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Engineering

ECEN 758 Data Mining and Analysis: Lecture 4, Dimensionality Reduction

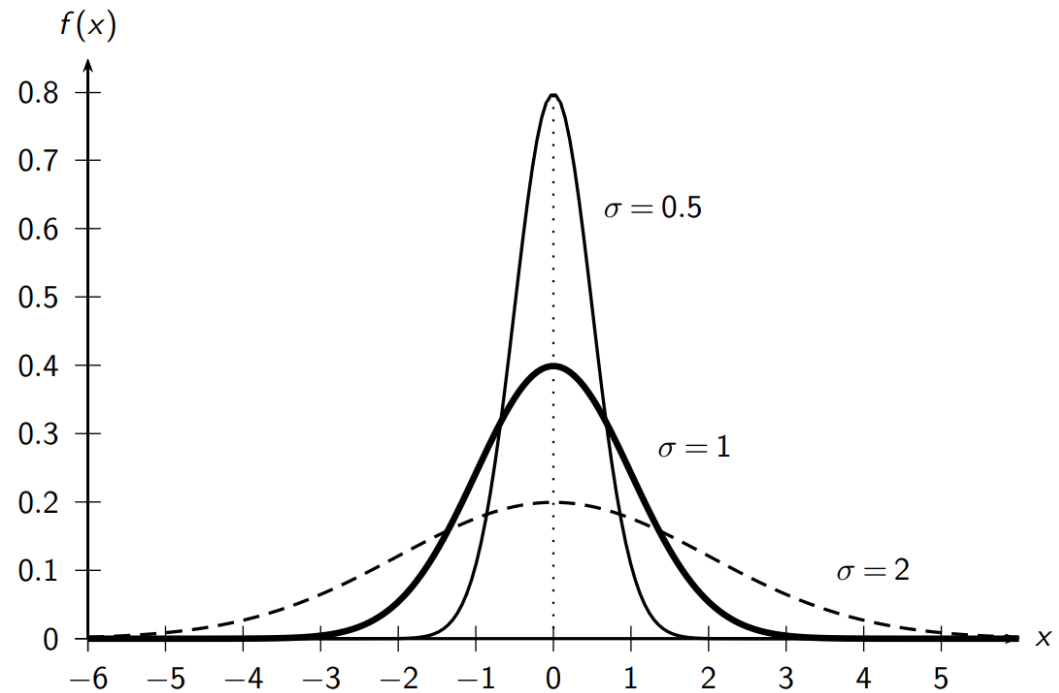
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Department of Electrical and Computer Engineering

- Assignment #1 is available today (08/28)
 - Due next Friday, 09/06
- Submit PDF for solutions (can include code in PDF or submit as separate file)

- Numerical attributes
 - Normal distribution
- Categorical attributes



- Dimensionality reduction
- Reading: ZM Chapter 7
- Supplemental reading: ZM Chapter 6



What are features?

Learning from experience



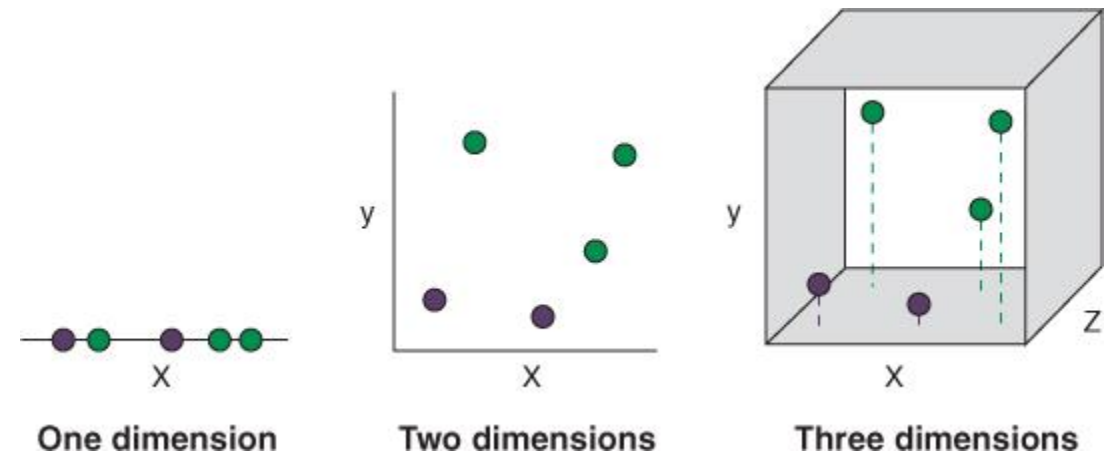
0: Macaw 1: Conure

Feature Extraction



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- Ideally, as you add more features, the data becomes more separable
- We'll explore this more for support vector machines





Curse of Dimensionality

Cats vs Dogs



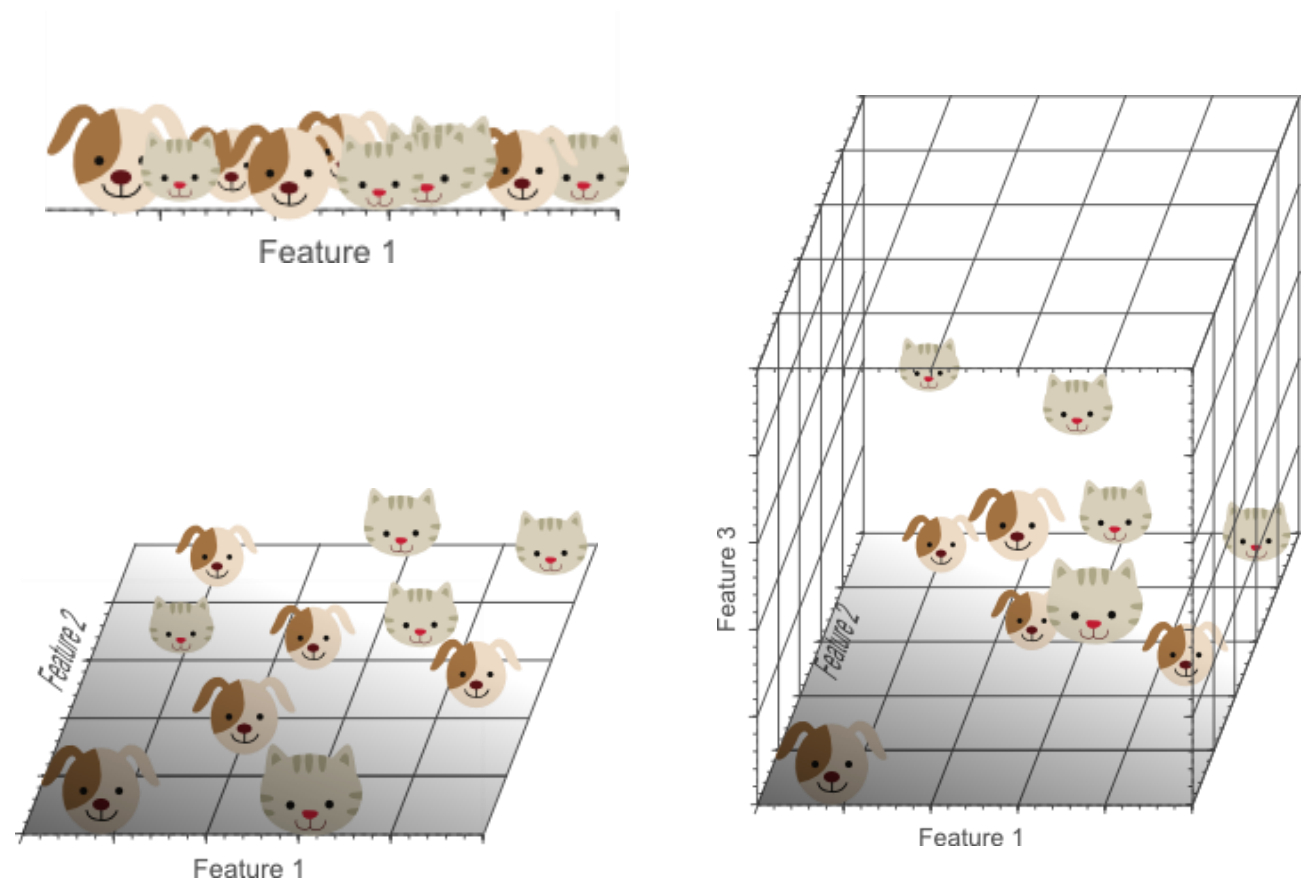
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- What features would you use to distinguish between cats and dogs?



Increasing Features

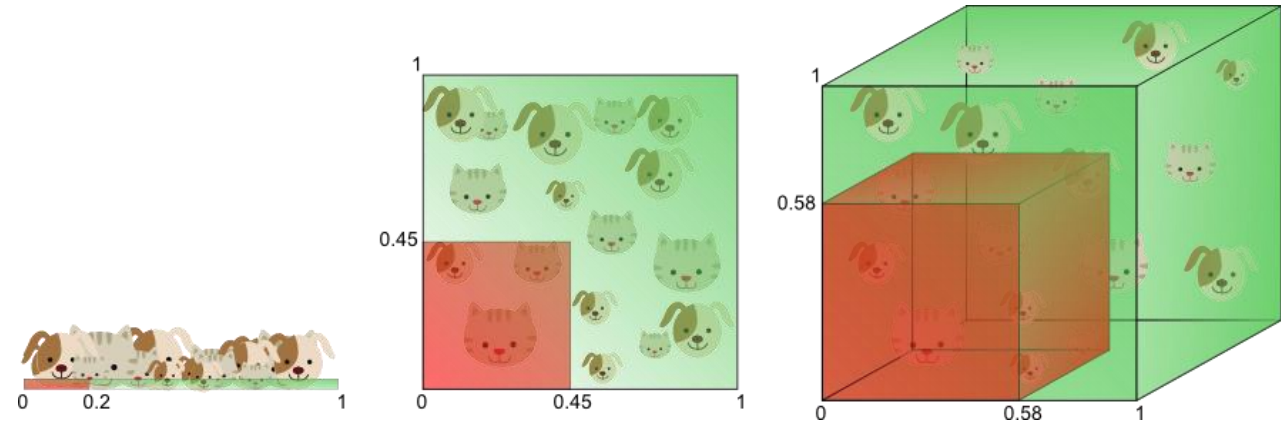
- To improve performance, we can increase the number of features



