Econ C103: Game Theory and Networks Module I (Game Theory): Lecture 7

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Readings:

- Osborne (2004) chapter 5
- Osborne and Rubinstein (1994) chapters 6.1-6.4

Extensive games with perfect information

Nash equilibrium shortcomings (include):

- NE ignore timing / sequential structure in players' decisions.
- NE is a "weak" notion: many games yield multiple MNE.

Adding sequential structure to the game provides additional information which can be used to refine the set of MNE...

Extensive games with perfect information: definition

Definition (Extensive form game)

An extensive game with perfect information is defined as a quadruplet $\langle N, H, P, \{u_i\}_{i \in N} \rangle$.

- $N = \{1, ..., n\}$: players,
- H: (finite or infinite) set of sequences ("histories"),
- P: player function, $P: H \setminus Z \mapsto N$, where player P(h) takes action after history $h \in H \setminus Z$ (terminal histories $Z \subset H$ defined below).
- $u_i(h)$: i's (vNM) utility from outcome $h \in Z$ (defined below).

Histories H must satisfy:

- $\emptyset \in H$ (i.e. the beginning of the game is the history \emptyset),
- For any $(a^k)_{k=1}^K \in H$, each $(a^k)_{k=1}^J \in H$ for 0 < J < K,
- If $(a^k)_{k=1}^{\infty}$ satisfies $(a^k)_{k=1}^K \in H$ for all $K \in \mathbb{Z}$, then $(a^k)_{k=1}^{\infty} \in Z$.

Terminal histories Z (these are "outcomes" of the game) are given by:

$$Z \equiv \{(a^k)_{k=1}^K \in H : (a^k)_{k=1}^L \in H, L \ge K \Rightarrow L = K\}.$$

Extensive games with perfect information: strategies

- Notation: For any $h \in H \setminus Z$ of length K, denote $(h, a) \in H$ a history of length K + 1 given by h followed by a.
- Terminology: When Z contains no infinite histories then the game has a "finite horizon".

Strategies and outcomes:

- For each $h \in H \setminus Z$, i = P(h), define $A_i(h) \equiv \{(h, a) \in H\}$.
- For each $i \in N$, define "decision nodes":

$$H_i \equiv \{h' \in H \setminus Z : P(h') = i\}.$$

- A pure strategy $s_i(h) \in A_i(h)$ for each $h \in H_i$ (one action for each of i's decision nodes). S_i denotes the set of all strategy functions $\{s_i\}$.
- Strategy profile $\mathbf{s} = (s_i)_{i \in N}$ maps to outcome $O(\mathbf{s}) \in Z$:

$$O(\mathbf{s}) \equiv (s_{P(\emptyset)}(\emptyset), s_{P(h^1)}(h^1), s_{P(h^2)}(h^2), \ldots),$$

where $h^{k+1} = (h^k, s_{P(h^k)}(h^k))$ for each $k \ge 0$, by setting $h^0 \equiv \emptyset$.

Extensive games with perfect information: normal form

Definition (Normal form of extensive game)

Given extensive form game $\Gamma = \langle N, H, P, \{u_i\}_{i \in N} \rangle$, the **normal form** of Γ is given by $\Gamma' = \langle N', \{A'_i\}_{i \in N}, \{u'_i\}_{i \in N} \rangle$ satisfying:

- \bullet N' = N,
- $A'_i = S_i$ for each $i \in N$,
- $u_i'(\mathbf{s}) = u_i(O(\mathbf{s}))$ for each $\mathbf{s} \in \times_{j \in N} S_i$.
- In words: A strategy in Γ' prescribes an action for i for each of her decision nodes, even for those that are never reached during play.
- Notice: Γ' removes the sequential information in Γ (i.e. Γ' drops the "tree structure"), but retains players' strategy spaces and preferences over outcomes in Γ .

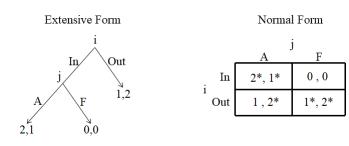


Figure: Extensive game I

- $N = \{i, j\},$
- $\bullet \ S_i = \{\mathsf{In}, \mathsf{Out}\}, \qquad S_j = \{\mathsf{A}, \mathsf{F}\},$
- $\bullet \ \mathit{PNE} = \{(\mathsf{In},\!\mathsf{A}),(\mathsf{Out},\!\mathsf{F})\}.$

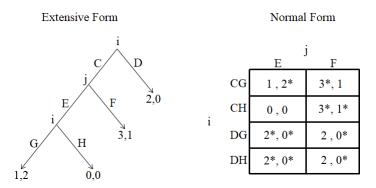


Figure: Extensive game II

- $N = \{i, j\},$
- $S_i = \{CG, CH, DG, DH\}, S_i = \{E, F\}$
- *PNE* = {(CH,F), (DG,E), (DH,E)}.

