

From fixed to random effects

Bayesian statistics 4 – random and mixed effects models

Frédéric Barraquand (CNRS, IMB)

09/11/2021

Some things that we learned the last time(s)

Session 3

- MCMC = Monte Carlo + Markov Chain
- Requires two types of convergence to compute an posterior means or posterior distribution
- JAGS uses the Gibbs sampler, a multicomponent variant of the Metropolis algorithm
- The Gibbs sampler allows to sample parameter-rich models

Session 2

- T-tests, ANOVA and the likes can be framed as the General Linear Model
- The Linear Model $Y = X\beta + E$ is easily fitted with JAGS
- Uncertainties in effects \rightarrow posteriors

Back to Snout-Vent Length (SVL) Snake data

From Kéry (2010) & TD 2

```
### Data generation
```

```
# same as TD2 but number of groups x 2
```

```
npop <- 10 # Number of populations: now choose 10 rather than 5
```

```
nsample <- 12 # Number of snakes in each
```

```
n <- npop * nsample # Total number of data points
```

```
pop.grand.mean <- 50 # Grand mean SVL
```

```
pop.sd <- 5 # sd of population effects about mean
```

```
pop.means <- rnorm(n = npop, mean = pop.grand.mean, sd = pop.sd)
```

```
sigma <- 3 # Residual sd
```

```
eps <- rnorm(n, 0, sigma) # Draw residuals
```

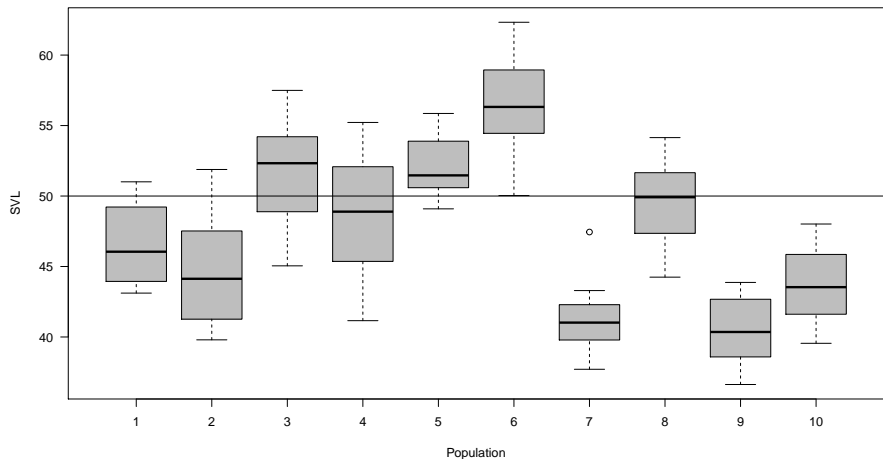
```
x <- rep(1:npop, rep(nsample, npop))
```

```
X <- as.matrix(model.matrix(~ as.factor(x)-1))
```

```
y <- as.numeric(X %*% as.matrix(pop.means) + eps) # as.numeric is E
```

The data: Snout-vent length in snakes

```
boxplot(y ~ x, col = "grey", xlab = "Population", ylab = "SVL", main = "Boxplot of SVL by Population")  
abline(h = pop.grand.mean)
```



Questions that we could ask

- Effect of being in population i
- Is there more variation between populations or more residual variation?

The one-way ANOVA: from code to maths

$J = 10$ Groups. Notations

$$Y_{ij} = \alpha_i + \epsilon_{ij}, \epsilon_{ij} \sim \mathcal{N}(0, \sigma^2)$$

Practical if $i = 1, \dots, I$ is the same number of individuals per group.
 $n = I \times J$.

The one-way ANOVA: from code to maths

$J = 10$ Groups. Notations

$$Y_{ij} = \alpha_i + \epsilon_{ij}, \epsilon_{ij} \sim \mathcal{N}(0, \sigma^2)$$

Practical if $i = 1, \dots, I$ is the same number of individuals per group.
 $n = I \times J$.

or again

$$Y_{ij} \sim \mathcal{N}(\mu_{ij}, \sigma^2), \mu_{ij} = \alpha_i$$

By that we mean that $\mathbb{E}(Y_{ij}) = \alpha_i$.

