```
In [*]: import snntorch as snn
    import torch.nn as nn
    from torchvision import datasets, transforms
    from snntorch import utils, spikegen
    from torch.utils.data import DataLoader, TensorDataset, Dataset
    from snntorch import surrogate
    from snntorch import functional as SF
    from snntorch import spikeplot as splt
    import matplotlib.pyplot as plt
    import torch
    import numpy as np
    from skorch import NeuralNetClassifier
    from sklearn.model_selection import GridSearchCV
```

Data transform and download

```
In [94]:
          class AddGaussianNoise(object):
              def init (self, mean=0., std=1.):
                  self.std = std
                  self.mean = mean
              def call (self, tensor):
                 return tensor + torch.randn(tensor.size()) * self.std + self.mean
              def repr (self):
                 return self. class . name + '(mean={0}, std={1})'.format(self.mean, self.
          class AddSaltPepperNoise(object):
              def init (self, salt prob=0.01, pepper prob=0.01):
                  self.salt prob = salt prob
                  self.pepper prob = pepper prob
              def call (self, tensor):
                 random tensor = torch.rand(tensor.shape)
                  salt mask = random tensor < self.salt prob</pre>
                  pepper mask = (random tensor > (1-self.pepper prob))
                  salt pepper noise = torch.zeros like(tensor)
                  salt_pepper_noise = salt_pepper_noise - pepper_mask.float() + salt_mask.float(
                  return tensor + salt pepper noise
              def repr (self):
                 transform1 = transforms. Compose(
              transforms. Resize ((28, 28)),
              transforms. Grayscale(),
              transforms. ToTensor(),
              transforms. Normalize ((0,),(1,)),
              transforms. RandomRotation ([-10, 10])
          ])
          transform2 = transforms.Compose([
              transforms. Resize ((28, 28)),
              transforms. Grayscale(),
              transforms. ToTensor(),
              transforms. Normalize ((0,),(1,)),
              transforms. RandomRotation ([-10, 10]),
              AddGaussianNoise (0, 0.3)
          ])
          transform3 = transforms.Compose([
              transforms. Resize ((28, 28)),
              transforms. Grayscale(),
              transforms. ToTensor(),
              transforms. Normalize ((0,),(1,)),
              transforms. RandomRotation([-10, 10]),
              AddSaltPepperNoise (0.1, 0.1)
          ])
          batch size = 128
          train path = '/final data/mnist/train'
          test_path = '/final_data/mnist/test'
          num classes = 10
          mnist train = datasets.MNIST(train path, train=True, download=True, transform=transf
```

```
mnist_test_ = datasets.MNIST(test_path, train=False, download=True, transform=transfo
```

#### Take a subset of data to save time

```
[19]:
          subset = 5
In
          mnist train = utils.data subset(mnist train, subset)
          mnist test = utils.data subset(mnist test , subset)
          print(mnist train)
          train loader = DataLoader(mnist train, batch size = batch size, shuffle=True)
           test loader = DataLoader(mnist test, batch size = batch size, shuffle=True)
          print(len(train loader))
          print(len(test loader))
          Dataset MNIST
               Number of datapoints: 12000
               Root location: /final data/mnist/train
               Split: Train
               Standard Transform\\
          Transform: Compose(
                          Resize (size=(28, 28), interpolation=bilinear, max size=None, antialia
          s=None)
                          Grayscale (num output channels=1)
                          ToTensor()
                          Normalize (mean=(0,), std=(1,))
                          RandomRotation(degrees=[-10.0, 10.0], interpolation=nearest, expand=F
          alse, fill=0)
                          AddGaussianNoise (mean=0, std=0.3)
                      )
          94
           16
```

