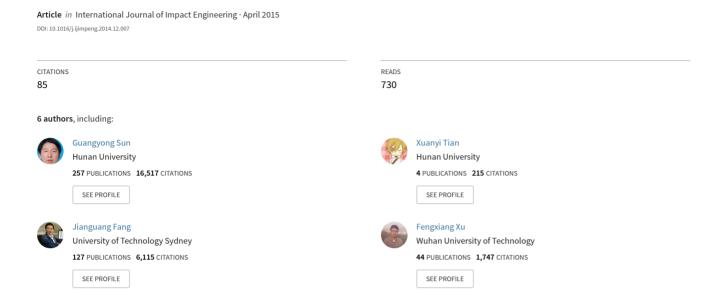
## Dynamical bending analysis and optimization design for functionally graded thickness (FGT) tube





Contents lists available at ScienceDirect

### International Journal of Impact Engineering

journal homepage: www.elsevier.com/locate/ijimpeng



## Dynamical bending analysis and optimization design for functionally graded thickness (FGT) tube



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#### ARTICLE INFO

# Article history: Received 11 July 2014 Received in revised form 17 November 2014 Accepted 19 December 2014 Available online 26 December 2014

Keywords: Crashworthiness design Multiobjective optimization Functionally graded thickness Thin-walled structures Energy absorption

#### ABSTRACT

As a relatively new component with a higher efficiency of material utilization, functionally graded thickness (FGT) structure with desired varying wall thickness has been becoming more and more attractive. In order to sufficiently understand the crashworthiness of FGT under lateral impact, firstly, the finite element (FE) models of thin-walled columns with uniform thickness (UT) and FGT under lateral loading are established and validated by experimental results. It is exhibited that the FE simulations are in good agreement with experimental tests. Then, the crashworthiness of UT tube and the corresponding FGT tube is compared, and the results reveal that the FGT tube can absorb more energy but generate larger force than UT tube under the same weight. Further, parametric analyses show the gradient exponent, wall thickness range, the tube diameter and yielding stress have significant effects on the crashworthiness of FGT tubes. Finally, a multiobjective particle swarm optimization (MOPSO) method is used to optimally seek for those design parameters, where surrogate modeling methods are adopted to formulate the specific energy absorption (SEA) and peak crushing force functions. The results yielded from the optimization demonstrate that the FGT tube is superior to its uniform thickness counterpart in overall crashing behavior under lateral impact. Therefore, FGT tubes are recommended as potential absorbers of crashing energy under lateral loading.

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#### 1. Introduction

Thin walled structures have the advantages of light weight, low price, high strength and stiffness, high reliability, excellent loading-carrying efficiency and energy absorption capacity, which have been widely used as energy absorbers in crashworthiness applications such as automobile, train and aeronautical industries to protect passenger from severe injury [1–3]. To better understand crashing mechanism of thin-walled structures and further improve the design quality of energy absorbers, exhaustive studies have been conducted by using analytical, numerical and experimental approaches for thin-walled structures with various sections, such as circular [4], square [5], hexagonal [6,7], top-hat [8], multi-cell [9,10], convex polygon [11], concave polygon [12], etc. Wierzbicki

and Abramowicz [13], Abramowicz and Jones [14,15] derived some approximate theoretical formula based on the balance of external and internal work to predict the average crushing force of circular and square tubes under either statically or dynamically loading. The general characteristics of force-displacement curves for circular tubes and square tubes are similar: the axial force first reaches an initial peak, followed by a drop and then fluctuates. However, their collapse modes are very different. The concertina mode, diamond mode, mixed mode and global bucking are the main collapse modes for a circular tube, while the common collapse mode of square tubes are symmetric mode, asymmetric mode, extensional mode and global bucking [16]. These different collapse modes directly affect the energy absorption ability of thin-walled columns. Further, these theoretical models were validated experimentally by Langseth and Hopperstad [17], and Abramowicz and Jones [14]. Although these theoretical formula show good agreements with the experimental results for some simple thin-walled structures, it is still a difficult task to derive a closed-form formula to predict the

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crashworthiness responses for some complex thin-walled structures up to date. Fortunately, Non-linear explicit finite element (FE) codes such as PAM-CRASH, ABAQUS Explicit and LS-DYNA provide powerful tools available in numerical simulations of highly nonlinear dynamic response of complicate thin-walled structures, which have been successfully applied in the crashworthiness design of thin-walled structures [18–23].