The one-way ANOVA: from code to maths

$J = 10$ Groups. Notations

$$Y_{ij} = \alpha_i + \epsilon_{ij}, \epsilon_{ij} \sim \mathcal{N}(0, \sigma^2)$$

Practical if $i = 1, \dots, I$ is the same number of individuals per group.
 $n = I \times J$.

or again

$$Y_{ij} \sim \mathcal{N}(\mu_{ij}, \sigma^2), \mu_{ij} = \alpha_i$$

By that we mean that $\mathbb{E}(Y_{ij}) = \alpha_i$.

Note: if you have an overall mean μ you need to remove a group

The one-way ANOVA: from code to maths

$J = 10$ Groups. Notations

$$Y_{ij} = \alpha_i + \epsilon_{ij}, \epsilon_{ij} \sim \mathcal{N}(0, \sigma^2)$$

Practical if $i = 1, \dots, I$ is the same number of individuals per group.
 $n = I \times J$.

or again

$$Y_{ij} \sim \mathcal{N}(\mu_{ij}, \sigma^2), \mu_{ij} = \alpha_i$$

By that we mean that $\mathbb{E}(Y_{ij}) = \alpha_i$.

Note: if you have an overall mean μ you need to remove a group

or again with $i = 1, \dots, n$

$$Y_i \sim \mathcal{N}(\mu_i, \sigma^2), \mu_i = \alpha_{k[i]}$$

where $k[i]$ returns in which group is i . How we coded this JAGS.

Running again the ANOVA

```
## List of 2
## $ y: num [1:120] 44.4 49.6 45.1 51 46.4 ...
## $ x: int [1:120] 1 1 1 1 1 1 1 1 1 1 ...

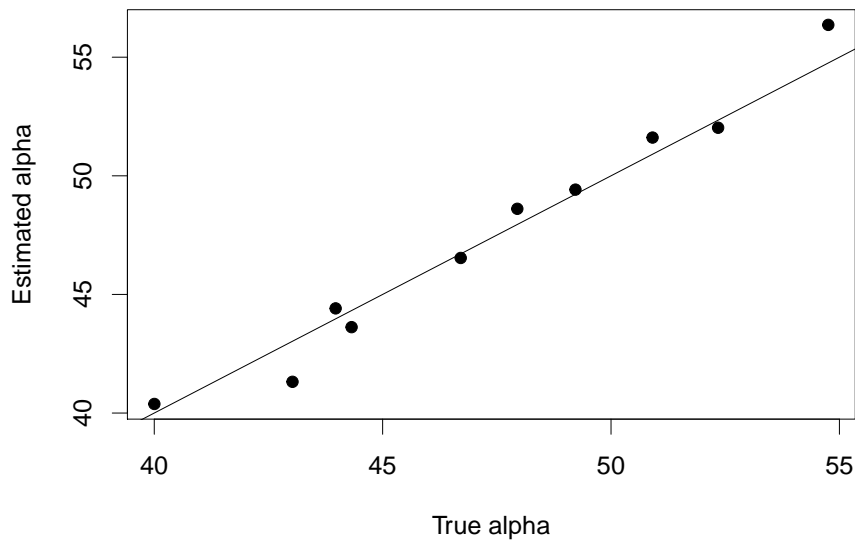
# Specify model in BUGS language
cat(file = "anova.txt", "
    model {

        # Priors
        for (i in 1:10){                # Implicitly define alpha as a vector
            alpha[i] ~ dnorm(0, 0.001) # Beware that a mean at 0 only works because
        }
        sigma ~ dunif(0, 100)

        # Likelihood
        for (i in 1:120) {
            y[i] ~ dnorm(mean[i], tau)
            mean[i] <- alpha[x[i]]
        }

        # Derived quantities
        tau <- 1 / ( sigma * sigma)
    }
```

