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ENDSEM

```
In [1]: import numpy as np
import matplotlib.pyplot as plt
import cv2
import skimage
```

Q15

```
In [2]: M = np.array([
    [0.7679, - 0.4938, -0.0234, 0.0067],
    [-0.0852, -0.0915, -0.9065, -0.0878],
    [0.1827,0.2988,-0.0742,1.000]
])
```

```
In [3]: H = M[:,3]
h = M[:,3].reshape(3,1)
H_inv = np.linalg.inv(H)
H_inv
```

```
Out[3]: array([[ 0.93072703, -0.14626022,  1.49334069],
               [-0.57636511, -0.1766679 ,  2.3401131 ],
               [-0.02930009, -1.07156483, -0.37656147]])
```

```
In [4]: R_T,K_inv = np.linalg.qr(H_inv)
R_T
```

```
Out[4]: array([[ -0.84987872, -0.13141145, -0.51033048],
               [ 0.52629872, -0.16249257, -0.83462915],
               [ 0.02675492, -0.97791983,  0.20726065]])
```

```
In [5]: K_inv
```

```
Out[5]: array([[ -1.09512923e+00,  2.65373217e-03, -4.76348136e-02],
               [ 0.00000000e+00,  1.09583198e+00, -2.08246122e-01],
               [ 0.00000000e+00,  0.00000000e+00, -2.79327026e+00]])
```

```
In [6]: K = np.linalg.inv(K_inv)
K = K/K[2,2]
K , 'Intrinsic Martix'
```

```
Out[6]: (array([[ 2.55063072, -0.00617676, -0.04303648],
               [-0.          , -2.54899501,  0.19003472],
               [ 0.          ,  0.          ,  1.          ]]),
        'Intrinsic Martix')
```

```
In [8]:
```

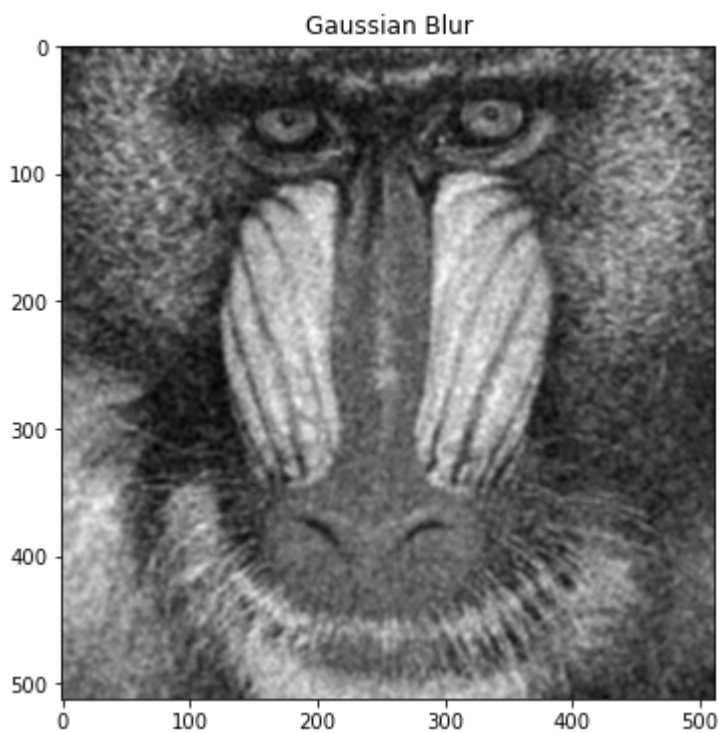
```
t = K_inv@h
t
```

```
Out[8]: array([[ -0.05520518],
              [-0.30446017],
              [-2.79327026]])
```

