R05631027\_楊皓文 \_影像處理 \_作業 #6

編譯環境:Windows 10 \ Matlab 2016

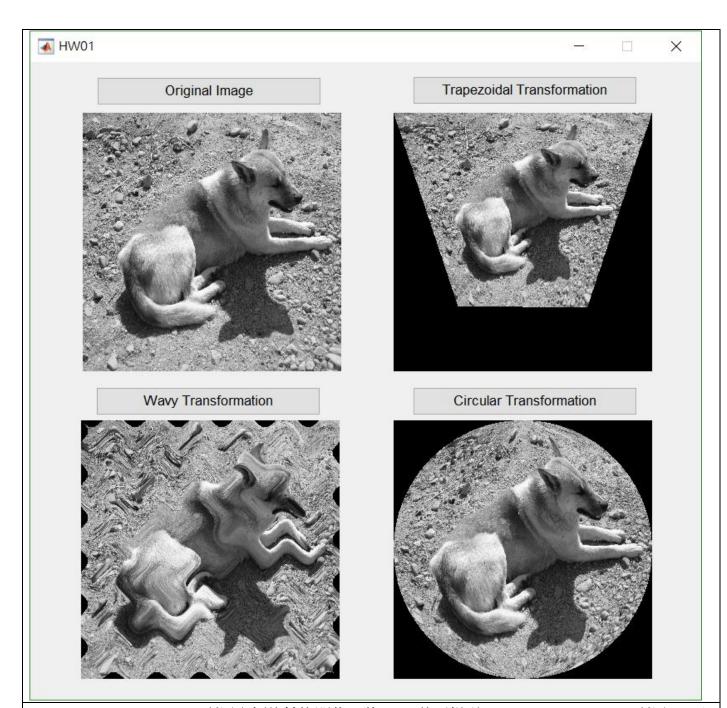
## Part 1: (50%) Geometric Transformation

程式碼:

```
function varargout = HW01(varargin)
gui_Singleton = 1;
gui_State = struct('gui_Name',
                                     mfilename, ...
                       'gui_Singleton', gui_Singleton, ...
                       'gui_OpeningFcn', @HW01_OpeningFcn, ...
                       'gui OutputFcn', @HW01_OutputFcn, ...
                       'gui_LayoutFcn', [],...
                      'gui_Callback', []);
if nargin && ischar(varargin{1})
    gui_State.gui_Callback = str2func(varargin{1});
end
if nargout
    [varargout{1:nargout}] = gui_mainfcn(gui_State, varargin{:});
else
    gui_mainfcn(gui_State, varargin{:});
end
function HW01 OpeningFcn(hObject, eventdata, handles, varargin)
handles.output = hObject;
guidata(hObject, handles);
function varargout = HW01 OutputFcn(hObject, eventdata, handles)
varargout{1} = handles.output;
function pushbutton1 Callback(hObject, eventdata, handles)
% 讀取圖片
filename = uigetfile({'*.jpg;*.tif;*.png;*.gif;*.bmp','All Image Files'});
handles.l = imread(filename);
%轉成灰階
```

```
[handles.row, handles.col, handles.lay] = size(handles.l);
if handles.lay == 1
     handles.I = handles.I;
     fprintf('1 layers image\n');
elseif handles.lay == 3
     R = uint8(handles.I(:, :, 1));
     G = uint8(handles.I(:, :, 2));
     B = uint8(handles.I(:, :, 3));
     handles.I = 0.299*R + 0.587*G + 0.114*B;
     fprintf('3 layers image\n');
end
axes(handles.axes1); imshow(handles.I);
handles.output = hObject;
guidata(hObject, handles);
function pushbutton2_Callback(hObject, eventdata, handles)
% Trapezoidal Transformation
img = handles.I;
[row, col] = size(handles.I);
img_new = zeros(row, col);
for i = 1:row
     for j = 1:col
          new_x = round(3*i/4 + j*i/(col*row));
          new_y = round(j+i/4 - j*i/(2*col));
          img_new(new_x, new_y) = img(i, j);
     end
end
axes(handles.axes2); imshow(uint8(img_new));
function pushbutton3_Callback(hObject, eventdata, handles)
% Wavy Transformation
img = handles.I;
[row, col] = size(handles.I);
```

```
img_new = zeros(row, col);
for i = 1:row
    for j = 1:col
         new_x = round(j-32*sin(i/32));
         new_y = round(i-32*sin(j/32));
         if new_x >= 1 && new_x <= row && new_y >= 1 && new_y <= col
              img_new(j, i) = img(new_x, new_y);
         end
     end
end
axes(handles.axes3); imshow(uint8(img_new));
function pushbutton4_Callback(hObject, eventdata, handles)
% Circular Transformation
img = handles.I;
[row, col] = size(handles.I);
img_new = zeros(row, col);
for i = 1:row
    for j = 1:col
         d = sqrt((row/2)^2-(row/2-i)^2);
         new_x = round((j-col/2) * col/(d*2) + col/2);
         new_y = i;
         if new_x >= 1 && new_x <= col && new_y >= 1 && new_y <= col
              img_new(i, j) = img(new_y, new_x);
         end
     end
end
axes(handles.axes4); imshow(uint8(img_new));
結果呈現與討論:
```



