# Gram Matrices and Statistical Signal Processing

## Imperial College London, July 2016

### Khalil Elkhalil khalil.elkhalil@kaust.edu.sa

Computer, Electrical, Mathematical Sciences and Engineering (CEMSE)



جامعة الملك عبدالله للعلوم والتقنية King Abdullah University of Science and Technology

## A work done with

- Dr Abla Kammoun (Research scientist, KAUST).
- ▶ Prof. Tareq Y. Al-Naffouri (Associate Professor, KAUST).



Prof. Mohamed-Slim Alouini (Professor, KAUST).



### Outline

Some history on RMT

Background on Random Matrix Theory (RMT)

Inverse Moments of One-Sided Correlated Gram Matrices

Blind Measurement Selection

Summary

## Some history on RMT

Background on Random Matrix Theory (RMT)

Inverse Moments of One-Sided Correlated Gram Matrices

Blind Measurement Selection

Summary

▶ All started with the work of E. Wigner in the 1950's in nuclear physics.



- High dimensional probability and statistics (Tao, Marcenko, Pastur...)
- ▶ Electrical Eng. at the end of the 1990's (Verdu, Tse, Debbah,...)
- Recently applied in the field of statistical signal processing and robust estimation (Mestre, Loubaton, Couillet,...)
- ▶ Applied in Machine Learning (2016, Couillet and Kammoun).
- The journey continues ...

### Some history on RMT

## Background on Random Matrix Theory (RMT)

Inverse Moments of One-Sided Correlated Gram Matrices

Blind Measurement Selection

Summary

$$\mathbf{X}_N = \begin{bmatrix} X_{1,1} & \cdots & X_{1,N} \\ \vdots & & \vdots \\ X_{N,1} & \cdots & X_{N,N} \end{bmatrix}.$$

where the entries  $X_{i,j}$  are random variables.

Usually we're interested in the following quantities

- ▶ The **spectrum** (The distribution of the  $\lambda_i$ 's,  $\lambda_{min}$  and  $\lambda_{max}$ ).
- ightharpoonup Some useful statistics involving the eigenvalues of  $X_N$

$$\begin{split} & \mathbb{E} \sum_{i} f(\lambda_{i}) \\ & f(x) : \frac{1}{x^{p}} (p \in \mathbb{Z}), \log x, ... \end{split}$$

Eigenvectors, ···

Two approaches to obtain the statistics of interest

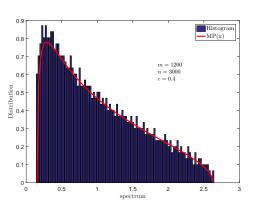
- ► Exact Approach (usually hard ②).
- Asymptotic Approach (usually feasible and leads to simple expressions ©).

$$m, n \to \infty, \frac{m}{n} \to c \in (0, \infty).$$

## Marcenko-Pastur's Theorem (Wishart matrices)

Let  $\mathbf{X} \in \mathbb{C}^{m \times n}$  a Gaussian random matrix with i.i.d zero mean unit variance entries and  $\mathbf{W} = \frac{1}{n} \mathbf{X} \mathbf{X}^*$  with spectral measure

$$\mathcal{E}\left(\mathbf{W}\right) = \frac{1}{m} \sum_{i} \delta_{\lambda_{i}\left(\mathbf{W}\right)}.$$



Let 
$$\lambda^- = (1 - \sqrt{c})^2$$
 and  $\lambda^+ = (1 + \sqrt{c})^2$ . Then as  $(m, n) \to \infty$  with  $\frac{m}{n} \to c \in (0, \infty)$ 

$$\mathcal{E}\left(\mathbf{W}\right) \xrightarrow[m,n \to +\infty]{d} \mathbb{P}_{MP}\left(dx\right) = \left(1 - \frac{1}{c}\right)^{+} \delta_{0}\left(dx\right) + \frac{\sqrt{(\lambda^{+} - x)(x - \lambda^{-})}}{2\pi x c} \mathbf{1}_{\left[\lambda^{-},\lambda^{+}\right]}(x) dx.$$

Some history on RMT

Background on Random Matrix Theory (RMT)

Inverse Moments of One-Sided Correlated Gram Matrices

Blind Measurement Selection

Summary

#### Gram random matrices

$$\begin{split} \mathbf{S} &= \mathbf{H}^* \mathbf{H} \\ &= \left( \mathbf{\Lambda}^{\frac{1}{2}} \mathbf{X} \right)^* \left( \mathbf{\Lambda}^{\frac{1}{2}} \mathbf{X} \right) \\ &= \mathbf{X}^* \mathbf{\Lambda} \mathbf{X}. \end{split}$$

where  $\mathbf{X} \in \mathbb{C}^{n \times m}$  with i.i.d zero mean unit variance Gaussian entries and  $\boldsymbol{\Lambda}$  is positive definite matrix with distinct eigenvalues  $\theta_1, \theta_2, \dots, \theta_n$ .

