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History of UAV

Early 20th century

1930s-1940s

1950s-1960s

1970s-1980s

- Radio-controlled aircraft developed, laying the groundwork for UAVs
- Early UAVs used for military target practice and reconnaissance, but limited in range and reliability
- Development of jet-powered UAVs for military reconnaissance and surveillance
- UAVs developed for military applications, including the armed Predator UAV for military strikes

History of UAV

1990s

2000s

Recent years

- Commercial applications for UAVs emerge, including aerial photography, surveying, and agriculture
- UAV technology used in military operations, including the War on Terror, with the development of the Global Hawk UAV for reconnaissance and surveillance
- Consumer drones for hobbyists and enthusiasts become popular, used for photography, videography, and recreational purposes

History of UAV

Today

- UAV technology used in a wide range of applications, including military, commercial, and consumer applications, such as search and rescue, wildlife conservation, and disaster response. UAV technology continues to advance, with more innovative applications expected in the future.



Fixed-Wing UAVs

- These UAVs have a fixed wing and use aerodynamic lift to fly.
- Eg: General Atomics MQ-9
 Reaper, Boeing Insitu ScanEagle,
 Northrop Grumman RQ-4 Global
 Hawk



Multi-Rotor UAVs

- These UAVs have multiple rotors and are used for short-range flights and hovering.
- Eg: DJI Phantom, Yuneec TyphoonH, DJI Inspire



Hybrid UAVs

- These UAVs combine features of both fixed-wing and multi-rotor UAVs, allowing for vertical takeoff and landing (VTOL) and efficient long-range flight.
- Eg: Vertical Aerospace VA-X4,
 Skyfront Perimeter 4, Quantum
 Systems Trinity



Vertical Aerospace VA-X4



Quantum Systems Trinity.



i. UAV Design



Fixed-wing

Advantages

- Can fly for long periods of time, covering large distances
- High payload capacity, allowing for larger cameras and sensors
- High speed and altitude capabilities

- Requires a runway or launcher for takeoff and landing
- Cannot hover in place or maneuver in tight spaces
- May require more advanced piloting skills to operate

i. UAV Design



Multi-Rotor UAVs

Advantages

- Can hover in place and maneuver in tight spaces
- Easy to operate and control, even for beginners
- VTOL capabilities, allowing for launch and landing in small areas

- Shorter flight times and range compared to fixed-wing UAVs
- Limited payload capacity, restricting the size of cameras and sensors that can be used
- Can be affected by wind and weather conditions, making them less stable in some situations

i. UAV Design



Hybrid UAVs

Advantages

- Combines the advantages of fixed-wing and multi-rotor UAVs, including VTOL capabilities and efficient long-range flight
- Can fly for longer periods of time than multi-rotor UAVs
- Can be used in a variety of applications, including military and commercial uses

- More complex and expensive than fixedwing or multi-rotor UAVs
- May require more advanced piloting skills to operate
- Payload capacity may be limited compared to fixed-wing UAVs

ii. Propulsion



Rotary propulsion

Advantages

- Provides stable and agile movement
- Good for hovering and maneuvering in tight spaces
- Can be used for vertical takeoff and landing (VTOL)

- Limited range and endurance compared to other propulsion systems
- High power consumption
- Can be noisy

ii. Propulsion



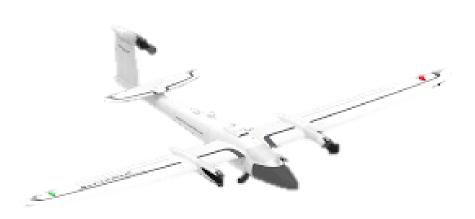
Fixed-wing propulsion

Advantages

- Efficient for long-range flight
- Can carry heavy payloads
- Can reach high speeds and altitudes

- Requires a runway or launcher for takeoff and landing
- Less agile than rotary propulsion systems
- Cannot hover in place

ii. Propulsion



Hybrid propulsion

Advantages

- Combines the advantages of rotary and fixed-wing propulsion systems, allowing for efficient and stable flight as well as VTOL capabilities
- Can be used in a variety of applications, including military and commercial uses
- Provides greater endurance and range compared to rotary propulsion systems

- More complex and expensive than single propulsion systems
- May require more advanced piloting skills to operate
- Payload capacity may be limited compared to fixed-wing UAVs

iii. Navigation System & Control

Flight Controller:

the brain of the UAV responsible for controlling its movement and stability in the air



