

ShahJalal University of Science and Technology
Department of Computer Science and Engineering
3rd Year 2nd Semester Final Examination, 2015
Course Title: Computer Graphics and Image Processing
Course No: CSE – 373
Credit: 03

Time: 3:00 Hours

Full Marks: 100

(Answer any 10 questions taking 5 questions from each group)

Group A

1. a) Indicate which locations would be chosen by Bresnham's algorithm when scan-converting a line from pixel coordinate (2,2) to pixel coordinate (7,5). 6
b) What are the differences between 4-connected and 8-connected approach for region filling? 4
2. a) Let R be the rectangular window whose lower-left corner is at (1,1) and upper-right corner is at (8,8). According to Cohen-Sutherland algorithm find out the region codes and identify which lines are inside/outside of the clipping window and why for the following lines:
 $AB = (4,4)(5,10)$ $EF = (2,3)(3,5)$ $CD = (5,3)(4,-4)$ $GH = (9,3)(13,7)$ 7
b) What is the co-ordinate value of a 3-D point P(3,2,1) after rotating it 30° about the Y-axis. 3
3. What is the difference between cavalier and cabinet projection? Let a unit cube ABCDEFGH is projected onto xy plane. Find the projected coordinates using perspective projection with $d=7$ where,
 $A = (0, 0, 0)$ $B = (1, 0, 0)$ $C = (1, 1, 0)$ $D = (0, 1, 0)$ $E = (0, 1, 1)$ $F = (0, 0, 1)$ $G = (1, 0, 1)$ $H = (1, 1, 1)$ 2+8
4. a) A Unit Cube is projected onto the yz plane. Draw the projected image using the standard perspective transformation with i) $d=2$ and ii) $d=8$, where d is the distance from the view plane. 6
b) How Z-Buffer algorithm works? 4
5. a) Convert the RGB color (0.7, 0.5, 0.7) of the point S to HIS color format where the angle between S and red axis is 45° . 5
b) Draw the model of degradation? During edge detection, what is the finding of the laplacian? 3+2
6. a) What is the relation between relative data redundancy and compression ratio? According to following table calculate the coding redundancy and compression ratio. 2+5

r_k	$p_r(r_k)$	Code 1	$I_1(r_k)$	Code 2	$I_2(r_k)$
$r_0 = 0$	0.19	000	3	11	2
$r_1 = 1/7$	0.25	001	3	01	2
$r_2 = 2/7$	0.21	010	3	10	2
$r_3 = 3/7$	0.16	011	3	001	3
$r_4 = 4/7$	0.08	100	3	0001	4
$r_5 = 5/7$	0.06	101	3	00001	5
$r_6 = 6/7$	0.03	110	3	000001	6
$r_7 = 1$	0.02	111	3	000000	6

b) Why the filter frequencies are kept limited near the values of origin during inverse filtering? 3
7. a) Write the Prewitt and Sobel masks for horizontal and vertical edge detection. What is the difference between Prewitt and Sobel masks? Why that difference was made? 4+1+2
b) What is the approximation of laplacian mask for diagonal neighbors? 3

Enayet

G. Faruq

Group B

1. a) What is Lookup Table? If a pixel S is at (2,1) has the actual value 9, but approximated as 5; calculate the updated values of neighboring pixels of S according to Floyd-Steinberg top-to-bottom and right-to-left Error-Diffusion method where, $a = 7/16$, $b = 5/16$, $c = 3/16$, $d = 1/16$. 1+4
- b) What is the key-idea behind Sutherland-Hodgman algorithm? Determine whether the point P lies to the left/right of line segments AB and AC where, $AB = 6I + J$; $AC = 4I + 3J$; $AP = 6I + 5J$ and point 'A' is at (2,3). 2+3
2. According to Scanline algorithm:
 a) Construct the initial edge-list for the following polygon. 4
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- The polygon is a pentagon with vertices labeled as follows: A(20, 0) at the bottom-left, B(15, 15) at the bottom-right, C(15, 25) at the top-right, D(25, 25) at the top-left, and E(5, 15) at the bottom-left. Vertex A is shared by edges AB and AC. Vertex B is shared by edges AB and BC. Vertex C is shared by edges BC and CD. Vertex D is shared by edges CD and DA. Vertex E is shared by edges DA and EA.
- b) Find out which edges will be active on scanlines at $y = 2, 7, 12, 17, 22$. 2
- c) Find out the intersection points of the above scanlines with the respective active edges. 4
3. a) Find the matrix that represents rotation of an object by 45° about the origin. 3
- b) What are the new coordinates of the point P(1,-5) after the rotation? 3
- c) Magnify the triangle with the vertices A(2,1)B(1,1) and C(2,4) to twice its size while keeping C(2,4) fixed. 4
4. Let R be the rectangular window whose lower-left corner is at (1,1) and upper-right corner is at (8,8). Use Liang-Darsky algorithm to clip the following lines:
 $AB = (3,-3)(5,3)$ $EF = (2,2)(4,4)$ $CD = (2,6)(5,10)$ $GH = (-2,9)(4,12)$ 10
5. a) Write masks to detect i) Horizontal Line, ii) $+45^\circ$ Line, iii) -45° Line and iv) Vertical Line. 6
- b) Find histogram for the following image. 4
- | | | | | | |
|---|---|---|---|---|---|
| 0 | 0 | 1 | 0 | 2 | 0 |
| 1 | 0 | 7 | 7 | 7 | 0 |
| 0 | 7 | 0 | 0 | 7 | 0 |
| 1 | 0 | 0 | 7 | 2 | 0 |
| 0 | 0 | 7 | 1 | 0 | 1 |
| 1 | 0 | 7 | 7 | 7 | 0 |
- frequencies
 $f(0) = 18$
 $f(1) = 6$
 $f(2) = 3$
 $f(3) = f(4) = f(5) = f(6) = 0$
 $f(7) = 10$
6. a) Define distance function. Show the pixel arrangement for D4 distance < 3 from the center point. 2+3
- b) What is the relation between spatial domain and frequency domain operation? 2
- c) Design a frequency domain filter that will force the average value of an image. 3
7. a) Write down the general form and function of different point-processing filters. 2
- b) What are the basic steps for frequency domain filtering? 3