

15. Address Translation

Operating System: Three Easy Pieces

Memory Virtualizing with Efficiency and Control

- ▣ Memory virtualizing takes a similar strategy known as **limited direct execution(LDE)** for efficiency and control.
- ▣ In memory virtualizing, efficiency and control are attained by **hardware support**.
 - ◆ e.g., registers, TLB(Translation Look-aside Buffer)s, page-table

Assumptions Made (just in this lecture)

- ▣ User address space is contiguous in memory
- ▣ User address space is smaller than the physical memory (up to 64KB)
- ▣ Each address space has the same size (up to 16KB)

Address Translation

- ▣ Hardware transforms a **virtual address** to a **physical address**.
 - ◆ The desired information is actually stored in a physical address.
- ▣ The OS must get involved at key points to set up the hardware.
 - ◆ The OS must manage memory to judiciously intervene.

Example: Address Translation

▣ C - Language code

```
void func()  
    int x;  
    ...  
    x = x + 3; // this is the line of code we are interested in
```

- ◆ **Load** a value from memory
- ◆ **Increment** it by three
- ◆ **Store** the value back into memory

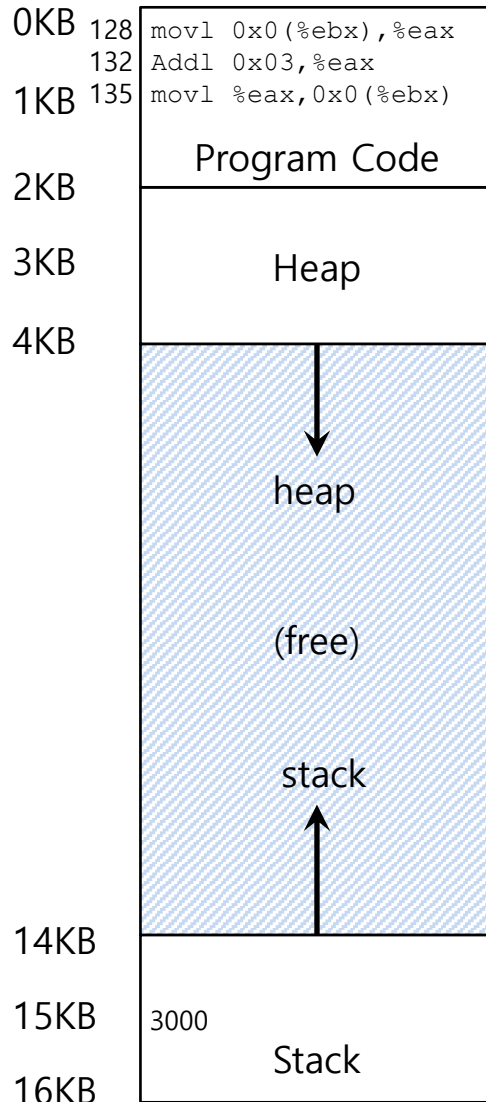
Example: Address Translation(Cont.)

▣ Assembly

```
128 : movl 0x0(%ebx), %eax      ; load 0+ebx into eax
132 : addl $0x03, %eax          ; add 3 to eax register
135 : movl %eax, 0x0(%ebx)      ; store eax back to mem
```

- ◆ **Load** the value at that address into `eax` register.
- ◆ **Add** 3 to `eax` register.
- ◆ **Store** the value in `eax` back into memory.

Example: Address Translation(Cont.)