GPS Receiver

provides location and orientation data to the flight controller

Remote Control

allows the operator to control the UAV from a safe distance

NAVIGATION SYSTEM

Sensors

have a variety of sensors

provide data on the aircraft's movement, environment, and performance

iii. Navigation System & Control

Power System

includes the battery or fuel source that powers the UAV's propulsion and electronic systems

Communication System

allows the UAV to send and receive data between the aircraft and the ground station



Ground Station

the control center for the UAV

includes a computer or mobile device running software

Manipulators

These allow the operator to manipulate objects with the ROV.

iv. Data Collection & Transmission



Camera

Cameras are commonly used on UAVs to capture images and video of the surrounding environment. The camera may be mounted on the UAV itself or on a gimbal that can stabilize the camera and adjust its angle.

Sensors

UAVs may be equipped with a variety of sensors for collecting data on the environment, such as temperature, humidity, air pressure, and wind speed. These sensors can provide valuable information for scientific research, environmental monitoring, and disaster response.

Data Storage

Data storage devices, such as memory cards or onboard hard drives, allow the UAV to store data collected during flight. This data can be later retrieved for analysis or processing.

Wireless Data Transmission

Wireless data transmission components, such as Wi-Fi, Bluetooth, or cellular networks, allow the UAV to transmit data back to the ground station in real-time.

VIDEORAY PRO 4 ROV

iv. Data Collection & Transmission



VIDEORAY PRO 4 ROV

Ground Control Software

Ground control software allows the operator to monitor the UAV's flight and data collection in real-time. The software may include features for viewing video feeds, analyzing sensor data, or controlling the UAV's flight path

Data Processing Software

Data processing software allows the collected data to be analyzed, processed, and visualized. This software may include tools for image processing, data analysis, or mapping.

Payload Integration

Payload integration allows additional equipment to be attached to the UAV for specific data collection purposes. Examples of payloads may include LiDAR sensors, magnetometers, or radiation detectors.

v. Power Management

Batteries	Batteries are the primary source of power for most UAVs. They can be either rechargeable or disposable, and come in a variety of chemistries, such as lithium-ion or nickel-metal hydride. The battery capacity and type must be selected based on the UAV's power requirements and flight time.
	Power distribution components, such as voltage regulators, distribute the power from the battery to the various electronic components on the UAV. The power distribution system must be designed to handle the UAV's power requirements and ensure that each component receives the correct voltage and current.
Solar Panels	Solar panels can be used to charge the UAV's batteries during flight. They are typically only used for long-endurance UAVs that can remain in flight for extended periods.
Fuel Cells	Fuel cells can be used to provide power to the UAV. They are typically used for larger UAVs that require longer flight times and higher power output.
Energy Harvesting	Energy harvesting techniques, such as regenerative braking or energy recovery systems, can be used to recover energy that would otherwise be lost during flight. This energy can be used to power the UAV or recharge its batteries
Power Monitoring	Power monitoring components, such as voltage and current sensors, are used to monitor the power consumption of the UAV's electronic components. This data can be used to optimize the UAV's power usage and maximize its flight time.



Advantages

1 2 3

UAVs are generally less expensive than manned aircraft, making them more accessible for a wider range of applications.

Cost

UAVs can be used in hazardous or difficult-to-reach locations without risking human life. They can also be used in disaster zones to survey damage or deliver supplies.

Safety

UAVs can be programmed to fly precise routes and perform repetitive tasks, which can save time and increase efficiency.

Efficiency

UAVs can be equipped with a wide range of sensors and cameras, making them useful for a variety of applications, such as mapping, agriculture, and search and rescue.

Flexibility



Limitations of ROV

Limitations

1 2 3

Limited Flight Time Payload Limitation s

Vulnerabilit y to Weather Cybersec urity Risks

UAVs have limited flight time due to their battery life, which can restrict their range and usefulness for certain applications.

UAVs have limited payload capacity, which can limit their ability to carry heavy or bulky equipment.

UAVs are vulnerable to adverse weather conditions, such as high winds or rain, which can limit their ability to fly. UAVs are vulnerable to cybersecurity risks, such as hacking or interception of data, which can compromise their mission and pose a threat to public safety.



In conclusion, UAVs have come a long way since their inception and have found applications across various numerous industries. They offer several advantages, such cost-effectiveness, safety, as efficiency, and flexibility. However, they also have limitations and disadvantages, such as limited flight time, payload restrictions, and vulnerability to weather and cybersecurity risks. With continued technological advancements and regulatory improvements, UAVs have the potential to revolutionize industries and improve our daily lives in many ways.



Thank You