This kind of matrices may arise in the following context

$$y = Hv + z$$
,  $m < n$ .

The error covariance matrix after applying least squares (LS)

$$S^{-1} = (H^*H)^{-1}$$
.

The mean square error is given by

$$\begin{aligned} \mathbf{MSE} &= \mathbb{E} \ \operatorname{trace} \left( \mathbf{H}^* \mathbf{H} \right)^{-1} \\ &= \mathbb{E} \sum_i \lambda_i^{-1} \left( \mathbf{H}^* \mathbf{H} \right) \\ \mathbf{f} \left( \mathbf{x} \right) &= \frac{1}{\sqrt{\epsilon}}. \end{aligned}$$

In this particular case: Yes, we can © Mellin transform approach

$$\mathcal{M}_{f_{\lambda}}(s) \triangleq \int_{0}^{\infty} \xi^{s-1} f_{\lambda}(\xi) d\xi. \tag{1}$$

$$\mathbb{E} \operatorname{trace} \left( \mathbf{H}^* \mathbf{H} \right)^{-p} = \lim_{s \to 0} \mathcal{M}_{f_{\lambda}} \left( s - p + 1 \right)$$

## Lemma 1[1]

$$\mathcal{M}_{f_{\lambda}}(s) = L \sum_{j=1}^{m} \sum_{i=1}^{m} \mathcal{D}(i,j) \Gamma(s+j-1) \left( \theta_{n-m+i}^{n-m+s+j-2} - \sum_{l=1}^{n-m} \sum_{k=1}^{n-m} \left[ \mathbf{\psi}^{-1} \right]_{k,l} \theta_{l}^{n-m+s+j-2} \theta_{n-m+i}^{k-1} \right),$$
(2)

with  $L = \frac{\det(\Psi)}{m \prod_{i=1}^{n} (\theta_{i} - \theta_{k}) \prod_{i=1}^{m-1} \mu_{i}}$ ,  $\Gamma(.)$  the Gamma function and  $\Psi$  is the  $(n-m) \times (n-m)$  Vandermonde matrix given by

$$\mathbf{\Psi} = \begin{bmatrix} 1 & \theta_1 & \cdots & \theta_1^{n-m-1} \\ \vdots & \vdots & \ddots & \vdots \\ 1 & \theta_{n-m} & \cdots & \theta_{n-m}^{n-m-1} \end{bmatrix}$$

and  $\mathcal{D}(i,j)$  is the (i,j)-cofactor of the  $(m \times m)$  matrix  $\mathcal{C}$  whose (l,k)-th entry is given by

$$[C]_{l,k} = (k-1)! \left( \theta_{n-m+l}^{n-m+k-1} - \sum_{n=1}^{n-m} \sum_{n=1}^{n-m} \left[ \mathbf{\Psi}^{-1} \right]_{p,q} \theta_{n-m+l}^{p-1} \theta_q^{n-m+k-1} \right).$$

- ▶  $p \le 0$ : straightforward.
- p > 0: singularity issues arise.

→ Divide and conquer

$$\mathcal{M}_{f_{\lambda}}(s-p+1) = \mathcal{M}_{1}(s-p+1) + \mathcal{M}_{2}(s-p+1),$$
 (3)

where

$$\mathcal{M}_{1}(s) = L \sum_{j=1}^{p} \sum_{i=1}^{m} \mathcal{D}(i,j) \Gamma(s+j-1) \left( \theta_{n-m+i}^{n-m+s+j-2} - \sum_{l=1}^{n-m} \sum_{k=1}^{n-m} \left[ \Psi^{-1} \right]_{k,l} \theta_{l}^{n-m+s+j-2} \theta_{n-m+i}^{k-1} \right).$$

$$\mathcal{M}_{2}(s) = L \sum_{j=p+1}^{m} \sum_{i=1}^{m} \mathcal{D}(i,j) \Gamma(s+j-1) \left( \theta_{n-m+i}^{n-m+s+j-2} - \sum_{l=1}^{n-m} \sum_{k=1}^{n-m} \left[ \Psi^{-1} \right]_{k,l} \theta_{l}^{n-m+s+j-2} \theta_{n-m+i}^{k-1} \right).$$