Curse of Dimensionality



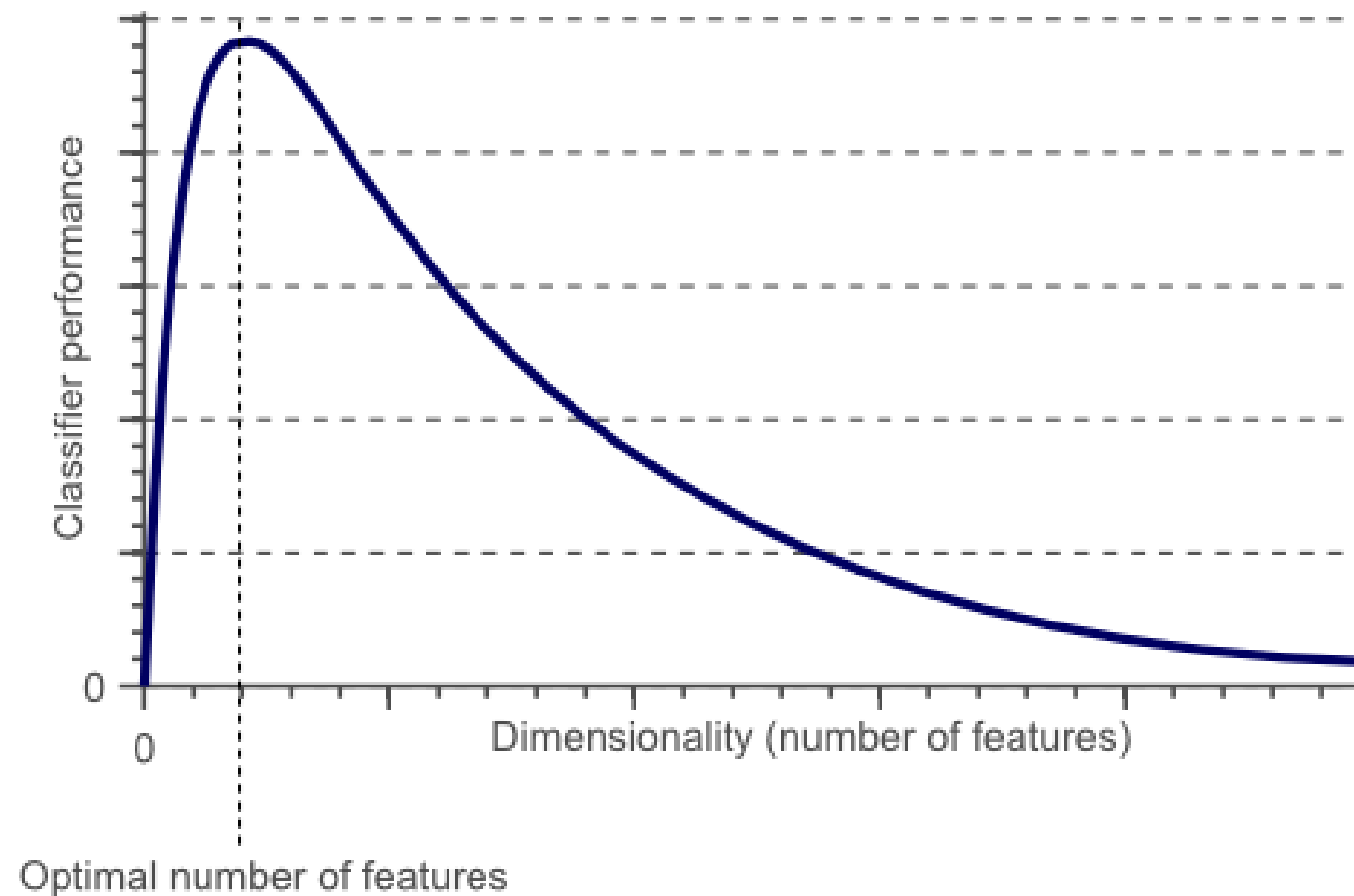
- As we increase the number of features, we need more data
- Grow exponentially as the feature dimension increases



Performance Saturation



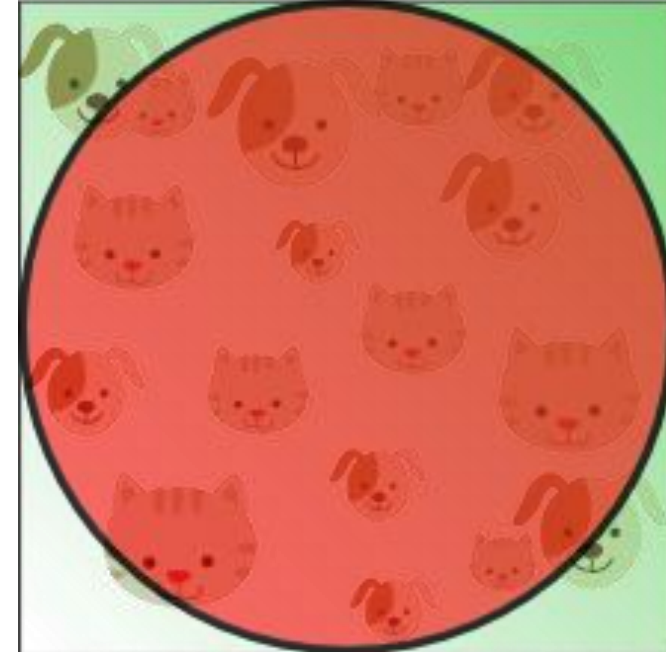
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Curse of Dimensionality



- Feature space lies on unit square (2D)
- Average of feature space is the center of square
- Samples not in unit circle are harder to classify



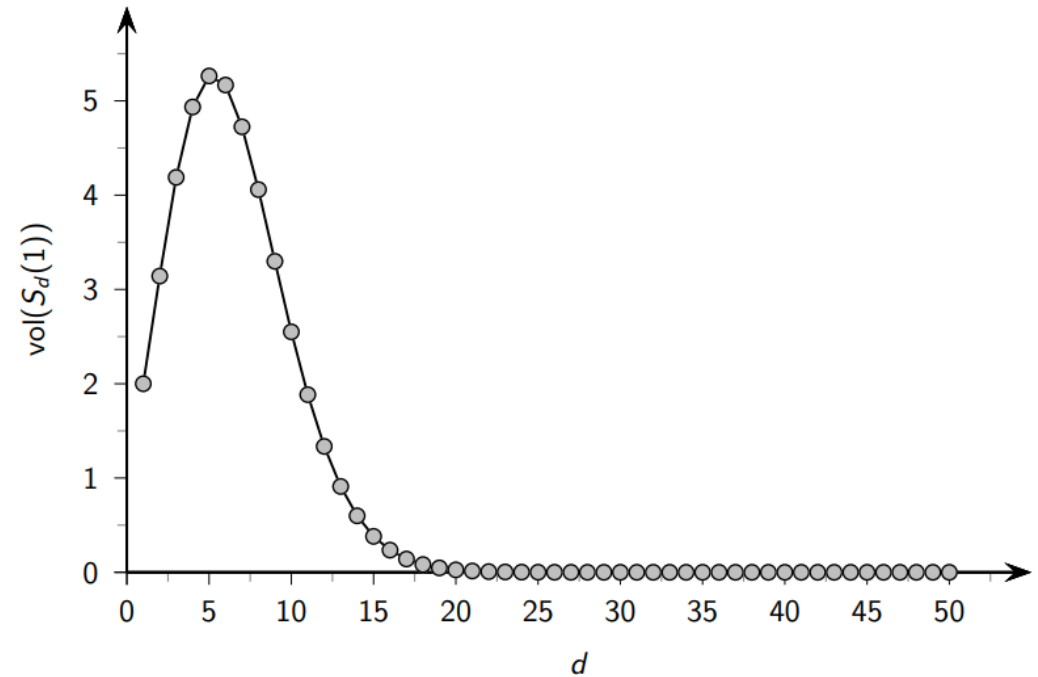
Curse of Dimensionality



- The volume of the circle (hypersphere) with the feature dimension (for radius 1)

$$\text{vol}(S_d(r)) = K_d r^d = \left(\frac{\pi^{\frac{d}{2}}}{\Gamma(\frac{d}{2} + 1)} \right) r^d$$

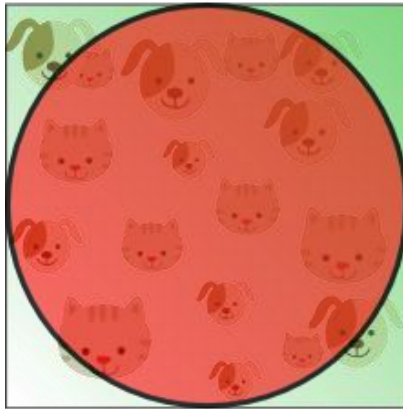
$$\Gamma\left(\frac{d}{2} + 1\right) = \begin{cases} \left(\frac{d}{2}\right)! & \text{if } d \text{ is even} \\ \sqrt{\pi} \left(\frac{d!!}{2^{(d+1)/2}}\right) & \text{if } d \text{ is odd} \end{cases}$$



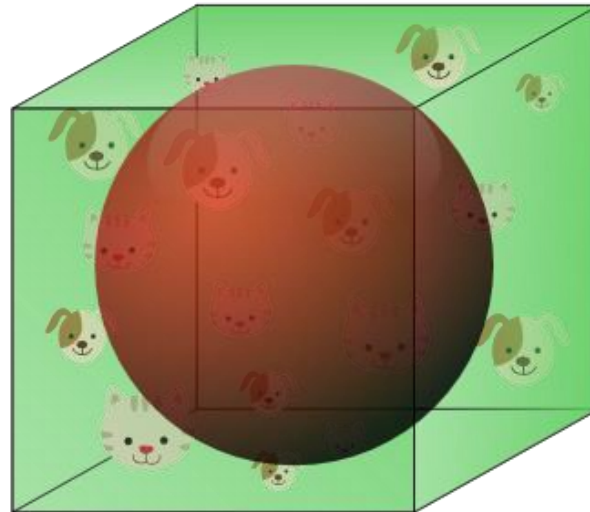
Curse of Dimensionality



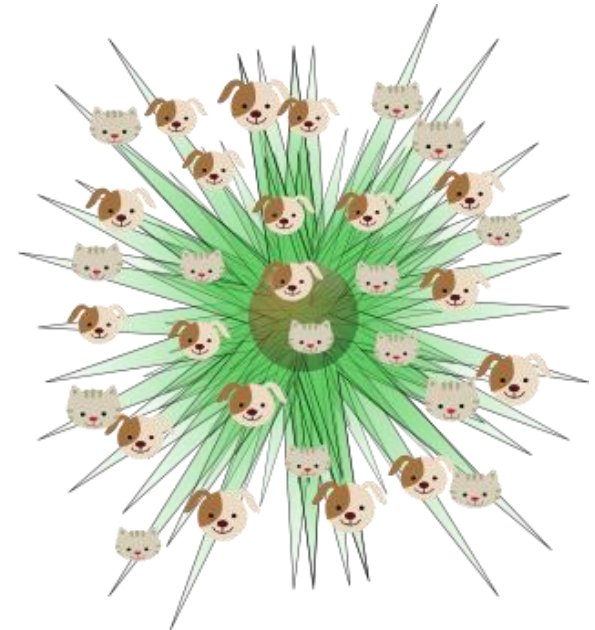
- Volume of hypersphere goes to zero as dimensionality increases



