

The Book of Math (Notes)

Kevin Kuo

December 6, 2020

Forward and Disclaimer

These are math notes made by a student (with a physics major and math minor) based off text books. It may contain misconceptions and misinterpretations, thus should not be viewed in the same light of a text book. Use at your own risk and mental sanity.

Symbols

Logic

Name	Symbol	Comment
Exists	\exists	There exists at least one
For all	\forall	
Not exists	\nexists	There does not exist
Exists one	$\exists!$	There only exists one and only one
And	\wedge	
Or	\vee	Inclusive or
Not	\neg	
Logically implies	\implies	If
Logically implied by	\impliedby	Only if
Logically equivalent	\iff	If and only if
Implies	\longrightarrow	
Implied by	\longleftarrow	
Double Implication	\longleftrightarrow	

Set Notation

Name	Symbol	Comment
Empty Set	\emptyset	The set that is empty
Natural Numbers	\mathbb{N}	Set of natural numbers not containing 0, equivalent to the set of positive integers
Integers	\mathbb{Z}	Set of integers
Rational Numbers	\mathbb{Q}	
Algebraic Numbers	\mathbb{A}	
Real Numbers	\mathbb{R}	
Complex Numbers	\mathbb{C}	
In	\in	
Not in	\notin	
Owns	\ni	Has an element
Proper Subset	\subset	Subset that is not itself
Subset	\subseteq	
Superset	\supset	Superset that is not itself
Proper Superset	\supsetneq	

Power set	\wp
Union	\cup
Intersection	\cap
Difference	\setminus

Relationships

Name	Symbol	Comment
Defined	\doteq	
Approximate	\approx	
Equivalent	\equiv	Isomorphic (Group Theory)
Congruent	\cong	Homomorphic (Group Theory)
Proportional	\propto	

Operators

Name	Symbol	Comment
	\oplus	
	\otimes	
	\odot	
	\circ	Convolution
Dagger	\dagger	Complex conjugate transpose of a matrix

Arrows

Name	Symbol	Comment
Maps to	\mapsto	

Hebrew

Name	Symbol	Comment
Aleph	\aleph	Carnality of infinite sets that can be well ordered

Other

Name	Symbol	Comment
Real part	Re	Real part of a number
Imaginary part	Im	Imaginary part of a number

Book Constitution

Intents and Purpose

The goal of this book is to organize mathematical knowledge of topics related to the study of physics or the author's interest. It is meant to be used as a source of for future reference, not as a textbook for students new to the topics. It is a notebook of a student, thus should be treated as one and not as a textbook. At most, it could be used as a study guide along side a textbook. Definitely not as the main source for acquiring knowledge.

Layout and Organization

The book is split into parts each containing a field of study mathematics, or a topic large enough to justify giving it its own part. Each part contains chapters that focuses on a particular topic required to understand the field, with sections dedicated to describing a particular knowledge required for the topic.

As axioms, definitions, theorems, corollary, and proofs are integral and abundant to the study of mathematics, each will have a unique style. Each environment and its styles are displayed as follows:

Axiom 0.1: Axiom name

Example Axiom Axioms are the “ground rules” of the set.

Theorem 0.0.1: Theorem name or citation

Example Theorem An important logical result from the axioms, with proof.

Conjecture 0.0.1: Name of conjecture or citation

Example Conjecture A hypothesis, without proof.

Corollary 0.0.1.1:

Example Corollary An implication as a result of a theorem.

Lemma 0.0.1.1:

Example Lemma Small theorems that build up to a larger theorem.

Proposition 0.0.1.1:

Example Proposition Example proposition.

Proof: Logical deductions that results in a theorem. Proofs I've written will be in grey, which may or may not be correct. □

Definition 0.0.1: Word

Example Definition The definition of a word.

Example 0.0.1 *An example.*

Remark. *Remark A comment by the author in the textbooks used.*

Observation. *Example Observation A remark by me.*

Question. *Example Question A question from me for a mystery to be answered later.*

Contents

I	Logic	1
1	Proofs	3
II	Numbers	5
2	Natural \mathbb{N}	7
3	Integers \mathbb{Z}	9
4	Rationals \mathbb{Q}	11
5	Constructible	13
6	Algebraic \mathbb{A}	15
7	Reals \mathbb{R}	17
8	Complex \mathbb{C}	19
III	Real Analysis	21
9	Sequences	23
9.1	Limits	23
9.1.1	Limit Theorems	23
9.2	Monotone and Cauchy Sequences	23
9.3	Subsequences	23
9.4	\limsup and \liminf	23

9.5	Series	23
9.6	Alternating Series and Integral Tests	23
10	Continuity	25
10.1	Continuous Functions	25
10.1.1	Properties	25
10.2	Uniform Continuity	25
10.3	Limits of Functions	25
11	Metric Spaces	27
IV	Complex Analysis	29
12	Basics	31
12.1	Complex Numbers	31
12.2	Triangle Inequality	32
12.3	Polar and Exponential Form	33
12.3.1	Properties of Polar and Exponential Form	35
12.3.2	Properties of Arguments	35
12.4	Roots of z	36
12.5	Complex Conjugate	38
12.6	Operations as Transformations	39
12.7	Complex Analysis Definitions	40
13	Analytic Functions	45
13.1	Functions as mappings	45
13.2	Limits	47
13.2.1	Limit Theorems	49
13.2.2	Limits of Points at Infinity	51
13.3	Continuity	53
13.3.1	Exercises	56
13.4	Differentiation	56
13.4.1	Differentiation Rules	58

13.5 Cauchy-Riemann Equations	60
13.5.1 Complex Form of the Cauchy-Riemann Equations	67
13.5.2 Conditions for Differentiability	67
14 Conformal Mapping	69
V Ordinary Differential Equations	71
VI Nonlinear Dynamics	73
VII Partial Differential Equations	75
VIII Integral Equations	77
IX Linear Algebra	79
15 Markov Chains	81
X Tensors	83
XI Riemann Geometry	85
XII Abstract Algebra	87
16 Groups	89
17 Rings	91
17.1 Ideals	91
18 Integral Domains	93
19 GCD Domains	95

20 Unique Factorization Domains	97
21 Principal Ideal Domains	99
22 Fields	101
XIII Galois Theory	103
XIV Lie Theory	105
23 Lie Groups	107
24 Lie Algebra	109
XV C-Star Algebra	111
XVI Set Theory	113
XVII Model Theory	115
XVIII Statistics	117
XIX Tips and Tricks	119
25 Integration Techniques	121
25.1 DI Method (Integration Table)	121
25.2 Feynman Integration	121
XX Index	123
XXI Bibliography	125

Part I

Logic

Chapter 1

Proofs

Part II

Numbers

Resources used in part II

content...

Chapter 2

Natural \mathbb{N}

Chapter 3

Integers \mathbb{Z}

Chapter 4

Rationals \mathbb{Q}

Chapter 5

Constructible

Chapter 6

Algebraic \mathbb{A}

Chapter 7

Reals \mathbb{R}

Chapter 8

Complex \mathbb{C}

Part III

Real Analysis

Resources used in part III

1. Kenneth A. Ross - Elementary Analysis (2nd Ed.) [1]

Chapter 9

Sequences

9.1 Limits

9.1.1 Limit Theorems

9.2 Monotone and Cauchy Sequences

9.3 Subsequences

9.4 \limsup and \liminf

9.5 Series

9.6 Alternating Series and Integral Tests

Chapter 10

Continuity

10.1 Continuous Functions

10.1.1 Properties

10.2 Uniform Continuity

10.3 Limits of Functions

Chapter 11

Metric Spaces

Part IV

Complex Analysis

Resources used in part IV

Primary:

1. Brown and Churchill - Complex Variables and Applications [2]

Supplement:

1. A. David Wunsch - Complex Variables with Applications [3]

Chapter 12

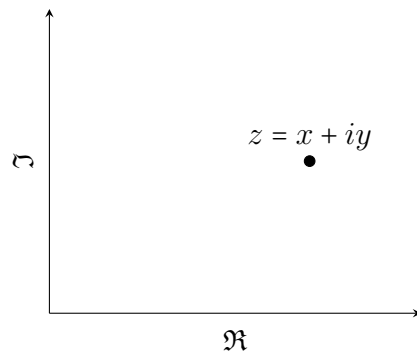
Basics

12.1 Complex Numbers

$$\mathbb{C} = \{x + iy \mid x, y \in \mathbb{R}, i = \sqrt{-1}\}$$

Complex numbers are elements of the complex field (\mathbb{C}), therefore, they obey all the properties of a field.

We will denote complex numbers by $z = x + iy$ with $x, y \in \mathbb{R}$, and refer the real part as $\operatorname{Re}(z) = \operatorname{Re}(z) = x$ and imaginary part as $\operatorname{Im}(z) = \operatorname{Im}(z) = y$. Complex numbers can also be defined as an ordered pair $z = (x, y)$ which is interpreted as points in the complex plane. $(x, 0)$ are points on the real axis while $(0, y)$ are points in the imaginary axis. This expression is often called a Couple, and was presented in 1833 by mathematician William Rowan Hamilton (1805 - 1865).



Like numbers in \mathbb{R} , numbers in \mathbb{C} obey the commutative, distributive, and associative laws. We add and multiply complex numbers in the usual way:

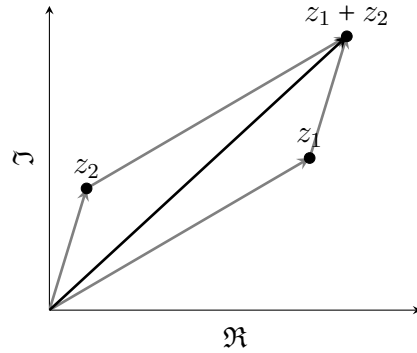
$$\begin{aligned} z_1 + z_2 &= (x_1 + iy_1) + (x_2 + iy_2) & z_1 z_2 &= (x_1 + iy_1)(x_2 + iy_2) \\ &= (x_1 + x_2) + i(y_1 + y_2) & &= (x_1 x_2 - y_1 y_2) + i(x_1 y_2 + x_2 y_1) \end{aligned}$$

$\forall z \in \mathbb{C}$, there is an unique additive inverse $(-z)$ and $\forall z \in \mathbb{C} \setminus \{0\}$, there is an unique multiplicative inverse (z^{-1}) such that

$$\begin{aligned} z + (-z) &= 0 & zz^{-1} &= 1 \\ \implies -z &= -x - iy & \implies (x_1x_2 - y_1y_2) &= 1 \wedge (x_1y_2 + x_2y_1) = 0 \\ & & \implies z^{-1} &= \frac{x_1}{x_1^2 + y_1^2} - i \frac{y_1}{x_1^2 + y_1^2} \end{aligned}$$

The existence and uniqueness of the inverses can be easily proven.

The addition of complex numbers may also be interpreted as akin to vector addition.



12.2 Triangle Inequality

It is not analysis without a section dedicated to the triangle inequality. For any given number $z_1, z_2 \in \mathbb{C}$ it makes no sense to write an inequality $z_1 = a_1 + ib_1 < a_2 + ib_2 = z_2$. Thus, we need have a different notion of size.

Definition 12.2.1: Modulus

The modulus of a complex number is a function $\mathbb{C} \rightarrow \mathbb{R}_{>0}$:

$$|z| = \sqrt{x^2 + y^2} = \sqrt{z\bar{z}}$$

It is obvious why the definition is not $|z| = \sqrt{x^2 + (iy)^2}$ as problems arise when $x = y$. The modulus is the distance of z from $(0,0)$. \bar{z} is the complex conjugate of z , which is explored in section 12.5

Theorem 12.2.1: Triangle Inequality

$$\forall z_1, z_2 \in \mathbb{C} [|z_1 + z_2| \leq |z_1| + |z_2|]$$

From the theorem, we can derive a similar inequality:

$$|z_1| = |z_1 + z_2 - z_2| \leq |z_1 + z_2| + |-z_2| \implies |z_1| - |z_2| \leq |z_1 + z_2|$$

An important property of polynomials is observed when theorem 12.2.1 is applied to polynomials.