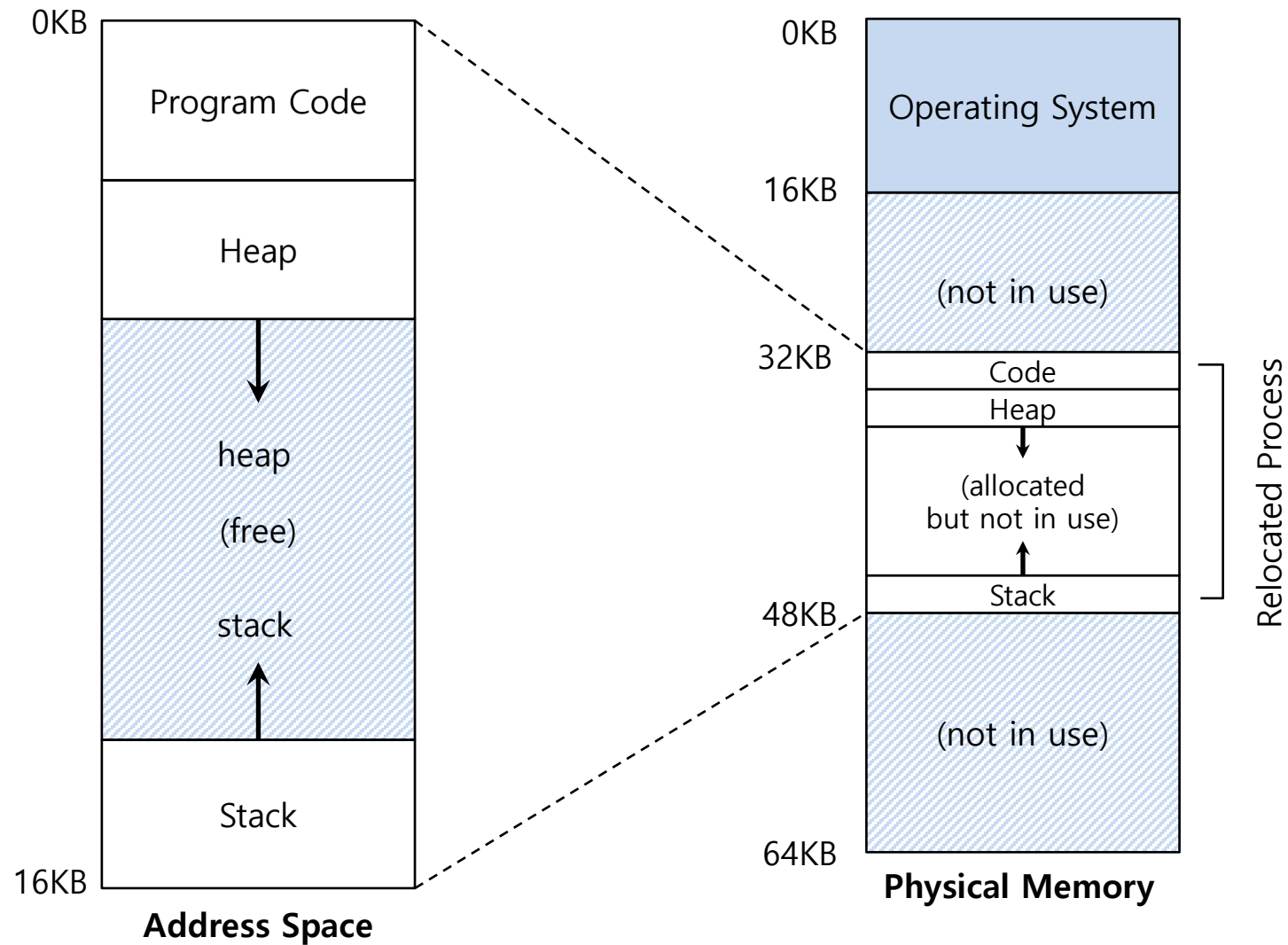


- Fetch instruction at address 128
- Execute this instruction (load from address 15KB)
- Fetch instruction at address 132
- Execute this instruction (no memory reference)
- Fetch the instruction at address 135
- Execute this instruction (store to address 15 KB)