2D



3D



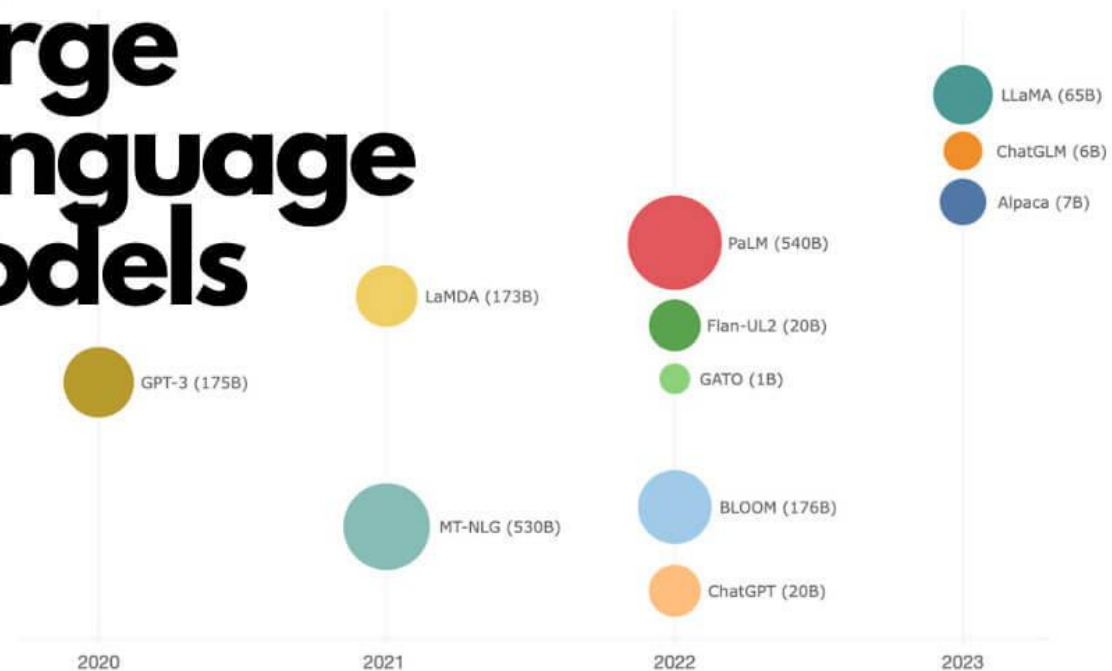
8D

Current State-of-the-Art Models



- Deep learning approaches have many parameters (e.g., features)
- “Data-hungry” approaches

Top Large Language Models





How can we mitigate Curse of Dimensionality?

Dimensionality Reduction



- Goal: find lower dimensional representation of data matrix **D**
- Can we express data using set of orthonormal vectors, **U**
- **a** represents data **x** in new basis

$$\mathbf{x} = a_1 \mathbf{u}_1 + a_2 \mathbf{u}_2 + \cdots + a_d \mathbf{u}_d$$

$$\mathbf{x} = \mathbf{U} \mathbf{a}$$

Dimensionality Reduction



- Infinite choices for orthonormal basis
- Goal is to find optimal basis that preserves most important information of data
- New dimension r should be less than d
- \mathbf{P} is the projection matrix

$$\mathbf{x}' = a_1 \mathbf{u}_1 + a_2 \mathbf{u}_2 + \cdots + a_r \mathbf{u}_r = \sum_{i=1}^r a_i \mathbf{u}_i = \mathbf{U}_r \mathbf{a}_r$$

$$\mathbf{x}' = \mathbf{U}_r \mathbf{U}_r^T \mathbf{x} = \mathbf{P}_r \mathbf{x}$$

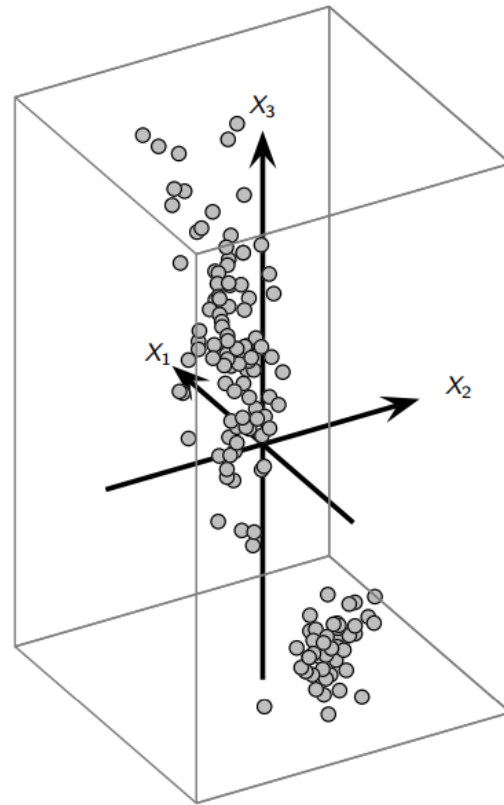
- Find projection that minimizes error vector

$$\epsilon = \sum_{i=r+1}^d a_i \mathbf{u}_i = \mathbf{x} - \mathbf{x}'$$

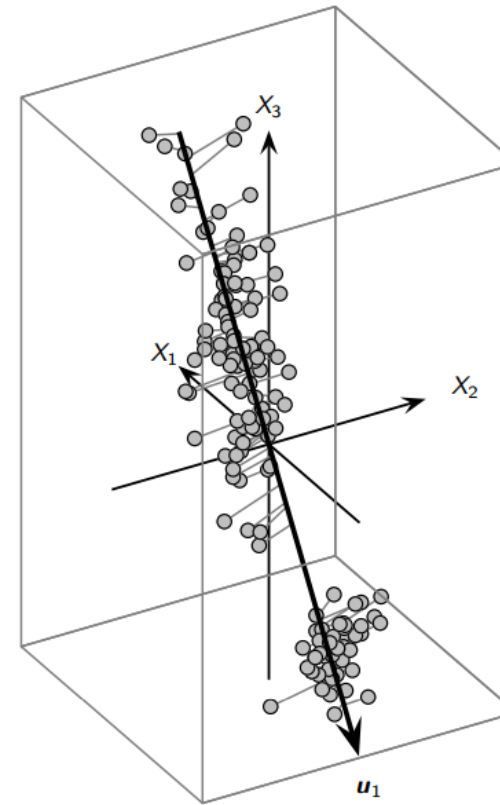
Iris Data: Optimal 1D Basis



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Iris Data: 3D



Optimal 1D Basis



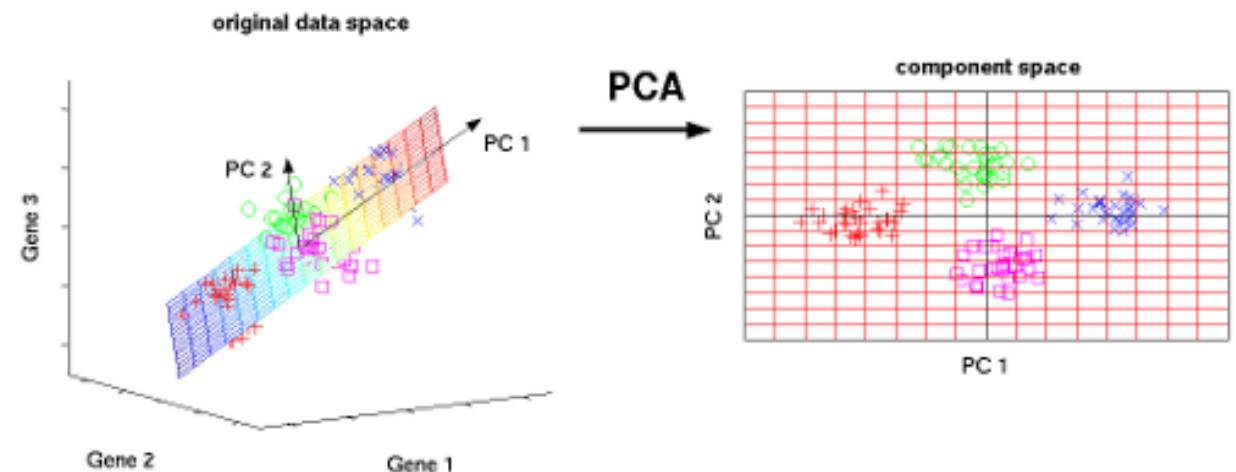
Principal Component Analysis

Principal Component Analysis (PCA)



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- Seek projection that best captures variance
- Direction with the largest projected variance is first principal component
- Direction that maximizes variance should minimize error



- Find unit vector \mathbf{u} that maximizes projected variance
- Data need to first be centered
- Computed projected variance along \mathbf{u}

$$\sigma_{\mathbf{u}}^2 = \frac{1}{n} \sum_{i=1}^n (a_i - \mu_{\mathbf{u}})^2 = \frac{1}{n} \sum_{i=1}^n \mathbf{u}^T (\mathbf{x}_i \mathbf{x}_i^T) \mathbf{u} = \mathbf{u}^T \left(\frac{1}{n} \sum_{i=1}^n \mathbf{x}_i \mathbf{x}_i^T \right) \mathbf{u} = \mathbf{u}^T \Sigma \mathbf{u}$$

- Maximize projected variance $J(\mathbf{u})$
- Constraint of $\mathbf{u}^T \mathbf{u} = 1$

$$\max_{\mathbf{u}} J(\mathbf{u}) = \mathbf{u}^T \Sigma \mathbf{u} - \alpha(\mathbf{u}^T \mathbf{u} - 1)$$

