# Islam Gamal 11 Karim Mohamed 45

# Search by Images

**Using Auto Encoders** 

## The selected one to expand on.

#### **Feature Detection**

Using algorithms for matching image deformation such as blur, rotation, scale, and illumination change.
Such as SIFT. PCA-SIFT and SURF

#### **Feature Detection**

A set of algorithms is used to analyze image attributes <u>ex</u> (<u>colour, shape, texture, luminosity, complexity, objects and regions</u>). These attributes are stored for indexing and this can be used with keywords to refine searches on extremely large collections.

#### Search by Color

"Piximilar Multicolor Search process"

Given archive of images  $\rightarrow$  create digital signature based colors (<u>color histograms</u>)  $\rightarrow$  store the extracted signatures in database  $\rightarrow$  whenever given a query image, extract its colors  $\rightarrow$  find the most suitable matching image

#### Auto Encoder

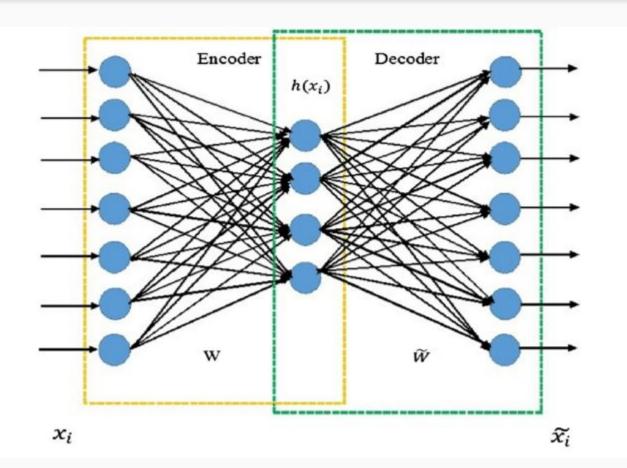
Encoding Images into 1D vector array and then finding the Nearest neighbours to a given query image.

#### Related work.

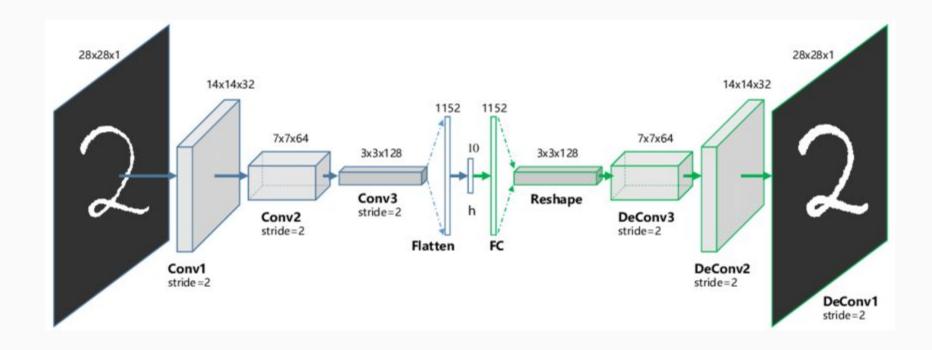
#### People Approaches to the Auto encoder.

- 1. Fully connected layers.
- 2. Fully convolutional way
  - a. Encoder: Conv + pooling
  - b. Decoder: Conv + Up sampling
- 3. Convolution, DeConvolution
  - a. Encoder: Accumulative convolutions layers + Pooling.
  - b. Decoder: Accumulative transpose convolutional layers.
- 4. Mix of 2 and 1

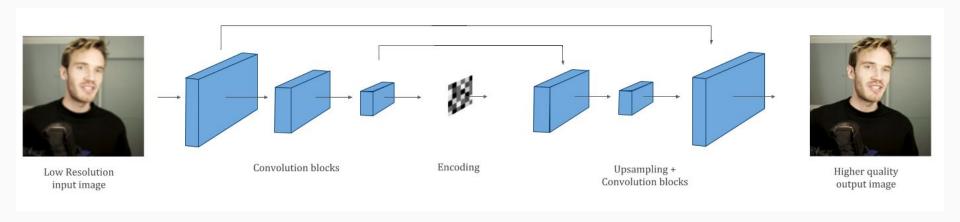
#### Fully Connected Layers Methodology - Architecture



