Minimum Operational Performance Standards for Traffic Alert and Collision Avoidance System II (TCAS II)

Version 7.1

Change 1

Prepared by: SC-147

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Executive Summary

This Change 1 document specifies a change to the TCAS II requirements contained in RTCA document DO-185B. The rationale for the change is described in change proposal CP123, which was approved by the SC-147 Requirements Working Group.

The first part of the change concerns an aspect of the TCAS multiaircraft logic. It affects the "middle" aircraft of a multi-threat situation, and removes the feature that would have required a green arc to accompany that aircraft's RA.

The second part of the change clarifies the coding of certain bits reporting Hybrid Surveillance capability within the Data Link Capability Report, to be consistent with a change made to DO-300.

Section 1 provides the text changes to Volume I.

Section 2 provides changes to the Pseudocode in Volume II, Attachment A.

Section 3 provides changes to the state charts in Volume II.

Section 4 provides changes to the TSIM data set that is specified for the verification of the TCAS implementation. This material is not part of DO-185B, but is accompanying material distributed by FAA, not by RTCA.



1 Changes to Volume I

The following correction is needed in order to more accurately describe the behavior of the multi-aircraft logic when own aircraft is "projected in the middle".

2.2.5.3.3 Multi-Aircraft Logic

<u>Note:</u> Special rules are invoked when a TCAS-equipped aircraft is involved in a multiple-aircraft encounter. The pilot of the aircraft with "projected clear airspace above" is told to CLIMB, and the pilot of the aircraft with "projected clear airspace below" is told to DESCEND. Aircraft "projected in the middle" are told to limit their climb and their descent until the aircraft above or below

are no longer in conflict.

The selection of a positive DESCEND advisory in a multi-aircraft situation is also subject to the performance limitations of the TCAS aircraft when it is near the Descend Inhibit altitude threshold. In this case, a negative DON'T CLIMB will be selected instead of DESCEND.

The multi-aircraft logic has been designed to prevent premature level-off RAs when own is to pass between two threats vertically. This requires retention of a positive RA until certain criteria have been met so that vertical separation is maximized. The multi-aircraft logic also includes the ability to model and select Increase Rate RAs and sense reversals to better resolve situations that are deteriorating due to adverse maneuvers by own aircraft or one of the threats. (The ability to generate an Increase Rate RA is subject to the INCREASE CLIMB and INCREASE DESCENT inhibit indications and thresholds.) The logic also performs an unbiased evaluation of all new threats to select the optimum RA against all rather than constraining the RA to be selected against the second or third threat by the initial choice against the first.

Following is the change needed to the coding of the data link capability report:

2.2.3.9.3.2.3.2.1 Coding of Data Link Capability Report - DO-185A,B Systems

Bits 48, 69, 70, 71 and 72 are used to convey TCAS capability information as follows:

Bit(s) Coding

0 = TCAS failed or on standby

1 = TCAS operating

0 =Hybrid surveillance not operational

1 = Hybrid surveillance fitted and operational

0 = TCAS generating TAs only

1 = TCAS generating TAs and RAs

72,71 TCAS Version

0.0 = RTCA DO-185

0.1 = RTCA DO-185A

1,0 = RTCA DO-185B and ED-143

1,1 = Future versions (see registers $E5_{16}$ and $E6_{16}$ in Ref. L)

2.2.3.9.3.2.3.2.2 Coding of Data Link Capability Report - FAA TSO-C119A Systems

Bit 48: Bit 48 = 1 indicates that the TCAS/transponder interface is operational and that TCAS is reporting RI=2 or 3 for use in the

air-to-air Reply Information field (2.2.3.9.3.1.14).

Bits 69, 70: On-Board Resolution Capability Bits - Bits 69 and 70 form a

capability code subfield which indicates aircraft's on-board

resolution advisory generation capability.

The codes are:

0 = No on-board resolution advisory generation capability.

1 = An on-board vertical-only resolution advisory generation capability

exists.