The studies mentioned above mainly focused on the crashing behavior and energy absorption characteristics of thin-walled tubes under axial loading. In fact, the front, rear and side components of cars often collapse in bending mode, thus bending collapse should be considered when designing vehicle body [24-27]. In addition, a crash test study on 81 vehicles showed that up to 90% involved structural members failed in bending collapse mode [28]. Thus, it has a great significance to carry out the investigation into the bending behavior of thin-walled structures. The first comprehensive experimental and theoretical study on the bending performance of square and rectangular prismatic beams was made by Kecman [29]. He proposed simple failure mechanisms involving stationary and moving plastic hinge lines, and found the momentrotation characteristics in the post-buckling range up to 40°. The proposed theory has been verified by quasi-static bending tests. Wierzbicki et al. [24] extended the concept of a superfolding element and derived a closed-form formula for the bending resistance of thin-walled box-section beams. Lately, Kim and Reid [25] proposed a more accurate theoretical solution to predict the bending collapse of thin-walled structures based on some existing analytical relationship [24]. Liu and Day [30] analyzed the bending collapse of the thin-walled channel section beams and derived their approximation moment-rotation characteristics. An empirical formula based on dimensional analysis has also been presented by Huang and Lu [31].

Generally, the bending collapse of thin-walled beams is localized in a plastic hinge, with the remaining parts of beams rotating as rigid bodies. Since the inward fold of plastic hinge significantly reduces the cross-section area of the crush zone, the plastic bending resistance drops significantly after local sectional collapse occurs at relatively small rotation angle [32]. A distinctive characteristic of such a deformation mechanism is that the plastic deformation is concentrated over a relatively narrow zone, which results in low energy absorption efficiency [27]. In order to achieve higher bending resistance and weight efficiency in energy absorption, ultra-light metal fillers such aluminum foams as honeycomb introduced into the thin-walled structures has attracted increasing interest. Santosa and Wierzbicki [33] and Santosa et al. [34] studied the effect of foam filling on the bending resistance of thin-walled prismatic columns through numerical simulations and quasi-static experiments. It was shown that filling of foam could improve the load-carrying capacity by offering additional support from inside and increased the absorbed energy, and concluded that partial filling of foam might be achieve even higher energy absorption to weight ratio of the structure. Chen et al. [35] carried out the numerical and experimental studies on the bending collapse of thin-walled tubes filled with aluminum foam or aluminum honeycomb. They showed the potentials of significant weight saving and volume reduction by utilizing ultralight metal filler. Zarei and Kroger [32] performed crashworthiness optimization for maximizing specific energy absorption on foam-filled tubes under bending, and found that the foam-filled tubes can save more weight to absorb the same energy. Recently, Yu and his co-authors [4,36,37] have carried out systematic experimental and numerical investigation into the performance of different topological thinwalled structures under three-point bending. Reyes et al. [38] developed a material model including fracture criteria for both extrusion and foam to study the influence of material failure on bending behavior of square aluminum extrusions filled with aluminum foam. Fang et al. [39] investigated and optimized the crashing behaviors of three types of functionally graded foam (FGF)-filled thin-walled structures subjected to lateral impact, and found that the FGF-filled tubes can provide better designs than the ordinary uniform foam (UF) filled counterpart.

Although the foam-filled thin-walled structures significantly improve the crashworthiness, the inherent discontinuity inside the metallic foam easily results in fracture at tensile flanges and diminishes the energy absorption [38,40], which directly limits the application of foam-filled thin-walled structures under bending load to some extent. In addition, the traditional thin-walled tube always form a localized plastic hinge on the compressed flanges for bending collapse, which weakens the impact resistant force and reduces the energy absorption. Therefore, some new thin-walled structures without foam filler need to be developed. In brief, if we can prevent or delay the formation of the localized plastic hinge, the bending collapse of thin-walled columns could be significantly improved. Based on this principle, a novel thin-walled structure named functionally graded thickness (FGT) tube will be presented in this paper. Unlike existing thin-walled structures with uniform thickness, the wall thickness of the present FGT tube varies along the longitudinal direction with a certain gradient. To the authors' best knowledge, no study has been conducted on the energy absorption response of non-uniform thickness thin-walled structures under lateral loads so far. Although fabricating FGT structures could be inherently more sophisticated than making uniform thickness (UT) structures, some advanced technologies e.g. tailor rolling blanks have been available to produce such structures with a given gradient [41,42]. It is the time to make use of FGT tubes for energy absorption under impact scenarios. To do so, it is essential to understand the energy absorption characteristics in comparison with those well-studied uniform thickness (UT) thin-walled structures under lateral loading. On the other hand, crashworthiness design of thin-walled structures is typically characterized by a number of quality and/or performance indices such as peak crushing force, specific energy absorption (SEA) and crash load efficiency, some of which could conflict with each other. Therefore, it is of particular significance to seek the best possible thickness gradient for optimal crashworthiness under multiple criteria.