#### Fully Convolutional way - Architecture



### Convolutional + Up Sampling - Architecture

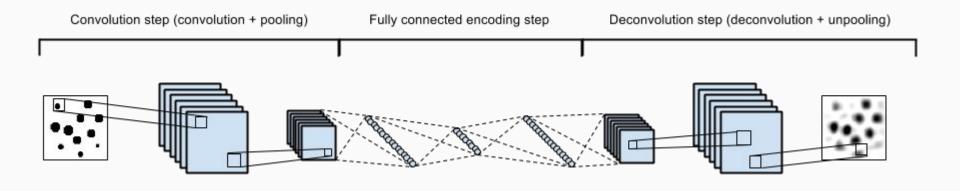


# Our proposed solution/model and Difference from related work.

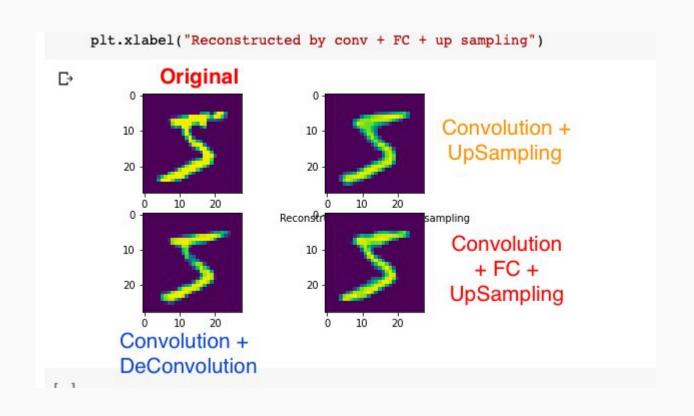
## mixed approach with <u>Convolutional Neural Networks (CNNs)</u> and <u>FC layers</u>

- The **Encoder** consists of the following layers
  - ✓ Convolutional Layers.
  - ✓ Non-Linearity layers.
  - ✓ Rectification Layers (can use just ReLU).
  - ✓ Pooling layers (Average and Max pooling)
  - ✓ Fully connected layers.
  - ✓ Dropout layers.
- The **<u>Decoder</u>** consists of the following layers
  - ✓ FC layers (undos effect of last layer in encoder).
  - ✓ Transpose Convolution Layers (Reversing the encoder)

### Model Architecture (CNN + FC + Trans Conv)



#### Applying the models on MNIST (Handwriting) dataset.



Approach MSE train loss by	Them	Winner	Us
Fully Connected Only	0.0214	$\rightarrow$	0.0026
Convolution + Up Sampling	0.0407	$\rightarrow$	0.0065
Convolution + DeConvolution	0.0297	$\rightarrow$	0.0091
Conv + FC + Up Sampling	0.0173	$\rightarrow$	0.0050

#### Them:

https://towardsdatascience.com/aligning-hand-written-digits-with-convolutional-autoencoders-99128b83af8b https://towardsdatascience.com/build-a-simple-image-retrieval-system-with-an-autoencoder-673a262b7921 https://medium.com/analytics-vidhya/building-a-convolutional-autoencoder-using-keras-using-conv2dtranspose-ca403c8d144e

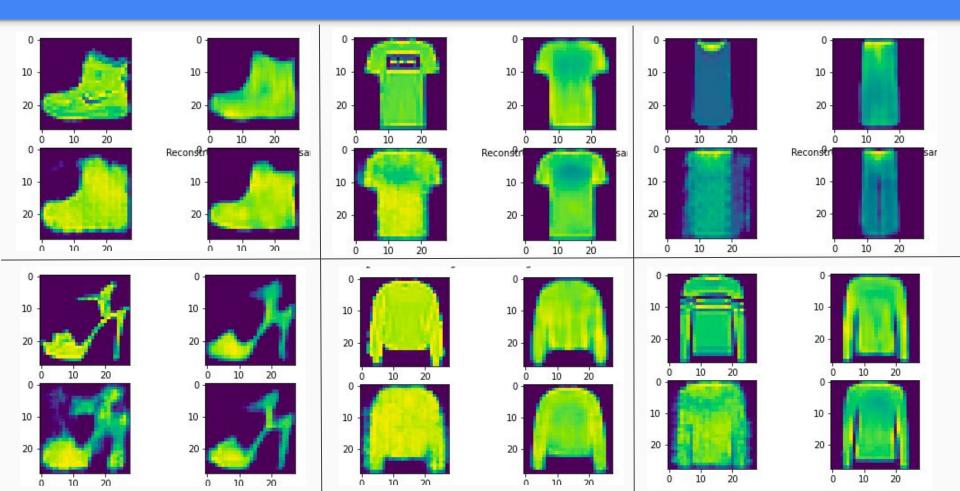
## Confusing



# Using a new dataset

MNIST for fashion

### Applying the models on MNIST (Handwriting) dataset.



Approach MSE train loss by	Them	Us (Fashion MNIST)	Us (HandWriting MNIST)
Fully Connected Only	0.0214	0.00543	0.0026
Convolution + Up Sampling	0.0407	0.0131	0.0065
Convolution + DeConvolution	0.0297	0.049	0.0091
Conv + FC + Up Sampling	0.0173	0.0091	0.0050

