6. Mechanism: Limited Direct Execution

Operating System: Three Easy Pieces

How to efficiently virtualize the CPU with control?

- The OS needs to share the physical CPU by time sharing.
- Issue
 - Performance: How can we implement virtualization without adding excessive overhead to the system?
 - **Control**: How can we run processes efficiently while retaining control over the CPU?

Direct Execution

Just run the program directly on the CPU.

| OS | Program |
|-----------------------------------|-------------------------------|
| 1. Create entry for process list | |
| 2. Allocate memory for program | |
| 3. Load program into memory | |
| 4. Set up stack with argc / argv | |
| 5. Clear registers | |
| <pre>6. Execute call main()</pre> | |
| | 7. Run main() |
| | 8. Execute return from main() |
| 9. Free memory of process | |
| 10. Remove from process list | |

Without *limits* on running programs, the OS wouldn't be in control of anything and thus would be "just a library"

Problem 1: Restricted Operation

- What if a process wishes to perform some kind of restricted operation such as ...
 - Issuing an I/O request to a disk
 - Gaining access to more system resources such as CPU or memory

- Solution: Using protected control transfer
 - User mode: Applications do not have full access to hardware resources.
 - Kernel mode: The OS has access to the full resources of the machine

System Call

- Allow the kernel to carefully expose certain key pieces of functionality to user program, such as ...
 - Accessing the file system
 - Creating and destroying processes
 - Communicating with other processes
 - Allocating more memory

System Call (Cont.)

- Trap instruction
 - Jump into the kernel
 - Raise the privilege level to kernel mode

- Return-from-trap instruction
 - Return into the calling user program
 - Reduce the privilege level back to user mode

Limited Direction Execution Protocol

| OS @ boot (kernel mode) | Hardware | |
|---|---|--|
| initialize trap table | remember address of syscall handler | |
| OS @ run (kernel mode) | Hardware | Program (user mode) |
| Create entry for process list Allocate memory for program Load program into memory Setup user stack with argv Fill kernel stack with reg/PC return-from -trap | restore regs from kernel stack move to user mode jump to main | Run main() Call system trap into OS |

Limited Direction Execution Protocol (Cont.)

| OS @ run (kernel mode) | Hardware | Program (user mode) |
|--|--|---|
| | (Cont.) | |
| | save regs to kernel stack move to kernel mode jump to trap handler | |
| Handle trap Do work of syscall | | |
| return-from-trap | restore regs from kernel stack move to user mode jump to PC after trap | |
| | | return from main trap (via exit()) |
| Free memory of process Remove from process list | | uap (via exic()) |

Problem 2: Switching Between Processes

- How can the OS regain control of the CPU so that it can switch between processes?
 - A cooperative Approach: Wait for system calls
 - A Non-Cooperative Approach: The OS takes control

A cooperative Approach: Wait for system calls

- Processes periodically give up the CPU by making system calls such as yield.
 - The OS decides to run some other task.
 - Application also transfer control to the OS when they do something illegal.
 - Divide by zero
 - Try to access memory that it shouldn't be able to access
 - Ex) Early versions of the Macintosh OS, The old Xerox Alto system

A process gets stuck in an infinite loop.

→ Reboot the machine

A Non-Cooperative Approach: OS Takes Control

A timer interrupt

- During the boot sequence, the OS start the <u>timer</u>.
- The timer <u>raise an interrupt</u> every so many milliseconds.
- When the interrupt is raised :
 - The currently running process is halted.
 - Save enough of the state of the program
 - A pre-configured interrupt handler in the OS runs.

A timer interrupt gives OS the ability to run again on a CPU.

Saving and Restoring Context

- Scheduler makes a decision:
 - Whether to continue running the current process, or switch to a different one.
 - If the decision is made to switch, the OS executes context switch.

Context Switch

- A low-level piece of assembly code
 - Save a few register values for the current process onto its kernel stack
 - General purpose registers
 - PC
 - kernel stack pointer
 - Restore a few for the soon-to-be-executing process from its kernel stack
 - Switch to the kernel stack for the soon-to-be-executing process

AOS@UC

13

Limited Direction Execution Protocol (Timer interrupt)

| OS @ boot (kernel mode) | Hardware | |
|----------------------------|--|-----------------------|
| initialize trap table | remember address of syscall handler | |
| | timer handler | |
| start interrupt timer | start timer interrupt CPU in X ms | |
| OS @ run | Hardware | Program |
| (kernel mode) | naidwaie | (user mode) |
| (kernel mode) | Haidwaie | (user mode) Process A |
| (kernel mode) | timer interrupt | |

Limited Direction Execution Protocol (Timer interrupt)

| OS @ run (kernel mode) | Hardware | Program (user mode) |
|--|--|------------------------|
| | (Cont.) | |
| Handle the trap Call switch() routine save regs(A) to proc-struct(A) restore regs(B) from proc-struct(E switch to k-stack(B) return-from-trap (into B) | 3) | |
| | restore regs(B) from k-stack(B) move to user mode jump to B's PC | |
| | | Process B |
| | | |

The xv6 Context Switch Code

```
1 # void swtch(struct context **old, struct context *new);
2. #
3 # Save current register context in old
4 # and then load register context from new.
5 .qlobl swtch
6 swtch:
         # Save old registers
8
         movl 4(%esp), %eax
                             # put old ptr into eax
                                   # save the old TP
         popl 0(%eax)
                                  # and stack
10
         movl %esp, 4(%eax)
         movl %ebx, 8(%eax)
11
                                 # and other registers
12
         movl %ecx, 12(%eax)
13
         movl %edx, 16(%eax)
         movl %esi, 20(%eax)
14
15
         movl %edi, 24(%eax)
16
         movl %ebp, 28(%eax)
17
18
         # Load new registers
19
         movl 4(%esp), %eax
                             # put new ptr into eax
20
                                    # restore other registers
         movl 28(%eax), %ebp
21
         movl 24(%eax), %edi
2.2
         movl 20(%eax), %esi
2.3
         movl 16(%eax), %edx
2.4
         movl 12(%eax), %ecx
25
         movl 8(%eax), %ebx
26
         movl 4(%eax), %esp
                                    # stack is switched here
2.7
         pushl 0(%eax)
                                      # return addr put in place
28
                                      # finally return into new ctxt
         ret
```

Worried About Concurrency?

- What happens if, during interrupt or trap handling, another interrupt occurs?
- OS handles these situations:
 - Disable interrupts during interrupt processing
 - Use a number of sophisticate **locking** schemes to protect concurrent access to internal data structures.

Disclaimer: This lecture slide set was initially developed for Operating System course in Computer Science Dept. at Hanyang University. This lecture slide set is for OSTEP book written by Remzi and Andrea at University of Wisconsin.