2 = An on-board vertical and horizontal resolution advisory generation

capability exists (not applicable to FAA TSO-C119A systems).

3 = Not assigned.

Following is the change needed to a test procedure, as a result of the change made to section 2.2.3.9.3.2.3.2.1:

2.4.2.2.5 TCAS Capability Reporting (2.2.3.13.2.2.4 and 2.2.3.13.2.2.1)

(text omitted)

When testing with an RTCA/DO-185A,B compatible Mode S transponder:

Msgs: DF=20 with BDS=16, bits 48, 69, 70, 71, 72 = 0xy01 at T=4 and 64

DF=21 with BDS=16, bits 48, 69, 70, 71, 72 = 0xy01 at T=9 and 69

DF=20 with BDS=16, bits 48, 69, 70, 71, 72 = 1x001 at T=24, 34

DF=21 with BDS=16, bits 48, 69, 70, 71, 72 = 1x001 at T=29, 39

DF=20 with BDS=16, bits 48, 69, 70, 71, 72 = 1x101 at T=44, 54

DF=21 with BDS=16, bits 48, 69, 70, 71, 72 = 1x101 at T=49, 59

Where x=0 if hybrid surveillance is not operational

x=1 if hybrid surveillance is fitted and operational

y=don't care



2 Changes to Pseudocode

The pseudocode changes needed to implement change proposal CP123 follow. Only a single pseudocode program is affected, Set_up_display_outputs (DO-185B, Volume II, Attachment A, pages 8-P16 and 8-P17). Both the published DO-185B version (BEFORE) and the revised version (AFTER) of both the high-level and low-level pseudocode are shown below. The changes in the AFTER versions are highlighted.

In addition to the changes needed to implement the change proposal, it was noted that the published version of the low-level pseudocode is missing a needed "G." reference to the global data structure G, and that is also fixed and highlighted.

<Determine advisory annunciation precedence>

<u>IF</u> (an RA is to be displayed this cycle)

THEN IF (increase rate RA issued)

THEN CLEAR reversal, maintain rate, and altitude crossing flags;

<u>IF</u> (increase rate RA was not present last cycle)

THEN indicate that RA changed to increase rate this cycle;

ELSE CLEAR indication that increase rate RA was present last cycle;

<u>IF</u> (RA requires maintenance of rate)

THEN SET maintain rate indication;

CLEAR sense reversal indication, if any; <announce maintain>

<u>ELSE</u> <u>IF</u> (previous cycle's RA was dual negative <u>AND</u> current RA is either single negative or positive)

THEN CLEAR maintain rate indication;

<u>IF</u> (sense of previously displayed RA has been reversed)

<u>THEN</u> <u>CLEAR</u> altitude crossing flag; <Reversal needs to be announced even if the reversed RA is altitude crossing>

<u>CLEAR</u> maintain rate indication; <If reversing maintain RA>

<u>IF</u> (RA is preventive) <Initial preventive neg. or VSL RA or weakening> <Note: All positive RAs are now corrective>

THEN IF (RA is dual negative) < Don't Climb/Don't Descend>

THEN SET maintain rate indication; <announce maintain>

ELSE CLEAR maintain rate indication;

<u>IF</u> (positive Climb is weakening to negative Don't Descend <u>OR</u> (positive Descend is weakening to negative Don't Climb <u>AND</u> not in extreme low altitude condition))

<u>THEN</u> indicate that weakened RA is corrective; <Results in green "fly-to" arc plus corrective aural annunciation for initial weakening>

Set displayed-model-goal rate to 0 fpm; <RA display device will use prescribed vertical rates for neg. & VSL RAs>

ELSE IF (RA is corrective negative or VSL)

THEN CLEAR maintain rate indication;

Set displayed-model-goal rate to 0 fpm;

CLEAR clear of conflict flag;

<u>ELSE</u> <u>CLEAR</u> maintain rate indication; <no RA is to be displayed this cycle> Set displayed-model-goal rate to 0 fpm;

