCODING EXAMPLE

TABLE 6-36

S/G HARDWARE PART NO. – Label 060 025

32	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1
P		SSM	BCD CHARACTER ***																	RESERVED			SDI	OCTAL LABEL 060							

Bit No.	Function	Bit Status	
		1	0
10	SDI (Indicates Sequence ID)*	Own P/N	Other P/N
11	RESERVED (Own P/N)		
12	RESERVED (Position ID)**		
13	RESERVED (Position ID)**		

* Refer to Table 1 below

** Refer to Table 2 below

*** Unused Characters (Digits) are Pad Zero

Table 1

Bits		Sequence ID
10	9	
0	1	First Three Digits
1	0	Next Four Digits
1	1	Last Three Digits

Table 2

Bits		Position ID
13	12	
0	0	Left
1	0	Center As Left
1	1	Center As Right
0	1	Right

ATTACHMENT 6
GENERAL WORD FORMATS AND ENCODING EXAMPLES

TABLE 6-37

S/G SOFTWARE PART NO. – Label 061 025

32	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	
P	SSM	BCD CHARACTER ***																	RESERVED			SDI	OCTAL LABEL 061									

Bit No.	Function	Bit Status	
		1	0
10	SDI (Indicates Sequence ID)*	Own P/N	Other P/N
11	RESERVED (Own P/N)		
12	RESERVED (Position ID)**		
13	RESERVED (Position ID)**		

- * Refer to Table 1 below
- ** Refer to Table 2 below
- *** Unused Characters (Digits) are Pad Zero

Table 1

Bits		Sequence ID
10	9	
0	1	First Three Digits
1	0	Next Four Digits
1	1	Last Three Digits

Table 2

Bits		Position ID
13	12	
0	0	Left
1	0	Center As Left
1	1	Center As Right
0	1	Right

ATTACHMENT 6
GENERAL WORD FORMATS AND ENCODING EXAMPLE

TABLE 6-37

OP. SOFTWARE PART NO. – Label 207 025

32	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1
P		SSM	BCD CHARACTER ***																	RESERVED			SDI	OCTAL LABEL 207							

Bit No	Function	Bit Status	
		1	0
10	SDI (Indicates Sequence ID)*	Own P/N	Other P/N
11	RESERVED (Own P/N)		
12	RESERVED (Position ID)**		
13	RESERVED (Position ID)**		

* Refer to Table 1 below

** Refer to Table 2 below

*** Unused Characters (Digits) are Pad Zero

Table 1

Bits		Sequence ID
10	9	
0	1	First Three Digits
1	0	Next Four Digits
1	1	Last Three Digits

Table 2

Bits		Position ID
13	12	
0	0	Left
1	0	Center As Left
1	1	Center As Right
0	1	Right

ATTACHMENT 6
GENERAL WORD FORMATS AND ENCODING EXAMPLES

TABLE 6-38

Tank Unit Data – Label 241 160

Word Number	SDI	DESCRIPTION	UNITS
1	1	Tank Unit #1	pF
2	1	Tank Unit #2	pF
3	1	Tank Unit #3	pF
4	1	Tank Unit #4	pF
5	1	Tank Unit #5	pF
6	1	Tank Unit #6	pF
7	1	Tank Unit #7	pF
8	1	Tank Unit #8	pF
9	1	Tank Unit #9	pF
10	1	Tank Unit #10	pF
11	1	Tank Unit #11	pF
12	1	Tank Unit #12	pF
13	1	Tank Unit #13	pF
14	1	Tank Unit #14	pF
15	1	BITE Capacitor	pF
16	1	Compensator	pF
17	1	Load Select	Lbs.
18	1	Load Select	Lbs.
19	1	Load Select	Lbs.
20	1	Undefined	-
21	1	Fuel Density	Lbs/Gal
22	2	Tank Unit #1	pF
23	2	Tank Unit #2	pF
24	2	Tank Unit #3	pF
25	2	Tank Unit #4	pF
26	2	Tank Unit #5	pF
27	2	Tank Unit #6	pF
28	2	Tank Unit #7	pF
29	2	Tank Unit #8	pF
30	2	Tank Unit #9	pF
31	2	Tank Unit #10	pF
32	2	Tank Unit #11	pF
33	2	Tank Unit #12	pF
34	2	Tank Unit #13	pF
35	2	Tank Unit #14	pF
36	2	Compensator	pF
37	2	BITE Capacitor #2	pF
38	2	Load Select	Lbs
39	2	Load Select	Lbs
40	2	Load Select	Lbs
41	2	Undefined	-
42	2	Fuel Density	Lbs/Gal
43	3	Tank Unit #1	pF
44	3	Tank Unit #2	pF
45	3	Tank Unit #3	pF
46	3	Tank Unit #4	pF
47	3	Tank Unit #5	pF
48	3	Tank Unit #6	pF
49	3	Tank Unit #7	pF
50	3	Tank Unit #8	pF
51	3	Tank Unit #9	pF
52	3	Compensator	pF
53	3	BITE Capacitor #3	pF
54	3	Undefined	-
55	3	Undefined	-
56	3	Undefined	-
57	3	Undefined	-
58	3	Undefined	-
59	3	Load Select	Lbs
60	3	Load select	Lbs
61	3	Load Select	Lbs
62	3	Undefined	-
63	3	Fuel Density	Lbs/Gal

ATTACHMENT 6
GENERAL WORD FORMATS AND ENCODING EXAMPLE

TABLE 6-38-1

Tank Unit Data – Label 241 160 (cont'd)

RAW DATA TABLE

All Data Entries are 12-bit Center Justified Words

Table Organization:	Words 1-20 raw data for left tank Word 1 = Tank Unit #1 Word 2 = Tank Unit #2 Word 3 = Tank Unit #3 Word 4 = Tank Unit #4 Word 5 = Tank Unit #5 Word 6 = Tank Unit #6 Word 7 = Tank Unit #7 Word 8 = Tank Unit #8 Word 9 = Tank Unit #9 Word 10 = Tank Unit #10 Word 11 = Tank Unit #11 Word 12 = Tank Unit #12 Word 13 = (Spare) Word 14 = (Spare) Word 15 = BITE Capacitor #1 Word 16 = Compensator Word 17 = Load Select 10,000 Digit Word 18 = Load Select 1,000 Digit Word 19 = Load Select 100 Digit Word 20 = None Word 21-40 raw data for right tank Word 21 = Tank Unit #1 Word 22 = Tank Unit #2 Word 23 = Tank Unit #3 Word 24 = Tank Unit #4 Word 25 = Tank Unit #5 Word 26 = Tank Unit #6 Word 27 = Tank Unit #7 Word 28 = Tank Unit #8 Word 29 = Tank Unit #9 Word 30 = Tank Unit #10 Word 31 = Tank Unit #11 Word 32 = Tank Unit #12 Word 33 = (Spare) Word 34 = (Spare) Word 35 = Compensator Word 36 = BITE Capacitor #2 Word 37 = Load Select 10,000 Digit Word 38 = Load Select 1,000 Digit Word 39 = Load Select 100 Digit Word 40 = None Words 41-60 raw data for Center Tank Word 41 = Tank Unit #1 Word 42 = Tank Unit #2 Word 43 = Tank Unit #3 Word 44 = Tank Unit #4 Word 45 = Tank Unit #5 Word 46 = Tank Unit #6 Word 47 = Tank Unit #7 Word 48 = Tank Unit #8 Word 49 = Tank Unit #9 Word 50 = Compensator Word 51 = BITE Capacitor #3 Word 52 = (Spare) Word 53 = (Spare) Word 54 = (Spare) Word 55 = (Spare) Word 56 = (Spare) Word 57 = Load Select 10,000 Digit Word 58 = Load Select 1,000 Digit Word 59 = Load Select 100 Digit Word 60 = None
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ATTACHMENT 6
GENERAL WORD FORMATS AND ENCODING EXAMPLES

TABLE 6-39

Note:
Bit examples for 24- bit ICAO address labels 24/216 have been moved to Part 2 of ARINC 429.

c-17

ATTACHMENT 6
GENERAL WORD FORMATS AND ENCODING EXAMPLES

TABLE 6-40**RADIO SYSTEMS MANAGEMENT WORD FORMATS**

ADF															
Function	PARITY (odd)	SIGN/STATUS MATRIX	1000 kHz (1)	100 kHz (0)	10 kHz (5)	1 kHz (7)	0.5 kHz	SPARE	ANT	BFO	RESERVED (SDI)	LABEL ADF Frequency (032)			
Bit No. Example	32 1	31 30 0 0	29 28 27 0 0 1	26 25 24 23 0 0 0 0	22 21 20 19 0 1 0 1	18 17 16 15 0 1 1 1	14 1	13 0	12 0	11 0	10 9 0 0	8 7 6 0 1 0	5 6 4 1 1 0	2 1 0 0	
Notes							[1]		[2]	[2]		2	3	0	

- [1] When bit no. 14 is “zero,” the radio should tune to the whole kilohertz frequency encoded in the word.
When bit no. 14 is “one,” the radio should tune 0.5 kHz above this frequency.

[2]

Bit	Zero	One
11	BFO off	BFO on
12	ADF Mode	ANT Mode

TABLE 6-41

DME														
Function	PARITY (odd)	SIGN/STATUS MATRIX	10 MHz	1 MHz	0.1 MHz	0.00/0.05 MHz	IDENT DISPLAY	MLS FREQ.	ILS FREQ.	DME Mode	SDI	LABEL DME Frequency (035)		
Bit No. Example	32 1	31 30 0 0	29 28 27 0 0 1	26 25 24 23 0 1 0 1	22 21 20 19 0 1 1 0	18 1	17 16 0 1	15 0	14 0	13 12 11 0 0 0	10 9 0 0	8 7 6 1 0 1	5 4 3 1 1 0	2 1 0 0
Notes [1] [5]						[2]	[7]	[3]		[4]		5	3	0

- [1] Directed Frequency #1, 115.65 MHz, VOR
- [2] Bit 18 is used only for VOR & ILS frequencies and is limited to .00 or .05
- [3] Bits 15 & 14 codes: VOR (0,0), ILS (0,1) or MLS (1,0), (1,1) is spare
- [4] Refer to table in Section 4.1.2 of ARINC Characteristic 709 for mode codes
- [5] Although not encoded in the tuning word all VOR & ILS frequencies have 1 as hundreds digit. Although not encoded in the tuning word all MLS frequencies have 5 as the thousand digit and 0 as the hundred digit. Add 5031 MHz to the coded value to obtain the MLS frequency.
- [6] (Original note deleted)
- [7] Bit 16 when equal to “one” specifies that a displayable BCD output is to be provided for that station, and when bit 17 is a “one,” an ident output is to be generated for that station.

ATTACHMENT 6

GENERAL WORD FORMATS AND ENCODING EXAMPLES

TABLE 6-42

RADIO SYSTEMS MANAGEMENT WORD FORMATS

HF COM Word #1	PARITY (Odd)	SIGN/STATUS MATRIX	10 MHz (2)	1 MHz (3)	0.1 MHz (5)	0.01 MHz (7)	0.001 MHz (9)	USB/LSB MODE SSM/AM MODE WORD IDENT.	LABEL HF COM Frequency (037)					
Function									8 7 6 1 1 1	5 4 3 1 1 0	2 1 0 0			
Bit No. Example	32 0	31 30 0 0	29 28 1 0	27 26 25 24 0 0 1 1	23 22 21 20 0 1 0 1	19 18 17 16 0 1 1 1	15 14 13 12 1 0 0 1	11 10 9 0 0 0	[1] [2]	7	3	0		
Notes														

- [1] Bit no. 11 should be set to “zero” for LSB operation and “one” for USB operation.
- [2] Bit no. 10 should be set to “zero” for AM operation and “one” for SSB operation.

TABLE 6-42-1

HF COM Word #2	PARITY (odd)	SIGN/STATUS MATRIX	0.1 kHz (5)	NOT USED	RESERVED WORD IDENT.	LABEL HF COM Frequency (037)		
Bit No. Example	32 0	31 30 0 0	29 28 27 26 0 1 0 1	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	10 9 0 1 [1]	8 7 6 1 1 1 7	5 4 3 1 1 0 3	2 1 0 0 0

- [1] Bit No. 10 is reserved for CW mode select. The CW mode is selected when bit number 10 is a “one”. When the second word is transmitted, it should immediately follow the first HF word.

ALTERNATE FORM

TABLE 6-43

HF COM Word #1	PARITY (odd)		SIGN/STATUS MATRIX		10MHz (2)	1 MHz (3)	0.1 MHz (5)	0.01MHz (7)	0.001MHz (9)	WORD IDENT.	SDI	LABEL HF COM Frequency (205)			
Bit No.	32	31 30	29 28	27 26 25 24	23 22 21 20	19 18 17 16	15 14 13 12	11	10 9	8 7 6	5 4 3	2 1			
Example	0	0 0	1 0	0 0 1 1	0 1 0 1	0 1 1 1	1 0 0 1	0	0 1	1 0 1	0 0 0	0 1	5	0 2	

ATTACHMENT 6
GENERAL WORD FORMATS AND ENCODING EXAMPLES

TABLE 6-43-1

HF COM Word #2	PARITY (odd)	SIGN/STATUS MATRIX	0.1 kHz (5)	NOT USED	WORD IDENT.	SDI	LABEL HF COM Frequency (205)		
Function									
Bit No. Example	32 0	31 30 0 0	29 28 27 26 0 1 0 0	25 24 23 22 21 20 19 18 17 16 15 14 13 12 0 0 0 0 0 0 0 0 0 0 0 0 0 0	11 1	10 9 0 0	8 7 6 1 0 1	5 4 3 0 0 0	2 1 0 1
							5	0	2

RADIO SYSTEMS MANAGEMENT WORD FORMATS**TABLE 6-44**

ILS	PARITY (odd)	SIGN/STATUS MATRIX	10 MHz (0)	1 MHz (9)	0.1 MHz (3)	0.01 MHz (0)	SPARE	ILS CAT.	RES. (SDI)	LABEL Frequency (033)		
Function												
Bit No. Example	32 1	31 30 0 0	29 28 27 0 0 0	26 25 24 23 1 0 0 1	22 21 20 19 0 0 1 1	18 17 16 15 0 0 0 0	14 13 0 0	12 11 0 0	10 9 0 0	8 7 6 1 1 0	5 4 3 1 1 0	2 1 0 0
										3	3	0

BIT POSITION	12	11
CATEGORY NOT	0	0
ILS CAT I	0	1
ILS CAT II	1	0
ILS CAT III	1	1

TABLE 6-44-1

VOR/ILS	PARITY (odd)	SIGN/STATUS MATRIX	10 MHz (0)	1 MHz (9)	0.1 MHz (3)	0.01 MHz (0)	ILS MODE	SPARE	RES. (SDI)	LABEL VOR/ILS Frequency (034)		
Function												
Bit No. Example	32 1	31 30 0 0	29 28 27 0 0 0	26 25 24 23 1 0 0 1	22 21 20 19 0 0 1 1	18 17 16 15 0 0 0 0	14 0 [1]	13 12 11 0 0 0 0	10 9 0 0	8 7 6 0 0 1	5 4 3 1 1 0	2 1 0 0
										4	3	0

[1] Bit number 14 should be set to “zero” for VOR frequencies and “one” for ILS frequencies by the tuning information sources.

ATTACHMENT 6
GENERAL WORD FORMATS AND ENCODING EXAMPLES

TABLE 6-45

<u>VHF/COM</u>									
Function	PARITY (odd)	SIGN/STATUS MATRIX	10 MHz (2)	1 MHz (8)	0.1 MHz (5)	0.01 MHz (3)	0.001 MHz (0)	RES (SDI)	LABEL VHF COM Frequency (030)
Bit No. Example	32 1	31 30 0 0	29 28 27 0 1 0	26 25 24 23 1 0 0 0	22 21 20 19 0 1 0 1	18 17 16 15 0 0 1 1	14 13 12 11 0 0 0 0	10 9 0 0	8 7 6 0 0 0 5 4 3 1 1 0 2 1 0 0 0
									0 3 0

TABLE 6-46**RADIO SYSTEMS MANAGEMENT WORD FORMATS**

<u>ATC TRANSPONDER</u>	PARITY (odd)	SIGN/STATUS MATRIX	Pilot Selected Mode A Reply Code				Hijack Mode	Control Function	ALT. DATA SOURCE SEL.	Ident (SPI)	CONTROL FUNCTION	ALT. REP. ON/OFF	RES. (SDI)	LABEL Beacon Transponder Code (031)							
<u>Function</u>			0-7 (3)	0-7 (6)	0-7 (2)	0-7 (0)								8	7	6	5	4	3	2	1
			A4 	A2 	A1 	B4 								B2 	B1 	C4 	C2 	C1 	D4 	D2 	D1
Bit No. Example	32 1	31 30 0 0	29 28 27 0 1 1	26 25 24 1 1 0	23 22 21 0 1 0	20 19 18 0 0 0	17 0	16 15 0 0	14 0	13 0	12 0	11 0	10 9 0 0	8 7 6 1 0 0	5 4 3 1 1 0	2 1 0 0					
Notes								[2]	[1]		[2]	[1]		1	3	0					

[1]

Bit	Zero	One
11	Altitude Report On	Altitude Reporting Off
13	Ident. (SPI) OFF	Ident. ON
14	Use #1 Alt. Data Source	Use #2 Alt. Data Source

Control Panel Function			
Function	16	15	12
DABS ON/ ASAS OFF	0	0	1
Reset Aural Warning Signal	0	1	0

LABEL_Beacon Transponder Code (031) New Bit Assignment	
Bit 17	Meaning
0	Transponder IS NOT operating in the Hijack Mode
1	Transponder IS operating in the Hijack Mode

c-17

ATTACHMENT 6
GENERAL WORD FORMATS AND ENCODING EXAMPLES

TABLE 6-47TACAN Control – Label 146 112

RANGE 126
 RESOLUTION 1.0
 RATE 5Hz ±10%

Bit No.	Description
1	<div style="display: inline-block; vertical-align: middle;"> <div style="display: inline-block; vertical-align: middle; text-align: center;">0 1 1 0 1 1 0</div> <div style="display: inline-block; vertical-align: middle; font-size: 3em; margin: 0 5px;">}</div> <div style="display: inline-block; vertical-align: middle;">1 4 6</div> </div>
2	
3	
4	
5	
6	
7	
8	
9-10	SDI
11	Distance Memory (DIST MEM=1)
12	Bearing Memory (BRG MEM=1)
13	Pad Zero
14	VOR/TAC Select (TAC=1, VOR=0)
15	TACAN Select (TAC 1=1, TAC 2=0)
16	Pad Zero
17-20	BCD Units Chan Cont (LSB=17)
21-24	Hex Tens Chan Cont (LSB=24)
25	Pad Zero
26	X/Y Mode (X=1, Y=0)
27-28	Mode Cont (See Table A)
29	Pad Zero
30-31	SSM (See Table B)
32	Parity (Odd)

RADIO SYSTEMS MANAGEMENT WORD FORMATSTable A – Mode Control

Bits	Description
27 28	
0 0	
0 1	
1 0	
1 1	A/A T/R

Table B - SSM

Bits	Description
30 31	
0 0	
0 1	
1 0	
1 1	Not Used

ATTACHMENT 6
GENERAL WORD FORMATS AND ENCODING EXAMPLES

TABLE 6-48

TACAN Control Word – Label 147 115

Bit No.	Function	1	0	Note
1 0	1 4 Label Number (147)			
2 1				
3 1				
4 0				
5 0	7			
6 1				
7 1				
8 1				
9	SEL	TACAN 1	TACAN 2	[1]
10	SEL	ANTENNA 2	ANTENNA 1	
11	LOBE	ANTENNA LOBE		
12	AUTO/MAN TUNE	AUTOTUNE	MANUAL TUNE	
13	A/A AGC Disable	ENABLE	DISABLE	
14	Pad		X	
15 -16	TACAN/MLS Select			
17	(LSB)			
18	BCD Channel Code Units			
19				
20	(MSB)			[2]
21	(LSB)			
22	HEX Channel Code Tens			
23				
24	(MSB)			[3]
25	TST	TEST	NO TEST	
26	X/Y	X	Y	
27-28	Mode Control			
29	INT	NORMAL	INVERSE	
30-31	SSM			
32	Parity (odds)			

[1] TACAN/MLS Select

Bits	Description
15 16	
0 0	TACAN
1 0	MLS W
0 1	Not Used
1 1	MLS Z

[2] Mode Control

Bits	Description
27 28	
0 0	REC
1 0	T/R
0 1	A/A REC
1 1	A/A T/R

[3] SSM

Bits	Description
30 31	
0 0	Valid Data
0 1	No Computed Data
1 0	Functional Test
1 1	Not Used

ATTACHMENT 6
GENERAL WORD FORMATS AND ENCODING EXAMPLES

TABLE 6-49

Horizontal Alarm Limit/Horizontal Integrity Threshold (BNR) – Label 124 – IE2

32	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1
P	SSM [Note 1]			Horizontal Alarm Limit (HAL) /Horizontal Integrity Threshold [Notes 2, 3]														Pad [Note 4]		Phase of Flight [Note 5]				Octal Label							
																								4		2		1			
																								0 0 1		0 1 0		1 0			

[1] SSM (Status Matrix):

BITS		Meaning
31	30	
0	0	Failure Warning
0	1	No Computed Data (NCD)
1	0	Functional Test
1	1	Normal Operation

[2] Horizontal Alarm Limit (HAL) / Horizontal Integrity Threshold

The LDPU's optional internal GNSS receiver will generate a horizontal position integrity alarm when the EPU (Estimated Position Uncertainty) exceeds the Horizontal Alarm Limit for a period of time equal to the Time To Alarm for the current phase of flight. If the value of the HPL (Horizontal Protection Level, label 130) output from the internal GNSS receiver exceeds the horizontal integrity threshold specified in label 124, then horizontal integrity is deemed to be unavailable.

In the HAL field, the LSB (bit 16) has a weight of 1 meter, while the MSB (bit 28) has a weight of 4096 m.

[3] “All Ones” Value for HAL Field

If an “all ones” value is encoded into bits 28 to 18, the HAL value should be assumed to be the default value for the phase of flight specified in bits 13 to 11. If the HAL value is “all ones” (8191 meters) and the phase of flight code is “000” (“unspecified”) then the SSM field should be set to NCD.

[4] Pad Bits

The pad bits, bits 15 and 14, should be set to 0.

[5] Phase of Flight

The “phase of flight” field, bits 13 to 11, informs an optional GNSS receiver within the LDPU of the current phase of flight, so that the GNSS receiver may adjust its internal parameters to meet requirements for that phase of flight.

BITS			<u>Phase of Flight</u>	<u>Alarm Limit</u>		<u>Time To Alarm</u>
13	12	11		Horizontal	Vertical	
0	0	0	Not Specified	Unchanged	Unchanged	Unchanged
0	0	1	Oceanic	4 NM (7408 m)	N/A	8 s
0	1	0	En Route	2 NM (3704 m)	N/A	8 s
0	1	1	Terminal/Departure	1 NM (1852 m)	N/A	8 s
1	0	0	Non-Precision Approach	0.3 NM (555.6 m)	N/A	8 s
1	0	1	LNAV/VNAV Precision Appr.	As specified in bits 28 to 18	As specified in Vertical Alarm Limit word, label TBD	1 s
1	1	0	APV-II Precision Approach			1 s
1	1	1	GLS Precision Approach			1 s

ATTACHMENT 6
GENERAL WORD FORMATS AND ENCODING EXAMPLES

TABLE 6-50

Vertical Alarm Limit / Vertical Integrity Threshold (BNR) – Label 127 – IE2

32	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1
<u>P</u>	SSM Note 1			Vertical Alarm Limit (VAL) /Vertical Integrity Threshold [Note 2]								Pad [Note 3]												<u>Octal Label</u>							
																								7		2		1			
																								1	1	1	0	1	0	1	0

[1] SSM (Status Matrix):

BITS		Meaning
31	30	
0	0	Failure Warning
0	1	No Computed Data
1	0	Functional Test
1	1	Normal Operation

[2] Vertical Alarm Limit (VAL) / Vertical Integrity Threshold

The LDPU's optional internal GNSS receiver will generate a vertical position integrity alarm when the estimated error in vertical position exceeds the Vertical Alarm Limit for longer than the time-to-alarm for the current phase of flight. (The phase of flight is specified in label 124.) If the value of the VPL (Vertical Protection Level, label 130) output from the internal GNSS receiver exceeds the vertical alarm limit specified in bits 28-21, then vertical position integrity is defined to be "unavailable."

The LSB, bit 21, has a weight of 1 meter, while the MSB, bit 28, has a weight of 128 m.

[3] Pad Bits

The pad bits, bits 20 to 11, should be set to 0.

ATTACHMENT 6
GENERAL WORD FORMATS AND ENCODING EXAMPLES

TABLE 6-51

CDTI Display Unit - Label 262 - 144

32	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1
P	SSM		S	Display Range														Spare				SDI		<u>Octal Label</u>							
	0 0		+	20 NM																		0 0		2 6 2							
0	0	0	0	0	0	0	0	0	1	0	1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	10	011	01			

<u>Bit</u>	<u>Description</u>	<u>Notes</u>
1	Label 1 st digit	1
2	Label 1 st digit	___2 0
3	Label 2 nd digit	1
4	Label 2 nd digit	1
5	Label 2 nd digit	___6 0
6	Label 3 rd digit	0
7	Label 3 rd digit	1
8	Label 3 rd digit	___2 10
9	Reserved for SDI	0
10	Reserved for SDI	0
11	Reserved	0
12	Reserved	0
13	Reserved	0
14	Reserved	0
15	Display Range	LSB (1/32 NM) [1]
16	Display Range	(1/16 NM) [1]
17	Display Range	(1/8 NM) [1]
18	Display Range	(1/4 NM) [1]
19	Display Range	(1/2 NM) [1]
20	Display Range	(1 NM) [1]
21	Display Range	(2 NM) [1]
22	Display Range	(4 NM) [1]
23	Display Range	(8 NM) [1]
24	Display Range	(16 NM) [1]
25	Display Range	(32 NM) [1]
26	Display Range	(64 NM) [1]
27	Display Range	(128 NM) [1]
28	Display Range	MSB (256 NM) [1]
29	sign (always positive) 0	
30	SSM	[2]
31	SSM	[2]
32	Parity	

NOTES

[1] All zeroes = "Range is less than 1/32 NM," All ones = "Range is 512 NM."

[2] Sign/Status Matrix (SSM):

<u>Bits</u>		<u>Meaning</u>
<u>31</u>	<u>30</u>	
0	0	Failure Warning
0	1	No Computed Data
1	0	Functional Test
1	1	Normal Operation

ATTACHMENT 6
GENERAL WORD FORMATS AND ENCODING EXAMPLES

TABLE 6-52

Range Ring Radius – 261 144

32	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1
P	SSM			<u>Range Ring Radius</u>																<u>Spare</u>	RR T	SDI	<u>Octal Label</u>								
	Valid			<u>2 NM</u>																		0 0	1 6 2								
1	1	1	0	0	0	0	0	0	0	1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	100	011	01				

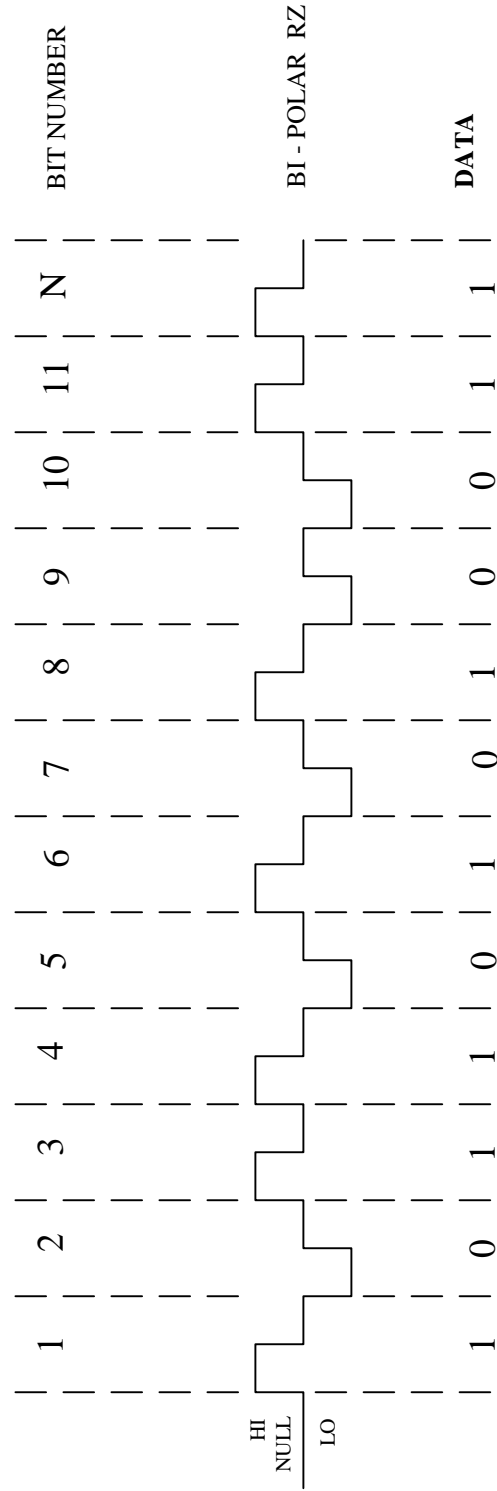
<u>Bit</u>	<u>Description</u>	<u>Notes</u>
1	Label 1 st digit	1
2	Label 1 st digit	___2 0
3	Label 2 nd digit	1
4	Label 2 nd digit	1
5	Label 2 nd digit	___6 0
6	Label 3 rd digit	0
7	Label 3 rd digit	0
8	Label 3 rd digit	___1 1
9	Reserved for SDI	0
10	Reserved for SDI	0
11	RRT, Range Ring Type	(0 = floating, 1 = locked)
12	Spare	0
13	Spare	0
14	Range ring radius	LSB (1/64 NM)
15	Range ring radius	(1/32 NM)
16	Range ring radius	(1/16 NM)
17	Range ring radius	(1/8 NM)
18	Range ring radius	(1/4 NM)
19	Range ring radius	(1/2 NM)
20	Range ring radius	(1 NM)
21	Range ring radius	(2 NM)
22	Range ring radius	(4 NM)
23	Range ring radius	(8 NM)
24	Range ring radius	(16 NM)
25	Range ring radius	(32 NM)
26	Range ring radius	(64 NM)
27	Range ring radius	(128 NM)
28	Range ring radius	MSB (256 NM)
29	sign (always positive)	0
30	SSM	[1]
31	SSM	[1]
32	Parity	

NOTES

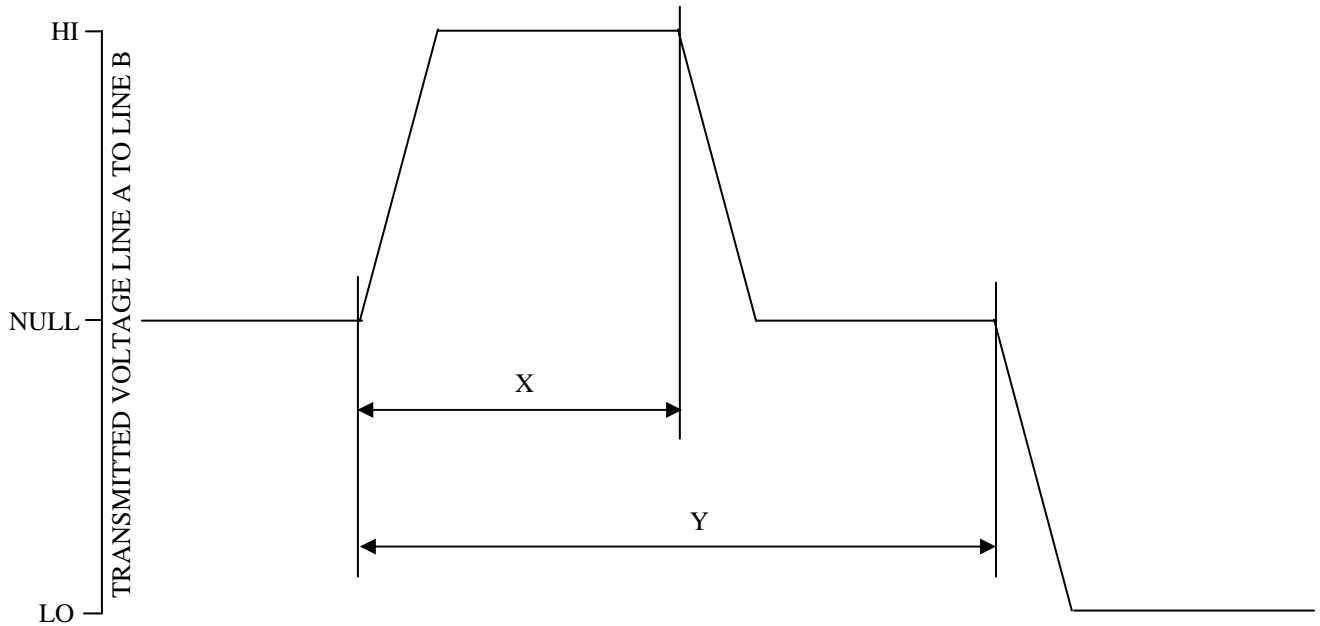
[1] Sign/Status Matrix (SSM)

Bits		Meaning
31	30	
0	0	Failure Warning
0	1	No Computed Data
1	0	Functional Test
1	1	Normal Operation

ATTACHMENT 7
DATA BIT ENCODING LOGIC



ATTACHMENT 8
OUTPUT SIGNAL TIMING TOLERANCES



PARAMETER	HIGH SPEED OPERATION	LOW SPEED OPERATION
Bit Rate	100k bps \pm 1%	12 – 14.5kbps
Time Y	10 μ sec \pm 2.5%	Z* μ sec \pm 2.5%
Time X	5 μ sec \pm 5%	Y/2 \pm 5%
Pulse Rise Time**	1.5 \pm 0.5 μ sec	10 \pm 5 μ sec
Pulse Fall Time**	1.5 \pm 0.5 μ sec	10 \pm 5 μ sec

* Z = 1 where R = bit rate selected from 12 – 14.5kbps range

** Pulse rise and fall times are measured between the 10% and 90% voltage amplitude points on the leading and trailing edges of the pulse and include permitted time skew between the transmitter output voltages A-to-ground and B-to-ground. These rise and fall times are for open circuit output measurements – Appendix 1 provides waveforms for typical test performance.

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ATTACHMENT 9A GENERAL AVIATION LABELS AND DATA STANDARDS

The following labels and data standards provided by GAMA (General Aviation Manufacturers Association) are typically used by general aviation. Labels with a "G" or "P" suffix refer to GAMA standard, or GA industry PRIVATE bit structures, respectively. All others are ARINC standard words.

LABEL (OCTAL)	EQPT. ID (HEX)	PARAMETER NAME	DATA TYPE	UNITS	RANGE	SIG BITS / DIGITS	POSITIVE SENSE	APPROX. RESOL.	MIN XMIT INT (msec)	MAX XMIT INT (msec)	MAX UPDATE INT	NOTES
0 0 1	0 2 0 9	Distance to go	BCD				Always Pos					
		Distance to go	BCD	N.M.	±3999.9	5	Always Pos	0.1	100	200		
0 0 2	0 2 0 9	Time to go	BCD				Always Pos					
		Time to go	BCD	Min.	0-399.9	4	Always Pos	0.1	100	200		
0 1 2	0 2 0 9	Ground Speed	BCD				Always Pos					
		Ground Speed	BCD	Knots	0-2000	4	Always Pos	1.0	250	500		
0 1 7	1 0	Selected Runway Heading	BCD	Degrees	0-359.9°	4	Always Pos	0.1°	167	333		
0 2 4 G	1 1	Selected Course 1	BCD	Degrees	0-359°	3	Always Pos	1.0°	167	333		Bit 11 Non Std
0 2 7	1 1	Selected Course 2	BCD	Degrees	0-359°	3	Always Pos	1.0°	167	333		
0 3 0 G	0 2 1 6	VHF COM Frequency	BCD	MHz	118-135.975	5			0.025	100	200	SSM Squelch
		VHF COM Frequency	BCD	MHz	118-135.975	5			0.025	100	200	SSM XMIT
0 3 1 G	0 2 1 8	Beacon Transponder Code	BCD	Discrete						100	200	SSM Reply
		Beacon Transponder Code	BCD	Discrete						100	200	
0 3 2	0 2 1 2	ADF Frequency	BCD	KHz	190-1750	5		0.5	100	200		
		ADF Frequency	BCD	KHz	190-1750	5		0.5	100	200		
0 3 3	0 2 1 0	ILS Frequency	BCD	MHz	108-111.95	4		0.05	167	333		
		ILS Frequency	BCD	MHz	108-111.95	4		0.05	167	333		
0 3 4 G	0 2 1 0 1 1	VOR/ILS Frequency	BCD	MHz	108-117.95	4		0.05	167	333		See Att. 9B
		VOR/ILS Frequency	BCD	MHz	108-117.95	4		0.05	167	333		See Att. 9B
		VOR/ILS Frequency	BCD	MHz	108-117.95	4		0.05	167	333		See Att. 9B
0 3 5 G	0 2 0 9	DME Frequency	BCD	MHz	108-135.95	4		0.05	100	200		See Att. 9B
		DME Frequency	BCD	MHz	108-134.95	4		0.05	100	200		See Att. 9B
0 4 1	0 2	Set Position Latitude	BCD	Deg:Min	180N-180S	6	North	0.1	250	500		
0 4 2	0 2	Set Position Longitude	BCD	Deg:Min	180E-180W	6	East	0.1	250	500		
0 4 3	0 2	Set Magnetic Heading	BCD	Deg	0-359°	3		1.0°	250	500		
0 6 0 P	0 2	Omega Data Select	BNR	Discrete					100	200		See Att. 9B
0 6 1 P	0 2	Covariance Data	BNR						100	200		See Att. 9B
0 7 4 G	0 2	Data Record Header	DSC	Discrete					See Note 1			See Att. 9B
0 7 5 G	0 2	Active WPT From/To Data	DSC	Discrete					See Note 1			See Att. 9B
1 0 0 G	0 2	Selected Course 1	BNR	Deg/180	±180°	12		0.05°	167	333		Bit 11 Non Std
1 0 0	1 1	Selected Course 1	BNR	Deg/180	±180°	12		0.05°	167	333		
1 0 1 G	0 2 2 5	Selected Heading	BNR	Deg/180	±180°	12		0.05°	31.3	62.5		Bit 11 Non Std
		Selected Heading	BNR	Deg/180	±180°	12		0.05°	31.3	62.5		
1 0 2 G	0 2	Selected Altitude	BNR	Feet	65536	16	Above S.L.	1	100	200		See Att. 9B
1 0 5	1 0	Selected Runway Heading	BNR	Deg/180	±180°	11		0.1°	167	333		
1 1 0	1 1	Selected Course 2	BNR	Deg/180	±180°	12		0.05°	167	333		
1 1 3 G	0 2	Message Checksum	BNR						See Note 2			See Att. 9B
1 1 4	0 2	Desired Track (True)	BNR	Deg/180	±180°	12		0.05°	31.3	62.5		
1 1 5	0 2	Waypoint Bearing (True)	BNR	Deg/180	±180°	12	A/C To WPT	0.05°	31.3	62.5		
1 1 6 G	0 2	Cross Track Distance	BNR	Naut Mi	128	18	Fly Left	0.0005	31.3	62.5		
1 1 7 G	0 2	Vertical Deviation	BNR	Feet	16384	14	Fly Down	1.0	31.3	62.5		See Att. 9B
1 2 1	0 2	HORIZ.CMD.(To Autopilot)	BNR	Deg/180	±180°	14	Fly Right	0.01°	50	100		
1 2 2 G	0 2	VERT.CMD. (To Autopilot)	BNR	Deg/180	±180°	12	Fly Up	0.05°	50	100		
1 2 3	0 2	Throttle Command	BNR	Deg/sec	2.56	18	Inc. Power	0.001°	50	100		
1 2 5	0 2	Greenwich Mean Time	BCD	Hr/Min	0-23.59.9	5		0.1	100	200		
1 4 7 G	0 2	Magnetic Variation	BNR	Deg/180	±180°	12	East	0.05°	500	1000		Bit 11 Non Std
1 5 0	0 2	Greenwich Mean Time	BNR	Hr:Min:Sec	23:59:59	5:6:6		1.0 sec	50	100		See Att. 6
1 5 7 P	0 6	Normalized AOA	BNR	1=Stall	±2	12	Upward	0.0005	125	125	125	
1 6 2 G	1 2	ADF Bearing	BNR	Deg/180	±180°	12		0.05°	31.3	62.5		Bit 11 Non Std
1 6 3 G	0 2	Wind on Nose	BNR	Knots	256	9	Head Wind	0.5	50	100		Bit 29 Non Std
1 7 3	1 0	Localizer Deviation	BNR	DDM	0.4	12	Fly Right	0.0001	33.3	66.6		
1 7 4	1 0	Glideslope Deviation	BNR	DDM	0.8	12	Fly Down	0.0002	33.3	66.6		
2 0 2	0 2 0 9	DME Distance	BNR	Naut Mi	512	16	Always Pos	0.005	83.3	167		
		DME Distance	BNR	Naut Mi	512	16	Always Pos	0.005	3.3	167		
2 0 4	0 2	Baro Corrected Alt.#1	BNR	Feet	131,072	17	Above S.L.	1.0	31.3	62.5		
2 1 0	0 2	True Airspeed	BNR	Knots	2047.93	15	Always Pos	0.0625	62.5	125		
2 1 3	0 2	Static Air Temperature	BNR	Deg C	512	11	Above Zero	0.25	250	500		
2 2 2 P	0 2	VOR Radial	BNR	Deg/180	±180°	12	To Station	0.044°	50	100		See Att. 6
2 2 2	0 2 1 0 1 1	VOR Omnibearing	BNR	Deg/180	±180°	12	From VOR	0.044°	50	100		More than one MKR beacon bit is MKR self test.
		VOR Omnibearing	BNR	Deg/180	±180°	12	From VOR	0.044°	31.3	62.5		
		VOR Omnibearing	BNR	Deg/180	±180°	12	From VOR	0.044°	31.3	62.5		
2 4 1 P		Normalized AOA	BNR	1=Stall	±2	12	Upward	0.0005	125	125	125	
2 5 1 G	0 2	Distance To Go	BNR	Naut Mi	4096	15	Always Pos	0.125	100	200		
2 5 2	0 2	Time-To-Go	BNR	Minutes	512	9	Always Pos	1.0	100	200		
2 6 0 G	0 2	Date	BCD	Discrete		6		1 Day	500	1000		See Att. 9B
2 6 1 P	0 2	GPS Discrete Word 1	DSC	Discrete					1000	1000	1000	
2 7 5 G	0 2	LRN Status Word	DSC	Discrete					200	400		See Att. 9B
2 7 7 P	0 2	Cabin DSPY Cont DSC	DSC	Discrete					200	200		
3 0 0 G	0 2	STN MAG DEC, Type & Class	BNR	Discrete					See Note 2			See Att. 9B

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ATTACHMENT 9A
GENERAL AVIATION LABELS AND DATA STANDARDS

LABEL (OCTAL)	EQPT. ID (HEX)	PARAMETER NAME	DATA TYPE	UNITS	RANGE	SIG BITS / DIGITS	POSITIVE SENSE	APPROX. RESOL.	MIN XMIT INT (msec)	MAX XMIT INT (msec)	MAX UPDATE INT	NOTES
3 0 1 G	0 2	Message Characters 7-9	BNR	Discrete					See Note 2			
3 0 2 G	0 2	Message Characters 10-12	BNR	Discrete					See Note 2			
3 0 3 G	0 2	Message Length / Type / Number	BNR	Discrete					See Note 2			
3 0 4 G	0 2	Message Characters 1-3	BNR	Discrete					See Note 2			
3 0 5 G	0 2	Message Characters 4-6	BNR	Discrete					See Note 2			
3 0 6 G	0 2	NAV/WPT/AP Latitude	BNR	Deg/280	180N-180S	20	North	.000172°	See Note 2			
3 0 7 G	0 2	NAV/WPT/AP Longitude	BNR	Deg/180	180E-180W	20	East	.000172°	See Note 2			
3 1 0	0 2	Present Position Latitude	BNR	Deg/180	180N-180S	20	North	.000172°	100	200		
3 1 1	0 2	Present Position Longitude	BNR	Deg/180	180E-180W	20	East	.000172°	100	200		
3 1 2	0 2	Ground Speed	BNR	Knots	4096	15	Always Pos	0.125	25	50		
3 1 3	0 2	Track Angle (True)	BNR	Deg/180	±180°	12		0.05	25	50		
3 1 4	0 2	True Heading	BNR	Deg/180	±180°	15		0.0055°	25	50		
3 1 5	0 2	Wind Speed	BNR	Knots	256	8	Always Pos	1.0	50	100		
3 1 6	0 2	Wind Angle (True)	BNR	Deg/180	±180°	8		0.7	50	100		
3 2 0	0 2	Magnetic Heading	BNR	Deg/180	±180°	15		0.0055°	25	50		
3 2 1	0 2	Drift Angle	BNR	Deg/180	±180°	12		0.05°	25	50		
3 2 6 G	0 2	Lateral Scale Factor	BNR	Naut Mi	±128	15		0.0039 NM	80	1200		
3 2 7 G	0 2	Vertical Scale Factor	BNR	Feet	±2048	15		0.0625 Ft	80	1200		
3 5 1 G	0 2	Distance To Destination	BNR	Naut Mi	32,768	18	Always Pos	0.125	500	1000		
3 5 2 G	0 2	Est Time to Destination	BNR	Minutes	4096	12	Always Pos	1.0	500	1000		Via Flight Plan
3 5 3 P	0 2	Dest Local Time Offset	BCD	Hour/Min	23:59	5	Always Pos	.01 Min	1000	1000	1000	Via Flight Plan
3 7 1 G	0 2 0 9 1 0 1 1 1 2 1 6 1 8	Specific Equipment Ident Specific Equipment Ident Specific Equipment Ident Specific Equipment Ident Specific Equipment Ident Specific Equipment Ident Specific Equipment Ident	DSC DSC DSC DSC DSC DSC DSC						500 500 500 500 500 500 500	1000 1000 1000 1000 1000 1000 1000		See Att. 9B

NOTE 1: These labels are transmitted once at the beginning of each flight plan/graphics map data transfer. Refer to the GAMA FMS Output Bus Standard for further information.

NOTE 2: These labels are used to make up the individual records that comprise a flight plan/graphics map data transfer. Not all labels are transmitted with each record. Ten records are transmitted in one second. Refer to the "FMS Waypoint/Navaid/Airport Data Transfer Protocol", addendum 3.

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ATTACHMENT 9B
GENERAL AVIATION WORD EXAMPLES

32	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1
P	SSM		See Chapter 3																	See Below		SDI	VOR/ILS Frequency Label 034G								

Bit 11 Bit 12 Bit 13	Marker Sensitivity Last Tune Source VOR Digital Filtering	“1” denotes high, “0” denotes low “1” denotes control head. “0” denotes other “1” denotes no filter. “0” denotes filter (Normally “1” but “0” for Honeywell (Olathe) manufactured equipment)
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32	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1
P	SSM		See Chapter 3																	See Below		SDI	DME Frequency Label 035G								

Bit	13	12	11	DME Mode
	0	0	0	Standby
	0	0	1	Directed Freq #1
	0	1	0	Directed Freq #2
	0	1	1	Directed Freq #3
	1	0	0	Hold Freq #1
	1	0	1	Hold Freq #2
	1	1	0	Not used
	1	1	1	Spare

32	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1
P	SSM		0			Relane		MSB	Binary Address																Omega Data Select Label 060P						

*Specific user word			
Bit 28	Full Restart Bit		“1” denotes restart
Bit 27	Rho Rho Updating		“1” inhibits update

Bit	26	25	Function
	0	0	No Action
	0	1	Relane
	1	0	Do Not Release
	1	1	Invalid Use

32	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1
P	SSM		Term Indent		-	Exponent (IEEE Flt. Pt.) MSB								Mantissa (IEEE Flt. Pt.)								Covariance Data* Label 061P									

*Specific user word			
Bit 27	Sign		“1” denotes negative

Bit	29	28	Functions
	0	0	Term 1
	0	1	Term 2
	1	0	Term 3
	1	1	Not Used

32	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1
P	SSM		Pad (Zeros)										Pad (Zeros)				MSB	Number of Records					Data Record Header Lable 074G								

Bit 21	Prior Record Change	“1” denotes changed record
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32	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1
P	SSM		0	From Waypoint LS Byte				To Waypoint LS Byte				From Waypoint MS Byte				To Waypoint MS Byte				See Below			Active Waypoint From/To Data Label 075G								

Bit 9 Bit 10 Bit 11 Bit 12	Auto/Leg/Man/Obs Mag/True Reference Radar Waypoint Displayed Lat/Long/ILS Mode	“1” denotes Auto/Leg, “0” denotes Man/Obs “1” denotes True, “0” denotes Magnetic “1” inhibits display “1” denotes ILS, “0” denotes Lat/Long	These are User Specific bits
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32	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1
P	SSM		Same as Attachment 2																				SDI		Selected Altitude Label 102G						

Bit 11 Bit 12	Altitude Select Knob Altitude Alert	“0” denotes “in motion” “1” denotes “on”	User-specific bits
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ATTACHMENT 9B
GENERAL AVIATION WORD EXAMPLES

32	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	
P	SSM		Check Sum																						Message Check Sum				Label 113G			

The message checksum is the two's complement 21 bit sum of all the other words transmitted in the group discarding the intermediate carry and replacing bit 32 with odd parity.

32	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1
P	SSM		+	Data														See Below		SDI		Vertical Deviation Label 117G									
			-																												

Bit 14	VNAV Arm Enable/Alert	User Specific bits
Bit 13	VNAV Bendover	
Bit 12	VNAV Bendover Direction	
Bit 11	Altitude with respect to 1000 ft.	
		“1” denotes enable “1” denotes “capture”, “0” denotes “track” “1” denotes “fly up”, “0” denotes flydown” “1” denotes “greater”, “0” denotes less

32	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1
P	SSM	Day						Month						Year						SDI	Date Label 260G										
		10s		1s				10s		1s				10s			1s														

32	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1
P	SSM		Spare						Waypoint Number (Binary)						See Below		Words in Message		Message Length/Type/No. Label 303G												

Bit 16	Date Record	“1” denotes “off route”, “0” denotes “on route”
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Bit 24	FMS Plan Mode	“1” denotes “SELECT”, “0” denotes “not SELECT”
Bit 25	WPT at Plan Center	“1” denotes “CENTER”, “0” denotes “not CENTER”
Bit 26	Flight Plan GAP Follows	“1” denotes “GAP”, “0” denotes “no GAP”

Bit	15	14	13	WYPT/STATION TYPE
	0	0	0	Waypoint
	0	0	1	Nav Aid
	0	1	0	Airport
	0	1	1	NDB
	1	0	0	Altitude Profile Point
	1	0	1	No Symbol
	1	1	0	VOR
	1	1	1	Intersection

ATTACHMENT 9B
GENERAL AVIATION WORD EXAMPLES

Bit No.	Function	Bit Status	
		1	0
1	Label 261G 02 LRN Status	x	
2			x
3			
4		x	
5		x	
6			x
7			x
8			x
9	SDI		
10			
11	Spare		Pad Zero
12			
13	Reserved		
14			
15			
16			
17			
18			
19			
20	Vert Dev (Final Appr)	Angular	Linear
21	Lat Dev Scaling in Transition	Yes	No
22	Lat Dev. (Final Appr)	Angular	Linear
23	Appr Integrity (Final Appr)	Valid	Invalid
24	GPS Integrity	Fail	Valid
25	GPS Annunciation 27(0) & 26(0) & 25(0) – Enroute 27(0) & 26(0) & 25(1) – Terminal 27(0) & 26(1) & 25(0) – Approach (27(1) & 26(0) & 25(0) – Oceanic		
26			
27			
28			
29	Spare		
30	SSM 31(0) & 30(0) – Normal Operations 31(0) & 30(1) – No Computed Data 31(1) & 30(0) – Functional Test 31(1) & 30(1) – Not used		
31			
32			
32	Parity (odd)		

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ATTACHMENT 9B
GENERAL AVIATION WORD EXAMPLES

Bit No.	Function	Bit Status	
		1	0
1	Label 275G 02 LRN Status	x	
2			x
3		x	
4		x	
5		x	
6		x	
7			x
8		x	
9	SDI		
10			
11	Waypoint Alert	On	Off
12	Dead Reckon	DR	Not DR
13	Direct To	Select	Not Select
14	Mode 15(0) & 14(0) – Multiple Sensor Based 15(0) & 14(1) – VOR/DME Offset (RNAV) Approach 15(1) & 14(0) – VOR/TACAN (non-Offset) Approach/Enroute 15(1) & 14(1) – ILS Approach		
15			
16	Vert & Lat Dev Scaling	Approach	Enroute
17	FMS Controlled Hdg Sub-mode	FMS/FGS	FGS Only
18	Remote FGS Army for Nav Capt	Arm	No Change
19	FMS Plan Mode	Select	Not Select
20	Display Final Appr Course	Display	No Change
21	Angular Scaling	Active	Not Active
22	Integrity Warn	Warn	Not Warn
23	To	To	Not To
24	From	From	Not From
25	Parallel XTK Offset	Selected	Not Selected
26	Airport Display Selected	Select	Not Selected
27	Message Alert	On	Off
28	True/Mag	True	Magnetic
29	HSI Valid (NAV Warn)	Valid	Warn
30	SSM		
31			
32	Parity (odd)		

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ATTACHMENT 9B
GENERAL AVIATION WORD EXAMPLES

Bit No.	Function	Bit Status	
		1	0
1	Label 277G 02 LRN Status	x	
2			x
3		x	
4		x	
5		x	
6		x	
7		x	
8		x	
9	SDI (if required)		
10			
11	Play Briefing #1		
12	Play Briefing #2		
13	Play Briefing #3		
14	Play Briefing #4		
15	Play Briefing #5		
16	Play Briefing #6		
17	Cancel Briefing #1		
18	Cancel Briefing #2		
19	Cancel Briefing #3		
20	Cancel Briefing #4		
21	Cancel Briefing #5		
22	Cancel Briefing #6		
23	Annunciate Cabin Message (Note)		
24	Spares		Pad Zero
25			
26			
27			
28			
29	Alternate Format	ALTERNATE	STD
30	SSM 31(0) & 30(0) – Normal Operation 31(0) & 30(1) – No Computed Data 31(1) & 30(0) – Functional Test 31(1) & 30(1) – Failure Warning		
31			
32	Parity (Odd)		

NOTE: The **ALTERNATE FORMAT** bit (#29) causes the briefing play (BITS 11 – 16) and briefing cancel (BITS 17 – 22) controls to be interpreted as the briefing number from 1 to 63 with the briefing #1 bit as the least significant. If BIT 29 is set to 1, this decoding will be used. If the briefing number is non zero, the indicated briefing will be played or canceled.

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ATTACHMENT 9B
GENERAL AVIATION WORD EXAMPLES

Bit No.	Function	Bit Status	
		1	0
1	Label 300 02 Station Declination	x	x x x x x x
2		x	
3			
4			
5			
6			
7			
8			
9	Spares		Pad Zero
10			
11			
12			
13			
14			
15	DME	Not Collated Being Received	Same Location Not Received
16	Tuned and Received		
17	Station Declination Binary number with sign bit 24 East is positive. West is 2's complement of the positive value. Range is 127 deg. E/W. Resolution is 1 degree at bit 17.		
18			
19			
20			
21			
22			
23			
24			
25	VOR at location	Yes	No
26	DME at location	Yes	No
27	TACAN at location	Yes	No
28	Class Bit 29/28/0 low 0/1 high 1/0 terminal		
29			
30	SSM		
31			
32	Parity		

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ATTACHMENT 9B
GENERAL AVIATION WORD EXAMPLES

32	31 30	29 28 27 26 25	24 23 22 21 20 19	18 17 16 15	14 13 12 11	10 9	8 7 6 5 4 3 2 1
P		Company Private Use	Company I. D. (Binary)	EQ Code MSD (Hex)	EQ Code MSD (Hex)	SDI	GA Equipment Ident LABEL 371

LABEL 371 Company I. D. Field Binary Bit Assignments						COMPANY
24	23	22	21	20	19	
0	0	0	0	0	1	B&D INSTRUMENTS
0	0	0	0	1	0	BEECH AIRCRAFT
0	0	0	0	1	1	BENDIX AVIONICS
0	0	0	1	0	0	CANADIAN MARCONI
0	0	0	1	0	1	CESSNA AIRCRAFT
0	0	0	1	1	0	COLLINS AVIONICS
0	0	0	1	1	1	DELCO ELECTRONICS
0	0	1	0	0	0	FOSTER RNAV
0	0	1	0	0	1	GABLE CONTROLS
0	0	1	0	1	0	GLOBAL SYSTEMS
0	0	1	0	1	1	GULFSTREAM AEROSPACE
0	0	1	1	0	0	HONEYWELL
0	0	1	1	0	1	KING RADIO
0	0	1	1	1	0	LEARJET
0	0	1	1	1	1	LITTON AERO PRODUCTS
0	1	0	0	0	0	OFFSHORE NAVIGATION
0	1	0	0	0	1	RACAL AVIONICS
0	1	0	0	1	0	SPERRY
0	1	0	0	1	1	UNIVERSAL NAVIGATION SYS
0	1	0	1	0	0	3M AVIATION SAFETY SYSTEMS
0	1	0	1	0	1	ALLIEDSIGNAL GENERAL AVIATION AVIONICS
0	1	0	1	1	0	ALLIEDSIGNAL GLOBAL WULFSBERG
0	1	0	1	1	1	BF GOODRICH AVIONICS
0	1	1	0	0	0	GARMIN
0	1	1	0	0	1	ARNAV
0	1	1	0	1	0	COMPUTER INSTRUMENT CORPORATION
0	1	1	0	1	1	SPARE
1	1	1	1	1	1	SPARE

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ATTACHMENT 9C
GENERAL AVIATION EQUIPMENT IDENTIFIERS

Equipment HEX ID	EQUIPMENT
01	Flight Control Computer
02	Flight Management Computer
04	Inertial Reference System
05	Attitude and Heading Ref. System
06	Air Data System
09	Airborne DME
0B	Global Positioning System
10	Airborne ILS Receiver
11	Airborne VOR Receiver
12	Airborne ADF System
16	Airborne VHF Comm Receiver
18	ATC Transponder
25	Electronic Flight Instruments
27	Microwave Landing System
36	Radio Management System
5A	Loran
5B	Omega
A9	Airborne DME Controller
B0	Airborne ILS Controller
B2	Airborne ADF Controller
B6	VHF Comm Controller
B8	ATC Transponder Controller
C7	Microwave Landing System Controller
FA	Loran Controller
FB	Omega Controller

ATTACHMENT 10
MANUFACTURER SPECIFIC STATUS WORD

32	31	30	29	28	27	26	25	24	23	22	21	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1
P	Company Private Use [A]														Company I.D. (Binary)						SDI [B]	Label (171)								

BIT	16	15	14	13	12	11	Company
	0	0	0	0	0	1	B&D INSTRUMENTS
	0	0	0	0	1	0	BEECH AIRCRAFT
	0	0	0	0	1	1	BENDIX AVIONICS
	0	0	0	1	0	0	CANADIAN MARCONI
	0	0	0	1	0	1	CESSNA AIRCRAFT
	0	0	0	1	1	0	COLLINS AVIONICS
	0	0	0	1	1	1	DELCO ELECTRONICS
	0	0	1	0	0	0	FOSTER RNAV
	0	0	1	0	0	1	GABLES CONTROLS
	0	0	1	0	1	0	GLOBAL SYSTEMS
	0	0	1	0	1	1	GULFSTREAM AEROSPACE
	0	0	1	1	0	0	HONEYWELL
	0	0	1	1	0	1	KING RADIO
	0	0	1	1	1	0	LEAR JET
	0	0	1	1	1	1	LITTON AERO PRODUCTS
	0	1	0	0	0	0	OFFSHORE NAVIGATION
	0	1	0	0	0	1	RACAL AVIONICS
	0	1	0	0	1	0	SPERRY
	0	1	0	0	1	1	UNIVERSAL NAVIGATION SYSTEMS
	0	1	0	1	0	0	3M AVIATION SAFETY SYSTEMS
	0	1	0	1	0	1	ALLIED SIGNAL GENERAL AVIATION AVIONICS
	0	1	0	1	1	0	ALLIED SIGNAL GLOBAL WULFSBAG
	0	1	0	1	1	1	BF GOODRICH AVIONICS
	0	1	1	0	0	0	GARMIN
	0	1	1	0	0	1	ARNAV
	0	1	1	0	1	0	COMPUTER INSTRUMENT CORPORATION
	0	1	1	0	1	1	RYAN
	0	1	1	1	0	0	SPARE
	1	1	1	1	1	1	SPARE

c-17

[A] This word is used for manufacturer-specific information exchange (e.g., sub-LRU-Level BITE status). The Company I.D. fields should be used to differentiate each manufacturer's unique use of the Company Private Use field.

[B] Per Section 2.1.4

ATTACHMENT 11
SYSTEM ADDRESS LABELS

	SYSTEMS	SYSTEM ADDRESS LABEL (OCTAL)
	777 CABIN INTERPHONE SYSTEM	152
c-17	CVR #2	156
c-16	CVR	157
	747 DFHR AND A330/340 SSFDR	163
c-15	DFDAU (MANDATORY LOAD FUNCTION)	170
	SDU #2	173
	RFU	174
c-17	HGA/IGA HPA	175
c-17	LGA HPA	177
	GPS/GNSS SENSOR	201
	FCMC Com A340-500/600	210
c-16	FCMC Mon A340-500/600	211
	FCMC Int A340-500/600	212
	MCDU 1	220
	MCDU 2	221
	MCDU 3	222
	PRINTER 1	223
	PRINTER 2	224
c-16	HUD	225
	HIGH SPEED DL (ARINC 615)	226
	MCDU 4	230
	EIVMU 1	234
c-14	EIVMU 2	235
	EIVMU 3	236
	EIVMU 4	237
	APM-MMR	241
	MMR	242
c-16	ILS	244
	MLS	245
	AHRS	246
c-17	HIGH-SPEED DATA (HSDU #1)	247
	HIGH-SPEED DATA (HSDU #2)	250
	VDR #1	251
	VDR #2	252
	VDR #3	253
	NETWORK SERVER SYSTEM	254
c-17	ELECTRONIC FLIGHT BAG LEFT	255
	ELECTRONIC FLIGHT BAG RIGHT	256
c-15	CABIN VIDEO SYSTEM (AIRSHOW)	266
	LOW SPEED DL (ARINC 603)	300
	FMC 1	300
	FMC 2	301
	DFDAU (AIDS)	302
c-14	CFDIU	303
	ACARS MU/CMU (724B, 748)	304
	WBS	305
	TCAS	306
	SDU #1	307

ATTACHMENT 11
SYSTEM ADDRESS LABELS

SYSTEMS	SYSTEM ADDRESS LABEL (OCTAL)	
GPWS	310	
GMLU 1	311	
GMLU 2	312	
GMLU 3	313	
GNU 1	314	
GNU 2	315	
GNU 3	316	
AUTOTHROTTLE COMPUTER	321	c-16
FCC 1	322	
FCC 2	323	
FCC 3	324	
APU	325	
APU CONTROLLER	326	
MODE CONTROL PANEL (MCP)	327	
FMC 3	330	
ATC TRANSPONDER	331	
DADC	332	
CABIN TELECOMMUNICATIONS UNIT (CTU)	334	
HF DATA RADIO/DATA UNIT #1	340	c-15
HF DATA RADIO/DATA UNIT #2	344	
REMOTE DATA CONCENTRATOR	345	c-17
ACCESS	360	c-14
EFIS	361	
PASSENGER SERVICES SYSTEM (PSS) 767300,400	362	
CABIN SERVICE SYSTEM (CSS) 747-400	363	c-16
AUDIO ENTERTAINMENT SYSTEM (AES)BOEING	364	
ENGINE INDICATION UNIT	365	c-14
MULTICAST	366	c-16
BRIDGE	367	
CABIN TERMINAL 3	372	
CABIN TERMINAL 4	373	
CABIN TERMINAL 1	374	c-14
CABIN TERMINAL 2	375	
OMEGA NAV. SYSTEMS	376	

APPENDIX A

LABORATORY VERIFICATION OF ARINC 429 DITS ELECTRICAL CHARACTERISTICS

A1-1.0 Introduction

Selection of the electrical characteristics of the Mark 33 DITS followed verification of the suitability of proposed values in laboratory tests performed by the Boeing Commercial Airplane Co. Boeing presented two reports to AEEC's Systems Architecture and Interfaces Subcommittee on these activities, one at the meeting held in Arlington, Virginia, in March 1977 and the other at the meeting held in Los Angeles, California, in May 1977. The material in this Appendix is excerpted from these reports.

A1-2.0 Electromagnetic Emission and Susceptibility Tests

Electromagnetic emission and susceptibility tests were conducted to determine if the proposed 100 kbps waveform was suitable for use in a commercial airplane EMI environment. The EMI conditions used for the tests were derived from RTCA Document DO-160, "Environmental Conditions and Test Procedures for Airborne Electronic/Electrical Equipment and Instruments" dated February 28th, 1975.

A1-2.1 Cable and Test Configuration

The cable used for the tests was standard aircraft type twisted shielded wire of 22 AWG. The wire configuration consisted of approximately 60 ft. of cable which was subjected to the EMI environment within a screened room. This cable was connected in series with 300 ft. of cable not subjected to the EMI environment. The test was configured to simulate the maximum length wire run with DO-160 conditions applied.

The 60 Ft. length of cable was connected to the transmitter for the emission tests and to the receiver for the susceptibility tests.

A1-2.2 Transmitter Characteristics

The block schematic of the bipolar line driving transmitter built for the tests is shown in Figure a-(i). The waveform was shaped at the pulse generator such that it exhibited the following characteristics:

Differential Output Voltage:	
HI	+10V
NULL	0V
LO	-10V
Risettime = Faltime = 1.0 μ sec	
Bit Rate= 100 kilobits/second	
HI time= NULL time= LO time	

A1-2.3 Receiver Input Circuit Description

To perform the susceptibility tests, receivers were constructed utilizing various methods of common mode rejection and various processing schemes.