In this paper, the energy absorption characteristic of FGT tube under lateral impact loading is studied by using nonlinear element code LS-DYNA. After validating finite element model with experiments, the effects of various parameters including the gradient exponent, wall thickness range, the tube diameter and yielding stress on the crashworthiness of FGT tubes are analyzed. Finally, a multiobjective particle swarm optimization method [43] is used to optimize those parameters, where surrogate modeling methods are adopted to formulate the specific energy absorption (SEA) and peak crushing force functions. To efficiently approximate the responses of interest, several widely-used surrogate modeling techniques such as Kriging, response surface method (RSM) and radial basis function (RBF) are compared with each other. The results will demonstrate that the FGT tube provides better crashworthiness performance than the UT tube.

#### 2. Simulation modeling and experimental validation

#### 2.1. Structural crashworthiness indicators

In order to evaluate the crashworthiness of the thin-walled structures under lateral impact load, peak crash force ( $F_{\text{max}}$ ), energy absorption (EA), specific energy absorption (EA) and crash force efficiency (CFE) are usually used as the important indicators for evaluating the crashworthiness.

The energy absorption of a structure subjected to the lateral impact load can be expressed as

$$EA(d) = \int_{0}^{d} F(x)dx \tag{1}$$

where d is a given deformation distance and F(x) denotes the corresponding crushing force. The specific energy absorption is defined as the ratio of the absorbed energy to the mass of the structure and can be written as [44].

$$SEA(d) = \frac{EA(d)}{M} \tag{2}$$

where *M* is the total mass of the structure. Apparently, the higher the SEA, the better the energy absorption capacity of a structure. Another indictor in relation to energy absorption capacity is crash force efficiency (CFE), which can be given as [45].

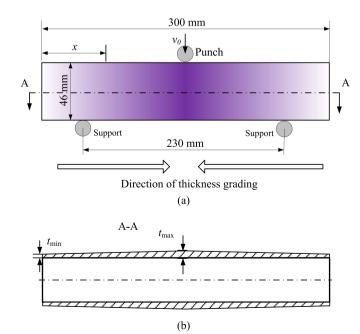
$$CFE = \frac{F_{avg}}{F_{max}} \times 100\% \tag{3}$$

where  $F_{\rm max}$  is the maximum impact force during the whole collision progress.  $F_{\rm avg}$  is the mean crash force expressed as the total energy absorption divided by the corresponding crushing displacement, as

$$F_{avg} = \frac{EA(d)}{d} \tag{4}$$

#### 2.2. Functional graded column

Fig. 1 illustrates the key geometrical features of the circular column under lateral impacting loads. The column lays on two cylindrical supports, and the span and diameters are 230 mm and 46 mm, respectively. A cylindrical punch with a diameter of 10 mm and a mass of 14.44 kg impacts on the mid-span of columns and an



**Fig. 1.** Schematic and profile showing thickness grading patterns in the axial direction: (a) Front view; (b) A-A cross-sectional view.

initial velocity of  $v_0 = 3.44$  m/s. As the local deformation zone is in the middle, it is reasonable that the middle thickness is set as the maximum value  $t_{\rm max}$  and both ends as minimum  $t_{\rm min}$ . The corresponding profile is shown in Fig. 1(b). It is assumed that the circular column is fabricated with gradually varying wall thickness along the axial direction. The idea is similar to the density gradient of the functionally graded foam materials developed by authors [3]. In the axial gradient case (x-direction), the thickness variation  $t_f(x)$  can be defined through the following power law function:

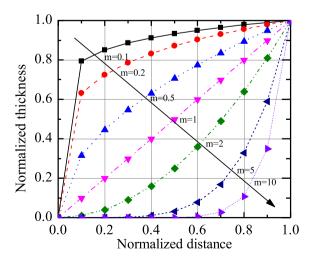
$$t_f(x) = t_{\min} + (t_{\max} - t_{\min}) \left(\frac{2x}{L}\right)^m$$
 (5)

where x is the distance starting from the left end to punch location  $(0 \le x \le L/2)$  due to symmetric), and m is the gradient exponent and assumed to vary between 0 and 10 in this study. L represents the total length of the column. From Eq. (5), it is easily found that the wall thickness increases along the length with a gradient function changing from convexity to concavity correspondingly when the gradient exponent m value varies from less than 1 to greater than 1, as shown in Fig. 2.

#### 2.3. Numerical models and validation

#### 2.3.1. Finite element modeling

The numerical models are developed using explicit non-linear finite element code LS-DYNA in this study. Fig. 3 shows the finite element model subjected to lateral impact. Belytschko-Tsay reduced integration shell elements with five integration points through the shell thickness were employed to model the wall of column, support and punch. Compared with column, the support and punch are almost not deformation, thus they are taken as rigid body. Stiffness-based hourglass control was employed to avoid spurious zero energy deformation modes, and reduced integration was used to avoid volumetric locking. The contact between the punch and the tube column is modeled with a surface-to-surface contact algorithm with a friction coefficient of 0.3. The contact between the supports and the specimen is also simulated with a surface-to-surface contact with the friction coefficient of 0 in order to allow sliding rotation [27]. The "automatic single surface" contact was used to prescribe the column wall itself to avoid interpenetration of column folding during bending collapse.