 $\underline{IF} \ (\text{an altitude-reporting threat became non-altitude-reporting during preceding RA})$

THEN CLEAR track drop and clear of conflict flags;

ELSE IF (a threat's track was dropped during preceding RA)

THEN CLEAR clear of conflict flag;

<u>PERFORM</u> Load_display_and_aural_info; <Load display information to be sent to the RA display, TA display and aural annunciation subsystem.>

END Set_up_display_outputs;

<Determine advisory annunciation precedence>

<u>IF</u> (an RA is to be displayed this cycle)

THEN IF (increase rate RA issued)

THEN CLEAR reversal, maintain rate, and altitude crossing flags;

<u>IF</u> (increase rate RA was not present last cycle)

THEN indicate that RA changed to increase rate this cycle;

ELSE CLEAR indication that increase rate RA was present last cycle;

<u>IF</u> (RA requires maintenance of rate)

THEN SET maintain rate indication;

<u>CLEAR</u> sense reversal indication, if any; <announce maintain>

<u>ELSE</u> <u>IF</u> (previous cycle's RA was dual negative <u>AND</u> current RA is either single negative or positive)

THEN CLEAR maintain rate indication;

<u>IF</u> (sense of previously displayed RA has been reversed)

<u>THEN</u> <u>CLEAR</u> altitude crossing flag; <Reversal needs to be announced even if the reversed RA is altitude crossing>

CLEAR maintain rate indication; <If reversing maintain RA>

<u>IF</u> (RA is preventive) <Initial preventive neg. or VSL RA or weakening> <Note: All positive RAs are now corrective>

THEN IF (RA is dual negative) <Don't Climb/Don't Descend>

THEN SET maintain rate indication; <announce maintain> ELSE CLEAR maintain rate indication;

<u>IF</u> ((positive Climb is weakening to negative Don't Descend <u>OR</u> (positive Descend is weakening to negative Don't Climb <u>AND</u> not weakening due to extreme low altitude condition)) <u>AND</u> not weakening due to multiaircraft "sandwich" encounter with both up-sense and down-sense VSLs)

THEN indicate that weakened RA is corrective; <Results in green "fly-to" arc plus corrective aural annunciation for initial weakening>

Set displayed-model-goal rate to 0 fpm; <RA display device will use prescribed vertical rates for neg. & VSL RAs>

ELSE IF (RA is corrective negative or VSL)

<u>THEN</u> <u>CLEAR</u> maintain rate indication; Set displayed-model-goal rate to 0 fpm;

CLEAR clear of conflict flag;

<u>ELSE</u> <u>CLEAR</u> maintain rate indication; <no RA is to be displayed this cycle> Set displayed-model-goal rate to 0 fpm;

IF (an altitude-reporting threat became non-altitude-reporting during preceding RA)

THEN CLEAR track drop and clear of conflict flags;

ELSE IF (a threat's track was dropped during preceding RA)

THEN CLEAR clear of conflict flag;

<u>PERFORM</u> Load_display_and_aural_info; <Load display information to be sent to the RA display, TA display and aural annunciation subsystem.>

END Set_up_display_outputs;

IF (any bit in G.RA(1–10)EQ \$TRUE)

THEN IF (G.ANYINCREASE EQ \$TRUE)

THEN CLEAR G.ANYREVERSE, G.MAINTAIN, G.ANYCROSS;

IF (G.PREVINCREASE EQ \$FALSE)

THEN SET G.ANYCORCHANG, G.PREVINCREASE;

ELSE CLEAR G.PREVINCREASE;

<u>IF</u> ((G.RA(1) <u>EQ</u> \$TRUE <u>AND</u> G.ZDMODEL <u>GT</u> P.CLMRT <u>AND</u>

G.ZDOWN GT P.CLMRT) OR (G.RA(6) EQ \$TRUE AND

G.ZDMODEL LT P.DESRT AND G.ZDOWN LT P.DESRT))

THEN SET G.MAINTAIN;

CLEAR G.ANYREVERSE;