Corollary 12.2.1.1:

Consider the polynomial $P(z)$ where $a_n \in \mathbb{C}$, $n \in \mathbb{N}$, $a_0 \neq 0$, and $z \in \mathbb{C}$.

$$P(z) = a_0 + a_1 z + a_2 z^2 + \dots + a_n z^n$$

Then $\forall z, \exists R \in \mathbb{R}_{>0}, |z| < R$ such that

$$\left| \frac{1}{P(z)} \right| < \frac{2}{|a_n| R^n}$$

Proof: Consider

$$w = \frac{P(z)}{z^n} - a_n = \frac{a_0}{z^n} + \frac{a_1}{z^{n-1}} + \dots + \frac{a_{n-1}}{z} \quad z \neq 0$$

$$\implies w z^n = a_0 + a_1 z + \dots + a_{n-1} z^{n-1}$$

$$\implies |w| |z|^n \leq |a_0| + |a_1| |z| + \dots + |a_{n-1}| |z|^{n-1}$$

$$\implies |w| \leq \frac{|a_0|}{|z|^n} + \frac{|a_1|}{|z|^{n-1}} + \dots + \frac{|a_{n-1}|}{|z|}$$

$$\implies |w| < n \frac{|a_n|}{2n} = \frac{|a_n|}{2} \quad \exists \text{ sufficiently large } R < |z| \text{ s.t.}$$

$$\forall m, 0 \leq m \leq n-1, \frac{|a_m|}{|z|^{n-m}} < \frac{|a_n|}{2n}$$

$$\implies |a_n + w| \geq ||a_n| - |w|| > \frac{|a_n|}{2} \quad R < |z|$$

$$\implies |P_n(z)| = |a_n + w| |z|^n > \frac{|a_n|}{2} |z|^n > \frac{|a_n|}{2} R^n \quad R < |z|$$

$$\implies \left| \frac{1}{P(z)} \right| < \frac{2}{|a_n| R^n}$$

□

This tells us that if z is a solution to a polynomial $P(z)$, then the reciprocal of the polynomial $1/P(z)$ is bounded above by $R = |z|$. (i.e. It is bounded by a circle of radius $|z|$.)

12.3 Polar and Exponential Form

Definition 12.3.1: Argument of z

Consider any $z \in \mathbb{C}$ where $z \neq 0$. Let θ be the angle in radians between z and the real axis. Then $\forall n \in \mathbb{N}$, $-\pi < \theta \leq \pi$, the argument of z :

$$\arg(z) = \theta + 2n\pi$$

We know $\forall n \in \mathbb{N}, \theta + 2\pi n = \theta$. This leads us to the definition of the principal argument of z .

Definition 12.3.2: Principal Argument of z

Consider any $z \in \mathbb{C}$ where $z \neq 0$. Let θ be the angle in radians between z and the real axis. Then for $-\pi < \theta \leq \pi$, the principal argument of z :

$$\text{Arg}(z) = \theta$$

It is clear that $\arg(z) = \text{Arg}(z) + 2n\pi$. It is common for the principal argument to be defined $-\pi < \theta \leq \pi$, although other definitions use $0 \leq \theta < 2\pi$.

Definition 12.3.3: Polar Form of z

Consider $z \in \mathbb{C}$. Let $r = |z|$, and $\theta = \arg(z)$. Then $\forall z \in \mathbb{C}, z \neq 0$:

$$z = x + iy = r(\cos(\theta) + i \sin(\theta))$$

Notice that all three definitions require that $z \neq 0$ as θ is undefined at $z = 0$.

Theorem 12.3.1: Euler's Formula

$$e^{i\theta} = \cos(\theta) + i \sin(\theta)$$

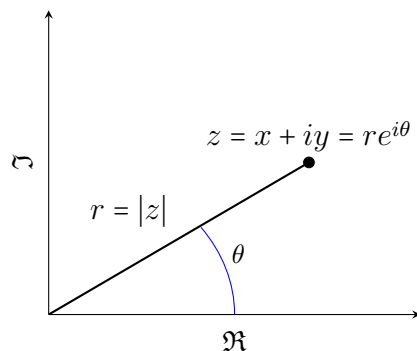
Combining definition 12.3.3 with theorem 12.3.1, we obtain the Exponential Form of z :

Definition 12.3.4: Exponential Form of z

Consider any $z \in \mathbb{C}$, and let $r = |z|$ and $\theta = \text{Arg}(z)$. Then the exponential form of z :

$$z = re^{i\theta}$$

Note: $\theta = \tan^{-1}(y/x)$ and $r = \sqrt{x^2 + y^2}$.



12.3.1 Properties of Polar and Exponential Form

It would be easier to work with the exponential form of z then convert it to the polar form later. The exponential form of a complex number is part of the exponential family of functions, thus possess all the properties of the family. Consider any complex number $z_1 = r_1 e^{i\theta_1}$ and $z_2 = r_2 e^{i\theta_2}$.

$$z_1 z_2 = r_1 r_2 e^{i(\theta_1 + \theta_2)} \qquad z^n = r^n e^{in\theta} \qquad \forall n \in \mathbb{Z}$$

A special case arrives for integer exponential of z on the unit circle.

Theorem 12.3.2: de Moivre's Formula

Consider any $z = e^{i\theta} \in \mathbb{C}$ on the unit circle, and let $n \in \mathbb{Z}$.

$$\forall z \in \mathbb{C} \quad \forall n \in \mathbb{Z} \quad [|z| = 1 \implies (\cos(\theta) + i \sin(\theta))^n = \cos(n\theta) + i \sin(n\theta)]$$

Proof: Consider $z = e^{i\theta}$ and let $n \in \mathbb{Z}$.

$$z^n = (e^{i\theta})^n = e^{in\theta} = \cos(n\theta) + i \sin(n\theta)$$

□

The proof hints that theorem 12.3.2 can be generalized to $\forall n \in \mathbb{R}$, which we will see shortly in ???. Using theorem 12.3.2, we can obtain the double angle identities.

Corollary 12.3.2.1: Double Angle Identities

$$\cos(2\theta) = \cos^2(\theta) - \sin^2(\theta) \qquad \sin(2\theta) = 2 \sin(\theta) \cos(\theta)$$

Proof: Consider any z on the unit circle, that is $z = e^{i\theta}$.

$$\begin{aligned} (\cos(\theta) + i \sin(\theta))^2 &= \cos(2\theta) + i \sin(2\theta) && \text{Theorem 12.3.2} \\ \implies \cos^2(\theta) - \sin^2(\theta) + i 2 \sin(\theta) \cos(\theta) &= \cos(2\theta) + i \sin(2\theta) \end{aligned}$$

Equating the real and imaginary parts yield the desired results.

□

12.3.2 Properties of Arguments

Recall from section 12.3.1:

$$z_1 z_2 = r_1 r_2 e^{i(\theta_1 + \theta_2)} \qquad z^n = r^n e^{in\theta} \qquad \forall n \in \mathbb{Z}$$

The arguments for the arguments of products of any $z_1, z_2 \in \mathbb{C}$ follows immediately from the properties of the exponential.

Corollary 12.3.2.2: Arguments of Products

$$\begin{aligned}\arg(z_1 z_2) &= \arg(z_1) + \arg(z_2) & \text{Arg}(z_1 z_2) &= \text{Arg}(z_1) + \text{Arg}(z_2) \\ \arg(z^n) &= n \arg(z) & \text{Arg}(z^n) &= n \text{Arg}(z)\end{aligned}$$

Proof:

$$\begin{aligned}z_1 z_2 &= r_1 r_2 e^{i(\theta_1 + \theta_2)} \\ \implies \arg(z_1 z_2) &= \arg(z_1) + 2n_1\pi + \arg(z_2) + 2n_2\pi & n_1, n_2 \in \mathbb{Z} \\ \implies \arg(z_1 z_2) &= \arg(z_1) + \arg(z_2) \\ \implies \text{Arg}(z_1 z_2) &= \text{Arg}(z_1) = \text{Arg}(z_2)\end{aligned}$$

$$\begin{aligned}z^n &= r^n e^{in\theta} \\ \implies \arg(z^n) &= n \arg(z) + 2n\pi & n \in \mathbb{Z} \\ \implies \arg(z^n) &= n \arg(z) \\ \implies \text{Arg}(z^n) &= n \text{Arg}(z)\end{aligned}$$

□

It is clear that:

$$\arg\left(\frac{z_1}{z_2}\right) = \arg(z_1) - \arg(z_2) \qquad \text{Arg}\left(\frac{z_1}{z_2}\right) = \text{Arg}(z_1) - \text{Arg}(z_2)$$

12.4 Roots of z

In definition 12.3.4, you might be wondering why $z^n = r^n e^{in\theta}$ is not for $n \in \mathbb{R}$. That is because there is more things to consider, which we will explore in this section. Recall that $z = re^{i\theta} = re^{i(\theta+2n\pi)}$ for $n \in \mathbb{Z}$.

Definition 12.4.1: Exponential of z

Consider any $z \in \mathbb{C}$ and any $x \in \mathbb{R}$

$$z^x = \left(r e^{i(\theta+2n\pi)} \right)^x = r^x e^{ix(\theta+2n\pi)}$$

For $x \notin \mathbb{Z}$, it is clear that $z^x = r^x e^{ix(\theta+2n\pi)} \neq r^x e^{ix\theta}$, since $2nx\pi = 0 \iff nx \in \mathbb{Z}$. In order to define the roots of z we must need a more general and proper definition of z .

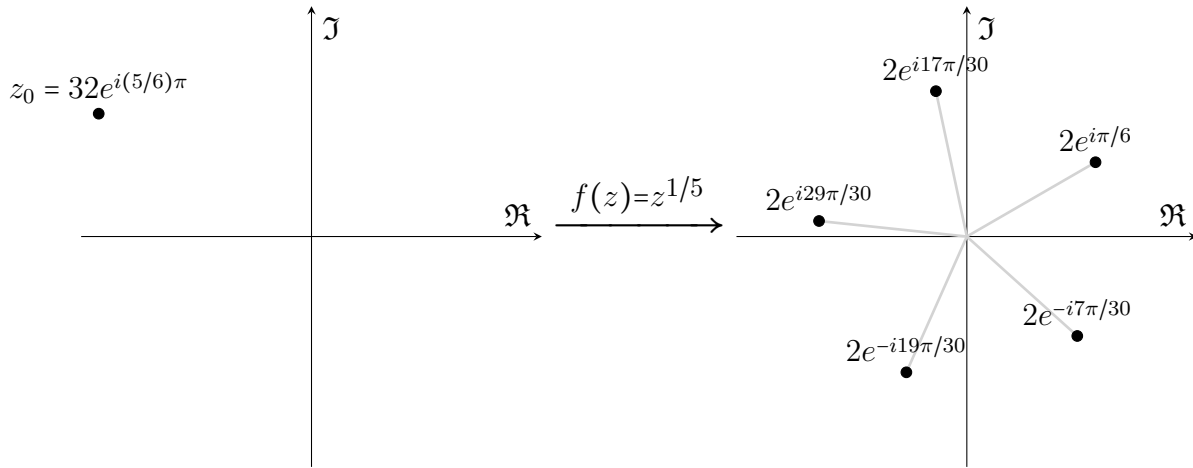
Definition 12.4.2: Roots of z_0

Consider any $z_0 \in \mathbb{C}$ and any $m \in \mathbb{N}$.

$$z_0^{\frac{1}{m}} = r_0^{\frac{1}{m}} e^{i\left(\frac{\theta_0 + 2n\pi}{m}\right)} = r_0^{\frac{1}{m}} e^{i\left(\frac{\theta_0}{m} + \frac{2n\pi}{m}\right)}$$

Taking the m -th root of $z_0 \in \mathbb{C}$ scales θ_0 by $1/m$, and provides solutions at equally spaced by $2\pi/m$ on a circle of radius $r_0^{1/m}$. That is, the roots lie on the vertices of a regular n -sided polygon inscribed in a circle of radius $|z|^{1/m}$.

Example 12.4.1 Consider $z_0 = 32e^{i(5/6)\pi}$, then $z_0^{(1/5)} = 2e^{i(\pi/6) + i(2/5)n\pi}$ for $n \in \mathbb{Z}$. The radius went from 32 to $32^{(1/5)} = 2$, and five roots appear equally spaced with distance of $(2/5)\pi$ on a circle with radius 2. Before and after graphs are as follows, note graph on right is zoomed in:



We can see that the roots of z_0 form a set:

Definition 12.4.3: Set of roots of z_0

Consider the m -th root of any $z_0 \in \mathbb{C}$. Let:

$$z_0 = r_0 e^{i\theta_0} \quad c_0 = r_0^{1/m} e^{i\theta_0/m} \quad \omega_n = e^{i\frac{2\pi}{m}} \quad m \in \mathbb{N}$$

Then the set of roots of z_0 :

$$z_0^{1/m} = \{c_k = c_0 \omega_m^k \mid k \in \mathbb{N}, 0 \leq k < m\}$$

c_0 is the principal root. The root corresponding to the principal argument of z .

