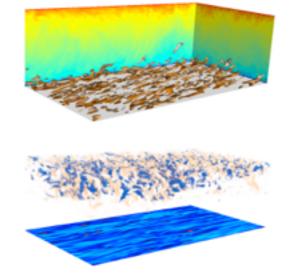
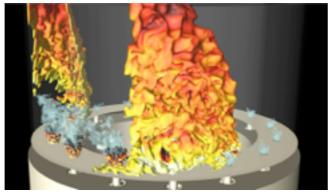
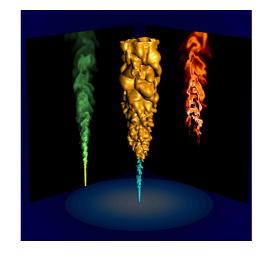
Numerical Methods in Engineering Applications

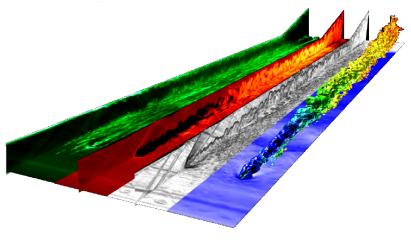
Session #4
Elliptic PDEs (2)

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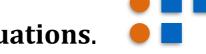


Course contents

I. Basics on numerical approximations

Theoretical lectureProblem-solving workshop

- Introduction and Finite Differences.
- Numerical solution of ordinary differential equations.



II. Solving large linear equations systems: Applications to steady heat equation.

- Elliptic PDE 1. 🔵 🔳
- Elliptic PDE 2. •

III. Methods for unsteady advection/diffusion problems

- Hyperbolic and parabolic PDE: Explicit methods.
- Characterization of numerical errors.
- Hyperbolic and parabolic PDE: Implicit methods.



IV. Towards computational fluid dynamics

- Methodology in numerical computations.
- Incompressible Flow equations.
- Semi-Implicit method for incompressible flows.
- Final project on incompressible flow.

Today's contents

- Elliptic PDEs
 - SOR: Succesive OverRelaxation
 - Preconditioning
 - Conjugate Gradient method
- Methods comparison (Hirsch):

Number of iterations to reduce error by k order of magnitude

Jacobi	$\mathcal{O}(n^2)$
Gauss-Seidel	$\mathcal{O}(n^2)$
SOR	$\mathcal{O}(n^{3/2})$
Preconditioned Conjugate Gradient	$\mathcal{O}(n^{5/4})$
MultiGrid	$\mathcal{O}(n)$

 ${\mathcal N}$ is the number of unknowns

Conjugate Gradient

Algorithm

```
Compute r_0 := b - Ax_0, p_0 := r_0.

For j = 0, 1, ..., until convergence Do:

\alpha_j := (r_j, r_j)/(Ap_j, p_j)

x_{j+1} := x_j + \alpha_j p_j

r_{j+1} := r_j - \alpha_j Ap_j

\beta_j := (r_{j+1}, r_{j+1})/(r_j, r_j)

p_{j+1} := r_{j+1} + \beta_j p_j

EndDo
```

Preconditioned Conjugate Gradient

With the preconditioning matrix M

```
Compute r_0 := b - Ax_0, z_0 = M^{-1}r_0, and p_0 := z_0

For j = 0, 1, \ldots, until convergence Do:

\alpha_j := (r_j, z_j)/(Ap_j, p_j)

x_{j+1} := x_j + \alpha_j p_j

r_{j+1} := r_j - \alpha_j Ap_j

z_{j+1} := M^{-1}r_{j+1}

\beta_j := (r_{j+1}, z_{j+1})/(r_j, z_j)

p_{j+1} := z_{j+1} + \beta_j p_j

EndDo
```