ELSE IF ((G.CLSTROLD EQ 4 AND G.DESTROLD EQ 4) AND

(G.CLSTRONG EQ 0 OR G.DESTRONG EQ 0))

THEN CLEAR G.MAINTAIN;

IF (G.ANYREVERSE EQ \$TRUE)

THEN CLEAR G.ANYCROSS;

CLEAR G.MAINTAIN;

IF (G.CORRECTIVE_CLM EQ \$FALSE AND

G.CORRECTIVE DES EQ \$FALSE)

THEN IF (G.RA(2) EQ \$TRUE AND G.RA(7) EQ \$TRUE)

THEN SET G.MAINTAIN;

ELSE CLEAR G.MAINTAIN;

IF (G.CLSTRONG EQ 4 AND

G.CLSTROLD EQ 8)

THEN SET G.CORRECTIVE_CLM,

G.ANYPRECOR;

ELSE IF (G.DESTRONG EQ 4 AND

G.DESTROLD EQ 8 AND

G.EXTALT EQ \$FALSE)

THEN SET CORRECTIVE_DES,

G.ANYPRECOR;

G.ZDMODEL = 0;

ELSE IF (G.RA(1 and 6) EQ \$FALSE)

THEN CLEAR G.MAINTAIN;

G.ZDMODEL = 0;

CLEAR G.ALLCLEAR;

ELSE CLEAR G.MAINTAIN, G.ANYINCREASE;

G.ZDMODEL = 0;

IF (ANYALTLOST EQ \$TRUE)

THEN CLEAR ANYTRACKDROP, G.ALLCLEAR;

ELSE IF (ANYTRACKDROP EQ \$TRUE)

THEN CLEAR G.ALLCLEAR;

PERFORM Load_display_and_aural_info;

END Set_up_display_outputs;

IF (any bit in G.RA(1–10)EQ \$TRUE)

THEN IF (G.ANYINCREASE EQ \$TRUE)

THEN CLEAR G.ANYREVERSE, G.MAINTAIN, G.ANYCROSS;

IF (G.PREVINCREASE EQ \$FALSE)

THEN SET G.ANYCORCHANG, G.PREVINCREASE;

ELSE CLEAR G.PREVINCREASE;

IF ((G.RA(1) EQ \$TRUE AND G.ZDMODEL GT P.CLMRT AND

G.ZDOWN GT P.CLMRT) OR (G.RA(6) EQ \$TRUE AND

G.ZDMODEL <u>LT</u> P.DESRT <u>AND</u> G.ZDOWN <u>LT</u> P.DESRT))

THEN SET G.MAINTAIN;

CLEAR G.ANYREVERSE;

ELSE IF ((G.CLSTROLD EQ 4 AND G.DESTROLD EQ 4) AND

(G.CLSTRONG EQ 0 OR G.DESTRONG EQ 0))

THEN CLEAR G.MAINTAIN;

IF (G.ANYREVERSE EQ \$TRUE)

THEN CLEAR G.ANYCROSS;

CLEAR G.MAINTAIN;

IF (G.CORRECTIVE_CLM EQ \$FALSE AND

G.CORRECTIVE DES EQ \$FALSE)

THEN IF (G.RA(2) EQ \$TRUE AND G.RA(7) EQ \$TRUE)

THEN SET G.MAINTAIN;

ELSE CLEAR G.MAINTAIN;

IF (G.CLSTRONG EQ 4 AND

G.CLSTROLD EQ 8 AND

G.DESTRONG <u>EQ</u> 0)

THEN SET G.CORRECTIVE_CLM,

G.ANYPRECOR;

ELSE IF (G.DESTRONG EQ 4 AND

G.DESTROLD EO 8 AND

G.CLSTRONG EQ 0 AND

G.EXTALT <u>EQ</u> \$FALSE)

THEN SET G. CORRECTIVE_DES,

G.ANYPRECOR:

G.ZDMODEL = 0;