Definition 12.4.4: Principal Root

Consider the m -th root of any $z_0 \in \mathbb{C}$. The principal root of z_0 is defined as:

$$c_0 = r_0^{\frac{1}{m}} e^{i\frac{\theta_0}{m}}$$

Example 12.4.2 Recall from the previous example: $z_0 = 32e^{i(5/6)\pi}$. This gives us

$$c_0 = 32^{1/5}e^{i\pi/6} = 2e^{i\pi/6} \qquad \omega_5 = e^{i2\pi/5}$$

Then

$$\begin{aligned} c_0 &= c_0\omega_5^0 = 2e^{i\pi/6} \\ c_1 &= c_0\omega_5^1 = 2e^{i\pi/6}e^{i2\pi/5} = 2e^{i17\pi/30} \\ c_2 &= c_0\omega_5^2 = 2e^{i\pi/6}e^{i4\pi/5} = 2e^{i29\pi/30} \\ c_3 &= c_0\omega_5^3 = 2e^{i\pi/6}e^{i6\pi/5} = 2e^{i41\pi/30} = 2e^{-i19\pi/30} \\ c_4 &= c_0\omega_5^4 = 2e^{i\pi/6}e^{i8\pi/5} = 2e^{i53\pi/30} = 2e^{-i7\pi/30} \end{aligned}$$



12.5 Complex Conjugate

Definition 12.5.1: Complex Conjugate

The complex conjugate of $z \in \mathbb{C}$ is denoted \bar{z} .

$$\bar{z} = x - iy = r(\cos(\theta) - i\sin(\theta)) = re^{-i\theta}$$

Graphically, it is the reflection of z across the real axis.



It is then easy to see

$$\operatorname{Re}(z) = \frac{z + \bar{z}}{2}$$

$$\operatorname{Im}(z) = \frac{z - \bar{z}}{2i}$$

$$|z|^2 = z\bar{z}$$

As $\operatorname{Re}(z) = x = r \cos(\theta)$ and $\operatorname{Im}(z) = y = r \sin(\theta)$ and using definition 12.3.4, we can obtain the complex forms of sine and cosine:

Definition 12.5.2: Complex Sine and Cosine

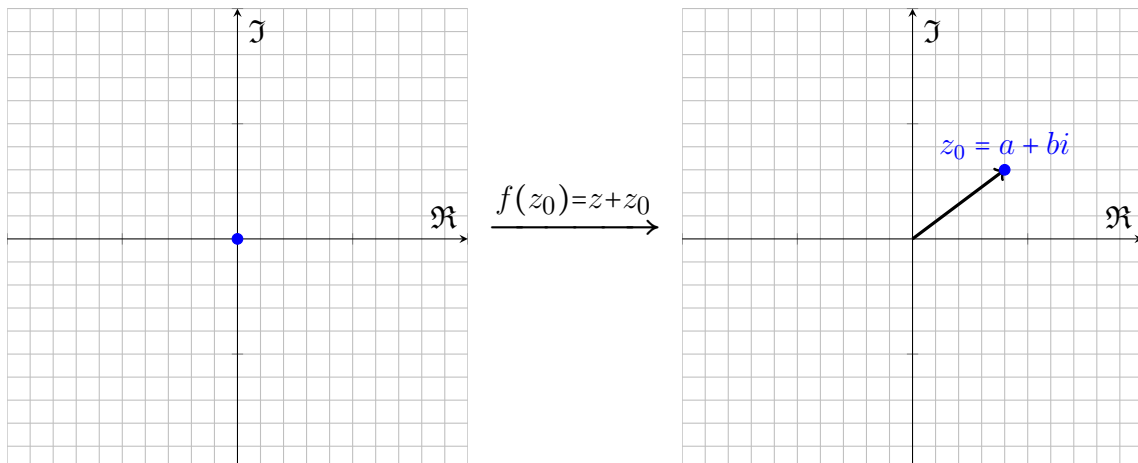
$$\cos(\theta) = \frac{e^{i\theta} + e^{-i\theta}}{2}$$

$$\sin(\theta) = \frac{e^{i\theta} - e^{-i\theta}}{2i}$$

12.6 Operations as Transformations

Consider any $z \in \mathbb{C}$. A function $f : \mathbb{C} \rightarrow \mathbb{C}$ can be viewed as transformations of the complex plane.

Example 12.6.1 (Addition as translation) Consider any $z_0 \in \mathbb{C}$, $z_0 = a + bi$ for $a, b \in \mathbb{R}$. Addition by z_0 can be seen as a shift in the complex plane by $a + bi$. (i.e. It takes the origin and shifts it by z_0 .)



Example 12.6.2 (Multiplication as scaling and rotation) Consider any $z_0 \in \mathbb{C}$, $z_0 = re^{i\theta}$. Multiplication by z_0 scales the entire complex plane by r and rotates it by θ . (Imagine rotating and stretching out a net.)



12.7 Complex Analysis Definitions

Definition 12.7.1: Neighbourhood

A neighbourhood of a point z_0 is the set of all points z with distance less than ϵ .

$$\{z : |z - z_0| < \epsilon\}$$

i.e. It is the set of all points that lie within a circle centred at z_0 with radius ϵ . Points on the circumference not included.



Definition 12.7.2: Deleted Neighbourhood

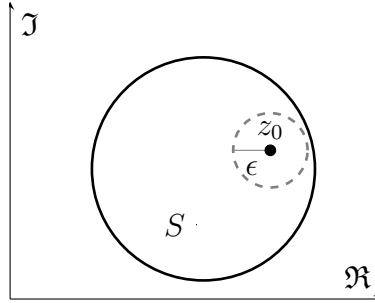
A deleted neighbourhood is the set of all points z with distance less than ϵ from a point z_0 , not including z_0 . That is, it is a neighbourhood of z_0 without z_0 .

$$\{z : |z - z_0| < \epsilon, z \neq z_0\}$$



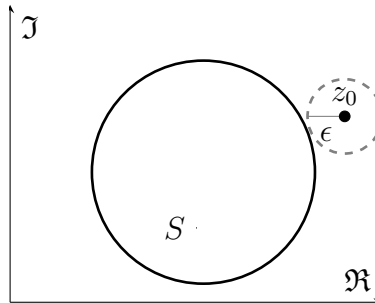
Definition 12.7.3: Interior Point

Let S be a set. A point z_0 is an interior point of S if $\exists \epsilon$ such that $\forall z, |z - z_0| < \epsilon \implies z \in S$. That is, z_0 is an interior point of S if it has a neighbourhood where all points in the neighbourhood are elements of S .



Definition 12.7.4: Exterior Point

Let S be a set. A point z_0 is an exterior point of S if $\exists \epsilon$ such that $\forall z, |z - z_0| < \epsilon \implies z \notin S$. That is, z_0 is an exterior point of S if it has a neighbourhood that does not contain any element of S .



Definition 12.7.5: Boundary Point

Let S be a set. A point z_0 is a boundary point of S if $\forall \epsilon, \exists z \in S, z' \notin S$, such that $|z - z_0| < \epsilon$ and $|z' - z_0| < \epsilon$. That is, for all neighbourhoods of z_0 there exists a point that is in S and a point not in S .



Note: A boundary point of S may or may not be in S .

Definition 12.7.6: Boundary of a Set

A boundary of a set S is the set of all boundary points of S . The set containing all boundary points of S .

$$\{z_0 : \forall \epsilon \exists z \in S, z' \notin S (|z - z_0| < \epsilon \wedge |z' - z_0| < \epsilon)\}$$

Definition 12.7.7: Open Set

A set that does not contain any boundary points.

Theorem 12.7.1:

Set S is open $\iff \forall s \in S, s$ is an interior point of S

Proof: \implies : Suppose S is open $\nRightarrow \forall s \in S, s$ is an interior point of S , for contradiction. That is, $\exists s \in S$ that is either a boundary point or an exterior point. $s \in S$ implies s is not an exterior point of S , so s has to be a boundary point of S . This contradicts that S is an open set.

$$S \text{ is open} \implies \forall s \in S (s \text{ is an interior point of } S)$$

\impliedby :

$$\begin{aligned} & \forall s \in S (s \text{ is an interior point of } S) \\ & \implies \forall s' \forall \epsilon (|s' - s| < \epsilon \implies s' \in S) \\ & \implies S \text{ does not contain boundary points} \implies S \text{ is open} \end{aligned}$$

□

A set can be neither open or closed. Consider the set $S = \{z : 0 < |z| \leq 1\}$. S is not closed since it does not contain the boundary point 0, and it is not open since it contains boundary points where $|z| = 1$. The set \mathbb{C} is both open and closed since it has no boundary points.

Definition 12.7.8: Closed Set

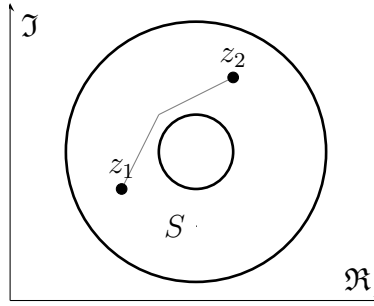
A set that contains all of its boundary points.

Definition 12.7.9: Closure of a Set

Let S be a set. The closure of S is a closed set containing all points of S and all boundary points of S .

Definition 12.7.10: Connected Set

An open set S is connected if $\forall z_1, z_2 \in S$, z_1 and z_2 can be connected by a polygonal line lying within S .

**Definition 12.7.11: Polygonal Line**

A finite set of line segments joined end to end.

Definition 12.7.12: Domain

A nonempty connected set.

Note: All neighbourhoods are domains.

Definition 12.7.13: Region

A domain with none, some, or all of its boundary points.

Definition 12.7.14: Closed Region

A domain with all of its boundary points.

Definition 12.7.15: Bounded Set/Region

A set S is bounded if $\exists R = |z| > 0$ such that $\forall s \in S$, $|s| < R$. That is, S is bounded if $\forall s \in S$, s is contained in some circle of radius R centred at the origin.

Definition 12.7.16: Closed Region

A bounded and closed region.

Definition 12.7.17: Accumulation/Limit Point

A point z_0 is a accumulation point of a set S if all deleted neighbourhood of z_0 contains an element of S .

$$\forall \epsilon \exists s \in S (s \neq z_0 \wedge |z - s| < \epsilon)$$

Note: Unlike a boundary point, an accumulation point does not require that all neighbourhood of z_0 contain an element not in S .

Theorem 12.7.2:

Set S is closed $\iff \forall$ accumulation points z_0 of S , $z_0 \in S$

Proof: \implies : Let S is closed and z_0 is an accumulation point of a set S where $z_0 \notin S$ for contradiction. If $\exists z_0 \notin S$, then z_0 is a boundary point of S . Contradicts closed set contains all boundary points.

\impliedby : Suppose all accumulation points of S are elements of S but S is not closed for contradiction. Then S does not contain one or more boundary points. Suppose z_0 is a boundary point of S that is not in S . Then $\forall \epsilon \exists s \in S$ where $|s - z_0| < \epsilon$, so by considering the deleted neighbourhood of z_0 , this makes z_0 an accumulation point of S . This contradicts that all accumulation points of S is in S . \square

Chapter 13

Analytic Functions

13.1 Functions as mappings

A function $f : S \rightarrow S'$ is a function that maps elements from S to elements on S' . The value of f at z is denoted $f(z)$ and the set S is the domain of f while S' is the image of f . Recall section 12.6, a function can likewise be viewed as a transformation or mapping, that maps $z \in \text{dom}(f) = S$ to values $z' \in \text{img}(f) = S'$.

Definition 13.1.1: Range

Let f be a function with domain S and image S' . The range of f is the entire image of S .

Note: Image is a subset of range, and can be a single point or a set of points.

Definition 13.1.2: Inverse Range

The set of all points $s \in S$ with the value $f(s) = s'$ for some $s' \in S'$.

$$\{s : f(s) = s', s' \in S'\}$$

Note: The domain of a function is often a domain, but it does not need to be a domain.