$$\lim_{s\to 0}\mathcal{M}_2\big(s-p+1\big)=0.$$

Proof

$$\begin{split} &\lim_{s \to 0} \mathcal{M}_{2}\left(s - p + 1\right) \\ &= L \sum_{j = p + 1}^{m} \sum_{i = 1}^{m} \mathcal{D}\left(i, j\right) \Gamma\left(-p + j\right) \\ &\times \left(\theta_{n - m - p + j - 1}^{n - m + j - 1} - \sum_{l = 1}^{n - m} \sum_{k = 1}^{m} \left[\boldsymbol{\Psi}^{-1}\right]_{k, l} \theta_{l}^{n - m - p + j - 1} \theta_{n - m + i}^{k - 1}\right) \\ &= L \sum_{j = p + 1}^{m} \sum_{i = 1}^{m} \left[\mathcal{D}\right]_{i, j} \left[\mathcal{C}\right]_{i, j - p} \\ &= L \sum_{j = p + 1}^{m} \left[\mathcal{D}^{t} \mathcal{C}\right]_{j, j - p}, \end{split}$$

where  $\mathcal D$  and  $\mathcal C$  are as defined in Lemma 1. Since  $\mathcal D$  is the cofactor of  $\mathcal C$ , then  $\mathcal D^t\mathcal C=\det\left(\mathcal C\right)\mathbf{I}_m$ . Therefore,  $\left[\mathcal D^t\mathcal C\right]_{i,j-p}=0$  for  $j=p+1,\cdots,m$ .

#### The first moment is more involved!

$$\begin{split} \mathbf{a}_j &= \left[\theta_1^{n-m-p+j-1}, \theta_2^{n-m-p+j-1}, \cdots, \theta_{n-m}^{n-m-p+j-1}\right]^t. \\ \mathbf{D}_i &= \operatorname{diag}\left[\log\left(\frac{\theta_{n-m+i}}{\theta_1}\right), \log\left(\frac{\theta_{n-m+i}}{\theta_2}\right), \cdots, \log\left(\frac{\theta_{n-m+i}}{\theta_{n-m}}\right)\right]. \\ \mathbf{b}_i &\triangleq \left[1, \theta_{n-m+i}, \cdots, \theta_{n-m+i}^{n-m-1}\right]^t. \end{split}$$

Proposition [1] Let  $q = \min(m, n - m)$ , then for  $1 \le p \le q$  we have

$$\begin{split} & \lim_{s \to 0} \mathcal{M}_1 \left( s - p + 1 \right) \\ & = L \sum_{j=1}^{p} \sum_{i=1}^{m} \mathcal{D} \left( i, j \right) \frac{(-1)^{p-j}}{(p-j)!} \mathbf{b}_i^t \mathbf{\Psi}^{-1} \mathbf{D}_i \mathbf{a}_j. \end{split}$$

#### Elements of the Proof

Some useful notations

$$\begin{split} \pmb{\psi}_s \triangleq \begin{bmatrix} \theta_1^s & \theta_1^{1+s} & \cdots & \theta_1^{n-m+s-1} \\ \vdots & \vdots & \ddots & \vdots \\ \theta_{n-m}^s & \theta_{n-m}^{1+s} & \cdots & \theta_{n-m}^{n-m+s-1} \end{bmatrix}, \pmb{\psi}_s = \pmb{\Psi} + o(s). \end{split}$$

$$\begin{split} \mathbf{a}_{s,j} &\triangleq \left[\theta_1^{n-m+s-p+j-1}, \theta_2^{n-m+s-p+j-1}, \cdots, \theta_{n-m}^{n-m+s-p+j-1}\right]^t.\\ \mathbf{b}_{s,i} &\triangleq \left[\theta_{n-m+i}^s, \theta_{n-m+i}^{1+s}, \cdots, \theta_{n-m+i}^{n-m+s-1}\right]^t.\\ \mathbf{b}_i &\triangleq \left[1, \theta_{n-m+i}, \cdots, \theta_{n-m+i}^{n-m-1}\right]^t.\\ \mathbf{e}_k &\triangleq \left[\mathbf{0}_{1\times(n-m-k-1)}, 1, \mathbf{0}_{1\times k}\right]^t,\\ k &= 0, \cdots, n-m-1, \end{split}$$

### Main idea: It starts with a simple observation

$$\begin{split} \pmb{\Psi}_s \triangleq \begin{bmatrix} \theta_1^s & \theta_1^{1+s} & \cdots & \theta_1^{n-m+s-p+j-1} & \theta_1^{n-m+s-1} \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ \theta_{n-m}^s & \theta_{n-m}^{1+s} & \cdots & \theta_{n-m}^{n-m+s-p+j-1} & \theta_{n-m}^{n-m+s-1} \end{bmatrix}, \end{split}$$

$$\begin{split} &\mathbf{a}_{s,j} \triangleq \left[\theta_1^{n-m+s-p+j-1}, \theta_2^{n-m+s-p+j-1}, \cdots, \theta_{n-m}^{n-m+s-p+j-1}\right]^t.\\ &\mathbf{b}_{s,i} \triangleq \left[\theta_{n-m+i}^s, \theta_{n-m+i}^{1+s}, \cdots, \theta_{n-m+i}^{n-m+s-1}\right]^t. \end{split}$$

$$\begin{array}{l} \Psi_s \mathbf{e}_{p-j} = \mathbf{a}_{s,j} \text{ and } \mathbf{b}_{s,i}^t \mathbf{e}_{p-j} = \theta_{n-m+i}^{n-m+s-p+j-1} \Longrightarrow \Psi_s^{-1} \mathbf{a}_{s,j} = \mathbf{e}_{p-j} \text{ and consequently } \\ \mathbf{b}_{s,i}^t \Psi_s^{-1} \mathbf{a}_{s,j} = \theta_{n-m+i}^{n-m+s-p+j-1}. \end{array}$$