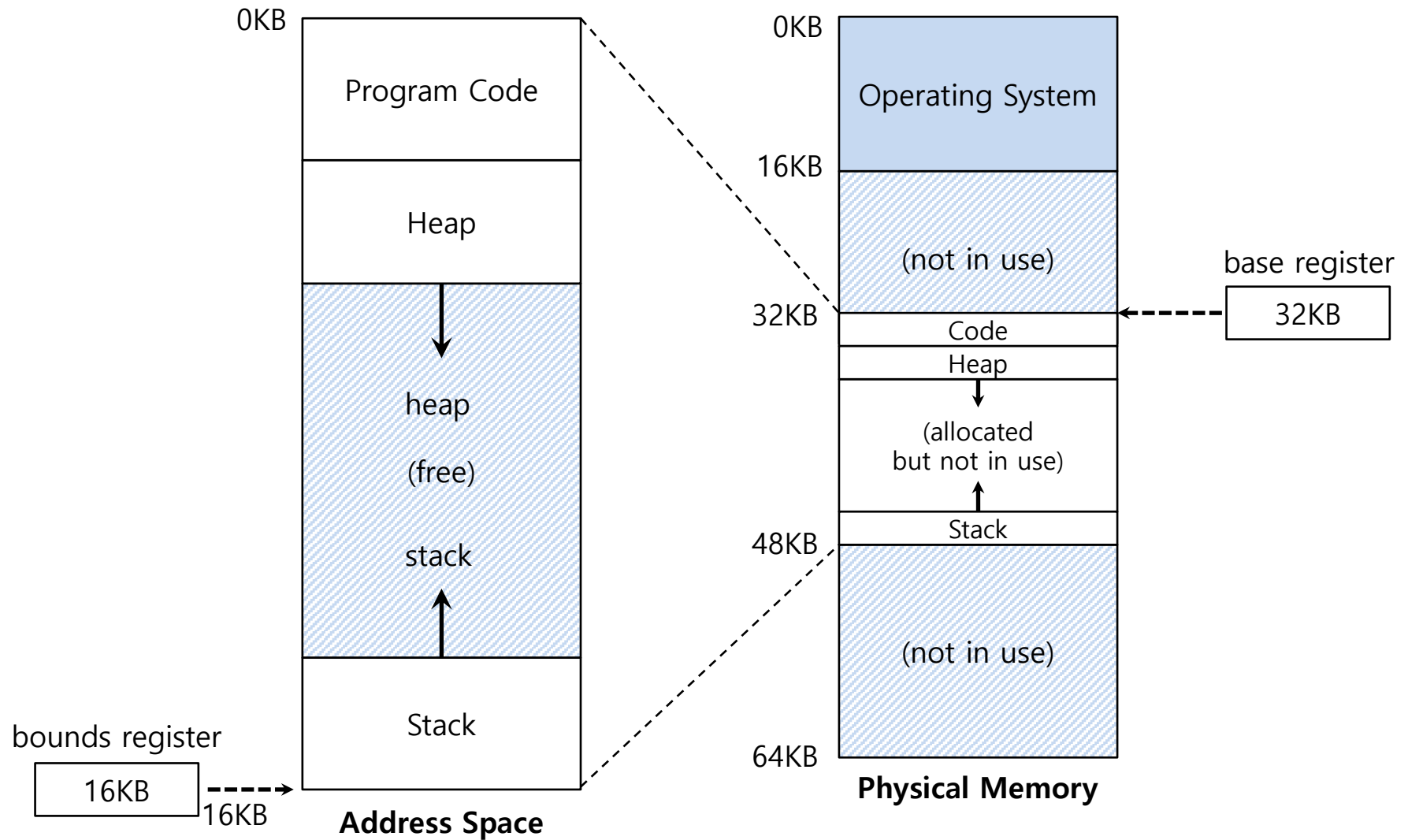
Relocation Address Space

- ▣ The OS wants to place the process **somewhere else** in physical memory, not at address 0.
 - ◆ The address space start at address 0.