Optimizing Objective Function



- In machine learning, typically want to minimize or maximize objective function
- Achieved by setting the derivative of objective function with variable of interest

$$\frac{\partial}{\partial \mathbf{u}} (\mathbf{u}^T \Sigma \mathbf{u} - \alpha(\mathbf{u}^T \mathbf{u} - 1)) = 0$$

$$\text{that is, } 2\Sigma \mathbf{u} - 2\alpha \mathbf{u} = 0$$

which implies

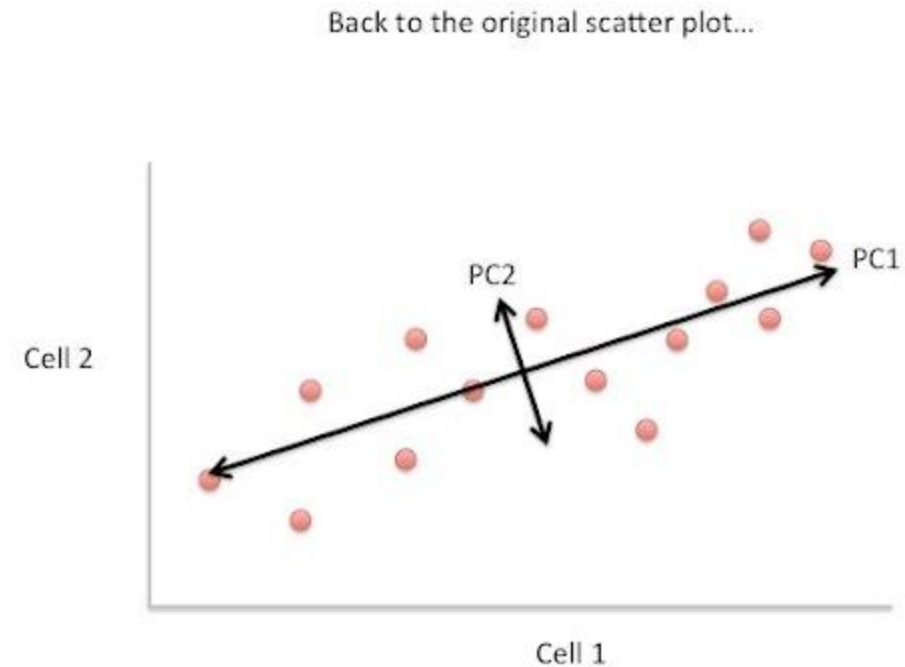
$$\Sigma \mathbf{u} = \alpha \mathbf{u}$$

PCA: Direction of Most Variance



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- Maximizing the projected variance means:
 - Selecting largest eigenvalue of covariance matrix
 - Dominant eigenvector is the direction of most variance (first principal component)





PCA: Minimum Squared Error

- Maximizing the variance also minimizes the squared error

$$MSE(\mathbf{u}) = \frac{1}{n} \sum_{i=1}^n \|\epsilon_i\|^2 = \frac{1}{n} \sum_{i=1}^n \|\mathbf{x}_i - \mathbf{x}'_i\|^2 = \sum_{i=1}^n \frac{\|\mathbf{x}_i\|^2}{n} - \mathbf{u}^T \Sigma \mathbf{u}$$

- First term is fixed for \mathbf{D}
- Same solution for maximization of variance and minimization of squared error

$$\sum_{i=1}^n \frac{\|\mathbf{x}_i\|^2}{n} - \mathbf{u}^T \Sigma \mathbf{u} = \text{var}(\mathbf{D}) = \text{tr}(\Sigma) = \sum_{i=1}^d \sigma_i^2$$

$$MSE(\mathbf{u}_1) = \text{var}(\mathbf{D}) - \mathbf{u}_1^T \Sigma \mathbf{u}_1 = \text{var}(\mathbf{D}) - \lambda_1$$

- 2D subspace captures the most variance in \mathbf{D} with the two eigenvectors that correspond to largest and second largest eigenvalues

$$\mathbf{a}_i = \mathbf{U}_2^T \mathbf{x}_i$$

$$\text{var}(\mathbf{A}) = \mathbf{u}_1^T \Sigma \mathbf{u}_1 + \mathbf{u}_2^T \Sigma \mathbf{u}_2 = \mathbf{u}_1^T \lambda_1 \mathbf{u}_1 + \mathbf{u}_2^T \lambda_2 \mathbf{u}_2 = \lambda_1 + \lambda_2$$

$$MSE = \frac{1}{n} \sum_{i=1}^n \|\mathbf{x}_i - \mathbf{x}'_i\|^2 = \text{var}(\mathbf{D}) - \frac{1}{n} \sum_{i=1}^n (\mathbf{x}_i^T \mathbf{P}_2 \mathbf{x}_i) = \text{var}(\mathbf{D}) - \text{var}(\mathbf{A})$$

- r-D subspace captures the most variance in \mathbf{D} with the r eigenvectors that correspond to r -largest eigenvalues

$$\text{var}(\mathbf{A}) = \frac{1}{n} \sum_{i=1}^n \mathbf{x}_i^T \mathbf{P}_r \mathbf{x}_i = \sum_{i=1}^r \mathbf{u}_i^T \boldsymbol{\Sigma} \mathbf{u}_i = \sum_{i=1}^r \lambda_i$$

$$\text{MSE} = \frac{1}{n} \sum_{i=1}^n \|\mathbf{x}_i - \mathbf{x}'_i\|^2 = \text{var}(\mathbf{D}) - \sum_{i=1}^r \lambda_i = \sum_{i=1}^d \lambda_i - \sum_{i=1}^r \lambda_i$$



PCA Algorithmic Design

Choosing the Dimensionality



- To select the appropriate dimension, use ratio of total variance captured by the first r -components
- If you want to capture 90% of the variance in your data, ratio should be at least 0.9

$$f(r) = \frac{\lambda_1 + \lambda_2 + \cdots + \lambda_r}{\lambda_1 + \lambda_2 + \cdots + \lambda_d} = \frac{\sum_{i=1}^r \lambda_i}{\sum_{i=1}^d \lambda_i} = \frac{\sum_{i=1}^r \lambda_i}{\text{var}(\mathbf{D})}$$

PCA (D, α):

- 1 $\mu = \frac{1}{n} \sum_{i=1}^n \mathbf{x}_i$ // compute mean
- 2 $\mathbf{Z} = \mathbf{D} - \mathbf{1} \cdot \mu^T$ // center the data
- 3 $\Sigma = \frac{1}{n} (\mathbf{Z}^T \mathbf{Z})$ // compute covariance matrix
- 4 $(\lambda_1, \lambda_2, \dots, \lambda_d) = \text{eigenvalues}(\Sigma)$ // compute eigenvalues
- 5 $\mathbf{U} = (\mathbf{u}_1 \quad \mathbf{u}_2 \quad \dots \quad \mathbf{u}_d) = \text{eigenvectors}(\Sigma)$ // compute eigenvectors
- 6 $f(r) = \frac{\sum_{i=1}^r \lambda_i}{\sum_{i=1}^d \lambda_i}$, for all $r = 1, 2, \dots, d$ // fraction of total variance
- 7 Choose smallest r so that $f(r) \geq \alpha$ // choose dimensionality
- 8 $\mathbf{U}_r = (\mathbf{u}_1 \quad \mathbf{u}_2 \quad \dots \quad \mathbf{u}_r)$ // reduced basis
- 9 $\mathbf{A} = \{\mathbf{a}_i \mid \mathbf{a}_i = \mathbf{U}_r^T \mathbf{x}_i, \text{ for } i = 1, \dots, n\}$ // reduced dimensionality data



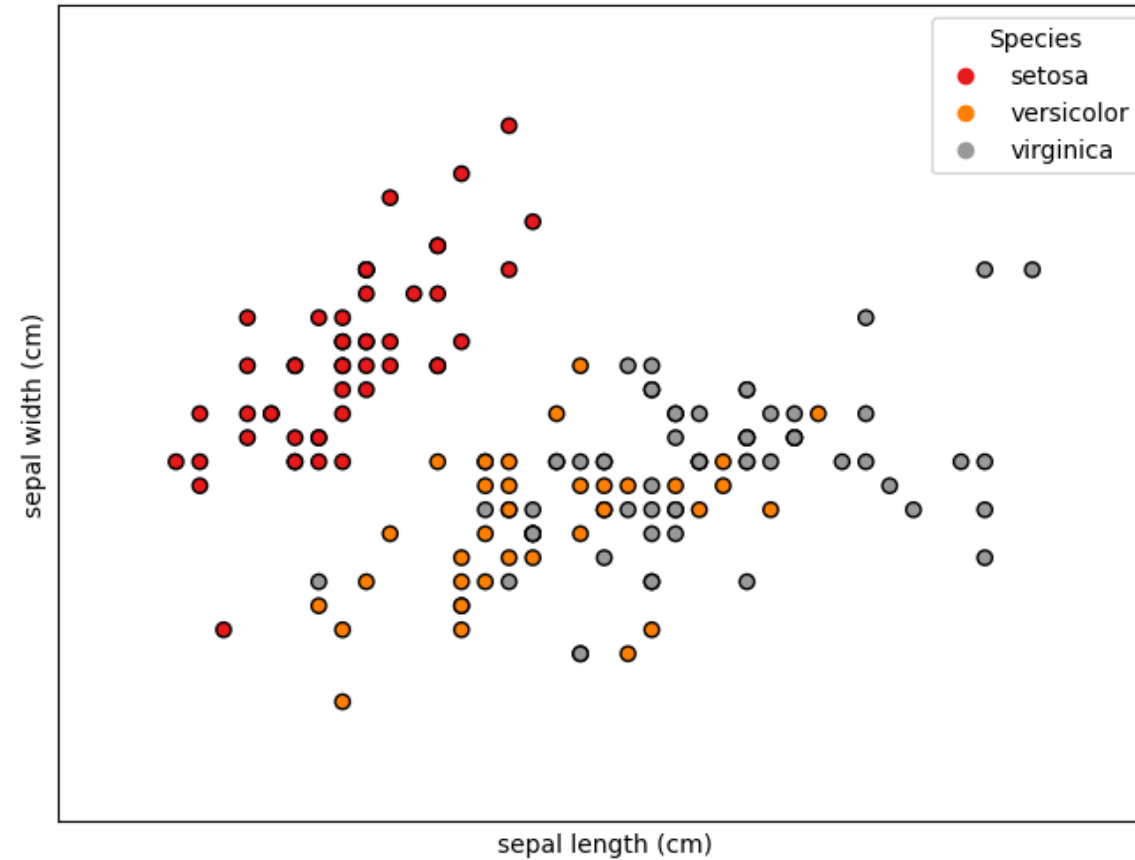
PCA Example

Iris Flower Dataset



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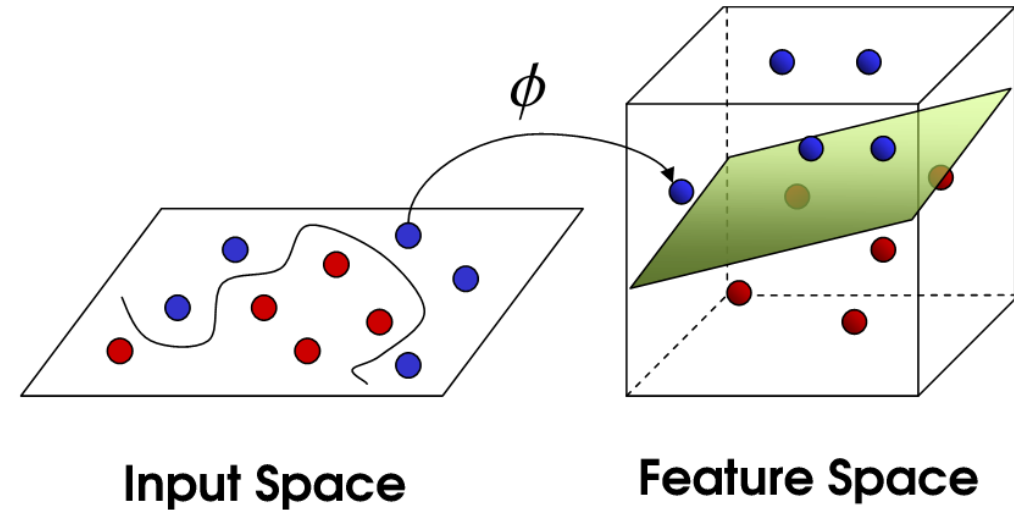
- [Google Colab notebook](#)