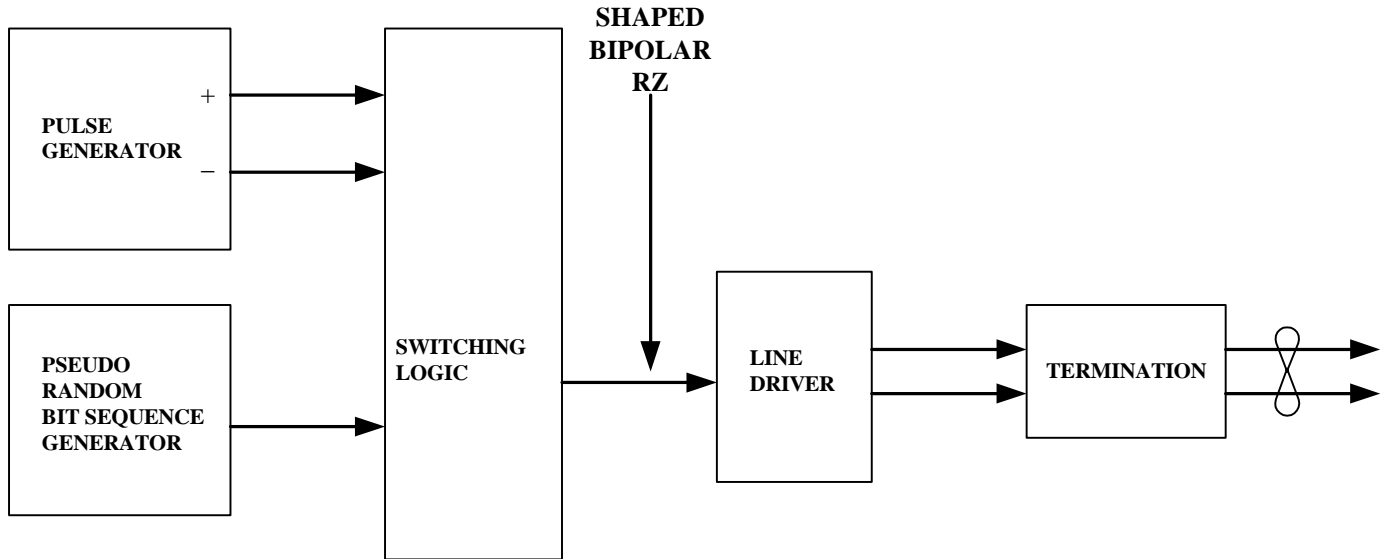
Differential Amplifier Input. Figure a-(ii) shows schematics of the differential input stages used for the receivers. The differential amplifier input stage required resistors to local ground at the input to provide a path for the input current for the voltage followers. Voltage protection was used to prevent damage to the voltage followers in the event of high voltage, common mode spikes. The voltage follower stages provided a controlled impedance for the differential amplifier stage.

Opto-Isolator Input The opto-isolator input stage utilized two H-P 5082-4371 isolators connected in opposite polarity to detect the bipolar data. The HP 5082-4371 input has a forward conduction "knee" at approximately 1.4 volts. A second simple LED (HP 5082-4650) was connected in series with each opto-isolator to provide a combined knee voltage of approximately 3 volts. A series resistor RL of 1000 ohms was placed in series with the LED/opto-isolator network to limit the receiver current to 7mA at 10 volts (differential) applied at the input. At 4.5V differential on the line, one opto-isolator conducts 1.5 mA.

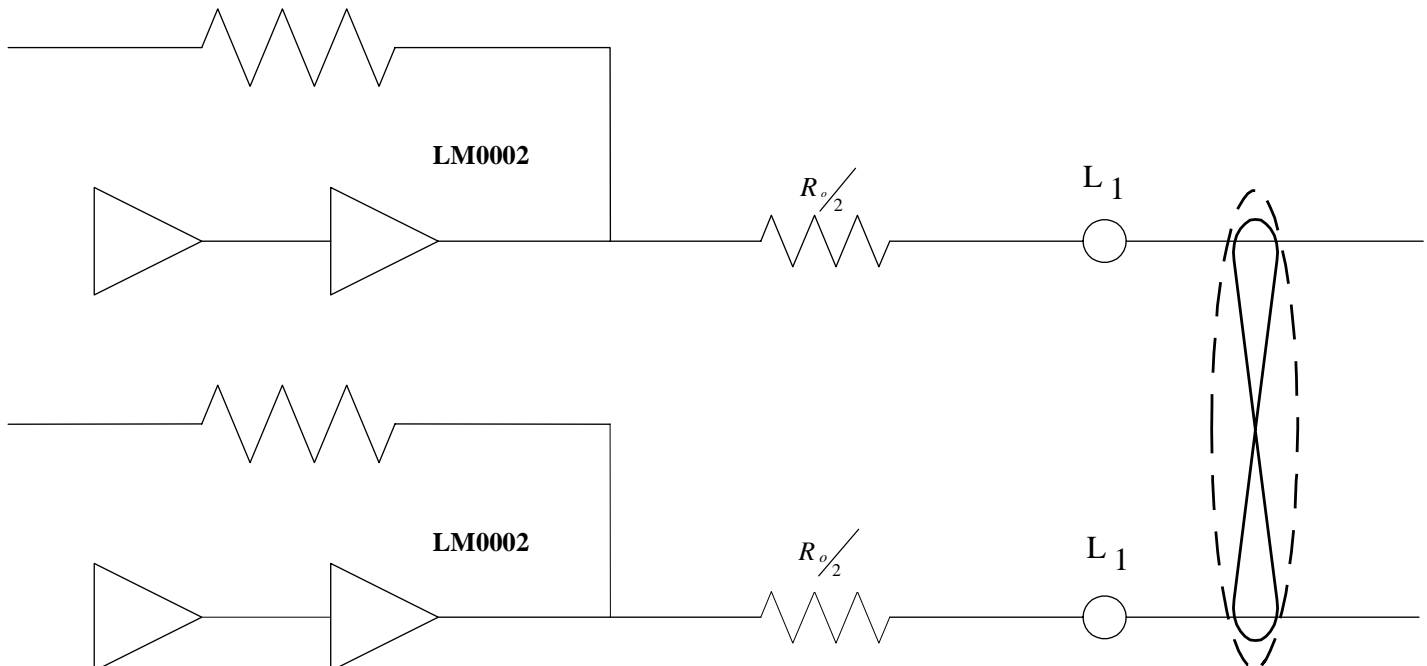
One circuit configuration which enables the opto-isolator to operate at 100 kilobits per second at these low input currents is shown in figure a-(iii). A potential of +15 volts is applied to pin 8 to provide maximum gain in the first transistor. During conduction, a charge on the second transistor is discharged via pin 7 and R2 to a potential of +0.5 volts set by R1 and R3. Discharging to a +0.5 volt potential reduces the possibility of a loss of the first bit following a long null period. This problem has been observed when discharging pin 7 to ground potential.

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FIGURE a-(i)
BIPOLAR TRANSMITTER BLOCK SCHEMATIC

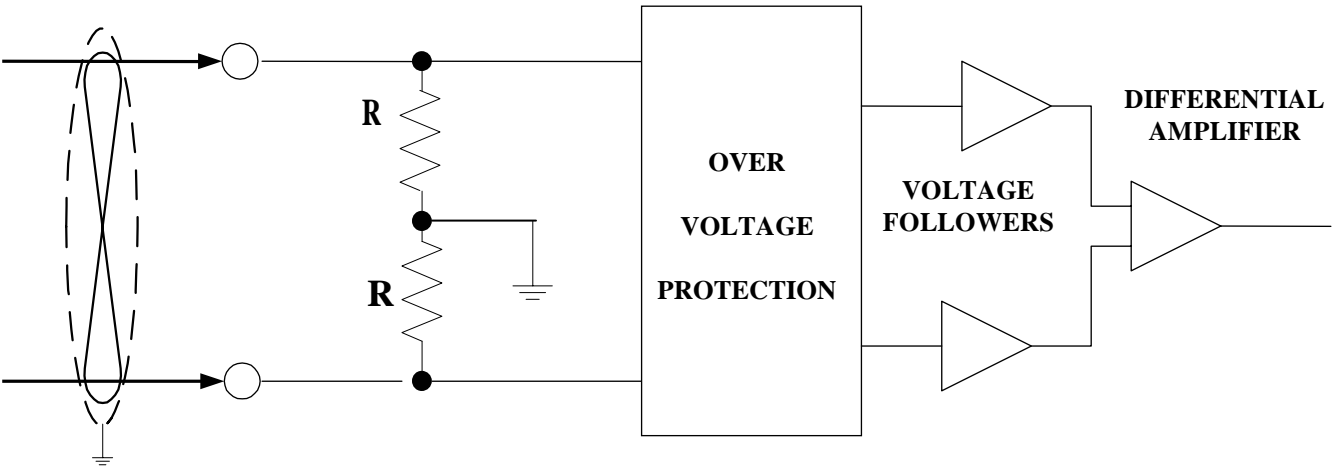


DETAIL OF LINE DRIVER AND TERMINATION



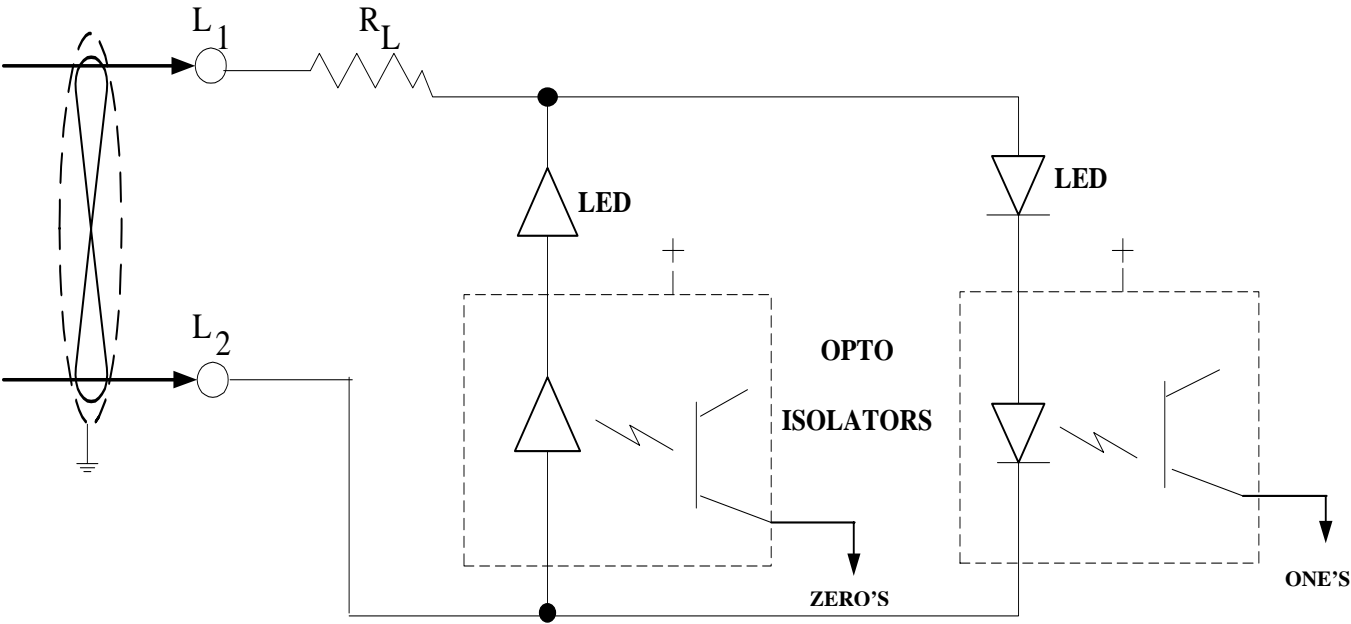
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FIGURE a-(ii)
RZ BIPOLAR RECEIVER INPUT TYPES TESTED



$R > 12\text{ K Ohms}$ (Provides Path for V. F. Input Current)

Figure (a) Differential amplifier input schematic.



R_L = CURRENT LIMITING = 1000 OHMS
LED = LED IN SERIES WITH OPTO ISOLATOR TO PROVIDE ON NULL LEVEL
OPTO-ISOL = HP 5082-4371

Figure (b) OPTO-ISOLATED INPUT SCHEMATIC

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LABORATORY VERIFICATION OF ARINC 429 DITS ELECTRICAL CHARACTERISTICS

A1-2.4 Receiver Data Detection Technique

Two data detection schemes were used, (i) data sampling (sample and decision) and (ii) integrate and dump (Figure a-(iv)).

The data sampling system detects positive-going or negative-going edges which exceed ± 3 volts differential voltage. The edges cause a timing circuit to time for approximately 2 μ sec. When the timing circuit has timed out, a sample of the input is taken. If the sample is HI, a ONE is declared. If the sample is LO, a ZERO is declared. If the sample is NULL, and error diagnostic can be output, since a NULL state is known to be invalid at the data sampling time. An error diagnostic will be output if, for example, during a period of NULL on the line, a short-duration noise spike causes the input to exceed the ± 3 V threshold, so initiating the edge detector timing circuit, but dissipates rapidly so that a NULL is estimated at the data sampling time.

The integrate-and-dump processor circuit detects positive or negative-going edges which exceed the ± 3 V differential threshold. The edge detection causes an integration circuit to integrate the input voltage for a period of 5 μ sec. The output of the integrator is sampled (timing is derived from the edge detector) at the end of the integration period. If it is above zero voltage, a ONE is declared; if it is below zero voltage, a ZERO is declared.

A threshold level could be introduced about zero voltage to provide an indication of the total energy contained in the pulse. If the integrator output fell within the threshold, an error diagnostic could be presented indicating the detection of the bit was marginal.

A1-2.5 Test Data Message

The test waveform was a continuous pseudo-random bit pattern. This continuous pattern did not test the initial synchronization or "false-alarm" aspects in a word-by-word transmission environment with NULL on the transmission line between words.

A1-2.6 Emission of RF Energy Test Results

The following tests were performed under conditions of light (one receiver) and heavy (20 receivers) line loading.

- A. Conducted RF Interference (RTCA DO-160 Paragraph 21.2)
The interference measured was within the limits specified in DO 160 Figure 21-2.
- B. Radiated RF Interference (RTCA DO-160 Paragraph 21.3)
The interference measured was within the limits specified in DO-160 Figure 21-5.

It should be noted that the 20dB limit exceedance permitted in DO 160 was not taken. The transmitter output spectrum can be further improved by the addition of filtering to attenuate output frequencies above those of interest in the digital data.

A1-2.7 Susceptibility Test Results

The tests were performed to determine the susceptibility of the Mark 33 DITS to RF, AF and spike interference levels specified in DO-160 under conditions of light (one receiver) and heavy (20 receivers) line loading.

The following receiver configurations were tested:

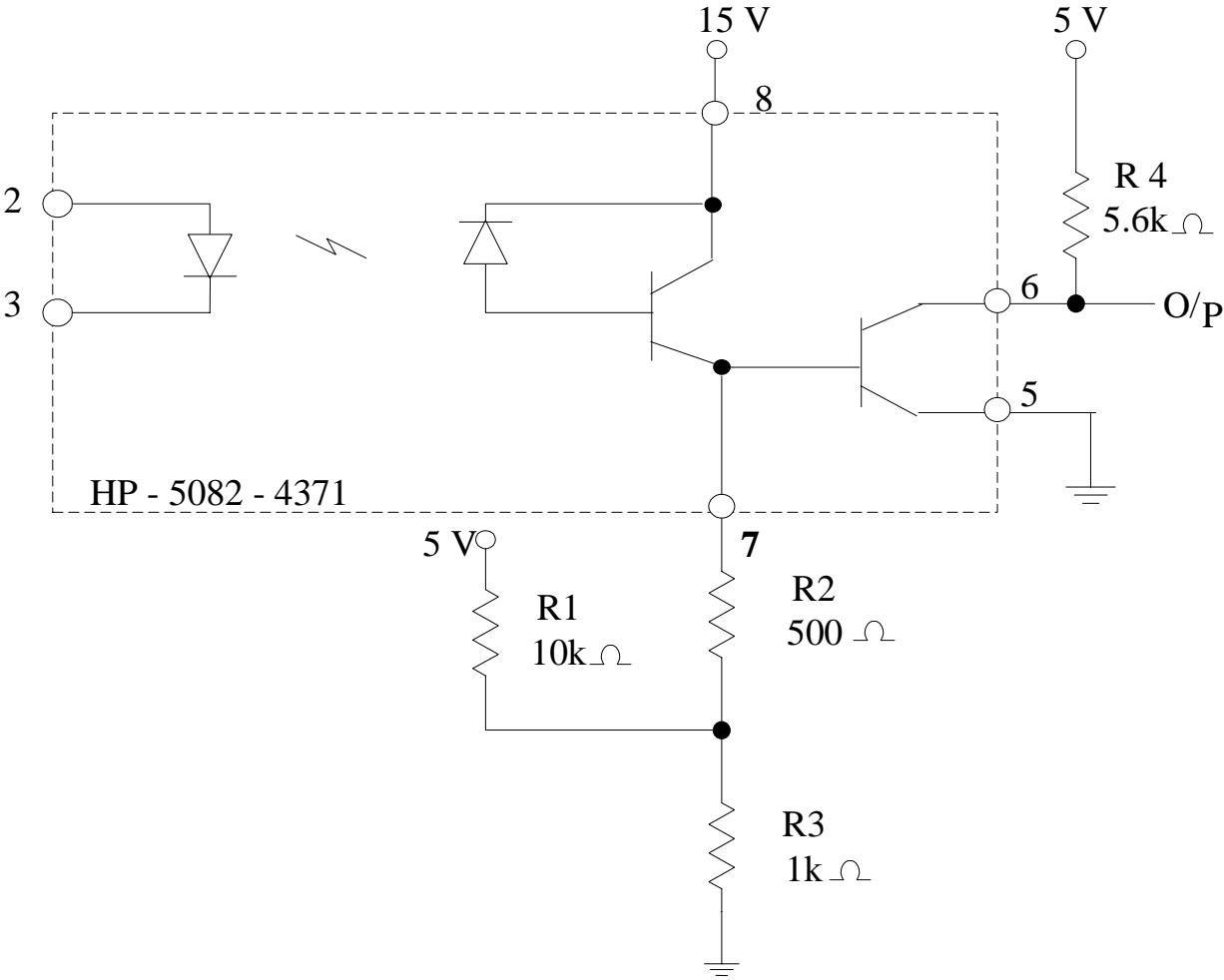
- (i) Differential Amplifier input, time sample processing
- (ii) Differential Amplifier input, integrate-and-dump processing
- (iii) Opto-isolator input, time sample processing
- (iv) Opto-isolator input, integrate-and-dump processing

The data transmitted consisted of a continuous pseudo-random bit sequence. Error checking was made on a bit-by-bit basis.

- A. Conducted RF Susceptibility (DO-160 Paragraph 20.20B Category Z)
No bit errors were detected with RF applied to any of the line loading and receiver configurations.
- B. Magnetic Fields Induced Into Interconnecting Cables (DO-160 Paragraph 19.3)
Test performed at a level above those specified in DO-160 Figure 19-1. No bit errors were detected with the field applied to the cable for any cable loading or receiver configuration.

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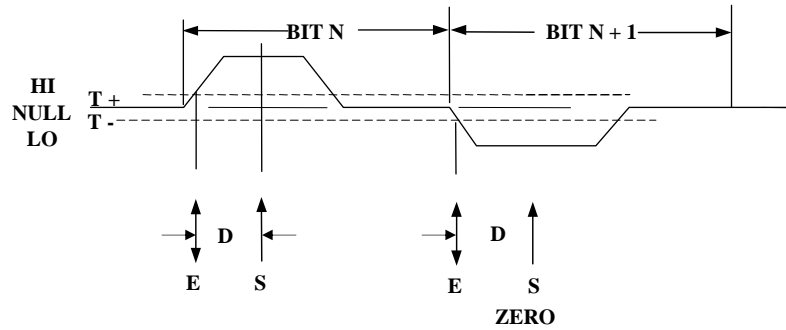
FIGURE a-(iii)
OPTO-ISOLATOR FRONT-END CIRCUIT SCHEMATIC



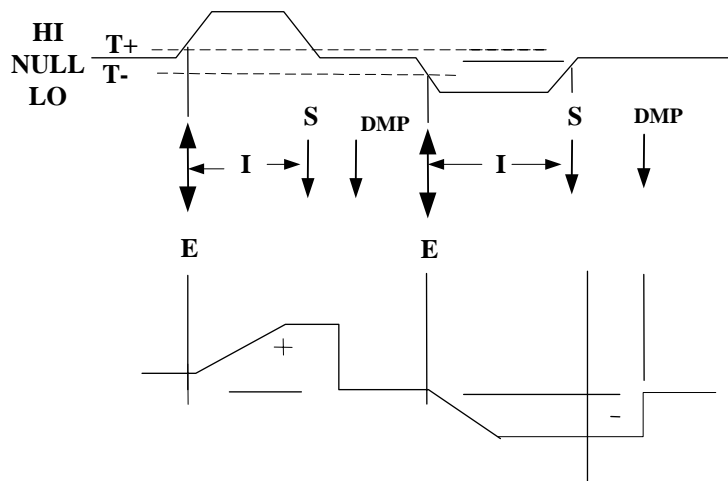
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FIGURE a-(iv)
DATA DETECTION

(a) SAMPLE - AND - DECISION



(b) INTEGRATE - AND - DUMP



LEGEND:

- E** = EDGE DETECT (BIT TIMING)
- D** = DELAY
- S** = SAMPLE
- I** = INTEGRATION INTERVAL
- DMP** = DUMP INTEGRATOR CHARGE

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- C. Electric Fields Induced Into Interconnecting Cables (DO-160 Paragraph 19.4)
The tests were performed with voltage levels above those specified in DO 160 Figure 19-1 Category Z. No bit errors were detected with the field applied for any cable loading or receiver configuration.
- D. Spikes Induced Into Interconnecting Cables (DO-160 Paragraph 19.5, Category Z)
The spikes were generated and applied to the cable as shown in DO-160, Figure 19-4. Bit errors were counted during the application of 50 transients and also following the transient test. The following results were observed:

Receiver Configuration	Line Light	Loading Heavy
Diff. Amp., Sample Det	0	0
Diff. Amp., Int. & Dump Det	0	0
Opto-Isolator, Sample Det	8	15
Opto-Isolator, Int & Dump Det	0	1

All configurations performed with zero bit errors for approximately 10^7 bits following the transient test.

A1-3.0 Pulse Distortion Tests For Typical Aircraft wire Installations

Laboratory testing and computer simulation studies were conducted to investigate the pulse distortion introduced on typical aircraft wire installations.

A1-3.1 Laboratory Tests

Receivers and a transmitter were constructed to operate using the DITS high speed (100 KBPS) waveform. Lengths of twisted shielded cable were connected to form a representative wiring configuration for digital data. The wire length and stub configuration were selected to represent postulated installations on a B747 airplane. The cable used for lab tests was 20 and 22 AWG twisted shielded cable with wrapped KAPTON insulation, no. BMS B-51, Class 2 type III. The pulse distortion at the receiver nodes of the wiring systems were recorded. The characteristics of the 20 AWG cable were measured and used to develop the cable model used in the computer simulation.

A1-3.2 Computer Simulation

A computer program was developed to evaluate pulse distortion on lines with stubs. The DITS transmitter impedance and voltage waveform was modeled. The cable model was developed from the measured cable characteristics. The DITS receiver input impedance was modeled.

The computer simulation was run and results were plotted for various line length and stub configurations representing postulated installations on a B747 airplane.

A1-3.3 Results

The results of the laboratory tests and computer simulation for the same cable configuration showed good agreement, with a maximum difference of 0.4 volts on rising and falling edges. The computer simulation showed slightly higher cable loss effect than the lab test. The lab test results were recorded using an oscilloscope camera; the computer results were plotted. Only the plotted results are presented here.

Figure a-(v) shows the schematic for the first simulation. This configuration represents a transmitter, a receiver and a single length of twisted shielded cable 200 feet long. The cable is modeled as Blocks 1 to 4, for later stub connection.

At the transmitter and receive ends of the cable, the shields are grounded via a 0.05 μ H inductor (which models the inductance of the ground lead). At other nodes, the shields and cable inners are carded through, representing a continuous length of cable.

Figure a-(vi) Transmitter open circuit differential output voltage. This waveform was used for all the simulation runs.

Figure a-(vii) The transmitter output voltage and receiver input voltage for the configuration in Figure a-(v).

Figure a-(viii) shows the schematic for the second simulation. This configuration represents a transmitter at an engine location, with receivers at the equipment bay and the flight deck. Four receiver loading configurations are shown with maximum loading of twenty receivers. The waveforms for this simulation run are shown in Figures a-(ix) through a-(xvi).

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Figures a-(ix) and a-(x) Transmitter and receiver waveform for loading configuration 1.

Figures a-(xi) to a-(xvi) Waveforms for loading configurations 2, 3 and 4.

Figure a-(xvii) shows the schematic for the third simulation. This configuration represents a transmitter at the flight deck with receivers at the equipment bay, the inner engine and the outer engine.

Figures a-(xviii) to a-(xxi) Waveforms for the third simulation.

Figure a-(xxii) shows the schematic for the fourth simulation. This configuration represents a transmitter at the equipment bay with receivers at the equipment bay, the flight engineer's panel, the first officer's panel and the captain's panel.

Figures a-(xxiii) to a-(xxvi) Waveforms for the fourth simulation.

Figure a-(xxvii) shows the schematic for the fifth simulation. This is a long line simulation and is included to show the operation of the system with lines longer than would realistically be used in a “B747-sized” airplane. This configuration represents a transmitter with one receiver close (10 feet) and one receiver remote (500 feet).

Figures a-(xxviii) and a-(xxix) Waveforms for the “long line” configuration.

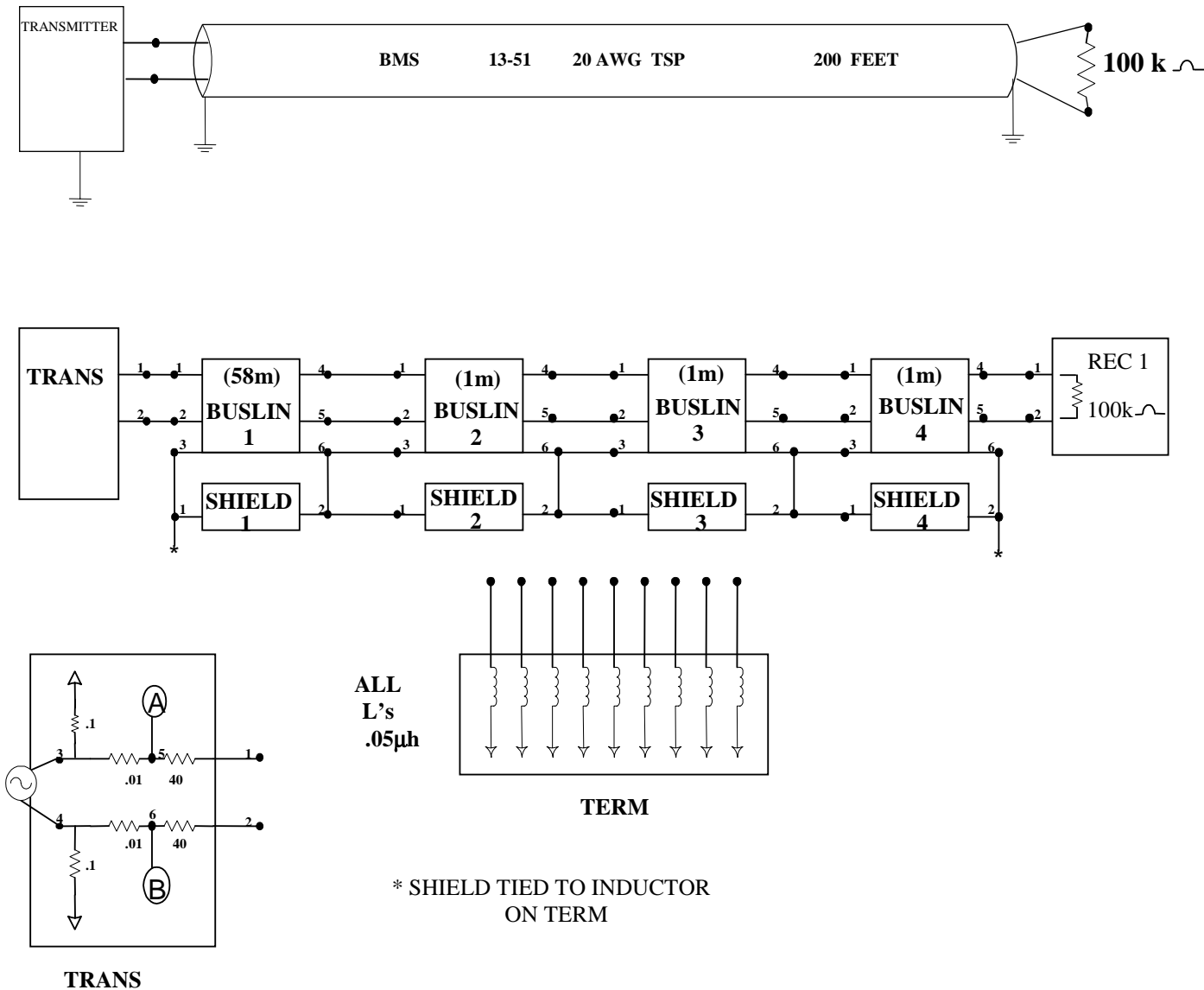
A1-3.4 Conclusions

From laboratory tests and simulations, it is concluded that no intolerable bit distortion is introduced into the “high speed DITS” waveform due to cable lengths and stub configurations likely to be encountered on a “B747-size” transport aircraft.

If installations are anticipated involving longer line lengths or cables with radically different electrical characteristics, then further investigation may be required.

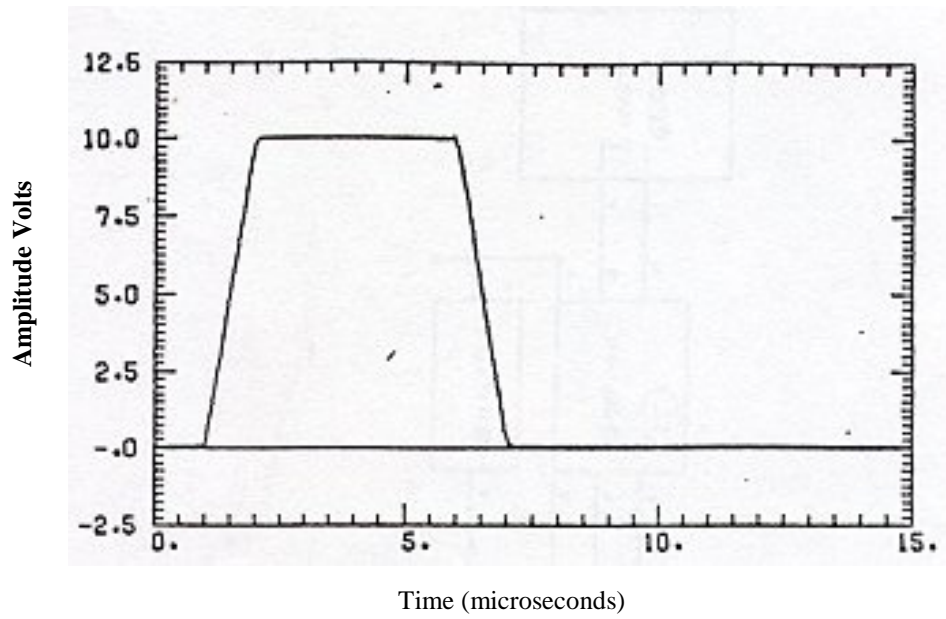
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FIGURE a-(v)



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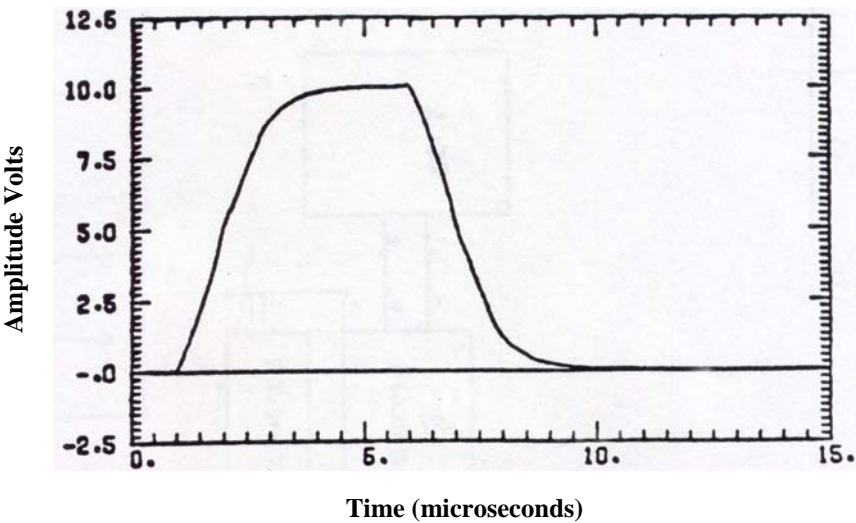
FIGURE a-(vi)



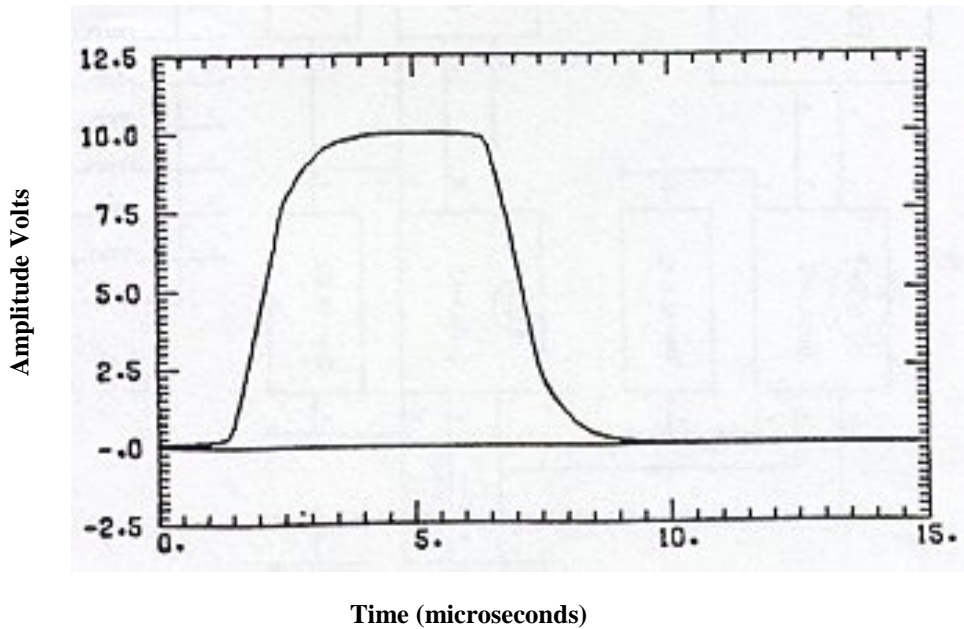
TRANSMITTER LEAD A TO LEAD B VOLTAGE

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FIGURE a-(vii)



TRANSMITTER OUTPUT VOLTAGE

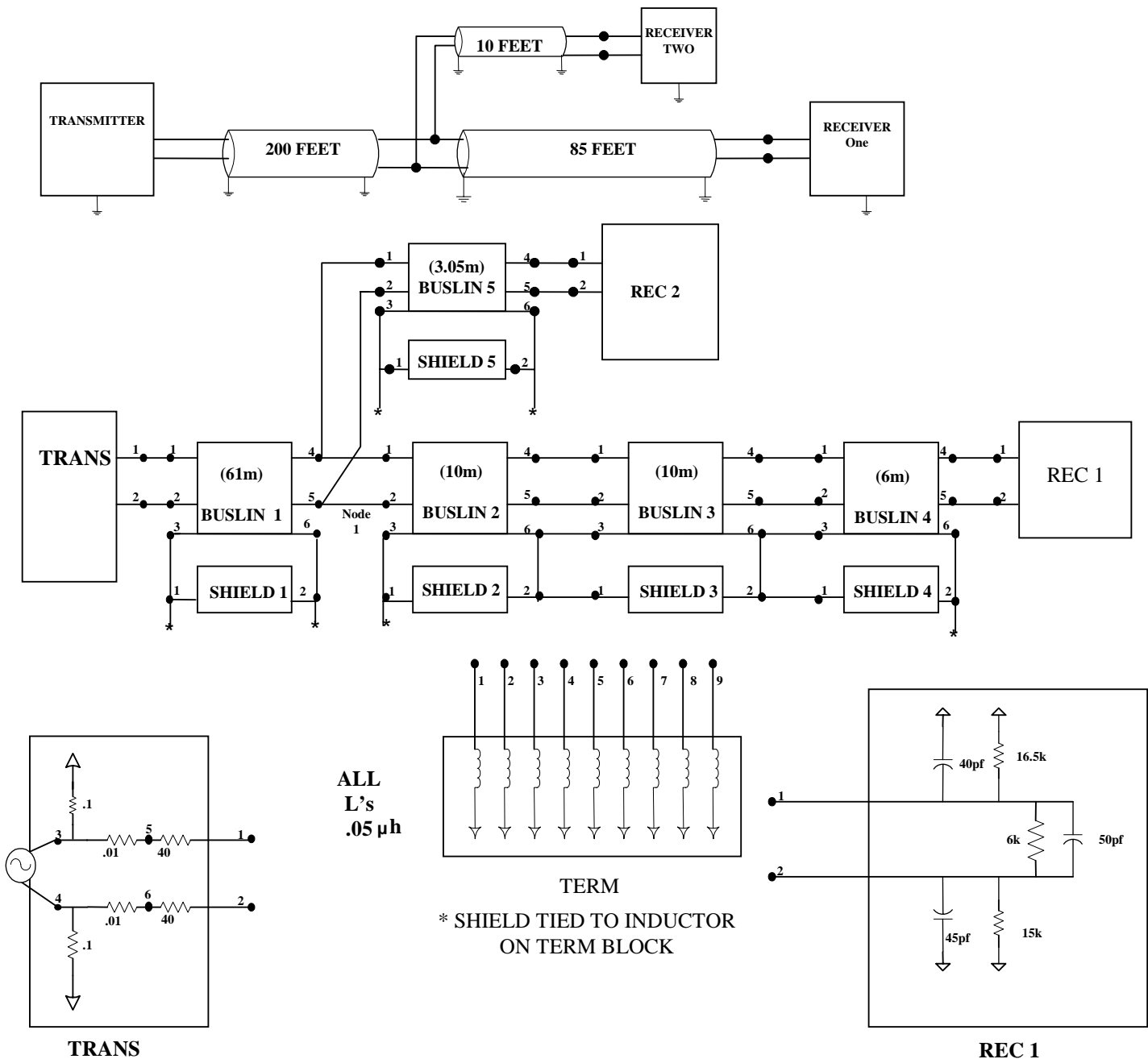


OPEN CIRCUIT VOLTAGE AT RECEIVER ONE

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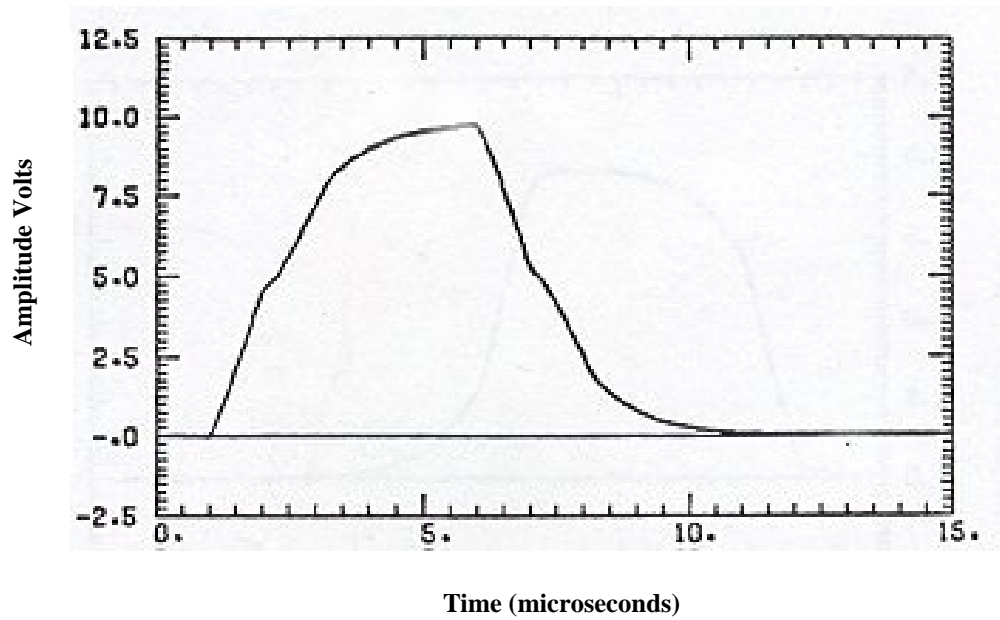
FIGURE a-(viii)

Configuration	# Load Rec 1	# Load Rec 2
1	1	1
2	1	10
3	10	1
4	10	10



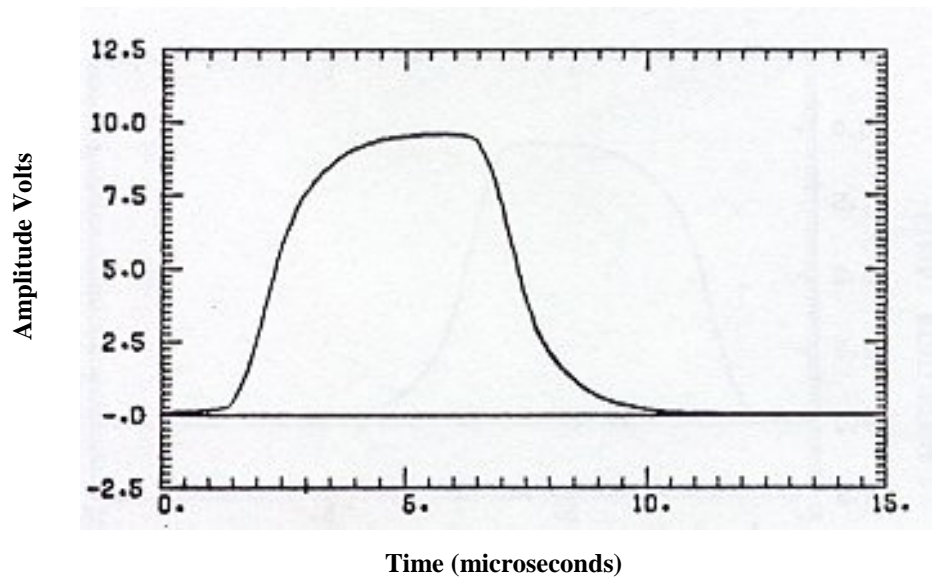
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FIGURE a-(ix)



CONFIGURATION 1

TRANSMITTER OUTPUT VOLTAGE

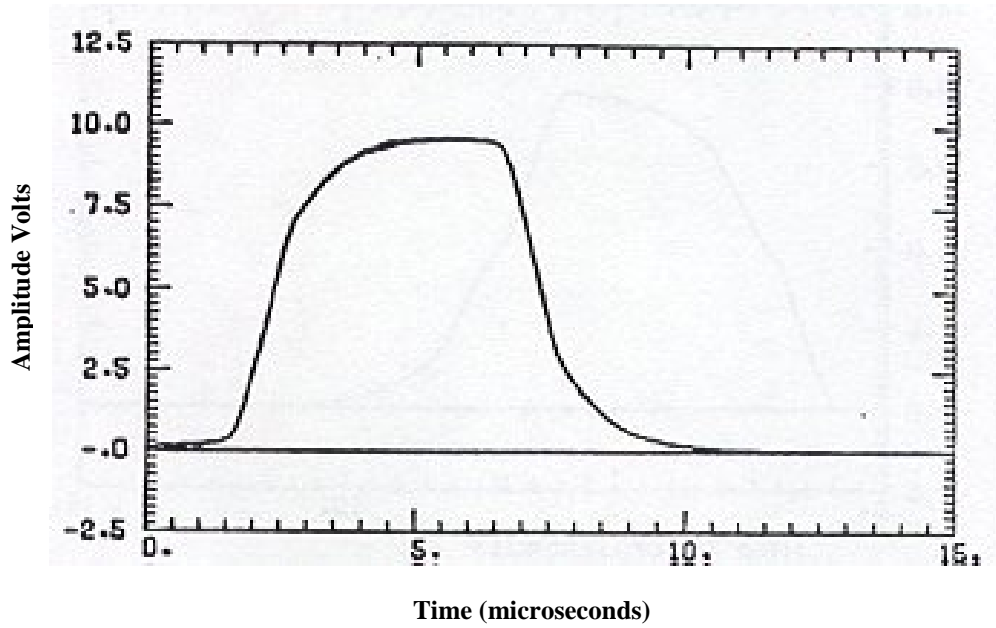


CONFIGURATION 1

VOLTAGE AT FIRST NODE

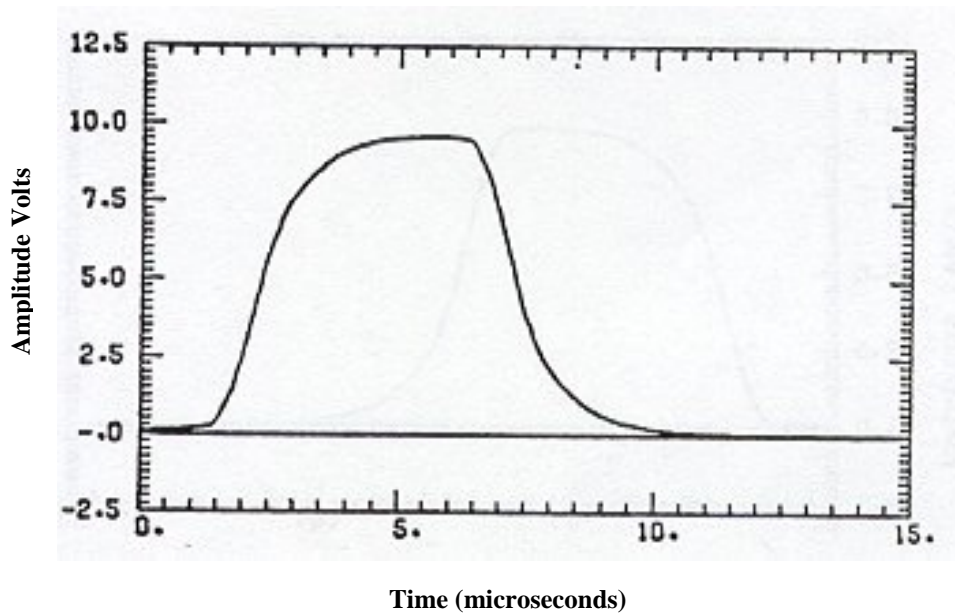
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FIGURE a-(x)



CONFIGURATION 1

VOLTAGE AT RECEIVER ONE

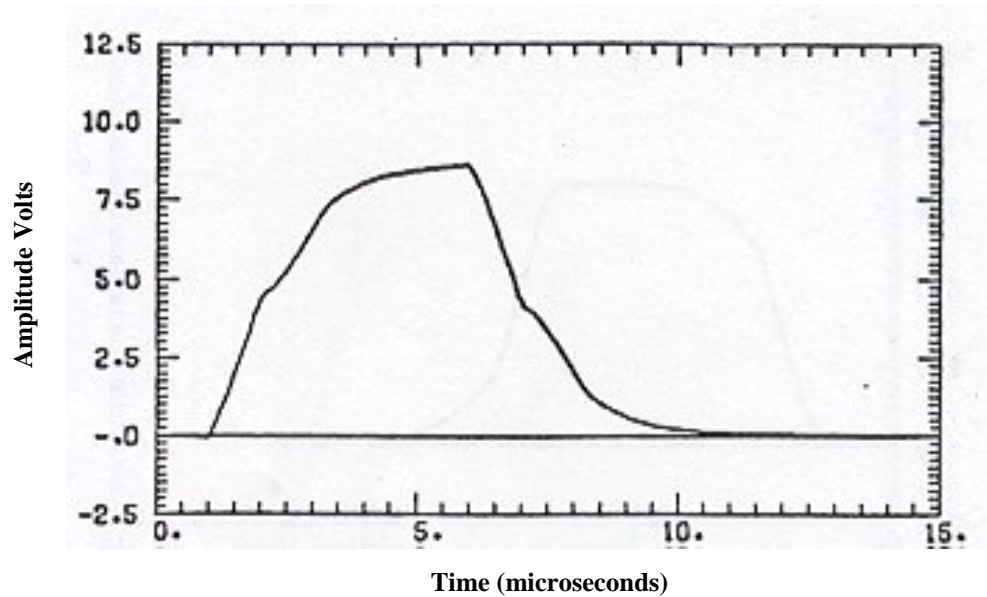


CONFIGURATION 1

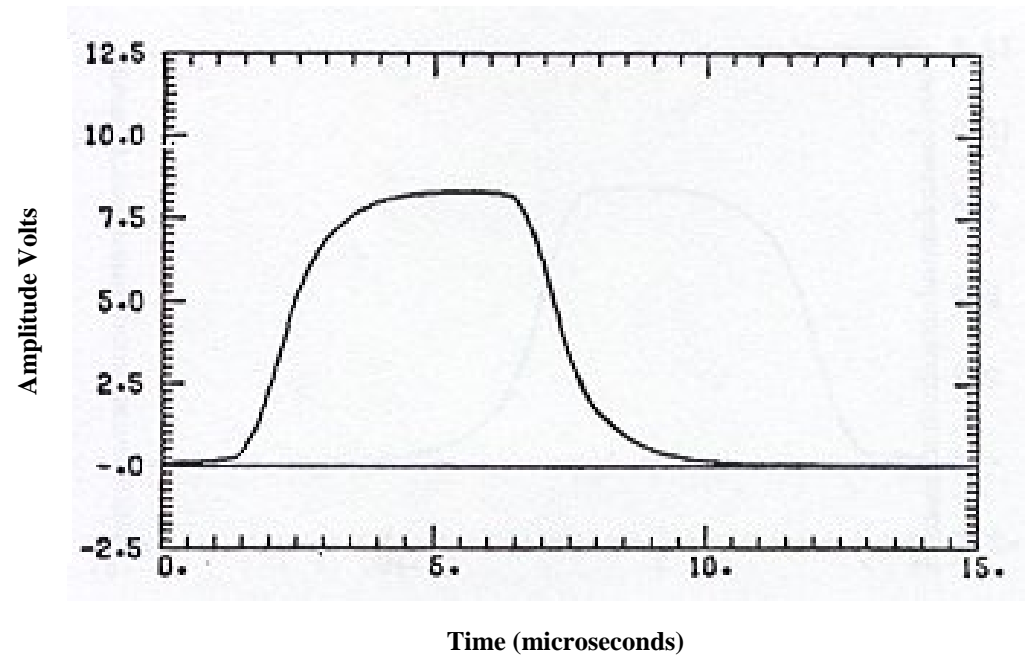
VOLTAGE AT RECEIVER TWO

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FIGURE a-(xi)



TRANSMITTER OUTPUT VOLTAGE



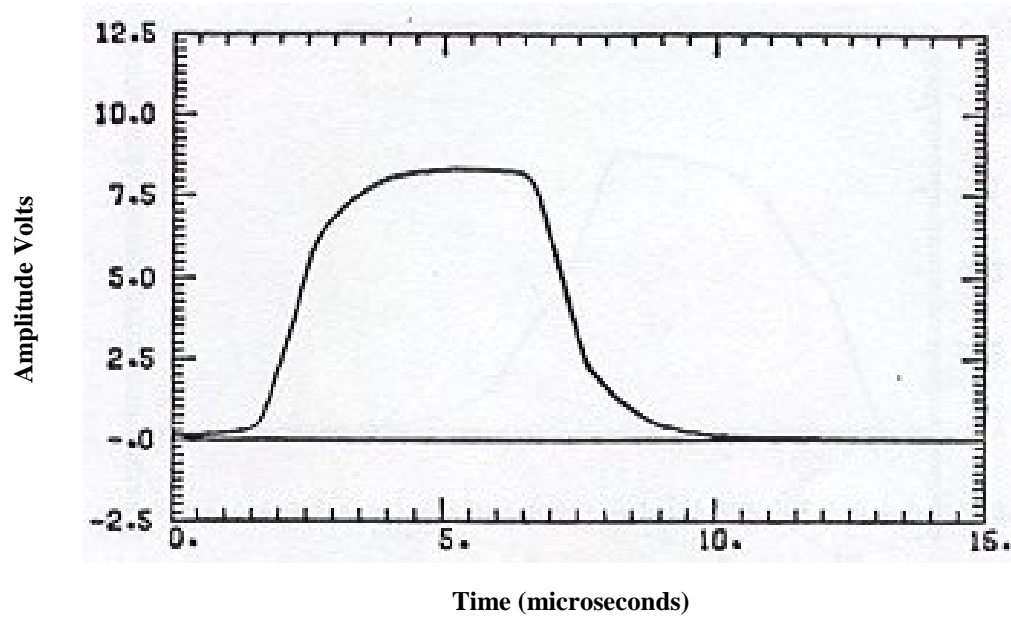
VOLTAGE AT FIRST NODE

CONFIGURATION 2

CONFIGURATION 2

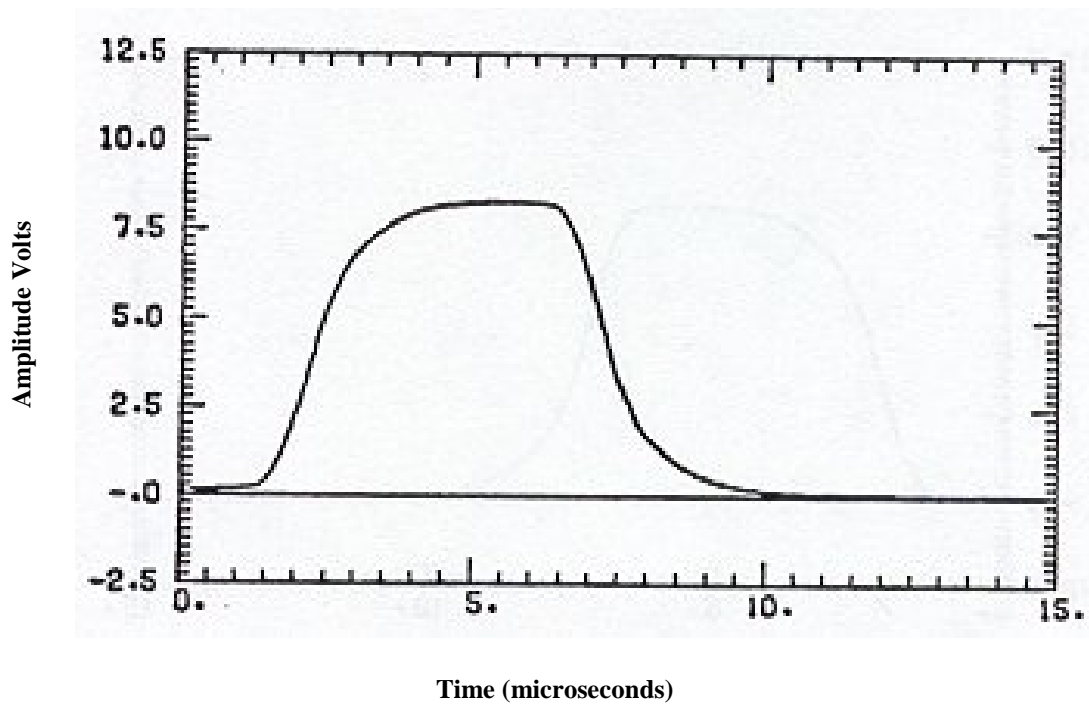
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FIGURE a-(xii)



VOLTAGE AT RECEIVER ONE

CONFIGURATION 2

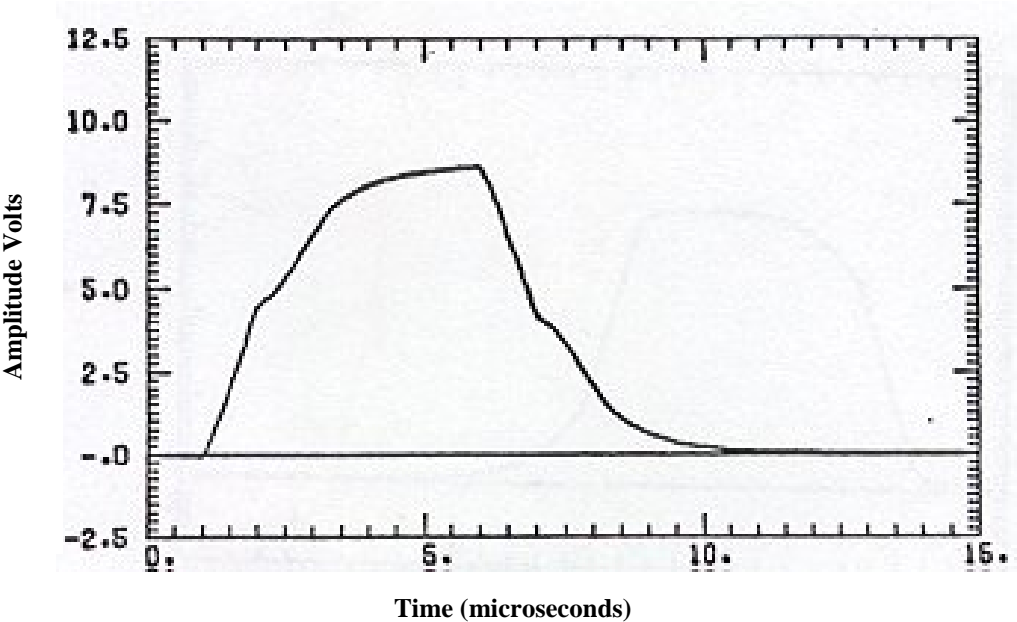


VOLTAGE AT RECEIVER TWO

CONFIGURATION 2

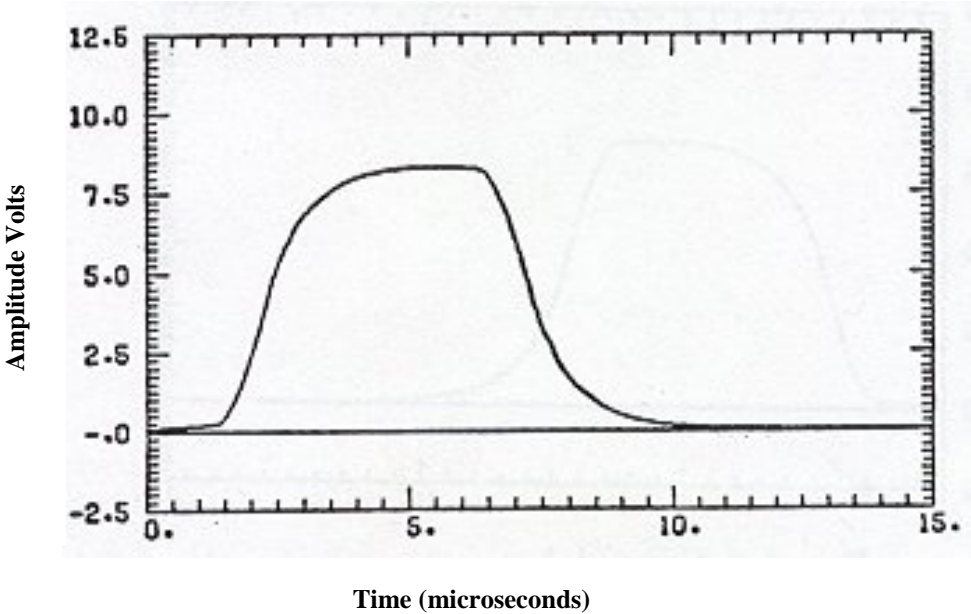
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FIGURE a-(xiii)



CONFIGURATION 3

TRANSMITTER OUTPUT VOLTAGE

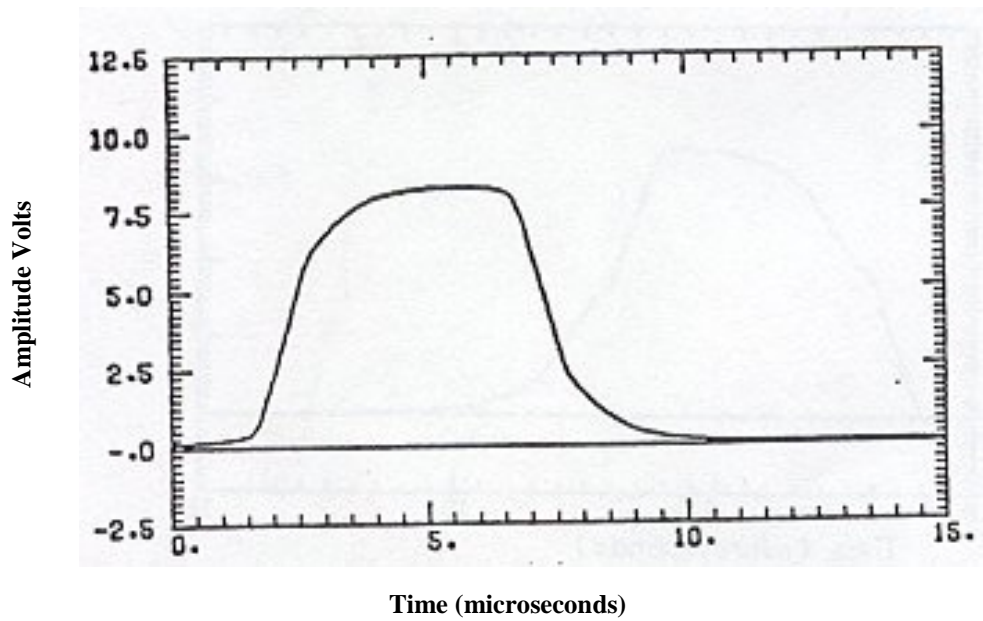


CONFIGURATION 3

VOLTAGE AT FIRST NODE

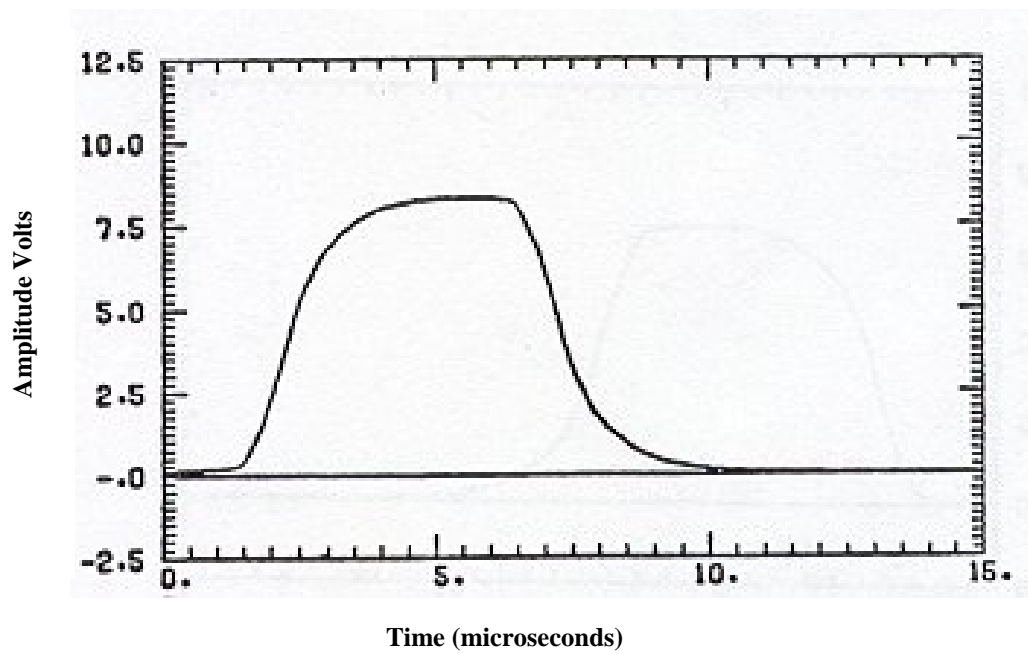
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FIGURE a-(xiv)



CONFIGURATION 3

VOLTAGE AT RECEIVER ONE

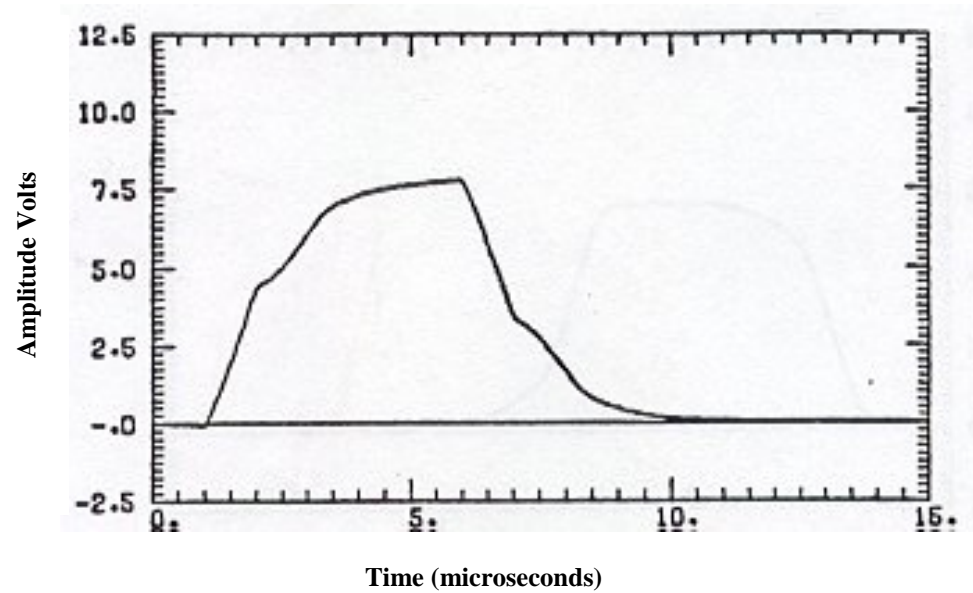


CONFIGURATION 3

VOLTAGE AT RECEIVER TWO

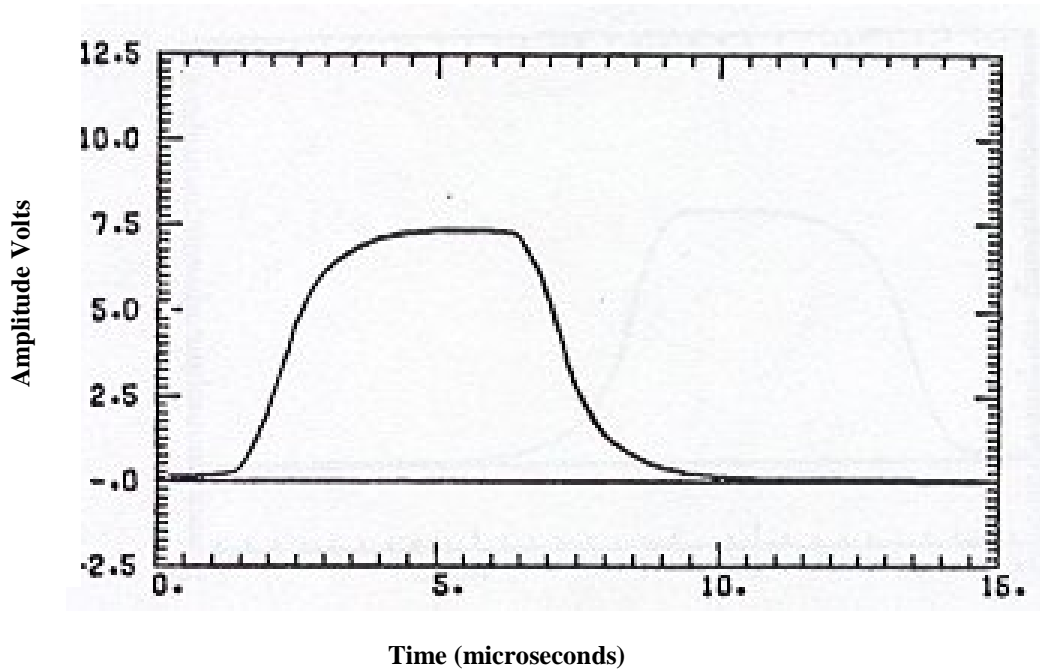
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FIGURE a-(xv)