A Single Relocated Process



Base and Bounds Registers



Dynamic (Hardware based) Relocation

- ▣ When a program starts running, the OS decides **where** in physical memory a process should be **loaded**.
 - ◆ Set the **base** register a value.

$$\text{physical address} = \text{virtual address} + \text{base}$$

- ◆ Every virtual address must **not be greater than bound** and **negative**.

$$0 \leq \text{virtual address} < \text{bounds}$$

- ◆ *Early days of software based relocation: rewrite addresses on program load*

Relocation and Address Translation

128 : `movl 0x0(%ebx), %eax`

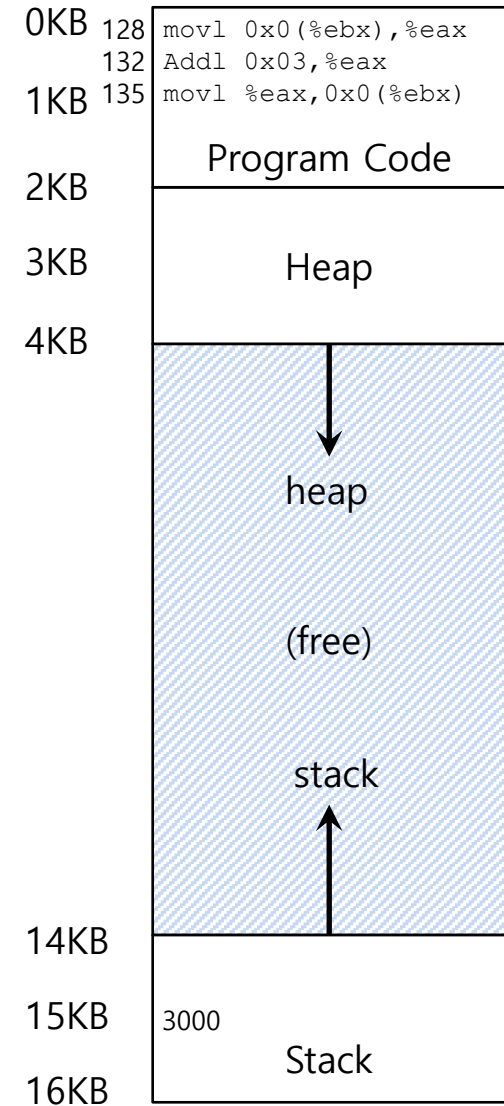
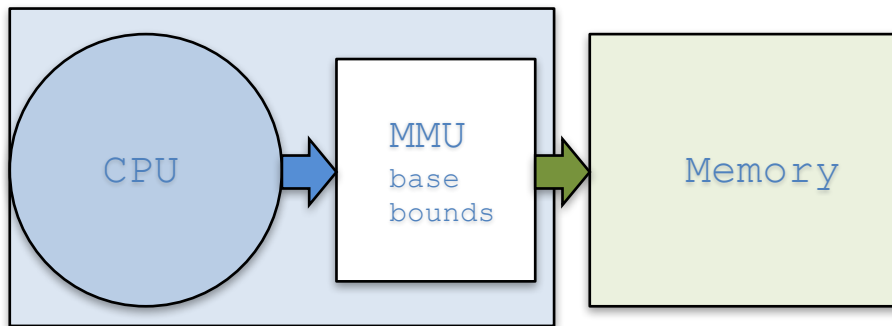
- ◆ **Fetch** instruction at address 128