Kernel PCA

- PCA can be extended to find non-linear “directions”
- Can leverage “kernel trick” to perform PCA in kernel space



$$\Sigma_{\phi} \mathbf{u}_1 = \lambda_1 \mathbf{u}_1$$

$$\Sigma_{\phi} = \frac{1}{n} \sum_{i=1}^n \phi(\mathbf{x}_i) \phi(\mathbf{x}_i)^T$$

- Principal component direction in feature space is linear combination of transformed points
- Weight vector, \mathbf{c} , is the eigenvector corresponding to largest eigen value of the kernel matrix
- Weight vector constraint

$$\mathbf{u}_1 = \sum_{i=1}^n c_i \phi(\mathbf{x}_i)$$

$$\mathbf{c} = (c_1, c_2, \dots, c_n)^T$$

$$\mathbf{K}\mathbf{c} = n\lambda_1\mathbf{c} = \eta_1\mathbf{c}$$

$$\|\mathbf{c}\|^2 = \frac{1}{\eta_1}$$

Kernel PCA Algorithm



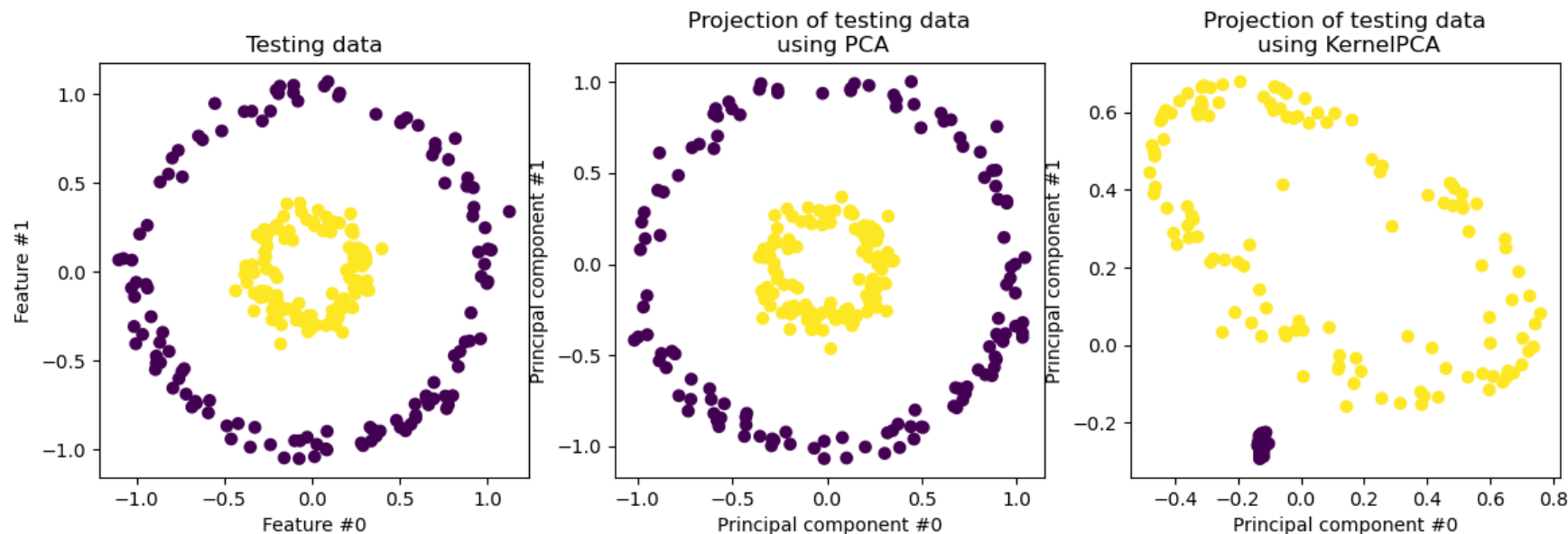
KernelPCA (D, K, α):

- 1 $K = \{K(\mathbf{x}_i, \mathbf{x}_j)\}_{i,j=1,\dots,n}$ // compute $n \times n$ kernel matrix
- 2 $K = (I - \frac{1}{n} \mathbf{1}_{n \times n}) K (I - \frac{1}{n} \mathbf{1}_{n \times n})$ // center the kernel matrix
- 3 $(\eta_1, \eta_2, \dots, \eta_d) = \text{eigenvalues}(K)$ // compute eigenvalues
- 4 $(\mathbf{c}_1 \quad \mathbf{c}_2 \quad \dots \quad \mathbf{c}_n) = \text{eigenvectors}(K)$ // compute eigenvectors
- 5 $\lambda_i = \frac{\eta_i}{n}$ for all $i = 1, \dots, n$ // compute variance for each component
- 6 $\mathbf{c}_i = \sqrt{\frac{1}{\eta_i}} \cdot \mathbf{c}_i$ for all $i = 1, \dots, n$ // ensure that $\mathbf{u}_i^T \mathbf{u}_i = 1$
- 7 $f(r) = \frac{\sum_{i=1}^r \lambda_i}{\sum_{i=1}^d \lambda_i}$, for all $r = 1, 2, \dots, d$ // fraction of total variance
- 8 Choose smallest r so that $f(r) \geq \alpha$ // choose dimensionality
- 9 $\mathbf{C}_r = (\mathbf{c}_1 \quad \mathbf{c}_2 \quad \dots \quad \mathbf{c}_r)$ // reduced basis
- 10 $\mathbf{A} = \{\mathbf{a}_i \mid \mathbf{a}_i = \mathbf{C}_r^T K_i, \text{ for } i = 1, \dots, n\}$ // reduced dimensionality data

PCA vs Kernel PCA



- PCA performs linear transformation (centering, rescaling, and rotation)
- Data is already centered and no rescaling (PCA causes rotation)
- Kernel PCA more effective for non-linearly separable data





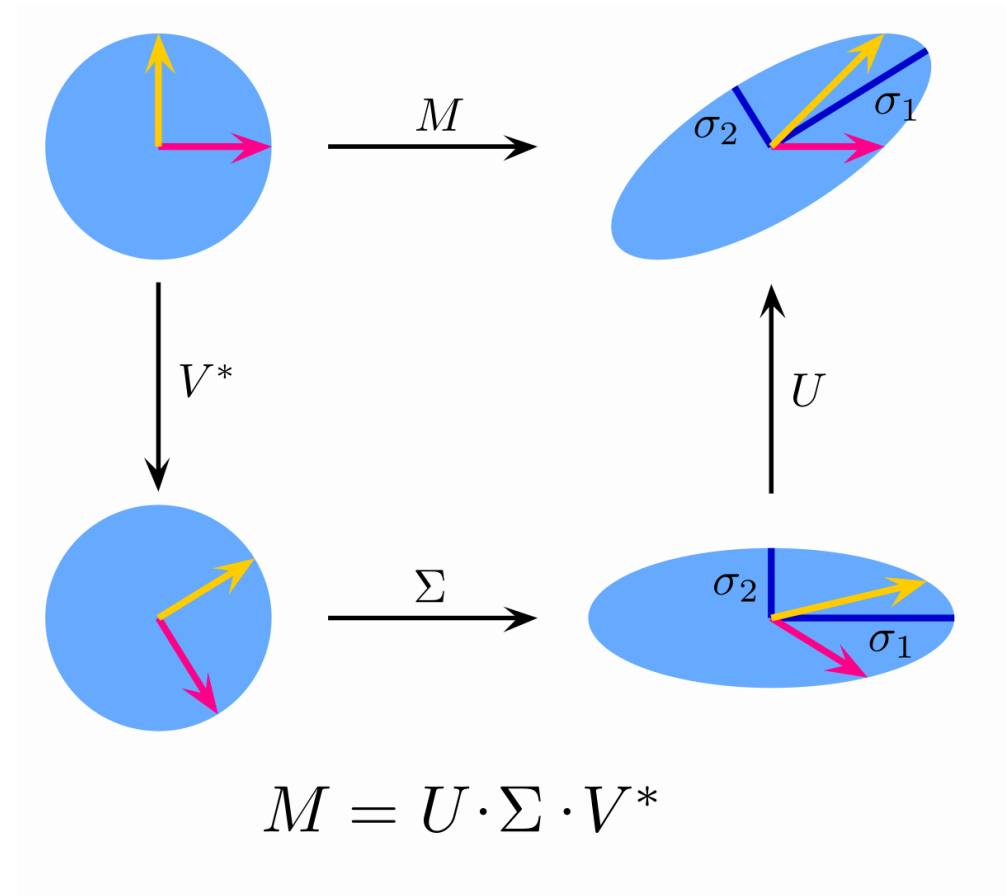
Singular Value Decomposition

Singular Value Decomposition



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- PCA special case of SVD
- Generalizes factorization for any matrix