We will consider functions $f : S \rightarrow S'$ where both $S, S' \subseteq \mathbb{C}$. For such functions we can break it into a two real valued functions:

$$\begin{aligned} f(z) &= u(x, y) + iv(x, y) & \text{dom}(u) \subseteq \mathbb{R}, \text{dom}(v) \subseteq \mathbb{R} \\ &= u(r, \theta) + iv(r, \theta) \end{aligned}$$

Recall that a real-valued function is a function with a domain that is a subset of \mathbb{R} (??). If $\forall z, v(x, y) = 0$, then f is called a real-valued function of a complex variable.

Definition 13.1.3: Polynomial

Let $a_i \in \mathbb{C}$, $0 \leq i \leq n$ where $i, n \in \mathbb{N} \cup \{0\}$. If $a_n \neq 0$, then a polynomial of degree n is

$$P(z) = a_0 + a_1z + a_2z^2 + \dots + a_nz^n = \sum_{i=0}^n a_iz^i$$

Definition 13.1.4: Rational Functions

Let $P(z)$ and $Q(z)$ are polynomials, then rational functions are quotients:

$$\frac{P(z)}{Q(z)}$$

Defined for all z where $Q(z) \neq 0$.

Definition 13.1.5: Multiple-Valued Function

Let f be a function and $z \in \text{dom}(f)$. f is a multiple-valued function if it assigns more than one value to a point z .

“When multiple-valued functions are studied, usually just one of the possible values assigned at each point is taken, in a systematic manner and a (single-valued) function is constructed from the multiple-valued one” - Brown and Churchill [2]

What this means that for $z \in \mathbb{C}$ a function f assigns $u(z)$ and $v(z)$ to z . By taking just u or v , we create a single-valued function from a multiple-valued function.

Example 13.1.1 ($f(z) = z^2$)

$$\begin{aligned} f(z) = z^2 &= x^2 - y^2 + i2xy \\ \implies u(x, y) &= x^2 - y^2 \quad v(x, y) = 2xy \end{aligned}$$

By setting $u = x^2 - y^2 = c_1$ where $c_1 \in \mathbb{R}_{>0}$ we can see that

$$u = x^2 - y^2 = c_1 \quad v = 2xy = \pm 2y\sqrt{y^2 + c_1}$$

This tells us that in the complex plane of u and v , if we fix u to a constant c_1 and move along $v = \pm 2y\sqrt{y^2 + c_1}$ by incrementing y we draw out two hyperbolas in the complex plane of x and y . This means that the function $f(z) = z^2$ takes points on hyperbolas the complex plane of x and y and translates them onto a vertical line in the complex plane of u and v where u is a constant.



Likewise if we set $v = c_2$ where $c_2 \in \mathbb{R}_{>0}$, we get:

$$u = x^2 - \frac{c_2^2}{4x^2} \qquad v = 2xy = c_2$$

Taking the limits:

$$\lim_{x \rightarrow 0^+} u = -\infty \qquad \lim_{x \rightarrow \infty, x > 0} u = \infty \qquad (13.1)$$

$$\lim_{x \rightarrow -\infty, x < 0} u = \infty \qquad \lim_{x \rightarrow 0^-} u = -\infty \qquad (13.2)$$

Equation 11.1 tells us as x goes from 0 to ∞ , u moves from $-\infty$ to ∞ , which corresponds to the hyperbola in the first quadrant of the xy complex plane. Similarly for equations 11.2.



If we look at f using the polar representation, we get $f(z) = r^2 e^{i2\theta}$. This tells us $\forall r \geq 0$, $r \mapsto r^2 = \rho \geq 0$, and $\forall \theta$, $\theta \mapsto \phi = 2\theta$. It is worth noting that mapping of points between $0 \leq \theta < 2\pi$ is not one-to-one, since points in $0 \leq \theta < \pi$ and points in $\pi \leq \theta < 2\pi$ both get mapped to $0 \leq \phi < 2\pi$.

13.2 Limits

Definition 13.2.1: Limit

Let $z, z_0, w_0 \in \mathbb{C}$ and f be a function. We say $f(z)$ has limit w_0 as z approaches z_0 if:

$$\forall \epsilon \exists \delta [0 < |z - z_0| < \delta \implies |f(z) - w_0| < \epsilon]$$

We then denote: $\lim_{z \rightarrow z_0} f(z) = w_0$

This tells us that $\lim_{z \rightarrow z_0} f(z) = w_0$ if some deleted neighbourhood $|z - z_0| < \delta$ corresponds to a neighbourhood $|f(z) - w_0| < \epsilon$. Note that the mapping of all points z in $|z - z_0| < \delta$ to $|f(z) - w_0| < \epsilon$ need not be surjective. It just needs to be mapped less than distance ϵ from w_0 .

Note: Definition 13.2.1 allows us to verify if a limit exists, but it is not a method for determining a limit.



Theorem 13.2.1: Uniqueness of Limits

Suppose the limit of f at z_0 exists, then it is unique.

Proof: Suppose two limits of f at z_0 exists for contradiction.

$$\begin{aligned} & [\lim_{z \rightarrow z_0} f(z) = w_0] \wedge [\lim_{z \rightarrow z_0} f(z) = w_1] \\ \implies & [0 < |z - z_0| < \delta_0 \implies |f(z) - w_0| < \epsilon] \wedge [0 < |z - z_0| < \delta_0 \implies |f(z) - w_1| < \epsilon] \end{aligned}$$

$$\begin{aligned} w_1 - w_0 &= [f(z) - w_0] + [w_1 - f(z)] \\ \implies |w_1 - w_0| &= |[f(z) - w_0] + [w_1 - f(z)]| \leq |f(z) - w_0| + |f(z) - w_1| \end{aligned}$$

Now choosing $\delta = \min\{\delta_1, \delta_2\}$, we get:

$$|w_1 - w_0| < \epsilon + \epsilon = 2\epsilon$$

Choosing ϵ to be arbitrary small, we end up with:

$$w_1 - w_0 = 0 \implies w_1 = w_0$$

□

Definition 13.2.1 requires that f be defined at all points in the deleted neighbourhood of z_0 . That is, z_0 is interior to the region which f is defined. We can extend the definition by agreeing that $0 < |z - z_0| < \delta \implies |f(z) - w_0| < \epsilon$ also holds for z that lie in the region where f is defined and the deleted neighbourhood of z_0 . That is $f(z_0)$ need not be defined for a limit at z_0 to exist.

Example 13.2.1 Show $(f(z) = iz/2) \wedge (|z| < 1) \implies \lim_{z \rightarrow 1} f(z) = i/2$.

We can see that we have restricted the domain of f to the region $|z| < 1$, this puts $z = 1$ right at the boundary of the domain of definition of f .

$$\begin{aligned} |z| < 1 &\implies \left| f(z) - \frac{i}{2} \right| = \left| \frac{iz}{2} - \frac{i}{2} \right| = \frac{|z - 1|}{2} \\ &\implies \forall \epsilon \forall \epsilon \exists \delta \left[0 < |z - 1| < \delta = 2\epsilon \implies \left| f(z) - \frac{i}{2} \right| < \epsilon \right] \\ &\implies \lim_{z \rightarrow 1} f(z) = \frac{i}{2} \end{aligned}$$

This highlights the fact that if the limit exists, then z is allowed to approach z_0 from any arbitrary direction.

Example 13.2.2 *Limit of $f(z) = z/\bar{z}$ does not exist at $z = 0$*

Consider $\lim_{z \rightarrow 0} f(z)$. Let us approach the limit from the x -axis and the y -axis.

$$\lim_{z=(x,0) \rightarrow 0} f(z) = \frac{x+i0}{x-i0} = 1 \qquad \lim_{z=(0,y) \rightarrow 0} f(z) = \frac{0+iy}{0-iy} = -1$$

We end up with two different limits. As limits are unique, we conclude that $\lim_{z \rightarrow 0} f(z)$ does not exist.

13.2.1 Limit Theorems

Theorem 13.2.2:

Consider $f(z) = u(x, y) + iv(x, y)$. Let $z_0 = x_0 + iy_0$ and $w_0 = u_0 + iv_0$.

$$\left[\lim_{(x,y) \rightarrow (x_0,y_0)} u(x, y) = u_0 \right] \wedge \left[\lim_{(x,y) \rightarrow (x_0,y_0)} v(x, y) = v_0 \right] \iff \lim_{z \rightarrow z_0} f(z) = w_0$$

Proof: \implies :

By definition:

$$\begin{aligned} & \left[\lim_{(x,y) \rightarrow (x_0,y_0)} u(x, y) = u_0 \right] \wedge \left[\lim_{(x,y) \rightarrow (x_0,y_0)} v(x, y) = v_0 \right] \\ & \implies \forall \epsilon \exists \delta_1, \delta_2 \left[\left(0 < \sqrt{(x-x_0)^2 + (y-y_0)^2} < \delta_1 \implies |u-u_0| < \frac{\epsilon}{2} \right) \right. \\ & \quad \left. \wedge \left(0 < \sqrt{(x-x_0)^2 + (y-y_0)^2} < \delta_2 \implies |v-v_0| < \frac{\epsilon}{2} \right) \right] \end{aligned} \tag{13.3}$$

Triangle inequality for the distance between points:

$$\begin{aligned} |(u+iv) - (u_0+iv_0)| &= |(u-u_0) + i(v-v_0)| \leq |u-u_0| + |v-v_0| \\ \sqrt{(x-x_0)^2 + (y-y_0)^2} &= |(x-x_0) + i(y-y_0)| = |(x+iy) - (x_0+iy_0)| \end{aligned}$$

Let $\delta = \min\{\delta_1, \delta_2\}$, it follows from eq. (13.3):

$$0 < |(x+iy) - (x_0+iy_0)| < \delta \implies |(u+iv) - (u_0+iv_0)| < \frac{\epsilon}{2} + \frac{\epsilon}{2} = \epsilon$$

Thus, $\lim_{z \rightarrow z_0} f(z) = w_0$.

\impliedby :

Suppose $\lim_{z \rightarrow z_0} f(z) = w_0$.

$$\begin{aligned} & \lim_{z \rightarrow z_0} f(z) = w_0 \\ & \implies \forall \epsilon \exists \delta > 0 [|(x+iy) - (x_0+iy_0)| < \delta \implies |(u+iv) - (u_0+iv_0)| < \epsilon] \end{aligned} \tag{13.4}$$

By the triangle inequality:

$$\begin{aligned}|u - u_0| &\leq |(u - u_0) + i(v - v_0)| = |(u + iv) - (u_0 + iv_0)| \\ |v - v_0| &\leq |(u - u_0) + i(v - v_0)| = |(u + iv) - (u_0 + iv_0)|\end{aligned}$$

$$|(x + iy) - (x_0 + iy_0)| = |(x - x_0) + i(y - y_0)| = \sqrt{(x - x_0)^2 + (y - y_0)^2}$$

Thus, it follows from the inequalities in eq. (13.4):

$$\begin{aligned}0 &< \sqrt{(x - x_0)^2 + (y - y_0)^2} < \delta \\ \implies & [|u - u_0| < \epsilon] \wedge [|v - v_0| < \epsilon] \\ \implies & \left[\lim_{(x,y) \rightarrow (x_0,y_0)} u(x,y) = u_0 \right] \wedge \left[\lim_{(x,y) \rightarrow (x_0,y_0)} v(x,y) = v_0 \right]\end{aligned}$$

□

Theorem 13.2.3:

Suppose

$$\left[\lim_{z \rightarrow z_0} f(z) = w_0 \right] \wedge \left[\lim_{z \rightarrow z_0} F(z) = W_0 \right]$$

Then

$$\begin{aligned}\lim_{z \rightarrow z_0} [f(z) + F(z)] &= w_0 + W_0 \\ \lim_{z \rightarrow z_0} [f(z)F(z)] &= w_0 W_0 \\ \lim_{z \rightarrow z_0} \frac{f(z)}{F(z)} &= \frac{w_0}{W_0} \quad W_0 \neq 0\end{aligned}$$