$$32896 = 128 + 32KB(base)$$

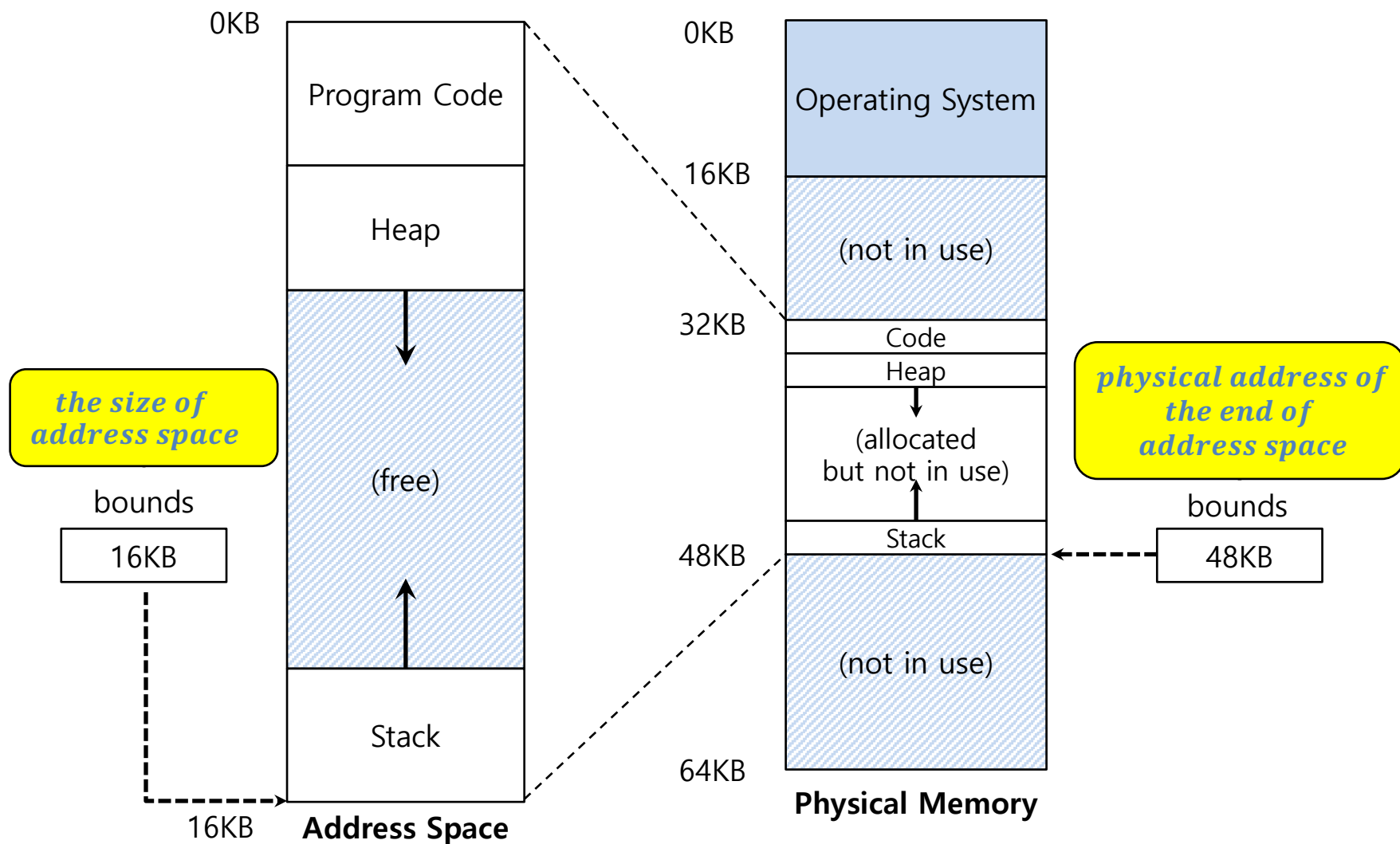
- ◆ **Execute** this instruction

- Load from address 15KB

$$47KB = 15KB + 32KB(base)$$



Two ways of Bounds Register

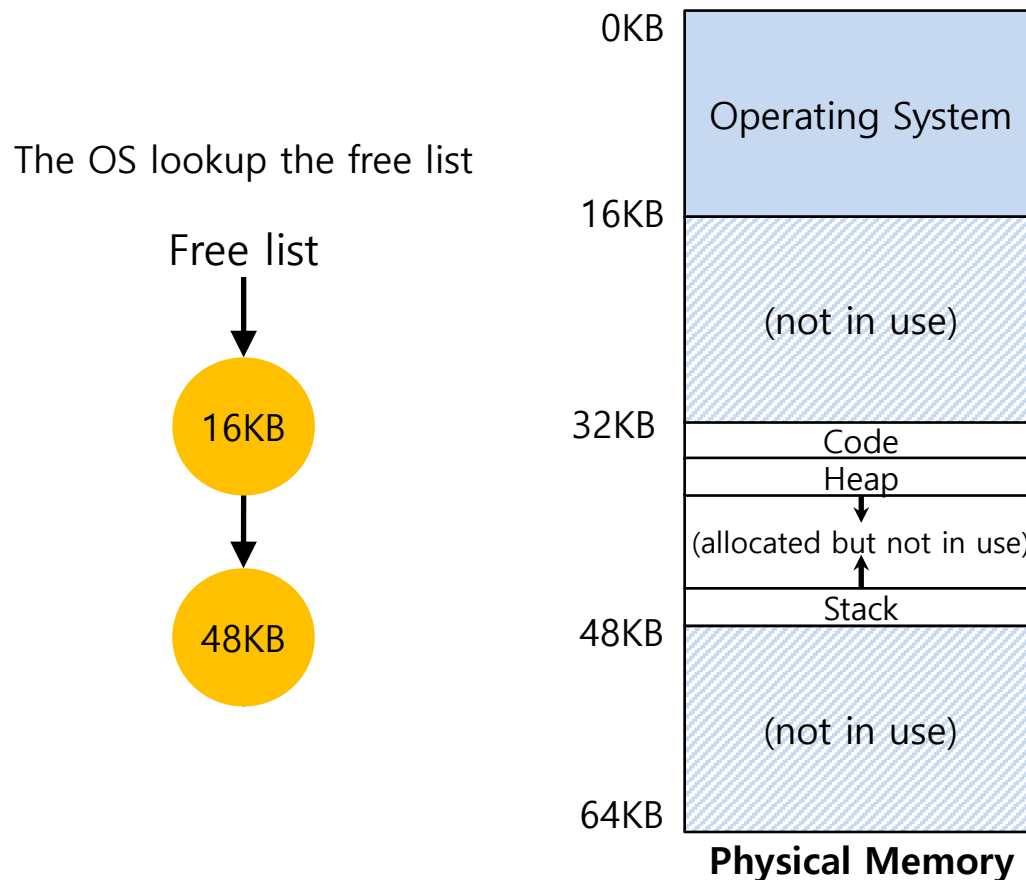


OS Issues for Memory Virtualizing

- ❑ The OS must **take action** to implement **base-and-bounds** approach.
- ❑ Three critical junctures:
 - ◆ When a process **starts running**:
 - Finding space for address space in physical memory
 - ◆ When a process is **terminated**:
 - Reclaiming the memory for use
 - ◆ When context **switch occurs**:
 - Saving and storing the base-and-bounds pair