Estimated effects vs theoretical effects



Classical random effect modelling I

```
### Restricted maximum likelihood (REML) analysis using R
library('lme4')                # Load lme4

pop <- as.factor(x)            # Define x as a factor and call it pop

lme.fit <- lmer(y ~ 1 + 1 | pop, REML = TRUE)
lme.fit                        # Inspect results
```

```
## Linear mixed model fit by REML ['lmerMod']
## Formula: y ~ 1 + 1 | pop
## REML criterion at convergence: 650.1976
## Random effects:
##   Groups      Name          Std.Dev.
##   pop        (Intercept)  5.041
##   Residual                        3.200
## Number of obs: 120, groups:  pop, 10
## Fixed Effects:
## (Intercept)
```

Classical random effect modelling II

```
##          47.47
```

```
ranef(lme.fit)           # Print random effects
```

```
## $pop
```

```
##      (Intercept)
```

```
## 1    -0.8446384
```

```
## 2    -2.9232184
```

```
## 3     4.0643402
```

```
## 4     1.1482505
```

```
## 5     4.4691200
```

```
## 6     8.6668906
```

```
## 7    -5.9309288
```

```
## 8     1.8830870
```

```
## 9    -6.8293818
```

```
## 10   -3.7035208
```

```
##
```

```
## with conditional variances for "pop"
```

Classical random effect model - maths

$$Y_i \sim \mathcal{N}(\mu_i, \sigma^2), \mu_i = \alpha_{k[i]}$$

where $k[i]$ returns in which group is i . What's missing?

Classical random effect model - maths

$$Y_i \sim \mathcal{N}(\mu_i, \sigma^2), \mu_i = \alpha_{k[i]}$$

where $k[i]$ returns in which group is i . What's missing?

i.i.d. observations. And then?

Classical random effect model - maths

$$Y_i \sim \mathcal{N}(\mu_i, \sigma^2), \mu_i = \alpha_{k[i]}$$

where $k[i]$ returns in which group is i . What's missing?

i.i.d. observations. And then?

We estimate the variance of the random effects

$$\alpha_j \sim \mathcal{N}(\mu_\alpha, \sigma_\alpha^2)$$

(we have to specify a mean too)

Random effect model in a Bayesian framework I

```
# Bundle and summarize the data set passed to JAGS  
str(bdata <- list(y = y, x = x, npop = npop, n = n))
```

```
## List of 4  
## $ y : num [1:120] 44.4 49.6 45.1 51 46.4 ...  
## $ x : int [1:120] 1 1 1 1 1 1 1 1 1 1 ...  
## $ npop: num 10  
## $ n : num 120
```

Random effect model in a Bayesian framework II

Specify model in BUGS language

```
cat(file = "re.anova.txt", "  
model {
```

```
# Priors and some derived things
```

```
for (i in 1:npop){  
    alpha[i] ~ dnorm(mu, tau.alpha)      # Prior for population means  
    effect[i] <- alpha[i] - mu           # Population effects as derived quantities  
}
```

```
mu ~ dnorm(0,0.001)                    # Hyperprior for grand mean svl  
sigma.alpha ~ dunif(0, 10)             # Hyperprior for sd of population effects  
sigma.res ~ dunif(0, 10)               # Prior for residual sd
```

```
# Likelihood
```

```
for (i in 1:n) {  
    y[i] ~ dnorm(mean[i], tau.res)  
    mean[i] <- alpha[x[i]]  
}
```

```
# Derived quantities
```

Fitting the model I

Inits function

```
inits <- function(){ list(mu = runif(1, 0, 100), sigma.alpha = rlnor
```

Params to estimate

```
params <- c("mu", "alpha", "effect", "sigma.alpha", "sigma.res")
```

MCMC settings

```
nb <- 1000 ; nc <- 3 ; ni <- 2000 ; nt <- 2
```

Call JAGS, check convergence and summarize posteriors

```
out2 <- jags(bdata, inits, params, "re.anova.txt", n.thin = nt, n.cl  
          n.burnin = nb, n.iter = ni)
```