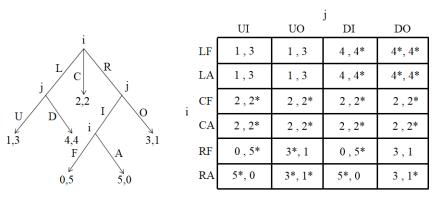


Figure: Extensive game III

- $N = \{i, j\},$
- $S_i = \{LF, LA, CF, CA, RF, RA\}, S_i = \{UI, UO, DI, DO\},$
- *PNE* = {(LF,DO), (LA,DO), (RA,UO)}.

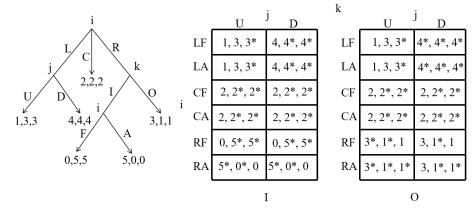


Figure: Extensive game IV

- $N = \{i, j, k\},$
- $S_i = \{LF, LA, CF, CA, RF, RA\}, S_j = \{U, D\}, S_k = \{I, O\},$
- $PNE = \{(LF, D, O), (LA, D, O), (RA, U, O)\}.$

Definition (Reduced normal form of extensive game)

Given extensive form game $\Gamma = \langle N, H, P, \{u_i\}_{i \in N} \rangle$ and corresponding normal form game $\Gamma' = \langle N', \{A'_i\}_{i \in N}, \{u'_i\}_{i \in N} \rangle$, the **reduced normal** form game is given by $\Gamma'' = \langle N'', \{A''_i\}_{i \in N}, \{u''_i\}_{i \in N} \rangle$ satisfying:

- N'' = N.
- $A_i'' \subseteq S_i$ for each $i \in N$ and satisfies:
 - of or each $s_i \in S_i \backslash A_i''$ there is some $s_i'' \in A_i''$ such that $u_i'(s_i'', \mathbf{s}_{-i}) = u_i'(s_i, s_{-i})$ for each $\mathbf{s}_{-i} \in A_{-i}'$ and all $j \in N$,
 - o for all s_i'' , $\tilde{s}_i'' \in A_i''$, $s_i'' \neq \tilde{s}_i''$, $u_j'(s_i'', \mathbf{s}_{-i}) \neq u_j'(\tilde{s}_i'', \mathbf{s}_{-i})$ for some $s_{-i} \in A_{-i}'$ and some $j \in N$.
- \bullet In Words: $\Gamma^{\prime\prime}$ combines payoff equivalent strategies into one strategy.
- Condition (a) requires that all players are indifferent between $s'' = (s_i'', \mathbf{s}_{-i})$ and $s = (s_i, \mathbf{s}_{-i})$ for s_i removed from i's strategy set.
- Condition (b) requires that $\{A_i''\}_{i\in N}$ give the most reduced action sets such that (a) is satisfied (combine as much as possible).

Reduced normal form: example

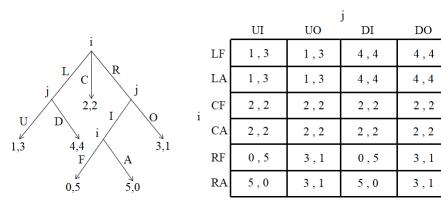


Figure: Extensive game III

- $N = \{i, j\},$
- $S_i = \{LF, LA, CF, CA, RF, RA\}, S_i = \{UI, UO, DI, DO\},$
- *PNE* = {(LF,DO), (LA,DO)}.

Reduced normal form: example

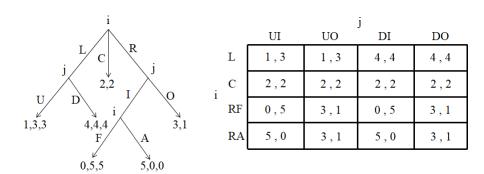


Figure: Extensive game III: reduced normal form

- $N = \{i, j\},$
- $S_i = \{L, C, RF, RA\}, S_j = \{UI, UO, DI, DO\},$
- $PNE = \{(L,DO)\}.$

Behavioral strategies

Given any extensive form game Γ with strategy space S_i for i, for $s_i \in S_i$ we define i's behavioral strategy at history $h \in H \setminus Z$, such that P(h) = i, as the element $s_i(h) \in \{(h, a) \in H\}$.