Q19

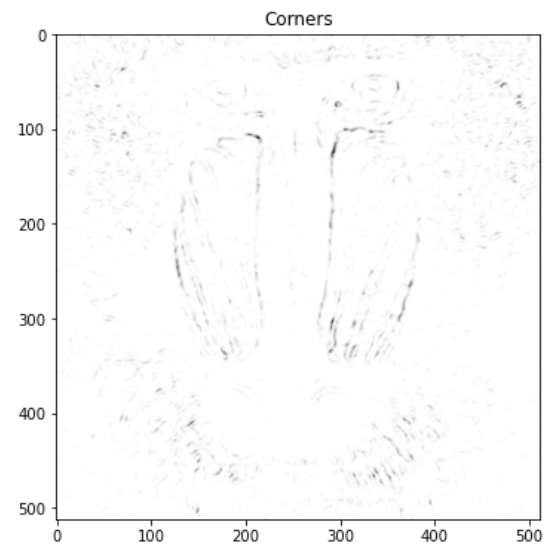
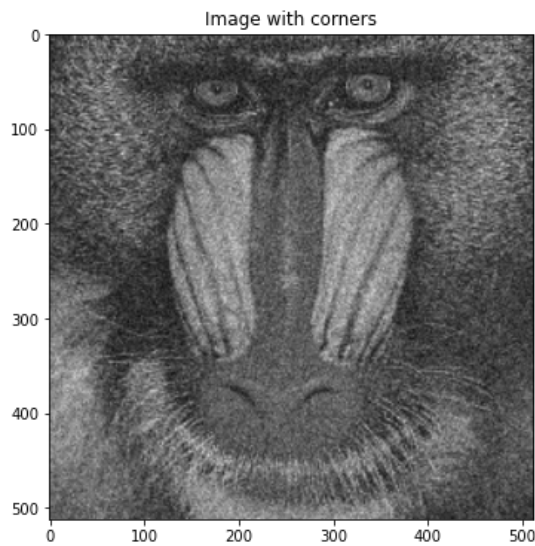
```
In [39]: img = cv2.imread('baboon.tiff')
img = cv2.cvtColor(img,cv2.COLOR_BGR2GRAY)
gauss_img = cv2.GaussianBlur(img,(5,5),2)
plt.figure(figsize = (16,6))
plt.subplot(121),plt.imshow(gauss_img,cmap = 'gray'),plt.title('Gaussian Blur')

plt.show()
```



```
In [41]: import cv2 as cv
gray = np.float32(gauss_img)
plt.figure(figsize = (16,6))
dst = cv.cornerHarris(gray,2,3,0.7)
#result is dilated for marking the corners, not important
# dst = cv.dilate(dst,None)
# Threshold for an optimal value, it may vary depending on the image.
img[dst>0.01*dst.max()]=[255]
# plt.imshow(img,'gray')
plt.subplot(121),plt.imshow(img,cmap = 'gray'),plt.title('Image with corners')
plt.subplot(122),plt.imshow(dst,cmap = 'gray'),plt.title('Corners')
```

```
Out[41]: (<AxesSubplot:title={'center':'Corners'}>,
<matplotlib.image.AxesImage at 0x110539d7820>,
Text(0.5, 1.0, 'Corners'))
```