Therefore,

$$\theta_{n-m+i}^{n-m+s-p+j-1} - \mathbf{b}_{s,i}^t \mathbf{\Psi}_s^{-1} \mathbf{a}_{s,j} = 0.$$

$$\begin{split} \mathcal{M}_{1}\left(s-p+1\right) &= L \sum_{j=1}^{p} \sum_{i=1}^{m} \mathcal{D}\left(i,j\right) \Gamma\left(s-p+j\right) \left(\theta_{n-m+i}^{n-m+s-p+j-1} - \sum_{l=1}^{n-m} \sum_{k=1}^{m-m} \left[\Psi^{-1}\right]_{k,l} \theta_{l}^{n-m+s-p+j-1} \theta_{n-m+i}^{k-1}\right) \\ &= L \sum_{j=1}^{p} \sum_{i=1}^{m} \mathcal{D}\left(i,j\right) \Gamma\left(s-p+j\right) \left(\theta_{n-m+i}^{n-m+s-p+j-1} - \mathbf{b}_{l}^{t} \Psi^{-1} \mathbf{a}_{s,j}\right) \end{split}$$

Substract and add  $\mathbf{b}_{i}^{t}\mathbf{\Psi}_{s}^{-1}\mathbf{a}_{s,j}$ 

$$=L\sum_{j=1}^{p}\sum_{i=1}^{m}\mathcal{D}\left(i,j\right)\Gamma\left(s-p+j\right)\left(\theta_{n-m+i}^{n-m+s-p+j-1}-\mathbf{b}_{i}^{t}\boldsymbol{\Psi}_{s}^{-1}\mathbf{a}_{s,j}\right)+L\sum_{j=1}^{p}\sum_{i=1}^{m}\mathcal{D}\left(i,j\right)\Gamma\left(s-p+j\right)\times\mathbf{b}_{i}^{t}\left(\boldsymbol{\Psi}_{s}^{-1}-\boldsymbol{\Psi}^{-1}\right)\mathbf{a}_{s,j}$$

Substract and add  $\mathbf{b}_{s,i}^t \mathbf{\Psi}_s^{-1} \mathbf{a}_{s,j}$ 

$$\begin{split} &=L\sum_{j=1}^{p}\sum_{i=1}^{m}\mathcal{D}\left(i,j\right)\Gamma\left(s-p+j\right)\left(\theta_{n-m+i}^{n-m+s-p+j-1}-\mathbf{b}_{s,i}^{t}\mathbf{\Psi}_{s}^{-1}\mathbf{a}_{s,j}\right)+L\sum_{j=1}^{p}\sum_{i=1}^{m}\mathcal{D}\left(i,j\right)\Gamma\left(s-p+j\right)\\ &\times\left(\mathbf{b}_{s,i}^{t}-\mathbf{b}_{i}^{t}\right)\mathbf{\Psi}_{s}^{-1}\mathbf{a}_{s,j}+L\sum_{i=1}^{p}\sum_{i=1}^{m}\mathcal{D}\left(i,j\right)\Gamma\left(s-p+j\right)\mathbf{b}_{i}^{t}\left(\mathbf{\Psi}_{s}^{-1}-\mathbf{\Psi}^{-1}\right)\mathbf{a}_{s,j} \end{split}$$

 $\bullet \quad \theta^s - 1 = s \log \theta + o(s).$ 

$$\begin{aligned} \mathbf{b}_{s,i} - \mathbf{b}_{i} &= s \left[ \log \left( \theta_{n-m+i} \right), \theta_{n-m+i} \log \left( \theta_{n-m+i} \right), \dots, \theta_{n-m+i}^{n-m-1} \log \left( \theta_{n-m+i} \right) \right]^{t} + o \left( s \right) \\ &= s \log \left( \theta_{n-m+i} \right) \mathbf{b}_{i} + o \left( s \right), \end{aligned}$$