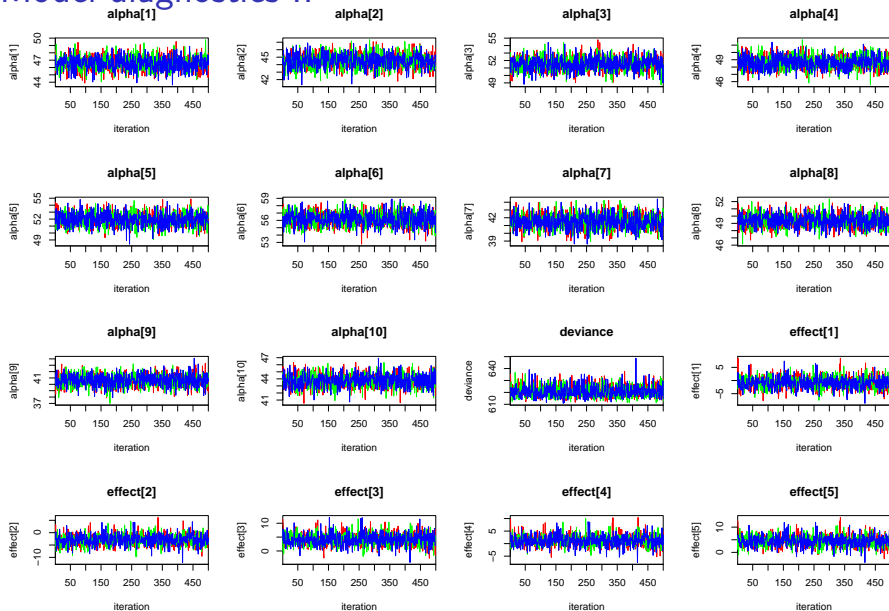
Fitting the model II

```
## Compiling model graph
##   Resolving undeclared variables
##   Allocating nodes
## Graph information:
##   Observed stochastic nodes: 120
##   Unobserved stochastic nodes: 13
##   Total graph size: 273
##
## Initializing model
```

Model diagnostics I

```
traceplot(out2,mfrow=c(4,4))
```

Model diagnostics II



Model results I

```
print(out2,dig=3)
```

```
## Inference for Bugs model at "re.anova.txt", fit using jags,  
## 3 chains, each with 2000 iterations (first 1000 discarded), n.thin = 2  
## n.sims = 1500 iterations saved  
##
```

	mu.vect	sd.vect	2.5%	25%	50%	75%	97.5%	Rhat	n.eff
## alpha[1]	46.594	0.930	44.684	45.980	46.588	47.249	48.464	1.002	1200
## alpha[2]	44.547	0.939	42.715	43.919	44.574	45.179	46.332	1.001	1500
## alpha[3]	51.548	0.912	49.811	50.942	51.554	52.174	53.316	1.000	1500
## alpha[4]	48.647	0.888	47.045	48.052	48.616	49.257	50.412	1.002	810
## alpha[5]	51.955	0.932	50.164	51.334	51.944	52.564	53.834	1.000	1500
## alpha[6]	56.186	0.929	54.409	55.539	56.210	56.838	58.016	1.000	1500
## alpha[7]	41.534	0.929	39.700	40.946	41.529	42.152	43.341	1.001	1500
## alpha[8]	49.379	0.895	47.641	48.785	49.366	49.972	51.231	1.000	1500
## alpha[9]	40.611	0.937	38.711	40.008	40.634	41.247	42.399	1.000	1500
## alpha[10]	43.734	0.917	41.999	43.094	43.742	44.349	45.648	1.001	1500
## effect[1]	-0.796	2.177	-4.967	-2.182	-0.798	0.556	3.489	1.003	1400
## effect[2]	-2.843	2.165	-7.068	-4.212	-2.893	-1.506	1.391	1.000	1500
## effect[3]	4.158	2.153	0.007	2.758	4.103	5.523	8.591	1.000	1500
## effect[4]	1.257	2.185	-2.820	-0.187	1.209	2.561	5.624	1.003	1200
## effect[5]	4.565	2.139	0.411	3.212	4.532	5.927	8.709	1.000	1500
## effect[6]	8.796	2.182	4.678	7.342	8.779	10.185	13.353	1.002	1500
## effect[7]	-5.856	2.156	-10.102	-7.273	-5.788	-4.526	-1.667	1.001	1500