- The set of behavioral strategies $\{s_i(h): h \in H \setminus Z, P(h) = i\}$ gives the same information regarding i's play as does s_i .
- With behavioral strategies, we can discuss a change to i's strategy at a particular decision node of the game holding fixed her behavioral strategies at other decision nodes (we call this a "single deviation").

Subgames

Selten (1965, 1975) and Kreps and Wilson (1982): use the sequential structure to impose "credibility" in off-equilibrium behavioral strategies...

Definition (Subgame)

Given extensive form game $\Gamma = \langle N, H, P, \{u_i\}_{i \in N} \rangle$, the **subgame** of Γ following any history $h \in H$ is the extensive form game $\Gamma|_h = \langle N, H|_h, P|_h, \{u_i|_h\}_{i \in N} \rangle$ satisfying:

- $N|_b = N.$
- $H|_h = \{h' \in H : h' = (h, \sigma) \text{ for some sequence } \sigma\},$
- $P|_{h}(h') = P(h'),$
- $u_i|_h(O|_h(\mathbf{s})) = u_i(O(\mathbf{s}))$ ($O|_h$ defined below).
- Strategy profile $\mathbf{s} = (s_i)_{i \in N}$ in $\Gamma(h)$ maps to outcome $O|_h(\mathbf{s}) \in Z$:

$$O|_{h}(\mathbf{s}) \equiv (h, s_{P(h)}(h), s_{P(h^{1})}(h^{1}), s_{P(h^{2})}(h^{2}), \ldots),$$

where $h^{k+1} = (h^k, s_{P(h^k)}(h^k))$ for each $k \ge 0$ and $h^0 \equiv h$.

Subgames

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- $N|_h = N$,
- $H|_h = \{h' \in H : h' = (h, \sigma) \text{ for some sequence } \sigma\},$
- $P|_h(h') = P(h')$ for each $h' \in H|_h$,
- $\bullet \ u_i|_h(O|_h(\mathbf{s})) = u_i(O(\mathbf{s})).$
- Can construct strategy space $S_i|_h$ from $H|_h$ and $P|_h$ for each $i \in N$.
- In words: $\Gamma|_h$ gives the continuation (i.e. remaining) game within the game Γ upon history $h \in H$ having been played already.

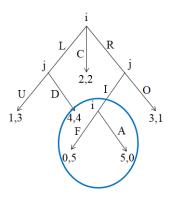


Figure: Extensive game III: 4 subgames, subgame to h = (R, I) circled

- $N = \{i, j\},$
- $S_i|_h = \{LF, LA\}, \qquad S_j|_h = \emptyset,$
- $PNE|_h = \{A\}.$

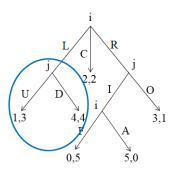


Figure: Extensive game III: 4 subgames, subgame to h = (L) circled

- $N = \{i, j\},$
- $S_i|_h = \emptyset$, $S_j|_h = \{U, D\}$,
- $PNE|_{h} = \{D\}.$

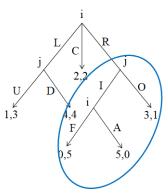


Figure: Extensive game III: 4 subgames, subgame to h = (R) circled

- $N = \{i, j\},$
- $S_i|_h = \{F, A\}, \qquad S_j|_h = \{I, O\},$
- $PNE|_{h} = \{(A,O)\}.$

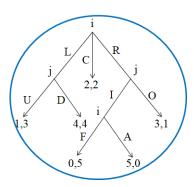


Figure: Extensive game III: 4 subgames, subgame to $h = \emptyset$ circled

- $N = \{i, j\},$
- $S_i = \{LF, LA, CF, CA, RF, RA\}, S_j = \{UI, UO, DI, DO\},$
- $PNE = \{(LF,DO), (LA,DO), (RA,UO)\}$ (recall slide 8).