For non positive arguments -k,  $k = 0, 1, \dots$ 

$$\Gamma(s-p+j) = \frac{(-1)^{p-j}}{s \to 0} + o(s).$$

٠

$$\Gamma(s-p+j)\left(\mathbf{b}_{s,i}^{t}-\mathbf{b}_{i}^{t}\right)\mathbf{\Psi}_{s}^{-1}\mathbf{a}_{s,j}$$

$$=\frac{\left(-1\right)^{p-j}\log\left(\theta_{n-m+i}\right)}{\left(p-j\right)!}\mathbf{b}_{i}^{t}\mathbf{\Psi}^{-1}\mathbf{a}_{j}+o(s)$$

The resolvent identity

$$\Psi_s^{-1} - \Psi^{-1} = \Psi_s^{-1} (\Psi - \Psi_s) \Psi^{-1}$$

Finally,

$$(\Psi - \Psi_s) = -s\Phi\Psi + o(s), \Phi = \operatorname{diag}(\log \theta_i, i = 1, \dots n - m).$$

## Possible Applications

 Performance of linear estimators such as the LS (correlated channel), or the best linear unbiased estimator (BLUE) when the noise in correlated.

$$y = Hv + z, (4)$$

$$\hat{\mathbf{v}}_{blue} = \left(\mathbf{H}^* \mathbf{\Sigma}_z^{-1} \mathbf{H}\right)^{-1} \mathbf{H}^* \mathbf{\Sigma}_z^{-1} \mathbf{y}$$

$$= \mathbf{v} + \left(\mathbf{H}^* \mathbf{\Sigma}_z^{-1} \mathbf{H}\right)^{-1} \mathbf{H}^* \mathbf{\Sigma}_z^{-1} \mathbf{z}$$

$$= \mathbf{v} + \mathbf{e}_{blue},$$
(5)

$$\mathbb{E}_{\mathbf{H}}\{\|\hat{\mathbf{v}}_{blue} - \mathbf{v}\|^{2}\} = \mathbb{E}_{\mathbf{H}} \operatorname{trace}\left(\mathbf{\Sigma}_{e,blue}\right)$$

$$= \mathbb{E}_{\mathbf{H}} \operatorname{trace}\left(\left(\mathbf{H}^{*}\mathbf{\Sigma}_{z}^{-1}\mathbf{H}\right)^{-1}\right)$$

$$= m\mu_{\mathbf{\Lambda}}\left(-1\right),$$
(6)

where  $\Lambda = \Sigma_z^{-1}$ .

Approximation of the LMMSE error

$$\mathbb{E}_{\mathbf{H}}\{\|\hat{\mathbf{x}}_{lmmse} - \mathbf{x}\|^{2}\} = \mathbb{E}_{\mathbf{H}} \operatorname{trace}\left(\mathbf{\Sigma}_{e, lmmse}\right)$$

$$= \mathbb{E}_{\mathbf{H}} \operatorname{trace}\left(\mathbf{\Sigma}_{\mathbf{x}}^{-1} + \mathbf{H}^{*}\mathbf{\Sigma}_{\mathbf{z}}^{-1}\mathbf{H}\right)^{-1}.$$
(7)

#### Theorem

Let  $\Lambda = \Sigma_z^{-1}$  and  $\Sigma_x = \sigma_x^2 I$ . Then, the LMMSE average estimation error at both the high SNR regime  $(\sigma_x^2 \gg 1)$  and the low SNR regime  $(\sigma_x^2 \ll 1)$  is given by

1. High SNR regime

$$\mathbb{E}_{\mathbf{H}} \{ \| \hat{\mathbf{x}}_{lmmse} - \mathbf{x} \|^2 \}$$

$$= m \sum_{k=0}^{p} \frac{(-1)^k}{\sigma_X^{2k}} \mu_{\mathbf{\Lambda}} (-k-1) + o(\sigma_X^{-2p}),$$
(8)

where  $p \le q - 1$  with  $q = \min(m, n - m)$ .

2. Low SNR regime

$$\mathbb{E}_{\mathbf{H}}\{\|\hat{\mathbf{x}}_{lmmse} - \mathbf{x}\|^2\} = m \sum_{k=0}^{\infty} (-1)^k \sigma_{\mathbf{x}}^{2k+2} \mu_{\mathbf{\Lambda}}(k).$$
 (9)

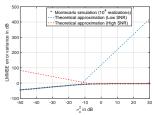


Figure: LMMSE mean square error with  $\Sigma_z$  modeled as Bessel correlation matrix: Montecarlo simulation versus theoretical approximations.

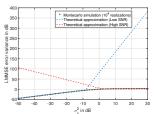


Figure: LMMSE mean square error with  $\Sigma_z$  modeled as random correlation matrix: Montecarlo simulation versus theoretical approximations.