TRANSMITTER OUTPUT VOLTAGE

CONFIGURATION 4

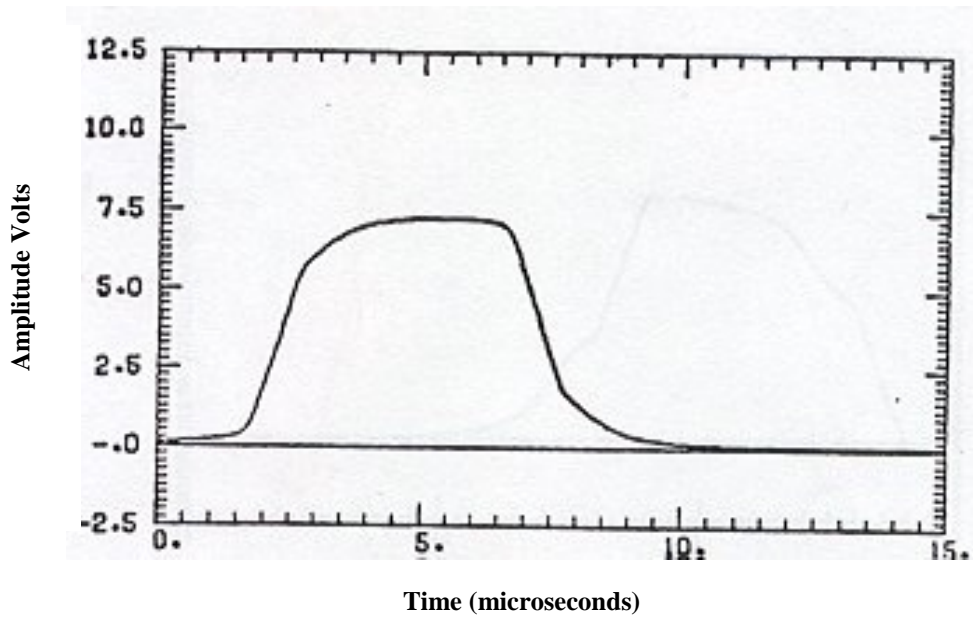


VOLTAGE AT FIRST NODE

CONFIGURATION 4

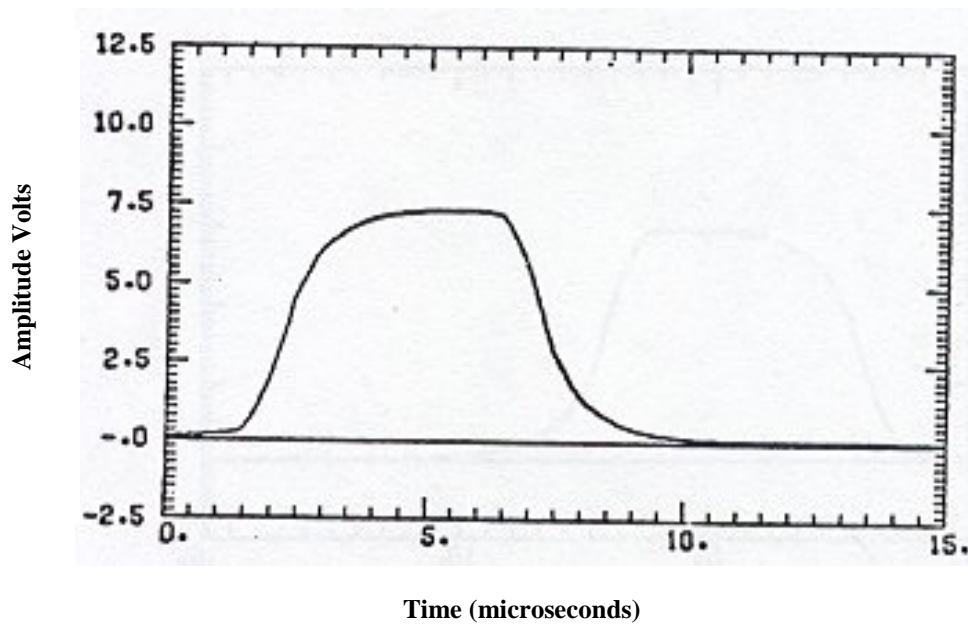
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FIGURE a-(xvi)



CONFIGURATION 4

VOLTAGE AT RECEIVER ONE

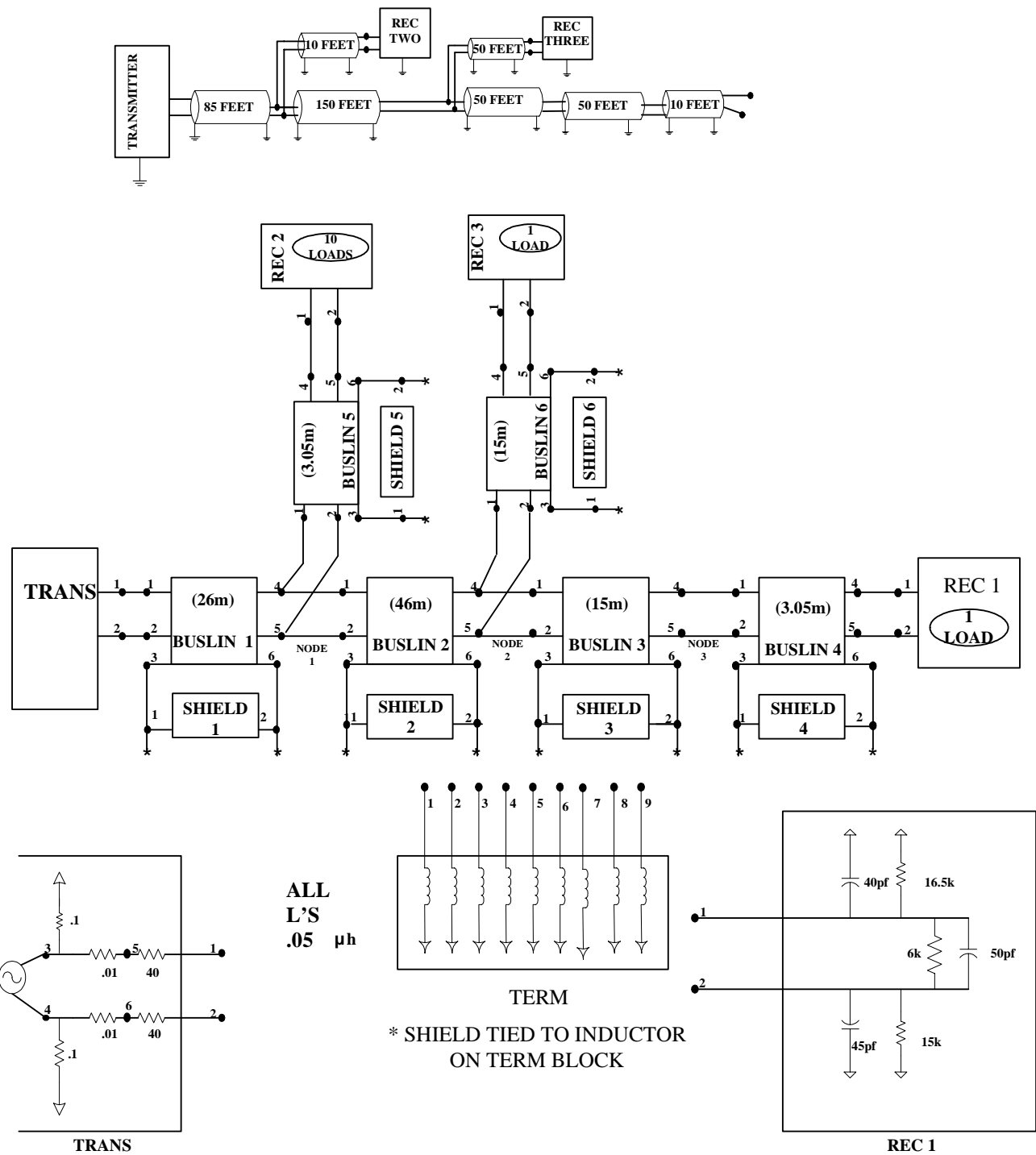


CONFIGURATION 4

VOLTAGE AT RECEIVER TWO

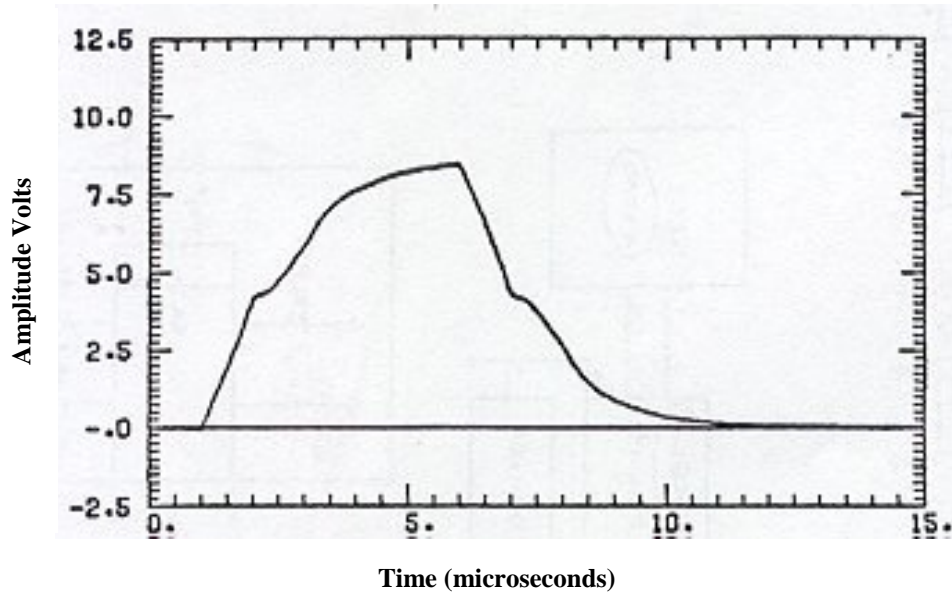
APPENDIX A
LABORATORY VERIFICATION OF ARINC 429 DITS ELECTRICAL CHARACTERISTICS

FIGURE a-(xvii)

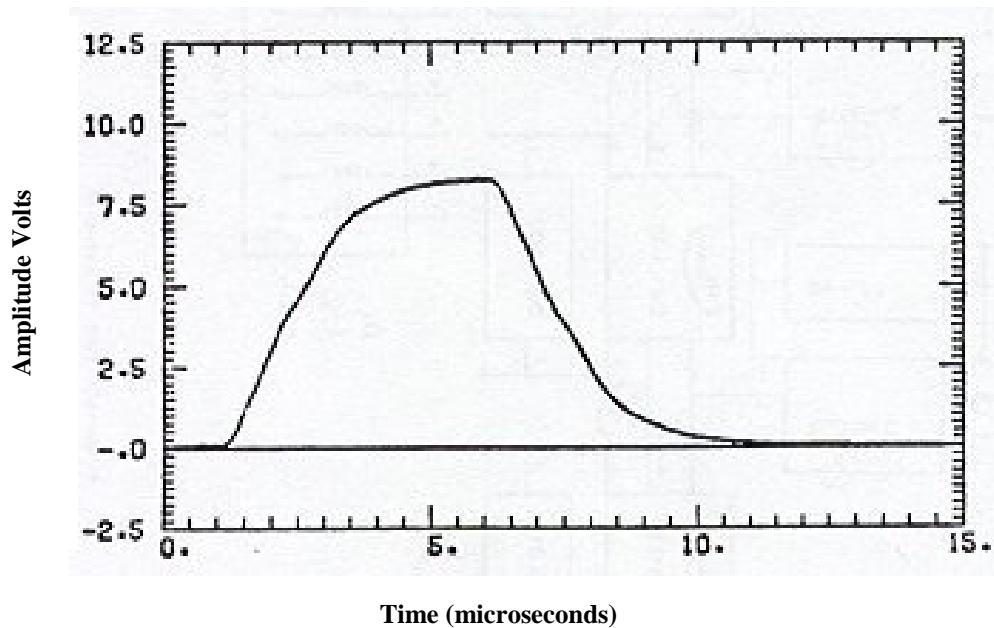


APPENDIX A
LABORATORY VERIFICATION OF ARINC 429 DITS ELECTRICAL CHARACTERISTICS

FIGURE a-(xviii)



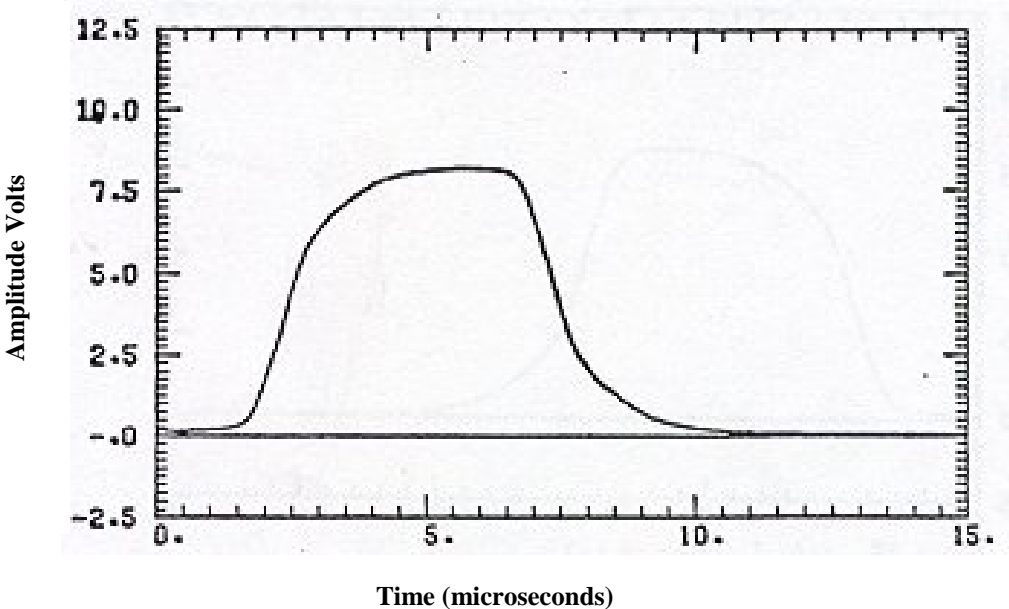
TRANSMITTER OUTPUT VOLTAGE



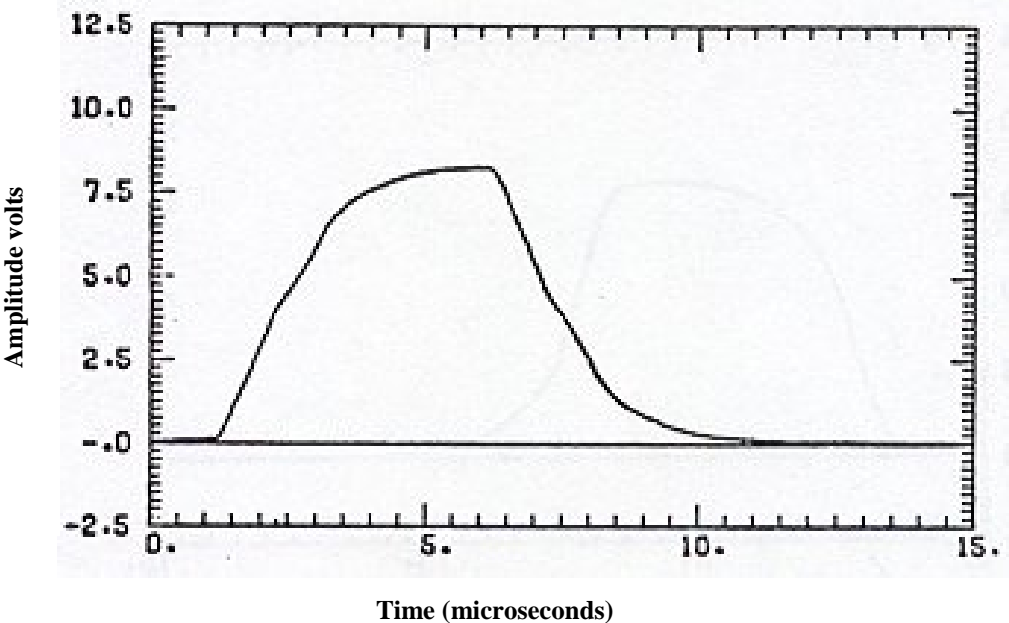
VOLTAGE AT FIRST NODE

APPENDIX A
LABORATORY VERIFICATION OF ARINC 429 DITS ELECTRICAL CHARACTERISTICS

FIGURE a-(xix)



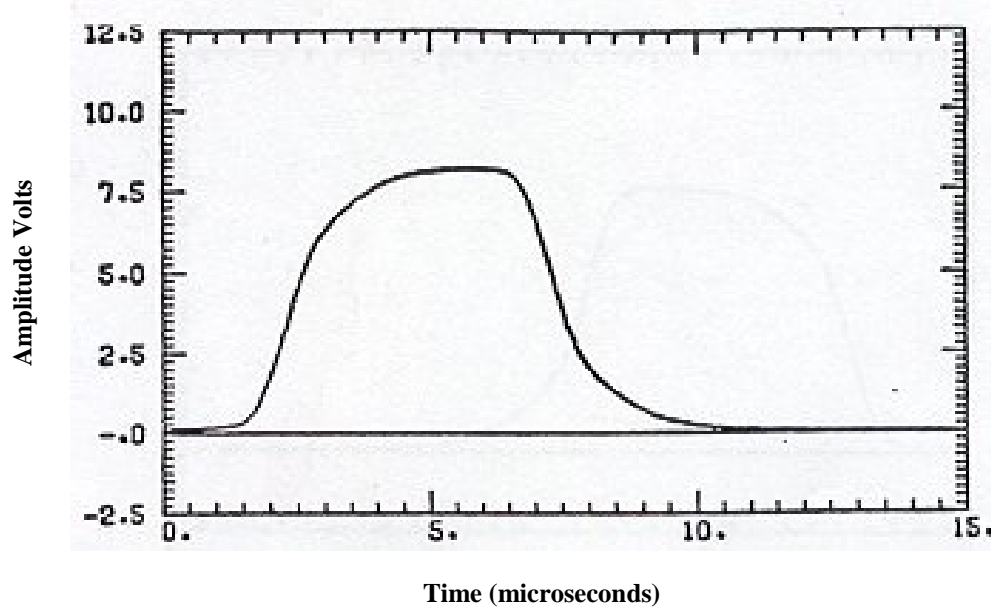
VOLTAGE AT RECEIVER ONE



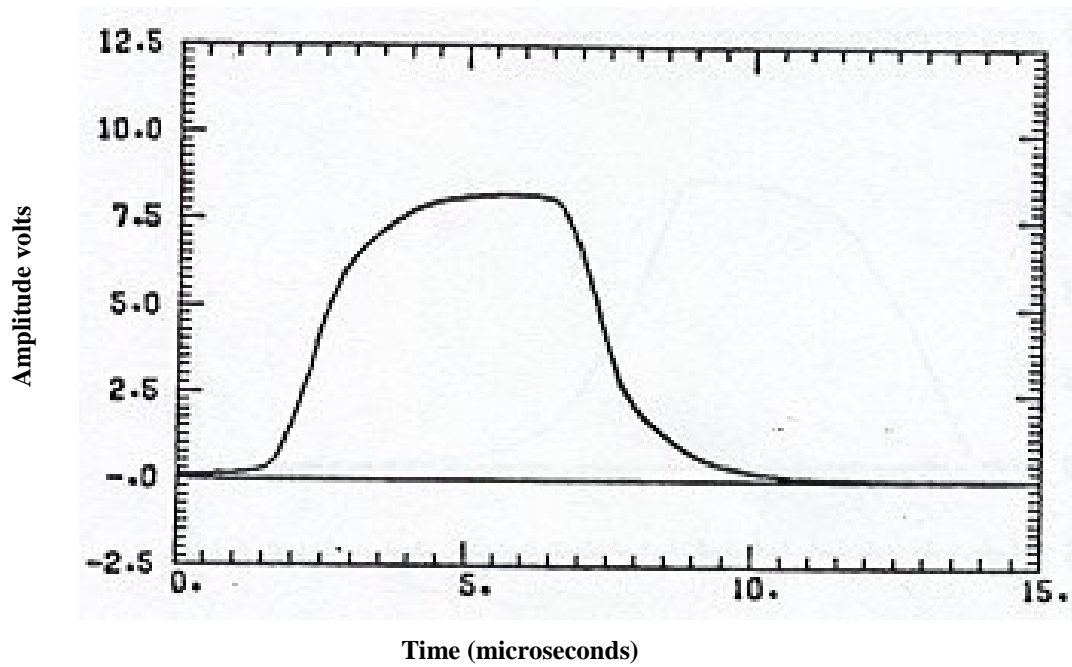
VOLTAGE AT RECEIVER TWO

APPENDIX A
LABORATORY VERIFICATION OF ARINC 429 DITS ELECTRICAL CHARACTERISTICS

FIGURE a-(xx)



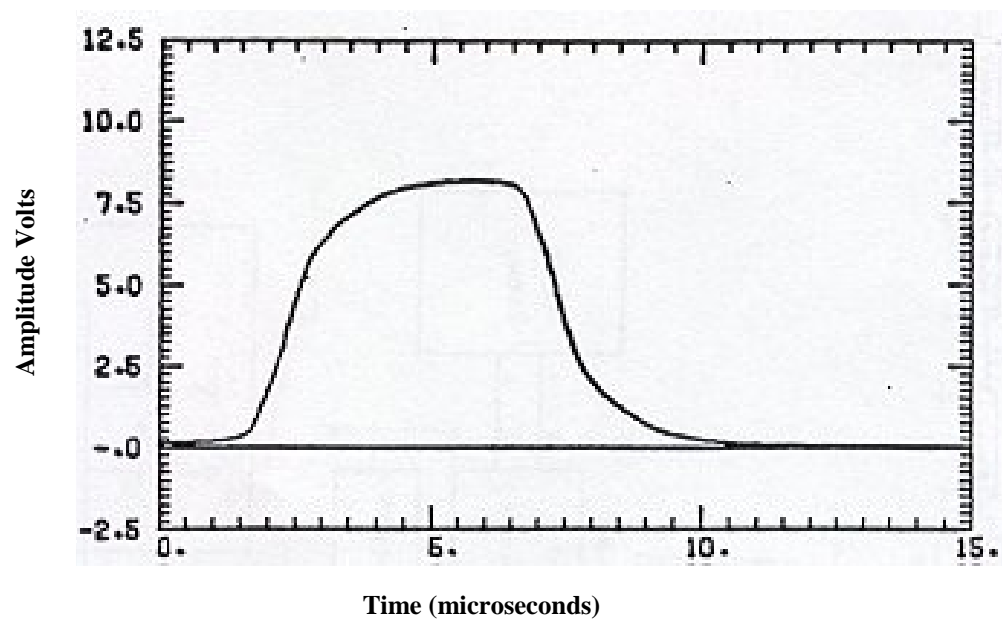
VOLTAGE AT SECOND NODE



VOLTAGE AT RECEIVER THREE

APPENDIX A
LABORATORY VERIFICATION OF ARINC 429 DITS ELECTRICAL CHARACTERISTICS

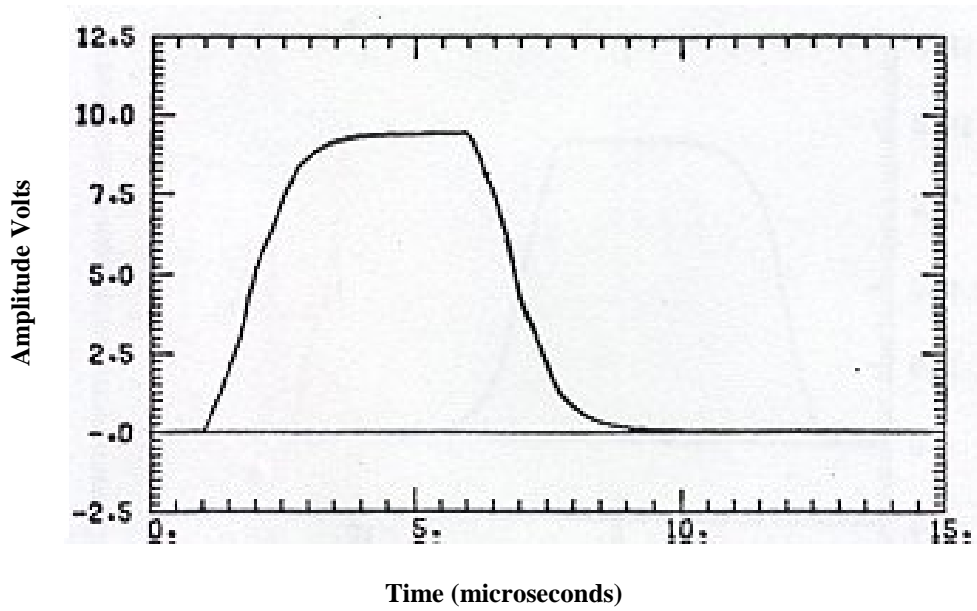
FIGURE a-(xxi)



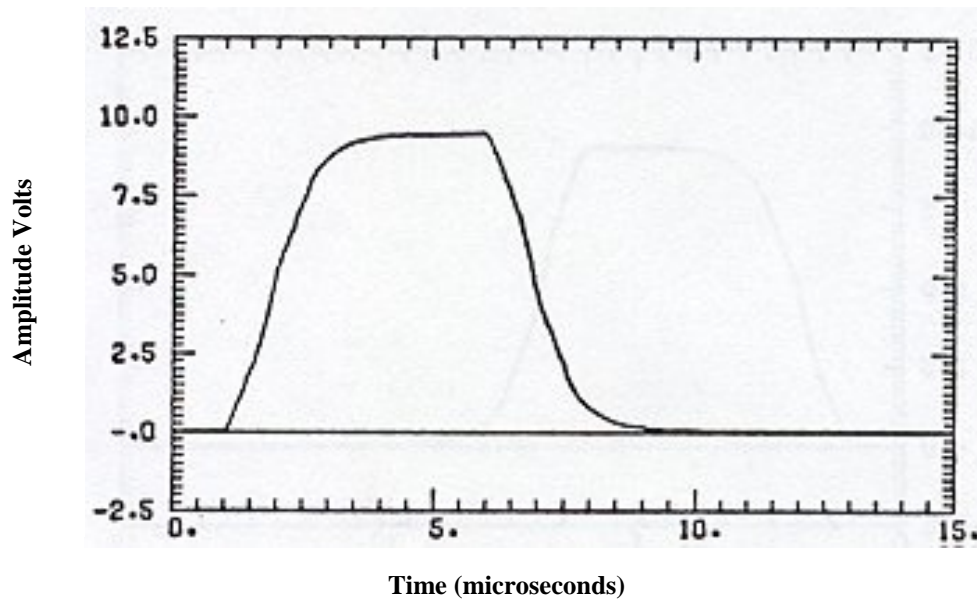
VOLTAGE AT THREE NODE

APPENDIX A
LABORATORY VERIFICATION OF ARINC 429 DITS ELECTRICAL CHARACTERISTICS

FIGURE a-(xxiii)



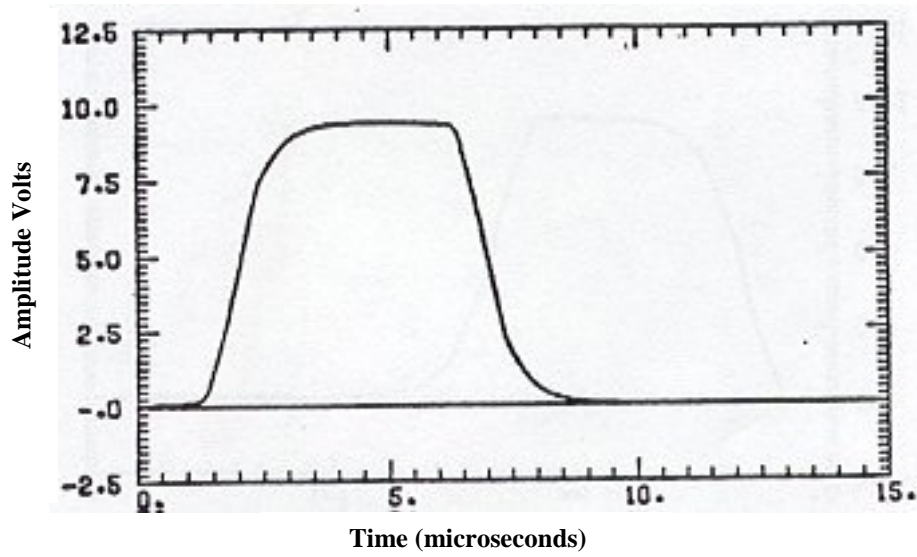
TRANSMITTER OUTPUT VOLTAGE



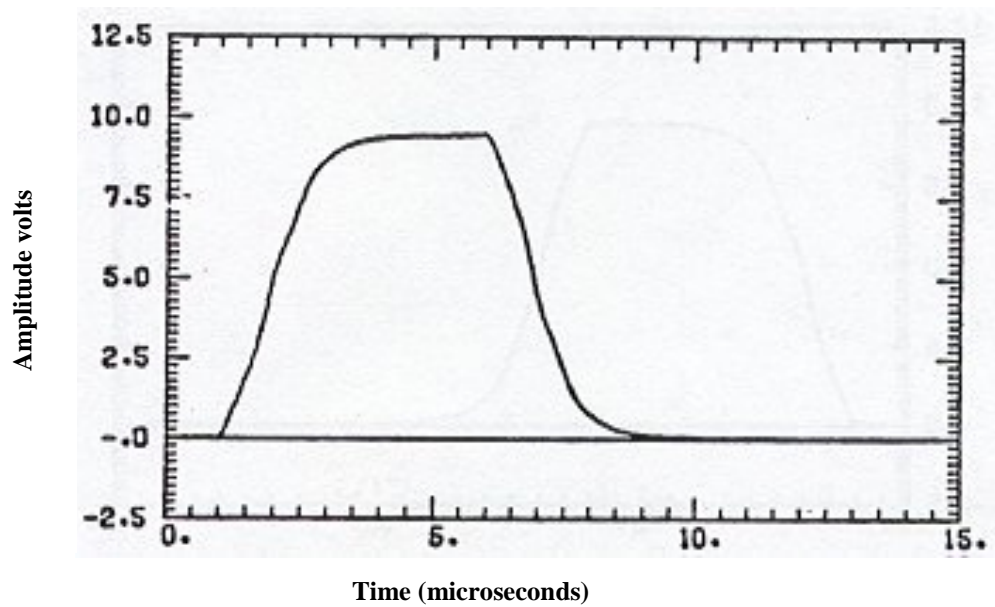
VOLTAGE AT FIRST NODE

APPENDIX A
LABORATORY VERIFICATION OF ARINC 429 DITS ELECTRICAL CHARACTERISTICS

FIGURE a-(xxiv)



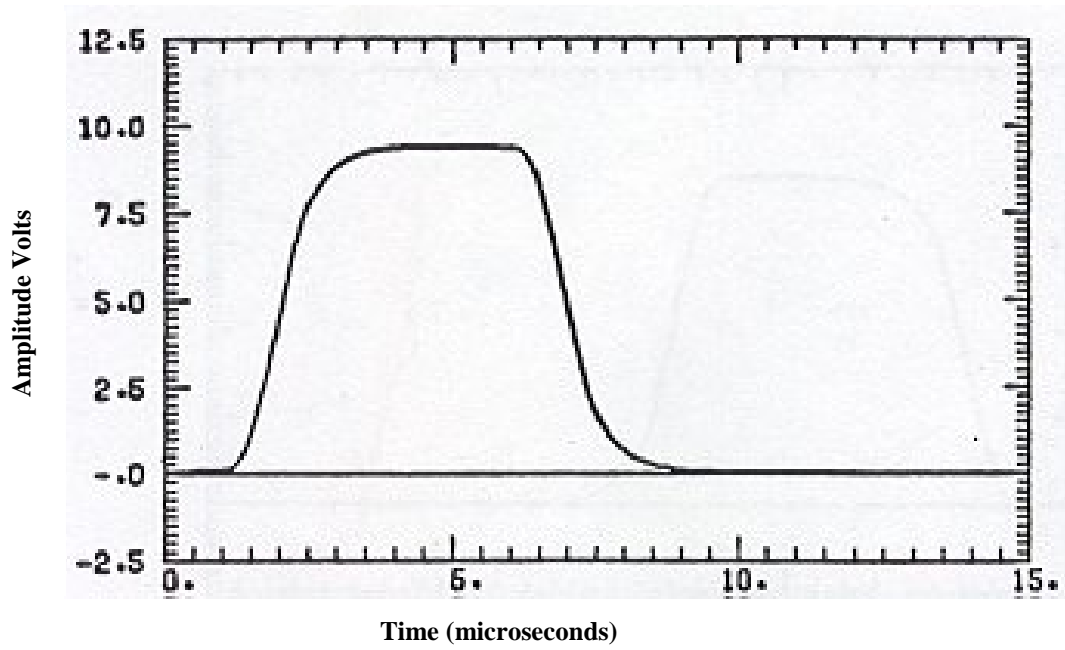
VOLTAGE AT RECEIVER ONE



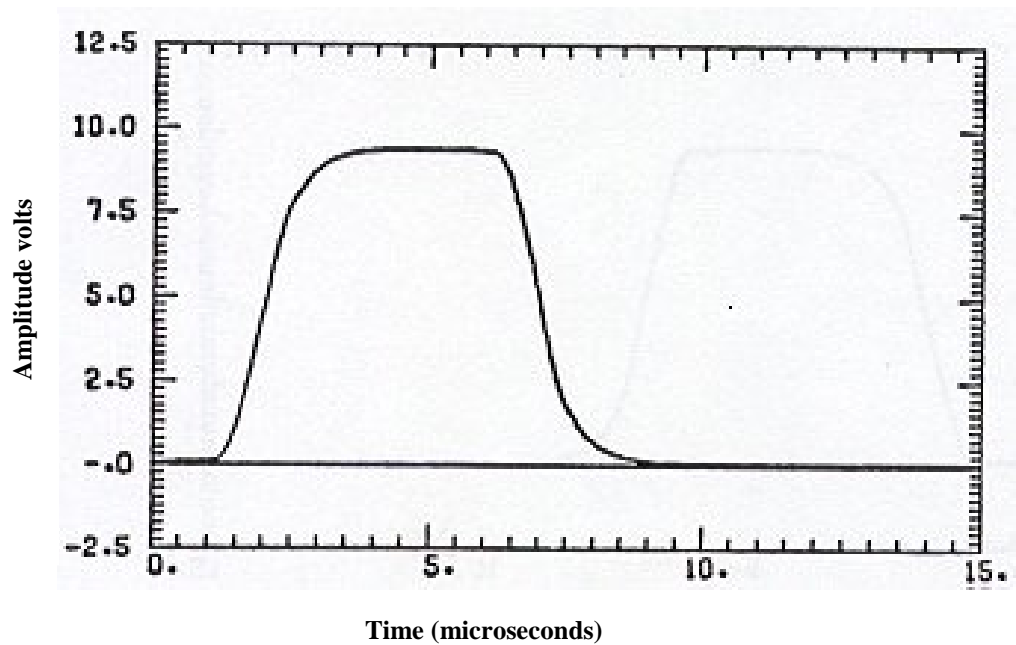
VOLTAGE AT RECEIVER TWO

APPENDIX A
LABORATORY VERIFICATION OF ARINC 429 DITS ELECTRICAL CHARACTERISTICS

FIGURE a-(xxv)



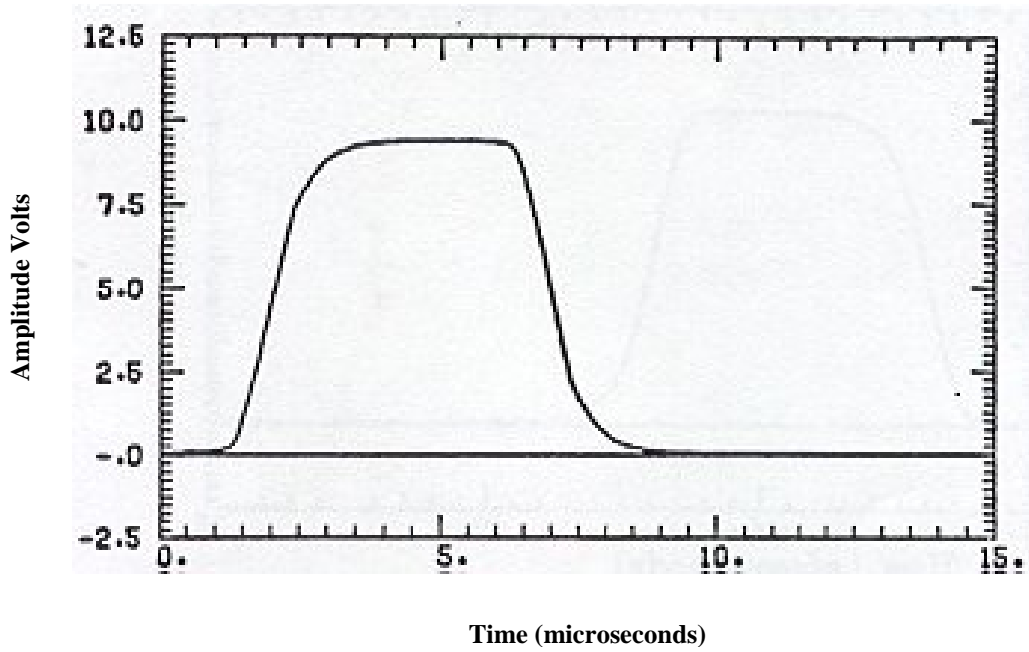
VOLTAGE AT SECOND NODE



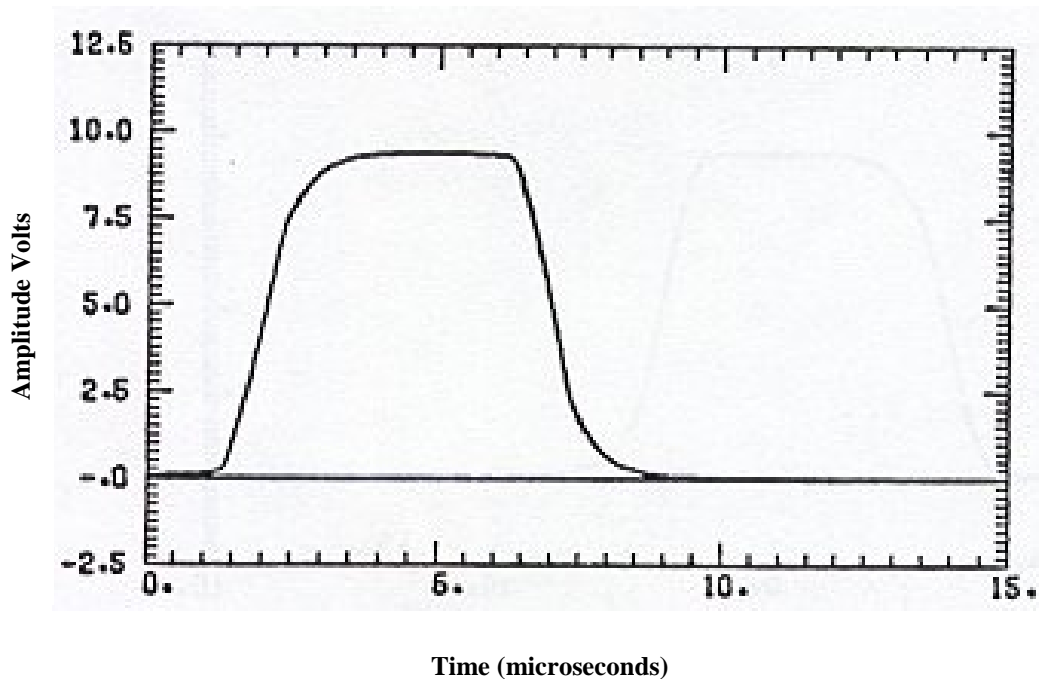
VOLTAGE AT RECEIVER THREE

APPENDIX A
LABORATORY VERIFICATION OF ARINC 429 DITS ELECTRICAL CHARACTERISTICS

FIGURE a(xxvi)

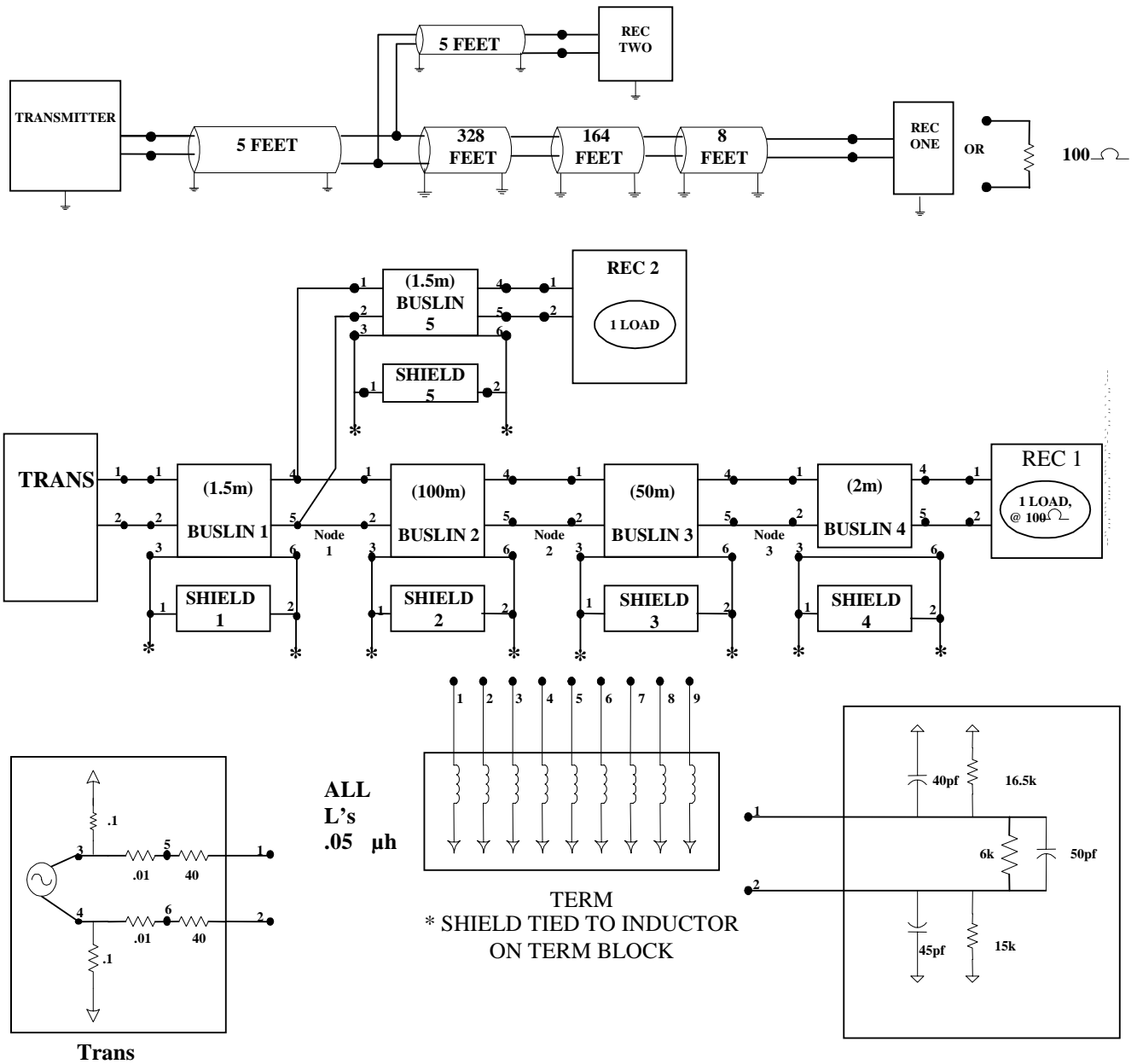


VOLTAGE AT NODE THREE



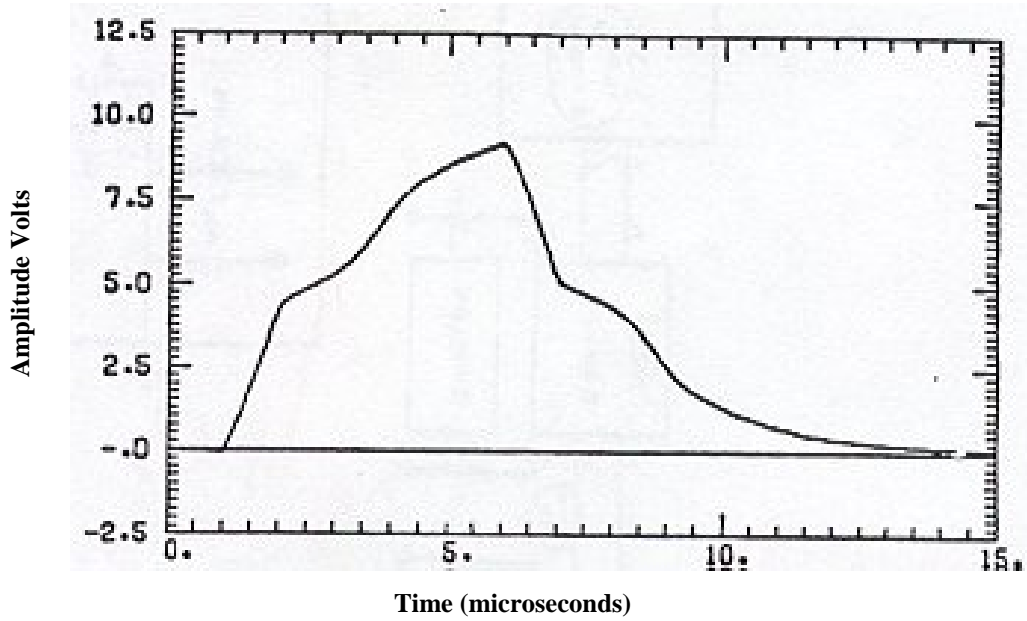
VOLTAGE AT RECEIVER FOUR

APPENDIX A
LABORATORY VERIFICATION OF ARINC 429 DITS ELECTRICAL CHARACTERISTICS

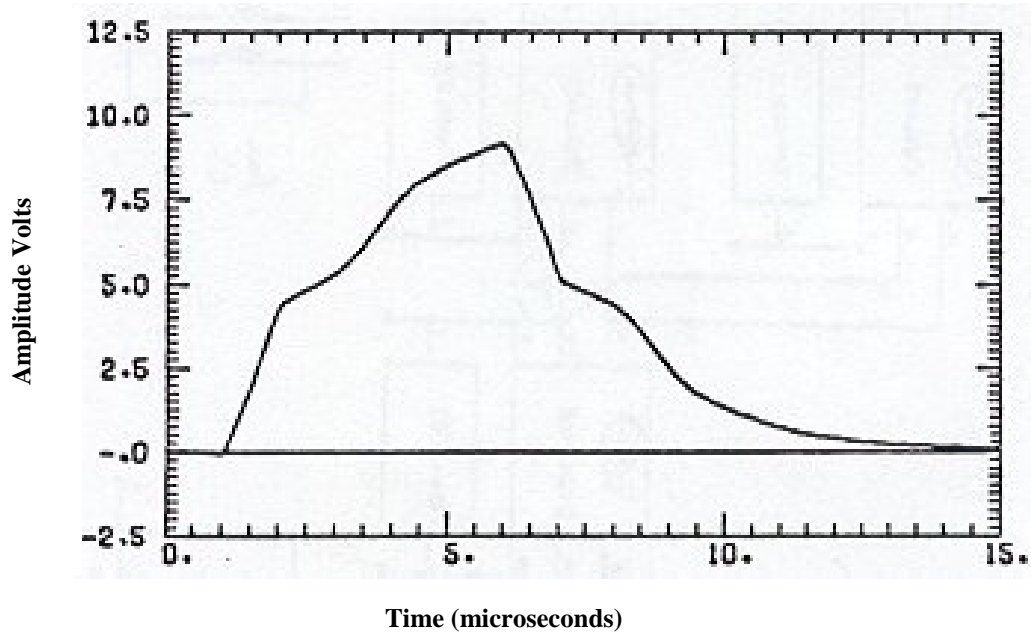
FIGURE a-(xxvii)

APPENDIX A
LABORATORY VERIFICATION OF ARINC 429 DITS ELECTRICAL CHARACTERISTICS

FIGURE a-(xxviii)



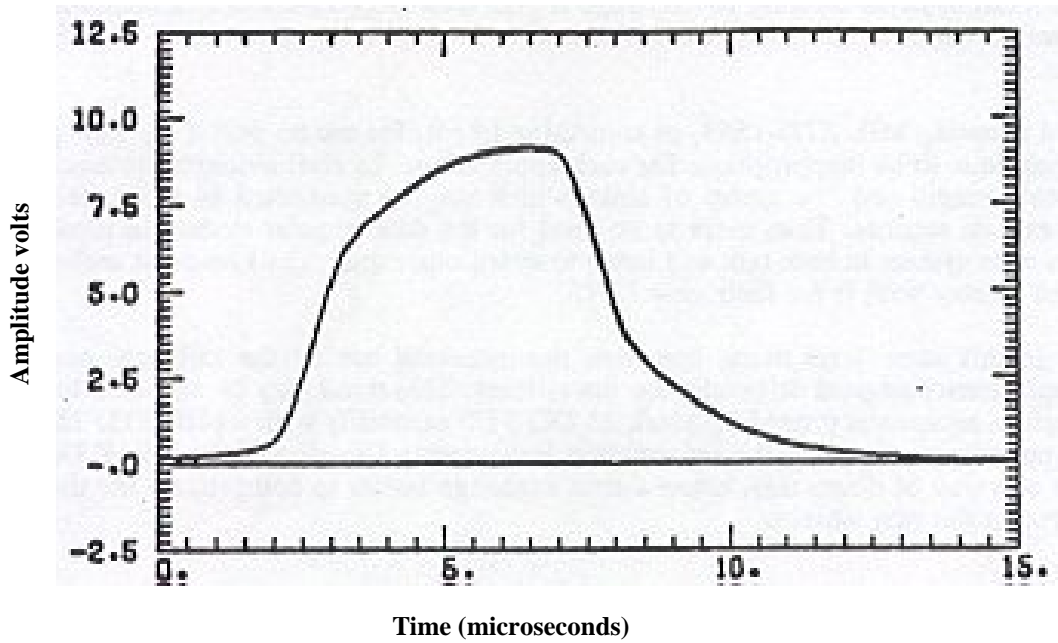
TRANSMITTER OUTPUT VOLTAGE



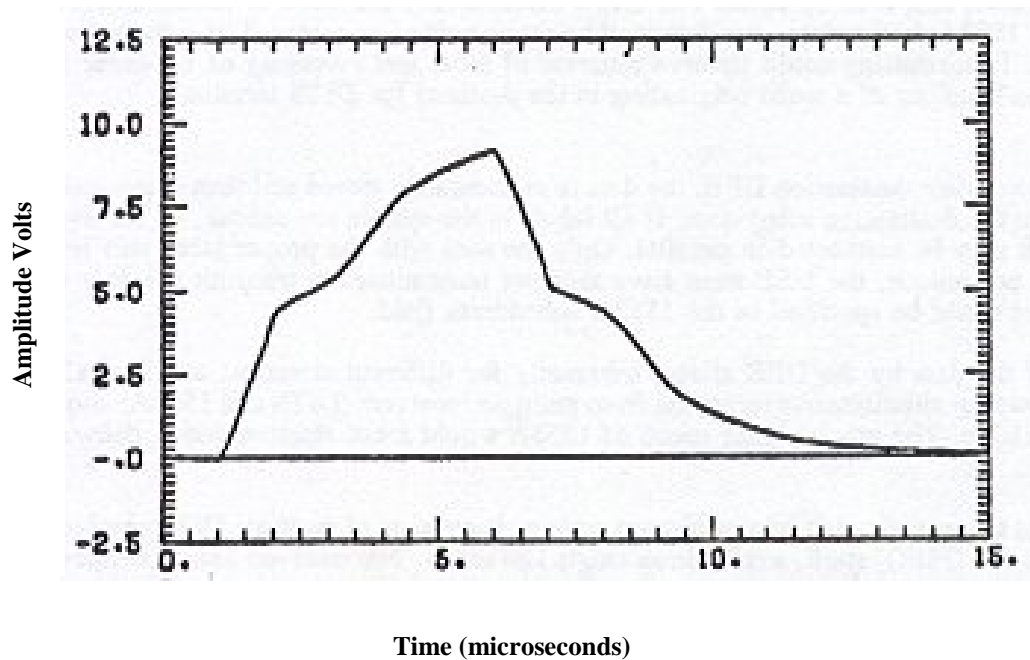
VOLTAGE AT FIRST NODE

APPENDIX A
LABORATORY VERIFICATION OF ARINC 429 DITS ELECTRICAL CHARACTERISTICS

FIGURE a-(xxix)



VOLTAGE AT RECEIVER ONE



VOLTAGE AT RECEIVER TWO

APPENDIX B

AN APPROACH TO A HYBRID BROADCAST-COMMAND/RESPONSE DATA BUS ARCHITECTURE

A2-1.0 Introduction

During the time that the broadcast approach to digital information transfer became established in the air transport industry, the military aviation community adopted a command/response time division multiplex technique as its standard. In this approach, all aircraft systems needing to exchange digital data are connected to a common bus and a dedicated "bus controller" determines which of them may output data on to the bus at any given time. MIL STD 1553 was written to describe this system.

The airlines considered adopting MIL STD 1553, or something like it, for use on post-1980 new civil aircraft types but found the multiplex technique to be inappropriate for such applications. In civil avionics systems, data typically flows from a given source to a single sink, or group of sinks which may be connected in a parallel, and these sinks are typically not themselves data sources. Thus there is no need for the data transfer system to provide the capability for every unit of every avionics system to both talk and listen to every other unit. The broadcast technique is adequate, and thus the airlines elected to stay with it for their new DITS.

Another development in this same time frame has been the increased use by the military, particularly in transport aircraft, of avionics equipment designed originally for the airlines. This trend may be expected to continue and so give rise to the need to interface equipment providing Mark 33 DITS I/O capability with a MIL STD 1553A data bus system. The material in this Appendix prepared by the Information Engineering Division of the USAF Directorate of Avionics Engineering describes one way of doing this, using a data exchange buffer to compensate for the electrical, logic and timing differences between the two systems.

A2-2.0 Suggested Mark 33 DITS/MIL STD 1553A Interface

The following is a proposed method for interfacing an avionic system employing sensors designed for any combination of ARINC Mark 33 DITS and MIL-STD-1553A. This method minimizes message related differences and compensates for electrical, logic and timing differences in a Data Exchange Buffer (DEB).

In a hybrid system such as shown in Figure b-(i), a signal may originate in either a DITS type subsystem or a 1553A subsystem and may be destined for either type of terminal. DITS data received by a DEB is momentarily stored and then retransmitted, complete with label, to the 1553A bus controller. The bus controller determines the intended destinations from the label and look-up table. For DITS destinations, the word is retransmitted, as received, to the appropriate DEB. For 1553A destinations, the data may be retransmitted as received or reformatted, as required by the destination subsystem. Reformatting could involve removal of label and reversing of bit order (MSB vs LSB first). Figure b-(ii) shows the handling of a word originating in the destined for DITS terminals.

Upon arrival at the appropriate destination DEB, the data is momentarily stored and then retransmitted in DITS format, complete with label, to the destination subsystem. If all labels in the system are unique, all receivers in all subsystems associated with a DEB may be connected in parallel. Only the data with the proper label will be recognized by each receiver. If labels are not unique, the DEB must have separate transmitters to transmit the data with identical labels. The desired transmitter could be specified in the 1553A subaddress field.

The retransmission of the data by the DEB allows inherently for different electrical and logical characteristics. The storage of the data allows for simultaneous reception from multiple receivers (DITS and 1553A) and retransmission when the desired bus is available. The much higher speed of 1553A would make retransmission delays small.

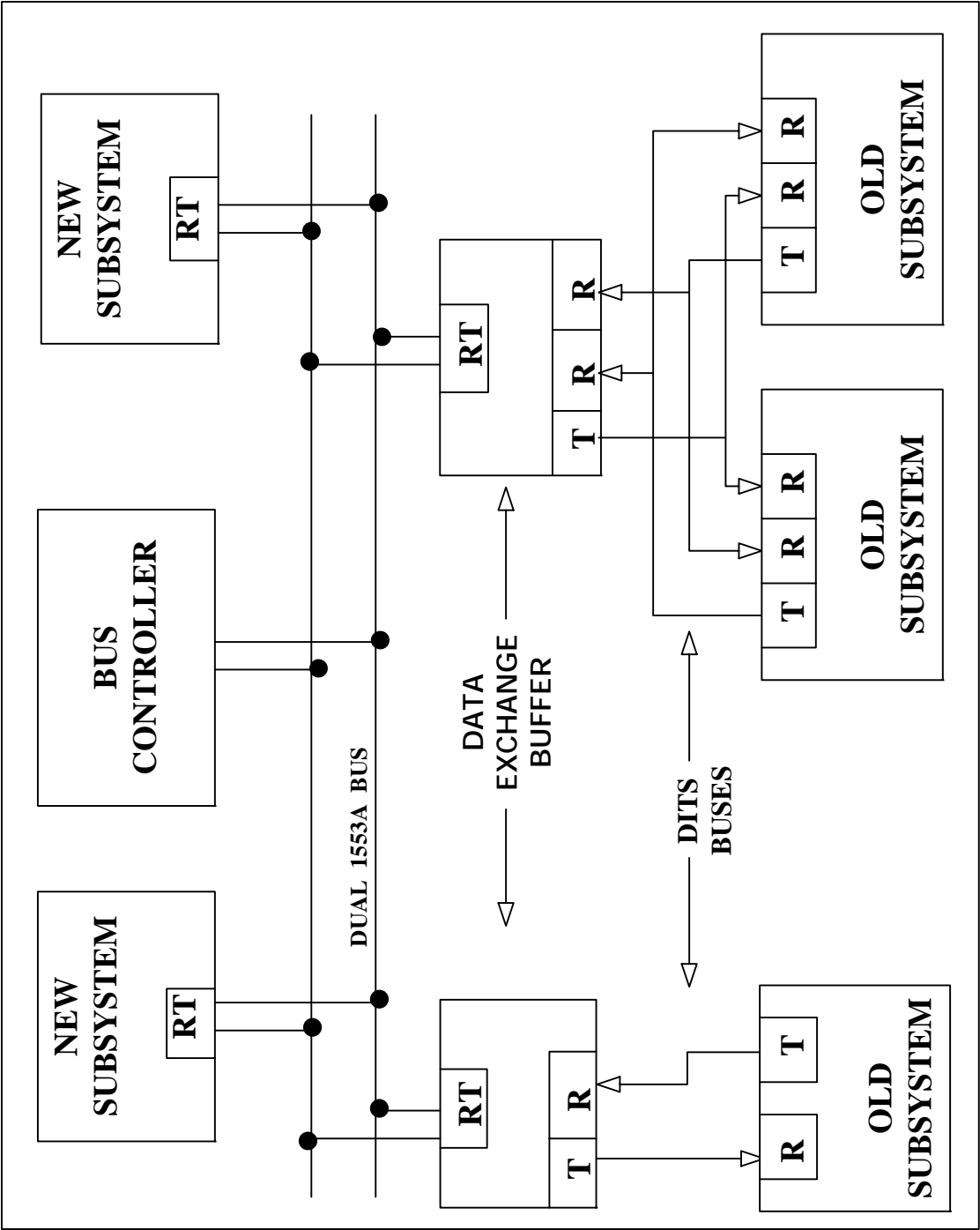
Figure b-(iii) illustrates the organization of a minimum system. It consists of multiple DITS receivers dumping received data into a first-in first-out (FIFO) stack, available as single LSI chips. The received data is temporarily stored and then retransmitted by the 1553A terminal. Data received via 1553A is dumped into another FIFO for retransmission by a DITS transmitter. The hardware consists only of DITS receivers, the 1553A terminal, the DITS transmitter, and as many FIFO's as are required. Hand-shaking signals available on the FIFO's eliminate almost all supporting SSI chips. This entire system would probably fit on one full ATR card or less.

Figure b-(iv) illustrates possible organization for a more sophisticated DEB. It consists of an many DITS transmitters and receivers as necessary, a single (internally redundant) 1553A remote terminal, a buffer memory, a controller (microprocessor), and a program for the controller contained in ROM. Whenever a complete, valid word is available at a receiver, the controller is notified. When the parallel data bus becomes available, the word is transferred to memory. When the desired transmitter (DITS or 1553A) becomes available, the data word is routed from memory to the transmitter. The low rate of DITS terminals (minimum 320 microsec/word) would result in a very low loading of the parallel bus and controller. The speed of the 1553A terminal might necessitate a direct memory access arrangement. The controller, the program memory, the buffer memory and a dual 1553A remote terminal would probably fit on one one-sided 3/4 ATR card. The required ARINC transmitters and receivers would probably fit on another card.

This method represents one way of constructing a hybrid system. The retransmission of the label with the data greatly reduces the intelligence required by the DEB but increases bus loading. A more intelligent DEB, perhaps located in the bus controller, could achieve much higher efficiencies.

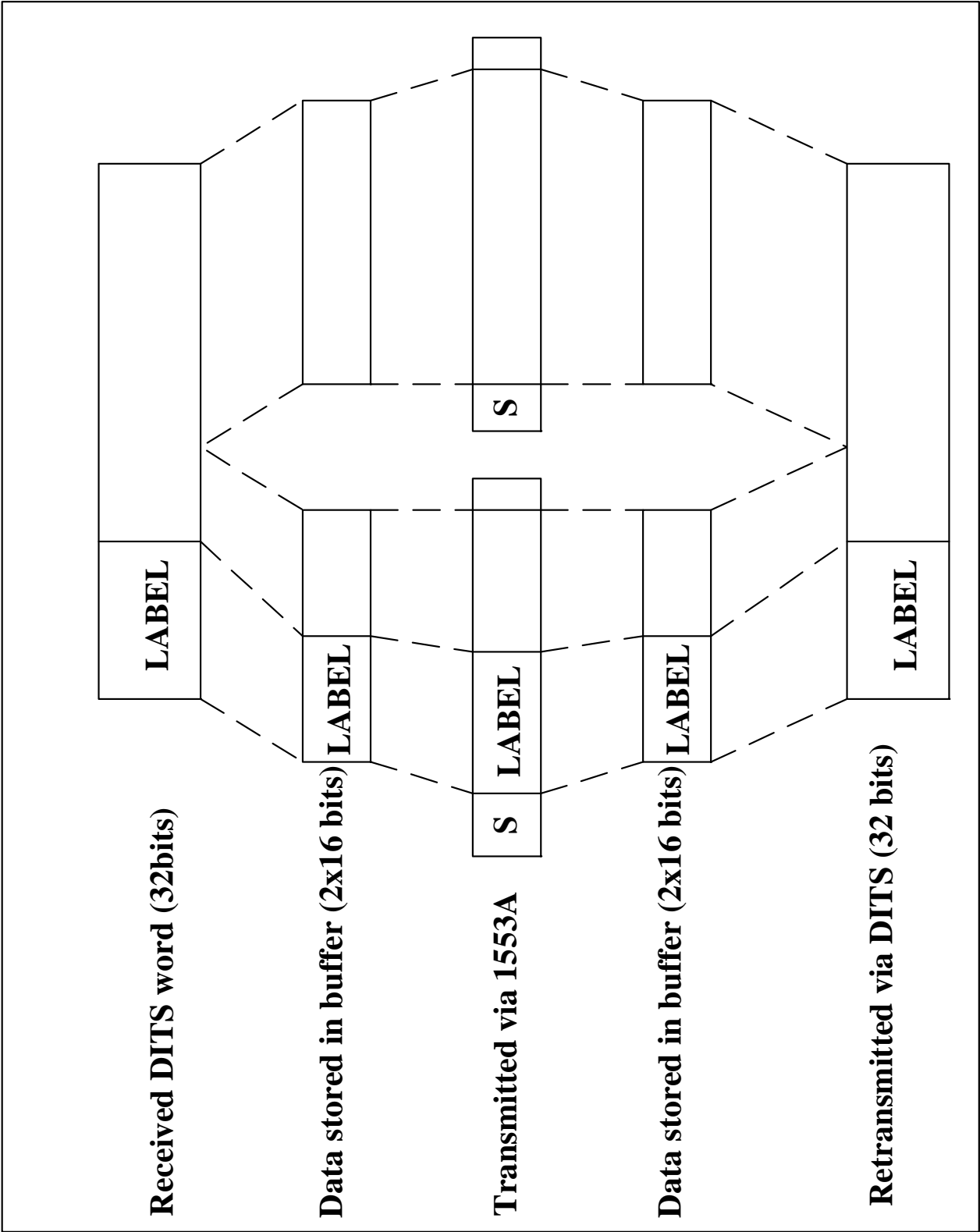
APPENDIX B
AN APPROACH TO A HYBRID BROADCAST-COMMAND/RESPONSE DATA BUS ARCHITECTURE

FIGURE b-(i)
HYBRID BUS ARCHITECTURE



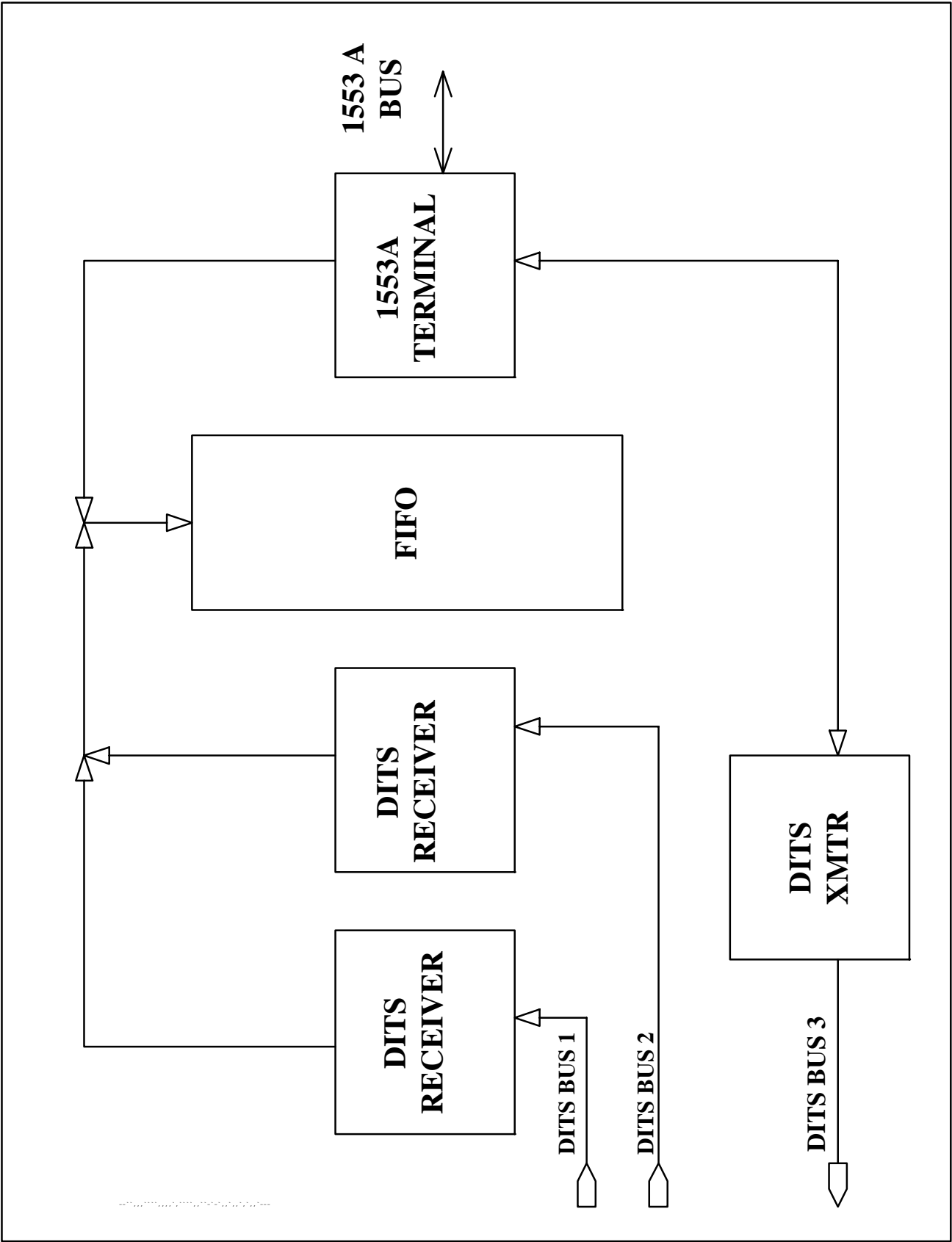
APPENDIX B
AN APPROACH TO A HYBRID BROADCAST-COMMAND/RESPONSE DATA BUS ARCHITECTURE

FIGURE b-(ii)
MESSAGE WORD FORMATTING



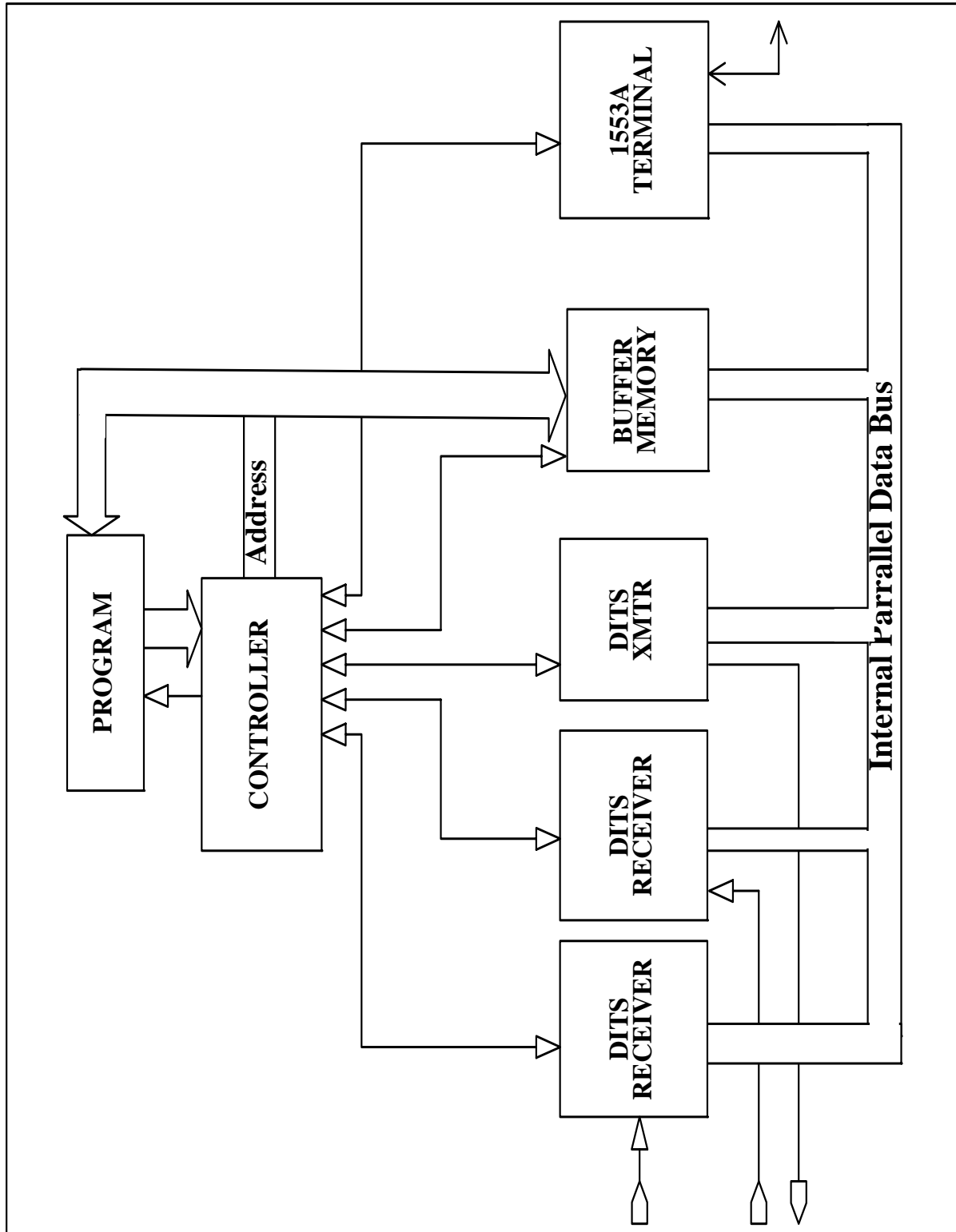
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FIGURE b-(iii)
MINIMUM DATA EXCHANGE BUFFER



APPENDIX B
AN APPROACH TO A HYBRID BROADCAST-COMMAND/RESPONSE DATA BUS ARCHITECTURE

FIGURE b-(iv)
PROGRAMMABLE DATA EXCHANGE BUFFER



Collins Avionics Divisions
400 Collins Road, NE
Cedar Rapids, Iowa, 52406
(319) 395-1000
Cable COLINRAD Cedar Rapids

**Rockwell
International**

4 May 1979

A Control System View of
ARINC 429 Bus Specifications

By
T. G. Sharpe and G. E. Forquer

Signal Degradation

- Modification Signal to Noise Ratio (MSN)
- Static Accuracy

Spectral Characteristics

- Update Interval
- Transmit Interval
- Pre-sampling Bandwidth Limit

The following discussion of these characteristics should aid the reader in understanding their purpose and assessing their adequacy. It is recognized that some changes may necessarily take place as the industry completes its digital interfacing standardization task.