**Fig. 2.** Variation of normalized thickness ( $0 = t_{\min}$ ,  $1 = t_{\max}$ ) vs normalized distance (0 = left/right cross-section, 1 = middle cross-section).

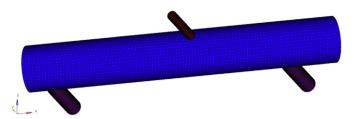


Fig. 3. Finite element model.

The material of thin wall column considered herein is aluminum alloy AA6061. The engineering stress—strain curve which is obtained by the standard uniaxial tension test depicted in Fig. 4. The mechanical properties are as follow: density  $\rho = 2700 \text{ kg/m}^3$ , Poisson's ratio  $\nu = 0.3$ , Young's modulus E = 70 GPa. The constitutive behavior of the aluminum column was modeled via the piecewise linear plasticity material model, Mat 24, in LS-DYNA [46]. The strain rate effect was neglected as the aluminum alloy is strain rate insensitive material [17].

For an ideal continuous variable thickness tube, the column wall should be divided to an infinite number of layers to approximate the actual thickness variation. In the finite element framework, the minimum width of a layer would be equal to the size of each shell element. In order to determine the optimum element size to balance the accuracy and computational cost, a convergence test with five different mesh sizes was carried out. The convergence results are listed in Fig. 5. From which, it can be found that the relative error between element sizes 2 mm and 3 mm is less than 1% for both FGT and UT. Further element refinement will not improve the accuracy significantly, while the computational efficiency will be largely decreased. Therefore, the optimum element size is 3 mm  $\times$  3 mm, which is adopted throughout this paper.

#### 2.3.2. Validation of the numerical model

To evaluate the effectiveness of the simulation models of FGT and UT tubes, the UT tube with the 1.5 mm thickness and the FGT tube with  $t_{max} = 1.5$  mm,  $t_{min} = 0.8$  mm and m = 1 were made and tested. The curves of force versus displacement and deformation of the experiments and simulations are given in Fig. 6. From which, it can be seen that the simulation results agree well with experimental results. The validation provides considerable confidence for us in exploring the energy absorption capacity of thin-walled

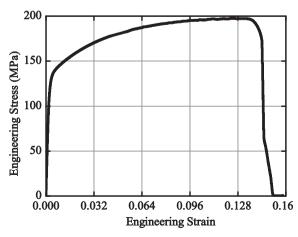


Fig. 4. Engineering stress—strain curves.

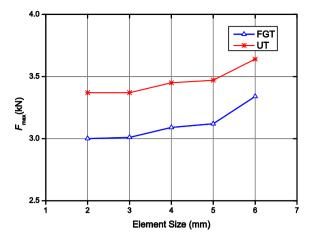


Fig. 5. Convergence results of element sizes.

circular column and optimization using the developed numerical model.

#### 3. Parametric analyses

To better understand the crashworthiness characteristics of FGT tubes under lateral impact loading, it is necessary to carry out the comprehensive parametric analyses. In this section, the parametric analyses mainly investigate the effects of the gradient exponent parameter, thickness range, diameter and yield stress of the tubes on crashworthiness performance. Because the crashworthiness indicators are essentially related with the given deformation distance, for comparison, the deformation distance is set as 40 mm for all these following parametric analyses and optimization design.

#### 3.1. Effect of thickness variation

In order to compare the energy absorption capacity between UT tubes and FGT tubes under the same weight, numerical simulations of the FGT tubes with different gradient parameters are performed. For all the FGT tubes,  $t_{\rm max}$  and  $t_{\rm min}$  are defined as 1.5 mm and 0.8 mm, respectively. To easily calculate the equivalent thickness  $(t_{\rm avg})$  of UT tube, it is assumed that the length of each layer is the same and defined as  $L_{\rm e}$ . Thus the  $t_{\rm avg}$  can be given as follows,

$$t_{avg} = \sum_{i=1}^{N} (t_i L_e) / (NL_e) = \sum_{i=1}^{N} t_i / N$$
 (6)

where N denotes the total number of element layers of the FGT tube along the axial direction, and  $t_i$  is thickness of the ith layer element.