Trapezoidal Transformation 利用座標的轉換關係,將 pixel 移至梯形。Wavy Transformation 利用 sin 函數,將縱橫的 pixel 重新排成 sin 波的形狀。最後 Circular Transformation 計算每一列的三角函數,將每一列的 pixel 壓縮成圓形的數量排列。

## Part 2: (50%) Hough Transform

function varargout = HW02(varargin)

```
if nargin && ischar(varargin{1})
     gui State.gui Callback = str2func(varargin{1});
end
if nargout
     [varargout{1:nargout}] = gui_mainfcn(gui_State, varargin{:});
else
     gui mainfcn(gui State, varargin{:});
end
function HW02 OpeningFcn(hObject, eventdata, handles, varargin)
handles.output = hObject;
guidata(hObject, handles);
function varargout = HW02_OutputFcn(hObject, eventdata, handles)
varargout{1} = handles.output;
function pushbutton1_Callback(hObject, eventdata, handles)
[row, col] = size(handles.I);
% 算出面積周長
imgfltrd = handles.imgfltrd;
[accum, axis_rho, axis_theta, lineprm, lineseg] = Hough_Grd(imgfltrd);
[line] = DrawLines_Polar(size(imgfltrd), lineprm);
for i = 1:1:size(lineprm, 1)-4
     a = [3 4 7 8];
     p2(i, 1:2) = polyfit(line(:,2*a(i)-1),line(:,2*a(i)),1);
end
pad2 = zeros(row, col);
for i = 1:row
     for j = 1:col
          if j-polyval(p2(1, 1:2),i) > 0 && j-polyval(p2(2, 1:2),i) < 0 &&...
                    j-polyval(p2(3, 1:2),i) < 0 && j-polyval(p2(4, 1:2),i) > 0
               pad2(i, j) = 1;
          end
```

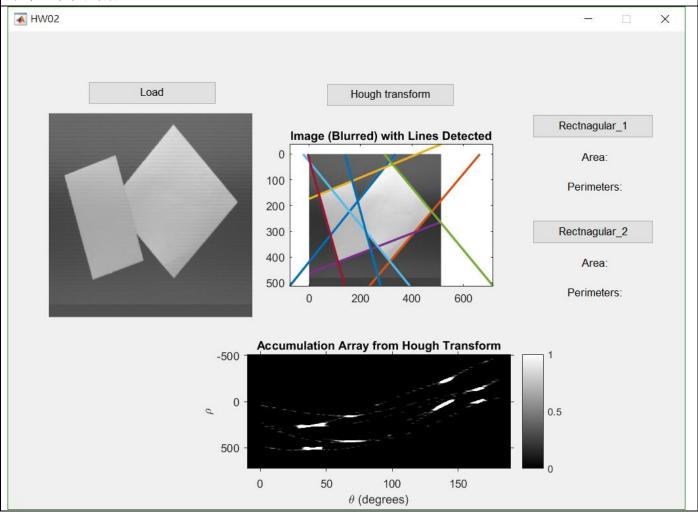
```
end
end
pad2 = imrotate(pad2, 90);
data = regionprops(pad2, 'all');
Area = data.Area*(0.5^2);
Perimeter = data.Perimeter*0.5;
set(handles.text2, 'String', ['Area: ', num2str(Area), 'mm^2']);
set(handles.text3, 'String', ['Perimeter: ', num2str(Perimeter), 'mm']);
%顯示圖片
imgfltrd = imrotate(handles.imgfltrd, 180);
[accum, axis rho, axis theta, lineprm, lineseg] = Hough Grd(imgfltrd);
[line] = DrawLines Polar(size(imgfltrd), lineprm);
cla(handles.axes2,'reset');
axes(handles.axes2);
set(gca,'xdir','reverse');
hold on;
imagesc(imgfltrd); colormap('gray'); axis image;
for i = 1:1:size(lineprm, 1)-4
     a = [3 4 7 8];
     plot(line(:,2*a(i)-1), line(:,2*a(i)), 'LineWidth', 2);
end
hold off;
handles.output = hObject;
guidata(hObject, handles);
function pushbutton2 Callback(hObject, eventdata, handles)
[row, col] = size(handles.I);
% 算出面積周長
imgfltrd = handles.imgfltrd;
[accum, axis_rho, axis_theta, lineprm, lineseg] = Hough_Grd(imgfltrd);
[line] = DrawLines_Polar(size(imgfltrd), lineprm);
for i = 1:1:size(lineprm, 1)-4
     a = [1 2 5 6];
     p(i, 1:2) = polyfit(line(:,2*a(i)-1),line(:,2*a(i)),1);
end
```