I. Introduction and Summary

The discussion below summarizes concepts that have grown out of an in-house effort to determine what parameter characteristics Collins feels should be included in the data standards tables of ARINC Bus Specification 429 (DITS). The DITS specification seems to be evolving as more than merely a digital bus description since in many ways it is taking on the characteristics of a system interface specification. This raises philosophical questions concerning those characteristics, which should appear in the individual equipment specifications versus those which should appear in "429". The authors cannot resolve such partitioning questions. Hopefully we can contribute, as outlined below, to an understanding of what information is required by control systems designers to achieve an acceptable system performance. The detailed discussion in this paper evolves a set of terms (outlined below) which are usable in a specification. Which of these terms appear in the individual equipment specifications and which appear in "429" remains to be determined.

At the present time, it is suggested that control system designers interfacing with digitally based data should be concerned with three prime areas: stability considerations, signal degradation, and spectral characteristics. Without these elements of information, thorough analysis of system performance will not be possible.

The following eight parameter characteristics should prove adequate for the minimal control of interfacing considerations.

Stability

- Control Band
- Magnitude Limits
- Phase Limits

II. Stability Consideration

There is nothing uniquely digital in this area. Here our concern is with those characteristics that are most often used in linear system stability analysis – namely gain and phase characteristics. We recognize at the outset that all sensor systems are not 100% linear but this does not prevent us from defining a linear model of sufficient quality to support stability analyses. It is useful to consider here that generally the sensor will be wideband relative to the band of frequencies of interest to the control system. This is necessary from a stability point of view since the converse (that is, signals narrowband relative to the control band) would introduce excessive phase lag in the control band. Thus far we have implicitly considered both bandpass and lowpass centered at zero frequency. For simplicity, however, the discussion below will assume low pass sensor characteristics but the ideas apply generally. Figure 1 illustrates an assumed sensor characteristic.

Gain and Phase Constraints

Note that prime concerns are that the gain remain essentially constant through the control band and that the phase be bounded by a linear characteristic through the control band. From a control law stability point of view, we are not concerned with what happens at frequencies above the control band because these are beyond the range where the data is being used by the control system. If we consider open loop Bode plots broken at the sensor output, the control band as used above should be wide enough to include the phase crossover as well as the gain crossover. The phase and gain characteristics provide information about phase and gain margin degradation. For most sensors the gain crossover in typical control laws is known approximately. Phase crossover is not as easily determined. A reasonable first cut would be to define the control band as approximately ten times the open loop crossover frequency with the expectation that beyond this range control law gain is low enough to prevent gain margin

APPENDIX C

DIGITAL SYSTEMS GUIDANCE (PART 1)

APPENDIX C
DIGITAL SYSTEMS GUIDANCE (PART 1)

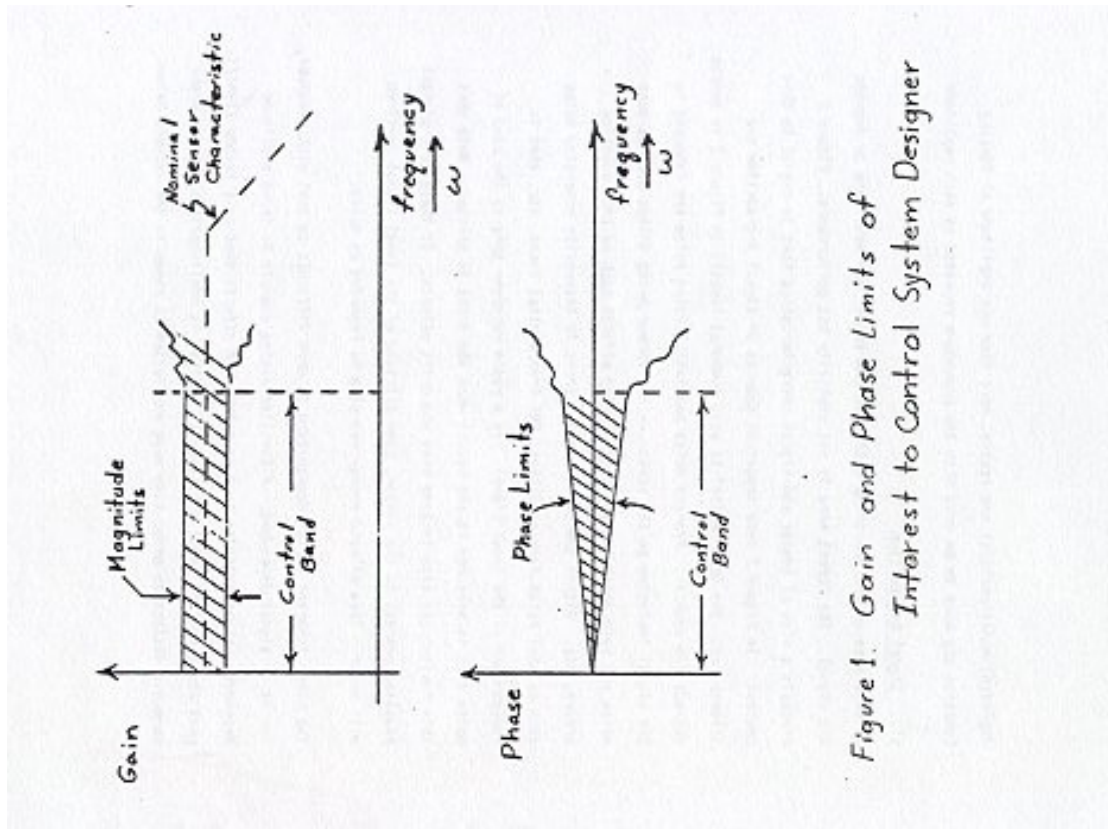


Figure 1. Gain and Phase Limits of Interest to Control System Designer

problems. However, some sensors may have trouble holding a tight gain (and phase) spec over this wide a bandwidth. Possibly in these cases a loosening of the spec between open loop crossover and ten times open loop crossover may be required. With this kind of specification a simple transport delay in combination with a gain change can be used for stability analysis or, for slightly more complex cases, simple transfer functions can be used to approximately fit the spec. The important point here is not to constrain the sensor designer to a first order or second order or any specific implementation, but to rather bound in a simple yet usable sense the stability degradation the sensor can introduce. The important stability characteristics are defined concisely below.

- **Control Band** – That band of frequencies over which magnitude and phase characteristics of the sensor are important to the control system stability.
- **Magnitude Constraint** – The bounds (envelope) on the permissible gain variation in a linear frequency response sense that are permissible over the control band.
- **Phase Constraint** – The bounds (envelope) on the permissible phase variation in a linear frequency response sense that are permissible over the control band.

APPENDIX C

DIGITAL SYSTEMS GUIDANCE (PART 1)

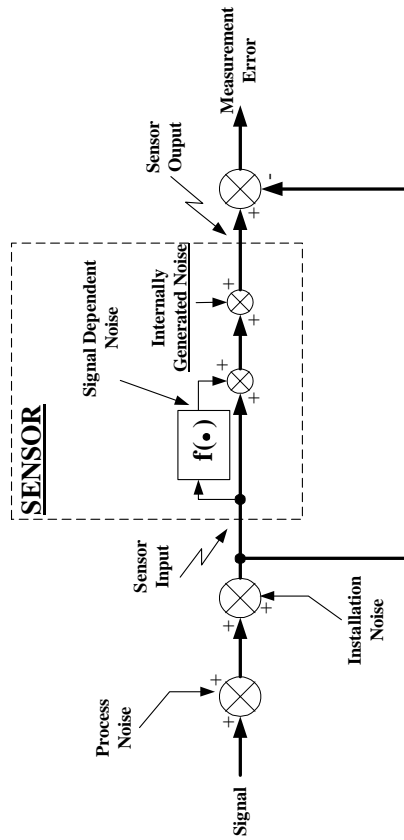
Potential Measurement Technique

These quantities could be measured by providing a sinusoidal input stimuli at selected frequencies in the control band using a mid-range amplitude. At each frequency the output component of interest (assuming some distortion) will be the output component whose frequency corresponds to the input frequency. The phase and amplitude of this component of this component relative to the forcing function will provide the magnitude and phase information. In the terminology of nonlinear system analysis, this procedure yields and empirically derived describing function for the sensor over the control band. If amplitude dependent nonlinearities are severe, more than one amplitude of forcing function may have to be used with the procedure repeated at each amplitude.

III. Signal Degradation

In this area we are concerned with what the sensor may have done to degrade the signal. The thrust here is not stability but performance. Figure 2 presents a view of sensor and signal characteristics that is useful in this context. In Figure 2 some important sources of signal degradation are illustrated. The term “noise” is used somewhat loosely in Figure 2 to denote degradation sources. Process noise and installation noise are inherent in the signal impinging on the sensor – the former being things such as gust noise and beam noise and the latter being effects such as EMI, mounting errors, etc. Within the sensor itself there is internally generated noise such as shot noise from resistors, EMI from digital buses, etc. that is independent of the input signal. In a radio receiver this is the kind of noise that is measured at the output when the input is shorted. Note that this “noise” can also include bias and drift effects. If there is a digital sampling process in the sensor, some aliasing of the input signal spectrum will occur. This aliased energy may also be regarded as noise.

The other inherent sensor degradation is more difficult to deal with, however, for it is signal dependent. A familiar analog example is input amplitude dependent characteristics such as saturation effects that only become significant above certain input amplitudes. Another is nonlinearities that produce harmonic distortion under sine wave excitation as shown in the example below.



**Figure 2. Sensor and Signal Characteristic
and Measurement Noise**

APPENDIX C

DIGITAL SYSTEMS GUIDANCE (PART 1)

Harmonic Distortion

Consider square law distortion in an otherwise linear sensor. Let the sensor output be

$$y(t) = x(t) + kx(t)^2$$

Where $x(t)$ is the sensor input and let $x(t) = \sin wt$. Then

$$y(t) = \sin wt + k \sin^2 wt$$

$$y(t) = \sin wt \pm \frac{k}{2} \mp \frac{k}{2} \cos 2wt$$

Note that d.c. and second harmonic components as well as the forcing frequency appear at the output. In digital systems a similar effect occurs when multiple rates are introduced, such as signals being received at one rate from a digital bus and being used at a different rate by a software program. If the analog signals originally sampled and put on the bus were sinusoidal at one frequency then, in general, frequency components less than and greater than the input frequency (as well as the input frequency) appear after the second sampler. The amplitude and number of these spurious outputs is a function of the two sampling rates as well as the input frequency. The net effect of all such internal sensor effects is observable by subtracting sensor input from sensor output to yield measurement error as shown in Figure 2.

Measurement Error

The involved nature of what can happen to the signal within the sensor as shown in Figure 2 is the source of ambiguity in conventional “accuracy” specs. Since measurement noise can be dependent on input amplitude as well as spectral characteristics, it is not possible to specify it with a single and simple metric. It should also be apparent that measurement error must be addressed statistically since a significant portion of the input, process noise, is only describable as a random process.¹ Technically the input signal is also in general a random processes influenced by such things as the gust striking the aircraft. Gusts also can only be described as random processes.

¹ Recognizing that a complete description of a random process includes not only probability distributions but also spectral characteristics.

To evaluate the spectral characteristics of measurement error will require tests which force the system with noise type inputs. Exponentially correlated noise of specified variance and correlation time (or bandwidth) should be sufficient in most cases. If a sensor is known to be susceptible to a specific type of noise, however, that noise should be included in the test. Often it will be useful to separate out the low frequency or d-c components of measurement error since these may be more tolerable in some applications than dynamic errors. A set of tests that will measure these characteristics is described below.

Modified Signal to Noise Ratio (MSN)

Force the sensor with random noise of specified rms value (σ) and correlation time (τ). Determine the power spectral density (PSD) of the input signal to the sensor. Determine the PSD of the measurement error. Plot the two PSD's on a common plot as shown in Figure 3. Define a modified signal to noise ratio (which will be a function of frequency) as the square root of noise ratio at each frequency of signal PSD amplitude to measurement error PSD. Note in the example shown in Figure 3 there is a bulge in the measurement error around zero frequency. This effect would indicate d-c bias and possibly low frequency bias drift from the sensor. This effect may or may not be important depending on whether the application permits washing out low frequency components, e.g. in a complementary filter. In the range of frequencies where accurate sensor response is required, it is suggested that appropriate values for the modified signal to noise (MSN) will be 100 to 1000. Roughly, these numbers correspond to noise power being 1% to .1% of signal power at each frequency or noise being 40 to 60 db down from signal. The relationship between MSD and ordinary signal to noise can be understood by assuming both signal and noise PSD's are flat over a band of frequencies Δw as shown in Figure 3. Let the value of the signal PSD in this band be S_o , then rms signal power in the band Δw is given by $\sqrt{S_o \cdot \Delta w}$. Similarly, rms error power is given by $\sqrt{P_{\Delta w} \cdot \Delta w}$. Therefore conventional signal to noise over the band w is given by $\sqrt{\frac{P_{\Delta w}}{S_o}}$. Requiring that this signal to noise be 100 is equivalent to requiring that noise power be 1% of signal power over this band. Carrying this back to the MSN implies that $MSN(w) = \sqrt{\frac{P_{\Delta w}}{S_o}} = 100$ over the band Δw . The above also represents the motivation for considering square root of the ratio than the ratio directly.

Amplitude Dependent Nonlinearities

The approach described above tests for input frequency dependent degradations by providing a realistic input spectrum. It should be realized that if there are amplitude dependent degradations, the MSN analysis will yield different answers depending on the rms value of the input noise. It is suggested that the MSN measurement be done with worst case input noise, i.e., largest rms and bandwidth

APPENDIX C DIGITAL SYSTEMS GUIDANCE (PART 1)

Potential Measurement Technique

Modified Signal to Noise (MSN) determination requires assuming a random process model for the signal impinging on the sensor. Normally an exponentially correlated signal with specified variance will be sufficient. Empirically determined power spectral densities (using discrete Fourier Transform techniques) will need to be measured for input signal as well as measurement error. Static accuracy measurement was described above.

IV. Spectral Characteristics

In this area the digital nature of the system interface must be faced squarely. The control system designer cannot alter the signal degradation introduced by

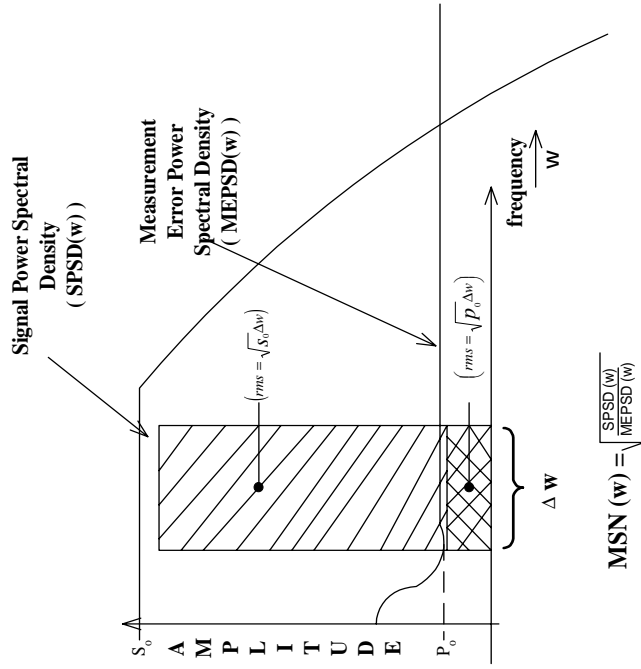


Figure 3. Modified Signal to Noise Ratio

that will be encountered. In some cases alternate MSN specs for different flight regimes may be appropriate.

In many cases a more explicit presentation of the amplitude dependent nonlinearities may be desirable. A good example here is localizer receiver linearity, specified as being linear within a given percentage up to .155 DDM, a larger percentage from .155 to .310 DDM and not decreasing between .310 and .400 DDM. Such a specification is important in defining localizer capture laws, where one can begin "using" the signal crudely before it is linear or precisely accurate. It should be noted that this is a slightly different use of sensor data than for precise state control, i.e. the control is carrying the system to a prescribed state rather than maintaining it at a prescribed state in the presence of noise. Normally the latter operation will require more accurate information from the sensor. The amplitude dependent degradations should be measured statically -- that is, one should provide a test input at specified amplitude, allow transients to settle, and measure the output value.

The important signal degradation terms are defined concisely below. Only the last two are proposed as parameter characteristics--the first three being definitions to clarify the last two.

- Measurement Error – The difference between the signal impinging on the sensor and the output representation of that signal by the sensor expressed in consistent units.
- Signal PSD (SPSD) – The power spectral density of the signal impinging on the sensor.
- Measurement Error PSD (MEPSD) – The power spectral density of measurement error introduced by the sensor.
- Modified Signal to Noise Ratio – A measure primarily of the spectral characteristics of sensor errors defined as the square root of the ratio of SPSP and MEPSD at each frequency in the control band.

$$\text{i.e., } MSN(w) = \sqrt{\frac{SPSD(w)}{MEPSD(w)}}$$

- Static Accuracy – A measure of the amplitude dependent characteristics of sensor errors defined as the difference between input and output signals after all transients have settled.

APPENDIX C

DIGITAL SYSTEMS GUIDANCE (PART 1)

Adequate roll off characteristic of the digitally based data reduces the aliasing problem of the second sampler if the second sampling is properly performed. However, not only this spectrum but also the frequency F_1 enters into the aliasing in $F_2(s)$, therefore, it is desirable also to carefully specify F_1 . This will be accomplished through the update interval. Assuming F_2 is somewhat fixed by computer speed and loading considerations, aliasing can be minimized for a given input spectrum by making F_1 as high relative to F_2 as possible.

The important spectral characteristic terms are defined concisely below.

- **Update Interval** – The cyclic time interval, as measured at the DITS bus interface, between transmissions of new freshly sensed and converted/derived values of the parameter.

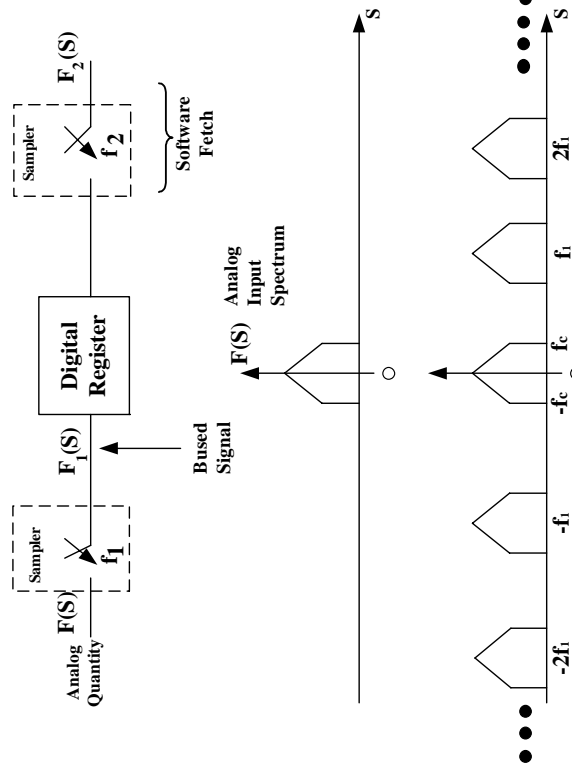


Figure 4 Analysis of Multirate Sampling

the sensor whether it be due to nonlinearities, aliasing, noise, etc. He has great potential, however, for making matters worse if he is not alert to potential aliasing problems that he may introduce. To analyze aliasing precisely he would need a precise definition of the spectrum of each signal being received on the digital bus including the update interval for each signal. A more practical approach is to place an upper bound on the received signal spectrum and then ensure downstream performance is adequate using this bound as the signal spectrum. These ideas are made more precise below.

Multirate Sampling

A simple model for signals received from a bus and used in a digital processor is shown in Figure 4. We note that the spectrum of the signal on the bus, $F_1(s)$, is an infinitely replicated version of the analog input spectrum with replicas spaced by the input sampling frequency F_1 . We cannot, therefore, speak of the bandwidth of $F_1(s)$ strictly. What we mean here is that a bound is required on each copy in $F_1(s)$. Deriving the spectrum of the signal $F_2(s)$ is beyond the scope of this discussion but a technique has been developed that will yield this spectrum, $F_2(s)$, given the quantities F_1 , F_2 , and the shape of the repeated spectrum of $F(s)$ in $F_1(s)$. There is considerable spreading of signal energy in this process with considerable "aliasing" potential even if the quantity f_c in Figure 4 is much less than the Nyquist frequency ($\frac{f_1}{2}, \frac{f_2}{2}$) for both F_1 and F_2 . The "aliasing" in the spectrum $F_2(s)$ occurs because the second sampler is not operating on a properly band limited function (see Figure 4) due to the "infinite replica" nature of the spectrum $F_2(s)$.

Deterministic Versus Random Signals

The discussion above did not specify whether the original analog quantity was a deterministic signal or a random process. For deterministic cases we deal with the Fourier transforms of the signals involved. However, as pointed out in Section III the signals of interest are really describable only in terms of random processes. For this case the development must proceed in terms of power spectral density of the signals involved. Figure 5 then illustrates the bound on based signal PSD that is envisioned. Recall that white noise through a lowpass filter yields a PSD that rolls off at 40 db/decade as shown below.

White Noise Input PSD: $U(S) = A - \infty < w < + \infty$

Filter Transfer Function: $T(jw) = \frac{1}{j\tau w + 1}$

Output PSD: $Y(S) = T(S)T^*(S)U(S)$

$$Y(w) = \frac{A}{\tau^2 w^2 + 1}$$

APPENDIX C
DIGITAL SYSTEMS GUIDANCE (PART 1)

- Transmit Interval – The cyclic time interval, as measured at the DITS bus interface, between transmissions of the parameter. Transmit Interval \leq Update Interval.
- Pre-sampling Bandwidth Limit – That bandwidth for a first order lag that will upper bound the spectral characteristics of the signal of the signal on the bus.

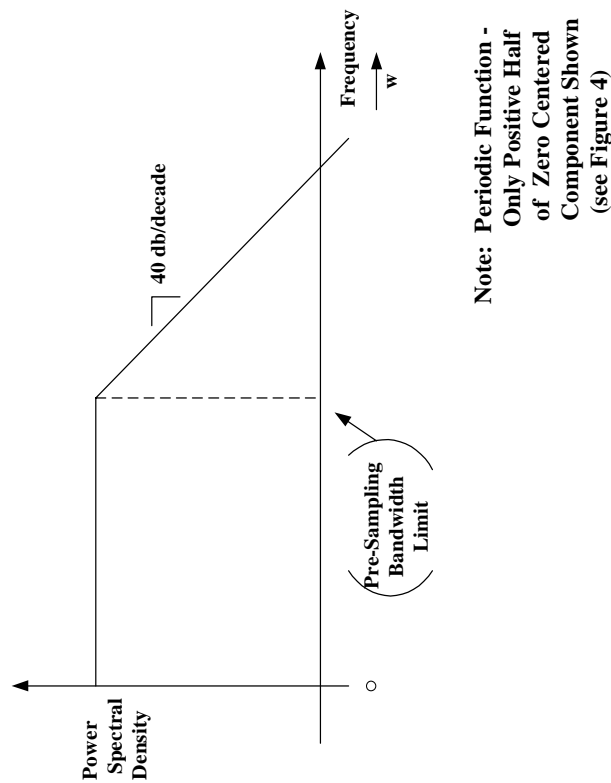


Figure 5 PSD Bound on Bused Signal

APPENDIX D
DIGITAL SYSTEMS GUIDANCE (PART 2)

Attachment to
SYST-B-8764-20-075

DESIGN PARAMETERS FOR DIGITAL AVIONIC SYSTEMS

Prepared by
Boeing Commercial Airplane Company
REVISION A

Summary

This paper explains the necessity for defining presampling filter characteristics, transport delays and minimum update rates for digital and noise characteristics are discussed. A design procedure for selecting the required filter characteristic and update rate is presented.

Introduction

The new generation of commercial aircraft will use digital technology to implement many functions, which were traditionally performed with analog hardware. These functions include inner and outer servo loops for aircraft control and guidance, processing and filtering signals from navigation and other sensors, and filtering of data prior to its display on cockpit instruments. Digital technology will also replace the majority of the formerly analog communication paths between systems, sensors, instruments and actuators.

A basic property of these and other digital systems is that they only process or transfer values of data from discrete points in time. The contrast between the discrete time nature of a digital system and the continuous time nature of an analog system is shown in Figure 1. Analog systems are said to operate in the continuous time domain while digital systems are said to operate in the discrete time domain.

In order for discrete time digital systems to be used to process or transfer the inherently continuous time data from real world physical systems, samples of the continuous data must be taken at periodic intervals. These samples from discrete points in time can then be used as the input to the discrete time digital system. It is intuitively obvious that the interval between samples affects the accuracy with which the continuous time data is represented by the discrete samples. It is also obvious that rapidly varying signals should be sampled more often than slowly varying signals in order to maintain an adequate representation of the continuous analog data. Selection of a proper sampling rate for each signal is a design task unique to digital systems. An understanding of the Sampling Theorem is necessary in order to make the proper trade offs between sampling rate, signal-to-noise ratio, signal delay, and system complexity.

BOEING COMMERCIAL AIRPLANE COMPANY
P.O. Box 3707
Seattle, Washington 98124
M/S 47-09
A Division of The Boeing Company

May 11, 1979
SYST-B8713-79-209

Mr. B. R. Climie, Chairman
Airlines Electronic Engineering Committee
Aeronautical Radio, Inc.
2551 Riva Road
Annapolis, Maryland 21401

Dear Rick:

The enclosed paper is a revised version of "Design Parameters for Digital Avionic Systems," which was originally circulated with AEEC letter 79-022/SAI-99. The revision addresses the topic of aliasing which could occur when reducing the sampling rate of a digitally encoded signal. This topic was discussed at the DITS working group meeting held on April 18 and 19.

Sincerely

AIR TRAFFIC CONTROL
AND ELECTRONIC SYSTEMS

FILED
A. F. Norwood

A. F. Norwood, Chief

AFN:
Enclosure

BOEING

APPENDIX D

DIGITAL SYSTEMS GUIDANCE (PART 2)

The Sampling Theorem

The Sampling Theorem states that a signal which contains no frequency components higher than f_0 Hertz can be exactly recovered from a set of its samples if the samples are spaced no further apart than $1/2 f_0$ seconds. This is equivalent to requiring that the sampling frequency be greater than twice the highest frequency component of the signal.

The reason for this requirement can be shown by examining the frequency spectrum of the sampler output. Modeling the sampling operation as the multiplication of the input signal by an impulse train as shown in Figure 2 allows the sampler output spectrum to be computed from a Fourier Transform identity. The required identity states that time domain multiplication is equivalent to frequency domain convolution. Therefore, the output spectrum is found by convolving the input spectrum with the spectrum of the impulse train. This relationship is shown in Figure 3. The convolution operation has the effect of reproducing the spectrum of the input signal about zero frequency and at all harmonics of the sampling frequency. If the sampling frequency, $1/T_s$, is greater than twice f_0 , the spectral components centered about the sampling frequency and its harmonics will not overlap the spectral component centered about zero frequency. Therefore, the spectral component centered about zero, which is identical to the input spectrum, can be obtained by passing the sampled output through a low pass filter with a bandwidth of f_0 Hz.

Application of the Sampling Theorem to Digital Avionics Systems

The discussion of the Sampling Theorem in the preceding section has shown that a signal which contains no frequency components higher than f_0 Hz. can be exactly represented by a series of samples spaced no further apart than $1/2 f_0$ seconds. However, signals, which represent physical quantities, such as those processed by avionic systems never satisfy the strict bandwidth limitation requirement stated above. Therefore exact reproduction of the original signal from its samples is not possible. The effect of the non-bandlimited nature of signals is to distort the replica reconstructed from the samples. The shaded area shown in Figure 4 represents typical high frequency signal energy which distorts the low frequency portion of the signal spectrum. The high frequency portion of the signal takes on the identity of the lower frequencies, hence the name "aliasing" for this phenomenon.

Aliasing becomes a greater problem when the signal is corrupted by noise, which has a wider bandwidth than the signal. When this occurs both signal energy and noise energy which is beyond one half of the sampling frequency is aliased into the low frequency portion of the recovered signal. This effect is shown in Figure 5. The signal-to-noise ratio is degraded by both noise and signal components which are aliased into the low frequency portion of the signal spectrum. The effect of aliasing can be decreased by sampling the incoming signal at a higher rate and/or using a presampling filter to reduce the bandwidth of the signal prior to sampling. Neither of these approaches can ever completely eliminate the

effect of aliasing and they each result in some negative impact on the overall system.

An increase in the sampling rate requires more computations to be done in a given period of time. This requires more computational resources, which increases the weight, complexity, and power requirements of the computer subsystems. The use of a presampling filter to limit the bandwidth prior to sampling distorts the signal. It also increases the delay experienced by signals as they propagate through the system. The increase in delay reduces phase margin if the signal is used in a closed loop control system. Therefore, more stringent delay requirements must be placed on other components in the loop if the system phase margin is to remain constant.

Design Tradeoffs for Digital Avionics Systems

The final choices of sample rate and presampling filter depend upon the input signal and noise spectra, maximum allowable signal-to-noise ratio degradation due to aliasing, maximum allowable transport delay, available computational resources, and the bandwidth of the system which uses the data. A practical way to make these choices is to analyze the system for various sample rates and filters. This can best be done with the aid of a computer program which computes the effect of each combination of sample rate and filter characteristic on the output signal-to-noise ratio for the defined input signal and noise spectra.

The initial computation is to determine the effect of the prefilter on the in-band signal-to-noise ratio without regard to aliasing effects. A typical plot of signal-to-noise ratio versus presampling filter bandwidth is shown in the top curve of Figure 6. This curve forms a baseline against which signal-to-noise ratio degradation caused by aliasing can be compared. The signal-to-noise ratio is determined by computing the input signal power and input noise power, which is passed by the selected prefilter. This parameter will generally exhibit a peak value at a specific bandwidth. The signal-to-noise ratio will decrease with increasing bandwidth as more noise is admitted and decrease with decreasing bandwidth as signal energy is eliminated.

The filter order is an important design parameter because higher order filters roll off more rapidly near the cutoff frequency. Therefore higher order filters admit less noise and signal from beyond the cutoff frequency than low order filters. Because of this characteristic, high order filters alias no more noise into the signal than slightly narrower bandwidth low order filters. However, high order filters delay the signal more than low order filters.

The ultimate objective of the design task discussed in this paper is to achieve acceptable system performance with the minimum possible

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DIGITAL SYSTEMS GUIDANCE (PART 2)

sampling rate. System performance is adversely affected by large propagation delays and high in-band noise levels.

If the maximum allowable propagation delay is given, the minimum usable filter bandwidth can be found standard plots of group delay versus frequency for the type and order of filter considered. (See for example Reference 1, page 112.) This minimum bandwidth is plotted on Figure 6 as a vertical line. The maximum achievable signal-to-noise ratio is constrained by the requirement for a presampling filter wide enough to limit delay to the given value. The intersection of the minimum bandwidth line with the top curve of Figure 6 gives the maximum achievable signal-to-noise ratio i.e., the signal-to-noise ratio which would be achieved by an unsampled system.

Sampling rate is chosen by comparing the maximum acceptable degradation in signal-to-noise ratio to the actual aliasing degradation due to sampling at the candidate rates. For the example shown in Figure 6, a sampling rate of 50Hz would be chosen.

A system interface which meets prescribed limits on signal delay and maximum noise due to aliasing can be designed using the procedures outlined above. Some systems which use sampled data, such as closed loop control systems, have a bandwidth which is much smaller than that of the sampling filter. For this reason it is important to verify that the signal and noise power which is aliased into the frequency band of interest is well below the inherent noise in that band.

This can be accomplished by constructing a signal and noise power spectral density plot for the filter and sampling rate chosen. The power spectral density plot is most easily obtained with the aid of a computer program. A typical plot of this type is shown in Figure 7. The example power spectral densities in Figure 7 show that the aliased signal and noise is much lower than the inherent noise level in the frequency range of interest. If this constraint is not met a different combination of filter and sampling frequency must be chosen.

In some situations it may be desired to reduce the sampling rate of a digitally encoded signal. This may be done where wideband digital data is used to drive an instrument or subsystem which responds only to narrower bandwidth data. Simple deletion of unwanted samples to reduce the sampling rate can cause aliasing problems similar to those encountered when sampling an analog signal at an insufficient rate. The aliasing can be elimination of the unwanted samples. Design of the digital filter is subject to the same set of delay versus aliasing noise tradeoffs as the design of an analog presampling filter.

Conclusion

The procedures outlined in this paper can be used to choose the presampling filter and sampling rate required for interfaces to a digital signal processing or control system. The values are chosen to meet the constraints of maximum allowable delay and maximum allowable noise

due to aliasing. Signal and noise spectra of the signal to be sampled must be supplied as an input to the design procedure.

Reference: Herman J. Blinchikoff and Anatol I. Zverev, Filtering in the Time and Frequency Domains, John Wiley and Sons, New York.

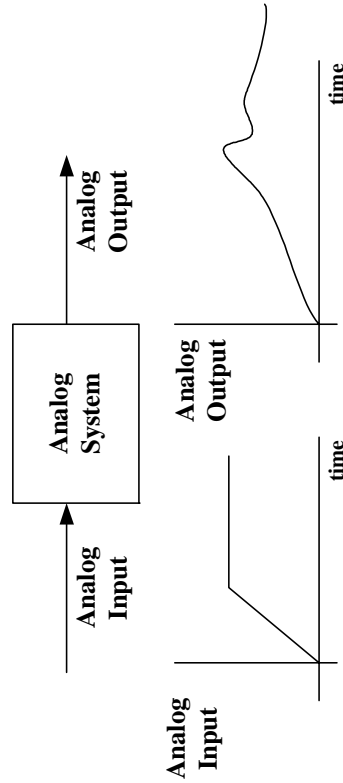


Figure 1(a) Typical Input and Output of Analog System

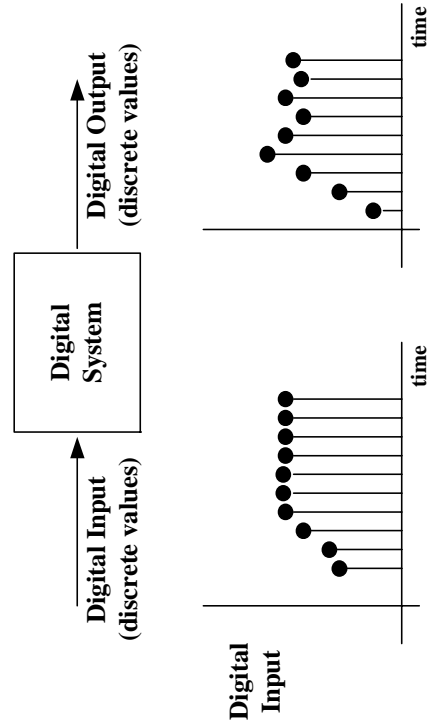


Figure 1(b) Typical Input and Output of Digital System

APPENDIX D
DIGITAL SYSTEMS GUIDANCE (PART 2)

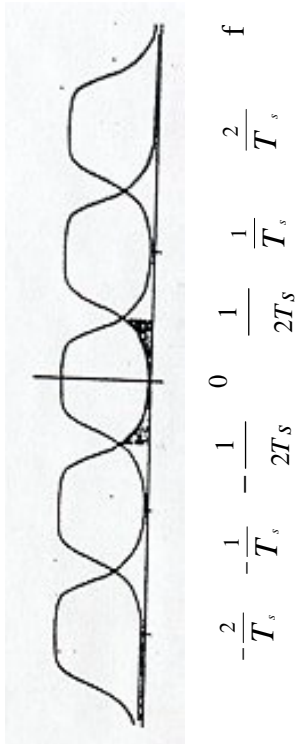


Figure 4 Sampler Output Spectrum When Input Signal Bandwidth is not Limited to One-Half of the Sampling Frequency

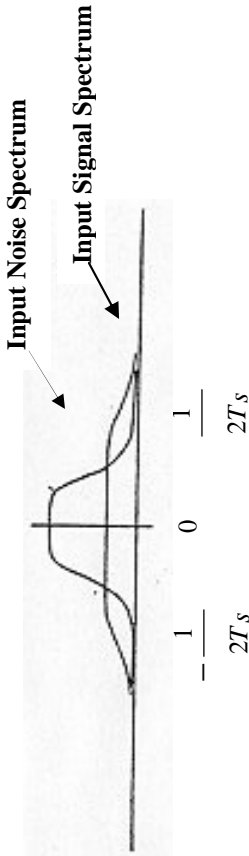


Figure 5(a) Input Signal and Noise Spectra

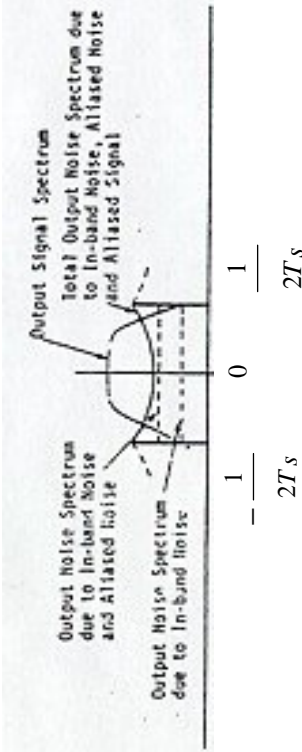


Figure 5(b) Output Signal and Noise Spectra Showing Signal-to-Noise Ratio Degradation Due to Aliasing of Signal and Noise

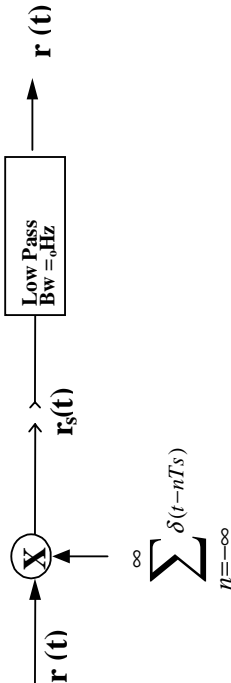


Figure 2 Mathematical Model of Sampling Process

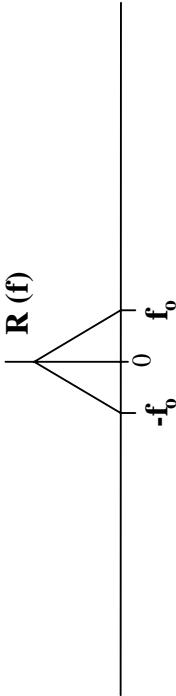


Figure 3(b) Spectrum of f(t) Bandlimited to f₀ Hz

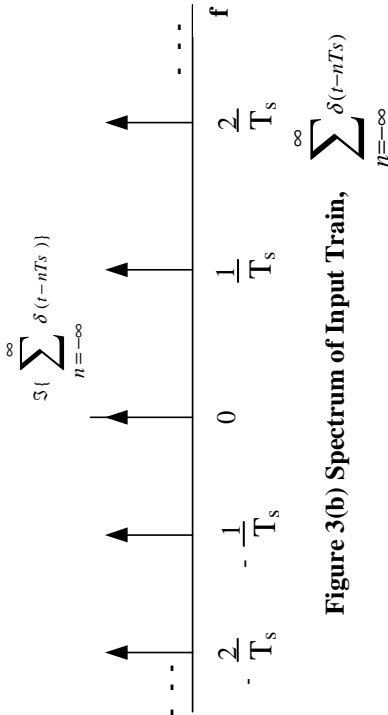


Figure 3(b) Spectrum of Input Train,

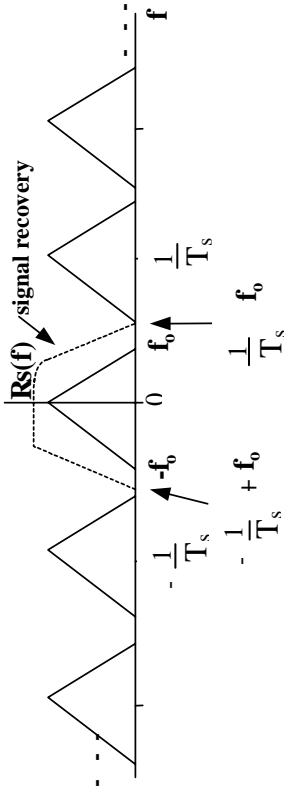


Figure 3(c) Spectrum of Sampling Output

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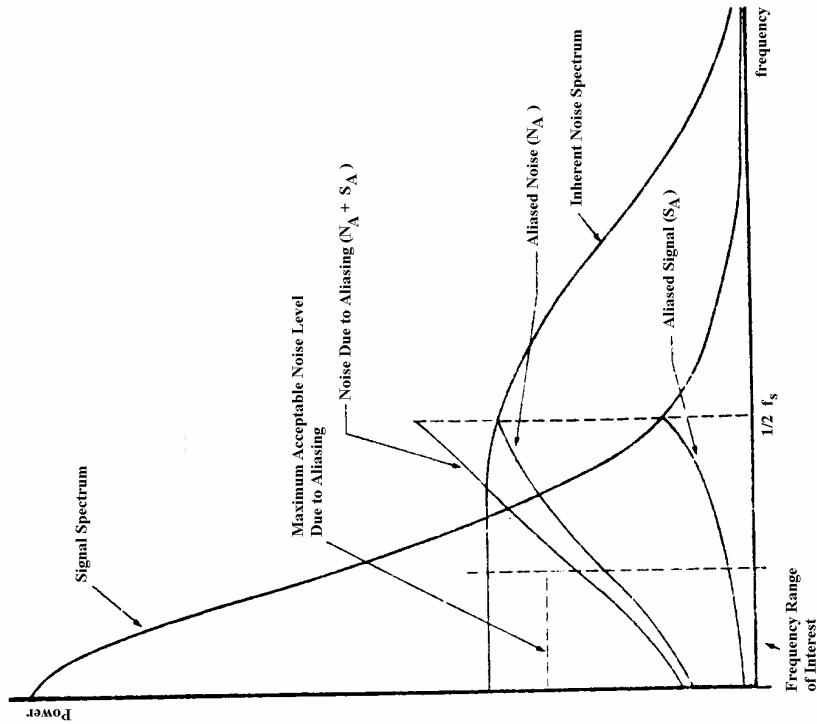


FIGURE 7 Sample Plot of Signal and Noise Power Spectral Densities

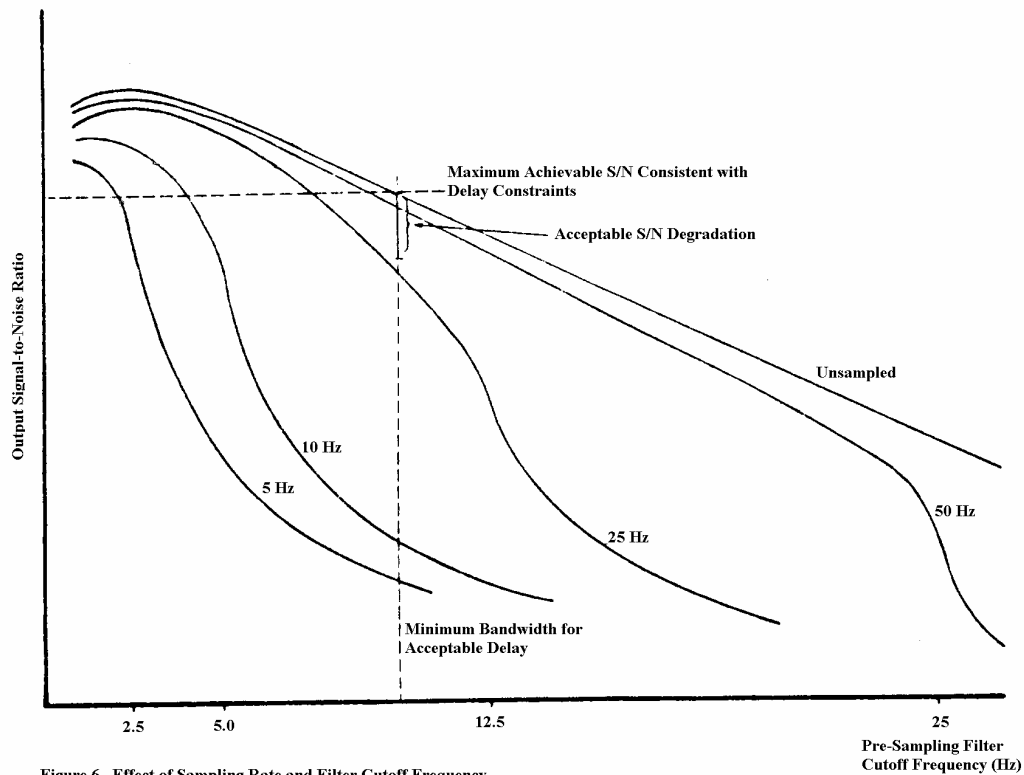


Figure 6 Effect of Sampling Rate and Filter Cutoff Frequency on Output Signal-to-Noise Ratio

APPENDIX E
GUIDELINES FOR LABEL ASSIGNMENTS

The ARINC 429 data bus was developed to provide a standardized means of digital information transfer between the “ARINC 700” series of avionics units. ARINC 429 has proven to be a very flexible standard and its usage has extended to provide data transfer between Line Replaceable Units (LRU) which are not otherwise covered by ARINC Characteristics. It is important that each new usage of ARINC 429 be coordinated and indexed by ARINC such that the information on usage (label allocation, data format, etc.) is available industry-wide. The use of the same label for two different functions on a particular LRU type built by different manufacturers can create serious problems.

To facilitate the coordination of ARINC 429 label usage between the industry and the ARINC staff, a set of guidelines is provided.

- c-17

1.

New labels should be selected from the five character field as defined in Section 2.3 (three octal and three hexadecimal).
- c-17

2.

The following labels have special significance and should not be used: label 000 (not used) and label 377 (equipment identification). The preferred SSM encoding for method for the Equipment Identification Word (label 377) is according to the Discrete word guidelines. When this label was originally assigned, it was recognized as a non-BNR word. The SSM encoding was according to the BCD and DISC guidelines that were identical at that time. During development of Supplement 4, the SSM for DISC was revised to its current form to provide enhanced failure warning. When the SSM encoding was changed, some systems retained the BCD encoding for the Equipment Identification word and others changed to DISC encoding.

- c-16

3.

The following labels are presently “spare” and should only be used for new parameters which may have very widespread usage throughout the airplane architecture.

005	040	050	054	107	163	227	371
006	046	051	055	113	167	240	
007	047	052	057	124	226	243	

- c-16

4.

Where possible, similar word usage should be “grouped”; for example, if Engine N 1 is to be provided from a new unit (PMUX) it should utilize label 246 which is presently N 1 (engine direct).
- c-16

5.

Where possible, grouped usage should have identical data specification (units, range, significant digits/bits, positive sense, resolution, min--max transmit interval). To facilitate this commonality it is permissible for a particular LRU to output a lower resolution signal (fewer significant digits/bits) if the least significant remainder of the data field is set to zeros.
- c-16

6.

Where word grouping is not possible, the labels should be selected from the following subgroups:

Binary coded decimal (BCD) sub-group 001 to 067, 125, 165, 170, 200, 201, 230 to 237.

Binary (BNR) subgroup 070 to 124, 126 to 144, 150 to 154, 162 to 164, 166, 167, 171 to 177, 202 to 227, 240 to 257, 262 to 265, 267, 310 to 347, 360 to 376.

Mixed BCD and BNR subgroup 260, 261

Discretes subgroup 145 to 147, 270 to 276

Maintenance and discrete data subgroup 155, 156

Maintenance data subgroup 157 to 161, 350 to 354

Test word subgroup 266, 277

Application dependent subgroups 300 to 307

Acknowledgement subgroup 355

Maintenance ISO #5 subgroup 356

ISO #5 message subgroup 357

A schematic of these subgroups is attached.

APPENDIX X

CHRONOLOGY & BIBLIOGRAPHY

X-1.0 Chronology

AEEC established the Systems Architecture and Interfaces (SAI) Subcommittee in 1975 to develop the air transport industry's approach to digital avionics systems architecture, to define digital system interface standards. With respect to this last-named, the Subcommittee soon determined that the industry's previous approaches to digital information transfer, described in ARINC Specification 419, "Digital Data System Compendium", needed rationalization and modernization to be applicable in the future digital systems world. However, this work was not started immediately because of the need to concentrate on the more basic tasks related to digital systems architecture.

About a year later, AEEC deemed it timely to start the spec-writing for a digital automatic flight control system based on the system architecture concepts developed by the SAI Subcommittee. The Subcommittee AEEC established to do this began its work in January 1977. Part of this activity was the definition of black box interface standards, and this brought into sharp focus the need for the new digital information transfer system to be properly specified.

The SAI Subcommittee immediately began to devote time to the discussion of the issues involved to give direction to the Digital Information Transfer System (DITS) working group it set up to develop a spec draft. This group met early in April 1977, and produced a draft which the full Subcommittee reviewed at its meeting in May. A second working group meeting during the period of that Subcommittee meeting, followed by a third in mid-June, produced the second draft of the spec. This draft was submitted to AEEC for adoption, which was achieved at the Summer 1977 General Session in July.

The spec adopted by AEEC contained details of numeric data (BNR and BCD) transfer only. The SAI Subcommittee notified AEEC of its intent to broaden the scope of the document to cover alpha/numeric (ISO Alphabet No. 5) and graphic data handling also. These subjects would be addressed in a Supplement to the spec which AEEC would be asked to approve at a later date.

X-2.0 Bibliography

The following is a list of AEEC letters associated with the preparation of ARINC Specification 429. A list of AEEC letters related the SAI Subcommittee's overall activities may be found in ARINC Report 299, "AEEC Letter Index".

<u>AEEC Letter No.</u>	<u>Date</u>	<u>Subject</u>
76-130/SAI-20	Dec. 9, 1976	Report of the Systems Architecture and Interfaces Subcommittee Meeting held November 16th, 17th and 18th, 1976 in Seattle, Washington
77-009/SAI-22	Jan. 27, 1977	Whither On-Board Digital Data Transmission Standards?
77-020/SAI-25	Feb. 11, 1977	More On Digital Data Transmission Standards
N77-035/SAI-26	Mar. 21, 1977	Boeing Report On Alternative Digital Information System Signalling Standards
77-037/SAI-28	Mar. 25, 1977	Report of the Systems Architecture and Interfaces Subcommittee Meeting Held March 7th, 8th and 9th, 1977 in Arlington, Virginia
77-047/SAI-33	Apr. 13, 1977	Circulation of Draft No. I of Project Paper 429, "Mark 33 Digital Information Transfer System (DITS)"
77-056/SAI-37	Apr. 18, 1977	Report of the SAI Subcommittee BITS Working Group Meeting Held April 5-6, 1977, in Annapolis, Maryland
77-066/SAI-41	Jun. 8, 1977	Report of the Systems Architecture and Interfaces Subcommittee Meeting Held May 9th, 10th and 11th, 1977 in Los Angeles, California
77-079/SAI-46	Jun. 23, 1977	Circulation of Draft No. 2 of Project paper 429, "Mark 33 Digital Information Transfer System (DITS)"

X-3.0 Meeting Attendees

The following people comprised the SAI Subcommittee's Digital Information Transfer System Working Group.

Tom Ellison	UNITED AIRLINES	San Francisco, California
Wolfgang Bull	DEUTSCHE LUFTHANSA	Hamburg, Germany
Siegmar Gomille	DEUTSCHE LUFTHANSA	Hamburg, Germany

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CHRONOLOGY & BIBLIOGRAPHY

Jim Wahlen
 Tony Martin
 Frank Rasmussen
 Ed Schroeder
 Arvind Dandekar
 Bill Harts
 David Lewis
 Ralph Bazil
 Hal Pierson
 Bob Clark
 Capt. Russ Glastetter
 David Featherstone

BENDIX AVIONICS
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 COLLINS RADIO, ROCKWELL INT.
 COLLINS RADIO, ROCKWELL INT.
 DELCO ELECTRONICS
 KING RADIO CORPORATION
 MITRE CORPORATION
 SPERRY FLIGHT SYSTEMS
 USAF
 AERONAUTICAL RADIO, INC.

Ft. Lauderdale, Florida
 Seattle, Washington
 Seattle, Washington
 Seattle, Washington
 Cedar Rapids, Iowa
 Cedar Rapids, Iowa
 Milwaukee, Wisconsin
 Olathe, Kansas
 McLean, Virginia
 Phoenix, Arizona
 Dayton, Ohio
 Annapolis, Maryland

The following people attended one or more of the SAI Subcommittee meetings held November 16th-18th, 1976, March 7th-9th, 1977 and May 9th-11th, 1977, during which the 429 DITS spec drafts and other proposals produced by the DITS working group were reviewed, refined and finalized.

Airlines and ARINC Staff

T. A. Ellison, Chairman
 J. S. Davidson
 Gerard Collin
 Jean Baptiste Rigaudias
 Jean Le Luc
 Clarence L. Richmond
 Robert M. Cook
 Jose M. Recacha
 P. Lorie
 Ludwig Kilchert
 Norton Codish
 Vic Persson
 Karl H. Riesen
 T. E. Jackson
 L. R. Berryhill
 M. W. Brecht
 O. R. Evans
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Manufacturers and Others

Bernard E. Bouet
 Jean Tambareau
 Russell Fine
 William M. Russell III
 S. R. Sporn
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 Jean Francois Ferreri
 Jay J. Ahmann
 T. H. Hitt
 Brendan J. Spratt
 William C. Thompson
 James C. Whalen
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 Ken Kendall
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 Ft. Lauderdale, Florida
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 Tukwila, Washington
 Teterboro, New Jersey
 Teterboro, New Jersey
 Teterboro, New Jersey
 Teterboro, New Jersey
 Lakewood, California

APPENDIX X

CHRONOLOGY & BIBLIOGRAPHY

Dwayne Broderson	BOEING COMMERCIAL AIRPLANE	Seattle, Washington
James R. Fries	BOEING COMMERCIAL AIRPLANE	Seattle, Washington
R. F. Gorman	BOEING COMMERCIAL AIRPLANE	Seattle, Washington
Anthony J. Martin	BOEING COMMERCIAL AIRPLANE	Seattle, Washington
J. McHutchison	BOEING COMMERCIAL AIRPLANE	Seattle, Washington
Richard A. Peal	BOEING COMMERCIAL AIRPLANE	Seattle, Washington
Frank A. Rasmussen	BOEING COMMERCIAL AIRPLANE	Seattle, Washington
Irving R. Reese	BOEING COMMERCIAL AIRPLANE	Seattle, Washington
E. T. Schroeder	BOEING COMMERCIAL AIRPLANE	Seattle, Washington
V. J. Small	BOEING COMMERCIAL AIRPLANE	Seattle, Washington
Robert W. Sutton	BOEING COMMERCIAL AIRPLANE	Seattle, Washington
Ray Hillman	BRITISH AEROSPACE	Surrey, England
Richard A. Keall	BRITISH AEROSPACE	Hatfield, England
Donald J. Gussin	CANADIAN MARCONI CO.	Montreal, Canada
Arvind J. Dandekar	COLLINS RADIO GROUP	Cedar Rapids, Iowa
R. V. Donaldson	COLLINS RADIO GROUP	Cedar Rapids, Iowa
J. C. Hall	COLLINS RADIO GROUP	Cedar Rapids, Iowa
Bryand C. Hawkins	COLLINS RADIO GROUP	Cedar Rapids, Iowa
Eugene C. Machacer	COLLINS RADIO GROUP	Cedar Rapids, Iowa
Donald H. Wickenkamp	COLLINS RADIO GROUP	Cedar Rapids, Iowa
John F. Lent	CROUZET	Pasadena, California
Michel Pascal	CROUZET	Valence, France
Richard A. Johnson	DELCO ELECTRONICS DIV. GMC	Milwaukee, Wisconsin
L. David Lewis	DELCO ELECTRONICS DIV. GMC	Milwaukee, Wisconsin
John H. Sheldrick	DELCO ELECTRONICS DIV. GMC	Milwaukee, Wisconsin
Tom Sizlo	DOUGLAS AIRCRAFT COMPANY	Long Beach, California
John Carter	E-A INDUSTRIAL CORP.	Chamblee, California
David Burton	ELDEC CORPORATION	Lynnwood, California
Roy F. Keating	ELDEC CORPORATION	Lynnwood, California
Rene Plouhinec	ELECTRONIQUE MARCEL DASSAULT	Saint Cloud, France
John E. Reed	FAA	Washington, D.C.
Charles Sheets	GARRETT CORP.	Torrance, California
Robert E. Weir	GARRETT AIREASEARCH	Torrance, California
Richard Haley	HAMILTON STANDARD	Windsor Locks, Connecticut
S. C. Caliendo	HAWKER SIDDELEY AVIATION	Hatfield, Herts, England
Harry Graves	HONEYWELL INC.	Minneapolis, Minnesota
Ronald G. Raymond	HONEYWELL INC.	St. Louis Park, Minnesota
Claude P. Roquefeuil	ISPENA	Paris, France
Jack Hawkins	ITT CANNON ELECTRIC	Santa Ana, California
J. Langenback	ITT CANNON ELECTRIC	Santa Ana, California
Ray Swanson	JAEGER	Pasadena, California
Ken Berg	KING RADIO CORP	Olathe, Kansas
David A. Nelson	KING RADIO CORP	Olathe, Kansas
John C. Cotton	LITTON AERO PRODUCTS	Woodland Hills, California
L. J. Singleton	LITTON AERO PRODUCTS	Woodland Hills, California
P. H. Weinheimer	LITTON AERO PRODUCTS	Seattle, Washington
William R. Beckman	LOCKHEED CALIFORNIA CO	Burbank, California
Job Van Der Blik	LOCKHEED CALIFORNIA CO	Burbank, California
Wm. J. Hillman	LOCKHEED CALIFORNIA CO	Burbank, California
Ed Selvig	LOCKHEED CALIFORNIA CO	Burbank, California
Barry J. Aldridge	MARCONI ELLIOTT AVIONICS	Rochester Kent, UK
Gordon Belcher	MARCONI ELLIOTT AVIONICS	Rochester Kent, UK
Derek Marshall	MARCONI ELLIOTT AVIONICS	Seattle, Washington
Karl-Heinz Terheiden	MESSERSCHMITT-BLOKOW-BLOHM	Hamburg, Germany
Harold L. Pierson	MITRE CORPORATION	McLean, Virginia
Richard W. Telsch	MITRE CORPORATION	McLean, Virginia
Gary C. Horan	PRATT & WHITNEY AIRCRAFT	East Hartford, Connecticut
G. A. Lucchi	RCA	Van Nuys, California
Gerard A. Collin	SAGEM	Paris, France
Lloret	SAGEM	Paris, France
Jean-Yves Begeault	SFENA	Velizy-Villacoublay, France
Jefferson Z. Amacker	SINGER KEARFOTT	Little Falls, New Jersey
Joseph Koprowski	SINGER KEARFOTT	Little Falls, New Jersey
John Desmond	SMITHS INDUSTRIES INC.	Clearwater, Florida
Dave Richardson	SMITHS INDUSTRIES INC.	Clearwater, Florida

APPENDIX X
CHRONOLOGY & BIBLIOGRAPHY

Brian Williams	SMITHS INDUSTRIES INC.	Cheltenham, Glos, UK
Mike C. Pietromonaco	S. P. INC	Bellevue, Washington
Donald Baker	SPERRY FLIGHT SYSTEMS	Phoenix, Arizona
Don Burkholder	SPERRY FLIGHT SYSTEMS	Phoenix, Arizona
Jack E. Emfinger	SPERRY FLIGHT SYSTEMS	Phoenix, Arizona
D. A. Few	SPERRY FLIGHT SYSTEMS	Phoenix, Arizona
Martin S. Klemes	SPERRY FLIGHT SYSTEMS	Phoenix, Arizona
R. J. Lofquist	SPERRY FLIGHT SYSTEMS	Phoenix, Arizona
Harry Miller	SPERRY FLIGHT SYSTEMS	Phoenix, Arizona
Ronald H. Neeves	SPERRY FLIGHT SYSTEMS	Phoenix, Arizona
Edmond Olive	SPERRY FLIGHT SYSTEMS	Phoenix, Arizona
R. E. Schaffer	SPERRY FLIGHT SYSTEMS	Phoenix, Arizona
Harry O. Smith	SPERRY FLIGHT SYSTEMS	Phoenix, Arizona
Al J. Venancio	SPERRY FLIGHT SYSTEMS	Phoenix, Arizona
Lou Borbely	SUNSTRAND DATA CONTROL	Redmond, Washington
Glenn H. Jones	SUNSTRAND DATA CONTROL	Redmond, Washington
Robert Schaeperkoetter	SUNSTRAND DATA CONTROL	Redmond, Washington
C. A. Bennet	TELEDYNE CONTROLS EI	Segundo, California
H. E. Sutherland	TELEDYNE CONTROLS EI	Segundo, California
D. A. Giroux	THOMSON-CSF	Les-Moulineaux, France
Charles Legrand	THOMSON-CSF	Les-Moulineaux, France
J. Ribiere	THOMSON-CSF	Malakoff, France
J. Lane Ware	THOMSON-CSF	New York, New York
William Donnell	TRACOR APPLIED TECHNOLOGY	Austin, Texas
R. R. Fay	TRACOR APPLIED TECHNOLOGY	Austin, Texas
Jean-Pierre Tomasi	TRT	Le Plessis-Robinson, France
Blaine C. Ferch	USAF	Wright Patterson AFB, Ohio
Erwin C. Gangi	USAF	Dayton, Ohio
Capt. R. A. Glastetter	USAF	Wright Patterson AFB, Ohio

AERONAUTICAL RADIO, INC.
2551 Riva Road
Annapolis, Maryland 21401- 7645 USA

SUPPLEMENT 1
TO
ARINC SPECIFICATION 429
MARK 33 DIGITAL INFORMATION TRANSFER SYSTEM (DITS)

Published: June 1, 1978

Prepared by the Airlines Electronic Engineering Committee
Adopted by the Airlines Electronic Engineering Committee: April 11, 1978

A. PURPOSE OF THIS SUPPLEMENT

This Supplement adds to Specification 429 material related to the transfer of graphic and ISO alphabet No. 5 encoded alpha/numeric data by the Mark 33 DITS. Also, it clarifies the purpose of the SDI function, adds BCD and BNR numeric data encoding examples to Attachment 6 and introduces two Appendices into the Specification.