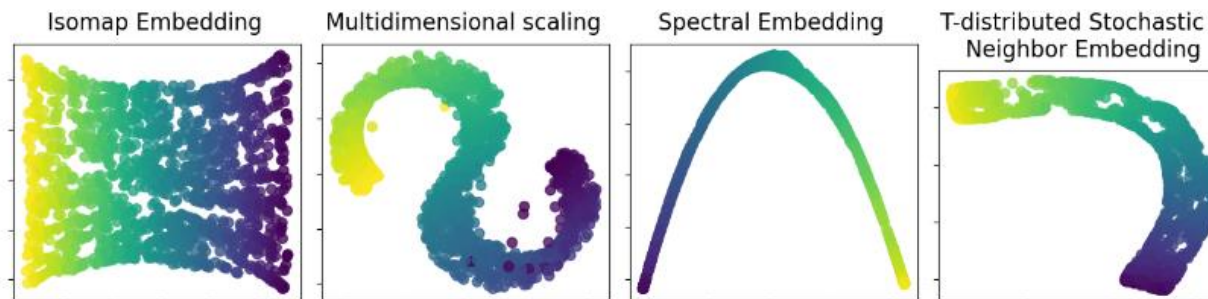
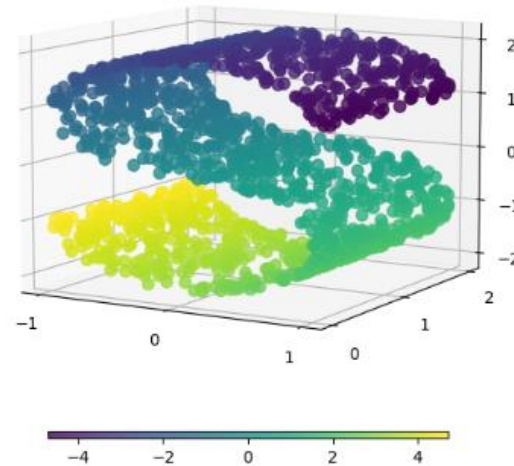


Other Dimensionality Reduction Techniques

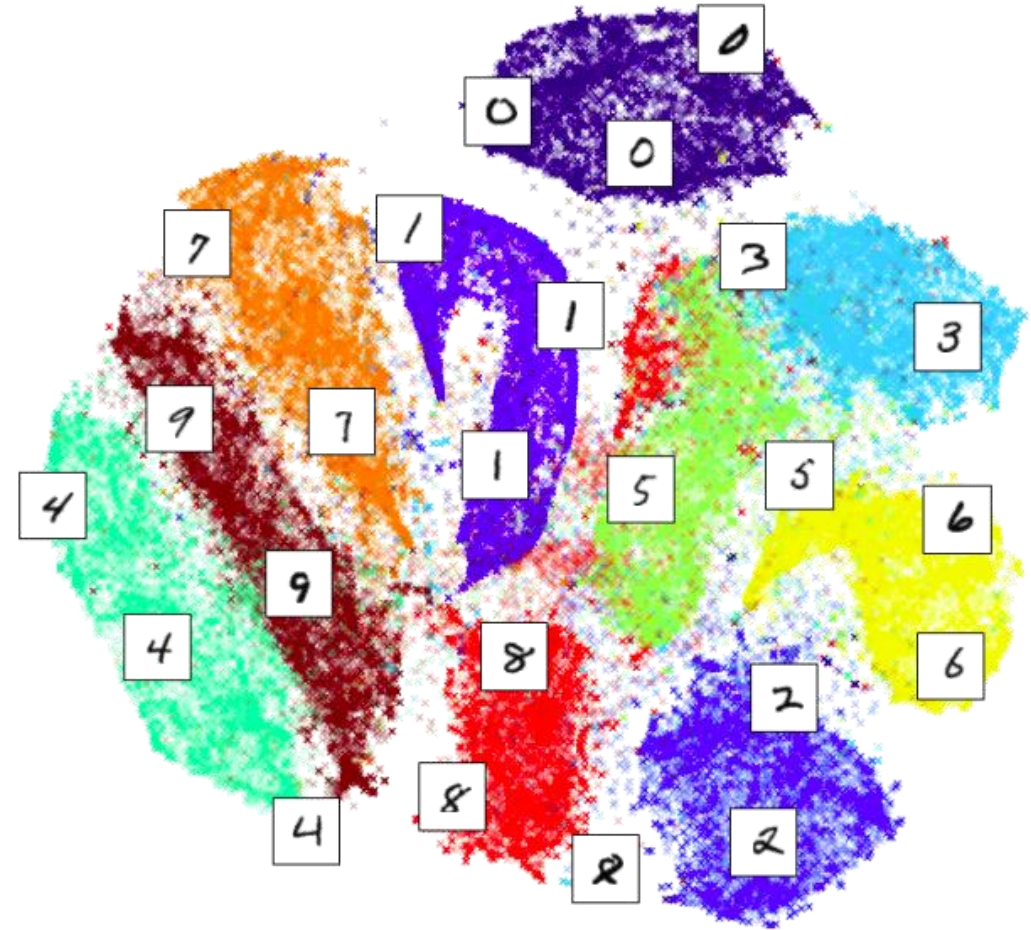
Sklearn Dimensionality Reduction



Original S-curve samples



- t-SNE
- Uses joint distribution of higher and lower dimension to model perform dimensionality reduction



- UMAP
- Assumptions
 - Data is uniformly distributed
 - Metric is locally constant
 - Manifold is locally connected



TSNE

UMAP



Dimension Reduction Applications

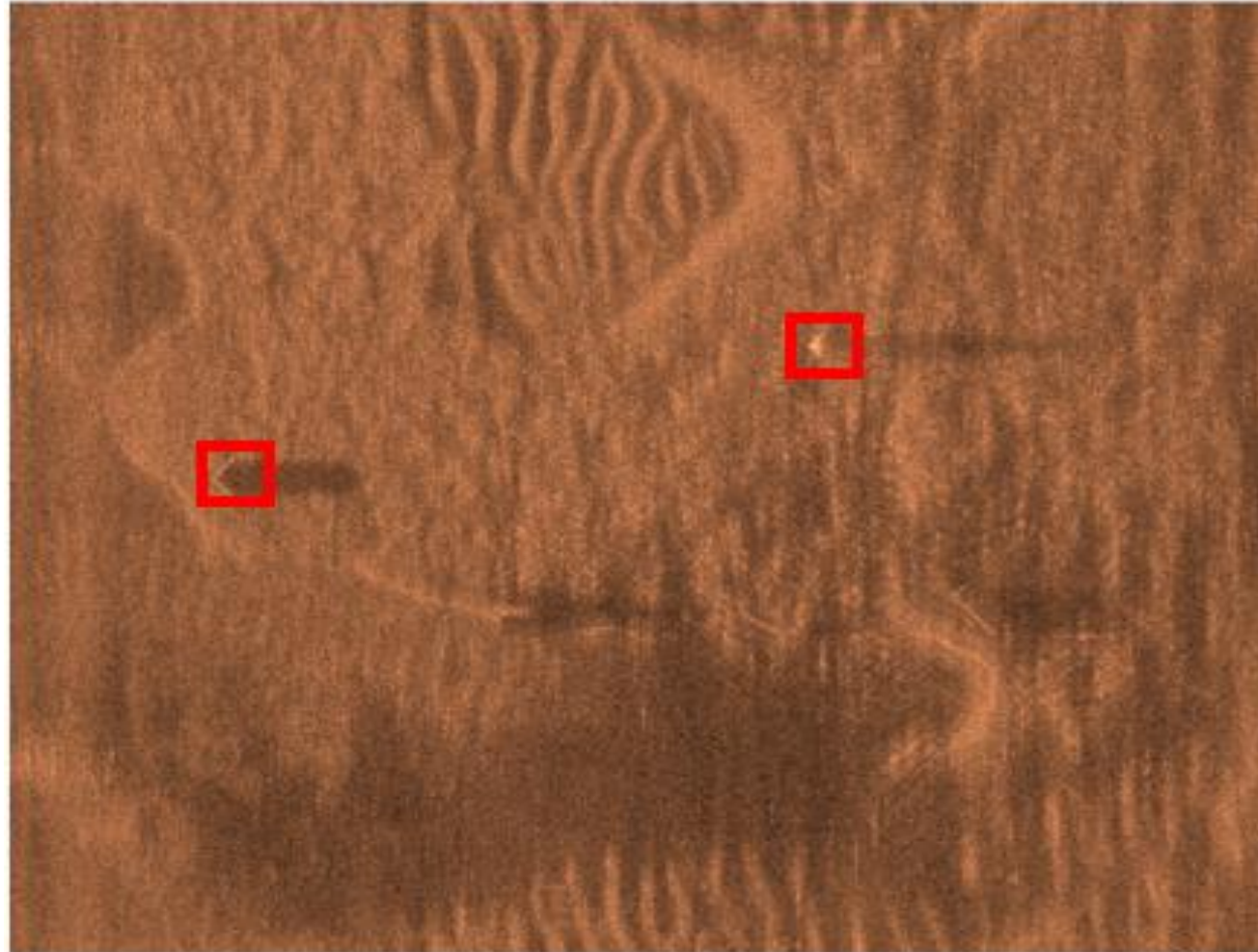


Defense

Automatic Target Recognition

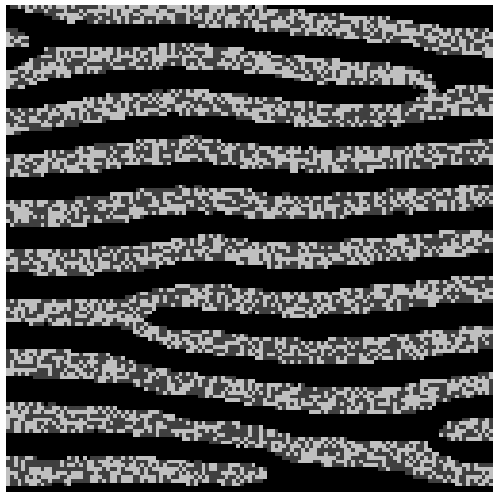


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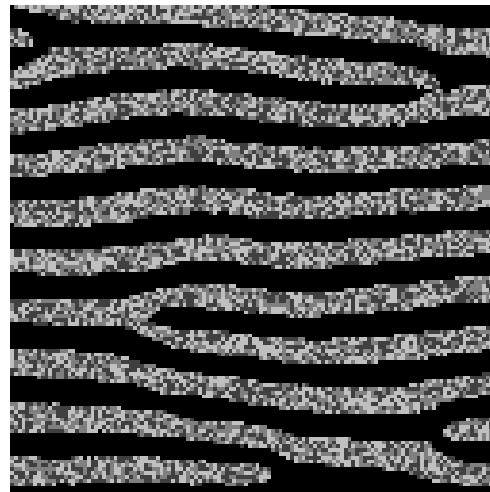


- Created statistical textures using Pseudo Image Synthetic Aperture Sonar (PISAS) dataset
- Two structures: sand ripple and rocky