Subgame Perfect Nash equilibrium

Definition (Subgame Perfect Nash equilibrium)

Given extensive game $\Gamma = \langle N, H, P, \{u_i\}_{i \in N} \rangle$, a strategy profile \mathbf{s}^* is a subgame Perfect Nash equilibrium (SPNE) iff for each $i \in N$ and each subgame $\Gamma|_h$ for $h \in H \setminus Z$:

$$u_i|_h(s_i, \mathbf{s}_{-i}) \ge u_i|_h(s_i', \mathbf{s}_{-i}), \ \forall s_i' \in S_i|_h.$$

Proposition (Kuhn)

Any extensive game with perfect information Γ has a SPNE.

- \mathbf{s}^* a SPNE $\Rightarrow \mathbf{s}^*$ is a PNE: SPNE "refines" PNE.
- Kuhn's Theorem \Rightarrow there exists a PNE in any extensive game Γ : never a "Matching Pennies" scenario!
- Uniqueness is not guaranteed: can have mutiple SPNE. But, Fact: A unique SPNE obtains if for all $z, z' \in Z$ and $i \in N$, $u_i(z) \neq u_i(z')$.
- Fact: IESWS of normal form Γ' of Γ may eliminate some SPNE.

Finding SPNE with Backward Induction

Algorythm (Backward Induction)

- Step 1: In all final subgames (i.e. subgames with no proper subgames), solve the subgame by setting payoff-maximizing behavioral strategy for unique player with non-empty strategy set.
- Step k > 1: In subgames including only subgames solved in Steps 1 to k-1, solve the subgame by setting payoff-maximizing behavioral strategy for player moving first, given solution in Step k-1.
- Continue until the subgame to empty history is solved.

Backward Induction: example (Step 1)

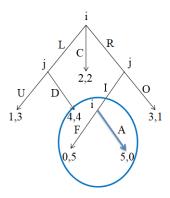


Figure: Extensive game III: 4 subgames, subgame to h = (R, I) circled

- $N = \{i, j\},$
- $S_i|_h = \{LF, LA\}, \qquad S_j|_h = \emptyset,$
- $SPNE|_h = \{A\}.$

Backward Induction: example (Step 1)

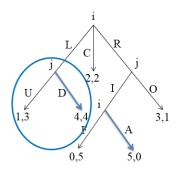


Figure: Extensive game III: 4 subgames, subgame to h = (L) circled

- $N = \{i, j\},$
- $S_i|_h = \emptyset$, $S_j|_h = \{U, D\}$,
- $SPNE|_{h} = \{D\}.$

Backward Induction: example (Step 2)

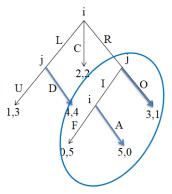


Figure: Extensive game III: 4 subgames, subgame to h = (R) circled

- $N = \{i, j\},$
- $S_i|_h = \{F, A\}, \qquad S_j|_h = \{I, O\},$
- $SPNE|_{h} = \{(A,O)\}.$

Backward Induction: example (Step 3)

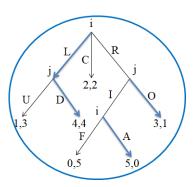


Figure: Extensive game III: 4 subgames, subgame to $h = \emptyset$ circled

- $N = \{i, j\},$
- $S_i = \{LF, LA, CF, CA, RF, RA\}, S_j = \{UI, UO, DI, DO\},$
- $SPNE = \{(LA,DO)\}$ (i.e. PNE (LF,DO) and (RA,UO) excluded).

Subgame Perfect Nash equilibrium: examples

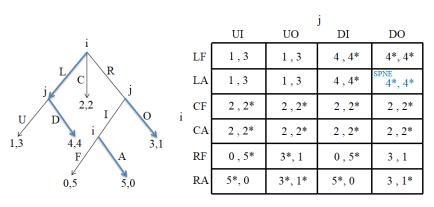
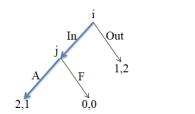


Figure: Extensive game III: SPNE

 $\bullet \ \mathit{SPNE} = \{(\mathsf{LA}, \mathsf{DO})\} \subset \mathit{PNE} = \{(\mathsf{LF}, \mathsf{DO}), (\mathsf{LA}, \mathsf{DO}), (\mathsf{RA}, \mathsf{UO})\}.$

Subgame Perfect Nash equilibrium: examples



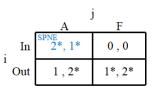


Figure: Extensive game I: SPNE

- "F" is an "incredible threat" of player j (to player i).
- $SPNE = \{(In,A)\} \subset PNE = \{(In,A), (Out,F)\}.$