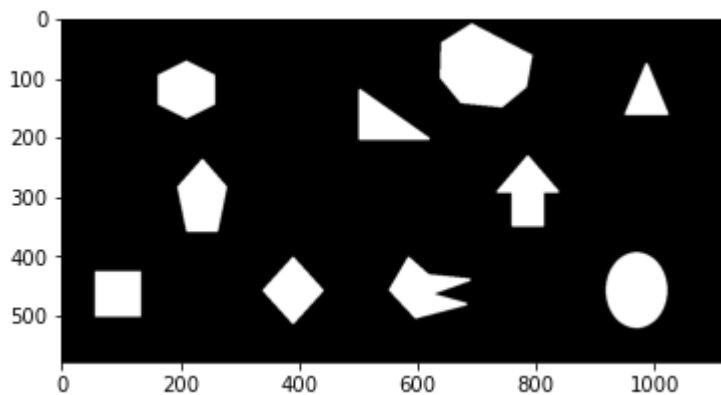


Explanation is in the written sheet

Q21

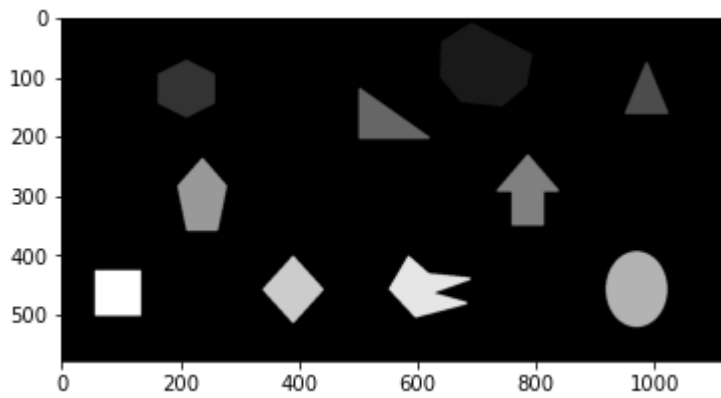
```
In [42]: from skimage.measure import label, regionprops
```

```
In [43]: img = cv2.imread('binaryshapes.png',cv2.IMREAD_GRAYSCALE)
ret1,thresh_img = cv2.threshold(img,100,1,cv2.THRESH_BINARY)
plt.imshow(img ,cmap ='gray')
plt.show()
```



```
In [44]: labelled_img,labels = label(thresh_img,connectivity=2,return_num=True) # for 8 Neighbo
print("No. of components is : ",labels)
plt.imshow(labelled_img ,cmap ='gray')
plt.show()
```

No. of components is : 10



In [56]:

```
regions_proper = regionprops(labelled_img)
for region in regions_proper:
    # print('Eccentricity:', region.eccentricity)
    print('Centroid:', region.centroid)
    print('BBox', region.bbox)
    print('_'*10)

plt.figure(figsize=[16,20])
plt.subplot(131)
plt.title('Original image')
plt.imshow(img, 'gray')
# ret, thresh = cv2.threshold(img, 127, 255, 0)
contours, hierarchy = cv2.findContours(thresh_img, 1, 2)
blank = np.zeros(thresh_img.shape[:2], dtype='uint8')
cv2.drawContours(blank, contours, -1, (255, 0, 0), 1)
plt.subplot(132)
plt.title('Contours')
plt.imshow(blank, 'gray')

fig, ax = plt.subplots()
ax.imshow(thresh_img, cmap=plt.cm.gray)

for props in regions_proper:
    y0, x0 = props.centroid

    ax.plot(x0, y0, '.g', markersize=15)

    minr, minc, maxr, maxc = props.bbox
    bx = (minc, maxc, maxc, minc, minc)
    by = (minr, minr, maxr, maxr, minr)
    ax.plot(bx, by, '-b', linewidth=2.5)

# ax.axis((0, 600, 600, 0))
plt.show()
```

Centroid: (81.55491618714035, 712.1126469852389)
BBox (7, 639, 149, 796)

Centroid: (118.5, 211.0)
BBox (70, 163, 168, 260)

Centroid: (130.93626750500144, 987.5261503286654)
BBox (74, 951, 162, 1025)

Centroid: (174.04909420289854, 543.1807971014492)
BBox (118, 502, 204, 622)

Centroid: (294.4080442583732, 787.0109150717703)
BBox (230, 735, 350, 840)

