

Results

```
khalid@khalid-VirtualBox: ~/catkin_ws/src/custom_package_for_smart_methods/scripts
khalid@khalid-VirtualBox:~/catkin_ws/src/custom_package_for_smart_methods/script
s$ rosnode list
/publisher
/rosout
/subscriber
khalid@khalid-VirtualBox:~/catkin_ws/src/custom_package_for_smart_methods/script
s$ rostopic list
/Topic
/rosout
/rosout_agg
khalid@khalid-VirtualBox:~/catkin_ws/src/custom_package_for_smart_methods/script
s$
```

[illegible]

```

roscore http://khalid-VirtualBox:11311/
started roslaunch server http://khalid-VirtualBox:44385/
ros_comm version 1.12.14

SUMMARY
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PARAMETERS
* /roscpp: kinetic
* /rosversion: 1.12.14

NODES

auto-starting new master
process[master]: started with pid [4712]
ROS_MASTER_URI=http://khalid-VirtualBox:11311/

setting /run_id to 515f3bf0-bbb2-11ea-8e47-080027d8cdcc
WARNING: Package name "01_package" does not follow the naming conventions. It sh
ould start with a lower case letter and only contain lower case letters, digits,
underscores, and dashes.
process[rosout-1]: started with pid [4725]
started core service [/rosout]

```

```
khalid@khalid-VirtualBox: ~/catkin_ws/src/custom_package_for_smart_methods/scripts
khalid@khalid-VirtualBox:~$ roscd custom_package_for_smart_methods/
khalid@khalid-VirtualBox:~/catkin_ws/src/custom_package_for_smart_methods$ ls
CMakeLists.txt  package.xml  scripts  src
khalid@khalid-VirtualBox:~/catkin_ws/src/custom_package_for_smart_methods$ cd sc
ripts
khalid@khalid-VirtualBox:~/catkin_ws/src/custom_package_for_smart_methods/script
s$ ./
publisher.py  subscriber.py
khalid@khalid-VirtualBox:~/catkin_ws/src/custom_package_for_smart_methods/script
s$ ./publisher.py
```