MAIN CONCEPTS CLASSIFICATION





NOTATION

- Input variables: $X = (X_1, X_2, \dots, X_p)$ independent variables, predictors, features
- Output variable: Y response, dependent variables categorical data

$$Y = j, \qquad j = 1, 2, ..., K$$

Classifier is a function (mapping) C

$$C: X \to Y$$
, $C: \mathbb{R}^p \to \{1, 2, \dots, K\}$

We assume a law

$$Y = C(X) + e, \qquad E[e] = 0$$

We should predict Y using

$$\hat{Y} = \hat{C}(X)$$

where \hat{C} is estimate of C and \hat{Y} is the prediction of Y

ERROR RATE OF CLASSIFICATION

Assume classification problem with training data

$$(X_1, Y_1), \dots, (X_n, Y_n)$$

where Y_k are some classes

Training accuracy

$$Accuracy = \frac{1}{n} \sum_{k=1}^{n} I(Y_k = \hat{Y}_k)$$

Training error rate

Error rate =
$$1 - Accuracy = \frac{1}{n} \sum_{k=1}^{n} I(Y_k \neq \hat{Y}_k)$$

Also known as mean misclassification error (MME)

TEST ERROR RATE OF CLASSIFICATION

- We are most interested in the error rates that result from applying our classifier to test observations that were not used in training
- This is known as test error rate
- A good classifier is one for which the test error rate is the smallest

PROBABILITY SETTING - BAYES CLASSIFIER

Probability of misclassification

$$R(C) = P\{\hat{C}(X) \neq Y\}$$

- How to minimize the test error?
- Calculate the following conditional probabilities

$$Pr(Y = j | X = x_0), j = 1, 2, ..., K$$

and

$$C^{Bayes}(X) = \underset{j \in \{1,2,\dots,K\}}{argmax} \Pr(Y = j | X = x_0)$$

- Bayes classifier assigns each observation to the most likely class
- This very simple classifier is called the Bayes classifier
- The Bayes classifier produces the lowest possible test error rate, called the Bayes error rate

BAYES CLASSIFIER: CONTINUED

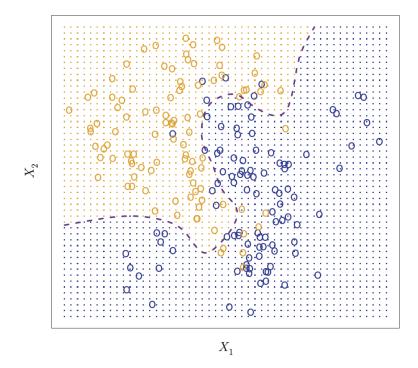
- The Bayes classifier is a useful benchmark in classification
- The following non-negative quantity (excess risk)

$$R(C) - R^{Bayes}(C)$$

is important for assessing the performance of different classification techniques

 A classifier is said to be consistent if the excess risk converges to zero as the size of the training data set tends to infinity

EXAMPLE



- Binary classification problem orange and blue circles
- For this simulated data, we can calculate

$$P_j = \Pr(Y = j | X = (x_1, x_2)),$$

 $j = orange, blue$

 The orange shaded region consists of the points for which

$$P_{orange} > 0.5 (P_{blue} \le 0.5)$$

 The blue shaded region consists of the points for which

$$P_{blue} > 0.5 (P_{orange} \le 0.5)$$

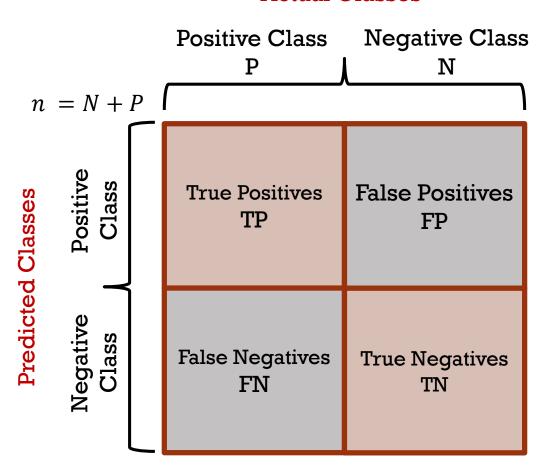
The dashed line consists of points

$$P_{orange} = P_{blue} = 0.5$$

- This is called the Bayes decision boundary
- The Bayes classifier's prediction is determined by the Bayes decision boundary; an observation that falls on the orange side of the boundary will be assigned to the orange class ...

