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import numpy as np
import cv2 as cv

img = cv.imread('img/1.jpg',0)

def gaussian_lowpass_filter(img,d):

    img_f = np.fft.fft2(img)

    img_fsh = np.fft.fftshift(img_f)

    rows, cols = img_f.shape

    img_fsh_real = np.real(img_fsh)
    img_fsh_imag = np.imag(img_fsh)

    dist = np.zeros((rows, cols))

    for i in range(rows):
        for c in range(cols):
            dist[i,c] = np.sqrt( (i-rows/2)**2 + (c-cols/2)**2 )

    mask = np.exp(-(dist**2) / (2*(d**2)))

    img_fsh_real = img_fsh_real * mask
    img_fsh_imag = img_fsh_imag * mask

    img_fsh = np.fft.ifftshift(img_fsh_real + 1j * img_fsh_imag )

    img = np.fft.ifft2(img_fsh)

    img = np.uint8(np.abs(img))
    return img

cv.imshow('origin',img)
cv.imshow('gaussian_lowpass_filter effect',gaussian_lowpass_filter(img, 15))
cv.waitKey(0)

```