B. ORGANIZATION OF THIS SUPPLEMENT

The first part of this document, printed on goldenrod paper, contains descriptions of the changes introduced into the Specification by this Supplement, and, where appropriate, extracts from the original text for comparison purposes. The second part consists of replacement white pages for the Specification, modified to reflect these changes. The modified and added material on each replacement page is identified with "c-1" symbols in the margins. Existing copies of Specification 429 may be updated by simply inserting the replacement white pages where necessary and destroying the pages they replace. The goldenrod pages should be inserted inside the rear cover of the Specification.

Copies of the Specification bearing the number 429-1 already contain this Supplement and thus do not require revisions by the reader.

C. CHANGES TO SPECIFICATION 429 INTRODUCED BY THIS SUPPLEMENT

This section presents a complete tabulation of the changes and additions to the Specification introduced by this Supplement. Each change or addition is identified by the section number and title currently employed in the Specification, or by the section number and title that will be employed when the Supplement is eventually incorporated. In each case there is included a brief description of the addition or change and, for other than very minor revisions, any text originally contained in the Specification is reproduced for reference.

1.3.2 ISO Alphabet No. 5 Data Transfer

Existing text supplemented – no other changes.

1.3.3 Graphic Data Transfer

New section added by this Supplement.

2.1.2 Information Element

COMMENTARY

revised to improved clarity of opening sentence, and to modify the statement concerning the BCD-encoding of latitude and longitude as a consequence of the clarification of the use priorities for bit nos. 9 and 10 introduced into Section 2.1.4 by this Supplement.

ORIGINAL TEXT FOLLOWS

To permit the use of common hardware elements for the transmission of BNR and BCD numeric data, the format for the Mark 33 DITS BCD word differs from that used formerly for this type of data. Bit no. 32 is assigned to parity, bit nos. 31 and 30 to the sign/status matrix, bit no. 29 is the most significant bit of the data field, and the maximum decimal value of the most significant character is 7. Previously, the BCD word contained no parity bit, the sign/status matrix occupied bit nos. 32 and 31, bit no. 30 was the most significant data bit and the maximum decimal value of the most significant character was 3. This format made the word 8-bit byte oriented with respect to the data. This characteristic is not retained in the Mark 33 system.

Also, the Mark 33 BCD word will not accommodate latitude and longitude to the formerly specified resolution of 0.1 minute of arc. If BCD transmission of these quantities is required, either the resolution must be decreased or the word must be restructured. Restructuring involves limiting the maximum decimal value of the most significant character to 1, moving the remaining BCD characters towards the MSB by two bit positions and using bit nos. 9 and 10 for data instead of reserving them for source/destination identification encoding per Section 2.1.4 of this document. It is probable, however, that future latitude and longitude displays will not be the simple, dedicated read-out type for which BCD data is intended. More likely is the use of some form of multiple-message display, such as a CRT, which will be backed by its own data processor and prefer inputs of BNR data. If this proves to be the case, there will be no problem!

2.1.3 Information Identifier

Text expanded to explain differing roles of label codes in numeric (BCD/BNR) and alpha/numeric (ISO Alphabet No. 5) data transfer. "Special Note" added.

ORIGINAL TEXT FOLLOWS

The first eight bits of each word are assigned to a label function so that the data contained in the word may be identified. Label code assignments are set forth in the table of Attachment 1 to this document.

2.1.4 Source/Destination Identifier

Section modified to indicate that bit nos. 9 & 10 are not available for the SDI function in DITS words employed for graphic and ISO Alphabet No. 5 data transfer, or in BNR/BCD words in which bit nos. 9 and 10 are needed for valid data in order to achieve the desired resolution. Code table revised and function application more fully described. Consequential revisions to Commentary.

ORIGINAL TEXT FOLLOWS

Bit nos. 9 & 10 of the word should be reserved for a data source/destination identification function. This function may find application when specific words need to be directed to a specific system of a multi-system installation or when the source system of a multi-system installation needs to be recognizable from the word content. When the source/destination identifier function is used, bit nos. 9 & 10 should be encoded as follows. When it is not used, binary zeros or valid data should be transmitted in these positions

Bit No.		System
10	9	
0	0	1
0	1	2
1	0	3
1	1	4

COMMENTARY

In many applications of the Mark 33 DITS, data source/destination identification will not be needed. In these cases, bits 9 & 10 will be used as pad bits for valid data. In certain other applications of the system, for example, BCD latitude and longitude encoding (if needed – see Commentary following Section 2.1.2 of this document), the need to use bit nos. 9 and 10 to obtain adequate data resolution will preclude source/destination identification in this way.

Note that this document does not address the practical question of how these bits will be set in those multi-system installations in which the source/destination identification function is desired. One way would be to use program pins on individual system black boxes which would be wired to set up the appropriate code. The ARINC Characteristics devoted to the individual systems will define the method actually to be used.

2.1.5 Sign/Status Matrix

Section divided into two sub-sections, one to describe the BCD numeric and ISO Alphabet #5 alpha/numeric data sign status matrix, and the other to describe the BNR numeric data sign/status matrix.

ORIGINAL TEXT FOLLOWS

The “sign” (plus, minus, north, south, etc.) of the transmitted data and the status of the transmitter hardware should be encoded in bit nos. 30 and 31 as shown in the table below.

Bit No.		Designation	
31	30	BNR/BCD Data	ISO # 5 Data
0	0	Plus, North, East	TBD
0	1	No Computed Data	
1	0	Functional Test	
1	1	Minus, South, West, Left, From	

Notes:

1. A source system should indicate failure by ceasing to supply data to a bus.
2. Both bits should be “zero” in BNR and BCD words when no sign is needed.
3. The “no computed data” code should be generated when computed data is not available for reasons other than equipment failure.
4. When it appears in a word identified by its label as a system output, the “functional test” code should be interpreted as advice that the data in the word results from the execution of a functional test. When it appears in a word identified by its label as an instruction, e.g., a radio channel change command, this code should be interpreted as a command to perform a functional test.

2.1.6 Data Standards

Typographical errors corrected in second paragraph of Commentary.

2.2.1 Transmission System Interconnect

Existing material supplemented with information concerning shield grounding.

2.2.3.2 Receiver Voltage Levels

DC levels between terminal A and ground and terminal B and ground at which receivers should not be damaged raised from +20VDC to +28VDC (min) and for –20VDC to –28VDC (min) respectively to align numerical values with aircraft DC power supply value.

2.3.1.3 ISO Alphabet No. 5 Data

New section added by this Supplement.

2.4.1 Bit Rate

Existing commentary supplemented with warning against selection of 13.6 KBPS and 100 KBPS because of possible interference with operation of OMEGA and LORAN C system on the aircraft.

Attachment 2: Data Standards Tables 1 and 2

Column heading “MIN TRANSMIT INTERVAL msec” changed to “MAX TRANSMIT INTERVAL msec” in each case.

Attachment 2: Data Standards Table 3

Table 3 (Alpha/Numeric (ISO Alphabet No. 5) Data Standards) deleted. Table 4 (Discrete Data) renumbered Table 3.

Note: Table 3 was reserved for alpha/numeric (ISO Alphabet No. 5) data standards prior to the preparation of this Supplement. The need for it disappeared as a result of the particular approach selected for handling this data introduced into Specification 429 by this Supplement.

Attachment 6: General Word Formats and Encoding Examples

BNR word format example amended as consequence of change to sign/status matrix (see Section 2.1.5) General Word Formats for ISO Alphabet No. 5 data added. Encoding examples added.

Appendix 1: Laboratory Verification of ARINC 429 DITS Electrical Characteristics

New material added by this Supplement.

Appendix 2: An Approach to a Hybrid Broadcast Command/Response Data Bus Architecture.

New material added by this Supplement.

NOTE: Due to the large number of changes
Created by this Supplement, it is NOT
available separately to update 429-1.

AERONAUTICAL RADIO, INC.
2551 Riva Road
Annapolis, Maryland 21401- 7645 USA

SUPPLEMENT 2
TO
ARINC SPECIFICATION 429
MARK 33 DIGITAL INFORMATION TRANSFER SYSTEM (DITS)

Published: March 1, 1979

A. PURPOSE OF THIS SUPPLEMENT

This Supplement amends the material added to Specification 429 on ISO Alphabet No. 5 data transfer, and expands the multiple-word DITS message concept first used in this application to cover Discrete, Acknowledgement and Maintenance (ISO Alphabet No. 5 and discrete data formats) information transfer as well. The Application Notes of Chapter 3 of the Specification are amended to bring them into line with adopted practice in the control of DME's and ATC transponders, and supplemented with material related to the multiple-word message applications of the system just mentioned. Also, additions and modifications have been made to the label codes and data standards in Attachments 1 and 2 of the Specification to bring them into line with adopted practice.

B. ORGANIZATION OF THIS SUPPLEMENT

The first part of this document, printed on goldenrod paper, contains descriptions of the changes introduced into the Specification by this Supplement, and, where appropriate, extracts from the original test for comparison purposes. The second part consists of replacement white pages for the Specification, modified to reflect these changes. The modified and added material on each replacement page is identified with "c-2" symbols in the margins. Existing copies of Specification 429 may be updated by simply inserting the replacement white pages where necessary and destroying the pages they replace. The goldenrod pages should be inserted inside the rear cover of the Specification.

Copies of the Specification bearing the number 429-2 already contain this Supplement and thus do not require revisions by the reader.

C. CHANGES TO SPECIFICATION 429 INTRODUCED BY THIS SUPPLEMENT

This section presents a complete tabulation of the changes and additions to the Specification introduced by this Supplement. Each change or addition is entitled by the section number and title currently employed in the Specification, or by the section number and title that will be employed when the Supplement is eventually incorporated. In each case there is included a brief description of the addition or change and, for other than very minor revisions, any text originally contained in the Specification is reproduced for reference.

2.1.2 INFORMATION ELEMENT

Text revised to describe word application groups.

ORIGINAL TEXT FOLLOWS:

2.1.2 Information Element

The basic information element is a digital word containing 32 bits. Word formats for the different types of data handled by the Mark 33 DITS (see Section 2.3.1 of this document) are depicted in Attachment 6. When less than the full data field is needed to accommodate the information conveyed in a word in the desired manner, the unused bit positions should be filled with binary zeros or valid data pad bits. If valid data bits are

used, the resolution possible for the information will exceed that called for in this specification. The Commentary following Section 2.1.6 of this document refers.

2.1.3 INFORMATION IDENTIFIER

Text revised to describe label use for AIM/Discrete/Maintenance data word type identification.

ORIGINAL TEXT FOLLOWS:

2.1.3 Information Identifier

The first eight bits of each word are assigned to a label function. Labels will a) identify the information contained within numeric (BCD/BNR) data words (e.g., DME distance, static air temperature), and b) act as receiving device addresses for alpha/numeric (ISO Alphabet No. 5) data words (e.g., navigation system CDU or map display). Label code assignments are set forth in Attachment 1 to this document.

2.1.5.1 BCD NUMERIC AND AIM DATA WORDS

Title and text revised to include other AIM applications in material originally prepared to describe sign/status matrix use in ISO Alphabet No. 5 words, and to provide definition of Self-Test.

ORIGINAL TEXT FOLLOWS:

2.1.5.1 BCD Numeric and ISO Alphabet No. 5 Data Words

The sign (plus, minus, north, south, etc.) of BCD numeric data, the word type of alpha/numeric (ISO alphabet No. 5) data and the status of the transmitter hardware should be encoded in bit nos. 30 and 31 of the word as shown in the table below.

Bit No.		Designation	
31	30	BNR/BCD Data	ISO #5 Data
0	0	Plus, North, East Right, to	Initial Word
0	1	No Computed Data	No Computed Data
1	0	Functional Test	Intermediate Word
1	1	Minus, South, West Left, From	Final Word

Notes:

1. A source system should annunciate any detected failure that causes one or more of the words normally output by that system to be unreliable by ceasing to supply the affected word or words to the data bus.
2. Both bits should be "zero" when no sign is needed.
3. The "no computed data" code should be generated when computed data is not available for reasons other than equipment failure.

4. When it appears in a word identified by its label as a system output, the “functional test” code should be interpreted as advice that the data in the word results from the execution of a functional test. When it appears in a word identified by its label as an instruction, e.g., a radio channel change command, this code should be interpreted as a command to perform a functional test.
5. See Section 2.3.1.3 of this document for definitions of the terms “Initial Word”, “Intermediate Word” and “Final Word”.

2.1.5.2 BNR NUMERIC DATA WORDS

Text revised to provide definition of Self-Test.

ORIGINAL TEXT FOLLOWS:

2.1.5.2 BNR Numeric Data Words

The sign (plus, minus, north, south, etc.) of BNR numeric data words and the status of the transmitter hardware should be encoded in bit nos. 29, 30 and 31 of the word as shown in the table below.

Bit No.			Designation BNR Data
31	30	29	
0	0	0	Failure Warning/Plus, North, East Right, To
0	0	1	Failure Warning/Minus, South, West, Left, From
0	1	0	No Computed Data
1	0	0	Functional Test/Plus, North, East, Right, To
1	0	1	Functional Test/Minus, South, West Left, From
1	1	0	Normal Operation/Plus, North, East, Right, To
1	1	1	Normal Operation/Minus, South West, Left, From
0	1	1	Not Used (Growth)

Notes:

1. A source system should annunciate any detected failure that causes one or more of the words normally output by that system to be unreliable by setting bit nos. 30 and 31 in the affected word(s) to the “failure warning” code defined above. Words containing this code should continue to be supplied to the data bus during the failure condition.
2. Bit no. 29 should be “zero” when no sign is needed.
3. The “no computed data” code should be generated when computed data is not available for reasons other than equipment failure.
4. When it appears in a word identified by its label as a system output, the “functional test” code should be interpreted as advice that the data in the word results from the execution of a functional test. A self-test should produce indications of 1/8 of positive full-scale values unless indicated otherwise in an ARINC Equipment Characteristic.

5. If, during the execution of a functional test, a source system detects a failure which causes one or more of the words normally output by that system to be unreliable, it should immediately change the states of bit nos. 30 and 31 in the annunciation is replaced with the “failure warning” annunciation

2.2.3.1 TRANSMITTER VOLTAGE LEVELS

Tolerances on “HI” and “LO” voltage states changed from ± 0.5 volt to ± 1.0 volt to correct previously undetected error.

2.3.1.2 DISCRETES

Minor changes to existing wording to improve clarity. New paragraphs added to describe two types of dedicated –to-discrete words and their applications.

ORIGINAL TEXT FOLLOWS:

2.3.1.2 Discretes

In addition to handling numeric data as specified above, the Mark 33 DITS should also be capable of accommodating discrete items of information, either in the “spare” bits of data words or, when necessary, in dedicated words. Any discrete information contained in a word assigned a label in Attachment 1 is specified in the definition for that word in Attachment 2.

The rule to be followed in the assignment of bits to discrete functions is to start with the least significant bit available in the word and to continue towards the most significant bit. Attachment 6 shows this against the background of the generalized word structure.

2.3.1.3 Maintenance Data (General Purpose)

This section inserted to describe use and application of general purpose Maintenance words.

ORIGINAL TEXT FOLLOWS:

2.3.1.3 Alpha/Numeric (ISO Alphabet No. 5) Data

ISO Alphabet No. 5 alpha/numeric data will consist of seven-bit characters encoded per the table of Attachment 5 to this document. Three such characters should occupy bit nos. 9 through 29 of a DITS 32-bit word, as shown in the general word format diagram in Attachment 6. As for numeric (BCD) data words, bit nos. 1 through 8 should be the word label (receiving device address-see Section 2.1.3), bit nos. 30 and 31 the sign/status matrix and bit no. 32 the word parity bit.

The typical alpha/numeric message contains more than three ISO Alphabet No. 5 characters, necessitating the transmission of multi-DITS-word messages. The following procedure should be used to permit receivers to determine that such messages are received in their entirety, with no words having been “lost along the way”. Only when this determination has been made, and the parity check for each word shows the data to be error-free, should the message be displayed to the aircrew or otherwise utilized.

2.3.1.3 Alpha/Numeric (ISO Alphabet No. 5) Data (cont'd)

The first DITS word of the message should contain the label in bit nos. 1 through 8, two numeric characters encoded per ISO Alphabet No. 5 in bit nos. 9 through 15 and 16 through 22 and the ISO Alphabet No. 5 control character "STX" in bit nos. 23 through 29. The two numeric characters should indicate the decimal number of DITS words in the message (maximum number is 99), with the most significant character occupying bit nos. 16 through 22. This count, which should include this initial word, will be one plus the next whole number greater than one third of the number of ISO Alphabet No. 5 characters to be transmitted. The sign/status matrix should contain the "initial word" code defined in Section 2.1.5 of this document.

The subsequent DITS words of the message should each contain the label in bit nos. 1 through 8 and three ISO Alphabet No. 5 characters. The sign/status matrix of all these words except the last word should contain the "intermediate word" code defined in Section 2.1.5.1 of this document. The last word of the message should contain the "final word" code in its sign/status matrix. Any unused bit positions in the final word resulting from the number of ISO characters in the message being one or two less than a number wholly divisible by three should be filled with binary "zeros".

2.3.1.4 AIM Data

Section number, text and title revised to include other AIM word applications in material originally prepared to describe ISO Alphabet No. 5 data handling (originally in Section 2.3.1.3). Detailed amendments in this area also.

3.1.4.2 DME

The "Override" switching function has been replaced by the "DME Mode Select" function.

3.1.4.7 ATC TRANSPONDER

"Mode A/B Select" and "Standby" deleted from list of switching functions. Control word format re-structured to release bits unneeded in numeric data part of word for assignment to discrete switching functions.

Fig. 3-1 Radio Systems Management Word Formats

Bit nos. 11 and 12 in the DME data word have been assigned to "DME Mode Select".

The description of bit 14 in the VOR/ILS data word has been revised to improve clarity.

ORIGINAL TEXT FOLLOWS:

- [1] When bit no. 4 is "zero", the ILS mode should be "off. When bit no 14 is "one", the ILS mode should be "one".

ORIGINAL ATC TRANSPONDER WORD FORMAT ILLUSTRATION FOLLOWS:

ATC TRANSPONDER	PARITY (odd)	SIGN/STATUS MATRIX																	A/B Mode Select				RESERVED (SDI)	LABEL Beacon Transponder Code										
			0.7 (3)			0.7 (6)				0.7 (2)				0.7 (0)				IDENT	STANDBY	ALT. REP. OFF														
			32	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13		12	11	10	9	8	7	6	5	4	3	2
Bit No. Example	0	0 0	0 1 1	0 1 1 0	0 0 1 1	0 0 0 0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	1	0	1	1	0	0	0	
																			[1]															

[1]

Bit	Zero	One
11	Alt. Rep. ON	Alt. Rep. OFF
12	Standby OFF	Standby ON
13	Ident OFF	Ident ON
14	Select Mode A	Select Mode B

The revised format of the ATC transponder word is as shown on page 10.

3.2 AIM Information Transfer

New section added by this Supplement.

Attachment 1: Label codes

Some parameter names have been changed and others have been added to the list. Instead of showing the entire list, only the original assignment of those that have been changed are shown below.

<u>Label (Octal)</u>	<u>Original Assignment</u>	<u>Proposed Assignment</u>
007	Align Status/Inertial Discretes	No assignment
014	None assigned	Magnetic Heading
015	None assigned	Wind Speed
016	None assigned	Wind Direction-True
017	None assigned	Selected Runway Heading
024	Selected Course	Selected Course #1
027	None assigned	Selected Course #2
041	None assigned	Set Latitude
042	None assigned	Set Longitude
043	None assigned	Set Magnetic Heading
044	None assigned	True heading
045	None assigned	Minimum Airspeed
100	Selected Course	Selected Course #1
107	AFS Discretes	No assignment
110	None assigned	Selected Course #2
112	None assigned	Selected EPR or N ₁
124	FMC Discretes	Caution & Warning DFDR Discretes #1
130	None assigned	Tt2
131	None assigned	Pt2
132	None assigned	Pt7
133	None assigned	Thrust Lever Angle
145	None assigned	AFS DFDR Discretes #1
146	None assigned	AFS DFDR Discretes #2
147	None assigned	AFS DFDR Discretes #3
166	None assigned	RALT Check Point Dev.
203	Altitude (29.92)	Altitude (1013.25mb)
204	Altitude (Baro)	Baro Corrected Altitude #1
214	Air Data Computer Discretes	No assignment
216	Baroset	No assignment
220	None assigned	Baro Corrected Altitude #2
221	None assigned	Indicated Angle of Attack
223	Altitude (29.92)	No assignment
224	Altitude Baro	Caution/Warning DFDR Discretes #2
225	Mach	No assignment
226	Computed Airspeed	No assignment
227	Max Allowable Airspeed	No assignment
234	Baroset (millibars)	Baro Correction (mb #1)
235	Baroset (ins. of Hg)	Baro Correction (mb #1)
236	None assigned	Baro Correction (mb #2)
237	None assigned	Baro Corrected (in of Hg #2)
241	None assigned	Corrected Angle of Attack
242	None assigned	Total Pressure
245	None assigned	Minimum Airspeed
247	None assigned	Total Fuel
270	None assigned	Discrete Data #1
271	None assigned	Discrete Data #2
272	None assigned	Discrete Data #3
273	None assigned	Discrete Data #4
274	None assigned	Discrete Data #5
334	Free Heading	Platform Heading
340	N ₁ or EPR Actual	EPR Actual
346	None assigned	N ₁ Actual
350	Engine Discretes	Maintenance Data #1
351	Control Panel Discretes	Maintenance Data #2
352	Control Panel Discretes	Maintenance Data #3
353	Control Panel Discretes	Maintenance Data #4
354	Instrument Discretes	Maintenance Data #5
355	None assigned	Acknowledgement
356	None assigned	Maintenance ISO #5 Message
357	None assigned	ISO #5 Message
360	None assigned	Potential Vertical Speed
372	None assigned	Wind Direction-Magnetic
373	None assigned	N-S Velocity-Magnetic
374	None assigned	E-W Velocity-Magnetic
375	None assigned	Along Heading Acceleration
376	None assigned	Cross Heading Acceleration

Attachment 2: Data Standards

A number of additions and changes have been made to the tables. The octal labels and parameter names are shown for each data item that has been changed. The original data is shown only for the data that has been changed by this supplement. Also a second "Note" has been added to Table 2.

Table 1 BCD DATA

Label (Octal)	Parameter Name	Max Transmit Interval	Range (Scale)	Sig. Fig.	Pad Fig.	Units	Resol
170	Decision Hgt Sel.(EFI)	200	0 - 500	3	2	Feet	1.0
201	DME Distance	200*	-1 - 399.99*	5	0	N.M.	0.01
230	True Airspeed	500*	130 - 599*	3	2	Knots	1.0
231	Total Air Temp.	500	+500 — 99*	2	3	o _c	1.0
233	Static Air Temp.	500	-99 - +60*	2	3	o _c	1.0
234	Baroset (mb)*	200*	0 - 3999*	4*	1*	mb	1.0*
235	Baroset (ins. of Hg*)	200*	0 - 39.99*	4*	1*	ins.Hg	0.01*

*This data has been changed.

Note: Labels 017, 027, 041, 042, 043, 044, 045, 236 and 237 previously had no values assigned. Values for labels 223, 224, 225, 226 and 227 have been changed.

Table 2 BNR DATA

Label (Octal)	Parameter Name	Max Transmit Interval	Sig. Bits (Not Inc. Sign)	Units	Range	Approx. Resol.
100	Selected Course	62.5*	9	Deg/180	± 180 °	0.35°
103	Selected Airspeed	62.5*	11*	Deg/180	± 180 °	0.25*
121	Horiz. Strg. Signal	100	9*	Deg/180	+45° *	0.1 ° *
122	Vert.Strg.Signal	100	9	Deg/180	+22.50 ° *	0.05 ° *
140	Flight Director-Roll	62.5*	9	Deg/180	±45 °	0.1 °
141	Flight Director-Pitch	62.5*	9	Deg/180	± 22.5	0.05 °
164	Radio Height	50	18*	Feet	32768*	0.125
202	DME Distance	200*	16	N.M.	512	0.0008
203	Altitude (29.92)	62.5	17*	Feet	131,071	1.0*
206	Computed Airspeed	125	12*	Knots	1024	0.25*
207	Max.Allowable Airspeed	500*	12	Knots	1024	0.25
210	True Airspeed	500*	11	Knots	2048	1.0
215	Impact Pressure	125	12*	ins/Hg*	32*	0.008*
313	Track Angle True	50*	12	Deg/180	± 180 °	0.05 °
314	True Heading	50*	12	Deg/180	± 180 °	0.05 °
317	Track Angle-Magnetic	50*	12	Deg/180	± 180 °	0.05 °
320	Magnetic Heading	50*	12	Deg/180	± 180 °	0.05 °
321	Drift Angle	50*	11	Deg/180	+90 °	0.05 °
322	Flight Path Angle	50*	10	Deg/180	± 45 °	0.05 °
323	Flight Path Acceleration	20	12*	g	4*	0.001*
324	Pitch Angle	50*	13	Deg/180	+90 °	0.01 °
325	Roll Angle	50*	14	Deg/180	± 180 °	0.01 °
331	Body Long-accel.	6.25*	12	g	4	0.001
334	Free Heading	20*	12*	Deg/180	± 180 °	0.05 °
335	Track Angle Rate	*	*	*	*	*
336	Inertial Pitch Rate	20	12*	Deg/sec	128	0.03 ° *
337	Inertial Roll Rate	20	12*	Deg/sec	128	0.03 ° *
340	N ₁ Actual *	200	12	RPM	4096	1
341	N ₁ Command	200	12*	RPM*	4096*	1*
342	N ₁ Limit	200	12*	RPM*	4096*	1*
343	N ₁ Derate	200	12*	RPM*	4096*	1*
344	N ₂	100	14	RPM*	16384*	1*

Table 2 BNR Data (cont'd)

Label (Octal)	Parameter Name	Max Transmit Interval	Sig. Bits (Not Inc. Sign)	Units	Range	Approx. Resol.
345	Exhaust Gas Temp.	200	11*	°C *	2048	1*
346	N ₁ Actual	200	12*	RPM*	4096*	1*
347	Fuel Flow	200	11*	Lbs/hr	32768	16*
362	Along Track Horiz. Accel.	50*	12	g	4	0.001
365	Integrated Vertical Accel.	50*	15*	Knots	4096*	0.125*
366	N-S Velocity	200*	15	Knots	4096	0.125
367	E-W Velocity	200*	15	Knots	4096	0.125

Note: Labels 110, 112, 130, 131, 132, 133, 241, 245, 247, 346, 360, 372, 373, 374 and 376 previously had no values assigned. Values for label 216 have been deleted.

*This data has been changed.

Attachment 6: General Word Formats and Encoding Examples

AIM word format examples have been added. Detailed descriptions of these words have been included in the text of Section 2.3.1.3.

AERONAUTICAL RADIO, INC.
2551 Riva Road
Annapolis, Maryland 21401- 7645 USA

SUPPLEMENT 3
TO
ARINC SPECIFICATION 429
MARK 33 DIGITAL INFORMATION TRANSFER SYSTEM (DITS)

Published: November 1, 1979

Prepared by the Airlines Electronic Engineering Committee
Adopted by the Airlines Electronic Engineering Committee: August 31, 1979

A. PURPOSE OF THIS SUPPLEMENT

This Supplement introduces material on the transfer of file data and the related protocol. The file transfer capability is being added primarily for the Flight management Computer (FMC) program/data load and update and FMC intersystem crosstalk. A number of labels and corresponding data standards have been added.

B. ORGANIZATION OF THIS SUPPLEMENT

The first part of this document, printed on goldenrod paper, contains descriptions of the changes introduced into the Specification by this Supplement; and, where appropriate, extracts from the original text for comparison purposes. The second part consists of replacement white pages for the Specification, modified to reflect these changes. The modified and added material on each replacement page is identified with “c-3” symbols in the margins. Existing copies of Specification 429 may be updated by simply inserting the replacement white pages where necessary and destroying the pages they replace. The goldenrod pages should be inserted inside the rear cover of the Specification.

Copies of the Specification bearing the number 429-3 already contain this Supplement and thus do not require revisions by the reader.

C. CHANGES TO SPECIFICATION 429 INTRODUCED BY THIS SUPPLEMENT

This section presents a complete tabulation of the changes and additions to the Specification introduced by this Supplement. Each change or addition is entitled by the section number and title currently employed in the Specification or by the section number and title that will be employed when the Supplement is eventually incorporated. In each case there is included a brief description of the addition or change and, for other than very minor revisions, any text originally contained in the Specification is reproduced for reference.

2.1.5.1 BCD NUMERIC, DISCRETE AND AIM DATA WORDS

Table amended to provide consistency between AIM and file transfer data words.

ORIGINAL TEXT FOLLOWS:

Bit No.		Designation	
31	30	BCD Numeric Data	AIM Data
0	0	Plus, North East Right, To	Final Word
0	1	No Computed Data	Intermed. Word
1	0	Functional Test	Control Word
1	1	Minus, South West, Left, From	Initial Word

2.1.6 DATA STANDARDS

Text added to clarify data encoding.

ORIGINAL TEXT FOLLOWS:

2.1.6 Data Standards

The units, ranges, resolutions, refresh rates, number of significant bits, pad bits etc. for the items of information to be transferred by the Mark 33 DITS are tabulated in Attachment 2 to this document.

COMMENTARY

Note that Section 2.3.1.1 of this document calls for numeric data to be encoded in BCD and binary, the latter using two’s complement fractional notation. In this notation, the most significant bit of the data filed represents one half of the maximum value chosen for the parameter being defined. Successive bits represents the increments of a binary fraction series. Negative number are encoded as the complements of positive values and the negative sign is annunciated in the sign/status matrix.

In establishing a given parameter’s binary data standards for inclusion in Attachment 2, the units, maximum value and resolution of the parameter are first determined in that order. The least significant bit of the word is then given a value equal to the resolution increment, and the number of significant bits is chosen such that the maximum value of the fractional binary series just exceeds the maximum value of the parameter, i.e., equals the next whole binary number greater than the maximum parameter value less one least significant bit value. For example, if the Mark 33 DITS is required to transfer altitude in units of feet over a range of zero to 100,000 feet with a resolution of one foot, the number of significant bits is 17 and the maximum value of the fractional binary series is 131,071 (i.e., 131,071 – 1). Note that because accuracy is a quality of the measurement process and not the data transfer process, it plays no part in the selection of word characteristics. Obviously, the resolution provided in the DITS word should equal or exceed the accuracy in order not to degrade it.

For the binary representation of angular data, the Mark 33 DITS employs “degrees divided by 180⁰⁰” as the unit of data transfer and ± 1 (semicircle) as the range for two’s complement fractional notation encoding ignoring, for the moment, the subtraction of the least significant bit value. Thus the angular range 0 through 359.XXX degrees is encoded as 0 through ± 179.XXX degrees, the value of the most significant bit is none half semicircle and there are no discontinuities in the code.

For convenience, all binary word ranges in Attachment 2 are shown as whole binary numbers rather than such numbers less one least significant bit value. Also the resolutions shown are approximate only. Accurate resolutions can be determined, if required, by reference to the range values and numbers of significant bits for the words of interest.

2.1.6 Data Standards (cont'd)

COMMENTARY (cont'd)

It should be noted that in all applications of the two's complement fractional notation, the maximum value of the word, once chosen, cannot be changed by the use of more bits in the data field. The number of bits in the word affects only the resolution of the data, not its range.

Binary coded decimal (BCD) data is encoded per the numeric subset of the ISO Alphabet No. 5 code (see Attachment 5 to this document) using bit nos. 1 through 4 of the seven-bit-per-character code. Alpha/numeric data is encoded using all seven bits per character of the ISO Alphabet #5 code and is transmitted using the special word format described in Section 2.3.1.3 of this document.

2.3.1.5 FILE DATA TRANSFER

Section added to provide description of file data transfer protocol.

3.1.4.3 HF COMMUNICATIONS

Text amended to describe switching functions and finer frequency selection increments.

ORIGINAL TEXT FOLLOWS:

3.1.4.3 HF Communications

Frequency Range: 2.8MHz to 24MHz
Frequency Selection Increments 1kHz
Characters encoded 10MHz, 1MHz, 0.1MHz, in DITS word: 0.01MHz, 0.001MHz
Switching Functions: USB/AM mode selection

Fig. 3-1 RADIO SYSTEMS MANAGEMENT WORD FORMATS

Error corrected in bits 24 and 25 of ILS word.

HF COMM frequency word format changed and second word added to enable the use of 100 Hz channel spacing.

ORIGINAL TEXT FOLLOWS:

HF COM																	
Function	PARITY (Odd)	SIGN/STATUS MATRIX	10MHz (2)	1MHz (3)	0.1MHz (5)	0.01MHz (7)	0.001MHz (9)	USB/AM MODE	RESERVED (SDI)	LABEL HF COM Frequency							
Bit No. Example Notes	32 0	31 30 0 0	29 28 27 0 1 0	26 25 24 23 0 0 1 1	22 21 20 19 0 1 0 1	18 17 16 15 0 1 1 1	14 13 12 11 1 0 0 1	10 0 [1]	9 0 [2]	8 1	7 1	6 1	5 1	4 1	3 0	2 0	1 0

- [1] When bit no. 10 is "zero" the equipment should operate in the AM mode. When bit no. 10 is "one" the equipment should operate in the SSB (USB) mode.
- [2] Only bit no. 9 is available for the SDI function in this word.

ATTACHMENT 1: LABEL CODES

The following labels have been given new assignments:

053, 056, 060, 061, 062, 063, 065, 066, 067, 070, 071, 075, 076, 077, 120, 126, 134, 137, 143, 175, 176, 177, 200, 217, 226, 251, 252-256, 257, 260, 261, 277, 300-307, 361.

ATTACHMENT 2: DATA STANDARDS

Tables 1 and 2 have both additions and modifications made to the data standards. Notes 2 thru 5 deleted. The original information provided in ARINC 429-2 is included in these tables. An asterisk beside a value designated that a change has been recommended. The formats of table 1 and 2 have also been changed to provide the addition of data standard descriptors.

Table 3.7 added for GPWS discretes.

ATTACHMENT 2: DATA STANDARDS (cont'd)TABLE 1 BCD DATA

LABEL (OCTAL)	PARAMETER NAME	MAX. TRANSMIT INTERVAL msec	RANGE (SCALE	SIG. FIG.	PAD FIG.	UNITS	RESOL
0 1 0	Present Position-Lat.	200*	90S-90N	5	0	Deg/Min*	0.1
0 1 1	Present Position-Long.	200*	180E-180W	6	0	Deg/Min*	0.1
0 1 2	Ground Speed	200*	0-2000	4	1	Knots	1.0
0 1 3	Track Angle (true)	200*	0-359.9	4	1	Deg	0.1
0 1 4	Magnetic Heading	200*	0-359	3	2	Deg	1.0
0 1 5	Wind Speed	200*	0-299	3	2	Knots	1.0
0 1 6	Wind Direction (true)	200*	0-359	3	2	Deg	1.0
0 4 1	Set Latitude	200*	90S-90N	5	0	Deg/Min	0.1
0 4 2	Set Longitude	200*	180E-180W	6	0	Deg/Min	0.1
0 4 3	Set Magnetic Heading	200*	0-359.9*	4*	1*	Deg	0.1*
1 2 5	Greenwich Mean Time	200	0-23.59.9	5	0	Hr/Min*	0.1
2 3 0	True Airspeed	62.5*	100-599	3	0	Knots	1.0

TABLE 2 BNR DATA

LABEL (OCTAL)	PARAMETER NAME	MAX. TRANSMIT INTERVAL msec	SIG. BITS (NOT INC. SIGN)	UNITS	RANGE See Note 1	APPROX RESOL
1 0 0	Selected Course #1	50	9*	Deg/180	±180°	0.35*
1 0 1	Selected Heading	62.5	9*	Deg/180	±180°	0.35*
1 0 5	Selected Runway Heading	62.5	9*	Deg/180	±180°	0.35*
1 1 0	Selected Course #2	50	9*	Deg/180	±180°	0.35*
1 1 6	Cross Track Distance	62.5	8*	N.M.	128	0.5*
1 2 1	Horiz. Steering Signal	100	10*	Deg/180	±60°	0.06*
1 2 2	Vertical Steering Signal	100	9*	Deg/180	±30°	0.06*
1 2 3	Throttle Command	*	*	*	*	*
1 3 0	Tt2*	200	11	°C	128	0.06
1 3 1	Pt2*	200	13	PSIA	32	0.004
1 3 2	Pt7*	200	13	PSIA	32	0.004
1 4 0	Flight Director-Roll	100	9*	Deg/180	±45°*	0.1*
1 4 1	Flight Director-Pitch	100	9*	Deg/180	±22.5°	0.05
1 4 2	Fast/Slow	62.5	8*	Knots	32	0.125*
1 4 3	Flight Director-Yaw*	100*	12*	Deg/180*	±180°	0.05*
1 6 4	Radio Height	50	17*	Feet	16384*	0.125
2 0 3	Altitude (1013.25mb)	62.5	18*	Feet	131,072	0.05*
2 1 0	True Airspeed	62.5*	11*	Knots	2048	1.0*
2 1 1	Total Air Temp.	500	10*	°C	512	0.5*
2 1 3	Static Air Temp.	500	10*	°C	512	0.5*
2 2 1	Indicated Angle of Attack	62.5	11*	Deg/90*	±90°*	0.05
2 4 1	Corrected Angle of Attack	62.5	11*	Deg/90*	±90°*	0.05
2 4 7	Total Fuel	200*	15*	Lb.	655,360	20*
3 1 0	Present Position-Lat.	200	18*	Deg/180	0-90N-0-90S	0.00035*
3 1 1	Present Position-Long.	200	18*	Deg/180	0-180E-0-180W	0.00070*
3 1 2	Ground speed	100*	15	Knots	4096	0.125
3 1 3	Track Angle True	40*	12	Deg/180	±180°	0.05
3 1 4	True Heading	40*	12	Deg/180	±180°	0.05
3 1 7	Track Angle-Mag	40*	12	Deg/180	±180°	0.05
3 2 0	Magnetic Heading	40*	12	Deg/180	±180°	0.05
3 2 1	Drift Angle	40*	11*	Deg/180	±90°*	0.05
3 2 2	Flight Path Angle	40*	10*	Deg/180	±45°*	0.05
3 2 4	Pitch Angle	20*	13*	Deg/180	±90°*	0.01
3 2 5	Roll Angle	20*	14	Deg/180	±180°	0.01
3 6 0	Potential Vertical Speed	50	10*	Ft/min*	16384*	16*

The change to MTI was erroneously omitted from Draft 1 of Supplement 3, but was included prior to publication of Supplement 3.

ATTACHMENT 2: DATA STANDARDS (cont'd)

NOTES

1. The number entered in the Range Column for each parameter that is not angular in nature is the nearest whole binary number greater than the parameter range required. As explained in the Commentary following Section 2.1.6 of this document, the weight of the most significant bit of the two's complement fractional notation binary word will be one half this value, and the actual maximum value of the parameter capable of being encoded will be the number in the range column less one least significant bit value. The numbers entered in the RANGE column for angular parameters are the actual degree ranges required. The way in which these parameters are encoded is also explained in the Commentary following Section 2.1.6.
2. Bit nos. 9 and 10 of the word may be used to achieve a 20 bit capability for high resolution of the Lat./Long. Position (codes 310 and 311). The resulting resolution is .000086° for latitude and .00017° for longitude.
3. A change in ARINC 707 not shown in Supplement 2 is a planned change for Supplement 3. A self-test inhibit bit will be added and the range of the data word will be halved to a value of 8192 ft.

4. A change in ARINC 710 not shown in Supplement 2 is a planned change for Supplement 3. The resolution of Selected Runway Heading (BCD and BNR) will be changed to .1°.

5. A change being considered for Supplement 3 is to change the range to -6g - +4g to facilitate direct recording by the flight recorder.

ATTACHMENT 6: GENERAL WORD FORMATS & ENCODING EXAMPLES

SSM codes in AIM words changed to reflect table amendment of section 2.1.5.1.

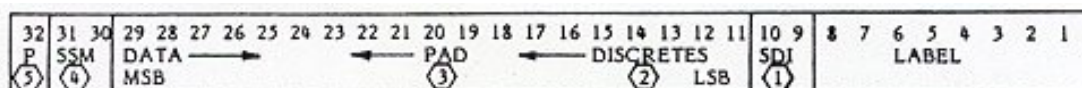
Radio Height code example changed to reflect shift in field.

Note 4 of Table 6.2 deleted to revert data coding to the original two's complement notation.

Word formats added for date/flight leg and flight number information.

Word format added for VOR Omnibearing.

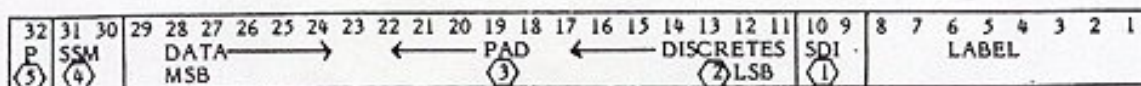
Codes 203, 204, 206 and 207 deleted in Table 6.1a.

ORIGINAL TEXT FOLLOWS:ATTACHMENT 6GENERAL WORD FORMATS AND ENCODING EXAMPLES1. GENERAL WORD FORMATSGENERALIZED BCD WORD FORMAT

P	SSM	BCD MSC	BCD CH #2	BCD CH #3	BCD CH #4	BCD CH #5	SDI	LABEL
0	0 0	4 2 1 0 1 0	8 4 2 1 0 1 0 1	8 4 2 1 0 1 1 1	8 4 2 1 1 0 0 0	8 4 2 1 0 1 1 0	0 0	1 0 0 0 0 0 0 1
Example		2	5	7	8	6		DME DISTANCE

BCD WORD FORMAT EXAMPLE (NO DISCRETES)

ATTACHMENT 6: GENERAL WORD FORMATS & ENCODING EXAMPLES (cont'd)



GENERALIZED BNR WORD FORMAT

P	SSM	1	1	1	1	1	1	1	etc		PAD		SDI		LABEL
		2	4	8	16	32	64	128							
0	1	1	0	0	0	1	0	0	0	0	0	0	0	0	0
Example 512 Knots (i.e. 1/8 x 4096 where 4096 is entry in range column of Table 2 in Attachment 2.										N-S VELOCITY					

BNR WORD FORMAT EXAMPLE (NO DISCRETES)

P	SSM	"STX"		SPARES		WORD COUNT		LABEL
32	31(11)	30	29	23	22 (Zeroes)	17	16 (Tens) 13 12 (Units)9	8 (356/357)
								1

MAINTENANCE (ISO ALPHABET NO. 5) DATA - INITIAL WORD FORMAT

P	SSM	DATA CH #3		DATA CH #2		DATA CH #1		LABEL
32	31(01)	30	29	23	22	16	15	9 8 (356/357)
			P	L		A		1

ALPHA/NUMERIC (ISO ALPHABET NO. 5) DATA - INTERMEDIATE WORD FORMAT

P	SSM	DATA CH #3		DATA CH #2		DATA CH #1		LABEL
32	31(00)	30	29	23	22	16	15	9 8 (356/357)
			(BNR ZEROS)	A		H		1

ALPHA NUMERIC (ISO ALPHABET NO. 5) DATA - FINAL WORD FORMAT

(Taken together, above three word format examples show encoding of the word ALPHA)

P	SSM		DISCRETES		SDI	LABEL
32	31(11)	30	29	MSB	10 9	8 (270-274)
				2	LSB 11	1

DISCRETE WORD FORMAT

P	SSM	MAINTENANCE DISCRETES		SDI	LABEL
32	31(11)	30	29	MSB	10 9
				DISCRETES	8 (350-354)
				LSB 11	1

MAINTENANCE (DISCRETE) WORD FORMAT

P	SSM	ACKNOWLEDGEMENT (FORMAT NOT DEFINED)		WORD COUNT		LABEL
32	31(11)	30	29	17	16 (Tens) 13 12 (Units)9	8 (355)
						1

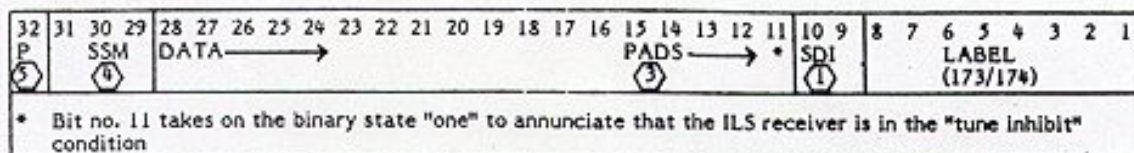
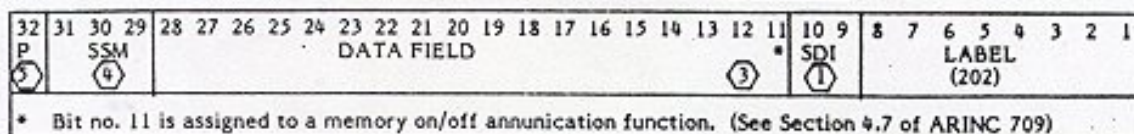
ACKNOWLEDGEMENT WORD-INITIAL WORD FORMAT

P	SSM	ACKNOWLEDGEMENT (FORMAT NOT DEFINED)		LABEL
32	31(01)	30	29	9 8 (355)
				1

ACKNOWLEDGEMENT WORD INTERMEDIATE WORD FORMAT

P	SSM	ACKNOWLEDGEMENT (FORMAT NOT DEFINED)		LABEL
32	31(00)	30	29	9 8 (355)
				1

ACKNOWLEDGEMENT WORD-FINAL WORD FORMAT

ATTACHMENT 6: GENERAL WORD FORMATS & ENCODING EXAMPLES (cont'd)ILS LOCALIZER/GLIDESLOPE DEVIATION WORDDME DISTANCE WORDDME DISTANCE WORD

Attachment 6 (cont'd)
GENERAL WORD FORMATS AND ENCODING EXAMPLES

NOTES[1] Source/Destination Identifier (SDI) Field

The purpose of the SDI field is explained in Section 2.1.4 of this document, as are also the limitations on its use. When the SDI function is not required, this field may be occupied by binary zero or valid data pad bits.

[2] Discretes

As discussed in Section 2.3.1.2 of this document, unused bits in a word may be assigned to discrete functions, one bit per variable. Bit #11 of the word should be the first to be so assigned; followed by bit #12 and so on in ascending numerical order until the data field is reached. In the absence of discretes, unused bit positions should be occupied by binary zero or valid data pad bits.

[3] Pad

All bit positions not used for data or discretes should be filled with binary zero or valid pad bits. Section 2.1.2 of this document refers.

[4] Sign/Status Matrix (SSM)

Section 2.1.5 of this document describes the functions of the sign/status matrix and the ways in which the bits constituting it are encoded.

[5] Parity Bit

This bit is encoded to render word parity odd. Section 2.3.4 of this document refers.

Bit No.	32	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	
PARAMETER (Label)			SSM	DATA FIELD																		SDI	LABEL										
				MSC				(4 2 1)				(8 4 2 1)				(8 4 2 1)				(8 4 2 1)				(1 2 4)		(1 2 4)		(1 2)					
Distance To Go (001)																																	
+2750.4 NM	1	0	0	0	1	0	0	1	1	1	0	1	0	1	0	0	0	0	0	1	0	0	0	0	0	1	0	0	0	0	0	0	0
Time To Go (002)																																	
145.3 min	0	0	0	0	0	1	0	1	0	0	0	1	0	1	0	0	1	1	P	P	P	P	0	0	0	1	0	0	0	0	0	0	0
Cross Track Distance (003)																																	
225.6 NM	1	0	0	0	1	0	0	0	1	0	0	1	0	1	0	1	1	0	P	P	P	P	0	0	1	1	0	0	0	0	0	0	0
Ground Speed (012)																																	
650 Knots	1	0	0	0	0	0	0	1	1	0	0	1	0	1	0	0	0	0	P	P	P	P	0	0	0	1	0	1	0	0	0	0	0
Track Angle (True) (013)																																	
165.5 deg	1	0	0	0	0	1	0	1	1	0	0	1	0	1	0	1	0	1	P	P	P	P	0	0	1	1	0	1	0	0	0	0	0
Selected Vertical Speed (020)																																	
-2200 ft/min	0	1	1	0	1	0	0	0	1	0	0	0	0	0	0	0	0	0	P	P	P	P	0	0	0	0	0	0	1	0	0	0	0
Selected EPR (021)																																	
2.05	0	0	0	0	1	0	0	0	0	0	0	1	0	1	P	P	P	P	P	P	P	P	0	0	1	0	0	0	1	0	0	0	0
Selected N ₁ (021)																																	
2750 RPM	1	0	0	0	1	0	0	1	1	1	0	1	0	1	0	0	0	0	P	P	P	P	0	0	1	0	0	0	1	0	0	0	0
Selected Mach (022)																																	
0.850 Mach	0	0	0	0	0	0	1	0	0	0	0	1	0	1	0	0	0	0	P	P	P	P	0	0	0	1	0	0	1	0	0	0	0
Selected Heading (023)																																	
177 deg	1	0	0	0	0	1	0	1	1	1	0	1	1	1	P	P	P	P	P	P	P	P	0	0	1	1	0	0	1	0	0	0	0
Selected Course (024)																																	
254 deg	1	0	0	0	1	0	0	1	0	1	0	1	0	0	P	P	P	P	P	P	P	P	0	0	0	0	1	0	1	0	0	0	0
Selected Altitude (025)																																	
41,000 ft.	0	0	0	1	0	0	0	0	0	1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	0	1	0	1	0	0	0	0
Selected Airspeed (026)																																	
423 Knots	0	0	0	1	0	0	0	0	1	0	0	0	1	1	P	P	P	P	P	P	P	P	0	0	0	1	1	0	1	0	0	0	0
Greenwich Mean Time (125)																																	
1545.5 hr	1	0	0	0	0	1	0	1	0	1	0	1	0	0	0	1	0	1	0	1	0	1	0	1	0	1	0	1	0	1	0	1	0
Radio Height (165)																																	
2450.5 ft	0	0	0	0	1	0	0	1	0	0	0	1	0	1	0	0	0	0	0	1	0	1	0	1	0	1	0	1	0	1	1	1	0
Decision Ht. Selected (170)																																	
200 ft.	0	0	0	0	1	0	0	0	0	0	0	0	0	0	P	P	P	P	P	P	P	P	0	0	0	0	0	1	1	1	1	0	0
DME Distance (201)																																	
257.86 NM	0	0	0	0	1	0	0	0	1	0	1	1	1	1	0	0	0	0	1	1	0	0	0	1	0	0	0	0	0	0	0	0	1
Altitude (29.92) (203)																																	
39500 ft.	1	0	0	0	1	1	1	0	0	1	0	1	0	1	0	0	0	0	0	0	0	0	0	0	0	1	1	0	0	0	0	0	1
Altitude (Baro) (204)																																	
41350 ft	0	0	0	0	1	0	0	0	0	1	0	0	1	1	0	1	0	1	0	0	0	0	0	0	0	0	0	1	0	0	0	0	1
Computed Airspeed (206)																																	
425 Knots	1	0	0	1	0	0	0	0	1	0	0	1	0	1	P	P	P	P	P	P	P	P	0	0	0	1	1	0	0	0	0	1	
Max Allowable Airspeed (207)																																	
450 Knots	1	0	0	1	0	0	0	1	0	1	0	0	0	0	P	P	P	P	P	P	P	P	0	0	1	1	0	0	0	0	0	1	
True Airspeed (230)																																	
565 Knots	0	0	0	1	0	1	1	0	0	1	0	1	P	P	P	P	P	P	P	P	P	P	0	0	0	0	1	1	0	0	0	1	
Total Air Temp (231)																																	
-025°C 2	0	1	1	0	0	0	0	0	1	0	0	1	0	1	P	P	P	P	P	P	P	P	0	0	1	0	0	1	1	0	0	1	
Altitude Rate (232)																																	
-15250 ft/min	1	1	1	0	0	1	0	1	0	1	0	0	1	0	0	1	0	1	0	0	0	0	0	0	0	0	1	0	1	1	0	0	1
Static Air Temp. (233)																																	
+013°C 2	1	0	0	0	0	0	0	0	0	1	0	0	1	1	P	P	P	P	P	P	P	P	0	0	1	1	0	1	1	0	0	1	
Baroset (ins Hg) (235)																																	
29.92 ins Hg	0	0	0	0	1	0	1	0	0	1	1	0	0	1	0	0	1	0	P	P	P	P	0	0	1	0	1	1	1	0	0	1	

TABLE 6-1a

BCD DATA ENCODING EXAMPLES

- NOTES: [1] "P" denotes pad "zero" or valid data. Section 2.1.2 of this document refers. Note possible use of pad bits for discrete functions per Section 2.3.1.2.
- [2] Because the actual maximum value of the most significant character of each of these quantities exceeds 7, it cannot be encoded in the most significant character position of the BCD word. For this reason each quantity has been given an "artificial" MSC of zero and its actual MSC encoded in the next most significant character position of the word.

Bit No.	32	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2				
PARAMETER (Label)	P	SSM				DATA FIELD																		LSB		SOI		LABEL							
																											(1 2 4)	(1 2 4)	(1 2 4)	(1 2 4)	(1 2 4)	(1 2 4)			
Selected Course (100)	0	1	1	0	0	0	0	0	0	0	0	0	0	0	P	P	P	P	P	P	P	P	P	0	0	0	0	0	0	0	0	1			
Selected Heading (101)	1	1	1	0	1	1	0	1	0	1	0	1	1	P	P	P	P	P	P	P	P	P	P	0	0	1	0	0	0	0	0	1			
Selected Altitude (102)	1	1	1	0	1	0	1	0	0	0	0	0	0	0	1	0	1	0	0	0	P	P	0	0	0	1	0	0	0	0	0	1			
Selected Airspeed (103)	0	1	1	0	1	1	0	1	0	0	1	1	1	0	P	P	P	P	P	P	P	P	0	0	1	1	0	0	0	0	1				
Selected Vertical Speed (104)	1	1	1	1	1	1	0	1	1	1	0	1	1	0	P	P	P	P	P	P	P	P	0	0	0	0	1	0	0	0	1				
Selected Mach (106)	1	1	1	0	0	0	1	1	0	0	1	0	0	0	0	P	P	P	P	P	P	P	0	0	0	1	1	0	0	0	1				
Desired Track (114)	0	1	1	1	1	0	0	0	0	1	1	1	0	0	1	0	P	P	P	P	P	P	0	0	0	0	1	1	0	0	1				
Cross Track Distance (116)	1	1	1	0	0	1	1	0	0	1	1	0	P	P	P	P	P	P	P	P	P	P	0	0	0	1	1	1	0	0	1				
Vertical Deviation (117)	0	1	1	0	0	1	0	0	1	0	1	1	0	0	P	P	P	P	P	P	P	P	0	0	1	1	1	1	0	0	1				
Flight Director Roll (140)	0	1	1	0	1	0	1	0	1	0	0	1	0	P	P	P	P	P	P	P	P	P	0	0	1	1	1	1	0	0	1				
Flight Director Pitch (141)	1	1	1	1	1	0	0	0	1	1	1	0	0	P	P	P	P	P	P	P	P	P	0	0	1	0	0	0	0	1	1				
Fast/Slow (142)	0	1	1	0	0	1	1	1	1	0	0	0	P	P	P	P	P	P	P	P	P	P	0	0	0	1	0	0	0	1	1				
Radio Height (164)	0	1	1	0	0	0	0	1	0	0	1	1	0	0	1	0	0	1	0	0	0	0	0	0	0	0	1	0	1	1	1	1			
Localizer Deviation (173)	1	1	1	0	0	0	0	0	1	1	0	1	0	0	P	P	P	P	P	P	P	0	0	1	1	0	1	1	1	1	1				
Glide Slope Deviation (174)	1	1	1	1	1	1	0	1	1	0	0	0	0	0	0	P	P	P	P	P	P	0	0	0	0	1	1	1	1	1	1				
DME Distance (202)	0	1	1	0	1	0	0	0	0	0	0	1	1	1	0	1	1	1	0	P	P	0	0	0	1	0	0	0	0	0	0	0			
Altitude (29.92) (203)	0	1	1	0	0	1	0	1	0	1	1	1	1	1	0	0	1	0	0	P	P	0	0	1	1	0	0	0	0	0	0	0			
Mach (203)	0	1	1	0	0	0	1	1	0	0	0	0	0	0	0	1	P	P	P	P	P	0	0	1	0	1	0	0	0	0	0	0			
Computed Airspeed (206)	1	1	1	0	0	1	1	0	1	0	1	0	1	0	P	P	P	P	P	P	P	0	0	0	1	1	0	0	0	0	0	0			
True Airspeed (210)	0	1	1	0	0	1	0	0	0	1	1	0	1	0	P	P	P	P	P	P	P	0	0	0	0	0	1	0	0	0	0	0			
Static Air Temp (213)	0	1	1	0	0	0	0	0	0	1	1	0	1	0	P	P	P	P	P	P	P	0	0	0	0	0	1	0	0	0	0	0			
Total Air Temp (211)	0	1	1	0	0	0	0	0	0	1	1	0	1	0	P	P	P	P	P	P	P	0	0	1	1	0	1	0	0	0	0	0			
Altitude Rate (212)	0	1	1	1	1	1	1	0	0	1	1	1	0	P	P	P	P	P	P	P	P	0	0	1	0	0	1	0	0	0	0	0			
Present Pos. Lat. (310)	0	1	1	1	1	0	0	0	1	0	0	0	1	1	P	P	P	P	P	P	P	0	0	0	1	0	1	0	0	0	0	0			
Present Pos. Long. (311)	1	1	1	0	1	1	0	0	1	1	1	1	1	1	1	0	0	0	0	0	0	0	0	0	0	0	0	1	0	0	1	0	1		
Ground Speed (312)	1	1	1	1	1	0	0	0	1	1	1	0	1	0	0	1	0	1	0	0	0	0	0	0	1	0	0	1	0	0	1	0	1		
650 Knots	1	1	1	0	0	1	0	1	0	0	0	1	0	1	0	0	0	0	0	P	P	0	0	0	1	0	1	0	0	1	0	1	0		
Flight Path Accel (323)	0	1	1	0	0	1	0	1	0	0	0	0	0	0	0	P	P	P	P	P	P	0	0	1	1	0	0	1	0	1	0	1	0		
+1.25g	0	1	1	0	0	1	0	1	0	0	0	0	0	0	0	P	P	P	P	P	P	0	0	1	1	0	0	1	0	1	0	1	0		

TABLE 6-2

BNR DATA ENCODING EXAMPLES

- NOTES: [1] "P" denotes pad "zero" or valid data. Section 2.1.2 of this document refers. Note possible use of pad bits for discrete functions per Section 2.3.1.2.
- [2] Negative values are encoded as the two's complements of positive values and the negative sign is annunciated in the sign/status matrix.
- [3] Angles in the range 0 to 180° are encoded as positive numbers. Angles in the range 180° to 360° are subtracted from 360° and the resulting number encoded as a negative value per note 2. Arc minutes and seconds are encoded as decimal degrees.
- [4] Latitude values are encoded as positive angles in the range 0 to 90° with the sign/status matrix indicating North or South. Longitude values are encoded as positive angles in the range 0 to 180° with the sign/status matrix indicating East or West. Arc minutes and seconds are encoded as decimal degrees.

AERONAUTICAL RADIO, INC.
2551 Riva Road
Annapolis, Maryland 21401 – 7645 USA

SUPPLEMENT 4
TO
ARINC SPECIFICATION 429
MARK 33 DIGITAL INFORMATION TRANSFER SYSTEM (DITS)

Published: August 1, 1980

Prepared by the Airlines Electronic Engineering Committee
Adopted by the Airlines Electronic Engineering Committee: June 17, 1980

A. PURPOSE OF THIS SUPPLEMENT

This Supplement introduces material on defining “No Computed Data” and “Failure Warning”, priority assignment of SSM codes, description of fault tolerance and isolation, address capability of A/N messages, command/response protocol, modification of data standards, addition of new labels, change of some word formats, addition of material on signal characteristics, change of receiver impedance limits, expansion of the current label, change of the receiver voltage thresholds and modification of the HF and DME word formats.

B. ORGANIZATION OF THIS SUPPLEMENT

The first part of this document, printed on goldenrod paper, contains description of the changes introduced into the Specification by this Supplement, and, where appropriate, extracts from the original text for comparison purposes. The second part consists of replacement white pages for the Specification, modified to reflect these changes. The modified and added material on each replacement page is identified with “c-4” symbols in the margins. Existing copies of Specification 429 may be updated by simply inserting the replacement white pages where necessary and destroying the pages they replace. The goldenrod pages should be inserted inside the rear cover of the Specification.

Copies of the Specification bearing the number 429-4 already contain this Supplement and thus do not require revisions by the reader.

C. CHANGES TO SPECIFICATION 429 INTRODUCED BY THIS SUPPLEMENT

This section presents a complete tabulation of the changes and additions to the Specification introduced by this Supplement. Each change or addition is entitled by the section number and title currently employed in the Specification, or the section number and title that will be employed when the Supplement is eventually incorporated. In each case there is included a brief description of the addition or change and, for other than very minor revisions, any text originally contained in the Specification is reproduced for reference.

2.1.3 INFORMATION IDENTIFIER

Text changed to describe use of five-character label.

Commentary text partially deleted.

ORIGINAL TEXT FOLLOWS:

2.1.3 Information Identifier

The first eight bits of each word are assigned to a label function. Label will:

- a. identify the information contained within BNR and BCD numeric data words (e.g., DME distance, static air temperature, etc.) and
- b. identify the word application for Discrete, Maintenance and AIM data.

Label code assignments are set forth in Attachment 1 to this document.

Special Note:

In some ARINC 429 DITS applications, a bus will be dedicated to delivering a single information element from a source to one or more identical sink devices. In such circumstances, the sink device designer might be tempted to assume that decoding the word label is not necessary. Experience has shown, however, that system developments frequently occur that result in the need for additional information elements to appear on the bus. If a sink device designed for service prior to such a development cannot decode the original word label, it cannot differentiate between this word and the new data in the new situation. The message for sink designers should therefore be quite clear – provide label decoding from the outset, no matter how strong the temptation to omit it might be.

COMMENTARY

Attachment 1 defines 256 discrete label codes. This quantity is expected to meet label assignment needs for the foreseeable future. Should additional labeling capability be required in the longer term, it is envisaged that, rather than extend the length of the label field, a scheme will be devised in which existing label assignments are duplicated. For example, the system could readily accommodate the assignment of the same label to two dissimilar parameters for which the probability of transmission on the same bus is very low.

Adherence to the label code assignments of Attachment 1 is essential in inter-system communications and in intra-system communications where the system elements are defined as “unit interchangeable” per ARINC Report No. 403. The assignment of label codes for all such communications must be coordinated with the air transport industry if chaos is to be avoided. A manufacturer who finds that Attachment 1 does not specify the label he needs for such system application must not simply choose one from those unassigned and “drive on”. He should contact ARINC for assistance.

2.1.5.1 BCD NUMERIC, DISCRETE, AIM DATA AND FILE TRANSFER WORDS

Text describing “no computed data” modified.

Commentary providing definitions added.

ORIGINAL TEXT FOLLOWS:

2.1.5.1 BCD Numeric, Discrete, AIM Data and File Transfer Words

The sign (Plus, minus, North, South, etc.) of BCD numeric data, the word type (first, intermediate, control, last) for AIM data, and the status of the transmitter hardware should be encoded in bit nos. 30 and 31 of the word as shown in the table below. The sign/status matrices of Discrete words should be encoded per the rules set forth for BCD numeric data.

Bit No.		Designation		
31	30	BCD Numeric Word	AIM	File Transfer
0	0	Plus, North East, Right To, Above	Intermediate Word	Intermediate Word, Plus, North, etc.
0	1	No Computed Data	Initial Word	Initial Word
1	0	Functional Test	Final Word	Final Word
1	1	Minus, South West, Left, From, Below	Control Word	Intermediate Word, Minus South, etc.

Notes:

1. A source system should annunciate any detected failure that causes one or more of the words normally output by that system to be unreliable by ceasing to supply the affected word or words to the data bus.
2. Bit nos. 30 and 31 of BCD numeric data words should be “zero” when no sign is needed.
3. The “no computed data” code should be generated for BCD numeric data words when computed data is not available for reasons other than equipment failure.
4. When it appears in a BCD numeric data word identified by its (label) as a system output, the “functional test” code should be interpreted as advice that the data in the word results from the execution of a functional test. When it appears in a BCD numeric data word identified by its label as an instruction, e.g., a radio channel change command, this code should be interpreted as a command to perform a functional test. A self-test should produce indications of 1/8 of positive full-scale values unless indicated otherwise in an ARINC Equipment Characteristic.
5. See Section 2.3.1.3 of this document for definitions of the terms “Initial Word”, “Control Word”, “Intermediate Word” and “Final Word.”

2.1.5.2 BNR NUMERIC DATA WORDS

Table modified to permit sign coding for “no computed data”.

Definition of “failure warning” and “no computed data” added.

ORIGINAL TEXT FOLLOWS:

2.1.5.2 BNR Numeric Data Words

The sign (plus, minus, north, south, etc.) of BNR numeric data words and the status of the transmitter hardware should be encoded in bit nos. 29, 30 and 31 of the word as shown in the table below.

Bit No.			Designation BNR Data
31	30	29	
0	0	0	Failure Warning/Plus, North, East Right, To
0	0	1	Failure Warning/Minus, South, West Left, From
0	1	0	No Computed Data
1	0	0	Functional Test/Plus, North, East, Right, To
1	0	1	Functional Test/Minus, South, West Left, From
1	1	0	Normal Operation/Plus, North, East, Right, To
1	1	1	Normal Operation/Minus, South West, Left, From
0	1	1	Not Used (Growth)

Notes:

1. A source system should annunciate any detected failure that causes one or more of the words normally output by that system to be unreliable by setting bit nos. 30 and 31 in the affected word(s) to the “failure warning” code defined above. Words containing this code should continue to be supplied to the data bus during the failure condition.
2. Bit no. 29 should be “zero” when no sign is needed.
3. The “no computed data” code should be generated when computed data is not available for reasons other than equipment failure.
4. When it appears in a word identified by its label as a system output, the “functional test” code should be interpreted as advice that the data in the word results from the execution of a functional test. A self-test should produce indications of 1/8 of positive full-scale values unless indicated otherwise in an ARINC Equipment Characteristic.
5. If, during the execution of a functional test, a source system detects a failure which causes one or more of the words normally output by that system to be unreliable, it should immediately change the states of bits nos. 30 and 31 in the annunciation to the “failure warning” annunciation.

2.1.5.3 STATUS PRIORITIES

New section inserted.

2.2.1 TRANSMISSION SYSTEM INTERCONNECT

Commentary expanded to provide description of possible solutions to single-wire fault conditions.

ORIGINAL TEXT FOLLOWS:

2.2.1 Transmission System Interconnect

A data source should be connected to the data sink(s) by means of a single twisted and shielded pair of wires. The shields should be grounded at both ends and at all production breaks in the cable. The interwiring diagram to be found in each ARINC Equipment Characteristic shows connector pins assigned to carry shields into black boxes for grounding. Equipment manufacturers should ensure, however, that their equipment will operate correctly if, instead of being terminated on these pins, shields are grounded in the aircraft close to the rack connector.

COMMENTARY

In practical wire line digital information transmission systems, cable characteristics and electrical mismatches can produce distortion of the digital data pulses. Also, noise due to electrical interference perturbs digital signals.

The performance of a digital receiver depends upon the receiver input signal characteristics (data with distortion and noise) and the receiver design.

