

# Kaiwen Zhou

 Kaiwen Zhou |  kevinz-01.github.io |  kzhou35@ucsc.edu

## EDUCATION

---

**University of California, Santa Cruz**  
Ph.D. in Computer Science and Engineering  
Research focus: Responsible AI, AI agents.

Sep. 2021 – Present  
Advisor: Prof. Xin Eric Wang.

**Zhejiang University**  
B.S. in Statistics

Sep. 2017 – June 2021

## SELECTED PUBLICATIONS

---

- **Diverse and Efficient Red-Teaming for LLM Agents via Distilled Structured Reasoning.**  
**Kaiwen Zhou**, Ahmed Elgohary, A S M Iftekhar, Amin Saied.  
*In submission.*
- **Presenting a Paper is an Art: Self-Improvement Aesthetic Agents for Academic Presentations.**  
Chengzhi Liu\*, Yuzhe Yang\*, **Kaiwen Zhou**, Zhen Zhang, Yue Fan, Yannan Xie, Peng Qi, Xin Eric Wang.  
*In submission.*
- **SafeKey: Amplifying Aha-Moment Insights for Safety Reasoning.**  
**Kaiwen Zhou**, Xuandong Zhao, Gaowen Liu, Jayanth Srinivasa, Aosong Feng, Dawn Song, Xin Eric Wang.  
*EMNLP 2025.*
- **The Hidden Risks of Large Reasoning Models: A Safety Assessment of R1.**  
**Kaiwen Zhou**, Chengzhi Liu, Xuandong Zhao, Shreedhar Jangam, Jayanth Srinivasa, Gaowen Liu, Dawn Song, Xin Eric Wang.  
*In submission.*
- **Multimodal Situational Safety.**  
**Kaiwen Zhou**\*, Chengzhi Liu\*, Xuandong Zhao, Anderson Compalas, Dawn Song, Xin Eric Wang.  
*ICLR 2025, NeurIPS Workshop on RBFM 2024 (Oral).*
- **Muffin or Chihuahua? Challenging Large Vision-Language Models with Multipanel VQA.**  
Yue Fan, Jing Gu, **Kaiwen Zhou**, Qianqi Yan, Shan Jiang, Ching-Chen Kuo, Xinze Guan, Xin Eric Wang.  
*ACL 2024.*
- **ViCor: Bridging Visual Understanding and Commonsense Reasoning with Large Language Models.**  
**Kaiwen Zhou**, Kwonjoon Lee, Teruhisa Misu, Xin Eric Wang.  
*Findings of ACL 2024.*
- **Navigation as the Attacker Wishes? Towards Building Byzantine-Robust Embodied Agents under Federated Learning.**  
Yunchao Zhang, Zonglin Di, **Kaiwen Zhou**, Cihang Xie, Xin Eric Wang.  
*NAACL 2024.*
- **ESC: Exploration with Soft Commonsense Constraints for Zero-shot Object Navigation.**  
**Kaiwen Zhou**, Kaizhi Zheng, Connor Pryor, Yilin Shen, Hongxia Jin, Lise Getoor, Xin Eric Wang.  
*ICML 2023.*
- **JARVIS: A Neuro-Symbolic Commonsense Reasoning Framework for Conversational Embodied Agents.**  
Kaizhi Zheng\*, **Kaiwen Zhou**\*, Jing Gu\*, Yue Fan\*, Jialu Wang\*, Zonglin Di, Xuehai He, Xin Eric Wang.  
*NeSy 2025 (Oral), SoCal NLP 2022*
- **FedVLN: Privacy-preserving Federated Vision-and-Language Navigation.**  
**Kaiwen Zhou**, Xin Eric Wang.

## SELECTED RESEARCH PROJECTS

---

<b>Diverse and Efficient Red-Teaming for LLM Agents</b>	Jun. 2025 – Sep. 2025
Develop a red-teaming framework that generates diverse seed tests and iteratively crafts adversarial attacks using a red-teamer trained via structured reasoning with supervised fine-tuning and reinforcement learning. <b>Deployed in Microsoft RAI product for agent safety.</b>	
<b>Improving the Safety Alignment of Large Reasoning Models</b>	March 2025 – May. 2025
Identify the safety aha-moment of large reasoning models (LRMs), and amplify it for safer LRM with the proposed SafeKey training method.	
<b>Safety Analysis on Large Reasoning Models</b>	Jan. 2025 – Feb. 2025
Identify safety gaps and safety behaviors in open-source reasoning models, including increased harmfulness level in unsafe responses, harmful reasoning outputs, and failure safety thinking when facing adversarial attacks, etc.	
<b>Multimodal Situational Safety</b>	Apr. 2024 – Sep. 2024
Propose a novel safety problem where the situation in visual input affects the safety of the user's intent; benchmark SOTA MLLMs and propose multi-agent pipelines to improve situational safety performance.	
<b>Visual Commonsense Reasoning with LLMs and VLMs</b>	Mar. 2023 – Sep. 2023
Define VCR as visual commonsense inference or understanding, and propose a workflow maximizing the capability of LLMs and VLMs to solve them.	
<b>LLM Commonsense Reasoning for Zero-shot Object Navigation</b>	Jun. 2022 – Jan. 2023
Combine commonsense reasoning of pre-trained LLMs and classical navigation via Probabilistic Soft Logic (PSL) to achieve SOTA zero-shot object navigation performance.	
<b>Amazon Alexa Prize SimBot Challenge</b>	Jan. 2022 – Apr. 2023
Build dialog-based embodied instruction following agent; won first place in the public challenge (phase I) and third place in real-user interaction stage (phase II).	
<b>Privacy-preserving Federated Learning for Navigation Agents</b>	Sep. 2021 – March 2022
Build a two-stage federated learning framework for vision-and-language navigation agents to preserve users' data privacy while maintaining navigation performance.	

## WORK EXPERIENCE

---

<b>Research Intern, Microsoft Responsible AI</b>	Mentor: Ahmed Elgohary	Jun. 2025 – Sep. 2025
<b>Research Intern, Samsung Research America</b>	Mentor: Yilin Shen	Jun. 2024 – Sep. 2024
<b>Research Intern, Honda Research Institute</b>	Mentor: Kwonjoon Lee	Apr. 2023 – Dec. 2023
<b>Research Intern, Samsung Research America</b>	Mentor: Yilin Shen	Jun. 2022 – Sep. 2022

## AI TECHNICAL EXPERIENCE

---

LLM post-training, alignment, reinforcement learning, supervised fine-tuning, reasoning models, multimodal LLMs.

## MISCELLANEOUS

---

- Dissertation-Year Fellowship, UCSC (2025-2026)
- First place of Alexa Prize SimBot Public Benchmark Challenge.
- Third place of Alexa Prize SimBot Challenge.