Proof: Let:

$$f(z) = u(x, y) + iv(x, y) \quad F(z) = U(x, y) + iV(x, y)$$

$$z_0 = x_0 + iy_0 \quad w_0 = u_0 + iv_0 \quad W_0 = U_0 + iV_0$$

$$\underline{\lim_{z \rightarrow z_0} [f(z) + F(z)] = w_0 + W_0}$$

From Theorem 13.2.2:

$$\begin{aligned}f(z) + F(z) &= (u + U) + i(v + V) \\ \implies \lim_{(x,y) \rightarrow (x_0,y_0)} f(z)F(z) &= (u_0 + U_0) + i(v_0 + V_0) = w_0 + W_0\end{aligned}$$

$$\underline{\lim_{z \rightarrow z_0} [f(z)F(z)] = w_0 W_0}$$

From Theorem 13.2.2:

$$\begin{aligned} f(z)F(z) &= (uU - vV) + i(vU + uV) \\ \implies \lim_{(x,y) \rightarrow (x_0,y_0)} f(z)F(z) &= (u_0U_0 - v_0V_0) + i(v_0U_0 + u_0V_0) = w_0W_0 \end{aligned}$$

$$\lim_{z \rightarrow z_0} \frac{f(z)}{F(z)} = \frac{w_0}{W_0} \text{ if } W_0 \neq 0$$

From Theorem 13.2.2:

$$\frac{f(z)}{F(z)} = \frac{u + iv}{U + iV} \implies \lim_{(x,y) \rightarrow (x_0,y_0)} \frac{f(z)}{F(z)} = \frac{u_0 + v_0}{U_0 + iV_0} = \frac{w_0}{W_0}$$

□

Corollary 13.2.3.1:

Let c be a constant, $z, z_0 \in \mathbb{C}$, and $P(z)$ be a polynomial. Then

$$\lim_{z \rightarrow z_0} c = c \qquad \lim_{z \rightarrow z_0} z = z_0 \qquad \lim_{z \rightarrow z_0} z^n = z_0^n \qquad n \in \mathbb{N}$$

$$\lim_{z \rightarrow z_0} P(z) = P(z_0)$$

Observation. It is surprisingly quick that Brown and Churchill went from ϵ - δ proofs straight to proving with limits. This is different to the approach in Sequences of Limits Theorem for Sequences Section by Kenneth A. Ross. [1]. (Section 9.1.1)

Question. It might be possible use a series approach to prove limit theorems for $z \in \mathbb{C}$ by having separate series for x and y (real and imaginary components of z), or a series in the form of $s_n = (x_n, y_n)$. Which would be the proper approach?

13.2.2 Limits of Points at Infinity

Definition 13.2.2: Extended Complex Plane

The complex plane union with the points at infinity:

$$\mathbb{C} \cup \{\pm\infty, \pm i\infty\}$$

Definition 13.2.3: Riemann Sphere

A unit sphere centred at the origin of the complex plane, which is consequently bisected by the complex plane.

Definition 13.2.4: Stereographic Projection

Consider the Riemann Sphere. Let N be the northern point of the sphere (the point on the sphere above the origin of the complex plane) and z be any point in the complex plane. Let l be a line that goes through N and z , then l will intersect the Riemann Sphere. Let P be the point where l intersects the Riemann Sphere. If we let N correspond to the points at infinity, then there is a one-to-one correspondence between points on the sphere and the points on the extended complex plane. This correspondence is called the Stereographic Projection. (Figure 13.1)

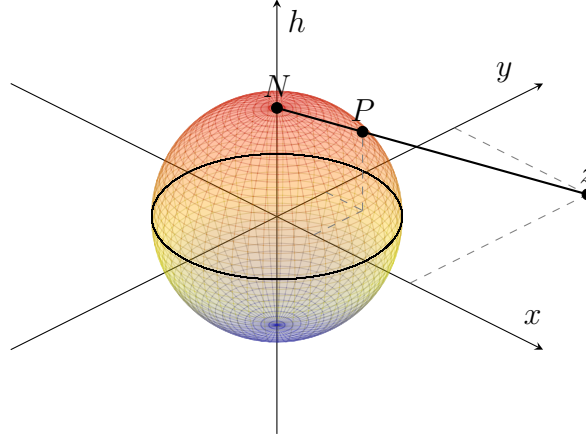


Figure 13.1: Riemann Sphere and Stereographic Projection

The region outside the unit circle enveloped by the Riemann sphere corresponds to the upper hemisphere of the Riemann sphere, with the point N deleted. N corresponds to the points at infinity, since l will be parallel to the complex plane.

Definition 13.2.5: Neighbourhood of ∞

The set: $\{|z| > 1/\epsilon : \epsilon \in \mathbb{R}_{>0}\}$

Note that since ϵ is a small positive number, $|z| > 1/\epsilon$ corresponds to points far away from the unit circle, hence P is close to N .

Note: When referring to any point z , it is referring to a point in the finite plane. Points at infinity will be specifically mentioned.

Theorem 13.2.4:

Let $z_0, w_0 \in \mathbb{C}$, then

$$\lim_{z \rightarrow z_0} \frac{1}{f(z)} = 0 \implies \lim_{z \rightarrow z_0} f(z) = \infty$$

$$\lim_{z \rightarrow 0} f\left(\frac{1}{z}\right) = w_0 \implies \lim_{z \rightarrow \infty} f(z) = w_0$$

$$\lim_{z \rightarrow 0} \frac{1}{f(1/z)} = 0 \implies \lim_{z \rightarrow \infty} f(z) = \infty$$

Proof: $\lim_{z \rightarrow z_0} \frac{1}{f(z)} = 0 \implies \lim_{z \rightarrow z_0} f(z) = \infty$

$$\begin{aligned} \lim_{z \rightarrow z_0} \frac{1}{f(z)} = 0 &\implies \forall \epsilon \exists \delta > 0 \left[|z - z_0| < \delta \implies \left| \frac{1}{f(z)} - 0 \right| < \epsilon \right] \\ &\implies \forall \epsilon \exists \delta > 0 \left[|z - z_0| < \delta \implies |f(z)| > \frac{1}{\epsilon} \right] \\ &\implies \lim_{z \rightarrow z_0} f(z) = \infty \end{aligned}$$

$\lim_{z \rightarrow 0} f\left(\frac{1}{z}\right) = w_0 \implies \lim_{z \rightarrow \infty} f(z) = w_0$

$$\begin{aligned} \lim_{z \rightarrow 0} f\left(\frac{1}{z}\right) = w_0 &\implies \forall \epsilon \exists \delta > 0 \left[|z - 0| < \delta \implies \left| f\left(\frac{1}{z}\right) - w_0 \right| < \epsilon \right] \\ &\implies \forall \epsilon \exists \delta > 0 \left[|z| > \frac{1}{\delta} \implies |f(z) - w_0| < \epsilon \right] \\ &\implies \lim_{z \rightarrow \infty} f(z) = w_0 \end{aligned}$$

$\lim_{z \rightarrow 0} \frac{1}{f(1/z)} = 0 \implies \lim_{z \rightarrow \infty} f(z) = \infty$

$$\begin{aligned} \lim_{z \rightarrow 0} \frac{1}{f(1/z)} = 0 &\implies \forall \epsilon \exists \delta > 0 \left[|z - 0| < \delta \implies \left| \frac{1}{f(1/z)} - 0 \right| < \epsilon \right] \\ &\implies \forall \epsilon \exists \delta > 0 \left[|z| > \frac{1}{\delta} \implies |f(z)| > \frac{1}{\epsilon} \right] \\ &\implies \lim_{z \rightarrow \infty} f(z) = \infty \end{aligned}$$

□

Note: As δ goes to 0, $1/\delta$ goes to ∞ , hence $|z|$ goes to ∞ if $|z| > 1/\delta$.

Observation. As expected, theorem 13.2.4 is consistent if $z \in \mathbb{R}$. (Check: Section 9.1.1).

13.3 Continuity

Definition 13.3.1: Continuous

Let f be a function. We say f is continuous at all point $z_0 \in \mathbb{C}$ if it satisfies the following:

$$\lim_{z \rightarrow z_0} f(z) \text{ exists} \wedge f(z_0) \text{ exists} \wedge \lim_{z \rightarrow z_0} f(z) = f(z_0)$$

Note:

$$\begin{aligned} \lim_{z \rightarrow z_0} f(z) = f(z_0) &\implies \lim_{z \rightarrow z_0} f(z) \text{ exists} \wedge f(z_0) \text{ exists} \\ \forall \epsilon \exists \delta > 0 [|z - z_0| < \delta \implies |f(z) - f(z_0)| < \epsilon] &\iff \lim_{z \rightarrow z_0} f(z) = f(z_0) \end{aligned}$$

Definition 13.3.2: Continuous at a Region

Let f be a function, $R \subset \mathbb{C}$ be a region, and $z \in R$:

$$f \text{ is continuous in } R \iff \forall z \in R (f \text{ is continuous})$$

Theorem 13.3.1:

Let $f(z)$ and $g(z)$ be continuous functions at $z_0 \in \mathbb{C}$. Then the following are also continuous at z_0 :

$$f(z_0) + g(z_0) \quad f(z_0)g(z_0) \quad \frac{f(z_0)}{g(z_0)} \quad g(z_0) \neq 0$$

Proof: Consequence of theorem 13.2.3. □

Corollary 13.3.1.1:

Let $P(z)$ be a polynomial, then $P(z)$ is continuous $\forall z \in \mathbb{C}$. That is $P(z)$ is continuous in the entire plane of \mathbb{C} .

Proof: Consequence of corollary 13.2.3.1. □

Observation. Both theorem 13.3.1 and corollary 13.3.1.1 rely on definition 13.3.1, which state for a function f and point $z_0 \in \mathbb{C}$:

$$\lim_{z \rightarrow z_0} f(z) \text{ exists} \implies f(z) \text{ is continuous at } z_0$$

This is why the proofs cite the results of theorem 13.2.3 and corollary 13.2.3.1.

Theorem 13.3.2:

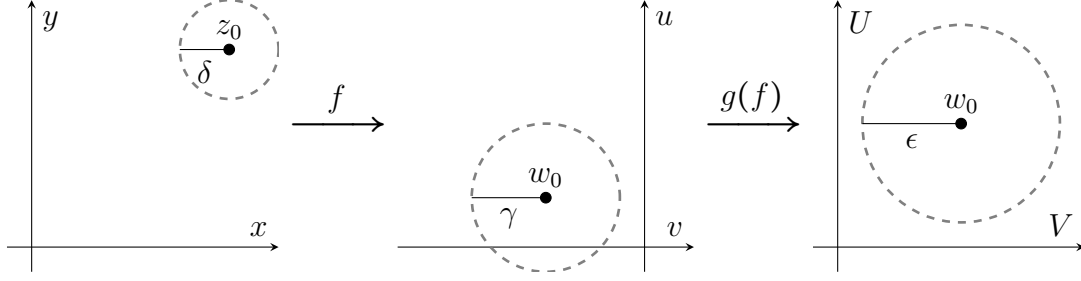
Let $f(z)$ and $g(z)$ be functions.

$$f(z) \text{ and } g(z) \text{ continuous} \implies g(f(z)) \text{ continuous}$$

Proof: Let $f(z) = w$ be defined in the neighbourhood $\forall z [|z - z_0| < \delta]$, and $g(w) = W$ where $\text{dom}(g) = \text{img}(f)$. Suppose that f is continuous at z_0 and g is continuous at $f(z_0)$.

$$\begin{aligned} f \text{ continuous at } z_0 &\iff \forall \gamma \exists \delta > 0 [|z - z_0| < \delta \implies |f(z) - f(z_0)| < \gamma] \\ &\implies \forall \epsilon \exists \gamma > 0 [|f(z) - f(z_0)| < \gamma \implies |g(f(z)) - g(f(z_0))| < \epsilon] \end{aligned}$$

We can always find a small enough δ for γ to satisfy $|g(f(z)) - g(f(z_0))| < \epsilon$. □



Theorem 13.3.3:

Let $f(z)$ be a function and $f(z_0) \neq 0$.

$$f(z_0) \neq 0 \implies \exists \epsilon \forall z [|f(z) - f(z_0)| < \epsilon \implies f(z) \neq 0]$$

That is, if $f(z_0) \neq 0$ then it has a neighbourhood where $f(z) \neq 0$.