Prior to the selection of the voltage and impedance parameters set forth in this Section of this document, the pulse distortion likely to be encountered in systems built around them in existing size commercial aircraft was evaluated and judged to be acceptable for a well-designed receiver. No restriction is placed by this specification, therefore, on the number or length of stubs for installations on aircraft no larger than those existing, e.g., B 747. See Appendix 1 to this document for a report of this investigation.

2.2.3.1 TRANSMITTER VOLTAGE LEVELS

Text changed to improve clarity.

ORIGINAL TEXT FOLLOWS:

2.2.3.1 Transmitter Voltage Levels

The differential output signal across the specified output terminals (balanced to ground at the transmitter) should be $+10 \pm 1.0$ volts, 0 ± 0.5 volts and -10 ± 1.0 volts respectively for the "HI", "NULL" and "LO" states when the transmitter is open circuit. The output impedance of the transmitter should be as specified in Section 2.2.4.1 of this document. This output impedance should be present for the "HI", "NULL" and "LO" transmitter output conditions and also during transitions between these levels.

2.2.3.2 RECEIVER VOLTAGE LEVELS

Receiver voltage thresholds changed.

Fault voltage text deleted.

Commentary revised to include description of receiver reaction to undefined voltages.

ORIGINAL TEXT FOLLOWS:

2.2.3.2 Receiver Voltage Levels

The differential voltage presented at the receiver input terminals will be dependent upon line length, stub configuration and the number of receivers connected. In the absence of noise, the normal ranges of voltages presented to the receiver terminals (A and B) would be:

"HI"	+6V to 10V
"NULL"	+0.5 to -0.5V
"LO"	-6V to -10V

In practice, these nominal voltages will be perturbed by noise and pulse distortion. Thus, receivers should associate the following voltage ranges with the three states indicated:

"HI"	+5V to 13V
"NULL"	+2.5V to -2.5V
"LO"	-5V to -13V

Receivers should not be damaged by the application of up to 20VAC (RMS) across terminals A and B by the application of up to +28Vdc (min) bias between terminal A and ground and -28Vdc (min) bias between terminal B and ground. See Attachment 3 to this document for a pictorial representation of transmitter and receiver voltage levels.

COMMENTARY

Receiver input common mode voltages (terminal A to ground and terminal B to ground) are not specified because of the difficulties of defining ground with any satisfactory degree of precision. Receiver manufacturers are encouraged to work with the differential input voltage (line A to line B) and not line-to-ground voltages.

The opinion is held by some people that conditions on transmission lines will be encountered which will require receivers to operate with less than the above-defined minimum difference of 2.5V between the NULL and HI and NULL and LO states. Receiver designers are encouraged to investigate the possibilities and problems of working with a minimum difference of 1 volt between these states and to report their findings.

2.2.4.1 TRANSMITTER OUTPUT IMPEDANCE

Text added to improve clarity.

ORIGINAL TEXT FOLLOWS:

2.2.4.1 Transmitter Output Impedance

The transmitter output impedance should be 75 ± 5 ohms, divided equally between line A and line B to provide an impedance balanced output.

COMMENTARY

The output impedance of the transmitter is specified as 75 ± 5 ohms to provide an approximate match to the characteristic impedance of the cable. The match can only be approximate due to the wide range of characteristic impedance which may be encountered due to the variety of conductor wire gages and insulation properties. Measurements on a few samples of wire showed a spread of characteristic impedance of 63 and 71 ohms. An extrapolation over the wire gages 20 to 26 for wrapped and extruded insulation indicate an expected characteristic impedance spread of 80 to 60 ohms approx. Twisted shielded wire specifications do not control the characteristic impedance of the cable, thus future developments in insulation techniques may result in cables having characteristic impedances outside the range estimated.

2.2.4.2 RECEIVER INPUT IMPEDANCE

Value of RI changed.

ORIGINAL TEXT FOLLOWS:

2.2.4.2 Receiver Input Impedance

The receiver should exhibit the following characteristics, measured at the receiver input terminals:

Differential Input Resistance $RI = 6,000$ ohms minimum

Differential Input Capacitance $CI = 50\text{pF}$ maximum
Resistance to Ground R_H and $R_G \geq 12,000$ ohms
Capacitance to Ground C_H and $C_G \leq 50\text{pF}$.

No more than twenty receivers should be connected on to one digital data bus and each receiver should incorporate isolation provisions to ensure that the occurrence of any reasonably probable failure does not cause loss of data to the others.

See Attachment 4 to this document for a pictorial representation of the input and output circuits standards.

COMMENTARY

The above characteristics apply to differential amplifier receivers. Opto-isolator technology is progressing and may soon find application in digital data receivers. Opto-isolator receivers impose slightly greater loads on data buses than differential amplifier receivers and the way in which they are characterized is different. It is probable, however, that a future revision of this

Specification will include material specifically related to their use.

2.2.5 Fault Tolerance

New section inserted.

2.2.5.1 Receiver External Fault voltage Tolerance

New section inserted.

2.2.5.2 Transmitter External Fault Voltage Tolerance

New section inserted.

2.2.5.3 Transmitter External Fault Load Tolerance

New section inserted.

2.2.6 Fault Isolation

New section inserted.

2.2.6.1 Receiver Fault Isolation

New section inserted.

2.2.6.2 Transmitter Fault Isolation

New section inserted.

2.3.1.2 Discretes

Text modified to expand label examples.

Reference to AIDS limitations deleted.

ORIGINAL TEXT FOLLOWS:

2.3.1.2 Discretes

In addition to handling numeric data as specified above, the Mark 33 DITS should also be capable of accommodating discrete items of information either in the unused (pad) bits of data words or, when necessary, in dedicated words. Any discrete information contained in a numeric data word assigned a label in Attachment 1 is specified in the definition for that word in Attachment 2.

The rule to be followed in the assignments of bits to discretes in numeric data words is to start with the least significant bit of the word and to continue towards the most significant bit available in the word. Attachment 6 shows that this against the background of the generalized word structure.

There are two types of discrete words. These are general purpose discrete words, and dedicated discrete words. Five labels (octal 270-274) are assigned to the general purpose words in Attachment 1. These words should be used in ascending label order (starting with octal 270) when the system receiving the data can identify its source by reference to the port at which it arrives. The dedicated words should be used when the

2.3.1.2 Discretes (cont'd)

data is intended for the AIDS DFDAU which cannot identify sources in this way.

COMMENTARY

The foregoing special provisions for the delivery of discrete data to an AIDS were made to compensate for the number of digital ports required when many ports are used is extremely difficult to achieve, which necessitated the development of the special AIDS words. These words should be limited to AIDS utilization. The few aircraft systems which deliver discretes to an AIDS by means of the Mark 33 DITS will be burdened very little by this. Similarly, the impact of label use will be small.

2.3.1.4 AIM DATA

Text added to describe unit addressing.

ORIGINAL TEXT FOLLOWS:

2.3.1.4 AIMS Data

AIM data (Acknowledgement, ISO Alphabet No. 5 and Maintenance information encoded in dedicated words) should be handled in the manner described in this Section.

All three of these applications may involve the transfer of more than 21 bits per "data package". Source equipment should format such long messages into groups of 32-bit DITS words, each word containing the relevant application label (see Attachment 1) in bit nos. 1 through 8, and a sign/status matrix code in bit nos. 30 and 31.

Bit no. 32 should be encoded to render word parity odd. The first word of each group should contain the sign/status matrix code defined for "initial word" in Section 2.1.5.1 of this document. It should also contain, in bit nos. 9 through 16, the binary representation of the number of words in the group, except that when this word is the only word to be transmitted, i.e., the total number of information bits to be transmitted is 13 or less, bit nos. 9 through 16 should all be binary "zeros".

When the word application label is assigned in Attachment 1 for Acknowledgement Data, bit nos. 17 through 29 of this initial word may be used for information transfer. When the word application label is either of those assigned in Attachment 1 for ISO Alphabet No. 5 data transfer or Maintenance Data (ISO Alphabet No. 5), bit nos. 17 through 22 should be binary "zeros" (spares) and bit nos. 23 through 29 should take on the pattern of the ISO Alphabet No. 5 control character "STX".

The second word of the ISO Alphabet No. 5 and Maintenance Data (ISO Alphabet No. 5) application groups is an optional control word containing the sign/status matrix code for "control" information for the display. When it is used, bit nos. 9 through 13 should contain the binary representation of the line count, bit nos. 14 through 16 should encode the required color, bit nos. 17 and 18 the required intensity,

bit nos. 19 and 20 the required character size and bit no. 21 should indicate whether or not the display is required to flash. See Attachment 6 to this document for the encoding standards. Bit nos. 22 through 29 of the word should be binary "zero" (spares).

Intermediate words, containing the sign/status matrix code for "intermediate word", follow the initial word of the group or the control word, when used. Intermediate words are optional in the sense that they are only transmitted if more words than the initial word and the final word (see below) are needed to accommodate the quantity of information to be transferred. When the word application group label that is assigned in Attachment 1 for Acknowledgement, Data bit nos. 9 through 29 of that word are available for information transfer. When the word application label is either of those assigned in Attachment 1 for ISO Alphabet No. 5 data transfer or Maintenance Data (ISO Alphabet No. 5), bit nos. 9 through 29 of each word should be divided into three seven-bit bytes (bit nos. 9 through 15, 16 through 22 and 23 through 29), each of which contains one ISO Alphabet No. 5 character.

Each AIM application group transmission other than single-word transmissions (see below) should be terminated with a word containing the sign/status matrix code for "final word" defined in Section 2.1.5.1 of this document. The data field of this word should be structured similarly to that of the intermediate word. Any unused bit positions in ISO Alphabet No. 5 final transfer or Maintenance Data (ISO Alphabet No. 5) final words resulting from the number of ISO Alphabet No. 5 characters in the message being one or two less than a number wholly divisible by three should be filled with binary "zeros".

2.3.1.5.1 COMMAND/RESPONSE PROTOCOL

Text modified to describe transmitter reaction to lack of "Clear to send".

ORIGINAL TEXT FOLLOWS:

2.3.1.5.1 Command/Response Protocol

File data will consist of both ARINC 429 BNR numeric words and ISO alphabet No. 5 characters. A file may contain from 1 to 127 records. Each record may contain from 1 to 126 data words.

A record will contain, at the minimum, one of the eight versions of the "initial word" described in Section 2.3.1.5.2. Records in which this initial word contains the "Data Follows" code will also contain from 1 to 126 "intermediate words" (data) and a "final word" (error control). The file data transfer protocol is as follows. A transmitter having the data to send to a receiver transmits, on the bus connecting it to that receiver, the "Request to Send" initial word. The receiver responds, on the separate bus provided for return data flow, with the "Clear to Send" reply. The transmitter then sends the "Data Follows" initial word, the "intermediate words" and the "final word". The receiver processes the error control information in the "final word" and, if no errors are revealed, closes out the transaction by

sending the "Data Received OK" word to the transmitter.

If the receiver is not ready to accept data when the transmitter sends its "Request to Send" word, it will so indicate in its response (see Section 2.3.1.5.2). The transmitter should then wait 200 milliseconds and retransmit the "Request to Send". The transmitter should also repeat a "Request to Send" transmission 50 milliseconds after the initial transmission if no response is obtained from the receiver. An alert should be raised in the system containing the transmitter if 4 attempts to obtain a "Clear to Send" response from a receiver are unsuccessful.

If the receiver detects a parity error during the transmission, it may request an error-correcting retransmission by sending a "Data Received Not OK" word to the transmitter in which is identified the record in which the error occurred. The transmitter will interrupt the data flow and back up to the start of the record so identified. It will then send a "Data Follows" initial word identifying this record as the starting point of the retransmission and recommence its output of data, continuing through the "final word". The receiver will then close out the transaction as before.

An error detected by processing the error control information in the "final word" will also result in the receiver sending a "Data Received Not OK" word to the transmitter. In the absence of identification of the record in which the error occurred, this word should contain the sequence number of the first record of the file. The transmitter's response will be to retransmit the whole file.

The receiver can signal loss of synchronization to the transmitter at any time by sending the "Synchronization Lost" initial word. On receiving this word the transmitter should curtail the data flow and back up to the beginning of the file. It should then re-establish that the receiver can accept data by going through the request-to-send/clear-to-send routine. Having done this it should send the "Data Follows" initial word, followed by the data and the "final word".

The protocol also allows a transmitter to send file size information to a receiver without any commitment to send, or request to the receiver to accept, the file itself. The "Header Information" initial word is used for this purpose. Additionally, a "Poll" initial word is defined for use in system in which continuous "handshaking" between two terminals is desired. The response to a "Poll" word will be either a "Request to Send" initial word when the polled terminal does have data to transmit, or another "Poll" word when it does not. An exchange of "Poll" words may be interpreted as the message, "I have nothing for you, do you have anything for me?"

2.4.2 INFORMATION RATES

Commentary added to describe refresh rate.

ORIGINAL TEXT FOLLOWS:

2.4.2 Information Rates

The minimum update interval for each item of information transferred by the Mark 33 DITS is specified in the tables of Attachment 2.

Discretes contained within data words will be transferred at the bit rate and repeated at the update rate of the primary data. Words dedicated to discretes should be repeated continuously at the rates defined in Attachment 2.

COMMENTARY

The time intervals between successive transmissions of a given BCD word specified in table 1 of Attachment 2 to this document are, in general, too short for the signal to be of use in driving a display device directly. If the signal was so used, the least significant character of the display would change too rapidly for human perception. Considerations other than human factors demand the time intervals specified. Thus, display designers should incorporate into their devices means for selecting those words to be used for updating the display from the greater quantity delivered.

3.1.4.2 DME

Encoding and switch functions modified.

ORIGINAL TEXT FOLLOWS:

3.1.4.2 DME

Frequency Range:	108.00MHz to 135.95MHz
Frequency Selection:	50kHz
Increment:	
Characters encoded	10MHz, 1MHz, 0.1MHz,
In DITS word:	0.01MHz, (100MHz
	Character is always
	Decimal 1)
Switching Functions:	Standby, DME Mode
	Select ILS Mode

FIGURE 3-1 Radio Systems Management Word Formats

HF and DME words modified.

ORIGINAL TEXT FOLLOWS:

DME																																		
Function	PARITY (odd)		SIGN/STATUS MATRIX																		ILS Mode		Standby		DME Mode Select		RESERVED (SDI)		LABEL DME Frequency					
Bit No.	32	31 30	29 28 27	26 25 24 23	22 21 20 19	18 17 16 15											14	13	12 11	10 9	8 7 6 5 4 3 2 1													
Example	1	0 0	0 0 1	0 0 0 1	0 1 0 1	0 0 0 0											0	0	0 0	0 0	1 0 1 1 1 0 0 0													
Notes																					[1]	[2]	[3]											

[1] Bit no. 14 should be set to “zero” for VOR frequencies and “one” for ILS frequencies by the tuning information source.

[2] [3]

Bit	Zero	One
11	DME Mode select coding per Section 4.1.6 of ARINC Char. 709	
12		
13	Standby off	Standby on

HF COM Word #1																					
Function	PARITY (odd)	SIGN/STATUS MATRIX	10MHz (2)	1MHz (3)	0.1MHz (5)	0.01MHz (7)	0.001MHz (9)												USB/LSB Mode	SSB/AM Mode Word Identifier	LABEL HF COM Frequency
Bit No.	32	31 30	29 28	27 26 25 24	23 22 21 20	09 18 17 16	15 14 13 12	11	10 9												
Example	0	0 0	1 1	0 0 1 1	0 1 0	0 1 1 1	1 0 0 1	0	0 0												
Notes								[1]	[2] [3]												

[1] Bit no. 11 should be set to “zero” for LSB operation and “one” for USB operation.

[2] Bit no. 10 should be set to “zero” for AM operation and “one” for SSB operation.

[3] Bit no. 9 should be set to “zero” when the 100 Hz option is not used and “one” when it is.

HF COM Word #2																					
Function	PARITY (odd)	SIGN/STATUS MATRIX	.1Khz (5)	NOT USED																	LABEL HF COM Frequency
Bit No. Example	32 0	31 30 0 0	29 28 27 26 0 1 0 1	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0												10 9 0 0	8 7 6 5 4 3 2 1 1 1 1 1 1 0 0 0				

Note: The HF COMM #2 word is used only when bit no. 9 of word #1 is “one”.

ATTACHMENT 1: LABEL CODES

Column “EQPT. ID (HEX)” has been added for five-character label implementation.

Table containing “Equipment ID Codes” added.

The following labels have been given new assignments:

004, 034, 056, 060-064, 070-106, 111, 114-122, 126, 127, 135, 136, 140-141, 144-162, 173-177, 202-212, 215, 217, 222-226, 242, 244-252, 256-265, 276, 310-322, 340-342, 344, 345, 347, 350, 370, 377.

Label 226 (FWC #2) deleted.

Labels 124 and 224 (C&W DFDR Discretes) deleted.

ATTACHMENT 2: DATA STANDARDS

The columns for “bandwidth”, “noise level” and “update interval” have been deleted. A column for “minimum transmit interval” has been added. The column for “transport delay” has been changed to “maximum transport delay”. A column for “EQPT.ID (HEX)” has been added.

Data standards added for new labels.

Note [2]: A nominal interval description has been added.

Note [3]: A definition for “maximum transport delay” has been added.

Note [4]: SDI assignments defined for labels 060-064.

The following tables list the parameters for which the data standards have changed. An asterisk beside a particular value designates that a new value is suggested.

TABLE 1 BCD DATA

LABEL (OCTAL)	PARAMETER NAMES	UNITS	RANGE (SCALE)	SIG. DIG.	POSITIVE SENSE	RESOL.	MAXIMUM TRANSMIT INTERVAL
010	Present Position – Lat.	Deg:Min	90S-90N*	5*		0.1	500
017	Selected Runway Heading	Deg	0-359.9	4		0.1	200*
024	Selected Course #1	Deg	0-359	3		1.0	200*
027	Selected Course #2	Deg	0-359	3			200*
033	ILS Frequency						200*
034	VOR/ILS Frequency						200*
041	Set Latitude	Deg:Min	90S-90N*	5*	N	0.1	500
065	Gross Weight	100lb.	0-10000*	5		1.0	200
067	Lateral CG	MLB-in.*	± 100.00*	4*		0.1*	200
200	Drift Angle	Deg	± 90*	3*		0.1	200
231	Total Air Temperature	°C	-60-+90*	2*		1.0	500
232	Altitude Rate	Ft/Min	± 20,000	4	Up	20.0*	62.5
233	Static Air Temperature	°C	-99-+60*	2*		1.0	500

TABLE 2 BNR DATA

LABEL (OCTAL)	PARAMETER NAME	UNITS	RANGE	SIG. BITS	POSITIVE SENSE	APPROX. RESOL.	MAXIMUM TRNASMIT INTERVAL
077	Lateral CG	MLB/in	± 128*	14*		0.001	200
100	Selected Course #1	Deg/180	± 180°	12		0.05°	50*
105	Selected Runway Heading	Deg/180	± 180°	11		0.05°	62.5*
110	Selected course #2	Deg/180	± 180°	12		0.05°	50*
173	Localizer Deviation	DDM	± 0.4	12		0.0001	62.5*
174	Glideslope Deviation	DDM	± 0.8	12		0.0002	62.5*
222	VOR Omnibearing	Deg/180	± 180°	12		0.044°	62.5*
256	Fuel Quantity #1	Lbs.	131,072	15		4	200*
257	Fuel Quantity #2	Lbs.	131,072	15		4	200*
310	Present Position – Lat.	Deg/180	0-90N-0-90S*	20		.000086°*	200

ATTACHMENT 2: DATA STANDARDS (cont'd)

ORIGINAL TEX FOLLOWS:

[2] Transmit intervals and the number of parameters to be transmitted are prime factors in bus loading. It was suggested that a Minimum Transmit Interval be specified (perhaps a value of ½ the Transmit Interval) to control bus loading. The ability of receivers to reject unwanted words would also be effective in improving bus efficiency.

Table 3.2 FCC DISCRETES – LABELS 270, 271

Existing tables replaced by new set of tables.

ORIGINAL TEXT FOLLOWS:

Table 3.2: FCC Discrettes – Labels 270, 271

Discrete Word #1

Bit No.	Function	Bit Status	
		1	0
1	Label	X	
2			X
3		X	
4		X	
5		X	
6			X
7			X
8			X
9*	Capt. Flight Director	On	Off
10*	F. O. Flight Director	On	Off
11	Turbulence Mode	Requested	Not Requested
12	Autopilot #1	Engaged	Not Engaged
13	Autopilot #2	Engaged	Not Engaged
14	RESERVED (A/P #3)	Engaged	Not engaged
15	Autothrottle #1	Armed	Not Armed
16	RESERVED (A/T #2)	Armed	Not Armed
17	Airspeed Hold Mode	Requested	Not Requested
18	Airspeed Select Mode	Requested	Not Requested
19	Mach Select Mode	Requested	Not Requested
20	Mach Hold Mode	Requested	Not Requested
21	Bank Angle Limit	See Below	
22			
23			
24	Heading Select Mode	Requested	Not Requested
25	N1/EPR Select Mode	Requested	Not Requested
26	IAS on Throttle	Requested	Not Requested
27	Mach on Throttle	Requested	Not Requested
28	Spare		
29	Spare		
30	Sign/Status		
31	Matrix		
32	Parity (Odd)		

ATTACHMENT 2: DATA STANDARDS (cont'd)Bank Angle Limit Encoding

Bit nos. 21, 22 and 23 of Discrete Word #1 should be encoded to indicate selected bank angle limit as follows:

*Bits 9 and 10, which are normally used for the SDI, have purposely been used for Discrete information.

Limit	Bit No.		
	21	22	23
Not used	0	0	0
5°	0	0	1
10°	0	1	0
15°	0	1	1
20°	1	0	0
25°	1	0	1
30°	1	1	0
Spare	1	1	1

Discrete Word #2

Bit No.	Function	Bit Status	
		1	0
1		X	
2			X
3		X	
4		X	
5		X	
6			X
7			X
8		X	
9*	Altitude Hold Mode	Requested	Not Requested
10*	Altitude Select Mode	Requested	Not Requested
11	Vertical Speed Select Mode	Requested	Not Requested
12	Vertical Speed Hold Mode	Requested	Not Requested
13	Horizontal Navigation	Requested	Not Requested
14	Vertical Navigation	Requested	Not Requested
15	Land Command	Requested	Not Requested
16	LOC Approach Command	Requested	Not Requested
17	Back Course Approach Command	Requested	Not Requested
18	CWS #1	Requested	Not Requested
19	CWS #2	Requested	Not Requested
20	CWS #3	Requested	Not Requested
21	Pitch Upper Mode Cancel	Requested	Not Requested
22	Roll Upper Mode Cancel	Requested	Not Requested
23	Heading Hold	Requested	Not Requested
24	Spare		
25			
26			
27			
28			
29	Sign/Status Matrix		
30			
31			
32			
	Parity (odd)		

* Bits 9 and 10, which are normally used for the SDI, have purposely been used for Discrete information.

TABLE 3.7 GPWS DISCRETE LABEL 270 23

Visual message bit assignments inserted.

TABLE 3.8 TCC DISCRETES LABELS 272 03, 273 03, 274 03, 275 03

New tables inserted.

ATTACHMENT 3: VOLTAGE LEVELS

Hi and Lo thresholds changed from 5-13 volts to 6.5-13 volts.

ATTACHMENT 4: INPUT/OUTPUT CIRCUIT STANDARDS

R_i increased from 6,000 to 12,000 ohms.

Total system resistance range of 300-6000 ohms changed to 400-8000 ohms.

ATTACHMENT 6: GENERAL WORD FORMATS AND ENCODING EXAMPLES

Format for alphanumeric message initial word modified.

Slat/Flap angle word added.

GMT binary word added.

Label Fields changed in discrete word and maintenance (discrete) word.

In table 6-1b note [1] deleted and bits 21 and 22 of latitude word interchanged.

In Table 6-2 examples corrected for Present Position (Latitude and Longitude).

Radio Height word added.

ORIGINAL TEXT FOLLOW:

P 32	SSM 31 (01) 30	29	"STX"	23	22 (Zeros)	17	WORD COUNT 16 BNR EQUIV.	9	8	LABEL (356/357)	1
---------	-------------------	----	-------	----	------------	----	-----------------------------	---	---	--------------------	---

ALPHA NUMERIC (ISO ALPHABET NO. 5) DATA – INITIAL WORD FORMAT

P 32	SSM 31 (00) 30	29	MSB	2	DISCRETES LSB	11	SDI 10 9	8	LABEL (270-274)	1
---------	-------------------	----	-----	---	------------------	----	-------------	---	--------------------	---

DISCRETE WORD FORMAT

P 32	SSM 31 (00) 30	29	MSB	MAINTENANCE DISCRETES	DISCRETES LSB	11	SDI 10 9	8	LABEL (350-354)	1
---------	-------------------	----	-----	-----------------------	------------------	----	-------------	---	--------------------	---

MAINTENANCE (DISCRETE) WORD FORMAT

APPENDIX 3: DIGITAL SYSTEMS GUIDANCE (PART 1)

Appendix added.

APPENDIX 4: DIGITAL SYSTEM GUIDANCE (PART 2)

Appendix added.

AERONAUTICAL RADIO, INC.
2551 Riva Road
Annapolis, Maryland 21401 – 7645 USA

SUPPLEMENT 5
TO
ARINC SPECIFICATION 429
MARK 33 DIGITAL INFORMATION TRANSFER SYSTEM (DITS)

Published: April 4 1981

A. PURPOSE OF THIS SUPPLEMENT

This Supplement introduces material on fault detection, transmit intervals for words using multiple SDI codes, modification of IRS/AHRS discrete formats, expansion of error control definition, revision of ILS word, addition of new labels and change of existing data standards.

B. ORGANIZATION OF THIS SUPPLEMENT

The first part of this document, printed on goldenrod paper, contains descriptions of the changes introduced into the Specification by this Supplement, and, where appropriate, extracts from the original text for comparison purposes. The second part consists of replacement white pages for the Specification, modified to reflect these changes. The modified and added material on each replacement page is identified with “c-5” symbols in the margins. Existing copies of Specification 429 may be updated by simply inserting the replacement white pages where necessary and destroying the pages they replace. The goldenrod pages should be inserted inside the rear cover of the Specification.

Copies of the Specification bearing the number 429-5 already contain this Supplement and thus do not require revisions by the reader.

C. CHANGES TO SPECIFICATION 429 INTRODUCED BY THIS SUPPLEMENT

This section presents a complete tabulation of the changes and additions to the Specification introduced by this Supplement. Each change or addition is entitled by the section number and title currently employed in the Specification, or by the section number and title that will be employed when the Supplement is eventually incorporated. In each case there is included a brief description of the addition or change and, for other than very minor revisions, any text originally contained in the Specification is reproduced for reference.

2.2.1 TRANSMISSION SYSTEM INTERCONNECT

Text revised for break connections.

Text added to Commentary describing increase of voltage threshold.

ORIGINAL TEXT FOLLOWS:

2.2.1 Transmission System Interconnect

A data source should be connected to the data sink(s) by means of a single twisted and shielded pair of wires. The shields should be grounded at both ends and at all production breaks in the cable to an aircraft ground close to the rack connector.

COMMENTARY

In practical wire line digital information transmission systems, cable characteristics and electrical mismatches can produce distortion of the digital data pulses. Also, noise due to electrical interference perturbs digital signals. The

performance of a digital receiver depends upon the receiver input signal characteristics (data with distortion and noise) and the receiver design.

Prior to the selection of the voltage and impedance parameters set forth in this Section of this document, the pulse distortion likely to be encountered in systems built around them in existing size commercial aircraft was evaluated and judged to be acceptable for a well-designed receiver. No restriction is placed by this specification, therefore, on the number or length of stubs for installations on aircraft no larger than those existing, e.g., B 747. See Appendix 1 to this document for a report of this investigation.

Tests have shown that some receivers continue decoding data properly when one side of the transmission line is open or shorted to ground. When this condition exists noise immunity decreases and intermittent operation may occur. Users desire protection against non-annunciated system operation in this mode. This protection may consist of additional circuitry to detect and annunciate the fault.

2.2.3.2 RECEIVER VOLTAGE LEVELS

Normal voltage ranges changed due to impedance changes.

ORIGINAL TEXT FOLLOWS:

2.2.3.2 Receiver Voltage Levels

The differential voltage presented at the receiver input terminals will be dependent upon line length, stub configuration and the number of receivers connected. In the absence of noise, the normal ranges of voltages presented to the receiver terminals (A and B) would be:

“HI” +6.5V to 10V
“NULL” +2.5V to –2.5V
“LO” –6.5V to –13V

In practice, these nominal voltages will be perturbed by noise and pulse distortion. Thus, receivers should associate the following voltage ranges with the three states indicated:

“HI” +6.5V to 13V
“NULL” +2.5V to –2.5V
“LO” –6.5V to –13V

COMMENTARY

Receiver reaction is currently undefined in Specification 429 for voltages that fall in the range just above and below the “NULL” range. Respective equipment Characteristics should be referenced for desired receiver response in this range. However, it is desirable that all DITS receivers will discontinue operation when the voltage levels fall into the undefined regions. Manufacturers are urged, as new equipment is developed, to “design in” the rejection capability.

The opinion is held by some people that conditions on transmission lines will be encountered which will require receivers to operate with less than the

above-defined minimum difference of 4.0V between the NULL and HI and NULL and LO states. Receiver designers are encouraged to investigate the possibilities and problems of working with a minimum difference of 1 volt between these states and to report their findings.

Receiver input common mode voltages (terminal A to ground and terminal B to ground) are not specified because of the difficulties of defining ground with any satisfactory degree of precision. Receiver manufacturers are encouraged to work with the differential input voltage (line A to line B) and not line-to-ground voltages.

2.3.1.5.4 FINAL WORDS

Text added to define checksum.

ORIGINAL TEXT FOLLOWS:

2.3.1.5.4 Final Words

The final word of each record contains error control information. Bit nos. 1 through 8 contain the file label. Bit nos. 9 through 29 contain an error control checksum computed from the states of bit nos. 9 through 31 of each intermediate word of the record. Bit nos. 30 and 31 of this word contain the code identifying it as a final word. Bit no. 32 is encoded to render word parity odd.

2.3.4 ERROR DETECTION/CORRECTION

Obsolete text deleted.

ORIGIANL TEXT FOLLOWS:

2.3.4 Error Detection/Correction

The last bit of each word should be encoded such that word parity is rendered odd to allow error detection in receivers. Note that the parity calculation encompasses all 31 label and information bits of the word. The Mark 33 DITS contains no provisions for message retransmission, the inclusion of redundant bits in words or other means of error correction.

Fig. 3-1: RADIO SYSTEMS MANAGEMENT WORD FORMATS

Bits 3 and 7 of transponder word changed to “0”. (editorial)

Bit 11 and 12 assigned to ILS category designation.

Control Panel Function Matrix added to transponder word.

ORIGINAL MATERIAL ON NEXT PAGE:

2.4.2 INFORMATION RATES

Text added to describe transmission of labels with multiple SDI codes.

ORIGINAL TEXT FOLLOWS:

2.4.2 Information Rates

The minimum and maximum transmit intervals for each item of information transferred by the Mark 33 DITS are specified in the tables of Attachment 2.

COMMENTARY

There are no values given for refresh rates in this Specification. However, it is desirable that data be refreshed at least once per transmission. Those data actually requiring long processing times or a large number of samples are the only types not expected to be refreshed with every transmission.

Discretes contained within data words should be transferred at the bit rate and repeated at the update rate of the primary data. Words dedicated to discretes should be repeated continuously at the rates defined in Attachment 2.

COMMENTARY

The time intervals between successive transmissions of a given BCD word specified in table 1 of Attachment 2 to this document are, in general, too short for the signal to be of use in driving a display device directly. If the signal was so used, the least significant character of the display would change too rapidly for human perception. Considerations other than human factors demand the time intervals specified. Thus, display designers should incorporate into their devices means for selecting those words to be used for updating the display from the greater quantity delivered.

Fig. 3-1: RADIO SYSTEMS MANAGEMENT WORD FORMATS (cont'd)

ILS																																
Function	PARITY (odd)	SIGN/STATUS MATRIX																							LABEL ILS Frequency							
			10MHz (0)				1MHz (9)				0.1MHz (3)				0.01MHz (0)				SPARE	SPARE	SPARE	SPARE	RESERVED (SDI)									
Bit No.	32	31 30	29 28 27	26 25 24 23	22 21 20 19	18 17 16 15	14	13	12	11	10 9									8 7 6 5 4 3 2 1												
Example	1	0 0	0 0 0	1 0 0 1	0 0 1 1	0 0 0 0	0	0	0	0	0 0									1 1 0 1 1 0 0 0												

ATTACHMENT 1: LABEL CODES

The following labels have been given new assignments:

073 02, 073 A2, 112 02, 130 1A, 131 2D, 132 1A, 133 1A, 151 02, 154 02, 164 02, 164 03, 174 03, 205 1A, 207 0A, 211 1A, 215 1A, 242 1A, 245 0A, 256 0A, 260 31, 262 0A, 263 0A, 264 0A, 265 0A, 270 1A, 270 1E, 270 30, 271 06, 271 1A, 271 1E, 272 1A, 274 0A, 275 2B, 300 1A, 301 1A, 303 1A, 304 1A, 305 1A, 306 1A, 307 1A, 325 1A, 340 1A, 340 2D, 341 1A, 342 1A, 344 1A, 345 1A, 346 1A, 350 1A, 351 1A, 352 1A, 353 1A, 354 1A.

Label 242** was deleted.

Label 316 04 changed form “Wind Angle” to “Wind Direction (True)”.

ATTACHMENT 1: EQUIPMENT CODES

New assignments were made for 0A and 2D.

Note added to 1A.

ATTACHEMENT 2: DATA STANDARDS

Data standards were added for new labels.

The following table lists the parameters for which the existing data standards have changed. An asterisk beside a particular value designates that a new value is suggested.

LABEL	EQPT ID (HEX)	PARAMETER NAME	UNITS	RANGE	SIG. DIG/ BITS	POS. SENSE	RESOL	MIN. TR. INT.	MAX. TR. INT.
004	01	Runway Distance to Go	Feet	0-79900	3		100.0	200*	400*
165	07	Radio Height	Feet	± 0-7999.9	5		0.1	100*	200*
205	06	Mach	mMach*	4096*	13*		0.5*	62.5	125
210	06	True Airspeed	Knots	2048*	13*		0.25*	62.5	125
215	06	Impact Pressure	mb	512*	9*		1.0*	62.5	125
242	06	Total Pressure	mb	2045*	11*		1.0*	62.5	125
313	04	Track Angle True	Deg/180	± 180°	12*		0.05°	25	50
314	04	True Heading	Deg/180	± 180°	12*		0.05°	25	50
317	04	Track Angle Magnetic	Deg/180	± 180°	12*		0.05°	25	50
317	05	Track Angle Magnetic	Deg/180	± 180°	12*		0.05°	25	50
320	04	Magnetic Heading	Deg/180	± 180°	12*		0.05°	25	50
320	05	Magnetic Heading	Deg/180	± 180°	12*		0.05°	25	50
323	04	Flight Path Acceleration	g	2*	14*		0.0001*	10	20
323	05	Flight Path Acceleration	g	2*	14*		0.0001*	10	20
324	04	Pitch Angle	Deg/180	± 180°	14		0.01°	25*	50*
324	05	Pitch Angle	Deg/180	± 180°	14		0.01°	25*	50*
325	04	Roll Angle	Deg/180	± 180°	14		0.01°	25*	50*
325	05	Roll Angle	Deg/180	± 180°	14		0.01°	25*	50*
360	04	Potential Vertical Speed	Ft/min	16384*	10*		16*	25	50
360	05	Potential Vertical Speed	Ft/min	16384*	10*		16*	25	50
361	04	Altitude (Inertial)	Feet	131,072	18*		0.5*	32.25*	62.5*
361	05	Altitude (Inertial)	Feet	131,072	18		0.5	31.25*	62.5*
365	04	Inertial Vert. Vel. (EFI)	Ft/min	16384*	10*		16*	20	40
365	05	Inertial Vert. Vel. (EFI)	Ft/min	16384*	10*		16*	20	40
375	05	Along Heading Accel.	g	4	12		0.001	25*	50*
376	05	Cross Heading Accel.	g	4	12		0.001	25*	50*

Note [2]: Guidance added for transmission intervals of labels with multiple SDI codes.

ORIGINAL TEXT FOLLOWS:

- [2] Transmit intervals and the number of parameters to be transmitted are prime factors in bus loading. The interval for transmission of parameters should fall between the minimum and maximum specified intervals and nominally should be near the center of the range at equal intervals between transmissions. When heavy bus loading dictates a shift from the center of the range, the shift should be toward the maximum transmit interval.

TABLE 3.1: INTERVAL DISCRETES – LABEL 270

Discrete word formats revised.

ORIGINAL TEXT FOLLOWS:

Table 3.1: Inertial Discretes – Label 270

Bit No.	Function	Bit Status	
		1	0
1	Label	x	
2			x
3		x	
4		x	
5		x	
6	SDI		x
7			x
8			x
9			
10			
11	Icing Detector	On	Off
12	Pitot Probe Heat	On	Off
13	ADS Computer	Fail	Good
14	Pitot/Static	On	Off
15	Static S	On	Off
16	TAT	On	Off
17	Angle of Attack Sensor	On	Off
18	Right Side Angle of Attack Sensor	On	Off
19	VMO/MMO Overspeed Warning	Warn	Not Warn
20	Spare		
21			
22			
23			
24			
25	SSM		
26			
27			
28			
29			
30	Parity (Odd)		
31			
32			

- Notes: [1] Attitude invalid is equivalent to IRS failure.
[2] Bit 14 "1" condition indicates that the "Magnetic Heading" outputs are no longer being computer and have the characteristics of a "free DG" which is subject to control by a "Set Heading" input to the IRU. (See Section 3.2.4 for further explanation).

TABLE 3.4: AIR DATA DISCRETES

Discrete word #1 format changed.

Discrete word #2 added.

ORIGINAL TEXT FOLLOWS:

Table 3.4: Air Data Discretes – Label 270

Bit No.	Function	Bit Status	
		1	0
1	Label	x	
2			x
3		x	
4		x	
5		x	
6	SDI		x
7			x
8			x
9			
10			
11	Align Mode/Not Read	Yes	No
12	Reversionary Atti	Yes	No
13	Normal Mode	Yes	No
14	Set Heading	Yes	No
16	Low Bat	Yes	No
17	On R	Yes	No
18	T	Yes	No
19	Maintenance Monitor Codes		
20			
21			
22			
23			
24	SSM		
25			
26			
27			
28			
29	Parity (Odd)		
30			
31			
32			

ATTACHMENT 6 – GENERAL WORD FORMATS AND ENCODING EXAMPLES

Examples revised to agree with adopted data standards changes. (editorial)

AERONAUTICAL RADIO, INC.
2551 Riva Road
Annapolis, Maryland 21401 – 7645 USA

SUPPLEMENT 6
TO
ARINC SPECIFICATION 429
MARK 33 DIGITAL INFORMATION TRANSFER SYSTEM (DITS)

Published: January 22, 1982

Prepared by the Airlines Electronic Engineering Committee
Adopted by the Airlines Electronic Engineering Committee: December 9, 1981

A. PURPOSE OF THIS SUPPLEMENT

This Supplement introduces the assignment of octal labels and hexadecimal equipment identifiers, the addition of guidance for label selection, a revision of failure warning annunciation in discrete words, deletion of the weight & balance words, editorial revisions to the label tables and addition of EEC discrete word formats.

B. ORGANIZATION OF THIS SUPPLEMENT

The first part of this document, printed on goldenrod paper, contains descriptions of the changes introduced into the Specification by this Supplement, and, where appropriate, extracts from the original text for comparison purposes. The second part consists of replacement white pages for the Specification, modified to reflect these changes. The modified and added material on each replacement page is identified with “c-6” symbols in the margins. Existing copies of Specification 429 may be updated by simply inserting the replacement white pages they replace. The goldenrod pages should be inserted inside the rear cover of the Specification.

Copies of the Specification bearing the number 429-6 already contain this Supplement and thus do not require revisions by the reader.

C. CHANGES TO SPECIFICATION 429 INTRODUCED BY THIS SUPPLEMENT

This section presents a complete tabulation of the changes and additions to the Specification introduced by this Supplement. Each change or addition is entitled by the section number and title currently employed in the Specification, or by the section number and title that will be employed when the Supplement is eventually incorporated. In each case there is included a brief description of the addition or change and, for other than very minor revisions, any text originally contained in the Specification is reproduced for reference.

2.1.5.1 BCD, NUMERIC, DISCRETE, AIM DATA AND FILE TRANSFER WORDS

Commentary revised to reflect use of failure warning flags in discrete words.

ORIGINAL TEXT FOLLOWS:

COMMENTARY

Definitions

Invalid Data – is defined as any data generated by a source system whose fundamental characteristic is the inability to convey reliable information for the proper performance of a user system. There are two categories of invalid data namely, “No Computed Data” and “Failure Warning”.

No Computes Data – is a particular case of data invalidity where the source system is unable to compute reliable data for reasons other than system failure. This inability to compute reliable data is caused exclusively be a definite set of events or

conditions whose boundaries are uniquely defined in the system characteristic. When such a condition exists, the source system should annunciate its outputs to be invalid by setting the sign/status matrix of the affected words to the “NCD” code, as defined in sections 2.1.5.1 and 2.1.5.2. The system indicators may or may not be flagged depending on system requirements.

Failure Warning – is a particular case of data invalidity where the system monitors have detected one or more failures. These failures are uniquely characterized by boundaries defined in the system characteristic. When such a condition exists, the source system should annunciate its outputs to be invalid by either ceasing to supply the affected words to the data bus (the case of BCD data and ILS-LRRA installations with provisions for the interruption of AFS BNR data – see ARINC characteristics 707 and 710) or by setting the sign/status matrix of the affected words to the “Failure Warning” code (BNR case), as defined in sections 2.1.5.1 and 2.1.5.2. The system indicators should always be flagged during a “Failure Warning” condition.

2.1.5.2 BNR NUMERIC DATA WORDS

Commentary for failure warning revised.

ORIGINAL TEXT FOLLOWS:

COMMENTARY

Definitions

Invalid Data – is defined as any data generated by a source system whose fundamental characteristic is the inability to convey reliable information for the proper performance of a user system. There are two categories of invalid data, namely, “No Computed Data” and “Failure Warning”.

No Computed Data – is a particular case of data invalidity where the source system is unable to compute reliable data for reasons other than system failure. This inability to compute reliable data is caused exclusively by a definite set of events or conditions whose boundaries are uniquely defined in the system characteristic. When such a condition exists the source system should annunciate its outputs to be invalid by setting the sign/status matrix of the affected words to the “NCD” code, as defined in sections 2.1.5.1 and 2.1.5.2. The system indicators may or may not be flagged depending on system requirements.

Failure Warning – is a particular case of data invalidity where the system monitors have detected one or more failures. These failures are uniquely characterized by boundaries defined in the system characteristic. When such a condition exists, the source system should annunciate its outputs to be invalid by either ceasing to supply the affected words to the data bus (the case of BCD data and ILS-LRRA Installations with provisions for the interruption of AFS BNR data – see ARINC Characteristics 707 and 710) or by setting the

↑ sign/status matrix of the affected words to the “Failure Warning” code (BNR case), as defined in sections 2.1.5.1 and 2.1.5.2. The system indicators should always be flagged during a “Failure Warning” conditions.

Fig. 3.1 RADIO SYSTEMS MANAGEMENT WORD FORMATS

Assignments for bits 12, 15 and 17 removed from table for note 1 of ATC transponder word (editorial).

ATTACHMENT 1: LABEL CODES

The following labels have been given new assignments:

021 02, 041 02, 042 02, 043 02, 066 02, 071 33, 072 2F, 072 33, 074 33, 075 02, 077 02, 114 2F, 115 2F, 130 2F, 131 2F, 132 33, 133 2F, 155 33, 156 33, 157 33, 160 33, 161 33, 241 2C, 244 33, 250 2B, 252 2F, 260 33, 261 33, 262 02, 262 33, 263 33, 264 2F, 264 33, 265 33, 267 0A, 267 33, 270 2F, 270 3A, 271 2F, 271 3A, 273 2F, 272 2F, 273 33, 274 2F, 274 33, 275 2F, 315 02, 340 2F, 341 2F, 342 2F, 344 2F, 344 33, 345 2F, 346 2F, 350 2F, 351 2E, 351 2F, 352 2E, 352 2F, 353 2F, 354 2F, 375 33, 376 33.

The following labels have been deleted:

060 32, 061 32, 062 32, 063 32, 064 32.

Editorial changes were made to provide for consistency between Attachment 1 and Attachment 2.

“Predictive” deleted from 207 0A.

ATTACHMENT 1: EQUIPMENT CODES

New assignments were made for 0D, 2E, 2F, 3A, 3B, 33, and 34.

Nomenclature modified for 2C and 32.

ATTACHMENT 2: DATA STANDARDS

Data standards were added for new labels.

Editorial changes made.

Resolutions revised for 315 04, 315 05, 316 04, 321 04, 321 05, 322 04, 334 04, and 334 05 to match ARINC 704 and 705.

EEC discrete words added.

ATTACHMENT 6: GENERAL WORD FORMATS AND CODING EXAMPLES

Format added for label 262 02.

Bit 12 corrected in DME distance word (editorial).

Example added for GMT binary word.

APPENDIX 5: LABEL SELECTION GUIDANCE

Appendix added.

AERONAUTICAL RADIO, INC.
2551 Riva Road
Annapolis, Maryland 21401 7645 USA

SUPPLEMENT 7
TO
ARINC SPECIFICATION 429
MARK 33 DIGITAL INFORMATION TRANSFER SYSTEM (DITS)

Published: January 3, 1983

Prepared by the Airlines Electronic Engineering Committee
Adopted by the Airlines Electronic Engineering Committee: November 4, 1982

A. PURPOSE OF THIS SUPPLEMENT

This Supplement introduces new label assignments, data standards and equipment identification codes, and means for transmitting data with reduced accuracy.

B. ORGANIZATION OF THIS SUPPLEMENT

The first part of this document, printed on goldenrod paper, contains descriptions of the changes introduced into the Specification by this Supplement, and, where appropriate, extracts from the original text for comparison purposes. The second part consists of replacement white pages for the Specification, modified to reflect these changes. The modified and added material on each replacement page is identified with “c-7” symbols in the margins. Existing copies of Specification 429 may be updated by simply inserting the replacement white pages they replace. The goldenrod pages should be inserted inside the rear cover of the Specification.

Copies of the Specification bearing the number 429-7 already contain this Supplement and thus do not require revisions by the reader.

C. CHANGES TO SPECIFICATION 429 INTRODUCED BY THIS SUPPLEMENT

This section presents a complete tabulation of the changes and additions to the Specification introduced by this Supplement. Each change or addition is entitled by the section number and title currently employed in the Specification, or by the section number and title that will be employed when the Supplement is eventually incorporated. In each case there is included and, for other than very minor revisions, any text originally contained in the Specification is reproduced for reference.

2.1.5.1 BCD, NUMERIC, DISCRETE, AIM DATA AND FILE TRANSFER WORDS

Note [6] added.

2.1.5.2 BNR NUMERIC DATA WORDS

Note [6] added.

ATTACHMENT 1 – LABEL CODES

The following labels have been given new assignments:

046 33, 047 33, 114 3F, 115 3F, 127 33, 130 30, 130 3F, 131 30, 131 33, 132 30, 133 3F, 164 3B, 173 3B, 174 3B, 175 33, 212 3B, 242 3B, 244 3B, 245 3B, 246 3B, 247 3B, 252 3F, 264 3F, 270 30, 270 33, 270 3B, 270 3F, 271 30, 271 33, 271 3B, 271 3F, 272 3B, 272 3F, 273 3B, 273 3F, 274 3B, 274 3F, 275 3B, 275 3F, 311 3B, 214 3B, 325 2F, 325 3F, 340 33, 340 3F, 341 3F, 342 3B, 342 3F, 344 3F, 345 3F, 346 33, 346 3F, 347 30, 350 3F, 351 3F, 352 3F, 353 3F, 354 3F, 377 30.

The terminology has been modified for the following labels:

072 33, 074 33, 132 33, 244 33, 262 33, 263 33, 264 33, 265 33.

Station identifiers deleted on engine related parameters.

ATTACHMENT 1 – EQUIPMENT CODES

Code 2F changed from “EEC (Full Authority)” to “Full Authority EEC-A”.

Code 30 assigned as “Airborne Separation Assurance System”.

Description of Code OD changed to “AIDS Data Management Unit (DMU)”

Code 3F assigned as “Full Authority EEC_B”.

ATTACHMENT 2 – DATA STANDARDS

Data standards were added for new labels.

Data standards added for the following existing labels:

270 3A, 271 3A, 270 2F-275 2F, 350 2F, -354 2F.

Note added to label 072 33.

Digits of label 014 changed from 3 to 4 (previously adopted).

Range of label 014 changed from 359 to 359.9 (previously adopted). Significant bits of label 321 changed from 12 to 11 (typo).

Note [4] added.

Note [5] added.

Note flag [5] added to following labels:

074 2C, 075 2C, 247 2C 250 2C, 256 2C, 257 2C, 260 2C, 262 2C.

ATTACHMENT 6 – GENERAL WORD FORMATS AND ENCODING EXAMPLES

Formats for engine serial number words added.

Formats for ASAS words added.

AERONAUTICAL RADIO, INC.
2551 Riva Road
Annapolis, Maryland 21401 – 7645 USA

SUPPLEMENT 8
TO
ARINC SPECIFICATION 429
MARK 33 DIGITAL INFORMATION TRANSFER SYSTEM (DITS)

Published: December 3, 1984

Prepared by the Airlines Electronic Engineering Committee
Adopted by the Airlines Electronic Engineering Committee: November 4, 1983

A. PURPOSE OF THIS SUPPLEMENT

This Supplement introduces new label assignments, revised data standards, expanded text describing SDI codes and makes note of a change in the resolution of the Magnetic Heading label incorporated in Supplement 7.

B. ORGANIZATION OF THIS SUPPLEMENT

The first part of this document, printed on goldenrod paper, contains descriptions of the changes introduced into the Specification by this Supplement, and, where appropriate, extracts from the original text for comparison purposes. The second part consists of replacement white pages for the Specification, modified to reflect these changes. The modified and added material on each replacement page is identified with “c-8” symbols in the margins. Existing copies of Specification 429 may be updated by simply inserting the replacement white pages they replace. The goldenrod pages should be inserted inside the rear cover of the Specification.

Copies of the Specification bearing the number 429-8 already contain this Supplement and thus do not require revisions by the reader.

C. CHANGES TO SPECIFICATION 429 INTRODUCED BY THIS SUPPLEMENT

This section presents a complete tabulation of the changes and additions to the Specification introduced by this Supplement. Each change or addition is entitled by the section number and title currently employed in the Specification, or by the section number and title that will be employed when the Supplement is eventually incorporated. In each case there is included a brief description of the addition or change and, for other than very minor revisions, any text originally contained in the Specification is reproduced for reference.

2.1.4 SOURCE DESTINATION IDENTIFIER

Text added to clarify use of SDI on combined source/sink equipment.

ORIGINAL TEXT FOLLOWS:

2.1.4 Source/Destination Identifier

Bit nos. 9 and 10 of numeric data words should be reserved for a data source/destination identification function. They are not available for this function in alpha/numeric (ISO Alphabet No. 5) data words (See Section 2.3.1.3 of this document) or when the resolution needed for numeric (BNR/BCD) data necessitates their use for valid data. The source/destination identifier function may find application when specific words need to be directed to a specific system of a multi-system installation or when the source system of a multi-system installation needs to be recognizable from the word content. When it is used, a source equipment should encode its aircraft installation number in bit nos. 9 and 10 as shown in the table below. A sink equipment should recognize words containing its own installation number code and words containing code “00”, the “all-call” code.

Bit No.		Installation No.
10	9	
0	0	See Note Below
0	1	1
1	0	2
1	1	3

Note: In certain specialized application of the SDI function the all-call capability may be forfeited so that code “00” is available as an “installation no. 4” identifier.

When the SDI function is not used, binary zeros or valid data should be transmitted in bit nos. 9 and 10.

COMMENTARY

This document does not address the practical question of how the SDI bits will be set in those multi-installation systems in which the source/destination function is desired. One way would be to use program pins on the individual installation black boxes which would be wired to set up the appropriate code. The ARINC Characteristics devoted to the individual systems will define the method actually to be used.

ATTACHMENT 1 – LABEL CODES

The following labels have been given new assignments:

012 25, 060 3C, 061 3C, 062 3C, 063 3C, 064 3C, 137 2F, 137 3F, 140 25, 141 25, 142 25, 151 27, 152 27, 153 27, 154 27, 155 27, 156 27, 157 27, 160 27, 161 27, 162 27, 163 27, 164 25, 164 27, 165 27, 170 C5, 173 25, 270 25, 271 C5, 272 C5, 273 C5, 274 25, 275 25, 313 25, 314 25, 317 25, 320 25, 324 25, 325 25, 330 2F, 330 3F, 331 2F, 332 2F, 332 3F, 333 3F, 334 2F, 334 3F, 350 25, 351 25, 352 25, 353 25, 370 C5.

ATTACHMENT 1 - EQUIPMENT CODES

Code 3C assigned to Tire Pressure System.

ATTACHMENT 2 – DATA STANDARDS

Table 1 had been modified in Supplement 7 to reflect the resolution of label 014 as 0.1, rather than 1.0, which had been incorrectly introduced in a previous Supplement. This change is hereby noted.

Data standards added for new labels.

Data standards revised for labels 115 2F, 115 3F, 325 2F, 325 3F.

ATTACHMENT 6 – GENERAL WORD FORMATS

Tire pressure SDI bit coding added.

AERONAUTICAL RADIO, INC.
2551 Riva Road
Annapolis, Maryland 21401 – 7645 USA

SUPPLEMENT 9
TO
ARINC SPECIFICATION 429
MARK 33 DIGITAL INFORMATION TRANSFER SYSTEM (DITS)

Published: April 30, 1985

Prepared by the Airlines Electronic Engineering Committee
Adopted by the Airlines Electronic Engineering Committee: October 11, 1984

A. PURPOSE OF THIS SUPPLEMENT

This Supplement introduces new label assignments and equipment identification codes. This Supplement also corrects a word format bit error introduced in a previous Supplement.

B. ORGANIZATION OF THIS SUPPLEMENT

The first part of this document, printed on goldenrod paper, contains descriptions of the changes introduced into the Specification by this Supplement, and, where appropriate, extracts from the original text for comparison purposes. The second part consists of replacement white pages for the Specification, modified to reflect these changes. The modified and added material on each replacement page is identified with "c-9" symbols in the margins. Existing copies of Specification 429 may be updated by simply inserting the replacement white pages they replace. The goldenrod pages should be inserted inside the rear cover of the Specification.

Copies of the Specification bearing the number 429-9 already contain this Supplement and thus do not require revisions by the reader.

**C. CHANGES TO SPECIFICATION 429
INTRODUCED BY THIS SUPPLEMENT**

This section presents a complete tabulation of the changes and additions to the Specification introduced by this Supplement. Each change or addition is entitled by the section number and title currently employed in the Specification, or by the section number and title that will be employed when the Supplement is eventually incorporated. In each case there is included a brief description of the addition or change and, for other than very minor revisions, any text originally contained in the Specification is reproduced for reference.

ATTACHMENT 1 – LABEL CODES

The following labels have been given new assignments:

075 3E, 076 3E, 103 1B, 104 1B, 105 1B, 106 1B, 107 1B, 130 35, 131 35, 132 35, 203 18, 270 1B, 270 35, 270 3E, 270 4A, 271 18, 271 35, 272 18, 272 35, 273 18, 273 35, 274 18, 274 35, 275 18, 275 4A, 276 18, 300 3D, 336 1A, 337 1A, 347 18, 347 35, 350 18, 350 35, 350 3E, 370 04, and 370 05.

ATTACHMENT 1 – EQUIPMENT CODES

Codes 3D, 3E, 4A, 4B, 4C and 90-9F given new assignments.

ATTACHMENT 2 – DATA STANDARDS

Data standards entered for new labels. Range for labels 012 and 170 changed to 7999.

**ATTACHMENT 6 – GENERAL WORD FORMATS
AND ENCODING EXAMPLES**

Label 150 and 323 examples corrected.

AERONAUTICAL RADIO, INC.
2551 Riva Road
Annapolis, Maryland 21401 – 7645 USA

SUPPLEMENT 10
TO
ARINC SPECIFICATION 429
MARK 33 DIGITAL INFORMATION TRANSFER SYSTEM (DITS)

Published: November 17, 1986

Prepared by the Airlines Electronic Engineering Committee
Adopted by the Airlines Electronic Engineering Committee: November 7, 1985

A PURPOSE OF THIS SUPPLEMENT

This Supplement introduces new label assignments, equipment identification codes and revised data standards.

B. ORGANIZATION OF THIS SUPPLEMENT

The first part of this document, printed on goldenrod paper, contains descriptions of the changes introduced into the Specification by this Supplement, and, where appropriate, extracts from the original text for comparison purposes. The second part consists of replacement white pages for the Specification, modified to reflect these changes. The modified and added material on each replacement page is identified with “c-10” symbols in the margins. Existing copies of Specification 429 may be updated by simply inserting the replacement white pages they replace. The goldenrod pages should be inserted inside the rear cover of the Specification.

Copies of the Specification bearing the number 429-10 already contain this Supplement and thus do not require revisions by the reader.

C. CHANGES TO SPECIFICATION 429 INTRODUCED BY THIS SUPPLEMENT

This section presents a complete tabulation of the changes and additions to the Specification introduced by this Supplement. Each change or addition is entitled by the section number and title currently employed in the Specification, or by the section number and title that will be employed when the Supplement is eventually incorporated. In each case there is included a brief description of the addition or change and, for other than very minor revisions, any text originally contained in the Specification is reproduced for reference.

3.1.4 FREQUENCY RANGES AND SWITCHING FUNCTIONS

Note 6 deleted on DME Frequency Word.

Attachment 1 – Label Codes

The following labels have been given new assignments:

072 02, 075 0B, 076 0B, 077 0B, 176 5A, 177 5A, 200 5A, 201 5A, 202 5A, 203 5A, 204 5A, 205 5A, 206 18, 213 8D, 227 7E, 241 4D, 242 09, 242 10, 242 11, 242 12, 244 8D, 247 4D, 251 1A, 255 2F, 255 3F, 256 4D, 270 0B, 272 3A, 272 5A, 273 5A, 274 5A, 275 5A, 276 2F, 276 3F, 335 2F, 336 2F, 336 3F, 356 XX, 371 00.

Labels for ARINC Characteristic 737 WBT and ARINC Characteristic 738 ADIRS added.

Attachment 1 – Equipment Codes

The following codes have been given new assignments:

0B, 35, 36, 37, 38, 4D, 4E, 5A, 5B, 5C, 5D, 5E, 5F, 6A, 6B, 6C, 6D, 6E, 6F, 7A, 7B, 7C, 7D, 7E, 7F, 8A, 8B, 8C, 8D, AD, C3.

Attachment 2 – Data Standards

Data standards entered for new labels.

Data standards revised for the following labels:

060 36, 061 3C, 062 3C, 063 3C, 064 3C, 150 31, 176 03, 176 29, 270 3A, 270 2F, 270 3F, 271 2F, 271 3F, 272 2F, 272 3F, 273 2F, 273 3F, 274 2F, 274 3F, 275 2F, 275 3F, 350 2F, 350 3F, 351 2F, 351 3F, 352 2F, 352 3F, 353 2F, 353 3F, 354 2F, 354 3F.

Labels 060 37-064 3C significant bits changed from 9 to 10 and range changed from 512 to 1024.

Following note added to words (labels 270 3B-275 3B):

Typical discrete functions are shown in the above tables. Slight variations of bit usage may arise according to the specific application.

Label 203 35 changed to 203 18 (typographical error).

Transmit interval range added to label 150 31.

Labels 176 03 and 176 29 resolutions changed from 0.05 to 0.5 (typographical error).

Original bit assignments for remaining labels listed in following pages.

Attachment 6 – General Word Formats and Encoding Examples

Example added for label 251 1A, 077 0B and 206 18.

For TPIS word formats:

Wheel #519 label corrected to read “060”. SDI labels clarified.

For BTMS word formats:

Wheel #10, #11, #12 labels corrected to read “116”. Bit 27 assigned to a value of “1024”. SDI labels clarified.

Special expanded format word example added for label 260 31.

Attachment 9A – General Aviation Labels and Data Standards

New attachment added.

Attachment 9B – General Aviation Word Examples

New attachment added.

Attachment 9C – General Aviation Equipment Identifiers

New attachment added.

Table 3.11 Propulsion Discrete Interface Unit – Labels 270 3A and 271 3A

Label 270 3A

Bit No.	Function	Bit Status		Notes
		1	0	
1	Label	X		
2			X	
3		X		
4		X		
5		X		
6			X	
7			X	
8			X	
9	SDI	1	0	
		Left Engine	Right Engine	
10	SDI	0	1	
11	PDIU Status Flag	Failed	OK	
12	T ₂ / P ₂ Probe Heat	HEAT OFF	HEAT ON	
13	TLA Interlock Fault	FAULT	OK	1
14	Idle Select	MINIMUM	APPROACH	
15	Air/Ground Switch	GROUND	AIR	
16	Opposite Engine Status	SHUT DOWN	RUNNING	
17	Spare		X	2
18	Spare		X	
19	N2 Mode Trim Release (PROV)	RELEASED	FIXED	1
20	Spare		X	
21	Spare		X	
22	Spare		X	
23	Maintenance Test (Provisional)	ON	OFF	1
24	Ground Test Power	ON	OFF	
25	Spare		X	
26	T/R Indication Power Failed (PROV)	FAILED	OK	1
27	T/R Not Stowed	NOT STOWED	STOWED	1
28	T/R Deployed Indication	DEPLOYED	NOT DEPLOYED	1
29	Engine Fire Warning	ON	OFF	1
30	SSM			
31	SSM			
32	Parity (Odd)			

1 = RETURN TO SPARE

2 = CHANGE SPARE TO DEFINITION ON NEXT PAGE

Table 3.12 EEC Status – Labels 270 2F, 270 3F, 271 2F, 271 3F, 272 2F, 272 3F, 273 2F, 273 3F, 274 2F, 274 3F, 275 2F, 275 3F

Label 270 2F

Bit No.	Function	Bit Status		Notes
		1	0	
1	Label	X		
2			X	
3		X		
4		X		
5		X		
6			X	
7			X	
8			X	
9	SDI			
10	SDI			
11	PAD		X	
12	PAD		X	
13	PAD		X	
14	Spare		X	2
15	Data Entry Plug	Failed	Normal	1
16	Auto Mode	Selected	Not Selected	3
17	Channel Manually Selected	Selected	Not Selected	3
18	N ₂ Droop Control Mode	Engaged	Not Engaged	
19	Reverser System Failed	Failed	OK	
20	Channel Controlling Status	Controlling	Not Controlling	
21	Bleed Fall-Safe Open	Fall-Safe	Operational	3
22	TCA Valve Failed Closed	Failed	OK	
23	Spare		X	2
24	Overspeed Self-Test Failed	Failed	OK	3
25	Channel Incapable (Failed)	Incapable	Capable	
26	Abnormal Start	Abnormal	OK (Provision)	3
27	SVA Fall-Safe	Fall-Safe		3
28	Starter Cutout Command	Cutout	Not Cutout	
29	Oil Overtemperature	Overtemp	OK	1
30	SSM			
31	SSM			
32	Parity (Odd)			

1 = RETURN TO SPARE

2 = CHANGE SPARE TO DEFINITION ON NEXT PAGE

3 = CHANGE DEFINITION TO DEFINITION ON NEXT PAGE

Label 270 3F

Bit No.	Function	Bit Status		Notes
		1	0	
1	Label	X		
2			X	
3		X		
4		X		
5		X		
6			X	
7			X	
8			X	
9	SDI			
10	SDI			
11	PAD		X	
12	PAD		X	
13	PAD		X	
14	Spare		X	2
15	Data Entry Plug	Failed	Normal	1
16	Auto Mode	Selected	Not Selected	3
17	Channel Manually Selected	Selected	Not Selected	3
18	N ₂ Droop Control Mode	Engaged	Not Engaged	
19	Reverser System Failed	Failed	OK	
20	Channel Controlling Status	Controlling	Not Controlling	
21	Bleed Fall-Safe Open	Fall-Safe	Operational	3
22	TCA Valve Failed Closed	Failed	OK	
23	Spare		X	2
24	Overspeed Self-Test Failed	Failed	OK	3
25	Channel Incapable (Failed)	Incapable	Capable	
26	Abnormal Start	Abnormal	OK (Provision)	3
27	SVA Fall-Safe	Fall-Safe		3
28	Starter Cutout Command	Cutout	Not Cutout	
29	Oil Overtemperature	Overtemp	OK	1
30	SSM			
31	SSM			
32	Parity (Odd)			

Label 271 2F

Bit No.	Function	Bit Status		Notes
		1	0	
1	Label	X		
2			X	
3		X		
4		X		
5		X		
6			X	
7			X	
8		X		
9	SDI			
10	SDI			
11	PAD		X	
12	PAD		X	
13	PAD		X	
14	Reverser Deploy Command	ON	OFF	
15	Turbine Cooling Air Valve Solenoid	ON	OFF	
16	Oil Cooler Bypass Valve Solenoid	ON	OFF	3
17	Cowl Vent Solenoid	ON	OFF	1
18	Breather Compartment Ejector Sol.	ON	OFF	1
19	Spare		X	2
20	Spare		X	
21	Spare		X	
22	Spare		X	
23	Autostar Relay	ON	OFF (Provision)	1
24	TLA Interlock Actuator Command	Block Fwd	Block Rev	
25	Spare Reverser Group Relay	ON	OFF (Provision)	1
26	Spare		X	2
27	Spare		X	2
28	Spare		X	2
29	Spare		X	2
30	SSM			
31	SSM			
32	Parity (Odd)			

Label 271 3F

Bit No.	Function	Bit Status		Notes
		1	0	
1	Label	X		
2			X	
3		X		
4		X		
5		X		
6			X	
7			X	
8		X		
9	SDI			
10	SDI			
11	PAD		X	
12	PAD		X	
13	PAD		X	
14	Reverser Deploy Command	ON	OFF	
15	Turbine Cooling Air Valve Solenoid	ON	OFF	
16	Oil Cooler Bypass Valve Solenoid	ON	OFF	3
17	Cowl Vent Solenoid	ON	OFF	1
18	Breather Compartment Ejector Sol.	ON	OFF	1
19	Spare		X	2
20	Spare		X	
21	Spare		X	
22	Spare		X	
23	Autostar Relay	ON	OFF (Provision)	1
24	TLA Interlock Actuator Command	Block Fwd	Block Rev	
25	Spare Reverser Group Relay	ON	OFF (Provision)	1
26	Spare		X	2
27	Spare		X	2
28	Spare		X	2
29	Spare		X	2
30	SSM			
31	SSM			
32	Parity (Odd)			

Label 272 2F

Bit No.	Function	Bit Status		Notes
		1	0	
1	Label	X		
2			X	
3		X		
4		X		
5		X		
6			X	
7		X		
8			X	
9	SDI			
10	SDI			
11	PAD		X	
12	PAD		X	
13	PAD		X	
14	N1 Loop	Engaged	Not Engaged	
15	N2 Loop	Engaged	Not Engaged	
16	N2 Topping Loop	Engaged	Not Engaged	
17	PB Topping Loop	Engaged	Not Engaged	
18	PB Topping Loop Minimum	Engaged	Not Engaged	
19	EPR Loop	Engaged	Not Engaged	
20	Acceleration Schedule Loop	Engaged	Not Engaged	
21	Deceleration Schedule Loop	Engaged	Not Engaged	
22	T4.9 Topping Loop	Engaged	Not Engaged	1
23	Back Up Mode	Engaged	Not Engaged	
24	Spare		X	2
25	Spare		X	
26	Spare		X	
27	Spare		X	
28	Spare		X	
29	Spare		X	
30	SSM			
31	SSM			
32	Parity (Odd)			

Label 272 3F

Bit No.	Function	Bit Status		Notes
		1	0	
1	Label	X		
2			X	
3		X		
4		X		
5		X		
6			X	
7		X		
8			X	
9	SDI			
10	SDI			
11	PAD		X	
12	PAD		X	
13	PAD		X	
14	N1 Loop	Engaged	Not Engaged	
15	N2 Loop	Engaged	Not Engaged	
16	N2 Topping Loop	Engaged	Not Engaged	
17	PB Topping Loop	Engaged	Not Engaged	
18	PB Topping Loop Minimum	Engaged	Not Engaged	
19	EPR Loop	Engaged	Not Engaged	
20	Acceleration Schedule Loop	Engaged	Not Engaged	
21	Deceleration Schedule Loop	Engaged	Not Engaged	
22	T4.9 Topping Loop	Engaged	Not Engaged	1
23	Back Up Mode	Engaged	Not Engaged	
24	Spare		X	2
25	Spare		X	
26	Spare		X	
27	Spare		X	
28	Spare		X	
29	Spare		X	
30	SSM			
31	SSM			
32	Parity (Odd)			

Label 273 2F

Bit No.	Function	Bit Status		Notes
		1	0	
1	<div> <div></div> <div>Label</div> </div>	X		
2			X	
3		X		
4		X		
5		X		
6			X	
7		X		
8		X		
9	SDI			
10	SDI			
11	PAD		X	
12	PAD		X	
13	PAD		X	
14	P4.9 Interface Failed	Failed	OK	3
15	PB Interface Failed	Failed	OK	3
16	P2 (Pamb) Interface Failed*	Failed	OK	3
17	C3C Interface Failed	Failed	OK	3
18	T2 Interface Failed	Failed	OK	3
19	T4.9 Interface Failed	Failed	OK	3
20	Tfuel Interface Failed	Failed	OK	3
21	A/D Interface Failed	Failed	OK	3
22	RES/LVDT Interface Failed	Failed	OK	3
23	SVA Interface Failed	Failed	OK	3
24	N1 Interface Failed	Failed	OK	3
25	N2 Interface Failed	Failed	OK	3
26	P4.9 Sensor Prom Failed	Failed	OK	3
27	P2 (Pamb) Sensor Prom Failed*	Failed	OK	3
28	PB Sensor Prom Failed	Failed	OK	3
29	Background is not Executing	Not Executing	Executing	3
30	SSM			
31	SSM			
32	Parity (Odd)			

* Primary channel uses P2, Secondary channel uses Pamb.