ELSE IF (G.RA(1 and 6) EQ \$FALSE)

THEN CLEAR G.MAINTAIN;

G.ZDMODEL = 0;

CLEAR G.ALLCLEAR;

ELSE CLEAR G.MAINTAIN, G.ANYINCREASE;

G.ZDMODEL = 0;

IF (ANYALTLOST EQ \$TRUE)

THEN CLEAR ANYTRACKDROP, G.ALLCLEAR;

ELSE IF (ANYTRACKDROP EQ \$TRUE)

THEN CLEAR G.ALLCLEAR;

PERFORM Load_display_and_aural_info;

END Set up display outputs;

Following is the pseudocode change to the routine Send_owndata_to_trans that refers to the coding of the hybrid surveillance capability in the Data Link Capability Report.

PROCESS Send_owndata_to_trans;

<Set up fields for SLC Update messages and data link capability report to transponder:>
OWNDATA_TO_TRANS.SL = G.INDEX; <Indicate current sensitivity level>

CLEAR OWNDATA_TO_TRANS.BIT_69;

<This bit must be set to 1 if hybrid surveillance is fitted and operational>

IF (G.INDEX GE 2 AND G.INDEX LE 7 AND G.OPFLG EQ \$TRUE)

THEN SET OWNDATA_TO_TRANS.BIT_48;

ELSE CLEAR OWNDATA_TO_TRANS.BIT_48;

IF (G.OPFLG EQ \$TRUE)

THEN SET OWNDATA_TO_TRANS.BIT_70;

ELSE CLEAR OWNDATA TO TRANS.BIT 70;

IF (G.RAMODE EQ \$TRUE)

<u>THEN</u> OWNDATA_TO_TRANS.RI = 3; <Onboard TCAS with vertical-only RA capability>

SET OWNDATA_TO_TRANS.BIT_70;

ELSE IF (G.TAMODE EQ \$TRUE)

<u>THEN</u> OWNDATA_TO_TRANS.RI = 2; <Onboard TCAS with RA capability inhibited>

<u>CLEAR</u> OWNDATA_TO_TRANS.BIT_70; ELSE OWNDATA TO TRANS.RI = 0; <No onboard TCAS>

OWNDATA_TO_TRANS.VI = 1; <u>CLEAR</u> OWNDATA_TO_TRANS.BIT_71;

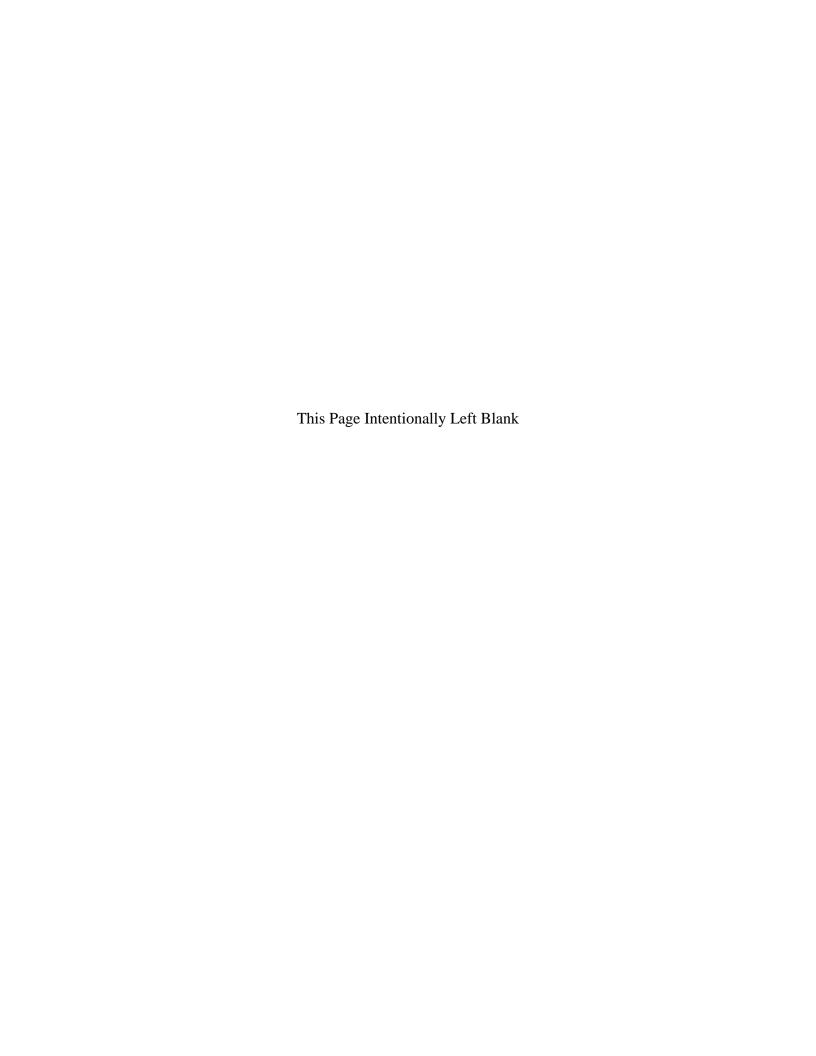
SET OWNDATA_TO_TRANS.BIT_72;