Fig. 7(a) and (b) compare the change trend of  $F_{max}$  and EA of the UT and FGT tubes with increasing gradient parameters, respectively. Generally, FGT tubes have larger values of  $F_{max}$  and EA comparing with their UT counterparts. Moreover, FGT tubes can produce larger SEA than UT tubes as shown in Fig. 7(c). It can also be found from Fig. 7(c) that the SEA of FGT tubes increases up to a peak value and then decreases with the increasing of the gradient exponent parameter m. Thus, the FGT tube seems much more promising than the corresponding UT tube in terms of EA and EA. The reason mainly lies in that the thickness of FGT tube is highest at the region of severe deformation (mid-span part of the tube). Meanwhile, Fig. 7(d) shows the similar relationship between CFE and E of the FGT tube and the corresponding UT tube. Note that CFE of the FGT tube is only slightly bigger than that of the corresponding UT tube when E of the FGT tube when E of tube when E of the FGT tube when E of t

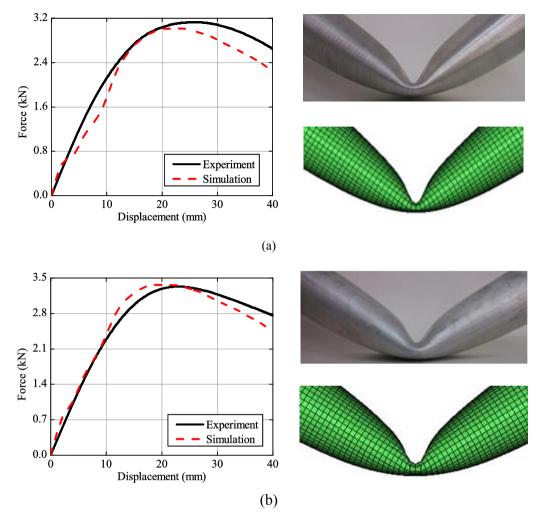


Fig. 6. Comparison between experiments and FE simulations (a) FGT tube ( $t_{max} = 1.5 \text{ mm}$ ,  $t_{min} = 0.8 \text{ mm}$  and m = 1); (b) UT tube (t = 1.5 mm).

#### 3.2. Effect of thickness range

To explore the effect of wall thickness range ( $\Delta p = t_{\rm max} - t_{\rm min}$ ) on the crashworthiness of FGT tube, the value of  $t_{\rm min}$  was varied with 0.8, 1.0 and 1.2 mm while the  $t_{\rm max}=1.5$  mm. Fig. 8(a)-(c) display  $F_{\rm max}$ , EA and SEA of FGT tubes with different gradient exponent m. Note that the thickness range ( $\Delta p$ ) has a noticeable effect on crashworthiness performance. Specifically, larger values of  $\Delta p$  (smaller values of  $t_{\rm min}$ ) can help improving SEA, while it could have a negative effect on EA. Besides, it could also reduce the values of  $F_{\rm max}$ . Meanwhile, it can be found from Fig. 8(d) that the CFE is decreased with  $\Delta p$  increasing.

#### 3.3. Effect of diameter

Four diameters of columns (d=40 mm, 44 mm, 48 mm and 52 mm) are considered here. Fig. 9(a) and (b) give the  $F_{\text{max}}$  and EA of four diameters of FGT tubes with different gradient exponent m. It can be found that  $F_{\text{max}}$ , and EA of four diameters are all decreased with the increasing of m.  $F_{\text{max}}$  of the FGT tube with a diameter of 40 mm is superior to others. Generally, the larger the diameter, the greater  $F_{\text{max}}$ . The rule of  $F_{\text{max}}$  is completely different with that of EA. EA of the FGT tube with a diameter 55 mm is better than other tubes for  $0 \le m \le 0.8$ . For 0.8 < m < 4, the diameter of 48 mm shows the best EA performance. However, the energy absorption of tube with a diameter of 44 mm becomes the highest for  $m \ge 4$ . In

addition, it can also be found from Fig. 9(a) and (b) that the differences of  $F_{\text{max}}$  and EA between four diameters shrink with the increasing of m, respectively.

Fig. 9(c) gives the tendency of SEA for different diameters with an increase of gradient exponent m. It can be seen that SEAs of FGT tubes increase up to their peak values and then decrease with the increasing of m. Meanwhile, SEA of the FGT tube with the diameter of 40 mm is larger than other tubes. From Fig. 9(d), it is observed that the difference of CFE is not so obvious with the change of diameters when m < 1, while the change of CFE is significant when  $m \ge 1$ . CFE is largest for the FGT tube with a diameter of 44 mm when m < 2, while the FGT with the 40 mm diameter is the best selection when m > 2.

#### 3.4. Effect of yielding stress

Fig. 10(a)-(c) depict  $F_{max}$ , EA and SEA of FGT tubes with different yielding stress ( $\sigma_y = 120$ , 135, 150 and 165 MPa). It shows that  $F_{max}$ , EA and SEA will increase with the increasing of yielding stress for all gradient exponents m. However, it can be found from Fig. 10(d) that the CFE is decreased with the increasing of yielding stress. Because the variation of yielding stress does not change the column mass at each specific case of m, the SEA values of different yielding stress follow the same order of magnitude as the EA values. The only difference is that the SEA values first increase and then decrease while the EA values decrease monotonically with the increasing of m.