CONFUSION MATRIX FOR A BINARY CLASSIFICATION

Actual Classes



CLASSIFICATION MEASURES

$$Accuracy = \frac{TP + TN}{n}$$

$$Precision = Positive \ Predictive \ Value(PPV) = \frac{TP}{TP + FP}$$

True Positive Rate (TPR) = Sensitivity = Recall =
$$\frac{TP}{TP + FN} = \frac{TP}{P}$$

False Positive Rate(FPR) = Fall Out =
$$\frac{FP}{FP + TN} = \frac{FP}{N}$$

PRECISION VS RECALL

- High precision means that an algorithm returned substantially more relevant results than irrelevant (usefulness), while high recall means that an algorithm returned most of the relevant results (completeness).
- **Example:** Search engine returns 30 pages where only 20 pages are relevant (TP = 20) while failing to return 40 additional relevant pages (FN = 40). Its precision = 20/30 while its recall = 20/60.
- So, in this case, precision is "how useful the search results are", and recall is "how complete the results are".

CLASSIFICATION MEASURES

$$Accuracy = \frac{TP + TN}{P + N} = \frac{TP + TN}{n}$$

$$Balanced\ Accuracy = \frac{\left(\frac{TP}{P} + \frac{TN}{N}\right)}{2} = \frac{Sensitivity + Specificity}{2}$$

$$Cohen's \ kappa = \frac{Accuracy - Expected \ Accuracy}{1 - Expected \ Accuracy}$$

Expected Accuracy~ Random Classifier Accuracy

CLASSIFICATION MEASURES

Prevalence ~ *percentage of each class*

$$Prevalence = \frac{P}{n}$$

$$Detection \ Prevalence = \frac{TP + FP}{n}$$

$$Detection Rate = \frac{TP}{n}$$

CONFUSION MATRIX FOR A MULTICLASS CLASSIFICATION

Actual Classes

$$n = A + B + C$$

A	В	С

Predicted Classes

A
В
Ŋ

TP_A	BA	CA
AB	TP_B	СВ
AC	ВС	TP_C

$$FPR_A = \frac{AB + AC}{B + C}$$

$$FPR_B = \frac{BA + BC}{A + C}$$

$$FPR_C = \frac{CA + CB}{A + B}$$

$$Accuracy = \frac{TP_A + TP_B + TP_C}{n}$$

$$TPR_A = \frac{TP_A}{A}$$

$$TPR_B = \frac{TP_B}{B}$$

$$TPR_C = \frac{TP_C}{C}$$

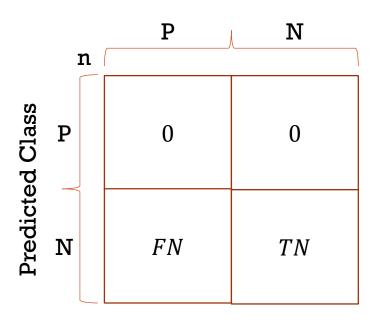
$$Precision_A = \frac{TP_A}{TP_A + FP_A} = \frac{TP_A}{TP_A + BA + CA}$$

$$Precision_A = \frac{TP_B}{TP_B + FP_B} = \frac{TP_B}{TP_B + AB + CB}$$

$$Precision_C = \frac{TP_C}{TP_C + FP_C} = \frac{TP_C}{TP_A + AC + BC}$$

BASELINE - MAJORITY CLASS CLASSIFIER

Actual Class

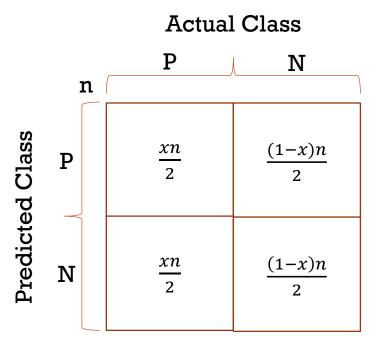


- Assume that the majority is the negative class
- x is the fraction of positives and 1-x is the fraction of negatives:

$$P = x n, \qquad N = (1 - x)n$$

- FN = xn,
- TN = (1 x)n
- TP = FP = 0
- Accuracy = 1 x
- Precision = 0
- TPR = FPR = 0