Sample Correlation Matrix (SCM)

$$R = \mathbb{E}\left[uu^*\right],$$

where  $\mathbf{u}(k) = \mathbf{R}^{\frac{1}{2}}\mathbf{x}(k)$  and  $\mathbf{x}(k) \sim \mathcal{CN}(\mathbf{0}, \mathbf{I}_m)$ . To estimate  $\mathbf{R}$ , we refer to the SCM as

$$\hat{\mathbf{R}}(n) = \frac{1}{n} \sum_{k=1}^{n} \mathbf{u}(k) \mathbf{u}^{*}(k)$$

- \*The SCM is the maximum likelihood (ML) estimator of R.
- \* For fixed *m* and large *n*

$$\|\mathbf{R} - \hat{\mathbf{R}}(n)\| \to 0$$
, a.s.

The SCM may not be robust for finite dimensions! Exponentially weighted SCM

$$\hat{\mathbf{R}}(n) = (1 - \lambda) \sum_{k=1}^{n} \lambda^{n-k} \mathbf{u}(k) \mathbf{u}^{*}(k)$$
$$= \mathbf{R}^{\frac{1}{2}} \mathbf{X} \mathbf{\Lambda}(n) \mathbf{X}^{*} \mathbf{R}^{\frac{1}{2}},$$

where  $\Lambda(n) = (1 - \lambda) \operatorname{diag}(\lambda^{n-1}, \lambda^{n-2}, \dots, 1)$ .

$$Loss(n) \triangleq \mathbb{E} \left\| \mathbf{R}^{\frac{1}{2}} \hat{\mathbf{R}}^{-1}(n) \mathbf{R}^{\frac{1}{2}} - \mathbf{I}_{m} \right\|_{Fro}^{2}.$$

## Lemma

Let  $\mathbf{S}_n = \mathbf{X} \mathbf{\Lambda} (n) \mathbf{X}^*$ . Then, the loss can be expressed as a function of inverse moments of  $\mathbf{S}_n$  as

Loss 
$$(n) = m (1 + \mu_{\Lambda(n)} (-2) - 2\mu_{\Lambda(n)} (-1)).$$
 (10)

#### How to choose $\lambda$ ?

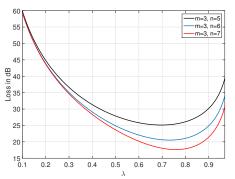


Figure: The estimation loss as a function of the forgetting factor  $\lambda$ .

## Large RMT (Asymptotic Approach)

## The Stieltjes Transform (ST)

For a probability measure  $\mathbb{P}$ , the associated ST is defined as

$$S_{\mathbb{P}}(z) = \int_{\mathbb{R}} \frac{\mathbb{P}(d\lambda)}{\lambda - z}, \ z \in \mathbb{C}^+$$

### Spectral Measure

$$\mathcal{E}\left(\mathbf{A}\right) = \frac{1}{m} \sum_{i} \delta_{\lambda_{i}}.$$

Then.

$$S_{\mathcal{E}}(z) = \frac{1}{m} \sum_{i} \frac{1}{\lambda_{i} - z}$$
$$= \frac{1}{m} \operatorname{trace} (\mathbf{A} - z\mathbf{I})^{-1}.$$

It follows that.

$$\left(\frac{\partial^k \mathcal{S}_{\mathcal{E}}(z)}{\partial z^k}\right)_{z=0} = \frac{k!}{m} \operatorname{tr}\left(\mathbf{A}^{-(k+1)}\right).$$

Theorem (Silverstein and Bai) Consider the Gram matrix  $S = \frac{1}{m}X^*\Lambda X$  with ST s(z).

- ▶ The entries of **X** are Gaussian i.i.d with zero mean and unit variance.
- $m, n \to \infty$  with  $\frac{m}{n} \to c \in (0, \infty)$ .
- Λ is nonnegative definite matrix with

$$\mathcal{E}(\mathbf{\Lambda}) \xrightarrow{n \to \infty} dH(\tau).$$

Then, the ST of S, s(z) satisfies

$$s(z) = \left(-z + c \int \frac{\tau dH(\tau)}{1 + \tau s(z)}\right)^{-1} \tag{11}$$

$$\approx \left(-z + c.\operatorname{trace}\left[\mathbf{\Lambda}\left(\mathbf{I} + s(z)\mathbf{\Lambda}\right)^{-1}\right]\right)^{-1} \tag{12}$$

$$=\frac{1}{-z+\frac{1}{m}\sum_{k=1}^{n}\frac{\lambda_{k}}{1+\lambda_{k}s(z)}}.$$
 (13)

$$s_0^{(k)} = \left(\frac{\partial^k s(z)}{\partial z^k}\right)_{z=0} = \frac{k!}{m} \operatorname{tr}\left(\mathbf{S}^{-(k+1)}\right).$$

How to obtain the higher order moments ?