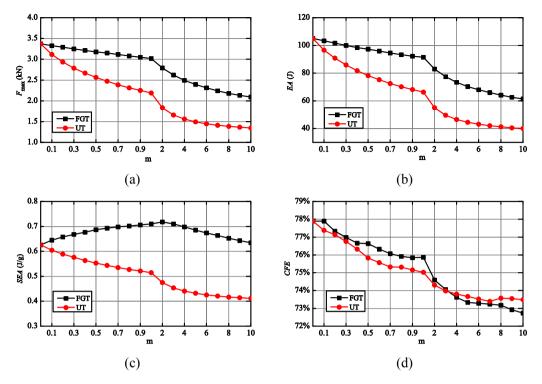


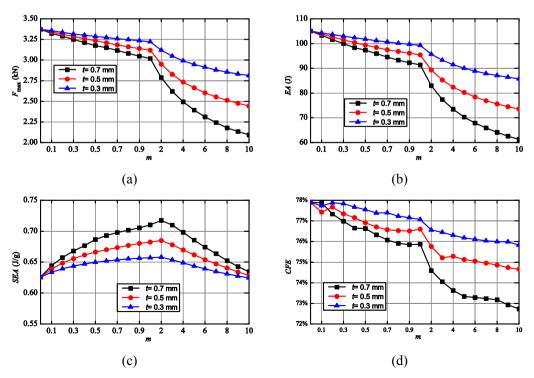
Fig. 7. Energy absorption characteristics versus gradient exponent m of the FGT tubes and the corresponding UT tubes: (a) F<sub>max</sub>; (b) EA; (c) SEA; (d) CFE.

It can also be observed that the tubes with  $\sigma_y=165$  MPa and 120 MPa perform worst and best for  $F_{\rm max}$  and CFE, respectively. Therefore, the columns with lower  $\sigma_y$  are preferred in terms of these two indicators. However, this conclusion conflicts with the requirements of SEA and EA, that is, the lower yield stress will result into the smaller SEA and EA.

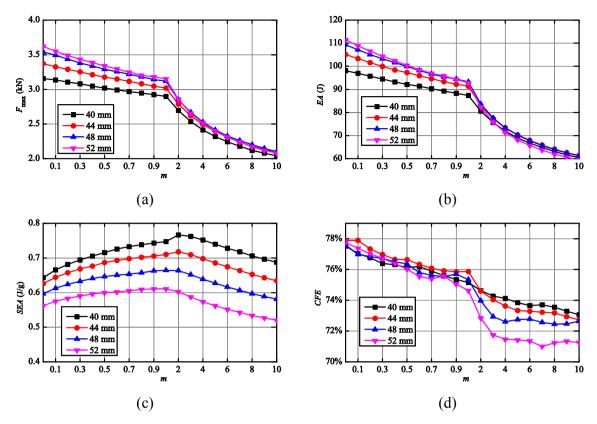
#### 4. Multiobjective optimization design

#### 4.1. Multiobjective optimization problem

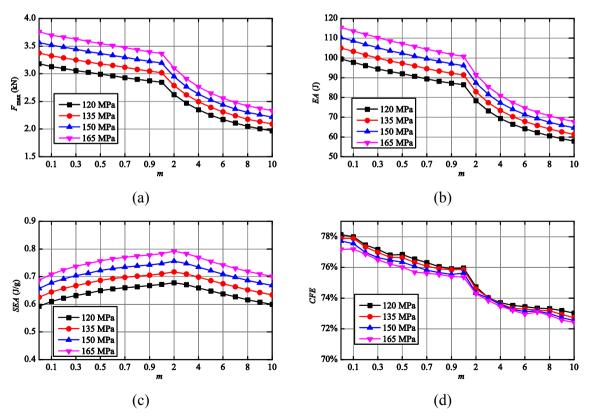
As an energy absorber, the column structure is expected to absorb as much energy as possible per unit mass. Thus, the SEA



**Fig. 8.** Variation of crashworthiness performance vs thickness range: (a)  $F_{\text{max}}$ ; (b) EA; (c) SEA; (d) CFE.



**Fig. 9.** Comparisons of energy absorption characteristics of FGT tube with different diameters: (a)  $F_{\text{max}}$ ; (b) EA; (c) SEA; (d) CFE.



