```
import numpy as np
import cv2 as cv
img = cv.imread('img/F1.bmp',0)
# Apply thresholding to convert to binary
_, img = cv.threshold(img, 127, 255, cv.THRESH_BINARY)
se = np.array([
   [1,1,1,1,1],
    [1,1,1,1,1],
    [1,1,1,1,1],
   [1,1,1,1,1],
   [1,1,1,1,1]
   ])
\# se = np.ones((5))
def Dilation(img , se):
   Dilation_img = np.zeros_like(img)
   r , c = img.shape
   k_r , k_c = se.shape
   for i in range(k_r//2, r-k_r//2):
       for j in range(k_c/2, c-k_c/2):
           image_patch = img[i-k_r//2 : (i+k_r//2)+1 , j-k_c//2 : (j+k_c//2)+1 ]
           apply_or = np.logical_and(image_patch , se)
           Dilation_img[i,j] = np.max(apply_or)
   return Dilation img
def erosion(img , se):
   erosion img = np.zeros like(img)
   r , c = img.shape
   k_r , k_c = se.shape
   for i in range(k_r//2, r-k_r//2):
for j in range(k_c//2, c-k_c//2):
           image_patch = img[i-k_r//2 : (i+k_r//2)+1 , j-k_c//2 : (j+k_c//2)+1 ]
           apply_and = np.logical_and(image_patch , se)
           erosion_img[i,j] = np.min(apply_and)
   return erosion img
def Open(img,se):
   return Dilation(erosion(img, se), se)
cv.imshow('orgin',img)
cv.waitKey(0)
```