## Higher order moments

Let  $p \ge 1$  and  $f_k(z) = -\frac{1}{1+[D]_{k,k}S(z)}$ . Denote by  $f_k^{(p)}$  the p-th derivative of  $f_k(z)$  at z = 0. Then, the following relations hold true:

$$\rho s_{0}^{(p-1)} + \frac{s_{0}^{(p)}}{m} \sum_{k=1}^{n} \frac{[\mathbf{D}]_{k,k} f_{k}^{(0)}}{1 + [\mathbf{D}]_{k,k} s(0)} + \frac{1}{m} \sum_{k=1}^{n} \sum_{l=1}^{p-1} {p \choose l} \frac{[\mathbf{D}]_{k,k} s_{0}^{(l)} f_{k}^{(p-l)}}{1 + [\mathbf{D}]_{k,k} s(0)} = 0,$$
(14)

$$f_{k}^{(p)} + \frac{[\mathbf{D}]_{k,k} s_{0}^{(p)} f_{k}^{(0)}}{1 + [\mathbf{D}]_{k,k} s(0)} + \sum_{l=1}^{p-1} {p \choose l} \frac{[\mathbf{D}]_{k,k} s_{0}^{(l)} f_{k}^{(p-l)}}{1 + [\mathbf{D}]_{k,k} s(0)} = 0.$$
 (15)

# **Algorithm 1** Asymptotic inverse moments computation

- 1: Compute s(0) using (22) 2: Compute  $f_k(0) = -\frac{1}{1+[D]_{k,k}s(0)}$
- 3: for  $i = 1 \rightarrow p$  do
- 4: compute  $s_0^{(i)}$  using (14)
- 5: compute  $f_{k}^{(i)}$  using (15)

#### Numerical validation

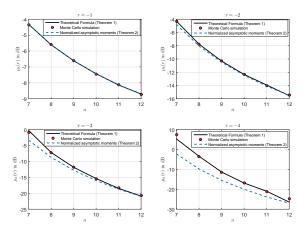


Figure: Inverse moments for  $\Lambda$  modeled as Bessel Correlation matrix: A comparison between theoretical result (Theorem 1), normalized asymptotic moments (Theroem 2) and Monte Carlo simulations ( $10^5$  realizations).

Some history on RMT

Background on Random Matrix Theory (RMT)

Inverse Moments of One-Sided Correlated Gram Matrices

## Blind Measurement Selection

Summary

$$y = Hx + z, z \sim CN(0, R).$$

The covariance of the estimation error vector is given by

$$\mathbf{\Sigma} = \left(\mathbf{H}^* \mathbf{R}^{-1} \mathbf{H}\right)^{-1}.$$

### Popular measures for the quality of estimation

Mean square error

$$MSE = trace(\Sigma), f(x) = \frac{1}{x}.$$

► The log volume of the concentration ellipsoid (VCE)

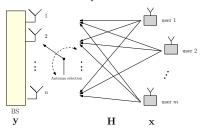
$$VCE \propto -\log \det (\Sigma), f(x) = -\log x.$$

Worst case error variance (WEV)

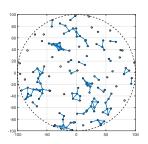
$$WEV = \max_{\|\mathbf{q}\|=1} \mathbf{q}^T \mathbf{\Sigma} \mathbf{q} = \max_{i} \lambda_i \left( \mathbf{\Sigma} \right) = \lambda_{max} \left( \mathbf{\Sigma} \right),$$

## Measurement selection

Antenna selection in massive MIMO systems.



Sensor selection.



$$y = Hx + z$$
.

$$\mathbf{y}_{\mathcal{S}} = \mathbf{S}\mathbf{y},\tag{16}$$

where S is defined as follows

$$[\mathbf{S}]_{i,j} = \begin{cases} 1 & j = \mathcal{S}[i] \\ 0 & \text{otherwise} \end{cases}, i = 1, \dots, k.$$
 (17)

Ee have the following properties

- $\triangleright$  SS<sup>T</sup> =  $I_k$ .
- ▶  $S^TS = diag(s)$ .

where  $\mathbf{s} = \{s_i\}_{i=1,\dots,n}$ .

The resultant error covariance matrix, which we denote by  $\Sigma_{\mathcal{S}}$ , easily writes as

$$\Sigma_{\mathcal{S}} = \left(\mathbf{H}^{H} \mathbf{S}^{T} \left(\mathbf{S} \mathbf{R} \mathbf{S}^{T}\right)^{-1} \mathbf{S} \mathbf{H}\right)^{-1}$$

$$= \left(\mathbf{W}^{H} \mathbf{R}^{\frac{1}{2}} \operatorname{diag}\left(\mathbf{s}\right) \mathbf{R}^{\frac{1}{2}} \mathbf{W}\right)^{-1}.$$
(18)

How to choose s?

Mathematically speaking, a general formulation of the selection problem can be illustrated as follows

$$S^* = \underset{S}{\operatorname{argmin}} \quad f(\mathbf{\Sigma}_S)$$
s.t. 
$$S \subseteq \{1, \dots, n\}$$

$$|S| = k.$$
(19)

where f = MSE, VCE, WEV.