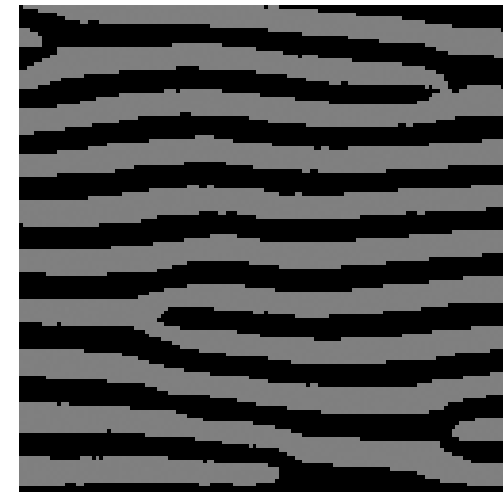
S1: Binomial



S2: Multinomial



S3: Constant



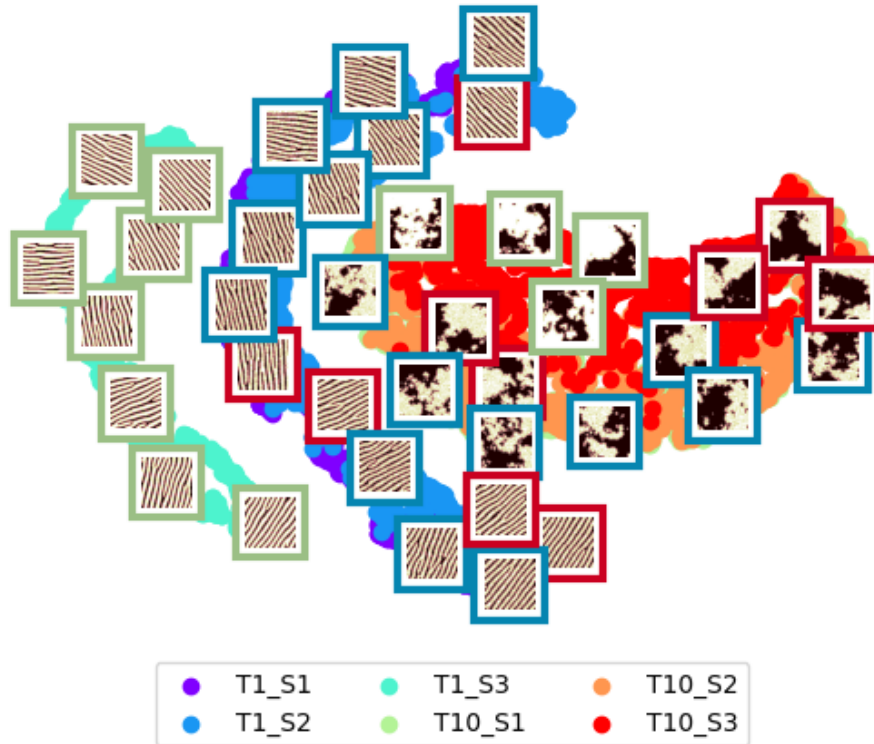
Statistical SAS Images Results



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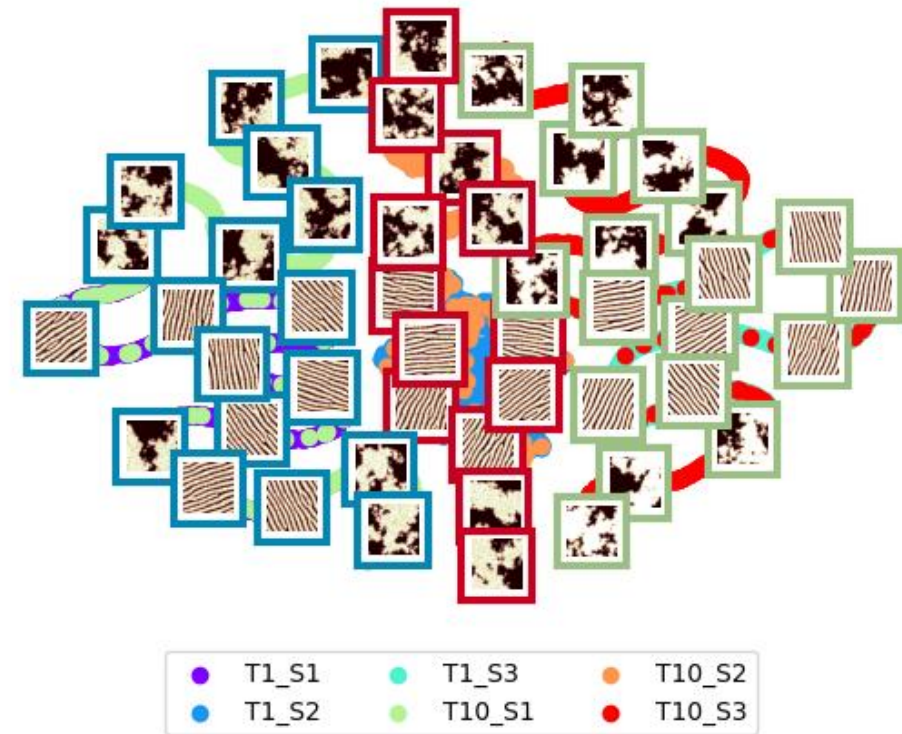
CNN (77.70)

TSNE Visualization of Training Data Features with Images



RBF (82.18)

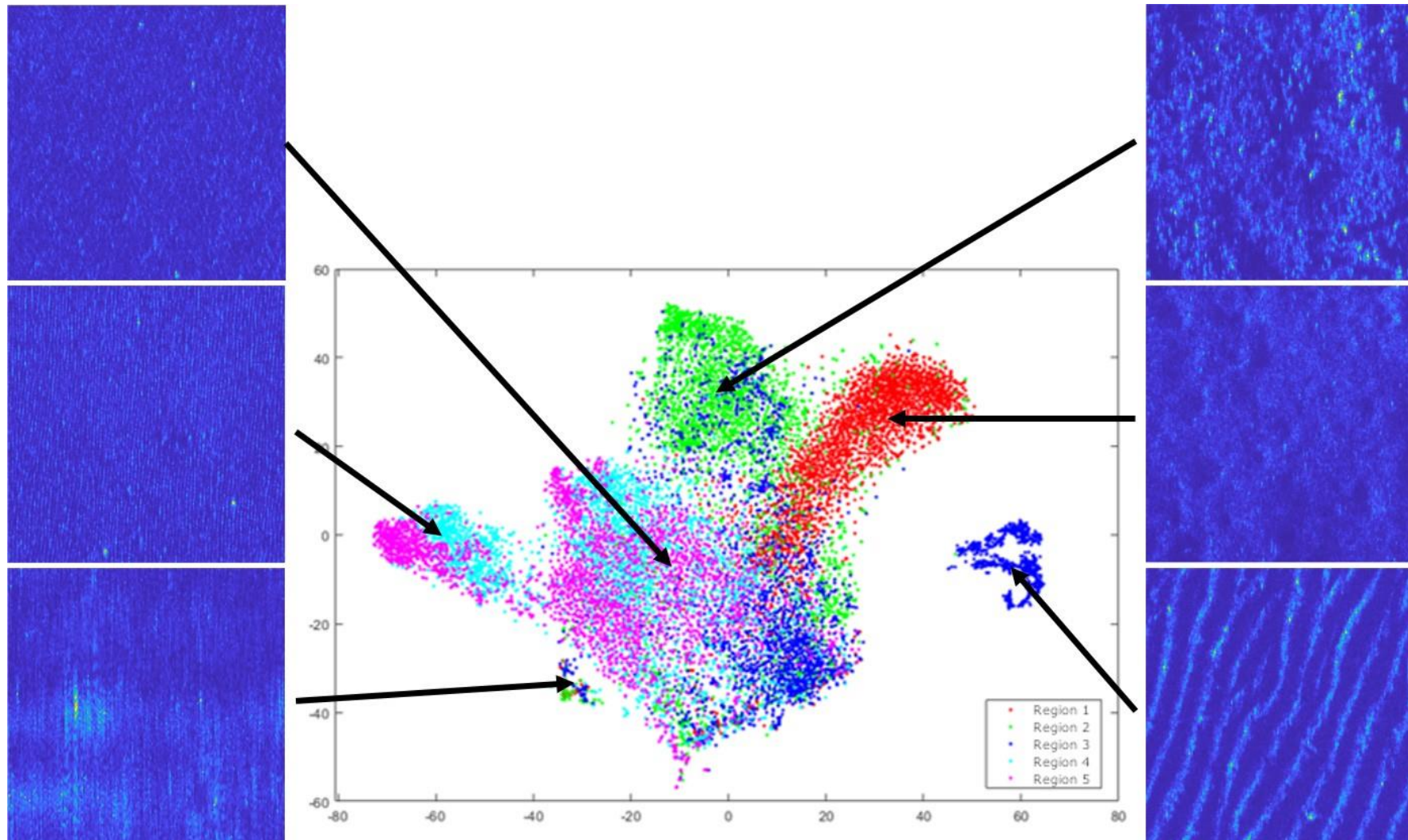
TSNE Visualization of Training Data Features with Images