BASELINE - RANDOM GUESS



- Randomly assign half of the labels to positives and the other half to negatives
- x is the fraction of positives and 1 –
 x is the fraction of negatives

$$TP = FN = \frac{xn}{2}$$

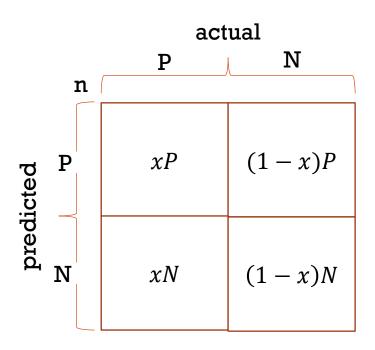
$$TN = FP = \frac{(1-x)n}{2}$$

•
$$Accuracy = \frac{1}{2}$$

•
$$Precision = x$$

$$TPR = FPR = \frac{1}{2}$$

BASELINE - WEIGHTED RANDOM GUESS



- x is the fraction of positives
- randomly assign x portion to positives, and 1-x to negatives
- $TP = x^2 n$
- FN = (1 x)xn
- $TN = (1-x)^2 n$
- FP = x(1-x)n
- $Accuracy = x^2 + (1-x)^2$
- Precision = x
- TPR = FPR = x

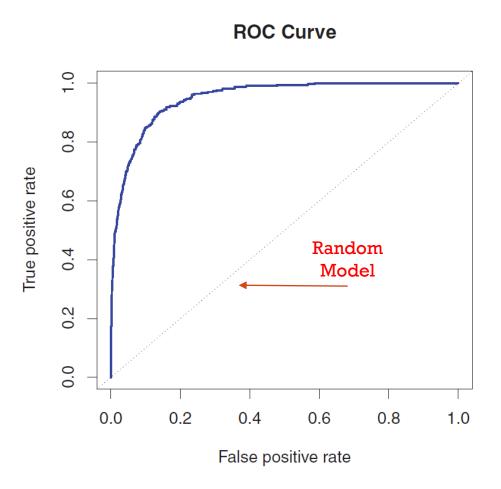
ROC CURVE

 ROC curve (receiver operating characteristics) is a graph of TPR against FPR for different thresholds

$$P(Y = j | X = x_0) = h$$

- ROC analysis provides tools to select possibly optimal models.
 Ideal classifier corresponds to the left-upper corner of the ROC curve with TPR = 1 and FPR = 0
- The overall performance of a classifier, summarized over all possible thresholds, is given by area under the curve (AUC)
- A random classifier has an area under the curve of 0.5, while
 AUC for a perfect classifier is equal to 1. In practice, most of the classification models have an AUC between 0.5 and 1

ROC CURVE



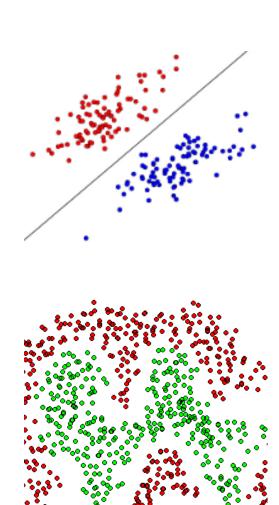
DECISION BOUNDARIES

Any classification algorithm determines decision boundaries which separate identified classes. The classifier will classify all the points on one side of the decision boundary as belonging to one class and all those on the other side as belonging to the other class.

DECISION BOUNDARIES

- Two classes are linearly separable if it is possible perfectly classify them with a linear decision boundary.
- Linear classifiers can only draw linear decision boundaries.

 Non-linear classifiers have non-linear, and possibly discontinuous decision boundaries.



DECISION BOUNDARIES

Two sets are linearly separable if their convex hulls have no intersection.