 $\rightarrow$  NP hard problem (we don't know an algorithm that can solve the problem in a polynomial time).

Convex Relaxation (Joshi and Boyd)

$$\widehat{\mathbf{s}} = \underset{\mathbf{s}}{\operatorname{argmin}} \quad f(\mathbf{s})$$
s.t. 
$$\mathbf{1}^{T} \mathbf{s} = k$$

$$0 \le s_{i} \le 1, i = 1, \dots, n.$$
(20)

 $\rightarrow$  polynomial complexity of  $\mathcal{O}\left(n^3\right)$ 

What if the channel **H** is time-varying ? Best we can do is  $NO(n^3)$  so far!

$$\widehat{S} = \underset{S}{\operatorname{argmin}} \quad \overline{f(\Sigma_{S})}$$
s.t. 
$$S \subseteq \{1, \dots, n\}$$

$$|S| = k.$$
(21)

where  $\overline{f(\mathbf{\Sigma}_{S})}$  is an approximation of  $f(\mathbf{\Sigma}_{S})$  (Deterministic equivalent, DE). Some useful DEs

MSE

$$s(0) = \frac{1}{\frac{1}{m} \sum_{k=1}^{n} \frac{\lambda_k}{1 + \lambda_k c(0)}}.$$
 (22)

VCE

$$\overline{\mathcal{I}} = \log \det \left( \mathbf{I}_n + \frac{c}{\overline{\delta}} \mathbf{D} \right) + m \log \left( \overline{\delta} \right) - nc, \quad \overline{\delta} = \frac{1}{n} \mathrm{tr} \left[ \mathbf{D} \left( \mathbf{I}_n + \frac{c}{\overline{\delta}} \mathbf{D} \right)^{-1} \right].$$

$$\mathbf{D} = \operatorname{diag}(\theta_1, \dots, \theta_n)$$
.

WEV

$$\overline{\lambda} = \left(-\frac{1}{\underline{m}} + \int \frac{t}{1 + c\underline{m}t} \nu(t) dt\right), \quad \underline{m}^2 = \frac{1}{c} \left(\int \frac{t^2}{(1 + c\underline{m}t)^2} \nu(t) dt\right)^{-1}.$$

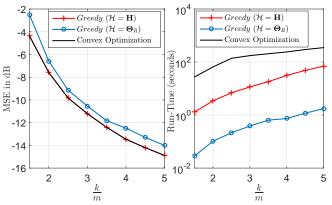
# Algorithm 2 Greedy Approach for Antenna Selection

```
1: Initialize S = randsample(n, k)
                                                                \triangleright randomly generate a pattern of size k
2: Compute metric* = f(\mathcal{H}, \mathcal{S})
3: for i = 1 \rightarrow \#iterations do
        \overline{S} = \{1, \dots, n\} \setminus S
 5:
       i \leftarrow 1
6:
       while j \le n - k do
               p \leftarrow \overline{S}[j]
 7:
8:
                T \leftarrow S
9:
                table \leftarrow zeros (k, 1)
10:
                 for l = 1 \rightarrow k do
11:
                      \mathcal{I}[I] \leftarrow p
12:
                      table [I] \leftarrow f(\mathcal{H}, \mathcal{I})
13:
                      T \leftarrow S
14:
                 if min(table) < metric* then
15:
                      metric* ← min (table)
16:
                      S[arg min (table)] \leftarrow p
```

Complexity of  $\mathcal{O}(n^2)$ .

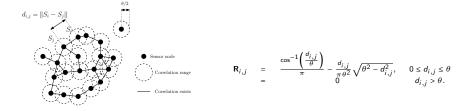
### Performance

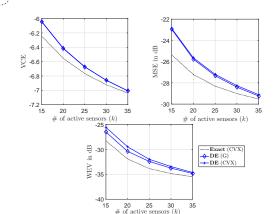
• Antennas selection in Massive MIMO:  $\mathbf{R}_{i,j} = \lambda^{|i-j|}$ .



**Figure:** Average MSE (over N=100 channel realizations) and Run-time vs. the ratio  $\frac{k}{m}$  for  $\Theta_R=$  Toeplitz ( $\lambda=0.75$ ). m=10 users, n=1.25k and  $\rho=10$  dB.

## Sensor selection:





Some history on RMT

Background on Random Matrix Theory (RMT)

Inverse Moments of One-Sided Correlated Gram Matrices

Blind Measurement Selection

Summary

- Exact derivation of the inverse moments of Gram matrices with one-sided correlation.
- Correlation can be exploited to figure out the potential measurements in a linear system.
- ▶ Good performances in some practical scenarios (massive MIMO and WSN).
- ▶ The case of identical eigenvalues is still an open question.

Thank you for your attention