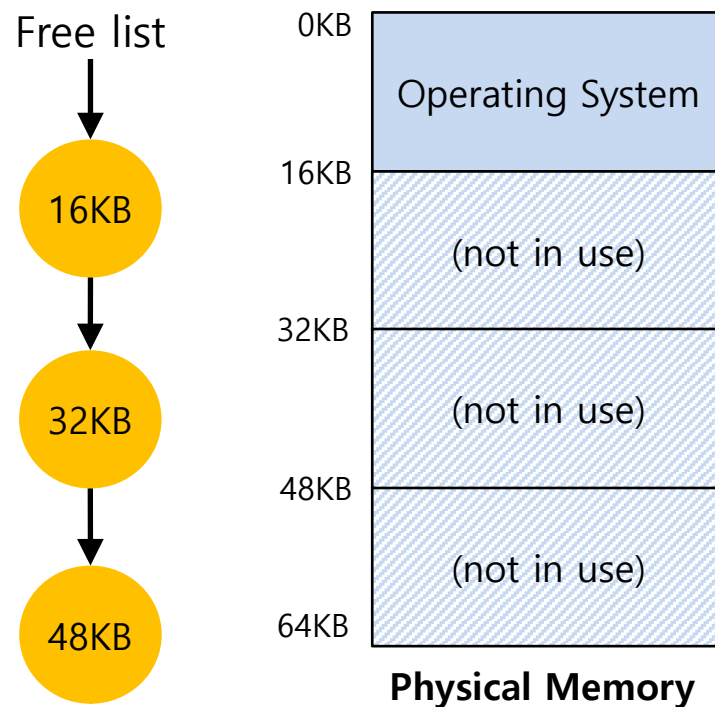
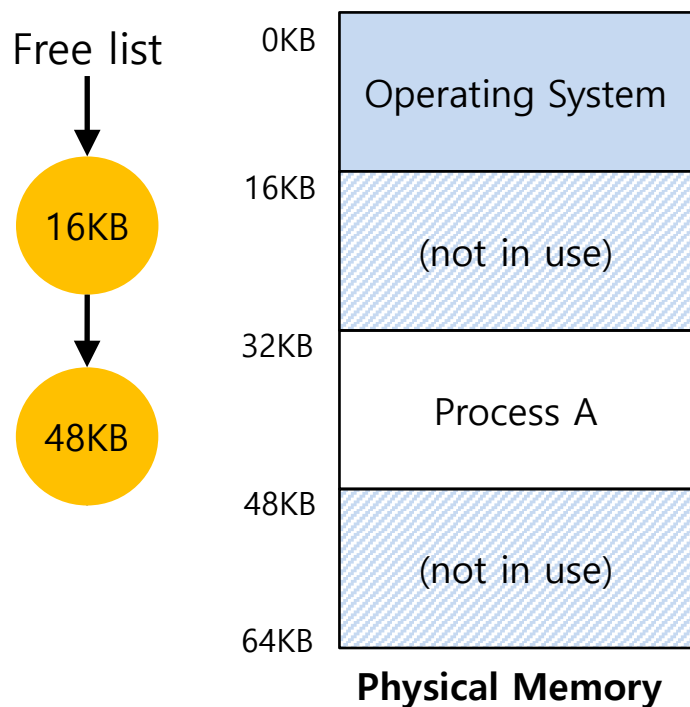
OS Issues: When a Process Starts Running

- ▣ The OS must **find a room** for a new address space.
 - ◆ free list : A list of the range of the physical memory which are not in use.