**Fig. 10.** Comparisons of energy absorption characteristics of FGT tube with different yielding stress: (a)  $F_{\text{max}}$ ; (b) EA; (c) SEA; (d) CFE.

should be an objective function and maximized. Besides,  $F_{\rm max}$  is another indicator for the safety of the occupants, which should be minimized. Therefore, the optimization problem can be formulated in a multiobjective framework as follows:

$$\begin{cases} \textit{Minimize} & [F_{\text{max}}(m, d, \sigma_y), -\textit{SEA}(m, d, \sigma_y)] \\ \textit{Subject} & \textit{to} \begin{cases} m^L \leq m \leq m^U \\ d^L \leq d \leq d^U \\ \sigma_y^L \leq \sigma_y \leq \sigma_y^U \end{cases} \end{cases}$$
 (7)

where m is the gradient exponent, d is the diameter,  $\sigma_y$  is the yielding stress of column wall, superscript L and U are lower limit and upper limit of parameter;  $m^L$  and  $m^U$  are 0 and 10,  $d^L$  and  $d^U$  are 40 mm and 52 mm,  $\sigma_y^L$  and  $\sigma_y^U$  are 120 MPa and 165 MPa, respectively.

#### 4.2. Surrogate model and error metrics

It is difficult to derive analytical objective functions mathematically for SEA and  $F_{\text{max}}$  that involve highly nonlinear contactimpact and large deformation mechanics, such as crashworthiness [3]. As an alternative, surrogate model is an effective way to alternate mathematical formulation of the relation between the design variables and responses, which will also reduce the cost of computation. For different problems, the precision of different surrogate model are not the same. In this study, three different surrogate models, Kriging approximation model (KRG) [47], response surface method (RSM) [48] and radial basis function (RBF) [49], are considered. Among these surrogates, the most accurate surrogate will be picked up to perform the multiobjective optimization design. To construct high accuracy surrogate, design of experiment (DOE) often was used to sample the design space. Of many different DOE methods available, Latin hypercube sampling (LHS) is used to generate the training points in the design space [50]. To capture high nonlinear responses, 200 training points are generated in this study.

To assess the modeling accuracy of the RSM, KRG and RBF, 20 additional validation points are randomly generated. Three numerical estimators, namely R-square ( $R^2$ ), Root-Mean-Square-Error (RMSE) and Maximum-Absolute-Percentage-Error (MAPE) are used to validate the accuracy of these surrogate models [51], as given in Eqs. (8)–(10).

$$R^{2} = 1 - \frac{\sum_{i=1}^{M} (y_{i} - \widehat{y}_{i})^{2}}{\sum_{i=1}^{M} (y_{i} - \overline{y})^{2}}$$
(8)

$$RMSE = \sqrt{\frac{1}{M} \sum_{i=1}^{M} (\widehat{y}_i - y_i)^2}$$
 (9)

$$\mathit{MAPE}(\%) = \max\left(\left|\frac{\widehat{y}_i - y_i}{y_i}\right|\right) \times 100(\%) \tag{10}$$

where M is the number of validation points,  $y_i$  is the true values,  $\widehat{y}_i$  is the corresponding approximate surrogate values, and  $\overline{y}$  is the mean of  $y_i$ . These performance metrics reflect the prediction capability of the surrogate models at some new points to some extent. Generally, the  $R^2$  and RMSE metrics indicate the overall accuracy of an approximation model, while the MAPE metrics indicate a local metrics, which describes the error in a sub-region of the design space. Overall, the closer the value of  $R^2$  to unity and/or the smaller the values of RMSE and MAPE, the higher the accuracy.

#### 4.3. Results and discussion

#### 4.3.1. Accuracy of surrogate models

Tables 1 and 2 show the accuracy assessment of these surrogates for FGT and UT tubes, respectively. It can be seen that RBF and Quartic-RSM surrogates are the most accuracy surrogate model in the approximation of  $F_{max}$  for FGT tube and UT tube, respectively. But for the approximation of SEA, the Quartic-RSM surrogate model is the most accuracy surrogate for the FGT and UT tube. The most accurate surrogates will be used to solve the optimization problem.

#### 4.3.2. Optimization results

To obtain the optimal design of the FGT and UT tubes, a multiobjective particle swarm optimization (MOPSO) is used herein. As an extension to the particle swarm optimization (PSO), MOPSO has drawn considerable attention recently because of its relatively fast convergence and well-distributed Pareto front [52]. The Pareto fronts of the FGT tubes and the corresponding UT tubes are shown in Fig. 11. It can be seen that the Pareto front of FGT is located in the lower left of that of UT, which indicates that the FGT has more excellent crashworthiness. Besides, it is clearly seen that -SEA and  $F_{\text{max}}$  are negatively correlated for FGT and UT tubes, which means that an increase of SEA (decrease of -SEA) always leads to an increase of  $F_{\text{max}}$  or decrease of  $F_{\text{max}}$  results in a reduction of SEA. These two performances can't attain simultaneously the optimal solution. Such problem is very fit to be solved by multiobjective optimization algorithm. By which, we can obtain a range of optimal solutions (Pareto front) in a single run, not just an optimal point. These solutions provide a large of design schemes for decision-maker. Here, the designers can effectively search for a more sophisticated optimal solution according to their design requirements.