## train a non-spiking cnn

```
In [27]: device = torch.device("cuda") if torch.cuda.is_available() else torch.device("cpu")
# reset the weight when needed.
def weight_reset(m):
    if isinstance(m, nn.Conv2d) or isinstance(m, nn.Linear):
        m.reset_parameters()
```

```
[70]:
       num classes=10
       learning rate = 0.02
       weight decay = 0.05
       num epochs = 7
       class ConvNeuralNet(nn.Module):
           def init (self, num classes):
                super(ConvNeuralNet, self).__init__()
                self. conv1 = nn. Conv2d(1, 12, 5)
                self.max pool1 = nn.MaxPool2d(2)
                self. conv2 = nn. Conv2d(12, 32, 5)
                self. max pool2 = nn. MaxPool2d(2)
                self.ft = nn.Flatten()
                self.relu1 = nn.ReLU()
                self. fc = nn. Linear (32*4*4, \text{ num classes})
           def forward(self, x):
               out = self.conv1(x)
               out = self.max_pool1(out)
               out = self. conv2(out)
               out = self.max pool2(out)
                out = self.ft(out)
                out = self.relul(out)
               out = self.fc(out)
               return out
       model = ConvNeuralNet(num classes)
       weight reset (model)
       model = model. to(device)
       criterion = nn. CrossEntropyLoss()
       # optimizer = torch.optim.Adam(model.parameters(), 1r=2e-2, betas=(0.9, 0.999))
       optimizer = torch.optim. SGD (model. parameters (), lr=learning rate, weight decay=weight
       for epoch in range (num epochs):
           for i, (images, labels) in enumerate(iter(train loader)):
                images = images.to(device)
                labels = labels. to (device)
                  print(images. size())
               outputs = model(images)
                loss = criterion(outputs, labels)
                optimizer.zero grad()
                loss.backward()
               optimizer. step()
           print ('Epoch [{}/{}], Loss: {:.4f}'.format(epoch+1, num epochs, loss.item()))
       Epoch [1/7], Loss: 0.4169
       Epoch [2/7], Loss: 0.2706
       Epoch [3/7], Loss: 0.3613
       Epoch [4/7], Loss: 0.2577
       Epoch [5/7], Loss: 0.3217
       Epoch [6/7], Loss: 0.3600
       Epoch [7/7], Loss: 0.2386
```

```
In [71]: # testing with CNN
with torch.no_grad():
    correct = 0
    total = 0
    for i, (data, label) in enumerate(iter(test_loader)):
        data = data.to(device)
        label = label.to(device)
        output = model(data)
        _, predicted = torch.max(output.data, 1)
        total += label.size(0)
        correct += (predicted==label).sum().item()
    print('Accuracy of the network on the {} train images: {}%'.format(12000, 100*correct)
```