#### Them:

https://towardsdatascience.com/aligning-hand-written-digits-with-convolutional-autoencoders-99128b83af8b https://towardsdatascience.com/build-a-simple-image-retrieval-system-with-an-autoencoder-673a262b7921 https://medium.com/analytics-vidhya/building-a-convolutional-autoencoder-using-keras-using-conv2dtranspose-ca403c8d144e

#### VAE

# Variational Autoencoders

2. Using Variational autoencoders instead on normal autoencoders.

#### WHY?

Given a dataset that we want to encode it all, the resulted latent layers will be in a clustering form, not a continuous form, so if a target image contained some noise or error, there is a high probability that the produced vector will not be close to the original one, it may be considered as another cluster.

(Unsupervised learning)

#### VAE

# Variational Autoencoders

2. Using Variational autoencoders instead on normal autoencoders.

#### **BUT**

With using Variational autoencoders, the encoded dataset will be in a continuous way since the latent layers has learnt a distribution in the input images.

So it will be more reasonable and confidential to use the nearest neighbour algorithms to find the target image from it's encoded version.

(Supervised learning)

#### VAE Model Architecture. (encoder)

C→	Model:	"encoder"
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Layer (type)	Output	Shape	Param #	Connected to
encoder_input (InputLayer)	(None,	784)	0	
dense_4 (Dense)	(None,	512)	401920	encoder_input[0][0]
z_mean (Dense)	(None,	2)	1026	dense_4[0][0]
z_log_var (Dense)	(None,	2)	1026	dense_4[0][0]
z (Lambda)	(None,	2)	0	z_mean[0][0] z_log_var[0][0]

Total params: 403,972

Trainable params: 403,972 Non-trainable params: 0

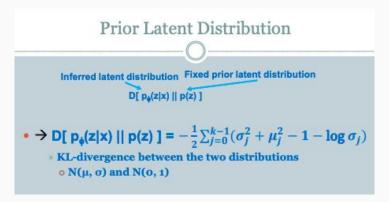
### VAE Model Architecture. (decoder)

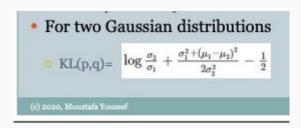
Layer (type)	Output	Shape	Param #
z_sampling (InputLayer)	(None,	2)	0
dense_5 (Dense)	(None,	512)	1536
dense_6 (Dense)	(None,	784)	402192
Total params: 403,728			
Trainable params: 403,728 Non-trainable params: 0			

## **Evaluation Metrics**

#### **Reconstruction loss + K-L loss.**

- Reconstruction loss → using (Cross Entropy) OR (mean square error)
- K-L loss → K-L Divergence Metric → rule.