Label 273 3F

Bit No.	Function	Bit Status		Notes
		1	0	
1	Label	X		
2			X	
3		X		
4		X		
5		X		
6			X	
7		X		
8		X		
9	SDI			
10	SDI			
11	PAD		X	
12	PAD		X	
13	PAD		X	
14	P4.9 Interface Failed	Failed	OK	3
15	PB Interface Failed	Failed	OK	3
16	P2 (Pamb) Interface Failed*	Failed	OK	3
17	C3C Interface Failed	Failed	OK	3
18	T2 Interface Failed	Failed	OK	3
19	T4.9 Interface Failed	Failed	OK	3
20	Tfuel Interface Failed	Failed	OK	3
21	A/D Interface Failed	Failed	OK	3
22	RES/LVDT Interface Failed	Failed	OK	3
23	SVA Interface Failed	Failed	OK	3
24	N1 Interface Failed	Failed	OK	3
25	N2 Interface Failed	Failed	OK	3
26	P4.9 Sensor Prom Failed	Failed	OK	3
27	P2 (Pamb) Sensor Prom Failed*	Failed	OK	3
28	PB Sensor Prom Failed	Failed	OK	3
29	Background is not Executing	Not Executing	Executing	3
30	SSM			
31	SSM			
32	Parity (Odd)			

* Primary channel uses P2, Secondary channel uses Pamb.

Label 274 2F

Bit No.	Function	Bit Status		Notes
		1	0	
1	Label	X		
2			X	
3		X		
4		X		
5		X		
6		X		
7			X	
8			X	
9	SDI			
10	SDI			
11	PAD		X	
12	PAD		X	
13	PAD		X	
14	Parity Test Hardware Fault	Error	OK	3
15	ROM Checksum Failure	Failed	OK	3
16	Ram Test Failure	Failed	OK	3
17	Instruction Test Failure	Failed	OK	3
18	High Speed Cross Link Failure	Failed	OK	3
19	Foreground Software Execution	Incorrectly	Correctly	
20	Watch Dog Timer Fault	Error	OK	3
21	Watch Dog/Parity Counter Latch	Latched	Not Latched	1
22	EAROM Failure	Failed	OK	3
23	ROM Parity Error Caused Reset	Yes	No	
24	RAM Parity Error Caused Reset	Yes	No	
25	Watchdog Timer Error Caused Reset	Yes	No	
26	Status Buffer or Watchdog/Parity	Failed	OK	3
27	Loss of Clock Caused Reset	Yes	No	
28	SDD Output #1 W/A	Failed	OK	
29	SDD Output #2 W/A	Failed	OK	
30	SSM			
31	SSM			
32	Parity (Odd)			

Label 274 3F

Bit No.	Function	Bit Status		Notes
		1	0	
1	Label	X		
2			X	
3		X		
4		X		
5		X		
6		X		
7			X	
8			X	
9	SDI			
10	SDI			
11	PAD		X	
12	PAD		X	
13	PAD		X	
14	Parity Test Hardware Fault	Error	OK	3
15	ROM Checksum Failure	Failed	OK	3
16	Ram Test Failure	Failed	OK	3
17	Instruction Test Failure	Failed	OK	3
18	High Speed Cross Link Failure	Failed	OK	3
19	Foreground Software Execution	Incorrectly	Correctly	
20	Watch Dog Timer Fault	Error	OK	3
21	Watch Dog/Parity Counter Latch	Latched	Not Latched	1
22	EAROM Failure	Failed	OK	3
23	ROM Parity Error Caused Reset	Yes	No	
24	RAM Parity Error Caused Reset	Yes	No	
25	Watchdog Timer Error Caused Reset	Yes	No	
26	Status Buffer or Watchdog/Parity	Failed	OK	3
27	Loss of Clock Caused Reset	Yes	No	
28	SDD Output #1 W/A	Failed	OK	
29	SDD Output #2 W/A	Failed	OK	
30	SSM			
31	SSM			
32	Parity (Odd)			

Label 275 2F

Bit No.	Function	Bit Status		Notes
		1	0	
1	Label	X		
2			X	
3		X		
4		X		
5		X		
6		X		
7			X	
8		X		
9	SDI			
10	SDI			
11	PAD		X	
12	PAD		X	
13	PAD		X	
14	Lamp (1,2 &/or 3) W/A Failed	Failed	OK	3
15	Other Channels Depower Discrete	Disagree	Agree	
16	PB Sensor Failed	Failed	OK	3
17	PT4.9 Sensor Failed	Failed	OK	3
18	PT2 (Pamb)* Sensor Failed	Failed	OK	3
19	EEC Temperature Status	High	OK	3
20	Spare (all “o” states)			2
21				2
22				2
23				2
24				2
25				2
26				2
27				2
28				2
29				
30	SSM			
31	SSM			
32	Parity (Odd)			

[3] Primary channel uses PT2, Secondary channel uses Pamb.

Label 275 3F

Bit No.	Function	Bit Status		Notes
		1	0	
1	Label	X		
2			X	
3		X		
4		X		
5		X		
6		X		
7			X	
8		X		
9	SDI			
10	SDI			
11	PAD		X	
12	PAD		X	
13	PAD		X	
14	Lamp (1,2 &/or 3) W/A Failed	Failed	OK	3
15	Other Channels Depower Discrete	Disagree	Agree	
16	PB Sensor Failed	Failed	OK	3
17	PT4.9 Sensor Failed	Failed	OK	3
18	PT2 (Pamb)* Sensor Failed	Failed	OK	3
19	EEC Temperature Status	High	OK	3
20	Spare (all “o” states)			2
21				2
22				2
23				2
24				2
25				2
26				2
27				2
28				2
29				
30	SSM			
31	SSM			
32	Parity (Odd)			

CHANGE * Primary channel uses PT2: Secondary channel uses Pamb.

Table 3.13 EEC Maintenance – Labels 350 2F, 350 3F, 351 2F, 351 3F, 352 2F, 352 3F, 353 2F, 353 3F, 354 2F, 354 3F

Label 350 2F

Bit No.	Function	Bit Status		Notes
		1	0	
1	Label	X		
2		X		
3		X		
4			X	
5		X		
6			X	
7			X	
8			X	
9	SDI			
10	SDI			
11	PAD		X	
12	PAD		X	
13	PAD		X	
14	N1 Failed	Failed	OK	3
15	N2 Failed	Failed	OK	3
16	TT2 Failed	Failed	OK	3
17	TT4.9 Failed	Failed	OK	3
18	Tfuel Failed	Failed	OK	3
19	Toll Failed	Failed	OK	3
20	Wf Resolver Failed	Failed	OK	3
21	SVA LVDT Failed	Failed	OK	3
22	Bleed Prox Input Failed	Failed	OK	3
23	ACC #1 LVDT Failed	Failed	OK	3
24	ACC #2 LVDT Failed	Failed	OK	3
25	Reverser LVDT Failed	Failed	OK	3
26	AOC LVDT Failed	Failed	OK	3
27	Spare LVDT Failed	Failed	OK	3
28	TLA Resolver Failed	Failed	OK	3
29	Oil Overtemperature	Overtemp	OK	1
30	SSM			
31	SSM			
32	Parity (Odd)			

Label 350 3F

Bit No.	Function	Bit Status		Notes
		1	0	
1	Label	X		
2		X		
3		X		
4			X	
5		X		
6			X	
7			X	
8			X	
9	SDI			
10	SDI			
11	PAD		X	
12	PAD		X	
13	PAD		X	
14	N1 Failed	Failed	OK	3
15	N2 Failed	Failed	OK	3
16	TT2 Failed	Failed	OK	3
17	TT4.9 Failed	Failed	OK	3
18	Tfuel Failed	Failed	OK	3
19	Toll Failed	Failed	OK	3
20	Wf Resolver Failed	Failed	OK	3
21	SVA LVDT Failed	Failed	OK	3
22	Bleed Prox Input Failed	Failed	OK	3
23	ACC #1 LVDT Failed	Failed	OK	3
24	ACC #2 LVDT Failed	Failed	OK	3
25	Reverser LVDT Failed	Failed	OK	3
26	AOC LVDT Failed	Failed	OK	3
27	Spare LVDT Failed	Failed	OK	3
28	TLA Resolver Failed	Failed	OK	3
29	Oil Overtemperature	Overtemp	OK	1
30	SSM			
31	SSM			
32	Parity (Odd)			

Label 351 2F

Bit No.	Function	Bit Status		Notes
		1	0	
1	Label	X		
2		X		
3		X		
4			X	
5		X		
6			X	
7			X	
8		X		
9	SDI			
10	SDI			
11	PAD		X	
12	PAD		X	
13	PAD		X	
14	Left ADC Inputs Failed	Failed	OK	3
15	Right ADC Inputs Failed	Failed	OK	3
16	Wf T/M W/A Failed	Failed	OK	3
17	SVA T/M W/A Failed	Failed	OK	3
18	BLD T/M W/A Failed	Failed	OK	3
19	ACC #1 T/M W/A Failed	Failed	OK	3
20	ACC #2 T/M W/A Failed	Failed	OK	3
21	AOC T/M W/A Failed	Failed	OK	3
22	Spare T/M W/A Failed	Failed	OK	1
23	Wf Track Check Failed	Failed	OK	3
24	SVA Track Check Failed	Failed	OK	3
25	Bld Track Check Failed	Failed	OK	3
26	ACC #1 Track Check Failed	Failed	OK	3
27	ACC #2 Track Check Failed	Failed	OK	3
28	AOC Track Check Failed	Failed	OK	3
29	Spare Track Check Failed	Failed	OK	1
30	SSM			
31	SSM			
32	Parity (Odd)			

Label 351 3F

Bit No.	Function	Bit Status		Notes
		1	0	
1	Label	X		
2		X		
3		X		
4			X	
5		X		
6			X	
7			X	
8		X		
9	SDI			
10	SDI			
11	PAD		X	
12	PAD		X	
13	PAD		X	
14	Left ADC Inputs Failed	Failed	OK	3
15	Right ADC Inputs Failed	Failed	OK	3
16	Wf T/M W/A Failed	Failed	OK	3
17	SVA T/M W/A Failed	Failed	OK	3
18	BLD T/M W/A Failed	Failed	OK	3
19	ACC #1 T/M W/A Failed	Failed	OK	3
20	ACC #2 T/M W/A Failed	Failed	OK	3
21	AOC T/M W/A Failed	Failed	OK	3
22	Spare T/M W/A Failed	Failed	OK	1
23	Wf Track Check Failed	Failed	OK	3
24	SVA Track Check Failed	Failed	OK	3
25	Bld Track Check Failed	Failed	OK	3
26	ACC #1 Track Check Failed	Failed	OK	3
27	ACC #2 Track Check Failed	Failed	OK	3
28	AOC Track Check Failed	Failed	OK	3
29	Spare Track Check Failed	Failed	OK	1
30	SSM			
31	SSM			
32	Parity (Odd)			

Label 352 2F

Bit No.	Function	Bit Status		Notes
		1	0	
1	Label	X		
2		X		
3		X		
4			X	
5		X		
6			X	
7		X		
8			X	
9	SDI			
10	SDI			
11	PAD		X	
12	PAD		X	
13	PAD		X	
14	Spare		X	1
15	Spare		X	1
16	Spare		X	
17	Spare		X	2
18	Spare		X	2
19	Spare		X	2
20	TCA Valve No. 1	Failed	OK	3
21	TCA Valve No. 2	Failed	OK	3
22	Channel Select Discrete	Failed	OK	3
23	PDIU SDD Input Failed	Failed	OK	3
24	N1 Sensor Failed*	Failed	OK (Provision)	3
25	Pb Pneumatic Line*	Failed	OK (Provision)	
26	P4.9 Pneumatic Line*	Failed	OK (Provision)	
27	TT4.9 Thermocouple Harness*	Failed	OK (Provision)	3
28	PDIU Status	Failed	OK	3
29	T/L Forward Interlock	Failed	OK	3
30	SSM			
31	SSM			
32	Parity (Odd)			

*Primary channel only.

Label 352 3F

Bit No.	Function	Bit Status		Notes
		1	0	
1	Label	X		
2		X		
3		X		
4			X	
5		X		
6			X	
7		X		
8			X	
9	SDI			
10	SDI			
11	PAD		X	
12	PAD		X	
13	PAD		X	
14	Spare		X	2
15	Spare		X	2
16	Spare		X	
17	Spare		X	2
18	Spare		X	2
19	Spare		X	2
20	TCA Valve No. 1	Failed	OK	3
21	TCA Valve No. 2	Failed	OK	3
22	Channel Select Discrete	Failed	OK	3
23	PDIU SDD Input Failed	Failed	OK	3
24	N1 Sensor Failed*	Failed	OK (Provision)	3
25	Pb Pneumatic Line*	Failed	OK (Provision)	
26	P4.9 Pneumatic Line*	Failed	OK (Provision)	
27	TT4.9 Thermocouple Harness*	Failed	OK (Provision)	3
28	PDIU Status	Failed	OK	3
29	T/L Forward Interlock	Failed	OK	3
30	SSM			
31	SSM			
32	Parity (Odd)			

* Primary channel only.

Label 353 2F

Bit No.	Function	Bit Status		Notes
		1	0	
1	Label	X		
2		X		
3		X		
4			X	
5		X		
6			X	
7		X		
8		X		
9	SDI			
10	SDI			
11	PAD		X	
12	PAD		X	
13	PAD		X	
14	N1 Crosscheck Failed	Failed	OK	3
15	N2 Crosscheck Failed	Failed	OK	3
16	PB Crosscheck Failed	Failed	OK	1
17	PT4.9 Crosscheck Failed	Failed	OK	1
18	TT2 Crosscheck Failed	Failed	OK	3
19	TT4.9 Crosscheck Failed	Failed	OK	3
20	Tfuel Crosscheck Failed	Failed	OK	3
21	Toil Crosscheck Failed	Failed	OK	3
22	Wf Resolver Crosscheck Failed	Failed	OK	3
23	SVA Resolver Crosscheck Failed	Failed	OK	3
24	Bld Prox Input Crosscheck Failed	Failed	OK	3
25	ACC #1 LVDT Crosscheck Failed	Failed	OK	3
26	ACC #2 LVDT Crosscheck Failed	Failed	OK	3
27	Reverser LVDT Crosscheck Failed	Failed	OK	3
28	AOC LVDT Crosscheck Failed	Failed	OK	3
29	TLA Resolver Crosscheck Failed	Failed	OK	3
30	SSM			
31	SSM			
32	Parity (Odd)			

Label 353 3F

Bit No.	Function	Bit Status		Notes
		1	0	
1	Label	X		
2		X		
3		X		
4			X	
5		X		
6			X	
7		X		
8		X		
9	SDI			
10	SDI			
11	PAD		X	
12	PAD		X	
13	PAD		X	
14	N1 Crosscheck Failed	Failed	OK	3
15	N2 Crosscheck Failed	Failed	OK	3
16	PB Crosscheck Failed	Failed	OK	1
17	PT4.9 Crosscheck Failed	Failed	OK	1
18	TT2 Crosscheck Failed	Failed	OK	3
19	TT4.9 Crosscheck Failed	Failed	OK	3
20	Tfuel Crosscheck Failed	Failed	OK	3
21	Toil Crosscheck Failed	Failed	OK	3
22	Wf Resolver Crosscheck Failed	Failed	OK	3
23	SVA Resolver Crosscheck Failed	Failed	OK	3
24	Bld Prox Input Crosscheck Failed	Failed	OK	3
25	ACC #1 LVDT Crosscheck Failed	Failed	OK	3
26	ACC #2 LVDT Crosscheck Failed	Failed	OK	3
27	Reverser LVDT Crosscheck Failed	Failed	OK	3
28	AOC LVDT Crosscheck Failed	Failed	OK	3
29	TLA Resolver Crosscheck Failed	Failed	OK	3
30	SSM			
31	SSM			
32	Parity (Odd)			

Label 354 2F

Bit No.	Function	Bit Status		Notes
		1	0	
1	Label	X		
2		X		
3		X		
4			X	
5		X		
6		X		
7			X	
8			X	
9	SDI			
10	SDI			
11	PAD		X	
12	PAD		X	
13	PAD		X	
14	REV Command Solenoid W/A Failure	Failure	OK	3
15	TCA Solenoid W/A Failure	Failure	OK	3
16	Spare Solenoid W/A Failure	Failure	OK	1
17	Spare Solenoid W/A Failure	Failure	OK	1
18	Spare Relay W/A Failure	Failure	OK	1
19	Spare Solenoid W/A Failure	Failure	OK	3
20	BCE Solenoid W/A Failure	Failure	OK	1
21	Spare Solenoid W/A Failure	Failure	OK	1
22	Oil Bypass Solenoid W/A Failure	Failure	OK	3
23	Hot Start Relay W/A Failure	Failure	OK	1
24	TLA Lockout Relay W/A Failure	Failure	OK	3
25	Spare Relay W/A Failure	Failure	OK	1
26	Spare		X	1
27	Essen. Sol. Current Sense Failure	Failure	OK	3
28	Critical & Noncritical Current Sense Failure	Failure	OK	3
29	Spare			
30	SSM			
31	SSM			
32	Parity (Odd)			

Label 354 3F

Bit No.	Function	Bit Status		Notes
		1	0	
1	Label	X		
2		X		
3		X		
4			X	
5		X		
6		X		
7			X	
8			X	
9	SDI			
10	SDI			
11	PAD		X	
12	PAD		X	
13	PAD		X	
14	REV Command Solenoid W/A Failure	Failure	OK	3
15	TCA Solenoid W/A Failure	Failure	OK	3
16	Spare Solenoid W/A Failure	Failure	OK	1
17	Spare Solenoid W/A Failure	Failure	OK	1
18	Spare Relay W/A Failure	Failure	OK	1
19	Spare Solenoid W/A Failure	Failure	OK	3
20	BCE Solenoid W/A Failure	Failure	OK	1
21	Spare Solenoid W/A Failure	Failure	OK	1
22	Oil Bypass Solenoid W/A Failure	Failure	OK	3
23	Hot Start Relay W/A Failure	Failure	OK	1
24	TLA Lockout Relay W/A Failure	Failure	OK	3
25	Spare Relay W/A Failure	Failure	OK	1
26	Spare		X	1
27	Essen. Sol. Current Sense Failure	Failure	OK	3
28	Critical & Noncritical Current Sense Failure	Failure	OK	3
29	Spare			
30	SSM			
31	SSM			
32	Parity (Odd)			

AERONAUTICAL RADIO, INC.
2551 Riva Road
Annapolis, Maryland 21401 – 7645 USA

SUPPLEMENT 11
TO
ARINC SPECIFICATION 429
MARK 33 DIGITAL INFORMATION TRANSFER SYSTEM (DITS)

Published: July 22, 1988

Prepared by the Airlines Electronic Engineering Committee
Adopted by the Airlines Electronic Engineering Committee: June 15, 1988

A. PURPOSE OF THIS SUPPLEMENT

This Supplement introduces new label assignments and equipment identification codes.

B. ORGANIZATION OF THIS SUPPLEMENT

The first part of this document, printed on goldenrod paper, contains descriptions of the changes introduced into the Specification by this Supplement, and, where appropriate, extracts from the original text for comparison purposes. The second part consists of replacement white pages for the Specification, modified to reflect these changes. The modified and added material on each replacement page is identified with “c-11” symbols in the margins. Existing copies of Specification 429 may be updated by simply inserting the replacement white pages they replace. The goldenrod pages should be inserted inside the rear cover of the Specification.

Copies of the Specification bearing the number 429-11 already contain this Supplement and thus do not require revisions by the reader.

C. CHANGES TO SPECIFICATION 429 INTRODUCED BY THIS SUPPLEMENT

This section presents a complete tabulation of the changes and additions to the Specification introduced by this Supplement. Each change or addition is entitled by the section number and title currently employed in the Specification or by the section number and title that will be employed when the Supplement is eventually incorporated. In each case there is included a brief description of the addition or change and, for other than very minor revisions, any text originally contained in the Specification is reproduced or reference.

2.1.5.1 BCD Numeric, Discrete, Aim Data, and File Transfer Words

SSM bit patterns separated from main figure.

FIGURE 3-1 RADION SYSTEMS MANAGEMENT WORD FORMATS

HF COM frequency control words added.

ATTACHMENT 1 – LABEL CODES

070 002, 070 0CC, 071 002, 071 0CC, 072 002, 072 0CC, 073 0CC, 074 002, 100 0BB, 101 0BB, 103 0BB, 104 0BB, 105 0BB, 106 0BB, 107 002, 114 0CC, 115 0BC, 115 0CC, 116 0CC, 117 0CC, 126 002, 127 002, 143 041, 143 241, 144 041, 144 341, 150 002, 152 041, 153 002, 153 041, 162 0DE, 173 0BD, 200 002, 202 002, 203 002, 204 002, 205 002, 205 0B9, 206 0CC, 207 002, 207 0B9, 211 002, 213 002, 213 08D, 220 002, 220 017, 220 024, 220 07E, 221 002, 221 017, 221 024, 221 07E, 222 002, 222 017, 222 024, 222 07E, 223 002, 223 017, 223 024, 223 07E, 224 002, 224 017, 224 024, 224 07E, 225 002, 226 0XX, 230 002, 230 017, 230 024, 230 07E, 241 002, 242 011, 243 0XX, 244 011, 244 08D, 245 002, 246 002, 246 006, 246 009, 247 002, 247 009, 247 0EB, 250 002, 250 12B, 252 0EB, 253 002, 254 002, 254 012, 255 002, 255 012, 255 08E, 256 002, 256 027, 257 002, 257 027, 263 002, 263 010, 264 002, 264 010, 265 002, 267 002,

271 002, 274 0C5, 275 002, 276 001, 276 002, 276 003, 300 039, 300 040, 301 002, 301 039, 301 040, 302 002, 302 039, 302 040, 303 002, 304 039, 304 040, 305 039, 305 040, 306 039, 306 040, 307 039, 307 040, 314 002, 316 002, 322 002, 341 002, 342 002, 343 01A, 350 00B, 350 027, 350 040, 350 241, 350 341, 351 00B, 351 029, 354 002, 355 027, 360 002.

Label 076 008 changed from “Ellipsoidal Altitude” to “GPS Height Above Referenced Ellipsoid”.

ATTACHMENT 1 – EQUIPMENT CODES

The following codes have been given new assignments:

039, 040, 041, 08E, 08F, 0AA, 0AB, 0AC, 0AE, 0AF, 0BA, 0BB, 0BC, 0BD, 0BE, 0BF, 0C2, 0CA, 0CB, 0CC, 0CD, 0CE, 0CF, 0DA, 0DB, 0DC, 0DD, 0DE, 0DF, 0EA, 0FF, 10A, 10B, 10C, 10C, 10D, 10E, 10F, 110, 12A, 12B, 136, 141, 241, 341.

ATTACHMENT 2 – DATA STANDARDS

Data Standards entered for new labels:

Label 076 008 changed from “Ellipsoidal Altitude” to “GPS Height Above Referenced Ellipsoid”.

Data Standards revised for following labels:

076 00B, 077 00B, 270 00B

ATTACHMENT 6

Example revised for label 077 00B.

Example for label 260 removed.

Example for label 260 031 expanded to include 260 002.

Format for label 270 00B added.

Format for label 274 0C5 added.

Format for label 350 027 added.

Code for 747 NR corrected in diagram of TPIS word.

Equipment ID word expanded to accommodate three-character identifier.

ATTACHMENT 9 – GENREAL AVIATION EQUIPMENT IDENTIFIERS

Code 08C added to list.

Codes for Loran and Omega changed from 08A/08B to 05A/05B, respectively.

NOTE: Due to the large number of changes
Created by this Supplement, it is NOT
available separately to update 429-11.

AERONAUTICAL RADIO, INC.
2551 Riva Road
Annapolis, Maryland 21401 – 7645 USA

SUPPLEMENT 12
TO
ARINC SPECIFICATION 429
MARK 33 DIGITAL INFORMATION TRANSFER SYSTEM (DITS)

Published: July 1, 1990

A. PURPOSE OF THIS SUPPLEMENT

The Supplement introduces the Williamsburg bit-oriented file data transfer protocol which supports the transfer of binary and character data. The previous AIM and character-oriented file transfer protocol sections are moved to Appendix 6. The Sign Status Matrix (SSM) information is revised and reorganized. In addition, this Supplement introduces new label assignments and equipment identification codes.

B. ORGANIZATION OF THIS SUPPLEMENT

The first part of this document, printed on goldenrod paper contains descriptions of the changes introduced into the Specification by this Supplement, and, where appropriate, extracts from the original text for comparison purposes. The second part consists of replacement white pages for the Specification, modified to reflect these changes. The modified and added material on each replacement page is identified with “c-12” symbols in the margins. Existing copies of Specification 429 may be updated by simply inserting the replacement white pages they replace. The goldenrod pages should be inserted inside the rear cover of the Specification.

Copies of the Specification bearing the number 429-12 already contain this Supplement and thus do not require revisions by the reader.

C. CHANGES TO SPECIFICATION 429 INTRODUCED BY THIS SUPPLEMENT

This section presents a complete tabulation of the changes and additions to the Specification introduced by this Supplement. Each change or addition is entitled by the section number and title currently employed in the Specification, or by the section number and title that will be employed when the Supplement is eventually incorporated. In each case there is included a brief description of the addition or change and, for other than very minor revision, any text originally contained into the Specification reproduced for reference.

2.1.3 Information Identifier

This section contains editorial corrections to comply with changes introduced in Supplement 11.

2.1.5 Sign/Status Matrix

This section was revised and reorganized. The changes include moving the AIM and file transfer SSM definitions to Appendix 6, adding failure reporting to the discrete word truth table (Section 2.1.5.3) and moving the description of status priorities to Section 2.1.5.

2.3.1 Digital Language

The contents of Sections 2.3.1.4 through 2.3.1.5.7 were moved to Appendix 6. The AIM Data and File Data Transfer section headings were retained for reference purposes. Section 2.3.1.5. File Data Transfer, provides the reason for moving the original file transfer protocol and introduces the Williamsburg protocol.

2.5 Bit-Oriented Communications Protocol

This new section was added to describe a bit-oriented data transfer protocol. The new protocol was developed to accommodate the interface of the ACARS Management Unit (MU) and the Satellite Data Unit (SDU).

3.2 AIM Information Transfer

The information previously contained in this section is no longer applicable to ARINC Specification 429. For reference purposes, the section header is retained and the original contents of this section are located in Appendix 6.

ATTACHMENT 1 – LABEL CODES

The following labels have been given new assignments:

002 115, 013 0B8, 016 0B8, 046 10A, 046 10B, 047 10A, 047 10B, 107 0BB, 110 0BB, 112 0BB, 114 0BB, 114 10A, 114 10B, 127 10A, 127 10B, 130 035, 130 10A130 10B, 131 035, 132 035, 133 10A, 133 10B, 134 10A, 134 10B, 137 10A, 137 10B, 155 10A, 155 10B, 156 10A, 156 10B, 157 10A, 157 10B, 160 10A, 160 10B, 161 10A, 161 10B, 201 115, 203 035, 203 10A, 203 10B, 205 10A, 205 10B, 211 10A, 211 10B, 220 116, 221 116, 222 115, 222 116, 223 116, 224 116, 226 035, 230 116, 234 039, 234 040, 235 039, 235 040, 236 039, 236 040, 237 039, 237 040, 244 10A, 244 10B, 256 114, 257 114, 260 10A, 260 10B, 260 114, 261 10A, 261 10B, 261 114, 262 10A, 262 10B, 262 114, 263 10A, 263 10B, 263 114, 264 10A, 264 10B, 264 114, 265 004, 265 038, 265 10A, 265 10B, 265 114, 267 10A, 267 10B, 270 10A, 270 10B, 270 114, 270 115, 271 10A, 271 10B, 271 114, 272 002, 272 10A, 272 10B, 272 114, 273 10A, 273 10B, 273 114, 274 10A, 274 10B, 274 114, 275 10A, 275 10B, 275 114, 276 114, 277 018, 300 10A, 300 10B, 300 TBD, 301 10A, 301 10B, 302 10A, 302 10B, 303 10A, 303 10B, 304 10A, 304 10B, 305 10A, 305 10B, 306 10D, 310 114, 311 114, 312 114, 313 114, 316 10A, 316 10B, 320 035, 321 10A, 321 10B, 322 10A, 322 10B, 323 10A, 323 10B, 324 10A, 324 10B, 325 10A, 325 10B, 326 10A, 326 10B, 327 10A, 327 10B, 330 10A, 330 10B, 331 10A, 331 10B, 335 10A, 335 10B, 336 002, 336 10A, 336 10B, 337 002, 337 002, 337 10A, 337 10B, 341 10A, 341 10B, 342 10A, 342 10B, 343 10A, 343 10B, 344 10A, 344 10B, 345 10A, 345 10B, 346 10A, 346 10B, 347 10A, 347 10B, 350 10A, 350 10B, 350 114, 350 115, 351 10A, 351 10B, 351 114, 352 10A, 352 10B, 352 114, 353 10A, 353 10B, 353 114, 354 10A, 354 10B, 357 035, 360 10A, 360 10B, 360 TBD, 361 10A, 361 10B, 362 10A, 362 10B, 362 115, 363 10A, 363 10B, 365 TBD, 372 10A, 372 10B, 373 10A, 373 10B, 374 10A, 374 10B, 374 TBD, 375 10A, 375 10B, 375 TBD.

Revised label 130 035 from “Traffic Advisory Range” to “Intruder Range”.

Revised label 131 035 from “Traffic Advisory Altitude” to “Intruder Altitude”.

Revised label 132 035 from “Traffic Advisory Bearing” to “Intruder Bearing”.

Removed label 130 030 Traffic Advisory Range.

Removed label 131 030 Traffic Advisory Altitude.

Removed label 132 030 Traffic Advisory Bearing Estimate.

Removed label 270 030 Transponder Discrete.

Removed label 347 030 Sector Control.

Removed label 347 035 Antenna Control.

ATTACHMENT 1 – EQUIPMENT CODES

The following codes have been given new assignments:

113, 114, 115, 116, 117, 118, 119, 11A, 123, 124, 125, 126, 127, 128, 129, 15A, 15B, 15C, 15D, 15E, 16A, 16B, 16C, 16D, 16E, 17A, 17B, 17C, 18A, 18B, 18C, 18D, 18E, 18F.

ATTACHMENT 2 – DATA STANDARDS

Tables 1, 2 updated to reflect changes to Attachment 1.

Binary Data notes 6, 7 and 8 added.

Discrete Data Standards entered for new labels:

272 002, 271 018, 272 018, 273 018, 275 018, 276 018, 277 018, 274 018, 270 035, 271 035, 273 035, 274 035, 275 035, 013 0B8, 016 0B8, 161 10A, 161 10B, 350 114, 351 114, 352 114, 353 114, 270 115, 350 115.

ATTACHMENT 6 – GENERAL WORD FORMATS AND ENCODING EXAMPLES

Add format for TCAS Intruder Range label 130.

Add format for TCAS Intruder Altitude label 131.

Add format for TCAS Intruder Bearing label 132.

Add format for Transponder Altitude/TCAS Own A/C Altitude label 203.

Removed 730 ASAS Sector Control Word example.

Removed 730 TCAS Traffic Advisory Range Word example.

Removed 730 TCAS Traffic Advisory Altitude Word example.

Removed 730 TCAS Traffic Advisory Bearing Estimate word example.

ATTACHMENT 9B – GENERAL AVIATION WORD EXAMPLES

Add new Company Name Identifier.

ATTACHMENT 10 – VARIABLES OF BIT-ORIENTED PROTOCOL

Add new Attachment.

ATTACHMENT 11 – BIT-ORIENTED DATA FILE TRANSFER WORD FORMATS

Add new Attachment.

ATTACHMENT 11A – DESTINATION CODES

Add new Attachment.

ATTACHMENT 11B – STATUS CODES

Add new Attachment.

ATTACHMENT 11C – ALOHA/ALOHA RESPONSE PROTOCOL WORDS

Add new Attachment.

ATTACHMENT 12 – FILE TRANSFER EXAMPLE

Add new Attachment.

ATTACHMENT 12A – FILED MAPPING EXAMPLE

Add new Attachment.

ATTACHMENT 13 – PROTOCOL DETERMINATION PROCEDURE DIAGRAMS

Add new Attachment.

ATTACHMENT 14 – SYSTEM ADDRESS LABELS

Add new Attachment.

ATTACHMENT 15 – LINK LAYER CRC DATA EXAMPLE

Add new Attachment.

APPENDIX 6 – FORMER MAINTENANCE, AIM AND FILE TRANSFER TECHNIQUES

Add new Appendix.

APPENDIX 7 – MATHEMATICAL EXAMPLE OF CRC ENCODING/DECODING

Add new Appendix.

AERONAUTICAL RADIO, INC.
2551 Riva Road
Annapolis, Maryland 21401 – 7645 USA

SUPPLEMENT 13
TO
ARINC SPECIFICATION 429
MARK 33 DIGITAL INFORMATION TRANSFER SYSTEM (DITS)

Published: December 30, 1991

A. PURPOSE OF THIS SUPPLEMENT

This Supplement introduces changes made to the Williamsburg protocol as a result of its initial implementation. This protocol supports the transfer of binary and character data. In addition, this Supplement introduces new label assignments and equipment identification codes.

B. ORGANIZATION OF THIS SUPPLEMENT

The first part of this document, printed on goldenrod paper contains descriptions of changes introduced into this Specification by this Supplement. The second part consists of replacement white pages for the Specification, modified to reflect the changes. The modified and added material on each page is identified by a c-13 in the margins. Existing copies of ARINC Specification 429 may be updated by simply inserting the replacement white pages where necessary and destroying the pages they replace. The goldenrod pages are inserted inside the rear cover of the Specification.

C. CHANGES TO ARINC SPECIFICATION 429 INTRODUCED BY THIS SUPPLEMENT

This section presents a complete tabulation of the changes and additions to the Specification introduced by this Supplement. Each change or addition is defined by the section number and the title currently employed in the Specification or by the section name and title that will be employed when the Supplement is eventually incorporated. In each case a brief description of the change or addition is included.

AEEC STAFF NOTE: THESE CHANGES APPLY TO ARINC 429, PART 3 ONLY.
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2.3.1.5 File Data Transfer

An editorial change, correction to section numbering.

2.3.1.5.1 Bit-Oriented Protocol Determination

New Section added to describe ALO/ALR protocol process to be used when a bilingual Link Layer protocol system needs to determine necessary bit-oriented interfaces.

2.5 Bit-Oriented communications Protocol

Included term “Williamsburg” parenthetically since this terminology well-known in industry. Added commentary to explain non-negotiation or parameters in this protocol.

D. Corrected Network Layer definition.

2.5.2 Link Data Unit (LDU) Size and Word Count

Added second paragraph to text, since it is a requirement, and removed second paragraph from commentary.

2.5.4 Bit Rate and Word Timing

Corrected the commentary to change the more ambiguous term “message” to LDU.

2.5.5.3 Destination Code

An editorial change was made.

2.5.6 Response to RTS

The last sentence in the second paragraph was reworded and moved to a more appropriate section, 2.5.6.2.

2.5.6.1 Clear to Send (CTS)

In the second to last sentence, the word “valid” was added to clarify the Not clear to send condition. The last sentence was added to clarify the resetting of RTS counters.

2.5.6.2 Not Clear to Send (NCTS)

The first paragraph was updated to include the information deleted from Section 2.5.6 and to clarify the validity requirements. The second paragraph was updated to describe that and NCTS counter would be reset upon a valid CTS response. The last sentence in the third paragraph was deleted and it's content expanded in the following commentary of that section.

2.5.6.3 Destination Busy

The second paragraph of this section was updated to indicate that a BUSY counter should be reset with a valid CTS response to RTS.

2.5.7 No Response to RTS

The first paragraph of this section was updated to describe proper response to RTS.

2.5.9 Unexpected RTS

This section was updated to include editorial changes and a description of the correct responses to RTS. The last sentence was deleted as redundant to Section in 2.5.13.1 and in conflict with other possible responses.

2.5.11 Data

The fourth paragraph of this section was updated to describe the proper ending of an LDU transmission, and to include the optional NAK response for receipt of an incomplete octet.

2.5.11.3 Character Data Words

In the last paragraph, the “note” designator was removed and the text clarified for the transfer of characters with a parity bit.

2.5.13 Negative Acknowledgement (NAK)

This section was updated to clarify conditions for sending the NAK word.

2.5.13.1 Missing SOT word

Text was corrected to refer to “reception” instead of “transmission” of a valid SOT word. Also, incorrect text referring to the NAK response timing was deleted.

2.5.13.2 LDU Sequence Number Error

The original text was omitted. Sections 2.5.13.1 – 2.5.13.7 were renumbered.

2.5.13.3 Parity Errors

A commentary section was added to describe the procedures for receiving words with bad parity.

2.5.13.4 Word Count Errors

This section was updated to clarify the NAK response time for word count errors.

2.5.13.5 CRC Errors

This section was updated to clarify the NAK response time for CRC errors.

2.5.13.6 Time Out Errors

This section was renumbered.

2.5.13.7 Restart Initialization

This section was omitted due to potential conflicts with the ALO/ALR procedures.

2.5.14 LDU Transfer Acknowledgement (ACK)

Text was revised to include LDU conditions for sink acknowledgement transmission.

2.5.14.1 Duplicate LDU

This section was added to describe duplicate LDU occurrences.

2.5.14.2 Auto-Synchronized Files

This section was added to describe the method of handling auto-synchronized files.

2.5.15 SYN Word

New text was added to describe SYN response times for non-consecutive LDU Sequence numbers. The last paragraph was incorrect and deleted.

2.5.16 Response to ACK/NAK/SYN

New text was added to describe actions when NAK and SYN are detected during a transmission.

2.5.19 ALO Response

A new section was added and updated to describe ALO responses.

ATTACHMENT 10 – VARIABLES OF BIT ORIENTED PROTOCOL

Tables 10-1 and 10-3 were updated to include events N_5 , N^6 , and time T_{12} . Options 0_7 and 0_{12} in Table 10-4 were changed to spares for consistency with corresponding text updates.

ATTACHMENT 11C – ALOHA/ALOHA RESPONSE PROTOCOL WORD DEFINITION

Table 11C-3 was added to clarify protocol version number assignments, and is referenced by “note 1”. “Note 2” was added to describe the GFI field of the ALOHA word.

ATTACHMENT 12A – FIELD MAPPING EXAMPLE

B_k was changed to B_{24} in the data word map, “nibble” was changed to “semi-octet”, and semi-octet arrow lengths were shortened to correspond to the proper four and eight-bit lengths.

APPENDIX 7 – MATHEMATICAL EXAMPLE OF CRC ENDODING/DECODING

Format (alignment) changes were made in the polynomial divisions, “(X)” was corrected to “Q(x)”, and the transmission order for the LDU Mapping of the 24-bit example was deleted to avoid possible misinterpretation.

AERONAUTICAL RADIO, INC.
2551 Riva Road
Annapolis, Maryland 21401 – 7645 USA

SUPPLEMENT 14
TO
ARINC SPECIFICATION 429
MARK 33 DIGITAL INFORMATION TRANSFER SYSTEM (DITS)

Published: January 4, 1993

A. PURPOSE OF THIS SUPPLEMENT

This Supplement introduces changes made to increase the efficiency of data transfer across an ARINC 429 high speed bit-oriented link. This protocol supports the transfer of binary and character data.

B. ORGANIZATION OF THIS SUPPLEMENT

The first part of this document, printed on goldenrod paper, contains descriptions of changes introduced into this Specification by this Supplement. The second part consists of replacement white pages for the Specification, modified to reflect the changes. The modified and added material on each page is identified by a c-14 in the margins. Existing copies of ARINC 429 may be updated by simply inserting the replacement white pages where necessary and destroying the pages they replace. The goldenrod pages are inserted inside the rear cover of the Specification.

C. CHANGES TO ARINC SPECIFICATION 429 INTRODUCED BY THIS SUPPLEMENT

This section presents a complete tabulation of the changes and additions to the Specification introduced by this Supplement. Each change and addition is defined by the section number and the title currently employed in the Specification or by the section name and title that will be employed when the Supplement is eventually incorporated. In each case a brief description of the change or addition is included.

AEEC STAFF NOTE: THESE CHANGES
APPLY TO ARINC 429, PART 3 ONLY.

2.3.1.5 File Data Transfer

An editorial change was needed to reference new section.

2.3.1.5.1 Bit-Oriented Protocol Determination

This section was expanded to include determination of different version numbers of the bit-oriented protocol, and was moved to Section 2.5.19.

2.5 Bit-Oriented Communication Protocol

An editorial change references a new section number.

2.5.4 Bit Rate and Word Timing

A maximum word gap of 64 bit-times, (averaged over the LDU transmission) was added to eliminate excessive delay in source transmission time.

Note: Sections 2.5.5 through 2.7 have been renumbered and reordered for consistency.

2.5.5 Word type

The basic definition of “word type” was corrected to include bits 31-29 in all bit-oriented words of an LDU.

2.5.6 Protocol Words

This section was added to specifically define the word type for protocol words.

2.5.6.1 Protocol Identifier

This section was added to clarify the definition of bits 28-25 for protocol words and to specify the relevant addition for error conditions.

2.5.6.2 Destination Code

This section was updated, and a commentary added, to clarify the role of the link layer protocol for upward compatibility with changing network functionality. The requirement for Destination code validation is not a link layer function.

2.5.6.3 Word Count

This section was renumbered.

2.5.7 Request to Send (RTS)

This section was previously titled “Response to TS”, and has been renumbered. The title was changed for consistency, and an introductory paragraph added to clarify the basic RTS function.

2.5.7.1 Clear to Send (CTS)

This section was renumbered.

2.5.7.2 Not Clear to Send (NCTS)

This section was renumbered.

2.5.7.3 Destination Busy

This section was renumbered, and an introductory replacement paragraph inserted to clarify the “optional” BUSY response, which may be used when a system cannot accept a transmission by the source in a “timely manner”. New commentary equates a “timely manner” to the shorter retry sequence of the NCTS series.

2.5.7.4 No Response to RTS

This section was renumbered, and the ALOHA word was included in the logic for error determination.

2.5.10 Start of Transmission (SOT)

Timer T₁₃ was added as a requirement on the source to begin transmission of an LDU within a specified interval after receipt of the CTS word from the sink.

2.5.10.1 General Format Identifier (GFI)

This section was updated, and commentary added to clarify the role of the GFI in pre-OSI as well as OSI environments. Validation of the GFI code is required by a high level entity (network layer) in both environments to determine the format of the data words to follow. GFI validation is not necessarily a link layer function.

2.5.11 Data

All references to Character Data word formats were deleted.

2.5.11.3 Character Data Words

This section was deleted. The Character Data Word format was removed from Supplement 14, as the format is incompatible with those for Full and Partial Data word formats. Currently, both binary and character data are transmitted in octets defined by the other two data word formats. The special character data format is not required.

2.5.12.1 CRC Encoding

References to character data words were deleted. The text for equation: $M9(x) = x^{16}G(x) + R(x)$ was corrected by moving the “bar” from $G(x)$ to $R(x)$.

2.5.13 Negative Acknowledgement (NAK)

NAK word interpretation was changed to remove constraint on source for specific order of file sequencing (i.e. Allows source to restart file with new FSN if necessary).

2.5.14.1 Duplicate LDU

This first paragraph was rewritten to clarify.

2.5.14.3 Incomplete File Timer

This section was added to allow the sink to discard a partial file of multiple LDUs when the T_{14} timeout between LDU transmissions is exceeded. It ensures that a source device cannot “lock-up” a sink.

2.5.15 SYN Word

The LDU sequence anomalies which generate a SYN response by the sink were clarified.

2.5.16 Response to ACK/NAK/SYN

The T_{16} timer was introduced to replace T_{10} and T_8 . Also, the action taken by the source upon receipt of a SYN word was updated, which relaxes requirements to maintain a specific File Sequence ordering by the source.

2.5.19 Protocol Initialization

2.5.19.1 Bit-Oriented Protocol Version,

2.5.19.2 ALOHA Response, and

2.5.19.3 Character-429 Determination

This section has been added to replace and expand on the definition of the process to determine the link layer protocol version supported by an interfacing system. These sections replace three sections from Supplement 13.

2.3.1.5.1 Bit-Oriented Protocol Determination

2.5.19 ALO Response, and

2.5.20 Bit Protocol Verification

2.6 Windowed Bit-Oriented Protocol

This is a completely new section which contains the system description of the new LLC2-like bit-oriented link layer protocol for 429. It is based on Section 2.5, “Bit-Oriented Communications Protocol”, with expanded text as specified to allow for more efficient use of the 429 high (or low) speed data bus through “windowing”. The definition includes provision for a Link Control Word prior to each LDU.

ATTACHMENT 1 – EQUIPMENT CODES

New Equipment Code Identifiers were added.

ATTACHEMENT 6 – WORD FORMATS AND ENCODING EXAMPLES

Example added for label 171.

ATTACHMENT 10 – VARIABLES OF BIT ORIENTED PROTOCOL

Table 10-1 was updated to include a standard value for N_7 , the maximum number of LDUs in a window (see Section 2.6 “Windowed Bit-Oriented Protocol”).

Table 10-3 deleted Option 6 (O_6) for NAK Send Time, and deleted Option 9 (O_9) for the Character Data Word, both of which are no longer used.

Table 10-4 was revised to include columns for low speed maximum and minimum values. These values were established for timers and as response time design goals for incoming transmissions. Timers T_{13} through T_{16} were added.

Table 10-5 was added to include a definition of high speed maximum and minimum values for timers and response time design goals. The format is the same as the revised Table 10-4. Timer T_{10} is not used in the high speed protocol.

Table 10-6 was added to include notes to Tables 10-1 through 10-5.

ATTACHMENT 11 – BIT-ORIENTED DATA FILE TRANSFER WORD FORMATS

Table 11-1A added “spares” for the deleted Character Data Formats and corrected “Protocol Data Word” to read “Protocol Word”.

Table 11-4 updated definitions for bits 9 through 24 of the ALO and ALR words, and added the LCW (LDU Control Word) format definition.

Table 11-4A was added as a partial replacement for ATTACHMENT 11C and Table 11-4B was added to define the new window definitions for the Windowed Bit-Oriented protocol in Section 2.6.

Table 11-6A was revised, changing the former GFI bit pattern (0001) for ISO 8208 to “unassigned”. The bit pattern (0100) for ISO 8473 was changed to a more

ATTACHMENT 11 – BIT-ORIENTED DATA FILE
TRANSFER WORD FORMATS (cont'd)

generic ISO 9577 definition. The bit pattern 1110 (hex"E") is now defined as "ACARS VHF Format". The "NOTES" in ATTACHMENT 11 have been renumbered to correspond to the new table definitions.

ATTACHMENT 11C – ALOHA/ALOHA RESPONSE
PROTOCOL WORD DEFINITION

This Attachment has been deleted. This information has been moved to Tables 11-4, 11-4A, and 11-4B.

ATTACHMENT 13A – ALOHA VERSION
DETERMINATION SEQUENCE

This Attachment was added to support the ALOHA version determination sequence called out in Section 2.5.19.1.1.

ATTACHMENT 14 – SYSTEM ADDRESS LABELS

New System Address Labels (SAL) were added.

ATTACHMENT 16 – SEQUENCE OF PROTOCOL
AND DATA WORDS IN WINDOW TRANSFER

This Attachment was added to illustrate the window transfers for new Section 2.6.

ATTACHMENT 17 – FLOW DIAGRAM USED TO
DETERMINE CHARACTER-ORIENTED VS BIT-
ORIENTED PROTOCOL

This Attachment was added to illustrate the logic flow that determines whether a character-oriented or bit-oriented link layer protocol interface is to be used.

AERONAUTICAL RADIO, INC.
2551 Riva Road
Annapolis, Maryland 21401 – 7645 USA

SUPPLEMENT 15
TO
ARINC SPECIFICATION 429
MARK 33 DIGITAL INFORMATION TRANSFER SYSTEM (DITS)

Published: September 1, 1995

Prepared by the Airlines Electronic Engineering Committee
Adopted by the Airlines Electronic Engineering Committee: April 18, 1995

A. PURPOSE OF THIS DOCUMENT

This Supplement introduces new label assignments, equipment IDs, system address labels and updates to the 429W protocol.

B. ORGANIZATION OF THIS SUPPLEMENT

The first part of this document, printed on goldenrod paper contains descriptions of changes introduced into this Specification by this Supplement. The second part consists of replacement white pages for the Specification, modified to reflect the changes. The modified and added material on each page is identified by a c-15 in the margins. Existing copies of ARINC Specification 429 may be updated by simply inserting the replacement white pages where necessary and destroying the pages they replace. The goldenrod pages are inserted inside the rear cover of the Specification.

C. CHANGES TO ARINC SPECIFICATION 429 INTRODUCED BY THIS SUPPLEMENT

This section presents a complete tabulation of the changes and additions to the Specification introduced by this Supplement. Each change or addition is defined by the section number and the title currently employed in the Specification or by the section name and title that will be employed when the Supplement is eventually incorporated. In each case a brief description of the change or addition is included.

2.0 Digital Information Transfer System Standards

Numerous changes were made to the protocol throughout this Section.

2.1.5.3 Discrete Data Words

The technique for encoding SSM bits in discrete words were revised.

ORIGINAL TEXT FOLLOWS:

2.1.5.3 Discrete Data Words

A source system should annunciate any detected failure that could cause one or more of the words normally output by that system to be unreliable. Three methods are defined. The first method is to set bit numbers 30 and 31 in the affected word(s) to the "Failure Warning" code defined in the table below. This is the preferred method. Words containing the "Failure Warning" code should continue to be supplied to the data bus during the failure condition. When using the second method, the equipment may stop transmitting the affected word or words on the data bus. The third method applies to data words which are defined such that they contain failure information within the data field. For these applications, refer to the associated ARINC equipment characteristic to determine the proper SSM reporting.

The "No Computed Data" code should be annunciated in the affected Discrete Data word(s) when a source system is unable to compute reliable data for reasons other than system failure.

When the "Functional Test" code appears as a system output, it should be interpreted as advice that the data in the Discrete Data word contents are the result of the execution of a functional test.

DISCRETE DATA WORDS

Bit		Meaning
31	30	
0	0	Verified Data, Normal Operation
0	1	No Computed Data
1	0	Functional Test
1	1	Failure Warning

2.2.2 Modulation

The following Commentary was added:

"Avionics manufacturers are warned that bus activity monitoring should be implemented with caution. Crossed wiring (interchanging A and B) at one end of the bus, which will cause improper LRU/system operation, may not necessarily be detected by a "simple" bus activity monitor."

2.2.4.2 Receiver Input Impedance

The word "parallel" was changed to "combination".

Figure 3.1 Radio Systems Management Word Formats

VHF Com Frequency Word - Bits 7,8,20,23 changed to "0" and bits 15,16,21,28 changed to "1".

ATTACHMENT 1 - LABEL CODES

This attachment was updated according to the tables on the following pages.

Designation for label 155 027 changed from BCD to BNR.

ATTACHMENT 1 - LABEL CODES

The following new equipment codes were assigned: 03D, 053, 05A, 0D0, 0E0, 12C, 160, 19F, 13B

ATTACHMENT 2 - DATA STANDARDS

This attachment was updated according to the tables on the following pages. Newly assigned discrete word formats are included.

In word 270 115, bit 12 was changed from "pad" to "Tune". AUTOTUNE was assigned for "1" and NO AUTOTUNE was assigned to "0".

Word 155 027 moved from Table 1 to Table 2.

In Table 2 "SIG DIG" was changed to "SIG BIT". In Table 2 under label 077, "0--" was changed to "037".

Duplicate 244 08D word removed.

ATTACHMENT 6 - GENERAL WORD FORMATS AND ENCODING EXAMPLES

Table 2 - examples for Flight Director Pitch and Total Air Temp corrected.

Examples for the following tables added.

Manufacturer Specific Data Word
010101 assigned to Garmin
010110 assigned to ARNAV Systems

Bit 11 modified for label 150 to include reference to precision source.

Word format for label 077 00B removed (from two places).

ATTACHMENT 9B - GENERAL AVIATION WORD EXAMPLES

Manufacturer Specific Data Word
010101 assigned to Garmin
010110 assigned to ARNAV Systems

ATTACHMENT 10 - VARIABLES OF BIT-ORIENTED PROTOCOL

Revised Notes 1 and 4.

Table 10-3 BIT-ORIENTED PROTOCOL OPTIONS - Added Option 0₁₂

Table 10-5 VARIABLES OF HIGH SPEED BIT-ORIENTED PROTOCOL - Revised Time T₁₀ min and max values.

ATTACHMENT 11 - BIT-ORIENTED DATA FILE TRANSFER WORD FORMATS

Table 11-6A GENERAL FORMAT IDENTIFIER (GFI) - Revised "Reserved ISO 9577" to "ISO 9577"

ATTACHMENT 11A - DESTINATION CODES

Added Cabin Packet Data Function. Corrected Ground Station bit encoding.

ATTACHMENT 11B - STATUS CODES

Revised description of Code 86. Added entries for Code 8E through 95.

ATTACHMENT 14 - SYSTEM ADDRESS LABELS

The following labels were added:

170	DFDAU (Mandatory Load Function)
266	Cabin Video System (Airshow)
334	Cabin Telecommunications Unit (CTU)
340	HF Data Radio/Data Unit #1
344	HF Data Radio/Data Unit #2

The following labels were revised:

175	HGA HPA
176	Spare
177	LGA HPA

APPENDIX 8 - INTEROPERABILITY OF BIT-ORIENTED LINK LAYER PROTOCOL

Appendix added.

APPENDIX 9 - SDL DIAGRAMS OF THE WILLIAMSBURG PROTOCOL

Appendix added.

NEW AND REVISED BNR LABEL ASSIGNMENTS

	LABEL	EQ ID	PARAMETER	BINARY UNITS	RANGE	SIG	RESOL	MIN TI	MAX TI	NOTES
New	061 002		ACMS Information							See Att. 6
New	062 002		ACMS Information							See Att. 6
New	063 002		ACMS Information							See At. 6
New	145 002		TACAN Control	See Section 3.1.4				180	220	See Att. 6
Add	226 002		Min Op. Fuel Temp (non-conflicting)							
New	233 002		ACMS Information							See Att. 6
New	234 002		ACMS Information							See Att. 6
New	235 002		ACMS Information							See Att. 6
New	236 002		ACMS Information							See Att. 6
Revise	265 002		Min Buffet Airspeed			11				
Revise	360 002		Flight information							See Att. 6
Revise	370 004		g							
Revise	014 005		Magnetic Heading	Deg						
Revise	370 005		g							
Revise	205 006		Mach		4096					
Revise	205 01A		Mach		4096					
New	034 025		VOR/ILS Frequency					125	250	
New	035 025		DME Frequency					125	250	
New	060 025		S/G HARDWARE PART NO.							See Att. 6
New	061 025		S/G HARDWARE PART NO.							See Att. 6
New	101 025		Selected Heading	Deg/180	+ - 180	12	0.05	125	250	
New	121 025		Pitch Limit	Deg/180	+ - 180	14	0.01	125	250	
New	145 025		Discrete Status 2 EFIS							
New	146 025		Discrete Status 3 EFIS							
New	147 025		Discrete Status 4 EFIS							
New	155 025		Discrete Status 5 EFIS							
New	160 025		Discrete Status 6 EFIS							
New	161 025		Discrete Status 7 EFIS							
New	162 025		ADF brg left/right	Deg/180	+ - 180	12	0.05	125	250	SDI-01 = left / SDI-10 = right
New	207 025		OP, SOFTWARE PART NO.							See Att. 6
New	272 025		Discrete Data #3							
New	273 025		Discrete Data #4							
New	276 025		Discrete Status 8 EFIS							
New	054 037		Zero Fuel Weight (kg)	kg	655360	15	20	100	200	
New	074 037		Zero Fuel Weight (lb)	lb	1310720	15	40	100	200	
Correction	076 037		Longitudinal C/G		163.84					
New	077 037		Lateral C/G	%MAC	131.072	17	0.01	100	200	
New	107 037		Long. Zero Fuel C/G	%MAC	163.84	14	0.01	100	200	
DELETE	256 037									
DELETE	257 037									
DELETE	347 037									
Revise	205 038		Mach		4096					
Revise	342 038		EPR Limit		4	12	0.001	150	250	
Revise	342 038		N1 Limit	%RPM	256	14	0.015	150	250	

NEW AND REVISED BNR LABEL ASSIGNMENTS

	LABEL	EQ ID	PARAMETER	BINARY UNITS	RANGE	SIG	RESOL	MIN TI	MAX TI	NOTES
New	227 03D		AVM Command							See Att. 2
New	270 03D		Discrete Data #1							See Att. 2
New	350 03D		Maintenance Data #1							See Att. 2
New	353 03D		Maintenance Data #4							See Att. 2
New	354 03D		N1 Vibration	Scalar	5.12	9	0.01			Bit 11-Chan. A/Bit 12-Chan. B
New	355 03D		N2 Vibration	Scalar	5.12	9	0.01			Bit 11-Chan. A/Bit 12-Chan. B
New	356 03D		N3 Vibration	Scalar	5.12	9	0.01			Bit 11-Chan. A/Bit 12-Chan. B
New	357 03D		BB Vibration	Scalar	5.12	9	0.01			Bit 11-Chan. A/Bit 12-Chan. B
New	360 03D		N1 Rotor Imbalance Angle	Deg.	+ -180	9	1			Bit 11-Chan. A/Bit 12-Chan. B
New	361 03D		LPT Rotor Imbalance Angle (737 only)	Deg.	+ -180	9	1			Bit 11-Chan. A/Bit 12-Chan. B
New	025 04D		Load SEL Control	na	204700	11	100			
New	156 04D		L TANK FAULTS					TBD	TBD	See Att. 2
New	157 04D		R TANK FAULTS					TBD	TBD	See Att. 2
New	160 04D		C TANK FAULTS					TBD	TBD	See Att. 2
New	161 04D		A TANK FAULTS					TBD	TBD	See Att. 2
New	241 04D		FQIS SYSTEM DATA		See Att. 6			500	1024	See Att. 6
New	254 04D		Actual Fuel Quan (teat)	Lbs	262144	15	8	500	1000	
New	255 04D		Fuel Quantity (gal)	Gallons	32768	15	1	500	1000	
New	256 04D		FUEL DISCRETES							
New	262 04D		T/U CAP-L TANK 1-4	PF	655.35	16	0.01	TBD	TBD	See Att. 2
New	263 04D		T/U CAP-L TANK 5-8	PF	655.35	16	0.01	TBD	TBD	
New	264 04D		T/U CAP - L TANK 9-12	PF	655.35	16	0.01	TBD	TBD	
New	265 04D		T/U CAP - L TANK 13-14	PF	655.35	16	0.01	TBD	TBD	
New	266 04D		T/U CAP - C TANK 1-4	PF	655.35	16	0.01	TBD	TBD	
New	267 04D		T/U CAP - C TANK 5-8	PF	655.35	16	0.01	TBD	TBD	
New	270 04D		T/U CAP - C TANK 9	PF	655.35	16	0.01	TBD	TBD	
New	271 04D		T/U CAP - A TANK 1-4	PF	655.35	16	0.01	TBD	TBD	
New	272 04D		T/U CAP - A TANK 5-8	PF	655.35	16	0.01	TBD	TBD	
New	273 04D		T/U CAP -A TANK 9-11	PF	655.35	16	0.01	TBD	TBD	
New	274 04D		T/U CAP - R TANK 1-4	PF	655.35	16	0.01	TBD	TBD	
New	275 04D		T/U CAP - R TANK 5-8	PF	655.35	16	0.01	TBD	TBD	
New	276 04D		T/U CAP - R TANK 9-12	PF	655.35	16	0.01	TBD	TBD	
New	277 04D		T/U CAP - R TANK 13-14	PF	655.35	16	0.01	TBD	TBD	
New	310 04D		COMP CAP-TANK	PF	327.67	15	0.01	TBD	TBD	See Att. 6 for SDI encoding
New	320 04D		DENSITY-TANK	LB/GAL	8.191	13	0.001	TBD	TBD	See Att. 6 for SDI encoding
New	324 04D		TANK VSO QUANTITY	GALS	32767	15	1	TBD	TBD	See Att. 6 for SDI encoding
New	326 04D		UPLIFT QUANTITY	LBS	1638300	14	100	TBD	TBD	
New	327 04D		UPLIFT DENSITY	LB/GAL	8.181	13	0.001	TBD	TBD	
New	341 04D		I/O S/W REV 1&2		(1)	16	N/A	TBD	TBD	
New	342 04D		S/W REV-TANK		(1)	16	N/A	TBD	TBD	See Att. 6 for SDI encoding
New	344 04D		FUEL DISCRETES					50	100	See Att. 2
New	345 04D		DISCRETES STATUS 1&3					100	200	See Att. 2
New	346 04D		CABLE CAP-HI-Z	PF	65535	16	1	100	200	See Att. 6 for SDI encoding

NEW AND REVISED BNR LABEL ASSIGNMENTS

	LABEL	EQ ID	PARAMETER	BINARY UNITS	RANGE	SIG	RESOL	MIN TI	MAX TI	NOTES
New	350 04D		MAINT. DATA FQIS 1-3					100	200	See Att. 2
New	351 04D		MAINT. DATA FQIS 1&3					100	200	See Att. 2
New	352 04D		MAINT. DATA FQIS 1-4					100	200	See Att. 2
New	353 04D		MAINT. DATA FQIS 1-4					100	200	See Att. 2
New	354 04D		FQIS TANK ID					100	200	See Att. 2, Att. 6 for SDI
New	355 04D		MAINT. DATA FQIS 2-4					100	200	See Att. 2
New	357 04D		MAINT. DATA FQIS 2-3					100	200	See Att. 2
New	151 05A		LB/KG Control Word							See Att. 2
Revise	176 05A		Fuel Temperature - Set to Zero	Deg. C	512	11	0.25	100	200	
Revise	177 05A		Fuel Temp. Left Wing Tank	Deg. C	512	11	0.25	100	200	
Delete	200 05A									
Revise	201 05A		Fuel Temp. Right Wing Tank	Deg. C	512	11	0.25	100	200	
Revise	202 05A		Fuel Temperature - Set to Zero	Deg. C	512	11	0.25	100	200	
New	247 05A		Total Fuel	lb	655360	14	40	100	200	
New	250 05A		Preselcted Fuel Quantity	lb	655360	14	40	100	200	
New	256 05A		Fuel Quantity - Left Outer Cell	lb	131072	15	4	100	200	Zero for A-321
New	257 05A		Fuel Quantity Left W/T Tank	lb	131072	15	4	100	200	
New	260 05A		Fuel Quantity Center Tank	lb	131072	15	4	100	200	
New	261 05A		Fuel Quantity Right I/C or W/T Tank	lb	131072	15	4	100	200	
New	262 05A		Fuel Quantity - Right Outer Cell	lb	131072	15	4	100	200	Zero for A-321
New	270 05A		Discrete Data #1					100	200	
New	271 05A		Discrete Data #2					100	200	
New	276 05A		Discrete Data #7					100	200	
New	300 05A		Internal Para. For SPARTIAAL							
New	301 05A		Internal Para. For SPARTIAAL							
New	302 05A		Internal Para. For SPARTIAAL							
New	303 05A		Internal Para. For SPARTIAAL							
New	304 05A		Internal Para. For SPARTIAAL							
New	305 05A		Internal Para. For SPARTIAAL							
New	306 05A		Internal Para. For SPARTIAAL							
New	307 05A		Internal Para. For SPARTIAAL							
New	310 05A		Internal Para. For SPARTIAAL							
New	311 05A		Internal Para. For SPARTIAAL							
New	312 05A		Fuel Quantity ACT 1	lb	131072	15	4	100	200	
New	313 05A		Fuel Quantity ACT 2	lb	131072	15	4	100	200	
New	314 05A		Internal Para. For SPARTIAAL							
New	315 05A		Internal Para. For SPARTIAAL							
New	316 05A		Internal Para. For SPARTIAAL							
New	317 05A		Internal Para. For SPARTIAAL							
New	324 05A		Effective Pitch Angle	Deg./180	+-180	14	0.01			
New	325 05A		Effective Roll Angle	Deg./180	+-180	14	0.01			
New	356 05A		Maintenance Word							
Revise	244 08D		Fuel Flow Rate		32768					

NEW AND REVISED BNR LABEL ASSIGNMENTS

	LABEL	EQ ID	PARAMETER	BINARY UNITS	RANGE	SIG	RESOL	MIN TI	MAX TI	NOTES
New	155	0BB	Maintenance Data #6							
New	156	0BB	Maintenance Data #7							
New	157	0BB	Maintenance Data #8							
New	160	0BB	Maintenance Data #9							
New	276	0BB	Discrete Data #5							
New	354	0BB	Maintenance Data #5							Bit 11-Chan. A/Bit 12-Chan. B
New	005	0D0	Engine Discrete							
New	006	0D0	Engine Discrete							
New	073	0D0	Engine Oil Quantity	US Pint	128	9	0.25			SDI1 = L/SD12 = R
New	173	0d0	Hydraulic Oil Quantity	US Pint	128	9	0.25			SDI1 = L/SD12 = B
New	174	0D0	Hydraulic Oil Pressure	PSI	4096	12	1			SDI1 = A/SD12 = B
New	316	0D0	Engine Oil Temperature	Deg. C	2048	12	0.5			SDI1 = L/SD12 = R
New	317	0D0	Engine Oil Pressure	PSI	4096	14	0.25			SDI1 = L/SD12 = R
New	344	0D0	N2	%RPM	256	13	0.03			SDI1 = L/SD12 = R
New	345	0D0	EGT	Deg. C	2048	12	0.5			SDI1 = L/SD12 = R
New	346	0D0	N1	%RPM	256	13	0.03			SDI1 = L/SD12 = R
New	347	0D0	Fuel Flow	Lb/Hr	32768	12	8			SDI1 = L/SD12 = R
New	353	0D0	Vibration	Scalar	5.12	8	0.02			SDI1 = L/SD12 = R
Revise	360	10A	Throttle Rate of Change		16	9/9				
New	146	112	TACAN Control	See Section 3.1.4				180	220	
New	222	112	TACAN Control	Deg/180	+/-180	12	0.05	180	220	
New	101	114	C/G Target	%	164	8	0.01	100	200	
Revise	270	115	Stored TACAN Control Word					25	50	See Att. 2
New	221	12C	Indicated Angle of Attack (Ave.)	Deg/180	+/-180	12	0.05	31.3	62.5	
New	222	12C	Indicated Angle of Attack (#1 left)	Deg/180	+/-180	12	0.05	31.3	62.5	
New	223	12C	Indicated Angle of Attack (#1 right)	Deg/180	+/-180	12	0.05	31.3	62.5	
New	224	12C	Indicated Angle of Attack (#2 left)	Deg/180	+/-180	12	0.05	31.3	62.5	
New	225	12C	Indicated Angle of Attack (#2 right)	Deg/180	+/-180	12	0.05	31.3	62.5	
New	114	13A	Ambient Pressure	PSIA	32	14	0.002	100	200	
New	130	13A	Inlet Temperature	Deg. C	128	11	0.0625	100	200	
New	131	13A	Inlet Pressure	PSIA	32	13	0.004	100	200	
New	134	13A	Throttle Lever Angle	Deg/180	+/-180	12	0.05	25	50	
New	254	13A	N1 Cruise	%N1 Nom	256	14	0.015	100	200	
New	255	13A	N1 Climb	%N1 Nom	256	14	0.015	100	200	
New	264	13A	Burner Pressure	PSIA	512	14	0.031	100	200	
New	340	13A	N1 Take Off	%N1 Nom	256	14	0.015	25	50	
New	341	13A	N1 Reference	%N1 Nom	256	14	0.015	25	50	
New	344	13A	N2 Speed	%RPM	256	14	0.015	25	50	
New	345	13A	EGT Trimmed	Deg. C	2048	12	0.5	25	50	
New	346	13A	N1 Speed Actual	%N1 Nom	256	14	0.015	25	50	
New	347	13A	Fuel Flow	Lb/Hr	32768	14	2	50	100	
New	364	13A	N1 APR Rating	%N1 Nom	256	14	0.015	100	200	
New	365	13A	N1 Max Reverse	%N1 Nom	256	14	0.015	100	200	

NEW AND REVISED BNR LABEL ASSIGNMENTS

	LABEL	EQ ID	PARAMETER	BINARY UNITS	RANGE	SIG	RESOL	MIN TI	MAX TI	NOTES
New	366	13A	IGV Position	Deg./180	+-180	12	0.05	100	200	
New	367	13A	IGV Request	Deg./180	+-180	12	0.05	100	200	
New	341	160	Tank Unit Data							
New	147	xxx	TACAN Control Word					100	200	
Correction	171	xxx	Manu. Specific Status Word							See Att. 6
New	214	xxx	ICAO Aircraft Address (part 1)							See Att. 6
New	316	xxx	ICAO Aircraft Address (part 2)							
New	375	xxx	GPS Differential Correction Word A							See ARINC 743A
New	376	xxx	GPS Differential Correction Word B							See ARINC 743A
Revised	021	002	Selected EPR	EPR	0-3	4	0.001	100	200	
New	027	002	TACAN Selected Course	Degrees	0-359	3	1	167	333	
Revised	020	020	Selected Vertical Speed	Ft/Min	0-6000	4	1	100	200	
Revised	021	020	Selected EPR	EPR	0-3	4	0.001	100	200	
New	047	020	VHF Com Frequency	See Chap. 3				100	200	
New	047	024	VHF Com Frequency	See Chap. 3				100	200	
Revised	155	027	MLS Selected GP Angle	Degrees				100	200	
Revised	065	037	Gross Weight		0-19999					
New	163	037	Zero Fuel Weight (lb)	Lbs	0-19999	5	1	100	200	
New	243	037	Zero Fuel Weight (kg)	KG	0-19999	5	1	100	200	
New	52	037	Long. Zero Fuel CG	%MAC	0-100.00	5	0.01	100	200	
New	012	04D	QTY-LD SEL (LB)	Lbs	0-79999	19	100			
New	013	04D	QTY - FLT DECK (LB)	Lbs	0-79999	19	100			
New	017	04D	TOTAL-FLT DECK (LB)	Lbs	0-79999	19	100			
New	020	04D	TNK-LD SEL (LB)	Lbs	0-79999	19	100			
New	022	04D	QTY-LD SEL (KG)	KG	0-79999	19	100			
New	023	04D	QTY-FLT DECK (KG)	KG	0-79999	19	100			
New	027	04D	TOTAL-FLT DECK (KG)	KG	0-79999	19	100			
New	030	04D	TNK-LD SEL (KG)	KG	0-79999	19	100			
New	135	05A	ACT 1 Fuel Quan. Display	KG/LB	0-9999	16	100	100	200	
New	136	05A	ACT 2 Fuel Quan. Display	KG/LB	0-9999	16	100	100	200	
New	137	05A	Center+ACT+ACT FQ Display	KG/LB	0-9999	16	100	100	200	
New	140	05A	Actual Fuel Quan. Display	KG/LB	0-9999	16	100	100	200	
New	141	05A	Preselcted Fuel Quan. Display	KG/LB	0-9999	16	100	100	200	
New	142	05A	Left Wing Fuel Quan. Display	KG/LB	0-9999	16	100	100	200	
New	143	05A	Center Wing Fuel Quan. Display	KG/LB	0-9999	16	100	100	200	
New	144	05A	Right Wing Fuel Quan. Display	KG/LB	0-9999	16	100	100	200	
New	272	05A	Fuel Density	KG/M3	0-9999	16	0.0001	100	200	
New	273	05A	Sensor Values Left Wing Tank	pF	0-100	13	0.1	100	200	
New	274	05A	Sensor Values Center Wing Tank	pF	0-100	13	0.1	100	200	
New	275	05A	Sensor Values Right Wing Tank	pF	0-100	13	0.1	100	200	
New	047	086	VHF Com Frequency	See Chap. 3				100	200	
Revised	021	0A1	Selected EPR	EPR	0-3	4	0.001	100	200	
New	201	112	TACAN Distance	N.M.	0-399.99	5	0.01	190	210	

AERONAUTICAL RADIO, INC.
2551 Riva Road
Annapolis, Maryland 21401 – 7645 USA

SUPPLEMENT 16
TO
ARINC SPECIFICATION 429
MARK 33 DIGITAL INFORMATION TRANSFER SYSTEM (DITS)

Published: September 27, 2001

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ARINC 429 SUPPLEMENT 16

SUPPLEMENT 16 TO ARINC SPECIFICATION 429 PART 1 - Page 2

A. PURPOSE OF THIS SUPPLEMENT

This Supplement introduces new label assignments, equipment IDs, and System Address Labels (SAL) to ARINC Specification 429.