Send SLC Update message (i.e., SL, RI and VI) to transponder; IF (G.TRANSVI EQ 1)

<u>THEN</u> send data link capability report (i.e., BIT_48, BIT_69, BIT_70, BIT_71, and BIT_72) to transponder;

END Send_owndata_to_trans;

_____TRACKING LOW-LEVEL LOGIC______4-P35



3 Changes to State Charts

There are two transition tables that need to be updated to match the Multiaircraft changes in the pseudocode. These are the Yes to No transition tables for the Corrective_Climb and the Corrective_Descend states on pages 125 and 127, respectively, of DO-185B Volume II. The original DO-185B form of those two transition tables are shown next, followed by the revised versions of those two tables with the changes highlighted.

Note that in addition to the changes made to match the proposed pseudocode change, the subscript page references for the functions Climb_Goal and Descend_Goal are changed because the values printed in DO-185B are incorrect.

Transition(s): Yes \rightarrow No

Location: Advisory_Status_{s-261} \triangleright Corrective_Climb_{s-123}

Trigger Event: Composite_RA_Evaluated_Event_{e-C2}

Condition:

			O	R
AND	Climb_RA_Weakened _{m-374}	T	Т	
	Climb_Goal _{f-410} = 0 ft/min	F	Т	
	Own_Tracked_Alt_Rate _{f-564} > Climb_Goal _{f-410}	Т		
	Own_Tracked_Alt_Rate _{f-564} > -300 ft/min _(HYSTERCOR)		Т	•
	Own_Tracked_Alt_Rate _{f-564} ≤ 300 ft/min _(HYSTERCOR)		Т	•
	Descend_Goal _{f-411} = 0 ft/min		Т	
	Not_Meeting_Descend_Goal _{m-411}		•	Т

Output Action: Corrective_Climb_Evaluated_Event_{e-C2}

- Notes: 1. Description: Transition out of corrective climb occurs for a weakened climb RA condition when either the own aircraft altitude rate exceeds a non-zero climb goal or the aircraft is considered level (i.e., within hysteresis) for a zero climb and descend goal. This transition also occurs whenever the aircraft is not meeting the current descend goal.
 - 2. Pseudocode Reference: Corrective_preventive_test.