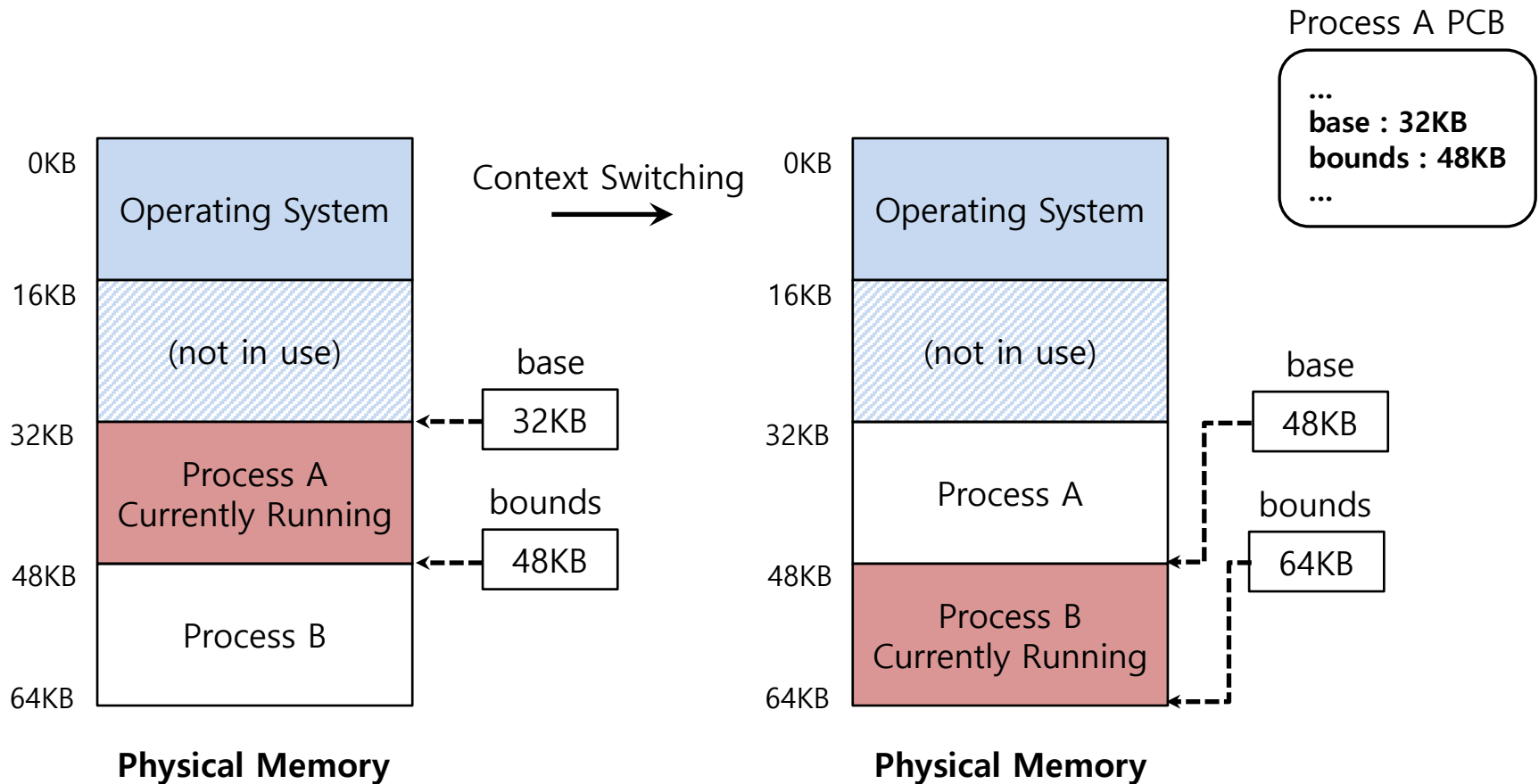
OS Issues: When a Process Is Terminated

- ▣ The OS must **put the memory back** on the free list.



OS Issues: When Context Switch Occurs

- The OS must **save and restore** the base-and-bounds pair.
 - ◆ In **process structure** or **process control block(PCB)**



Summary: Dynamic Relocation (strawman version)

OS @ boot (kernel mode)	Hardware	
initialize trap table	remember addresses of... system call handler timer handler illegal mem-access handler illegal instruction handler	
start interrupt timer	start timer; interrupt after X ms	
initialize process table		
initialize free list		
OS @ run (kernel mode)	Hardware	Program (user mode)
To start process A: allocate entry in process table allocate memory for process set base/bounds registers return-from-trap (into A)	restore registers of A move to user mode jump to A's (initial) PC	
	Translate virtual address and perform fetch	Process A runs Fetch instruction
	If explicit load/store: Ensure address is in-bounds; Translate virtual address and perform load/store	Execute instruction
		...
	Timer interrupt move to kernel mode Jump to interrupt handler	
Handle the trap Call <code>switch()</code> routine save regs(A) to proc-struct(A) (including base/bounds) restore regs(B) from proc-struct(B) (including base/bounds) return-from-trap (into B)	restore registers of B move to user mode jump to B's PC	
	Load is out-of-bounds; move to kernel mode jump to trap handler	Process B runs Execute bad load
Handle the trap Decide to terminate process B de-allocate B's memory free B's entry in process table		

- Disclaimer: Disclaimer: This lecture slide set is used in AOS course at University of Cantabria. Was initially developed for Operating System course in Computer Science Dept. at Hanyang University. This lecture slide set is for OSTEP book written by Remzi and Andrea Arpaci-Dusseau (at University of Wisconsin)