```matlab
% HW_03_CODE_01.m
% Authors: Karl Parks and Jaden Bowyer
% x = theta
% v = theta_dot
% w = omega

%clear; clc; close all;

x_0 = (2/180)*pi;
v_0 = -1/100;

w_n = 10;

t_0 = 0;
t_f = (3*pi)/(2*w_n);
t = linspace(t_0,t_f,1000);

phi = atan(x_0 * w_n/v_0);
X = x_0/sin(phi);

x = X * sin(w_n*t + phi);
fig1 = figure;
plot(t,x)
xlabel('$t$ [s]', 'Interpreter','latex');
ylabel('$\theta(t)$ [rad]', 'Interpreter','latex');
title('Undamped Response');
grid on;
```