Transition(s): Yes \rightarrow No

Location: Advisory_Status_{s-261} > Corrective_Descend_{s-229}

Trigger Event: Corrective_Climb_Evaluated_Event_{e-C2}

Condition:

				OR					
AND	Descend_RA_Weakened _{m-378}	T	T			T	•		
	Descend_Goal _{f-411} = 0 ft/min	F	Т			T	,		
	Own_Tracked_Alt_Rate _{f-564} < Descend_Goal _{f-411}	T							
	Own_Tracked_Alt_Rate _{f-564} < 300 ft/min _(HYSTERCOR)	•	Т			Т	,		
	Own_Tracked_Alt_Rate _{f-564} ≥ -300 ft/min _(HYSTERCOR)		Т						
	Climb_Goal _{f-410} = 0 ft/min		Т						
	Not_Meeting_Climb_Goal _{m-410}				T				
	Extreme_Alt_Check _{m-378}					Т	,		
	Multiple_Threats _{m-403}					F			

Output Action: Corrective_Descend_Evaluated_Event_{e-C2}

- Notes: 1. Description: Transition out of corrective descend occurs for a weakened descend RA condition when (1) the own aircraft altitude rate is less than a non-zero descend goal, or (2) the aircraft is considered level (i.e., within hysteresis) for a zero climb and descend goal, or (3) the aircraft is not meeting the current climb goal, or (4) a descend RA is weakened to a zero climb rate goal under extreme low altitude against a single threat aircraft.
 - **2. Pseudocode Reference:** Corrective_preventive_test, Set_up_display_outputs, Extreme_altitude_check.

Transition(s): Yes \rightarrow No

Location: Advisory_Status_{s-261} \triangleright Corrective_Climb_{s-123}

Trigger Event: Composite_RA_Evaluated_Event_{e-C2}

Condition:

		OR					
	Climb_RA_Weakened _{m-374}	Т	T		T		
AND	Climb_Goal _{f-467} = 0 ft/min	F	T		Т		
	Own_Tracked_Alt_Rate _{f-564} > Climb_Goal _{f-467}	T			•		
	Own_Tracked_Alt_Rate _{f-564} > -300 ft/min _(HYSTERCOR)		T		Т		
	Own_Tracked_Alt_Rate _{f-564} ≤ 300 ft/min _(HYSTERCOR)		T		•		
	Descend_Goal _{f-473} = 0 ft/min		T		•		
	Not_Meeting_Descend_Goal _{m-411}		•	T	•		
	Descend_Goal _{f-473} < 100,000 ft/min _(HUGE)				Т		

Output Action: Corrective_Climb_Evaluated_Event_{e-C2}

Notes: 1. Description: Transition out of corrective climb occurs for a weakened climb RA condition when either the own aircraft altitude rate exceeds a non-zero climb goal or the aircraft is considered level (i.e., within hysteresis) for a zero climb and descend goal. This transition also occurs whenever the aircraft is not meeting the current descend goal or there is a simultaneous opposite-sense VSL due to a multiaircraft encounter.

2. Pseudocode Reference: Corrective_preventive_test, Set_up_display_outputs.

 Ω D

Transition(s): Yes \rightarrow No

Location: Advisory_Status_{s-261} \triangleright Corrective_Descend_{s-229}

Trigger Event: Corrective_Climb_Evaluated_Event_{e-C2}

Condition:

				(OR		_
	Descend_RA_Weakened _{m-378}	T	T			T	T
AND	Descend_Goal _{f-473} = 0 ft/min	F	T			T	T
	Own_Tracked_Alt_Rate _{f-564} < Descend_Goal _{f-473}	T	•				
	Own_Tracked_Alt_Rate _{f-564} < 300 ft/min _(HYSTERCOR)		T			T	T
	Own_Tracked_Alt_Rate _{f-564} ≥ -300 ft/min _(HYSTERCOR)		T			•	
	Climb_Goal _{f-467} = 0 ft/min		T		•		
	Not_Meeting_Climb_Goal _{m-410}		•		T	•	•
	Extreme_Alt_Check _{m-378}	•	•		•	T	•
	Multiple_Threats _{m-403}		•			F	
	$Climb_Goal_{f-467} > -100,000 \text{ ft/min}_{(HUGE)}$		•				T

Output Action: Corrective_Descend_Evaluated_Event_{e-C2}.