Proof: Suppose $f(z)$ is continuous and non-zero at z_0 , and let $\epsilon = |f(z_0)|/2$:

$$\begin{aligned} & \exists z [f(z) = 0] \wedge \forall \epsilon \exists \delta > 0 \left[|z - z_0| < \delta \implies |f(z) - f(z_0)| < \frac{|f(z_0)|}{2} \right] \\ & \implies |f(z_0)| < \frac{|f(z_0)|}{2} \end{aligned} \quad \text{Contradiction!}$$

□

Theorem 13.3.4:

Let $f(z) = u(x, y) + iv(x, y)$ be a function, and $z = x + iy$, $z \in \mathbb{C}$.

$$f \text{ continuous at } z_0 \iff [u \text{ continuous at } z_0] \wedge [v \text{ continuous at } z_0]$$

Proof: Direct consequence of theorem 13.2.2

□

Theorem 13.3.5:

Let f be continuous in a closed and bounded region R , then

$$\forall z \in R, \exists M \in \mathbb{R}_{>0} [|f(z)| \leq M] \wedge |\{z : |f(z)| = M\}| \geq 1$$

That is, for $\forall z \in R$, $|f(z)| \leq M$ and there is at least one point z where $|f(z)| = M$. $f(z)$ is bounded in R .

Proof: Let $f(z) = u(x, y) + iv(x, y)$ be continuous, then

$$\left(|f(z)| = \sqrt{[u(x, y)]^2 + [v(x, y)]^2} \text{ is continuous in } R \right) \wedge (\exists M \in \mathbb{R}_{>0} [|f(z)| < M])$$

□

13.3.1 Exercises

Example 13.3.1 *Prove:*

$$\lim_{z \rightarrow z_0} f(z) = w_0 \implies \lim_{z \rightarrow z_0} |f(z)| = |w_0|$$

Note: $||f(z_0)| - |w_0|| \leq |f(z) - w_0|$

Proof: Use definition of limit, then plug and chug. □

Example 13.3.2 *Prove: Limits involving points at infinity are unique.*

Proof: Suppose that limit of the point at infinity is not unique, that is there is two neighbourhoods of infinity. Using the definition of the limit, we will arrive at a contradiction where the two neighbourhoods are the same. □

Example 13.3.3 *Prove:*

$$S \text{ is unbounded} \iff \forall \epsilon \exists z \left[z \in S : |z| > \frac{1}{\epsilon} \right]$$

That is, S is unbounded \iff every neighbourhood of the point at infinity contains at least one point in S

Proof: Proof Sketch: Recall the Riemann Sphere. (Definition 13.2.3). The set $|z| > 1/\epsilon$ corresponds to the points close to N , which is the neighbourhood of the point at infinity. If we let $\gamma = 2\epsilon$, $\exists z$ where $|z| > 1/\gamma$ holds. This along with $z \in \mathbb{C}$ (which is S in our case), implies the direction \Leftarrow is true. That is, we can still find elements in S as we shrink the circle around N .

S is unbounded implies that for all circle with radius R centred at the origin there is at least one element of $s \in S$ where $|s| > R$. Suppose for contradiction that there is a neighbourhood of the point at infinity that does not contain any points in S . We will arrive at a contradiction, where there is $M \in \mathbb{R}_{>0}$ such that $\forall s \in S [|s| < M]$. Thus S is bounded, a contradiction. This implies that the direction \implies is true. □

13.4 Differentiation

Definition 13.4.1: Derivative

Let f be a function where $|z - z_0| < \epsilon$ and $z \in \text{dom}(f)$. Then the derivative of f at point z_0 :

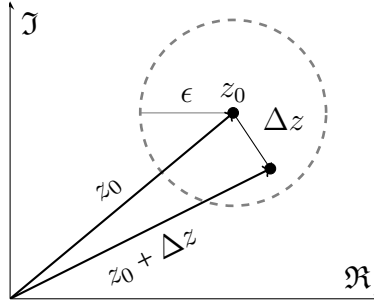
$$f'(z_0) = \lim_{z \rightarrow z_0} \frac{f(z) - f(z_0)}{z - z_0}$$

Definition 13.4.2: Differentiable

A function f is differentiable at $z_0 \in \mathbb{C}$ if $f'(z_0)$ exists.

If we let $\Delta z = z - z_0$ where $z \neq z_0$:

$$f'(z_0) = \lim_{\Delta z \rightarrow 0} \frac{f(z_0 + \Delta z) - f(z_0)}{\Delta z}$$



There's another notation by letting $\Delta w = f(z + \Delta z) - f(z)$:

$$f'(z) = \frac{dw}{dz} = \lim_{\Delta z \rightarrow 0} \frac{\Delta w}{\Delta z}$$

Example 13.4.1 Let $f(z) = \bar{z}$:

$$\frac{\Delta w}{\Delta z} = \frac{\overline{z + \Delta z} - \bar{z}}{\Delta z} = \frac{\bar{z} + \overline{\Delta z} - \bar{z}}{\Delta z} = \frac{\overline{\Delta z}}{\Delta z}$$

Consider $\Delta z = (\Delta x, \Delta y) \rightarrow (0, 0)$. If we move on the real axis, that is $(\Delta x, 0)$:

$$\overline{\Delta z} = \overline{\Delta x + i0} = \Delta x - i0 = \Delta x + i0 = \Delta z \implies \frac{\Delta w}{\Delta z} = \frac{\overline{\Delta z}}{\Delta z} = \frac{\Delta z}{\Delta z} = 1$$

If we move on the imaginary axis, that is $(0, \Delta y)$:

$$\overline{\Delta z} = \overline{0 + i\Delta y} = 0 - i\Delta y = -\Delta z \implies \frac{\Delta w}{\Delta z} = \frac{\overline{\Delta z}}{\Delta y} = \frac{-\Delta z}{\Delta z} = -1$$

Limits are unique, so the limit of dw/dz does not exist anywhere.

Example 13.4.2 Consider $f(z) = |z|^2$:

$$\begin{aligned} \frac{\Delta w}{\Delta z} &= \frac{|z + \Delta z|^2 - |z|^2}{\Delta z} = \frac{(z + \Delta z)(\overline{z + \Delta z}) - z\bar{z}}{\Delta z} \\ &= \frac{(z + \Delta z)(\bar{z} + \overline{\Delta z}) - z\bar{z}}{\Delta z} = \frac{z\bar{z} + \Delta z\bar{z} + \overline{\Delta z}z + \overline{\Delta z}\Delta z - z\bar{z}}{\Delta z} = \bar{z} + \overline{\Delta z} + z \frac{\overline{\Delta z}}{\Delta z} \end{aligned}$$

As in the previous example, as $(\Delta x, \Delta y) \rightarrow (0, 0)$:

$$\overline{\Delta z} = \Delta z$$

From the real axis

$$\overline{\Delta z} = -\Delta z$$

From the imaginary axis

Thus

$$\begin{aligned}\frac{\Delta w}{\Delta z} &= \bar{z} + \Delta z + z & \Delta z &= (\Delta x, 0) \\ \frac{\Delta w}{\Delta z} &= \bar{z} - \Delta z - z & \Delta z &= (0, \Delta y)\end{aligned}$$

Therefore, by uniqueness of limits as $\Delta z \rightarrow 0$:

$$\lim_{\Delta z \rightarrow 0} (\bar{z} + \Delta z + z) = \lim_{\Delta z \rightarrow 0} (\bar{z} - \Delta z - z) \implies z = -z \implies z = 0$$

Hence, dw/dz does not exist for $z \neq 0$. We can also see that:

$$\frac{\Delta w}{\Delta z} = \bar{z} + \overline{\Delta z} + z \frac{\overline{\Delta z}}{\Delta z} = \overline{\Delta z} \quad z = 0$$

Thus, dw/dz only exists at $z = 0$:

$$\left. \frac{dw}{dz} \right|_{z=0} = 0$$

Remark. The following are facts:

- (1) A function $f(z)$ can be differentiable at a point z_0 , but nowhere else in the neighbourhood of z_0 .
- (2) $f(z) = |z|^2 \implies u(x, y) = x^2 + y^2 \wedge v(x, y) = 0$, hence $u(x, y)$ and $v(x, y)$ can have continuous partial derivatives of all orders at a point z_0 , even though f may not be differentiable at z_0 .
- (3) $f(z)$ differentiable at $z_0 \implies f(z)$ continuous at z_0

Proof: Assume $f'(z_0)$ exists:

$$\begin{aligned}\lim_{z \rightarrow z_0} [f(z) - f(z_0)] &= \lim_{z \rightarrow z_0} \frac{f(z) - f(z_0)}{z - z_0} \lim_{z \rightarrow z_0} (z - z_0) = f'(z_0) \cdot 0 = 0 \\ &\implies \lim_{z \rightarrow z_0} f(z) = f(z_0)\end{aligned}$$

So, f is differentiable at $z_0 \implies f$ is continuous at z_0 . □

Note: Continuity of a function at $z_0 \in \mathbb{C} \not\Rightarrow$ existence of derivative at point z_0 .

Ex: $f(z) = |z|^2$ is continuous everywhere in \mathbb{C} for $z_0 \neq 0$, but $f'(z_0)$ does not exist at z_0 .

13.4.1 Differentiation Rules

Definition of derivative in \mathbb{C} (definition 13.4.1) is the same of that in \mathbb{R} , so rules remain the same.

Let $c \in \mathbb{C}$ be a constant and functions f and g be differentiable at point z . Then

$$\frac{d}{dz}c = 0 \quad \frac{d}{dz}z = 1 \quad \frac{d}{dz}[cf(z)] = cf'(z) \quad \frac{d}{dz}z^n = nz^{n-1} \quad n \in \mathbb{Z} \setminus \{0\}$$

Let functions f and g be differentiable at point z . Then

$$\frac{d}{dz}[f(z) + g(z)] = f'(z) + g'(z) \quad \frac{d}{dz}[f(z)g(z)] = f(z)g'(z) + f'(z)g(z)$$

$$\frac{d}{dz} \left[\frac{f(z)}{g(z)} \right] = \frac{g(z)f'(z) - f(z)g'(z)}{[g(z)]^2}$$

Proof: Deriving: $\frac{d}{dz}[f(z)g(z)] = f(z)g'(z) + f'(z)g(z)$

Let $w = f(z)g(z)$:

$$\begin{aligned} \Delta w &= f(z + \Delta z)g(z + \Delta z) - f(z)g(z) \\ &= f(z)[g(z + \Delta z) - g(z)] + [f(z + \Delta z) - f(z)]g(z + \Delta z) \end{aligned}$$

Thus

$$\frac{\Delta w}{\Delta z} = f(z) \frac{g(z + \Delta z) - g(z)}{\Delta z} + \frac{f(z + \Delta z) - f(z)}{\Delta z} g(z + \Delta z)$$

Hence

$$\frac{dw}{dz} = \lim_{\Delta z \rightarrow 0} \frac{\Delta w}{\Delta z} = f(z)g'(z) + f'(z)g(z)$$

□

Theorem 13.4.1: Chain Rule for Composite Functions

Let function f be differentiable at z_0 and function g be differentiable at $f(z_0)$. Then $F(z) = g[f(z)]$ is differentiable at z_0 .

$$F'(z_0) = g'[f(z_0)]f'(z_0)$$

Proof: Suppose f is differentiable at z_0 . Let $w_0 = f(z_0)$ and assume that $g'(w_0)$ exists. Then

$$\forall w \exists \epsilon [|w - w_0| < \epsilon \implies \Phi(w_0) = 0]$$

Where

$$\Phi(w) = \frac{g(w) - g(w_0)}{w - w_0} - g'(w_0) \quad w \neq w_0$$

Note: $\lim_{w \rightarrow w_0} \Phi(w) = 0$, so Φ is continuous at w_0 . Then

$$g(w) - g(w_0) = [g'(w_0) + \Phi(w)](w - w_0) \quad |w - w_0| < \epsilon$$

Note: This is valid for $w = w_0$.

$$\begin{aligned} f'(z_0) \text{ exists} &\implies f \text{ continuous at } z_0 \\ &\implies \forall \epsilon \exists \delta > 0 [|z - z_0| < \delta \implies |w - w_0| < \epsilon] \end{aligned}$$

Hence, we can replace w by $f(z)$ when $|z - z_0| < \delta$. Subbing $w = f(z)$ and $w_0 = f(z_0)$:

$$\frac{g[f(z)] - g[f(z_0)]}{z - z_0} = \{g'[f(z_0)] + \Phi[f(z)]\} \frac{f(z) - f(z_0)}{z - z_0} \quad 0 < |z - z_0| < \delta, \quad z \neq z_0$$

Then

$$(f \text{ continuous at } z_0) \wedge (\Phi \text{ continuous at } w_0 = f(z_0)) \implies \Phi[f(z)] \text{ continuous at } z_0$$

$$\Phi(w_0) = 0 \implies \lim_{z \rightarrow z_0} \Phi[f(z)] = 0$$

Thus

$$\begin{aligned} \lim_{z \rightarrow z_0} \frac{g[f(z)] - g[f(z_0)]}{z - z_0} &= \lim_{z \rightarrow z_0} \{g'[f(z_0)] + \Phi[f(z)]\} \frac{f(z) - f(z_0)}{z - z_0} \\ &= g'[f(z_0)] f'(z_0) \end{aligned}$$

We then get

$$F'(z_0) = g'[f(z_0)] f'(z_0)$$

□

Alternatively, if we let $w = f(z)$ and $W = F(z)$, then the Chain Rule becomes:

$$\frac{dW}{dz} = \frac{dW}{dw} \frac{dw}{dz}$$

Note: Although this looks like a fraction, it is not a fraction and should not be treated as such! (Logical inconsistency when infinitesimals when viewed as ratios.)