Model results II

```
## effect[8]      1.989    2.149   -2.222    0.598    1.946    3.342    6.418  1.001  1500
## effect[9]     -6.779    2.158  -10.938   -8.163   -6.770   -5.399   -2.398  1.000  1500
## effect[10]    -3.656    2.188   -8.157   -5.095   -3.692   -2.337    0.878  1.000  1500
## mu            47.390    2.001   43.232   46.146   47.436   48.652   51.305  1.001  1500
## sigma.alpha    5.812    1.452    3.562    4.675    5.640    6.668    9.199  1.006   310
## sigma.res      3.227    0.219    2.847    3.077    3.209    3.369    3.696  1.002  1500
## deviance      620.795    4.802  613.389  617.307  620.047  623.532  631.576  1.001  1500
##
## For each parameter, n.eff is a crude measure of effective sample size,
## and Rhat is the potential scale reduction factor (at convergence, Rhat=1).
##
## DIC info (using the rule,  $pD = \text{var}(\text{deviance})/2$ )
##  $pD = 11.5$  and  $DIC = 632.3$ 
## DIC is an estimate of expected predictive error (lower deviance is better).
```


Comparison of variance estimates

```
### Well, comparison of sigma's...
```

```
VarCorr(lme.fit)
```

```
## Groups      Name      Std.Dev.  
## pop      (Intercept) 5.0409  
## Residual              3.2005
```

```
out2$BUGSoutput$mean$sigma.res #true value is 3
```

```
## [1] 3.226858
```

```
out2$BUGSoutput$mean$sigma.alpha #true value is 5
```

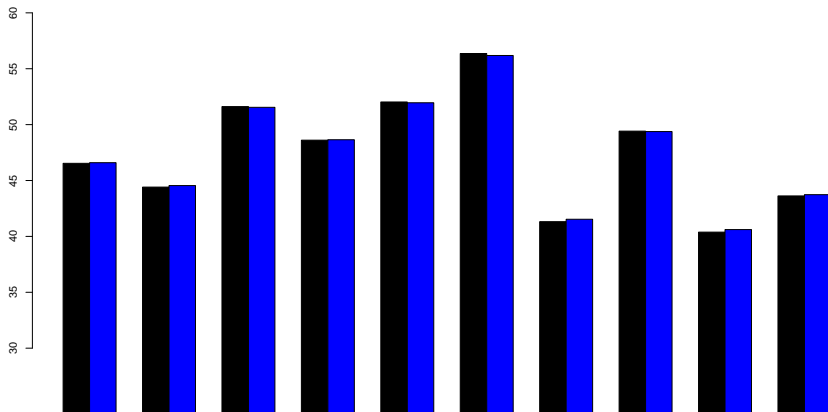
```
## [1] 5.811853
```

Comparison of fixed and random effects

```
## Plotting shrinkage
```

```
alpha_mean2 = out2$BUGSoutput$mean$alpha
```

```
barplot(t(matrix(c(alpha_mean,alpha_mean2),ncol=2,nrow=10)),beside=T)
```



Re-running the analysis with more shrinkage I

Now we assume a prior $\sigma_\alpha \sim \text{Gamma}(100, 50)$.