Accuracy of the network on the 12000 train images: 89.95%

## Rate coding

```
# num_steps =100
In [20]:
          # train event = []
          # train target = []
          \# test event = []
          # test target = []
          # for i, (data, target) in enumerate(iter(train_loader)):
                   print(data. size())
                 train spike data = spikegen.rate(data, num steps=num steps)
          #
          #
                 target = target.unsqueeze(0).expand(num steps, -1)
          #
                 if i == 0:
          #
                     train event = train spike data
          #
                     train target = target
                else:
          #
          #
                     try:
          #
                         train event = torch.cat((train event, train spike data), dim=0)
                         train target = torch.cat((train target, target), dim=0)
          #
          #
                     except:
                         continue
          # # train event = spikegen.rate(train event, num steps=num steps)
            print(train event.size())
                   train event. append (train spike data)
          # #
                   train target.append(target)
          # # for i, (data, target) in enumerate(iter(test loader)):
                   test_spike_data = spikegen.rate(data, num_steps=num_steps)
          ##
                   target = target.unsqueeze(0).expand(num steps, -1)
          ##
                   test event.append(test spike data)
          ##
                   test target.append(target)
          # for i, (data, target) in enumerate(iter(test loader)):
                 test spike data = spikegen.rate(data, num steps=num steps)
          #
                 target = target.unsqueeze(0).expand(num steps, -1)
          #
                 if i == 0:
          #
                     test event = test spike data
          #
                     test target = target
                else:
          #
                     try:
                         test event = torch.cat((test_event, test_spike_data), dim=0)
          #
                         test target = torch.cat((test target, target), dim=0)
          #
                     except:
                         continue
          class CustomTensorDataset(Dataset):
               def __init__(self, data_list, target_list):
                   self.data list = data list
                   self.target list = target list
              def getitem (self, index):
                   return self.data list[index], self.target list[index]
              def <u>len</u> (self):
                   return len(self.data list)
          # Use your lists of tensors to create a Dataset
          # def add noise(inputs, noise factor=0.3):
                  noisy = inputs+torch.randn like(inputs) * noise factor
          #
                  noisy = torch.clip(noisy, 0., 1.)
                  return noisy
```

```
num steps =150
train event = []
train target = []
test event = []
test target = []
for i, (data, target) in enumerate(iter(train loader)):
      data = add noise(data, 0.3)
    train spike data = spikegen.rate(data, num steps=num steps)
    target = target.unsqueeze(0).expand(num steps, -1)
    train event. append (train spike data)
    train target.append(target)
for i, (data, target) in enumerate(iter(test loader)):
      data = add noise(data, 0.3)
    test_spike_data = spikegen.rate(data, num_steps=num_steps)
    target = target.unsqueeze(0).expand(num steps, -1)
    test event.append(test spike data)
    test target.append(target)
# train data = iter(train loader)
# clean out the non-consistent data
train event.pop()
train target.pop()
# print(len(test event))
test event.pop()
# print(len(test event))
test_target.pop()
# print(test event)
train event = torch.stack(train event)
test_event = torch.stack(test_event)
train target = torch.stack(train target)
test target = torch.stack(test target)
# # train_event, train_target = next(train_data)
# test data = iter(test loader)
# test event, test_target = next(test_data)
# print('1')
train data = CustomTensorDataset(train event, train target)
test data = CustomTensorDataset(test event, test target)
# train_data = TensorDataset(train_event, train_target)
# test data = TensorDataset(test event, test target)
# manually set the dataset and adjust the batchsize
final train loader = DataLoader(train data, batch size = 1, shuffle=True)
final test loader = DataLoader(test data, batch size = 1, shuffle=True)
print(len(final train loader))
```

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### dataset for CNN

```
In [ ]:
In [23]: event, target = next(iter(final_train_loader))
    print(event.size())

    torch.Size([1, 150, 128, 1, 28, 28])
```

```
[24]: | # train data = iter(train loader)
       # clean out the non-consistent data
       # train event.pop()
       # train target.pop()
       # print(len(test event))
       # test_event.pop()
       # # print(len(test event))
       # test target.pop()
       # print(test event)
       # train_event = torch.stack(train_event)
       # test event = torch.stack(test event)
       # train_target = torch.stack(train_target)
       # test_target = torch.stack(test_target)
       # # train event, train target = next(train data)
       # test data = iter(test loader)
       # test_event, test_target = next(test_data)
       # print(train event.size())
       # train_event = train_event.squeeze(0)
       # test_event = test_event.squeeze(0)
       # train data = TensorDataset(train event, train target)
       # test data = TensorDataset(test event, test target)
       # final_train_loader = DataLoader(train_data, batch_size = batch_size, shuffle=True)
       # final test loader = DataLoader(test data, batch size = batch size, shuffle=True)
       # print(train spike data.shape)
```

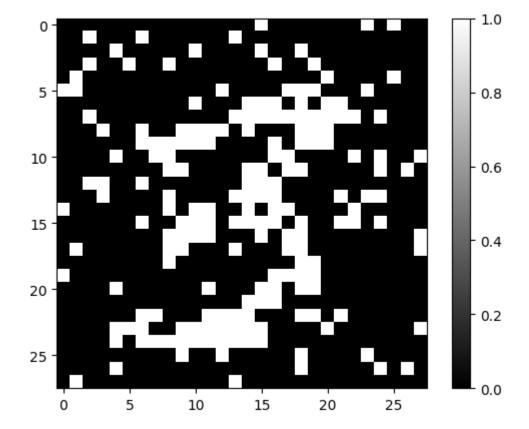
# In [25]: print(len(final\_train\_loader))