13.5 Cauchy-Riemann Equations

Theorem 13.5.1: Cauchy-Riemann Equations (Cartesian)

Let $f(z) = u(x, y) + iv(x, y)$. If $f'(z)$ exists at a point $z_0 = x_0 + iy_0$, then $u'(x_0, y_0)$ and $v'(x_0, y_0)$ exist and satisfy Cauchy-Riemann equations:

$$u_x = v_y \qquad u_y = -v_x$$

Also, as a result of evaluating $f'(z)$ from the horizontal and vertical direction:

$$f'(z_0) = [u_x + iv_x] \Big|_{(x_0, y_0)} = [v_y - iu_y] \Big|_{(x_0, y_0)}$$

Proof: Let $f(z) = u(x, y) + iv(x, y)$, and suppose $f'(z)$ exists at z_0 . Then

$$z_0 = x_0 + iy_0 \quad \Delta z = \Delta x + i\Delta y \quad \Delta w = f(z_0 + \Delta z) - f(z_0)$$

So that

$$\Delta w = [u(x_0 + \Delta x, y_0 + \Delta y) + iv(x_0 + \Delta x, y_0 + \Delta y)] - [u(x_0, y_0) + iv(x_0, y_0)]$$

Therefore

$$\frac{\Delta w}{\Delta z} = \frac{u(x_0 + \Delta x, y_0 + \Delta y) - u(x_0, y_0)}{\Delta x + i\Delta y} + i \frac{v(x_0 + \Delta x, y_0 + \Delta y) - v(x_0, y_0)}{\Delta x + i\Delta y}$$

Note: This equation remains valid as $(\Delta x, \Delta y) \rightarrow (0, 0)$.

Horizontal Approach:

Let $(\Delta x, 0) \rightarrow (0, 0)$ in the horizontal direction, then

$$\begin{aligned} f'(z_0) &= \lim_{\Delta x \rightarrow 0} \frac{u(x_0 + \Delta x, y_0) - u(x_0, y_0)}{\Delta x} + i \lim_{\Delta x \rightarrow 0} \frac{v(x_0 + \Delta x, y_0) - v(x_0, y_0)}{\Delta x} \\ &\implies f'(z_0) = u_x(x_0, y_0) + iv_x(x_0, y_0) \end{aligned}$$

Vertical Approach:

Let $(0, \Delta y) \rightarrow (0, 0)$ in the vertical direction, then

$$\begin{aligned} f'(z_0) &= \lim_{\Delta y \rightarrow 0} \frac{u(x_0, y_0 + \Delta y) - u(x_0, y_0)}{i\Delta y} + i \lim_{\Delta y \rightarrow 0} \frac{v(x_0, y_0 + \Delta y) - v(x_0, y_0)}{i\Delta y} \\ &= -i \lim_{\Delta y \rightarrow 0} \frac{u(x_0, y_0 + \Delta y) - u(x_0, y_0)}{\Delta y} + \lim_{\Delta y \rightarrow 0} \frac{v(x_0, y_0 + \Delta y) - v(x_0, y_0)}{\Delta y} \\ &\implies f'(z_0) = v_y(x_0, y_0) - iu_y(x_0, y_0) \end{aligned}$$

Putting it together:

For $f'(z)$ to exist at z_0 , $f'(z_0)$ from the horizontal approach must equal that of the vertical approach. By equating the real and imaginary parts:

$$\begin{aligned} u_x(x_0, y_0) + iv_x(x_0, y_0) &= v_y(x_0, y_0) - iu_y(x_0, y_0) \\ \implies (u_x = v_y) \wedge (u_y = -v_x) \end{aligned}$$

□

Theorem 13.5.2: Cauchy-Riemann Equations (Polar)

Let $f(z) = u(r, \theta) + iv(r, \theta)$ be defined in some neighbourhood ϵ of $z_0 = r_0 e^{i\theta_0}$, $z_0 \neq 0$. If the first order partials derivatives of u and v with respect to r and θ exist and satisfy the polar form of the Cauchy-Riemann equations:

$$ru_r = v_\theta \quad u_\theta = -rv_r$$

Then $f'(z_0)$ exists:

$$f'(z_0) = e^{-i\theta} (u_r + iv_r) \Big|_{(r_0, \theta_0)} = \frac{-i}{z_0} (u_\theta + iv_\theta) \Big|_{(r_0, \theta_0)}$$

Proof: Let $f(z) = u(r, \theta) + iv(r, \theta)$. Suppose that the first order partial derivatives of u and v exists in some neighbourhood ϵ of z_0 and is continuous at z_0 . By differentiating u with respect to x and y :

$$\frac{\partial u}{\partial r} = \frac{\partial u}{\partial x} \frac{\partial x}{\partial r} + \frac{\partial u}{\partial y} \frac{\partial y}{\partial r} \qquad \frac{\partial u}{\partial \theta} = \frac{\partial u}{\partial x} \frac{\partial x}{\partial \theta} + \frac{\partial u}{\partial y} \frac{\partial y}{\partial \theta}$$

Likewise for v . As $x = r \cos \theta$ and $y = r \sin \theta$:

$$\begin{aligned} u_r &= u_x \cos \theta + u_y \sin \theta & u_\theta &= -u_x r \sin \theta + u_y r \cos \theta \\ v_r &= v_x \cos \theta + v_y \sin \theta & v_\theta &= -v_x r \sin \theta + v_y r \cos \theta \end{aligned}$$

From theorem 13.5.1 we have:

$$u_x = v_y \qquad u_y = -v_x$$

Subbing the Cauchy-Riemann equations into v_r and v_θ :

$$\begin{aligned} u_r &= u_x \cos \theta + u_y \sin \theta & u_\theta &= -u_x r \sin \theta + u_y r \cos \theta \\ v_r &= -u_y \cos \theta + u_x \sin \theta & v_\theta &= u_y r \sin \theta + u_x r \cos \theta \end{aligned}$$

We can see that:

$$ru_r = v_\theta \qquad u_\theta = -rv_r$$

Which are the Cauchy Riemann equations in polar form. Let's verify it without relying on the Cauchy-Riemann equations in Cartesian form:

Recall:

$$\begin{aligned} u_r &= u_x \cos \theta + u_y \sin \theta & u_\theta &= -u_x r \sin \theta + u_y r \cos \theta \\ v_r &= v_x \cos \theta + v_y \sin \theta & v_\theta &= -v_x r \sin \theta + v_y r \cos \theta \end{aligned}$$

Writing u_r and v_r in matrix notation:

$$\begin{bmatrix} u_r \\ u_\theta \end{bmatrix} = \begin{bmatrix} \cos \theta & \sin \theta \\ -r \sin \theta & r \cos \theta \end{bmatrix} \begin{bmatrix} u_x \\ u_y \end{bmatrix}$$

Solving for u_x and u_y :

$$\begin{aligned} \begin{bmatrix} u_x \\ u_y \end{bmatrix} &= \begin{bmatrix} \cos \theta & \sin \theta \\ -r \sin \theta & r \cos \theta \end{bmatrix}^{-1} \begin{bmatrix} u_r \\ u_\theta \end{bmatrix} \\ &= \frac{1}{r \cos^2 \theta + r \sin^2 \theta} \begin{bmatrix} r \cos \theta & -\sin \theta \\ -r \sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} u_r \\ u_\theta \end{bmatrix} \quad \begin{bmatrix} a & b \\ c & d \end{bmatrix}^{-1} = \frac{1}{ad - cb} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix} \\ &= \frac{1}{r} \begin{bmatrix} r \cos \theta & -\sin \theta \\ r \sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} u_r \\ u_\theta \end{bmatrix} \end{aligned}$$

It is clear that for u_x and u_y , and likewise for v_x and v_y :

$$u_x = u_r \cos \theta - \frac{1}{r} u_\theta \sin \theta \quad u_y = u_r \sin \theta + \frac{1}{r} u_\theta \cos \theta \quad (13.5)$$

$$v_x = v_r \cos \theta - \frac{1}{r} v_\theta \sin \theta \quad v_y = v_r \sin \theta + \frac{1}{r} v_\theta \cos \theta \quad (13.6)$$

Using the Cauchy-Riemann equations $u_x = v_y$ and $u_y = -v_x$, we see:

$$\begin{aligned} u_r \cos \theta - \frac{1}{r} u_\theta \sin \theta &= v_r \sin \theta + \frac{1}{r} v_\theta \cos \theta \\ u_r \sin \theta + \frac{1}{r} u_\theta \cos \theta &= -v_r \cos \theta + \frac{1}{r} v_\theta \sin \theta \end{aligned}$$

Clearly, the equations are equal only if

$$ru_r = v_\theta \quad u_\theta = -rv_r$$

Which are the polar forms of the Cauchy-Riemann equations.

Show $f'(z_0) = e^{-i\theta}(u_r + iv_r)$:

Recall from theorem 13.5.1:

$$f'(z_0) = u_x + iv_y$$

Using eq. (13.5) and eq. (13.6) from before and substituting them into $f'(z_0)$:

$$\begin{aligned} f'(z_0) &= \left(u_r \cos \theta - \frac{1}{r} u_\theta \sin \theta + iv_r \cos \theta - \frac{i}{r} v_\theta \sin \theta \right) \Big|_{(r_0, \theta_0)} \\ &= (u_r \cos \theta + v_r \sin \theta + iv_r \cos \theta - iu_r \sin \theta) \Big|_{(r_0, \theta_0)} \\ &= [u_r(\cos \theta - i \sin \theta) + v_r(\sin \theta + i \cos \theta)] \Big|_{(r_0, \theta_0)} \\ &= [u_r(\cos \theta - i \sin \theta) + iv_r(\cos \theta - i \sin \theta)] \Big|_{(r_0, \theta_0)} \\ &= \left[\left(\frac{e^{i\theta} + e^{-i\theta}}{2} - \frac{e^{i\theta} - e^{-i\theta}}{2} \right) (u_r + iv_r) \right] \Big|_{(r_0, \theta_0)} \\ &= e^{-i\theta}(u_r + iv_r) \Big|_{(r_0, \theta_0)} \\ &= \frac{-i}{re^{i\theta}}(u_\theta + iv_\theta) \Big|_{(r_0, \theta_0)} = \frac{-i}{z_0}(u_\theta + iv_\theta) \Big|_{(r_0, \theta_0)} \quad (ru_r = v_\theta) \wedge (u_\theta = -rv_r) \end{aligned}$$

Thus

$$f'(z_0) = e^{-i\theta}(u_r + iv_r) \Big|_{(r_0, \theta_0)} = \frac{-i}{z_0}(u_\theta + iv_\theta) \Big|_{(r_0, \theta_0)}$$

□

Question. When comparing the Cartesian form to the polar form of the Cauchy-Riemann equations:

$$\begin{aligned} f'(z_0) \text{ exists} &\implies \forall z_0 [(u_x = v_y) \wedge (u_y = -v_x)] \\ (z_0 \neq 0) \wedge \forall z_0 [(ru_r = v_\theta) \wedge (u_\theta = -rv_r)] &\iff f'(z_0) \text{ exists} \end{aligned}$$

Should the Cartesian one also be \iff instead of \implies ? Yes, but only under the condition $z_0 \neq 0$ as we will see in example 13.5.3.