B. ORGANIZATION OF THIS SUPPLEMENT

The material in Supplement 16 is integrated into ARINC Specification 429 to form an updated version of the standard. Changes introduced by Supplement 16 are identified using change bars and are labeled by a “c-16” symbol in the margin.

C. CHANGES TO ARINC SPECIFICATION 429 INTRODUCED BY THIS SUPPLEMENT

This section presents a complete tabulation of the changes and additions to the Specification introduced by this Supplement. Each change or addition is defined by the section number and the title currently employed in the Specification or by the section name and title that will be employed when the Supplement is eventually incorporated. In each case a brief description of the change or addition is included.

ATTACHMENT 1-1 - LABEL CODES

Attachment 1-1 was updated to include new label assignments, of these new assignments 35 labels were revised and 3 label assignment deletions. A summary of label codes added by Supplement 16 is reproduced as Attachment 1-16 to this Supplement.

The deleted labels are:

Label Code	PARAMETER
053	Track Angle Magnetic
217	Average Static Pressure
231	Total Air Temperature

ATTACHMENT 1-2 - EQUIPMENT CODES

Attachment 1-2 was updated to include new equipment codes:

EQ ID	EQUIPMENT TYPE
055	Multi-Mode Receiver (MMR) (755)
056	GNSS Navigation Landing Unit (GNLU) (756)
057	Cockpit Voice Recorder (CVR) (757)
058	Communication Management Unit Mark 2 (758)
060	GNSS Navigation Unit (GNU) (760)
061	Satellite Terminal Unit (STU) (761)
0BB	Flap Control Unit (B747-400)/Flap Slat Electronics Unit (B767-400)
108	Electronic Engine Control (EEC) Channel A (B737-700)
109	Electronic Engine Control (EEC) Channel B (B737-700)

122	Ground Auxiliary Power Unit (A320/319/321)
12D	Logic Drive Control Computer (B747/B767)
12E	Cargo Control Logic Unit (B767)
12F	Cargo Electronics Interface Unit (B767)
13B	Audio Entertainment System (AES) Controller (Boeing)
13F	Camera Interface Unit (A340/B777)
130	Load Management Unit (LMU) Airbus
140	Supersonic Air Data Computer (Honeywell)
142	ADS-B Link Display Processor Unit (LPDU)
143	Vertical/Horizontal Gyro (Litton)
167	Air Traffic Service Unit (Airbus)
168	Integrated Standby Instrument System (A340/330, A320/319/321)
169	Data Link Control and Display Unit (A340/330)
200	Versatile Integrated Avionics Unit (B717/MD-10)
201	Electronic Spoiler Control Unit (B717)
202	Brake Control Unit (B717)
203	Pneumatic Overheat Detection Unit (B717)
204	Proximity Switch Electronics Unit (B717)
205	APU Electronic Control Unit (B717)
206	Aircraft Interface Unit (MD-10)
207	Fuel Quantity Gauging Unit (MD-10)

ATTACHMENT 2 - DATA STANDARDS

Attachment 2 was updated to reflect new data standards. The basis of the changes introduced in Supplement 16 are reproduced as Attachment 1-16 to this Supplement.

ATTACHMENT 4 - INPUT/OUTPUT CIRCUIT STANDARDS

Text was added to identify the drawing as defining total system characteristics.

ATTACHMENT 6 - GENERAL WORD FORMATS AND ENCODING EXAMPLES

The text describing Label 150 bit 11 was revised to reflect the contents of ARINC Characteristic 743A, GNSS Sensor.

The text describing Label 214 and Label 216 was revised to reflect the contents of ARINC Characteristic 758, Communications Management Unit.

ATTACHMENT 8 - OUTPUT SIGNAL TIMING TOLERANCES

The text was modified to define pulse rise and fall times.

ATTACHMENT 11 - SYSTEM ADDRESS LABELS

The following System Address Labels were added:

SAL OCTAL LABEL	SYSTEM
157	CVR
210	FCMC Com A340-500/600
211	FCMC Mon A340-500/600
212	FCMC Int A340-500/600
225	HUD
241	APM-MMR
242	MMR
244	ILS
245	MLS
246	AHRS
251	VDR #1
252	VDR #2
253	VDR #3
310	GPWS
311	GNLU 1
312	GNLU 2
313	GNLU 3
314	GNU 1
315	GNU 2
316	GNU 3
321	AUTOTHROTTLE COMPUTER
322	FCC 1
323	FCC 2
324	FCC 3
325	APU
326	APU CONTROLLER
327	Mode Control Panel (MCP)
330	FMC 3
331	ATC TRANSPONDER
332	DADC
362	Passenger Services System (PSS) 767-300,400
363	Cabin Service System (CSS) 747-400
364	Audio Entertainment System (AES) Boeing
366	Multicast
367	Bridge

APPENDIX E – GUIDELINES FOR LABEL
ASSIGNMENTS

Labels 171, 172, 214 and 216 were removed from spare labels (item 3).

ATTACHMENT 1-16
SUPPLEMENT 16 UPDATES TO LABEL CODES

Code No. (Octal)	Data	Eqpt. ID (Hex)	Parameter	Units	Range	Sig Bits	Resolution	MIN TX	MAX TX
001	BCD	056	Distance To Go	The Same Parameters as the FMS EQ ID 002					
001	BCD	060	Distance To Go	The Same Parameters as the FMS EQ ID 002					
002	BCD	056	Time To Go	The Same Parameters as the FMS EQ ID 002					
002	BCD	060	Time To Go	The Same Parameters as the FMS EQ ID 002					
012	BCD	056	Ground Speed	The Same Parameters as the FMS EQ ID 002					
012	BCD	060	Ground Speed	The Same Parameters as the FMS EQ ID 002					
017	BCD	055	Selected Runway Heading	Degrees	0-359.9	4	0.1		
020	Discrete	06D	Landing Gear Position Infor & System Status					90	100
021	Discrete	06D	Landing Gear Position Infor & System Status					90	100
022	Discrete	06D	Landing Gear Position Infor & System Status					90	100
023	Discrete	06D	Landing Gear Position Infor & System Status					90	100
024	Discrete	06D	Landing Gear Position Infor & System Status					90	100
027	BCD	056	TACAN Selected Course	The Same Parameters as the FMS EQ ID 002					
027	BCD	060	TACAN Selected Course (Bed)	The Same Parameters as the FMS EQ ID 002					
033	BCD	055	Landing System Mode/Frequency						
033	BCD	056	ILS Frequency	The Same Parameters as the FMS EQ ID 002					
033	BCD	060	ILS Frequency	The Same Parameters as the FMS EQ ID 002					
034	BCD	056	VOR/ILS Frequency	The Same Parameters as the FMS EQ ID 002					
034	BCD	060	VOR/ILS Frequency #1	The Same Parameters as the FMS EQ ID 002					
035	BCD	055	Paired DME Frequency	MHz	1008-135.9	4	0.05		
035	BCD	056	DME Frequency	The Same Parameters as the FMS EQ ID 002					
035	BCD	060	DME Frequency #1	The Same Parameters as the FMS EQ ID 002					
036	BCD	055	MLS Channel Selection		500-600	3	1		
036	BCD	056	MLS Frequency Channel	The Same Parameters as the FMS EQ ID 002					
036	BCD	060	MLS Frequency/Channel	The Same Parameters as the FMS EQ ID 002					
041	BCD	056	Set Latitude	The Same Parameters as the FMS EQ ID 002					
041	BCD	060	Set Latitude	The Same Parameters as the FMS EQ ID 002					
042	BCD	056	Set Longitude	The Same Parameters as the FMS EQ ID 002					
042	BCD	060	Set Longitude	The Same Parameters as the FMS EQ ID 002					
043	BCD	056	Set Magnetic Heading	The Same Parameters as the FMS EQ ID 002					
043	BCD	060	Set Magnetic Heading	The Same Parameters as the FMS EQ ID 002					
052	BNR	004	Body Pitch Accel	Deg/Sec ²	± 64	15	0.002	50 Hz	117 Hz
052	BNR	038	Body Pitch Accel	Deg/Sec ²	± 64	15	0.002	50 Hz	117 Hz
053	BNR	004	Body Roll Accel	Deg/Sec ²	± 64	15	0.002	50 Hz	117 Hz
053	BNR	038	Body Roll Accel	Deg/Sec ²	± 64	15	0.002	50 Hz	117 Hz
054	BNR	004	Body Yaw Accel	Deg/Sec ²	± 64	15	0.002	50 Hz	117 Hz
054	BNR	038	Body Yaw Accel	Deg/Sec ²	± 64	15	0.002	50 Hz	117 Hz
056	BCD	056	ETA (Active Waypoint)	The Same Parameters as the FMS EQ ID 002					
056	BCD	060	ETA (Active Waypoint)	The Same Parameters as the FMS EQ ID 002					
061	BNR	00B	Pseudo Range	Meters	±268435456	20	256	200	1200
061	BNR	056	ACMS Information	The Same Parameters as the FMS EQ ID 002					
061	BNR	060	ACMS Information	The Same Parameters as the FMS EQ ID 002					
062	BNR	00B	Pseudo Range Fine	Meters	256	11	0.125	200	1200
062	BNR	056	ACMS Information	The Same Parameters as the FMS EQ ID 002					
062	BNR	060	ACMS Information	The Same Parameters as the FMS EQ ID 002					
063	BNR	00B	Range Rate	M/S	±4096	20	0.0039	200	1200
063	BNR	056	ACMS Information	The Same Parameters as the FMS EQ ID 002					
063	BNR	060	ACMS Information	The Same Parameters as the FMS EQ ID 002					
064	BNR	00B	Delta Range	Meters	±4096	20	0.0039	200	1200
065	BNR	00B	SV Position X	Meters	±67108864	20	64	200	1200
066	BNR	00B	SV Position X Fine	Meters	64	14	0.0039	200	1200
070	BNR	00B	SV Position Y	Meters	±67108864	20	64	200	1200
070	BNR	056	Reference Airspeed (Vref)	The Same Parameters as the FMS EQ ID 002					
070	BNR	060	Reference Airspeed (Vref)	The Same Parameters as the FMS EQ ID 002					
071	BNR	00B	SV Position Y Fine	Meters	64	14	0.0039	200	1200
072	BNR	00B	SV Position Z	Meters	±67108864	20	64	200	1200
073	BNR	00B	SV Position Z Fine	Meters	64	14	0.0039	200	1200
074	BNR	00B	UTC Measure Time	Seconds	10.0	20	9.536743µs	200	1200

ATTACHMENT 1-16
SUPPLEMENT 16 UPDATES TO LABEL CODES

Code No. (Octal)	Data	Eqpt. ID (Hex)	Parameter	Units	Range	Sig Bits	Resolution	MIN TX	MAX TX
074	BNR	056	Zero Fuel Weight	The Same Parameters as the FMS EQ ID 002					
074	BNR	060	Zero Fuel Weight	The Same Parameters as the FMS EQ ID 002					
074	BNR	114	Zero Fuel Weight	Pounds	1310680	15	40	100	400
075	Discrete	008	Maximum Hazard Alert Level Output						
075	BNR	114	Aircraft Gross Weight	Pounds	1310680	15	40	100	200
076	BNR	00B	GNSS Altitude (Msl)	Feet	±131072	20	0.125	200	1200
076	Discrete	008	Hazard Azimuth Output						
076	BNR	114	Aircraft Longitudinal Center Of Gravity	Percent	163.83%	14	0.01%	100	200
077	Discrete	008	Hazard Range Output						
077	BNR	056	Target Airspeed	The Same Parameters as the FMS EQ ID 002					
077	BNR	060	Target Airspeed	The Same Parameters as the FMS EQ ID 002					
077	BNR	114	Zero Fuel Center Of Gravity	Percent	163.83%	14	0.01%	100	200
100	BNR	056	Selected Course #1	The Same Parameters as the FMS EQ ID 002					
100	BNR	060	Selected Course #1	The Same Parameters as the FMS EQ ID 002					
101	BNR	00B	HDOP	N/A	1024	15	0.031	200	1200
102	BNR	00B	VDOP	N/A	1024	15	0.031	200	1200
102	BNR	056	Selected Altitude	The Same Parameters as the FMS EQ ID 002					
102	BNR	060	Selected Altitude	The Same Parameters as the FMS EQ ID 002					
103	BNR	00B	GNSS Track Angle	Degrees	±108°	15	0.0055°	200	1200
103	BNR	056	Selected Airspeed	The Same Parameters as the FMS EQ ID 002					
103	BNR	060	Selected Airspeed	The Same Parameters as the FMS EQ ID 002					
104	BNR	056	Selected Vertical Speed	The Same Parameters as the FMS EQ ID 002					
104	BNR	060	Selected Vertical Speed	The Same Parameters as the FMS EQ ID 002					
105	BNR	055	Selected Runway Heading	Degrees	± 180	11	0.1		
105	BNR	056	Selected Runway Heading	The Same Parameters as the FMS EQ ID 002					
105	BNR	060	Selected Runway Heading	The Same Parameters as the FMS EQ ID 002					
106	BNR	060	Selected Mach	The Same Parameters as the FMS EQ ID 002					
106	BNR	056	Selected Mach	The Same Parameters as the FMS EQ ID 002					
107	BNR	056	Selected Cruise Altitude	The Same Parameters as the FMS EQ ID 002					
107	BNR	060	Selected Cruise Altitude	The Same Parameters as the FMS EQ ID 002					
110	BNR	00B	GNSS Latitude	Degrees	±108°	20	0.000172°	200	1200
111	BNR	00B	GNSS Longitude	Degrees	±108°	20	0.000172°	200	1200
112	BNR	00B	GNSS Ground Speed	Knots	4096	15	0.125	200	1200
114	BNR	056	Desired Track	The Same Parameters as the FMS EQ ID 002					
114	BNR	060	Desired Track	The Same Parameters as the FMS EQ ID 002					
115	BNR	056	Waypoint Bearing	The Same Parameters as the FMS EQ ID 002					
115	BNR	060	Waypoint Bearing	The Same Parameters as the FMS EQ ID 002					
116	BNR	00B	Horizontal GLS Deviation Rectilinear	Feet	± 24000	18	.00915		100
116	BNR	055	Horizontal GLS Deviation Rectilinear	Feet	± 24000	18	.00915		100
116	BNR	056	Cross Track Distance	The Same Parameters as the FMS EQ ID 002					
116	BNR	060	Cross Track Distance	The Same Parameters as the FMS EQ ID 002					
117	BNR	00B	Vertical GLS Deviation Rectilinear	Feet	± 1024	14	.0625		100
117	BNR	055	Vertical GLS Deviation Rectilinear	Feet	± 1024	14	.0625		100
117	BNR	056	Vertical Deviation	The Same Parameters as the FMS EQ ID 002					
117	BNR	060	Vertical Deviation	The Same Parameters as the FMS EQ ID 002					
120	BNR	00B	GNSS Latitude Fine	Degrees	0.000172°	11	8.38-E-8°	200	1200
120	BNR	056	Range To Altitude	The Same Parameters as the FMS EQ ID 002					
120	BNR	060	Range To Altitude	The Same Parameters as the FMS EQ ID 002					
121	BNR	00B	GNSS Longitude Fine	Degrees	0.000172°	11	8.38-E-8°	200	1200
121	BNR	056	Horizontal Command Signal	The Same Parameters as the FMS EQ ID 002					
121	BNR	060	Horizontal Command Signal	The Same Parameters as the FMS EQ ID 002					
122	BNR	056	Vertical Command Signal	The Same Parameters as the FMS EQ ID 002					
122	BNR	060	Vertical Command Signal	The Same Parameters as the FMS EQ ID 002					
124	Discrete	00B	Digital Time Mark	-				200	1200
125	BCD	00B	UTC	Hr:Min	23:59.9	5	0.1 Min	200	1200
125	BCD	002	Universal Coordinate Time	Hr:Min	0-23.59.9	4	0.1	100	200
125	BCD	056	Universal Coordinated Time (UTC)	The Same Parameters as the FMS EQ ID 002					
125	BCD	060	Universal Coordinated Time (UTC)	The Same Parameters as the FMS EQ ID 002					

ATTACHMENT 1-16
SUPPLEMENT 16 UPDATES TO LABEL CODES

Code No. (Octal)	Data	Eqpt. ID (Hex)	Parameter	Units	Range	Sig Bits	Resolution	MIN TX	MAX TX
126	BNR	056	Vertical Deviation (Wide)	The Same Parameters as the FMS EQ ID 002					
126	BNR	060	Vertical Deviation (Wide)	The Same Parameters as the FMS EQ ID 002					
130	BNR	00B	Aut Horiz Integ Limit	NM	16	17	1.2E-4	200	1200
133	BNR	00B	Aut Vert Integ Limit	Feet	32, 768	18	0.125	200	1200
136	BNR	00B	Vertical Figure Of Merit	Feet	32, 768	18	0.125	200	1200
137	BNR	140	Flap Angle	Degrees	180	12	0.05	62.5	200
140	BNR	00B	UTC Fine	Seconds	1	20	0.953674μs	200	1200
140	Discrete	114	Pump Contactor States						
141	BNR	00B	UTC Fine Fractions	Seconds	0.9536743μs	10	0.9313225ns	200	1200
141	Discrete	114	Pump Contactor and Pushbutton States						
142	Discrete	114	Pump Push Button and LP Switch State						
143	Discrete	114	Pump LP Switch State and FCMC Commands						
144	Discrete	114	Valve Feedback						
145	Discrete	114	Valve Feedback						
146	Discrete	114	Valve Feedback						
147	Discrete	114	Valve Feedback						
150	BNR	00B	UTC	Hr:Min:S	±23:59:59	17	1.0 sec	200	1200
150	BNR	056	Universal Coordinated Time	The Same Parameters as the FMS EQ ID 002					
150	BNR	060	Universal Coordinated Time	The Same Parameters as the FMS EQ ID 002					
150	Discrete	114	FCMC Valve Commands						
151	BNR	055	MLS AZ Deviation	mV	± 2400	15	0.0732		
151	BNR	056	Localizer Bearing (True)	The Same Parameters as the FMS EQ ID 002					
151	BNR	060	Localizer Bearing (True)	The Same Parameters as the FMS EQ ID 002					
151	Discrete	114	FCMC Valve Commands						
152	BNR	055	MLS GP Deviation	mV	± 2400	15	0.0732		
152	Discrete	114	Overhead Panel Switch/ Pushbutton & Refuel Panel Battery Power Supply Switch States						
153	BNR	055	MLS Selected Azimuth	Degrees	0-359	9	1		
153	Discrete	114	Level States						
154	BNR	055	MLS Max Selectable GP	Degrees	±51.1	9	1		
154	BNR	056	Runway Heading (True)	The Same Parameters as the FMS EQ ID 002					
154	BNR	060	Runway Heading (True)	The Same Parameters as the FMS EQ ID 002					
154	Discrete	114	Level States and Low Warning and Transfer Indications						
155	BNR	055	MLS Selected Glide Path	Degrees	±51.1	9	0.01		
155	Discrete	114	XFR Pump Faults & Wing Imbalance Warning						
156	BNR	055	MLS Basic Data Wd 1	N/A	N/A	N/A	N/A		
156	Discrete	114	Refuel Panel Switch States						
157	SAL		System Address Label For CVR						
157	BNR	055	MLS Basic Data Wd 2	N/A	N/A	N/A	N/A		
157	BCD	114	Trim Tank Probe Capacitance	pf	0-400	14	0.1		
160	BNR	055	MLS Basic Data Wd 3	N/A	N/A	N/A	N/A		
160	Discrete	114	Valve Feedback						
161	BNR	055	MLS Basic Data Wd 4	N/A	N/A	N/A	N/A		
161	Discrete	114	Indicated Pump Status						
162	BNR	055	MLS Basic Data Wd 5	N/A	N/A	N/A	N/A		
162	Discrete	114	Indicated Pump Status						
162	BNR	140	Density Altitude	Feet	131072	16	2	250	500
163	BNR	055	MLS Basic Data Wd 6	N/A	N/A	N/A	N/A		
163	Discrete	114	Indicated Pump Status						
164	BNR	055	MLS ABS GP Angle	Degrees	± 41	15	0.00125		
164	Discrete	114	Indicated Pump Status						
165	BNR	00B	Vertical Velocity	Feet/Min	±32768	15	1.0	200	1200
165	BNR	055	MLS ABS Azimuth Angle	Degrees	± 82	16	0.00125		
165	Discrete	114	Indicated Valve Status						
166	BNR	00B	North/South Velocity	Knots	±4096	15	0.125	200	
166	Discrete	114	Indicated Valve Status						
167	BNR	002	EPU Estimate Position Uncertainty/ (ANP) Actual Navigation Performance	NM	0-128	16	0.00195		

ATTACHMENT 1-16
SUPPLEMENT 16 UPDATES TO LABEL CODES

Code No. (Octal)	Data	Eqpt. ID (Hex)	Parameter	Units	Range	Sig Bits	Resolution	MIN TX	MAX TX
167	Discrete	114	Indicated Valve Status						
170	Discrete	114	Wing Imbalance And FOI Failure Warning						
171	BNR	002	RNP Reduced Navigation Performance	NM	0-128	16	0.001953		
171	BNR	056	Current RNP	The Same Parameters as the FMS EQ ID 002					
171	BNR	060	Current RNP	The Same Parameters as the FMS EQ ID 002					
172			Subsystem Identifier						
173	BNR	055	Localizer Deviation	DDM	± 0.4	12	0.0001		
174	BNR	00B	East/West Velocity	Knots	±4096	15	0.125	200	1200
174	BNR	055	Glide Slope Deviation	DDM	± 0.8	12	0.0002		
176	BNR	0AD	Static Pressure Left, Uncorrected, mb	mb	2048	18	0.008	20	200
176	BNR	038	Left Static Pressure Uncorrected, mb	mb	2048	18	0.008	20	200
176	BNR	114	Left Outer Tank Fuel Temp & Advisory Warn	Degree C	±512	11	0.025		
177	BNR	0AD	Static Pressure Right, Uncorrected, mb	mb	2048	18	0.008	20	200
177	BNR	038	Right Static Pressure, Uncorrected, mb	mb	2048	18	0.008	20	200
177	BNR	055	Distance To Runway Threshold	Nmiles	1024	16	0.007812		
177	BNR	114	Inner Tank 1 Fuel Temp & Advisory Warning	Degree C	±512	11	0.025		
200	BCD	056	Drift Angle	The Same Parameters as the FMS EQ ID 002					
200	BCD	060	Drift Angle	The Same Parameters as the FMS EQ ID 002					
200	BNR	114	Inner Tank 2 Fuel Temp & Advisory Warning	Degree C	±512	11	0.025		
201	BNR	114	Inner Tank 3 Fuel Temp & Advisory Warning	Degree C	±512	11	0.025		
201	BNR	140	Mach Maximum Operation (Mmo)	Mach	4.096	12	0.001	62.5	125
201	BNR	142	Projected Future Latitude	Degrees	± 180	20	0.000172	150	400
202	BNR	114	Inner Tank 4 Fuel Temp & Advisory Warning	Degree C	±512	11	0.025		
202	BNR	140	Mach Rate	M/minute	4.096	12	0.001	62.5	125
202	BNR	142	Projected Future Latitude Fine	Degrees	.000172	11	2E-32 Cir	150	400
203	BNR	114	Trim Tank Fuel Temp & Advisory Warning	Degree C	±512	11	0.025		
203	BNR	140	Altitude	Feet	131072	17	1	31.25	62.5
204	BNR	056	Baro Altitude	The Same Parameters as the FMS EQ ID 002					
204	BNR	060	Baro Altitude	The Same Parameters as the FMS EQ ID 002					
204	BNR	114	Right Outer Tank Fuel Temp & Advisory Warning	Degree C	±512	11	0.025		
204	BNR	140	Baro Corrected Altitude	Feet	131072	17	1	31.25	62.5
205	BNR	140	Mach	Mach	4.096	16	0.0000625	62.5	125
206	BNR	056	Computed Airspeed	The Same Parameters as the FMS EQ ID 002					
206	BNR	060	Computed Airspeed	The Same Parameters as the FMS EQ ID 002					
206	BNR	140	Computed Airspeed (CAS)	Knots	1024	14	0.0625	62.5	125
207	BNR	140	Airspeed Maximum Operating (VMO)	Knots	1024	12	.025	62.56	125
210	BNR	140	True Airspeed	Knots	2048	15	0.0625	62.5	125
210	SAL		FCMC Com A340-500/600						
211	BNR	0AD	Total Air Temperature Indicated	Degree C	512	12	0.125	250	500
211	BNR	140	Total Air Temp (TAT)	Degree C	512	11	0.25	250	500
211	BNR	142	Projected Future Longitude	Degrees	± 180	20	0.000172	150	400
211	SAL		FCMC M on A340-500/600						
212	BNR	056	Altitude Rate	The Same Parameters as the FMS EQ ID 002					
212	BNR	060	Altitude Rate	The Same Parameters as the FMS EQ ID 002					
212	BNR	140	Altitude Rate	Ft/Min	32768	11	16	31.25	62.5
212	BNR	142	Projected Future Longitude Fine	Degrees	.000172	11	2E -32 Cir	150	400
212	SAL		FCMC Int A340-500/600						
213	BNR	140	Static Air Temp (SAT)	Degree C	512	11	0.25	250	500
213	BNR	142	Vertical Time Interval	Minute	265 min	10	.25 mile	500	2000
215	BNR	OAD	Impacted Pressure, Uncorrected, mb	mb	512	16	0.008	20	40
215	BNR	038	Impacted Pressure, Uncorrected, mb	mb	512	14	0.03125	62.5	125
215	BNR	006	Impacted Pressure, Uncorrected, mb	mb	512	14	0.03125	62.5	125
215	BNR	140	Impact Pressure Subsonic	mb	512	14	0.03125	62.5	125
217	BNR	0AD	Average Static Pressure	mb	2048	18	0.008	20	200
217	BNR	002	Geometric Vertical Rate	Ft/Min	20000	11	16		

ATTACHMENT 1-16
SUPPLEMENT 16 UPDATES TO LABEL CODES

Code No. (Octal)	Data	Eqpt. ID (Hex)	Parameter	Units	Range	Sig Bits	Resolution	MIN TX	MAX TX
217	BNR	006	Static Pressure, Corrected (In. Hg)	Inches Hg	64	16	0.001	20	200
217	BNR	038	Static Pressure, Average, Corrected (In. Hg)	Inches Hg	64	16	0.001	20	200
217	BNR	140	Static Pressure Corrected (In. Hg)	Inches Hg	64	16	0.001	62.5	125
220		056	MCDU #1 Address Label	The Same Parameters as the FMS EQ ID 002					
220		060	MCDU #1 Address Label	The Same Parameters as the FMS EQ ID 002					
220	BNR	140	Baro Corrected Altitude #2	Feet	131072	17	1	31.25	62.5
221		056	MCDU #2 Address Label	The Same Parameters as the FMS EQ ID 002					
221		060	MCDU #2 Address Label	The Same Parameters as the FMS EQ ID 002					
221	BNR	140	Angle Of Attack Indicated Average	Degrees	180	12	0.05	31.25	62.5
222		056	MCDU #3 Address Label	The Same Parameters as the FMS EQ ID 002					
222		060	MCDU #3 Address Label	The Same Parameters as the FMS EQ ID 002					
222	BNR	140	Angle Of Attack, Indicated #1 Left	Degrees	180	12	0.05	31.5	62.5
223		056	Printer #1 Address Label	The Same Parameters as the FMS EQ ID 002					
223		060	Printer #1 Address Label	The Same Parameters as the FMS EQ ID 002					
223	BNR	140	Angle Of Attack, Indicated #1 Right	Degrees	180	12	0.05	31.5	62.5
224		056	Printer #2 Address Label	The Same Parameters as the FMS EQ ID 002					
224		060	Printer #2 Address Label	The Same Parameters as the FMS EQ ID 002					
224	BNR	140	Angle Of Attack, Indicated #2 Left	Degrees	180	12	0.05	31.5	62.5
225	SAL		System Address Label For HUD						
225	BNR	056	Minimum Maneuvering Air Speed	The Same Parameters as the FMS EQ ID 002					
225	BNR	060	Minimum Maneuvering Air Speed	The Same Parameters as the FMS EQ ID 002					
225	BNR	140	Angle Of Attack, Indicated #2 Right	Degrees	180	12	0.05	31.5	62.5
226		00B	Data Loader Responses					200	1200
227	Discrete	019	CFDS Bite Command Summary For HFDR						
227	Discrete	053	CFDS Bite Command Word For HFDR						
230	BCD	114	Left Outer Probes Capacitance	pf	0-400	14	0.1		
231	BCD	0AD	Total Air Temperature	Degree C	512	12	20	200	
231	BCD	114	Inner 2 Tank Probe Capacitance	pf	0-400	14	0.1		
232	File Format	002	Active Intent Data Block						
232	DISC	055	GLS Airport ID						
232	Discrete	056	Active Intent Data Block	The Same Parameters as the FMS EQ ID 002					
232		060	Active Intent Data Block	The Same Parameters as the FMS EQ ID 002					
232	BCD	114	Inner 4 Tank Probe Capacitance	pf	0-400	14	0.1		
233	BNR	056	ACMS Information	The Same Parameters as the FMS EQ ID 002					
233	BNR	060	ACMS Information	The Same Parameters as the FMS EQ ID 002					
233	BCD	114	Right Outer Probe Capacitance	pf	0-400	14	0.1		
234	BNR	056	ACMS Information	The Same Parameters as the FMS EQ ID 002					
234	BNR	060	ACMS Information	The Same Parameters as the FMS EQ ID 002					
235	BNR	056	ACMS Information	The Same Parameters as the FMS EQ ID 002					
235	BNR	060	ACMS Information	The Same Parameters as the FMS EQ ID 002					
236	BNR	056	ACMS Information	The Same Parameters as the FMS EQ ID 002					
236	BNR	060	ACMS Information	The Same Parameters as the FMS EQ ID 002					
237	BNR	00B	Horizontal Uncertainty Level	Nm	16	17	0.000122		1200
237	BNR	002	ACMS Information	The Same Parameters as the FMS EQ ID 002					
237	BNR	056	ACMS Information	The Same Parameters as the FMS EQ ID 002					
237	BNR	060	ACMS Information	The Same Parameters as the FMS EQ ID 002					
241	SAL		System Address Label For APM-MMR						
241	BNR	056	Min. Airspeed for Flap Extension	The Same Parameters as the FMS EQ ID 002					
241	BNR	060	Min. Airspeed for Flap Extension	The Same Parameters as the FMS EQ ID 002					
241	BNR	140	Angle Of Attack, Corrected	Degrees	180	12	0.05	31.5	62.5
242	SAL		System Address Label for MMR						
242	BNR	0AD	Total Pressure, Uncorrected, mb						
242	File Format	002	Modified Intent Data Block						
242	BNR	056	Modified Intent Data Block	The Same Parameters as the FMS EQ ID 002					
242		060	Modified Intent Data Block	The Same Parameters as the FMS EQ ID 002					
242	BNR	140	Total Pressure	mb	2048	16	0.03125	62.5	125
243	DISC	055	GLS Runway Selection						

ATTACHMENT 1-16
SUPPLEMENT 16 UPDATES TO LABEL CODES

Code No. (Octal)	Data	Eqpt. ID (Hex)	Parameter	Units	Range	Sig Bits	Resolution	MIN TX	MAX TX
244	SAL		System Address Label for ILS						
244	BNR	140	Angle Of Attack, Normalized	Ratio	2	11	0.001	62.5	125
245	SAL		System Address Label For MLS						
245	BNR	0AD	Average Static Pressure mb, Uncorrected	mb	2048	18	0.008	20	200
245	BNR	038	Average Static Pressure mb, Uncorrected						
245	BNR	056	Minimum Airspeed	The Same Parameters as the FMS EQ ID 002					
245	BNR	060	Minimum Airspeed	The Same Parameters as the FMS EQ ID 002					
245	BNR	140	Static Pressure, Uncorrected	mb	2048	16	0.03125	62.5	125
246	SAL		System Address Label for AHRS						
246	BNR	038	Average Static Pressure mb, Corrected						
246	BNR	056	General Max Speed (Vcmax)	The Same Parameters as the FMS EQ ID 002					
246	BNR	060	General Max Speed (Vcmax)	The Same Parameters as the FMS EQ ID 002					
246	BNR	140	Static Pressure, Corrected	mb	2048	16	0.03125	62.5	125
247	BNR	00B	Horizontal Figure Of Merit	NM	16	18	6.1 E-5	200	1200
247	BNR	056	Control Minimum Speed (Vcmin)	The Same Parameters as the FMS EQ ID 002					
247	BNR	060	Control Minimum Speed (Vcmin)	The Same Parameters as the FMS EQ ID 002					
247	BNR	114	Fuel On Board	Pounds	655320	13	40		
247	BNR	140	Airspeed Minimum Vmc	Knots	512	11	0.25	62.5	125
250	BNR	0AD	Indicated Side Slip Angle or AOS	Deg/180	±180	14	0.01	31.3	200
250	BNR	114	Preselected Fuel Quantity	Pounds	655320	13	40		
251	SAL		System Address Label VDR #1						
252	SAL		System Address Label VDR #2						
253	SAL		System Address Label VDR #3						
254	Discrete	055	GBAS ID						200
254	BNR	140	Altitude Rate	Ft/Min	131072	13	16	31.25	62.5
255	Discrete	055	GBAS Airport ID						200
255	BNR	140	Impact Pressure	mb	4096	17	0.03125	62.5	125
256	BLOCK	055	MLS Station ID #1						
256	BNR	056	Time For Climb	The Same Parameters as the FMS EQ ID 002					
256	BNR	060	Time For Climb	The Same Parameters as the FMS EQ ID 002					
256	BNR	114	Left Outer Tank Fuel Quantity	Pounds	131068	15	4		
256	BNR	140	Equivalent Airspeed	Knots	1024	14	0.0625	62.5	125
257	BLOCK	055	MLS Station ID #2						
257	BNR	056	Time For Descent	The Same Parameters as the FMS EQ ID 002					
257	BNR	060	Time For Descent	The Same Parameters as the FMS EQ ID 002					
257	BNR	114	Inner Tank 1 Fuel Quantity	Pounds	131068	15	4		
257	BNR	140	Total Pressure (High Range)	mb	4096	17	0.03125	62.5	125
260	BCD	00B	Date	dd:Mo:Yr	dd:mm:yr	6	1 day	200	1200
260	BCD	056	Date/Flight Leg	The Same Parameters as the FMS EQ ID 002					
260	BCD	060	Date/Flight Leg	The Same Parameters as the FMS EQ ID 002					
260	BNR	114	Collector Cell 1 and 2 Fuel Quantity	Pounds	131068	15	4		
261	BCD	056	Flight Number (BCD)	The Same Parameters as the FMS EQ ID 002					
261	BCD	060	Flight Number (BCD)	The Same Parameters as the FMS EQ ID 002					
261	BNR	114	Fuel On Board At Engine Start	Pounds	131068	15	4		
262	BNR	056	Documentary Data	The Same Parameters as the FMS EQ ID 002					
262	BNR	060	Documentary Data	The Same Parameters as the FMS EQ ID 002					
262	BNR	114	Center Tank Fuel Quantity	Pounds	131068	15	4		
263	BLOCK	055	Ground Station/Approach						
263	BNR	056	Min. Airspeed For Flap Retraction	The Same Parameters as the FMS EQ ID 002					
263	BNR	060	Min. Airspeed For Flap Retraction	The Same Parameters as the FMS EQ ID 002					
263	BNR	114	Collector Cell 3 And 4 Fuel Quantity	Pounds	131068	15	4		
264	BLOCK	055	Ground Station/Approach						
264	BNR	056	Time To Touchdown	The Same Parameters as the FMS EQ ID 002					
264	BNR	060	Time To Touchdown	The Same Parameters as the FMS EQ ID 002					
264	BNR	114	Spare						
265	BNR	056	Min. Buffet Airspeed	The Same Parameters as the FMS EQ ID 002					
265	BNR	060	Min. Buffet Airspeed	The Same Parameters as the FMS EQ ID 002					
265	BNR	114	Inner Tank 3 Fuel Quantity	Pounds	131068	15	4		

ATTACHMENT 1-16
SUPPLEMENT 16 UPDATES TO LABEL CODES

Code No. (Octal)	Data	Eqpt. ID (Hex)	Parameter	Units	Range	Sig Bits	Resolution	MIN TX	MAX TX
266	BNR	114	Inner Tank 2 Fuel Quantity	Pounds	131068	15	4		
267	BNR	056	Max. Maneuver Airspeed	The Same Parameters as the FMS EQ ID 002					
267	BNR	060	Max. Maneuver Airspeed	The Same Parameters as the FMS EQ ID 002					
267	BNR	114	Inner Tank 4 Fuel Quantity	Pounds	131068	15	4		
270	Discrete	024	MU Output Data Word, Communication Link Status						
270	Discrete	039	MCDU Normal Discrete Word						
270	Discrete	041	SDU To ACARS MU/CMU Status Word						
270	Discrete	050	VDR Status Word						
270	Discrete	053	HFDL Status Word						
270	DISC	055	MLS Discrete						
270	Discrete	056	Status Discretes						
270	Discrete	058	Output Status Word #1						
270	DISC	060	Intent Status						
270	DISC	060	Status Discretes						
270	DISC	060	Discrete Data #1						
270	Discrete	114	Unusable, and Empty Warning						
270	Discrete	140	Discrete Data # 1					250	500
270	Discrete	142	Aircraft Category (Disc Data 1)					5000	15000
271	Discrete	041	SDU To ACARS MU/CMU Join /Leave Message						
271	DISC	055	MMR Discrete						
271	Discrete	056	Discrete Data #2						
271	DISC	060	Discrete Data #2						
271	Discrete	114	Fuel Transfer Indication						
271	Discrete	140	Discrete Data # 2					250	500
271	Discrete	142	Altitude Filter Limits (Disc Data 2)					500	2000
272	Discrete	053	HFDL Slave (Disc Data 3)						
272	Discrete	056	Discrete Data #3						
272	DISC	060	Discrete Data #3						
272	Discrete	114	Fuel Transfer Indication						
272	Discrete	140	Discrete Data # 3					250	500
273	DIS	00B	GNSS Sensor Status	N/A				200	1200
273	DISC	055	GNSS Status						
273	Discrete	114	Memos And Status						
274	Discrete	114	Fuel Transfer Indications						
275	Discrete	038	IR Discrete Word #2						
275	Discrete	056	Discrete Data #6						
275	DISC	060	Discrete Data #6						
275	Discrete	114	Miscellaneous Warning						
276	Discrete	024	MU Output Data Word, Pin Program Status						
276	Discrete	041	SDU To EICAS/ECAM/EDU For Dual SATCOM						
276	Discrete	050	VDR Mode Command						
276	Discrete	056	Discrete Data #7						
276	Discrete	058	Output Status Word #2						
276	DISC	060	Discrete Data #7						
276	Discrete	114	Miscellaneous Discrete						
277	Discrete	004	IRS Maintenance Discrete						
277	Discrete	114	Fuel Transfer and CG Status						
301		056	Application Dependent	The Same Parameters as the FMS EQ ID 002					
301		060	Application Dependent						
302		056	Application Dependent	The Same Parameters as the FMS EQ ID 002					
302		060	Application Dependent						
303		056	Application Dependent	The Same Parameters as the FMS EQ ID 002					
303		060	Application Dependent						
310	SAL		System Address Label for GPWS						
310	BNR	056	Present Position Latitude	The Same Parameters as the FMS EQ ID 002					
310	BNR	060	Present Position Latitude	The Same Parameters as the FMS EQ ID 002					

ATTACHMENT 1-16
SUPPLEMENT 16 UPDATES TO LABEL CODES

Code No. (Octal)	Data	Eqpt. ID (Hex)	Parameter	Units	Range	Sig Bits	Resolution	MIN TX	MAX TX
310	BNR	114	Right Outer Tank Fuel Quantity	Pounds	131068	15	4		
311	SAL		System Address Label for GNLU 1						
311	BNR	056	Present Position Longitude	The Same Parameters as the FMS EQ ID 002					
311	BNR	060	Present Position Longitude	The Same Parameters as the FMS EQ ID 002					
311	BNR	114	Trim Tank Fuel Quantity	Pounds	131068	15	4		
312	SAL		System Address Label for GNLU 2						
312	BNR	056	Ground Speed	The Same Parameters as the FMS EQ ID 002					
312	BNR	060	Ground Speed	The Same Parameters as the FMS EQ ID 002					
312	BNR	114	Additional Center Tank (Act 1) Fuel Quantity	Pounds	131068	15	4		
313	SAL		System Address Label For GNLU 3						
313	BNR	056	Track Angle True	The Same Parameters as the FMS EQ ID 002					
313	BNR	060	Track Angle True	The Same Parameters as the FMS EQ ID 002					
313	BNR	114	Additional Center Tank (Act 2) Fuel Quantity	Pounds	131068	15	4		
314	SAL		System Address Label For GNU 1						
314	BNR	114	Rear Center Tank (RCT) Fuel Quantity	Pounds	131068	15	4		
315	SAL		System Address Label For GNU 2						
315	BNR	056	Wind Speed	The Same Parameters as the FMS EQ ID 002					
315	BNR	060	Wind Speed	The Same Parameters as the FMS EQ ID 002					
316	SAL		System Address Label For GNU 3						
316	BNR	056	Wind Direction (True)	The Same Parameters as the FMS EQ ID 002					
316	BNR	060	Wind Direction (True)	The Same Parameters as the FMS EQ ID 002					
317	BNR	056	Track Angle Magnetic	The Same Parameters as the FMS EQ ID 002					
317	BNR	060	Track Angle Magnetic	The Same Parameters as the FMS EQ ID 002					
320	BNR	05A	Fuel Quantity Act 3						
320	BNR	056	Magnetic Heading	The Same Parameters as the FMS EQ ID 002					
320	BNR	060	Magnetic Heading	The Same Parameters as the FMS EQ ID 002					
321	SAL		System Address Label for Autothrottle Computer						
321	BNR	056	Drift Angle	The Same Parameters as the FMS EQ ID 002					
321	BNR	060	Drift Angle	The Same Parameters as the FMS EQ ID 002					
322	SAL		System Address Label for FCC 1						
322	BNR	056	Flight Path Angle	The Same Parameters as the FMS EQ ID 002					
322	BNR	060	Flight Path Angle	The Same Parameters as the FMS EQ ID 002					
323	SAL		System Address Label For FCC 2						
323	BNR	002	Geometric Altitude	Feet	50000	17	1		
323	BNR	056	Geometric Altitude	The Same Parameters as the FMS EQ ID 002					
323	BNR	060	Geometric Altitude	The Same Parameters as the FMS EQ ID 002					
324	SAL		System Address Label For FCC 3						
324	BNR	056	Estimated Position Uncertainty	The Same Parameters as the FMS EQ ID 002					
324	BNR	060	Estimated Position Uncertainty	The Same Parameters as the FMS EQ ID 002					
324	BNR	114	Effective Pitch Angle	Degrees	±180	13	0.02		
325	SAL		System Address Label For APU						
325	BNR	114	Effective Roll Angle	Degrees	±180	13	0.02		
326	SAL		System Address Label For APU Controller						
327	SAL		SAL Mode Control Pane (MCP)						
330	SAL		System Address Label For FMC 3						
331	SAL		System Address Label For ATC Transponder						
332	SAL		System Address Label For DADC						
335	BNR	002	Track Angle Rate	Deg/Sec	32	11	0.015	10	20
335	BNR	056	Track Angle Rate	The Same Parameters as the FMS EQ ID 002					
335	BNR	060	Track Angle Rate	The Same Parameters as the FMS EQ ID 002					
340	BNR	004	Inertial Yaw Rate	Deg/Sec	128	13	0.015	10	20
340	BNR	004	Track Angle Grid	Degree	± 180	15	0.0055	20 Hz	110 Hz
340	BNR	005	Inertial Yaw Rate	Deg/Sec	128	13	0.015	10	20
340	BNR	140	Pressure Ratio (Pt/Ps)	Ratio	16	14	0.001	62.5	125
341	BNR	004	Grid Heading	Degree	± 180	15	0.0055	20 Hz	110 Hz
341	BNR	038	Grid Heading	Degree	± 180	15	0.0055	20 Hz	110 Hz
341	BNR	140	Pressure Ratio (Ps/Pso)	Ratio	4	12	0.001	62.5	125

ATTACHMENT 1-16
SUPPLEMENT 16 UPDATES TO LABEL CODES

Code No. (Octal)	Data	Eqpt. ID (Hex)	Parameter	Units	Range	Sig Bits	Resolution	MIN TX	MAX TX
342	BNR	140	Air Density Ratio	Ratio	4	12	0.001	250	500
350	Discrete	004	IRS Maintenance Discrete						
350	Discrete	018	Maintenance Data #1						
350	Discrete	019	CFDS Bite Fault Summary Word For HFDR						
350	Discrete	024	MU Output Data Word Failure Status						
350	Discrete	038	IRS Maintenance Word #1						
350	Discrete	050	VDR Fault Summary Word						
350	Discrete	053	CFDS Bite Fault Summary Word For HFDU						
350	DISC	055	ILS Maintenance Word						
350	Discrete	058	Maintenance Word #1						
350	BCD	114	Fuel Density	kg/l	0-.999	4	0.01		
350	Discrete	140	Maintenance Data # 1					250	500
351	Discrete	024	MU Output Data Word, Failure Status						
351	Discrete	038	IRS Maintenance Word #2						
351	DISC	055	MMR Maintenance Word						
351	Discrete	058	Maintenance Word #2						
351	BCD	114	Inner Tank 1 Probe Capacitance	pf	0-400	14	0.1		
351	Discrete	140	Maintenance Data # 2					250	500
352	DISC	055	MLS Bite Status						
352	Discrete	058	Maintenance Word						
352	BCD	114	Center, ACT & RCT Probe Capacitance	pf	0-400	14	0.1		
352	Discrete	140	Maintenance Data # 3 Flight Count		524287			250	500
353	Discrete	038	IRS Maintenance Word #3						
353	BCD	114	Inner Tank 3 Probe Capacitance	pf	0-400	14	0.1		
354		056	Maintenance Data #5	The Same Parameters as the FMS EQ ID 002					
354		060	Maintenance Data #5						
355	DIS	00B	GNSS Fault Summary	-		21		200	1200
355	Discrete	038	IRS Maintenance Word #4						
357	ISO-5	056	ISO Alphabet #5 Message	The Same Parameters as the FMS EQ ID 002					
357	ISO-5	060	ISO Alphabet #5 Message	The Same Parameters as the FMS EQ ID 002					
360	BNR	056	Flight Information	The Same Parameters as the FMS EQ ID 002					
360	BNR	060	Flight Information	The Same Parameters as the FMS EQ ID 002					
360	BNR	142	RAIM Status Word	NM	16	13	0.00195		
362	SAL		System Address Label For PSS						
363	SAL		System Address Label For CSS						
364	SAL		System Address Label For AES						
366	SAL		System Address Label For Multicast						
367	SAL		System Address Label For Bridge						
370	BNR	00B	GNSS Height WGS-84 (Hae)	Feet	±131,072	20	0.125		1200
370	BNR	00B	GNSS Height	Feet	±131,072	20	0.125	200	1200
375	BNR	004	Along Hdg Accel	Gs	4	18	1.53E-5	50 Hz	110Hz
375	BNR	038	Along Hdg Accel	Gs	4	18	1.53E-5	50 Hz	110Hz
376	BNR	004	Cross Hdg Accel	Gs	4	18	1.53E-5	50 Hz	110Hz
376	BNR	038	Cross Hdg Accel	Gs	4	18	1.53E-5	50 Hz	110Hz

AERONAUTICAL RADIO, INC.
2551 Riva Road
Annapolis, Maryland 24101-7465

SUPPLEMENT 17
TO
ARINC SPECIFICATION 429 P1
MARK 33 DIGITAL INFORMATION TRANSFER SYSTEM (DITS)
PART 1
FUNCTIONAL DESCRIPTION, ELECTRICAL INTERFACE,
LABEL ASSIGNMENTS AND WORD FORMATS

Published: May 17, 2004

A. PURPOSE OF THIS DOCUMENT

This Supplement introduces new label assignments, equipment IDs, system address labels and updates to ARINC Specification 429.

B. ORGANIZATION OF THIS SUPPLEMENT

The material in Supplement 17 is integrated into ARINC Specification 429 to form an updated version of the standard.

Changes introduced by Supplement 17 are identified using change bars and are labeled by a “c-17” symbol in the margin.

C. CHANGES TO ARINC SPECIFICATION 429 INTRODUCED BY THIS SUPPLEMENT

This section presents a complete tabulation of the changes and additions to the Specification introduced by this Supplement. Each change or addition is defined by the section number and the title currently employed in the Specification or by the section name and title that will be employed when the Supplement is eventually incorporated. In each case a brief description of the change or addition is included.

3.1.4.6 VHF Communications

The Frequency Range and Frequency Selection Increments were revised to reflect 8.33 kHz spacing.

ATTACHMENT 1-1 LABEL CODES

This Attachment was updated according to ARINC 429 New and Revised Label Assignments Table on page 3.

A Note was added to label 377 to clarify the SSM.

ATTACHMENT 1-2 - EQUIPMENT CODES

The following Equipment Codes were added:

EQ ID	EQUIPMENT TYPE
061	High-Speed Data Unit (HSDU)
0C4	A429W SDU Controller
11E	Integrated Static Probe
120	Multifunctional Air Data Probe
144	CDTI Display Unit
14A	Slide Slip Angle (SSA)
171	Electronic Flight Bag
1E2	ADS-B LDPU Controller

ATTACHMENT 2 - DATA STANDARDS

This Attachment was updated according to ARINC 429 New and Revised Label Assignments Table on page 3.

ATTACHMENT 6 – GENERAL WORD FORMATS AND ENCODING EXAMPLES

Table 6-17 was revised to correct the error in the SSM.

Table 6-24 was revised to correctly identify SPI. In addition, bit 17 was revised to indicate Hijack Mode.

Table 6-39 (ICAO Address) will be removed from Part I and added to Part II

Tables 6-49, 6-50, and 6-51 were added by this Supplement.

ATTACHMENT 10 – MANUFACTURER-SPECIFIC STATUS

Bits 9 and 10 were revised to indicate SDI and Note B was added.

Company identification was added for RYAN.

ATTACHMENT 11 - SYSTEM ADDRESS LABELS

The following System Address Labels were added or revised:

SAL OCTAL LABEL	SYSTEM
156	CVR #2
174	HGA/IGA HPA
175	HGA/HPA Starboard
177	LGA HPA
247	High-Speed Data (HSDU #1)
250	High-Speed Data (HSDU #2)
254	Network Server System
255	Electronic Flight Bag Left
256	Electronic Flight Bag Right
345	Remote Data Concentrator

APPENDIX E – GUIDELINES FOR LABEL ASSIGNMENTS

Item 2 was revised to clarify the confusion on the SSM for label 377 Equipment Identification.

ARINC 429 NEW AND REVISED LABEL ASSIGNMENTS

	LABEL	Data	EQ ID	PARAMETER	UNITS	RANGE	SIG Bits	RESOL	MIN TX	MAX TX
New	101	Binary	05A	FQIC	Lbs	4- 65532	14	4	900	1100
New	124	Binary	1E2	Horizontal Alarm Limit	Meters	0 – 8190	13	1 meter	800	1200
New	124	Binary	0A5	Client Device for GNSS Receiver	Meters	8192	13	1 meter		200
New	127	Binary	1E2	Vertical Alarm Limit	Meters	0 – 255	8	1 meter	800	1200
Revised	141	Binary	00B	UTC Fine Fractions	Seconds	0.9536743 μ s	10	0.931225ns	200	1200
New	152	Binary	038	Cabin Pressure	mB	2048	16	0.03125	62.5	125
New	152	Binary	0AD	Cabin Pressure	mB	2048	18	0.008	20	200
Revised	155	Discrete	05A	FQIC					900	1100
New	156	SAL		CVR #2						
Revised	171			Manufacturer-Specific Status						
New	171	BINARY	0A5	Vertical Alarm limit (VAL) and SBAS System Identifier	Meters	256	8	1 meter		200
Revised	214	Discrete	xxx	ICAO Aircraft Address Part 1						
Revised	216	Discrete	xxx	ICAO Aircraft Address Part 2						
New	247	SAL		High-Speed Data Unit #1 (HSDU #1)						
New	250	SAL		High-Speed Data Unit #2 (HSDU #2)						
New	254	SAL		Network Server System (NSS)						
New	255	SAL		Electronic Flight Bag – Left						
New	256	SAL		Electronic Flight Bag – Right						
New	261	Binary	144	Range Ring Radius	NM	512	15	1/64 NM	800	1200
New	262	Binary	144	Display Range	NM	512	14	1/32 NM	800	1200
New	270	Discrete	144	Display Mode					800	1200
New	271	Discrete	144	Altitude Filter Setting					800	1200
New	272	Discrete	144	Target Selection Word					800	1200
New	272	Discrete	005	Air Data AHARS					250	500
New	276	Discrete	058	VDR Mode					250	500
deleted	320	Binary	05A	Fuel Quantity ACT 3						
New	345	SAL		Remote Data Concentrator						
New	350	Discrete	144	CDTI Fault Summary Word					800	1200
New	357	Discrete	05A	Part Number (manufacturer-Specific)						
New	377	Discrete	xxx	Equipment Identification						

ARINC IA Project Initiation/Modification (APIM) Guidelines for Submittal

(Wednesday, May 19, 2004)

1. ARINC Industry Activities Projects and Work Program

A project is established in order to accomplish a technical task approved by one or more of the committees (AEEC, AMC, FSEMC). Projects generally but not exclusively result in a new ARINC standard or modify an existing ARINC standard. All projects are typically approved on a calendar year basis. Any project extending beyond a single year will be reviewed annually before being re-authorized. The work program of Industry Activities (IA) consists of all projects authorized by AEEC, AMC, or FSEMC (The Committees) for the current calendar year.

The Committees establish a project after consideration of an ARINC Project Initiation/Modification (APIM) request. This document includes a template which has provisions for all of the information required by The Committees to determine the relative priority of the project in relation to the entire work program.

All recommendations to the committees to establish or reauthorize a project, whether originated by an airline or from the industry, should be prepared using the APIM template. Any field that cannot be filled in by the originator may be left blank for subsequent action.

2. Normal APIM Evaluation Process

Initiation of an APIM

All proposed projects must be formally initiated by filling in the APIM template. An APIM may be initiated by anyone in the airline community, e.g., airline, vendor, committee staff.

Staff Support

All proposed APIMs will be processed by committee staff. Each proposal will be numbered, logged, and evaluated for completeness. Proposals may be edited to present a style consistent with the committee evaluation process. For example, narrative sentences may be changed to bullet items, etc. When an APIM is complete, it will be forwarded to the appropriate Committee for evaluation.

The committee staff will track all ongoing projects and prepare annual reports on progress.

Committee Evaluation and Acceptance or Rejection

The annual work program for each Committee is normally established at its annual meeting. Additional work tasks may be evaluated at other meetings held during the year. Each committee (i.e., AMC, AEEC, FSEMC) has its own schedule of annual and interim meetings.

The committee staff will endeavor to process APIMs and present them to the appropriate Committee at its next available meeting. The Committee will then evaluate the proposal. Evaluation criteria will include:

- Airline support – number and strength of airline support for the project, including whether or not an airline chairman has been identified
- Issues – what technical, programmatic, or competitive issues are addressed by the project, what problem will be solved
- Schedule – what regulatory, aircraft development or modification, airline equipment upgrade, or other projected events drive the urgency for this project

Accepted proposals will be assigned to a subcommittee for action with one of two priorities:

- High Priority – technical solution needed as rapidly as possible
- Routine Priority – technical solution to proceed at a normal pace

Proposals may have designated coordination with other groups. This means that the final work must be coordinated with the designated group(s) prior to submittal for adoption consideration.

Proposals that are not accepted may be classified as follows:

- Deferred for later consideration - the project is not deemed of sufficient urgency to be placed on the current calendar of activities but will be reconsidered at a later date
- Deferred to a subcommittee for refinement – the subcommittee will be requested to, for example, gain stronger airline support or resolve architectural issues
- Rejected – the proposal is not seen as being appropriate, e.g., out of scope of the committee

3. APIM Template

The following is an annotated outline for the APIM. Proposal initiators are requested to fill in all fields as completely as possible, replacing the italicized explanations in each section with information as available. Fields that cannot be completed may be left blank. When using the Word file version of the following template, update the header and footer to identify the project.

ARINC IA Project Initiation/Modification (APIM)

Name of proposed project

APIM #: _____

Name for proposed project.

Suggested Subcommittee assignment

Identify an existing group that has the expertise to successfully complete the project. If no such group is known to exist, a recommendation to form a new group may be made.

Project Scope

Describe the scope of the project clearly and concisely. The scope should describe “what” will be done, i.e., the technical boundaries of the project. Example: “This project will standardize a protocol for the control of printers. The protocol will be independent of the underlying data stream or page description language but will be usable by all classes of printers.”

Project Benefit

Describe the purpose and benefit of the project. This section should describe “why” the project should be done. Describe how the new standard will improve competition among vendors, giving airlines freedom of choice. This section provides justification for the allocation of both IA and airline resources. Example: “Currently each class of printers implements its own proprietary protocol for the transfer of a print job. In order to provide access to the cockpit printer from several different avionics sources, a single protocol is needed. The protocol will permit automatic determination of printer type and configuration to provide for growth and product differentiation.”

Airlines supporting effort

Name, airline, and contact information for proposed chairman, lead airline, list of airlines expressing interest in working on the project (supporting airlines), and list of airlines expressing interest but unable to support (sponsoring airlines). It is important for airline support to be gained prior to submittal. Other organizations, such as airframe manufacturers, avionics vendors, etc. supporting the effort should also be listed.

Issues to be worked

Describe the major issues to be addressed by the proposed ARINC standard.

Recommended Coordination with other groups

Draft documents may have impact on the work of groups other than the originating group. The APIM writer or, subsequently, The Committee may identify other groups which must be given the opportunity to review and comment upon mature draft documents.

Projects/programs supported by work

If the timetable for this work is driven by a new airplane type, major avionics overhaul, regulatory mandate, etc., that information should be placed in this section. This information is a key factor in assessing the priority of this proposed task against all other tasks competing for subcommittee meeting time and other resources.

Timetable for projects/programs

Identify when the new ARINC standard is needed (month/year).

Documents to be produced and date of expected result

The name and number (if already assigned) of the proposed ARINC standard to be either newly produced or modified.

Comments

Anything else deemed useful to the committees for prioritization of this work.

Meetings

The following table identifies the number of meetings and proposed meeting days needed to produce the documents described above.

Activity	Mtgs	Mtg-Days
Document a	# of mtgs	# of mtg days
Document b	# of mtgs	# of mtg days

For IA staff use

Date Received _____ IA staff assigned: _____

Potential impact: _____

(A. Safety B. Regulatory C. New aircraft/system D. Other)

Forward to committee(s) (AEEC, AMC, FSEMC): _____ Date Forward: _____

Committee resolution: _____

(0. Withdrawn 1. Authorized 2. Deferred 3. More detail needed 4. Rejected)

Assigned Priority: _____ Date of Resolution: _____

A. – High (execute first) B. – Normal (may be deferred for A.)

Assigned to SC/WG _____

ARINC Standard – Errata Report

1. Document Title

ARINC Specification 429P1-17: *Mark 33 Digital Information Transfer System (DITS) Part 1, Functional Description, Electrical Interface, Label Assignments and Word Formats*

2. Reference

Page Number: _____ Section Number: _____ Date of Submission: _____

3. Error

(Reproduce the material in error, as it appears in the standard.)

4. Recommended Correction

(Reproduce the correction as it would appear in the corrected version of the material.)

5. Reason for Correction

(State why the correction is necessary.)

6. Submitter (Optional)

(Name, organization, contact information, e.g., phone, email address.)

Note: Items 2-5 may be repeated for additional errata. All recommendations will be evaluated by the staff. Any substantive changes will require submission to the relevant subcommittee for incorporation into a subsequent Supplement.

Please return comments to fax +1 410-266-2047 or standards@arinc.com