More details on the [Gamma distribution](#)

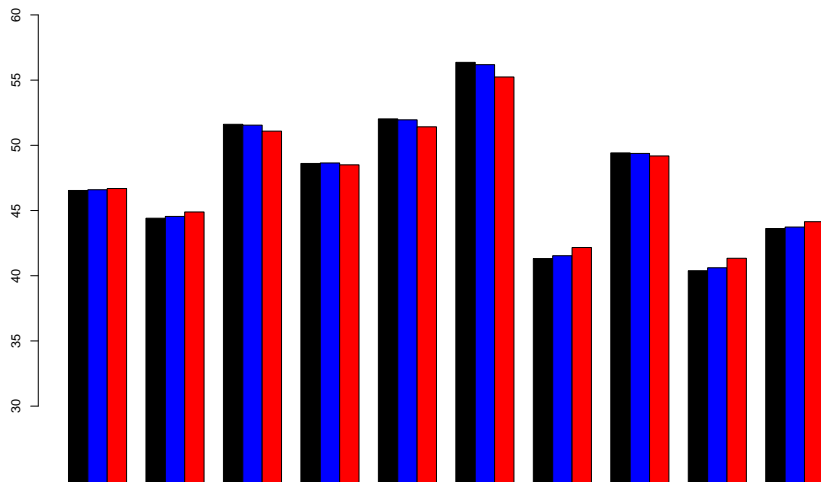
- $X \sim \text{Gamma}(a, b)$ with $a = \text{shape}$, $b = \text{rate} = \frac{1}{\theta}$ where θ is scale.
- Properties: $\mathbb{E}(X) = a\theta = 100/50 = 2$ and $\mathbb{V}(X) = a\theta^2 = \frac{100}{2500} = 0.04$ so that $\text{SD}(X) = 0.2$.

```
alpha_mean3 = out3$BUGSoutput$mean$alpha
out3$BUGSoutput$mean$sigma.alpha
```

```
## [1] 2.451122
```

```
barplot(t(matrix(c(alpha_mean, alpha_mean2, alpha_mean3), ncol=3,
```

Re-running the analysis with more shrinkage II



To wrap up – ANOVA vs REs in a Bayesian setup

- The difference between ANOVA and random effects models boils down to estimation of variance between group-level effects

To wrap up – ANOVA vs REs in a Bayesian setup

- The difference between ANOVA and random effects models boils down to estimation of variance between group-level effects
- (usually confusing because ANOVA *does* some variance partitioning)

To wrap up – ANOVA vs REs in a Bayesian setup

- The difference between ANOVA and random effects models boils down to estimation of variance between group-level effects
- (usually confusing because ANOVA *does* some variance partitioning)
- ANOVA e.g. $\alpha_j \sim \mathcal{N}(50, 100)$

To wrap up – ANOVA vs REs in a Bayesian setup

- The difference between ANOVA and random effects models boils down to estimation of variance between group-level effects
- (usually confusing because ANOVA *does* some variance partitioning)
- ANOVA e.g. $\alpha_j \sim \mathcal{N}(50, 100)$
- RE model $\alpha_j \sim \mathcal{N}(\mu_\alpha, \sigma_\alpha^2)$ and $\sigma_\alpha \sim \mathcal{U}(0, 10)$ or $\sigma_\alpha \sim \text{Exp}(0, 1/5)$

To wrap up – ANOVA vs REs in a Bayesian setup

- The difference between ANOVA and random effects models boils down to estimation of variance between group-level effects
- (usually confusing because ANOVA *does* some variance partitioning)
- ANOVA e.g. $\alpha_j \sim \mathcal{N}(50, 100)$
- RE model $\alpha_j \sim \mathcal{N}(\mu_\alpha, \sigma_\alpha^2)$ and $\sigma_\alpha \sim \mathcal{U}(0, 10)$ or $\sigma_\alpha \sim \text{Exp}(0, 1/5)$
- RE model with more shrinkage $\sigma_\alpha \sim \text{Gamma}(100, 50)$.

More material

- Shrinkage aka partial pooling is a property of mixed models, not Bayesian estimation (though you can top it up using informative priors)
- Kruschke's post on parameterizing the Gamma distribution

Bonus: fun and pretty snakes



Figure 1: *Vipera ursinii* Benny Trapp (CC BY)

Super épisode de La méthode scientifique sur France Culture, 08/11/2021