- Notes: 1. Description: Transition out of corrective descend occurs for a weakened descend RA condition when (1) the own aircraft altitude rate is less than a non-zero descend goal, or (2) the aircraft is considered level (i.e., within hysteresis) for a zero climb and descend goal, or (3) the aircraft is not meeting the current climb goal, or (4) a descend RA is weakened to a zero climb rate goal under extreme low altitude against a single threat aircraft, or (5) there is a simultaneous opposite-sense VSL due to a multiaircraft encounter.
 - 2. **Pseudocode Reference:** Corrective_preventive_test, Set_up_display_outputs, Extreme_altitude_check.

The following output interface change, section 1.3.10 of DO-185B Volume II, corrects the Hybrid Surveillance capability reporting within the Data Link Capability Report.

1.3.10 Interface: Data_Link_Capability_Report

Source: CAS

Destination: Mode_S_Transponder

Trigger Event: Effective_SL_Evaluated_Event_{e-C2}

Condition:

$$Mode_S_Version_{v-55} = Version_7$$
 T

Assignments: None

Output Action: SEND(Data_Link_Capability_Report(BIT48, BIT69, BIT70, BIT71, BIT72)

Abbreviations:

BIT48 =

```
 \begin{cases} 1 & \text{if } (Effective\_SL_{s-97} \text{ in one of } \{2,3,4,5,6,7\} \text{ and} \\ & TCAS\_Operational\_Status_{v-42} = Operational) \end{cases}
```

BIT69 = 0 ***** This bit must be set to 1 if hybrid surveillance is fitted and operational *****

BIT70 =

```
 \begin{cases} 1 & \text{ if } RA\_Inhibit_{m-419} = False \text{ or } (Effective\_SL_{s-97} \text{ in state 1 and} \\ & TCAS\_Operational\_Status_{v-42} = Operational) \end{cases}
```

BIT71 = 0

BIT72 = 1

Notes: 1. **Description:** The data link capability report is sent to the Mode S transponder for downlink to a ground station receiver.

2. **Pseudocode Reference:** Send_owndata_to_trans.



4 Changes to TSIM

This material is not part of DO-185B. It is accompanying material distributed by FAA, not by RTCA.

Certain files that are compiled into the TSIM simulation program or that provide input data to that program must be modified to reflect the changes to both the pseudocode and the statecharts. The necessary changes are indicated below. The headings are the names of the files that must be modified.

4.1 Trans7.dat

```
[Corrective_Climb, Yes -> No]
Base Number = 2.1.11.2
Trigger = Composite_RA_Evaluated_Event
Output = Corrective_Climb_Evaluated_Event
!Climb_RA_Weakened;
                                      T T
Climb_Goal = 0;
Descend_Goal = 0;
Own_Tracked_Alt_Rate > Climb_Goal;
Own_Tracked_Alt_Rate > 0 - HYSTERCOR;
Own_Tracked_Alt_Rate <= HYSTERCOR;</pre>
!Not Meeting Descend Goal;
Descend_Goal < HUGE;
*** The row above and new column is added by Hui Men (JHU/APL)
2008.12.12 IP-15
[Corrective Descend, Yes -> No]
Base_Number = 2.1.11.3
Trigger = Corrective_Climb_Evaluated_Event
Output = Corrective_Descend_Evaluated_Event
*** Begin: Hui Men (JHU/APL) 2007.08.27 CP116
!Descend RA Weakened;
Descend Goal = 0;
                                      . T
Climb Goal = 0;
Own Tracked Alt Rate < Descend Goal;
Own_Tracked_Alt_Rate < HYSTERCOR;
Own_Tracked_Alt_Rate >= 0 - HYSTERCOR;
!Not_Meeting_Climb_Goal;
!Extreme_Alt_Check;
Multiple_Threats;
*** End: Hui Men (JHU/APL) 2007.08.27 CP116
Climb_Goal > 0 - HUGE; . . . . . T
*** The above row and new column is added by Hui Men (JHU/APL)2008.12.12
for IP-15
```

4.2 S7.c

Line 946