Generalization to SAS Images



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Agriculture

Traditional WinRhizotron Analyses do not capture the whole picture



All images stacked across cultivars

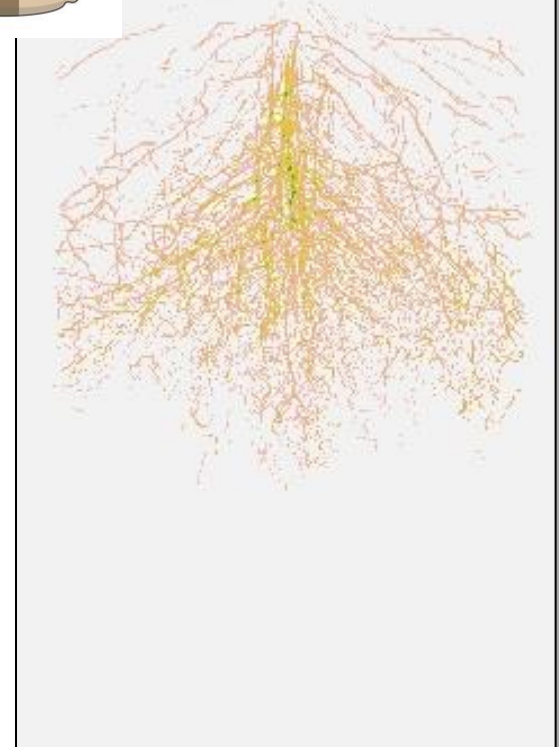
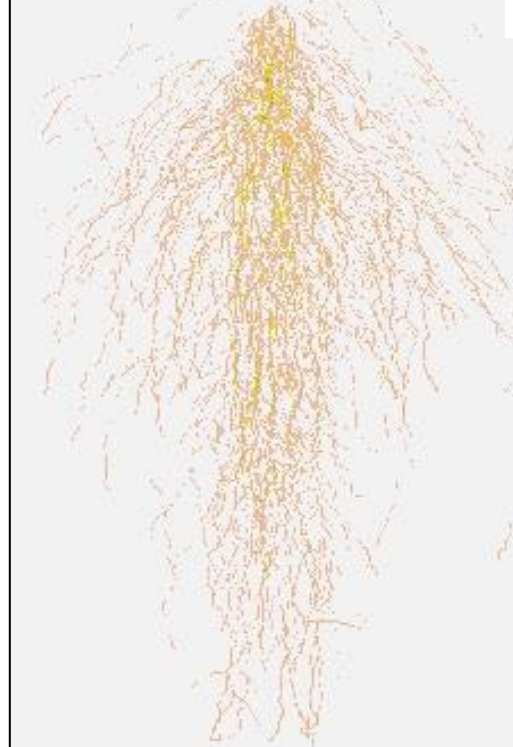
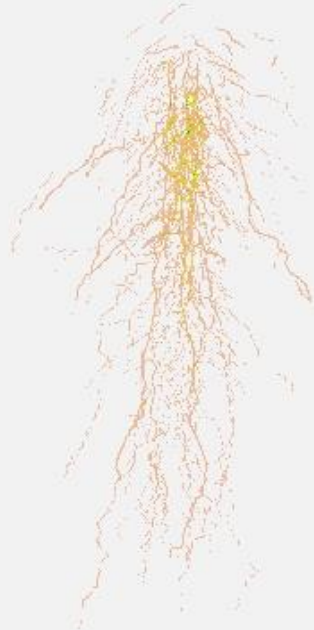
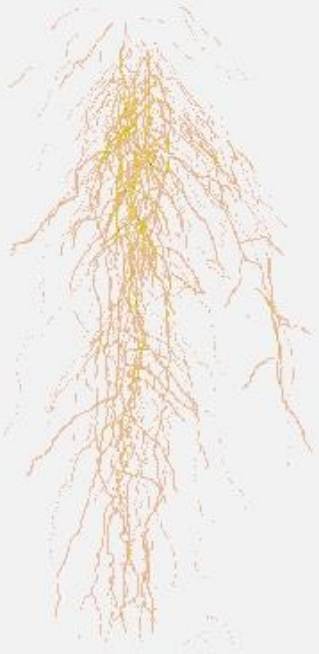
60% moisture

120% moisture



60% moisture

120% moisture



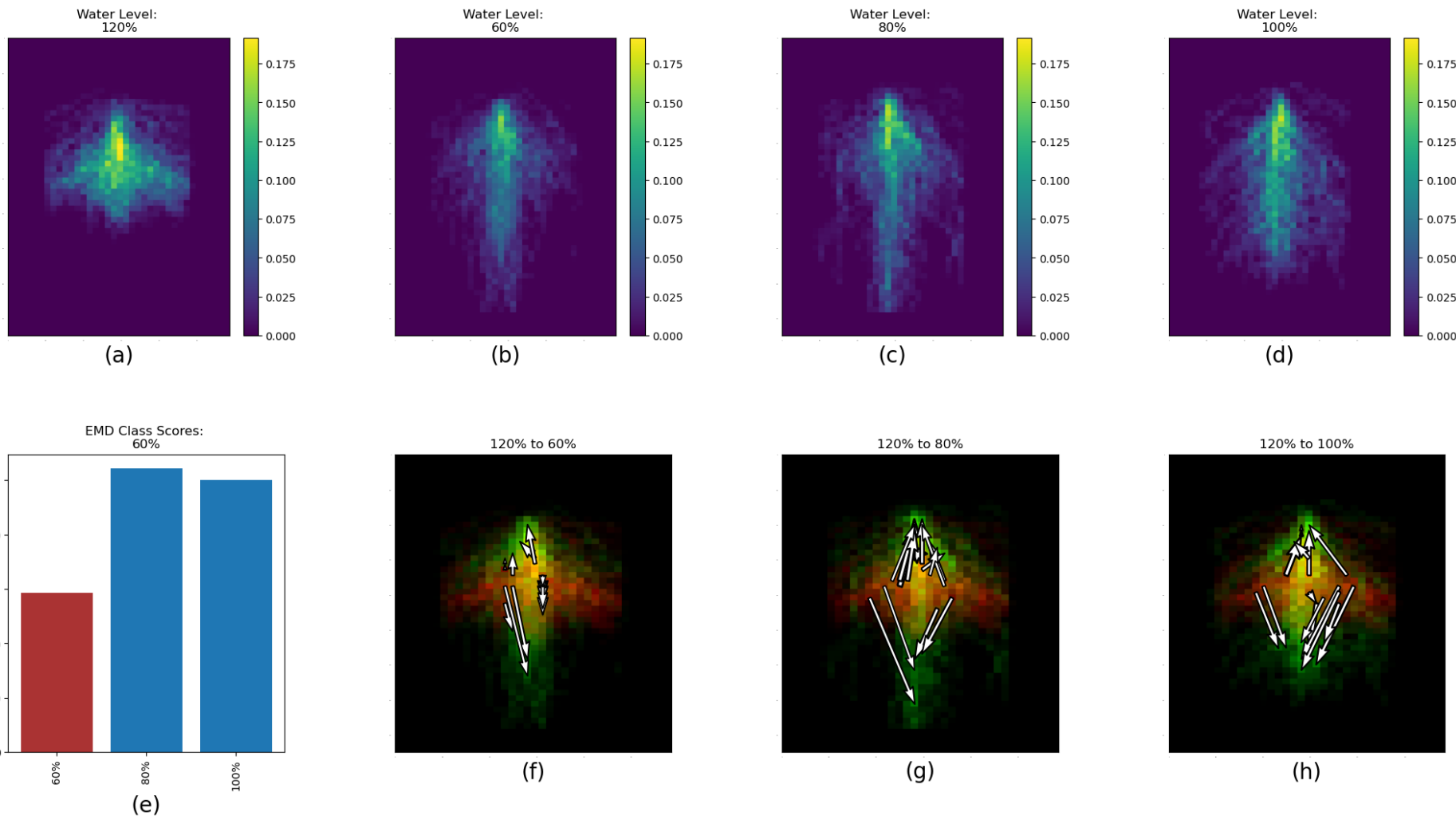
Not enough resources to avoid the flooding stress

Enough resources to produce more lateral roots and avoid the waterlogged soil

EMD Workflow for Water Level 120% (with fertilizer)

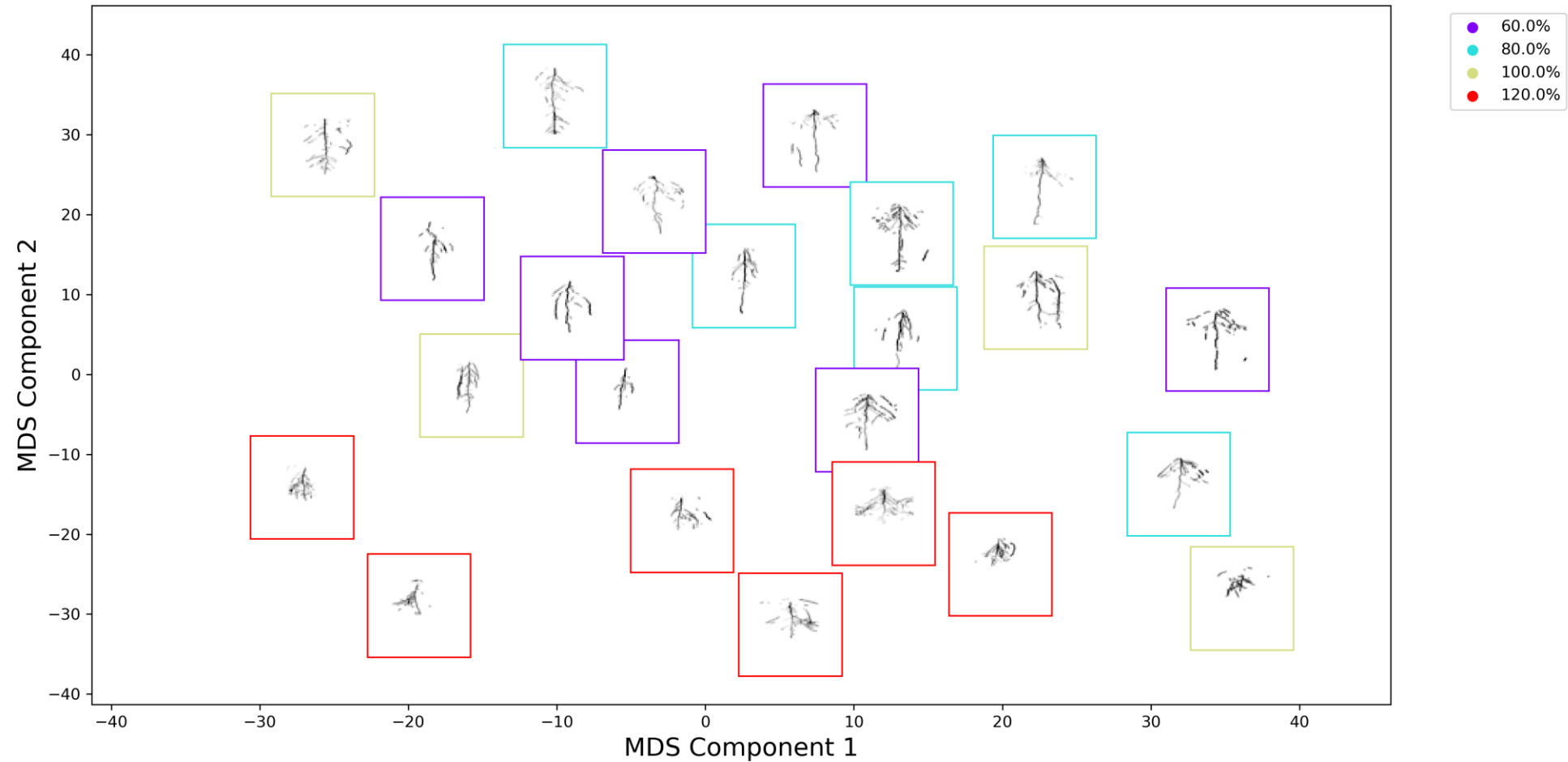


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Red channel is current class; green channel is other class; yellow means "unchanged"

Plant Root Analysis



Next class



- No class Monday (Labor Day)
- Wednesday (09/04): Frequent Itemset Mining and Association Rules

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Thank You! Questions?
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Supplemental Slides

- [Eigenvectors and eigenvalues](#)
- [PCA in 5 minutes](#)
- [PCA Step-by-Step](#)
- [Introduction to KPCA](#)