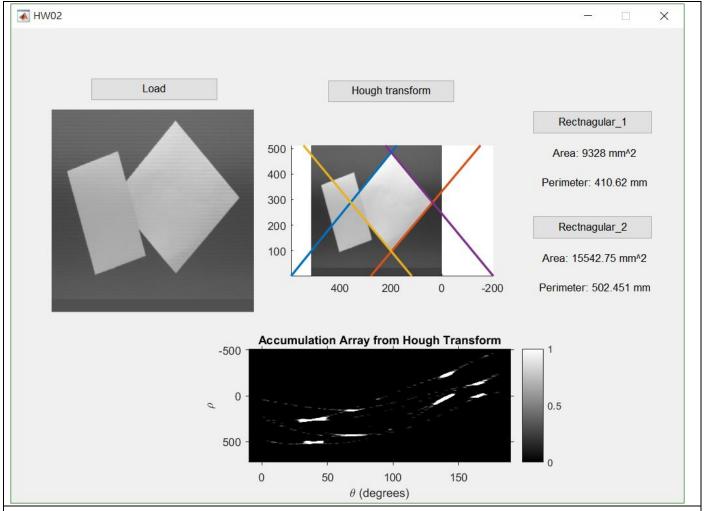
```
pad = zeros(row, col);
for i = 1:row
     for j = 1:col
          if j-polyval(p(1, 1:2),i) > 0 && j-polyval(p(2, 1:2),i) < 0 &&...
                    j-polyval(p(3, 1:2),i) > 0 && j-polyval(p(4, 1:2),i) < 0
               pad(i, j) = 1;
          end
     end
end
pad = imrotate(pad, 90);
data = regionprops(pad, 'all');
Area = data.Area*(0.5^2);
Perimeter = data.Perimeter*0.5;
set(handles.text4, 'String', ['Area: ', num2str(Area), 'mm^2']);
set(handles.text5, 'String', ['Perimeter: ', num2str(Perimeter), 'mm']);
% 顯示圖片
imgfltrd = imrotate(handles.imgfltrd, 180);
[accum, axis_rho, axis_theta, lineprm, lineseg] = Hough_Grd(imgfltrd);
[line] = DrawLines_Polar(size(imgfltrd), lineprm);
cla(handles.axes2,'reset');
axes(handles.axes2);
set(gca,'xdir','reverse');
hold on;
imagesc(imgfltrd); colormap('gray'); axis image;
for i = 1:1:size(lineprm, 1)-4
     a = [1 2 5 6];
     plot(line(:,2*a(i)-1), line(:,2*a(i)), 'LineWidth', 2);
     p(i, 1:2) = polyfit(line(:,2*a(i)-1),line(:,2*a(i)),1);
end
hold off;
handles.output = hObject;
guidata(hObject, handles);
function pushbutton3_Callback(hObject, eventdata, handles)
```

```
% 讀取圖片
filename = uigetfile({'*.jpg;*.tif;*.png;*.gif;*.bmp','All Image Files'});
handles.I = imread(filename);
% 轉成灰階
[handles.row, handles.col, handles.lay] = size(handles.l);
if handles.lay == 1
     handles.I = handles.I;
     fprintf('1 layers image\n');
elseif handles.lay == 3
     R = uint8(handles.l(:, :, 1));
     G = uint8(handles.I(:, :, 2));
     B = uint8(handles.I(:, :, 3));
     handles.I = 0.299*R + 0.587*G + 0.114*B;
     fprintf('3 layers image\n');
end
axes(handles.axes1); imshow(handles.I);
handles.output = hObject;
guidata(hObject, handles);
function pushbutton5_Callback(hObject, eventdata, handles)
filter = [1 1 1 1 1; 1 2 2 2 1; 1 2 4 2 1; 1 2 2 2 1; 1 1 1 1 1];
filter = filter / sum(filter(:));
imgfltrd = filter2( filter , handles.I );
[accum, axis_rho, axis_theta, lineprm, lineseg] = Hough_Grd(imgfltrd);
% 呈現霍夫轉換累積矩陣
axes(handles.axes3);
imshow(imadjust(mat2gray(accum*255)), [], 'XData',axis_theta*(180/pi), 'YData',axis_rho, ...
'InitialMagnification','fit');
xlabel('\theta (degrees)'), ylabel('\rho');
axis on, axis normal, hold on;
title('Accumulation Array from Hough Transform');
colormap(hot), colorbar;
% 劃出直線
```

hold on;
axes(handles.axes2);
imagesc(imgfltrd); colormap('gray'); axis image;
[line] = DrawLines\_Polar(size(imgfltrd), lineprm);
title('Image (Blurred) with Lines Detected');
hold off;
handles.imgfltrd = imgfltrd;
handles.output = hObject;
guidata(hObject, handles);

## 結果呈現與討論:





利用 Hough transform 可以求出 pho 和 theta,將 pho 和 theta 畫出可以看出有較亮的點,即可以找到 8 個最大值的部分,找到 8 條直線。主要影響的因子就是取幾個最大值的部分來畫成線,過多或過少都無法正確畫出矩形的邊界。