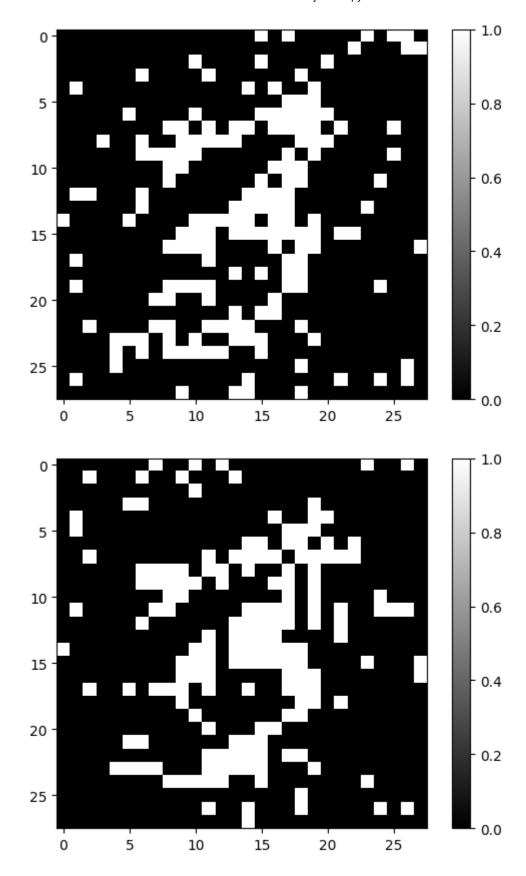
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```
In [26]: for i in range(3):
    spike_image1 = train_spike_data[i][3][0]

# spike_image2 = train_spike_data[2][4][0]
# spike_image3 = train_spike_data[3][4][0]
    plt.imshow(spike_image1, cmap='gray')
# plt.imshow(spike_image2, cmap='gray')
# plt.imshow(spike_image3, cmap='gray')

plt.colorbar()
    plt.show()
```





build network

```
[85]:
          spike grad = surrogate.atan()
          beta = 0.1
          #Initialize Network
          net = nn. Sequential (nn. Conv2d (1, 12, 5),
                               snn.Leaky(beta=beta, spike grad=spike grad, init hidden=True, lear
                               nn. MaxPoo12d(2),
                               nn. Conv2d(12, 32, 5),
                               snn.Leaky(beta=beta, spike grad=spike grad, init hidden=True, lear
                               nn. MaxPoo12d(2),
                               nn.Flatten(),
                               nn. Linear (32*4*4, 10),
                               snn.Leaky(beta=beta, spike grad=spike grad, init hidden=True, out
                               ). to (device)
          \# net = nn. Sequential (nn. Conv2d(1, 12, 5),
                                 snn. Leaky (beta=beta, spike grad=spike grad, init hidden=True),
          #
                                 nn. MaxPoo12d(2),
          #
                                 nn. Conv2d (12, 32, 5),
          #
                                 snn. Leaky (beta=beta, spike grad=spike grad, init hidden=True),
          #
                                 nn. MaxPoo12d(2),
          #
                                 nn.Conv2d(32, 64, 3), # new convolutional layer
          #
                                 snn. Leaky (beta=beta, spike grad=spike grad, init hidden=True),
                                 nn. MaxPool2d(2), # new pooling layer
          #
                                 nn. Flatten(),
                                 nn.Linear(64*1*1, 100), # adjusted for new layer sizes
          #
                                 snn. Leaky (beta=beta, spike grad=spike grad, init hidden=True),
          #
                                 nn. Linear (100, 10), # new linear layer
          #
                                 snn. Leaky (beta=beta, spike grad=spike grad, init hidden=True, out
                                 ). to (device)
          def weight reset (m):
              if isinstance (m, nn. Conv2d) or isinstance (m, nn. Linear):
                  m. reset parameters()
          net.apply(weight reset)
Out[85]: Sequential(
            (0): Conv2d(1, 12, kernel size=(5, 5), stride=(1, 1))
            (2): MaxPool2d(kernel size=2, stride=2, padding=0, dilation=1, ceil mode=False)
            (3): Conv2d(12, 32, kernel size=(5, 5), stride=(1, 1))
            (4): Leaky()
            (5): MaxPool2d(kernel size=2, stride=2, padding=0, dilation=1, ceil mode=False)
            (6): Flatten(start dim=1, end dim=-1)
            (7): Linear(in features=512, out features=10, bias=True)
            (8): Leaky()
```