Example 13.5.1 (Solving the $f'(z)$ using the partial derivative with respect to one variable)
Recall in theorem 13.5.1:

$$f'(z_0) = [u_x + iv_x] \Big|_{(x_0, y_0)} = [v_y - iu_y] \Big|_{(x_0, y_0)}$$

This implies we can solve $df(z)/dz$ by taking the partial of $f(z)$ with respect to x or y . Consider $f(z) = z^2$:

$$f(z) = z^2 = x^2 - y^2 + i2xy$$

We then have:

$$u(x, y) = x^2 - y^2 \qquad v(x, y) = 2xy$$

Hence

$$u_x = 2x = v_y \qquad u_y = -2y = -v_x$$

Thus

$$f'(z) = 2x + i2y = 2(x + iy) = 2z$$

Example 13.5.2 (Using Cauchy-Riemann equations to find where $f(z)$ is not differentiable)
Using the contrapositive of $f'(z_0) \text{ exists} \implies \exists u' \exists v' [(u_x = v_y) \wedge (u_y = -v_x)]:$

$$\exists z_0 [(u_x \neq v_y) \vee (u_y \neq -v_x)] \implies f(z) \text{ not differentiable at } z_0$$

Consider $f(z) = |z|^2$:

$$u(x, y) = x^2 + y^2 \qquad v(x, y) = 0$$

By Cauchy-Riemann:

$$2x = 0 \qquad 2y = 0$$

Therefore, $f'(z)$ only exists at $(0, 0)$ and does not exist elsewhere.

Note: Theorem 13.5.1 does not guarantee the existence of $f'(z)$ at z_0 .

Example 13.5.3 ($f(z)$ satisfy Cauchy-Riemann equations at $(0,0)$, but $f'(0)$ does not exist)
Consider

$$f(z) = \begin{cases} \bar{z}^2/z & z \neq 0 \\ 0 & z = 0 \end{cases}$$

Then

$$u(x, y) = \frac{x^3 - 3xy^2}{x^2 + y^2} \quad v(x, y) = \frac{y^3 - 3x^2y}{x^2 + y^2} \quad (x, y) \neq (0, 0)$$

Checking differentiability at $(0,0)$, note $u(0,0) = 0$ and $v(0,0) = 0$:

$$\begin{aligned} u_x(0,0) &= \lim_{\Delta x \rightarrow 0} \frac{u(0 + \Delta x, 0) - u(0,0)}{\Delta x} = \lim_{\Delta x \rightarrow 0} \frac{\Delta x}{\Delta x} = 1 \\ v_y(0,0) &= \lim_{\Delta y \rightarrow 0} \frac{v(0, 0 + \Delta y) - v(0,0)}{\Delta y} = \lim_{\Delta y \rightarrow 0} \frac{\Delta y}{\Delta y} = 1 \\ u_y(0,0) &= \lim_{\Delta y \rightarrow 0} \frac{u(0, 0 + \Delta y) - u(0,0)}{\Delta y} = \lim_{\Delta y \rightarrow 0} \frac{0/(\Delta y)^2}{\Delta y} = 0 \\ v_x(0,0) &= \lim_{\Delta x \rightarrow 0} \frac{v(0 + \Delta x, 0) - v(0,0)}{\Delta x} = \lim_{\Delta x \rightarrow 0} \frac{0/(\Delta x)^2}{\Delta x} = 0 \end{aligned}$$

We can see that the Cauchy-Riemann equations are satisfied:

$$u_x = v_y = 1 \quad u_y = -v_x = 0$$

However, $f'(0)$ does not exist: (Brown and Churchill - Complex Variables and Applications, Section 20, Exercise 9 [2])

Let $\Delta w = f(z + \Delta z) - f(z)$. We need to show for all nonzero points on the real and imaginary axis, $\Delta w/\Delta z = -1$, but for all nonzero points on the line $\Delta x = \Delta y$, $\Delta w/\Delta z = 1$. Hence, a contradiction, so $f'(0)$ does not exist.

$$\frac{\Delta w}{\Delta z} = \frac{f(z + \Delta z) - f(z)}{\Delta z} = \frac{u(x + \Delta x, y + \Delta y) + v(x + \Delta x, y + \Delta y)}{\Delta x + \Delta y} - \frac{u(x, y) + v(x, y)}{\Delta x + \Delta y}$$

Along the real axis:

Evaluating along $(\Delta x, 0) \rightarrow (0, 0)$.

$$\begin{aligned} \lim_{(\Delta x, 0) \rightarrow (0, 0)} \frac{\Delta w}{\Delta z} &= \frac{u(\Delta x, 0) + v(\Delta x, 0)}{\Delta x} - \frac{u(0, 0) + v(0, 0)}{\Delta x} \\ &= \frac{1}{\Delta x} \left[\frac{(\Delta x)^3}{(\Delta x)^2} + \frac{0}{(\Delta x)^2} \right] - 0 = \frac{\Delta x}{\Delta x} = 1 \end{aligned}$$

Along the imaginary axis:

Evaluating along $(0, \Delta y) \rightarrow (0, 0)$.

$$\begin{aligned}\lim_{(0, \Delta y) \rightarrow (0, 0)} \frac{\Delta w}{\Delta z} &= \frac{u(0, \Delta y) + v(0, \Delta y)}{\Delta y} - \frac{u(0, 0) + v(0, 0)}{\Delta y} \\ &= \frac{1}{\Delta y} \left[\frac{0}{(\Delta y)^2} + \frac{(\Delta y)^3}{(\Delta y)^2} \right] - 0 = \frac{\Delta y}{\Delta y} = 1\end{aligned}$$

Along the axis $\Delta x = \Delta y$:

Evaluating along $(\Delta x, \Delta x) \rightarrow (0, 0)$.

$$\begin{aligned}\lim_{(\Delta x, \Delta x) \rightarrow (0, 0)} \frac{\Delta w}{\Delta z} &= \frac{u(\Delta x, \Delta x)}{\Delta x + \Delta x} - \frac{u(0, 0) + v(0, 0)}{\Delta x + \Delta x} \\ &= \frac{1}{2\Delta x} \left[\frac{(\Delta x)^3 - 3(\Delta x)^3}{2(\Delta x)^2} + \frac{(\Delta x)^3 - 3(\Delta x)^3}{2(\Delta x)^2} \right] \\ &= \frac{1}{2\Delta x} \left[-\frac{2(\Delta x)^3}{2(\Delta x)^2} - \frac{2(\Delta x)^3}{2(\Delta x)^2} \right] = \frac{1}{2\Delta x} [-\Delta x - \Delta x] = -\frac{2\Delta x}{2\Delta x} = -1\end{aligned}$$

As we can see, the limits are not unique regardless of the path we take to approach $(0, 0)$, hence $f'(0)$ does not exist. Therefore, an equation can satisfy the Cauchy-Riemann equations at $0, 0$, yet have a derivative that does not exist. The Cauchy-Riemann equations does not guarantee differentiability at $z_0 = 0$.

Example 13.5.4 (Any branch of $f(z) = z^{1/2}$ is differentiable everywhere in domain of definition) Let

$$f(z) = z^{1/2} = \sqrt{r}e^{i\theta} \quad r > 0, \quad \alpha < \theta < \alpha + 2\pi$$

Hence

$$u(r, \theta) = \sqrt{r} \cos\left(\frac{\theta}{2}\right) \quad v(r, \theta) = \sqrt{r} \sin\left(\frac{\theta}{2}\right)$$

By Cauchy-Riemann:

$$ru_r = \frac{\sqrt{r}}{2} \cos\left(\frac{\theta}{2}\right) = v_\theta \quad u_\theta = -\frac{\sqrt{r}}{2} \sin\left(\frac{\theta}{2}\right) = -rv_r$$

Thus, the derivative exists wherever $f(z)$ is defined. Also, by theorem 13.5.2:

$$\begin{aligned}f'(z) &= e^{i\theta}(u_r + iv_r) \Big|_{(r_0, \theta_0)} \\ &= e^{-i\theta} \left[\frac{1}{2\sqrt{r}} \cos\left(\frac{\theta}{2}\right) + i \frac{1}{2\sqrt{r}} \sin\left(\frac{\theta}{2}\right) \right] = \frac{1}{2\sqrt{r}} e^{-i\theta} \left[\cos\left(\frac{\theta}{2}\right) + i \sin\left(\frac{\theta}{2}\right) \right] \\ &= \frac{1}{2\sqrt{r}e^{i\theta/2}} = \frac{1}{2f(z)} = \frac{1}{2} z^{-1/2}\end{aligned}$$

13.5.1 Complex Form of the Cauchy-Riemann Equations

Theorem 13.5.3: Cauchy-Riemann Equation (Complex Form)

Let $f(z) = u(x, y) + iv(x, y)$. If the first order partial derivatives of u and v with respect to x and y exists and satisfy the Cauchy-Riemann equations. Then

$$\frac{\partial}{\partial \bar{z}} f(z) = 0$$

Proof: Recall:

$$x = \frac{z + \bar{z}}{2} \qquad y = \frac{z - \bar{z}}{2i}$$

Let F be a real valued function, that is $x, y \in \mathbb{R}$. Then

$$\frac{\partial F}{\partial \bar{z}} = \frac{\partial F}{\partial x} \frac{\partial x}{\partial \bar{z}} + \frac{\partial F}{\partial y} \frac{\partial y}{\partial \bar{z}}$$

Substituting $\frac{\partial x}{\partial \bar{z}} = 1/2$ and $\frac{\partial y}{\partial \bar{z}} = i/2$:

$$\frac{\partial F}{\partial \bar{z}} = \frac{1}{2} \left(\frac{\partial F}{\partial x} + i \frac{\partial F}{\partial y} \right)$$

Define the operator:

$$\frac{\partial}{\partial \bar{z}} = \frac{1}{2} \left(\frac{\partial}{\partial x} + i \frac{\partial}{\partial y} \right)$$

Then

$$\begin{aligned} \frac{\partial f}{\partial \bar{z}} &= \frac{1}{2} \left(\frac{\partial f}{\partial x} + i \frac{\partial f}{\partial y} \right) = \frac{1}{2} \left(\frac{\partial u}{\partial x} + i \frac{\partial v}{\partial x} + i \frac{\partial u}{\partial y} - \frac{\partial v}{\partial y} \right) \\ &= \frac{1}{2} [(u_x - v_y) + i(u_y + v_x)] \end{aligned}$$

We can see that if $\frac{\partial f}{\partial \bar{z}}$ satisfies the Cauchy-Riemann equations (theorem 13.5.1):

$$\frac{\partial}{\partial \bar{z}} f(z) = 0 \qquad \frac{\partial}{\partial x} f = -i \frac{\partial f}{\partial y} \implies i \frac{\partial}{\partial x} f = \frac{\partial f}{\partial y}$$

□

13.5.2 Conditions for Differentiability

Chapter 14

Conformal Mapping

Part V

Ordinary Differential Equations

Part VI

Nonlinear Dynamics

Part VII

Partial Differential Equations

Calculus of Variations

Part VIII

Integral Equations

Part IX

Linear Algebra

Chapter 15

Markov Chains

Part X

Tensors

Part XI

Riemann Geometry

Part XII

Abstract Algebra

Chapter 16

Groups

Chapter 17

Rings

17.1 Ideals

Chapter 18

Integral Domains

Chapter 19

GCD Domains

Chapter 20

Unique Factorization Domains

Chapter 21

Principal Ideal Domains

Chapter 22

Fields

Part XIII

Galois Theory

Part XIV

Lie Theory

Chapter 23

Lie Groups

Chapter 24

Lie Algebra

Part XV

C-Star Algebra

Part XVI

Set Theory

Part XVII

Model Theory

Part XVIII

Statistics

Part XIX

Tips and Tricks

Chapter 25

Integration Techniques

25.1 DI Method (Integration Table)

25.2 Feynman Integration

Part XX

Index

Part XXI

Bibliography

Bibliography

- [1] Kenneth A. Ross. *Elementary Analysis*. Springer, 2 edition, 2013.
- [2] James Ward Brown and Ruel V. Churchill. *Complex Variables and Applications*. McGraw-Hill Education, 9 edition, 2014.
- [3] A. David Wunsch. *Complex Variables with Applications*. Pearson, 3 edition, 2005.