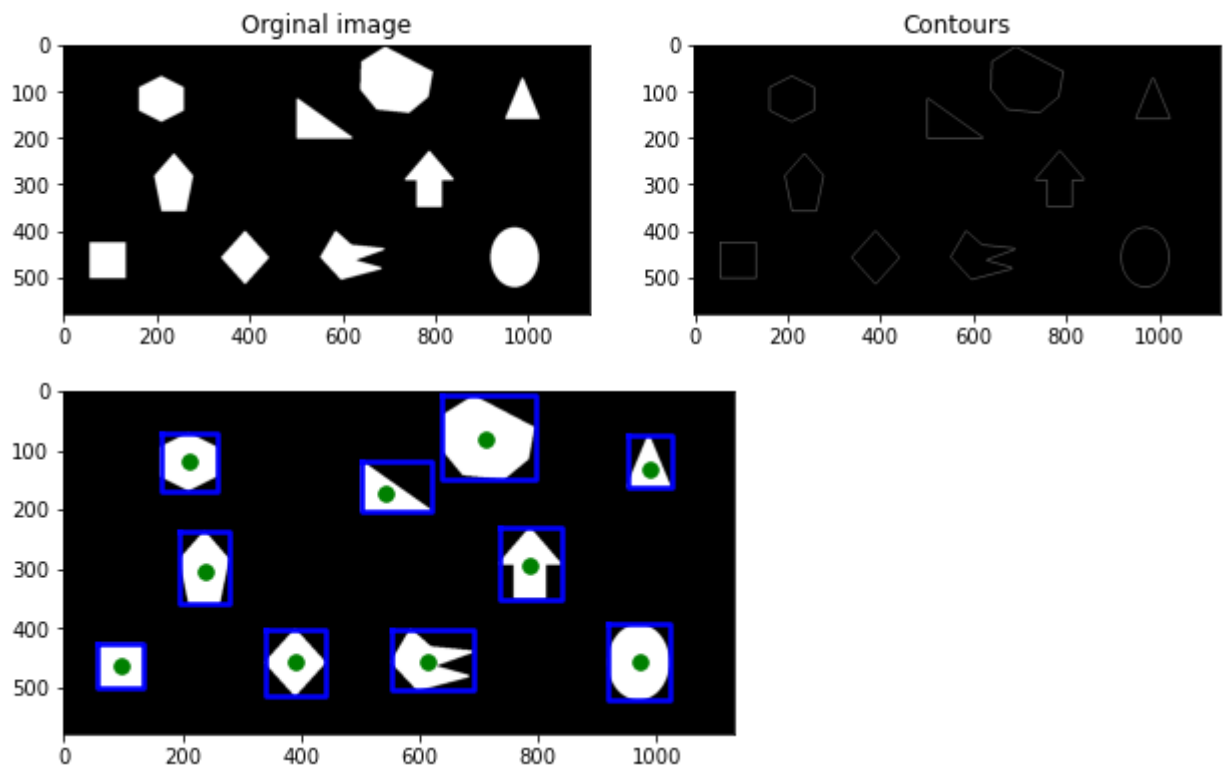
Centroid: (303.2117210070161, 237.58206080616316)
BBox (236, 196, 359, 280)

Centroid: (456.5222381635581, 970.5423242467718)
BBox (393, 919, 521, 1023)

Centroid: (457.03032311516154, 391.0245236122618)
BBox (401, 340, 514, 443)

Centroid: (457.21307439824943, 612.2175875273523)
BBox (401, 553, 505, 691)

Centroid: (463.0, 95.5)
BBox (425, 57, 502, 135)



Q18

```
In [58]: F = np.array([
    [-0.00310695, -0.0025646, 2.96584],
    [-0.028094, -0.00771621, 56.3813],
    [13.1905, -29.2007, -9999.79]
])
```

```
Out[58]: array([ 1.32993765e+00,  4.50194844e+01, -1.19422527e+04])
```

```
In [61]: np.linalg.matrix_rank(F)
```

```
Out[61]: 3
```

```
In [75]: Ua, Da, Va = np.linalg.svd(F)
         _Da = np.zeros([3,3])
         _Da[0,0] = Da[1]
         _Da[1,1] = Da[2]
         _Da
```

```
Out[75]: array([[0.17879964, 0.          , 0.          ],
                [0.          , 0.00212909, 0.          ],
                [0.          , 0.          , 0.          ]])
```

```
In [76]: _F = Ua@_Da@Va
```

```
In [78]: np.linalg.matrix_rank(_F)
```

```
Out[78]: 2
```

```
In [79]: X = np.array([343.53,221.70,1.0]).T
         _F@X
```

```
Out[79]: array([-0.016428 , -0.26509613, -0.21503112])
```

```
In [ ]:
```