```
[86]: def forward pass(net, data):
            spk rec = []
            utils.reset(net) # resets hidden states for all LIF neurons in net
            for step in range(data.size(0)): # data.size(0) = number of time steps
                 spk out, mem out = net(data[step])
                 spk rec. append (spk out)
            return torch. stack (spk rec)
In [87]:
          # optimizer = torch.optim.SGD(net.parameters(), 1r=learning rate snn, weight decay=weig
          loss fn = SF. mse count loss (correct rate=0.8, incorrect rate=0.2)
   [88]:
          def val accuracy (net, data, label):
              net.eval()
              accur_list = []
              with torch.no grad():
                   for data, labels in zip(data, label):
                       data = data
                       labels = labels
                       data = data. to (device)
                       labels = labels. to (device)
                       output = forward pass(net, data)
                       accur = SF.accuracy rate(output, labels[0])
                       accur list.append(accur)
              return sum(accur list)/len(accur list)
          def test accuracy (net, dataloader):
              net.eval()
              accur list = []
              with torch. no grad():
                   for data, labels in iter(dataloader):
                       data = data[0]
                       labels = labels[0]
                       data = data. to (device)
                       labels = labels. to (device)
                       output = forward_pass(net, data)
                       accur = SF.accuracy rate(output, labels[0])
                       accur list.append(accur)
              return sum(accur list)/len(accur list)
```

### grid search hyperparameter tuning

```
In [ ]:
```

```
learning rate = [0.01, 0.02, 0.04, 0.06]
[89]:
       testing accuracy = []
       for i in learning rate:
           net.apply(weight reset)
           learning rate snn = i
           optimizer = torch.optim.Adam(net.parameters(), 1r=learning_rate_snn, betas=(0.9, 0
           num epochs snn = 5
           loss hist = []
           acc hist = []
           val acc list = []
           validation iter = len(final train loader)-int(len(final train loader)*0.1)
           print(validation iter)
           # training loop
           for epoch in range (num epochs snn):
               for i, (data, targets) in enumerate(iter(final train loader)):
                   if i \le validation iter:
                       data = data[0]
                       targets = targets[0]
                       net. train()
                       data = data. to (device)
                       targets= targets[0] #set the target to be int rather than list
                       targets = targets. to (device)
                       net.train()
                       spk rec = forward pass(net, data)
                       loss val = loss fn(spk rec, targets)
                       # Gradient calculation + weight update
                       optimizer.zero grad()
                       loss val.backward()
                       optimizer.step()
                       # Store loss history for future plotting
                       loss hist.append(loss val.item())
                       print(f"Epoch {epoch}, Iteration {i} \nTrain Loss: {loss_val.item():.2f
                       acc = SF.accuracy rate(spk rec, targets)
                       acc hist.append(acc)
                   else:
                       validation accuracy = val accuracy(net, data, targets)
                       val acc list.append(validation accuracy)
                       print (f"validation accuracy: {validation accuracy*100:.2f}%\n")
                   print (f''Accuracy: {acc * 100:.2f}%\n'')
           test accuracy = test accuracy(net, final test loader)
           testing accuracy.append(test accuracy)
```

Accuracy: 9.38%

validation accuracy: 7.03%

Accuracy: 9.38%

validation accuracy: 6.25%

Accuracy: 9.38%

validation accuracy: 11.72%

Accuracy: 9.38%

validation accuracy: 7.03%

Accuracy: 9.38%

validation accuracy: 7.03%

# testing set

```
In [90]: test_accuracy = test_accuracy(net, final_test_loader)
    print(test_accuracy)
    fig = plt.figure(facecolor='w')
    plt.axhline(y=test_accuracy, color='r', linestyle='--', label='test accuracy')
    plt.plot(acc_hist)
    plt.plot(val_acc_list, color='g', label='val accuracy')
    # plt.plot(loss_hist, color='b', label='train loss')
    plt.title('train set accuracy')
    plt.xlabel("iteration")
    plt.ylabel('accuracy')
    plt.legend()
    plt.show
```

## 0.08697916666666666

Out[90]: <function matplotlib.pyplot.show(close=None, block=None)>