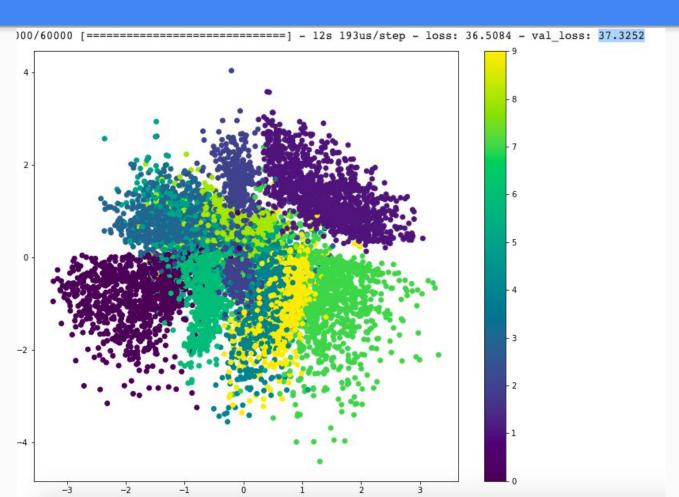
#### From Dr. Moustafa Youssef Slides

https://piazza.com/class\_profile/get\_resource/k6mquuyyw903ch/k9cp4lzsi2a1n8

## 37.3252

**Evaluated Loss** 

#### Visualizations to the continuous distribution of the latent vectors.



#### Visualizations to the continuous distribution of the latent vectors. (Interpolation)

# Another proposed solution/model and Difference from related work.

- 3. Third we will try to improve that by using Recurrent Neural Networks (**RNN**) instead of CNN:
  - <u>LSTM</u> network:
    - ✓ Each layer of LSTM has as many cells as the timesteps and using ReLU as activation function.
    - ✓ It takes 2d as input (each layer).
    - ✓ If the subsequent layer is also LSTM, we will duplicate this vector using "RepeatVector(timeSteps)" to get a 2D array for the next layer.

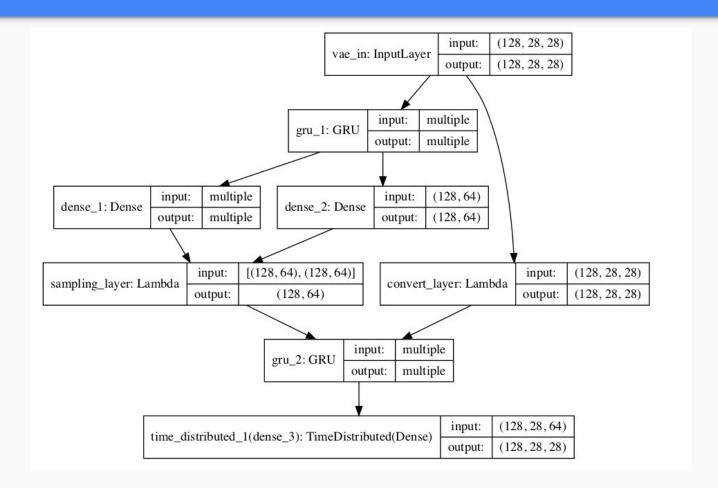
## RNN architectures made no sense

Since there is no sequence in the input, they are just random consecutive numbers from 0 to 9 so it's not confidential to use the RNN for this type of problems except

1. Sorting the input in a circular way  $\rightarrow$  0, 1,2,3 .. ,8 , 9, 0, 1 2 .. and learn the natural counting pattern in order to identify whether an input sequence is in correct counting order or not.

2. Using videos instead of images and predicting the next frame to enhance the searching speed.

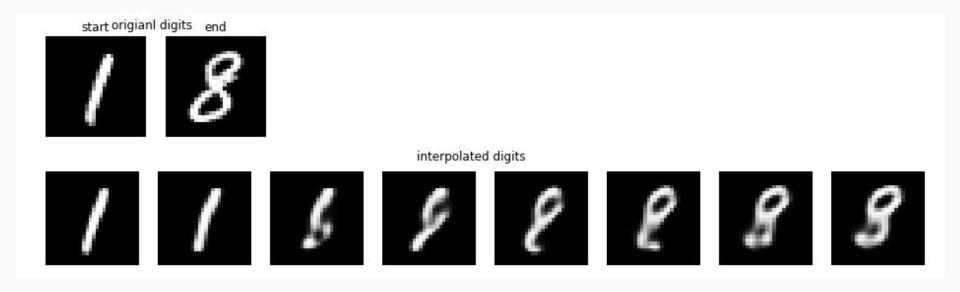
#### RNN (GRU) Model Architecture



## 67.4471

**Evaluated Loss** 

#### Interpolation example (8 steps)



# Our proposed solution/model and Difference from related work.

4. Finally we will try to use the <u>Attention model</u> alongside RNN Encoder-Decoder model:

A potential issue with this encoder—decoder approach is that a neural network needs to be able to compress all the necessary information of a source information into a fixed-length vector. This may make it difficult for the neural network to cope with long or big images, especially those that are larger than the images in the training corpus.

Attention model is proposed as a solution to this limitation.

#### **Achievements**

- ✓ FC layers.
- ✓ Conv + Up Sampling.
- ✓ Conv + TransposeConv.
- ✓ Conv + FC + Up Sampling.
- ✓ Conv + FC + Transpose Conv.
- ✓ Using different datasets
- ✓ Variational AutoEncoders.
- ✓ RNNs + VAE
- Attention Model
- Apply nearest neighbour to be done.

# What we have achieved so far.

## Thanks!