**Table 1**Accuracy assessment of the surrogate models for FGT tube.

Responses	Surrogate models		Estimators			
			$R^2$	RMSE	MAPE (%)	
F <sub>max</sub> (kN)	KRG	_	0.8627	0.1395	11.4548	
	RBF	_	0.9991	0.0112	0.9271	
	RSM	Linear	0.9110	0.1123	8.9026	
		Quadratic	0.9911	0.0354	2.3664	
		Cubic	0.9964	0.0226	1.8135	
		Quartic	0.9966	0.0220	2.1162	
SEA (J/g)	KRG	_	0.7140	0.0325	12.8440	
	RBF	_	0.9899	0.0061	3.5530	
	RSM	Linear	0.8223	0.0256	11.8580	
		Quadratic	0.9308	0.0160	7.2242	
		Cubic	0.9728	0.0100	4.3019	
		Quartic	0.9837	0.0078	3.0405	

Accuracy assessment of the surrogate models for UT tube.

Responses	Surrogate models		Estimators			
			$R^2$	RMSE	MAPE (%)	
F <sub>max</sub> (kN)	KRG	_	0.5923	0.3095	30.6333	
	RBF	_	0.9784	0.0712	8.8250	
	RSM	Linear	0.7143	0.2591	23.0073	
		Quadratic	0.9270	0.1309	12.9272	
		Cubic	0.9846	0.0602	6.7023	
		Quartic	0.9948	0.0348	3.3140	
SEA (J/g)	KRG	_	0.5377	0.0465	22.2011	
	RBF	_	0.9894	0.0071	4.2059	
	RSM	Linear	0.8415	0.0272	11.3773	
		Quadratic	0.9648	0.0128	6.1665	
		Cubic	0.9940	0.0053	2.3621	
		Quartic	0.9987	0.0024	1.1598	

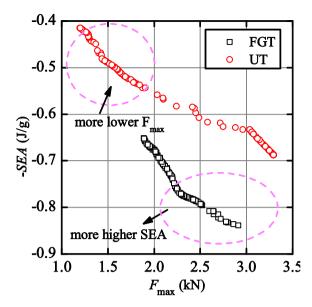


Fig. 11. Comparison of Pareto fronts of the FGT tube and UT tube.

The ideal optimal values of the two single objective functions SEA and  $F_{\rm max}$  are provided in Table 3. Here, the "ideal" means only a single objective (SEA or  $F_{\rm max}$ ) is pursued. These four single "ideal" optimums listed in Table 3 correspond to the four special points in the Pareto space, which just lie at both ends of the Pareto curves. It can be seen from Table 3 that the FGT is superior to UT in Ideal Max SEA which is 0.83 J/g and 0.68 J/g, respectively. However, the Ideal Min  $F_{\rm max}$  of FGT (1.88 kN) is worse than that of UT (1.19 kN). If we only aim to low  $F_{\rm max}$ , we can adopt UT tube. Otherwise, we perfect to use the FGT tube.

#### 5. Conclusions

In this paper, a functionally graded thickness (FGT) tube under lateral impact loads has been investigated by employing the validated finite element model. A series of FGT tubes whose gradient exponent varies from 0 to 10 are compared with the uniform thickness (UT) tubes under the same weight. It was found that the FGT tubes would provide better values in the specific energy absorption (SEA), energy absorption (EA) and crash force efficiency (CFE) but worse values in maximum impact force ( $F_{max}$ ). Through the further parametric study, the gradient exponent, thickness range, diameter of tube and yielding stress of wall material could affect the crashworthiness performance significantly. To achieve the optimum design for the crashworthiness of UT and FGT tubes, the multiobjective optimization problems are formulated, aiming to simultaneously minimize the  $F_{max}$  and maximize the SEA. The optimal results show that the FGT and UT tubes have their cons and pros in practical applications. As the SEA is the most important indicator of an energy absorber for the designers, in this sense, FGT tubes can provide better crashworthiness performance than UT tubes under bending.

**Table 3**Ideal optimums of the two single objective functions for the FGT and UT tubes under lateral impact.

Type	Single objective	m	d (mm)	$\sigma_y(MPa)$	SEA (J/g)	F <sub>max</sub> (kN)
FGT	Ideal Max SEA	2.48	40	165	0.83	2.91
	Ideal Min $F_{\text{max}}$	10.00	40	120	0.65	1.88
UT	Ideal Max SEA	0.00	40	165	0.68	3.29
	Ideal Min $F_{\text{max}}$	8.51	40	120	0.41	1.19

#### Acknowledgment

This work was supported from The National Natural Science Foundation of China (11202072, 11102067), The Doctoral Fund of Ministry of Education of China (20120161120005), The Hunan Provincial Science Foundation of China (13JJ4036) and the Program of the Methodology Study on Designing Automotive Parts with Variable Thickness Blanks (QYT-KT-2013-003).

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