

# 1 Classification and Representation

## 1.1 Classification

The **classification problem** is just like the regression problem, except that *the values we now want to predict take on only a small number of discrete values*.

For now, we will focus on the binary classification problem in which  $y$  can take on only two values, 0 and 1. (Most of what we say here will also generalize to the multiple-class case.) For instance, if we are trying to build a spam classifier for email, then  $x^{(i)}$  may be some features of a piece of email, and  $y$  may be 1 if it is a piece of spam mail, and 0 otherwise. Hence,  $y \in \{0, 1\}$ .

0 is also called the negative class, and 1 the positive class, and they are sometimes also denoted by the symbols  $-$  and  $+$ . Given  $x^{(i)}$ , the corresponding  $y^{(i)}$  is also called the label for the training example.

To attempt classification, one method is to use linear regression and map all predictions greater than 0.5 as a 1 and all less than 0.5 as a 0. However, this method doesn't work well because classification is not actually a linear function.

**Logistic Regression** is a classification algorithm that we apply to settings where the label  $y$  is discrete value, when it's either zero or one.

Don't be confused by the name "**Logistic Regression**"; it is named that way for historical reasons and is actually an approach to classification problems, not regression problems.

## 1.2 Hypothesis Representation

We could approach the classification problem ignoring the fact that  $y$  is discrete-valued, and use our old linear regression algorithm to try to predict  $y$  given  $x$ . However, it is easy to construct examples where this method performs very poorly.

Intuitively, it also doesn't make sense for  $h_{\theta}(x)$  to take values larger than 1 or smaller than 0 when we know that  $y \in \{0, 1\}$ .

To fix this, let's change the form for our hypotheses  $h_{\theta}(x)$  to satisfy  $0 \leq h_{\theta}(x) \leq 1$ . This is accomplished by plugging  $\theta^T x$  into the Logistic Function.

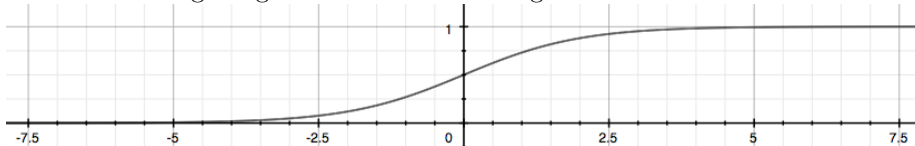
Our new form uses the "**Sigmoid Function**," also called the "**Logistic Function**":

$$h_{\theta}(x) = g(\theta^T x)$$

$$z = \theta^T x$$

$$g(z) = \frac{1}{1 + e^{-z}}$$

The following image shows us what the sigmoid function looks like:



The function  $g(z)$ , shown here, maps any real number to the  $(0, 1)$  interval, making it useful for transforming an arbitrary-valued function into a function better suited for classification.

$h_\theta(x)$  will give us the probability that our output is 1. For example,  $h_\theta(x) = 0.7$  gives us a probability of 70% that our output is 1. Our probability that our prediction is 0 is just the complement of our probability that it is 1 (e.g. if probability that it is 1 is 70%, then the probability that it is 0 is 30%).

$$\begin{aligned}h_\theta(x) &= P(y = 1|x; \theta) = 1 - P(y = 0|x; \theta) \\P(y = 0|x; \theta) + P(y = 1|x; \theta) &= 1\end{aligned}$$

### 1.3 Decision Boundary

In order to get our discrete 0 or 1 classification, we can translate the output of the hypothesis function as follows:

$$\begin{aligned}h_\theta(x) \geq 0.5 &\rightarrow y = 1 \\h_\theta(x) < 0.5 &\rightarrow y = 0\end{aligned}$$

The way our logistic function  $g$  behaves is that when its input is greater than or equal to zero, its output is greater than or equal to 0.5:

$$\begin{aligned}g(z) &\geq 0.5 \\&\text{when } z \geq 0\end{aligned}$$

Remember.

$$\begin{aligned}z = 0, e^0 = 1 &\Rightarrow g(z) = 1/2 \\z \rightarrow \infty, e^{-\infty} \rightarrow 0 &\Rightarrow g(z) = 1 \\z \rightarrow -\infty, e^{\infty} \rightarrow \infty &\Rightarrow g(z) = 0\end{aligned}$$

So if our input to  $g$  is  $\theta^T X$ , then that means:

$$\begin{aligned}h_\theta(x) = g(\theta^T x) &\geq 0.5 \\&\text{when } \theta^T x \geq 0\end{aligned}$$

From these statements we can now say:

$$\begin{aligned}\theta^T x \geq 0 &\Rightarrow y = 1 \\ \theta^T x < 0 &\Rightarrow y = 0\end{aligned}$$

The **decision boundary** is the line that separates the area where  $y = 0$  and where  $y = 1$ . It is created by our hypothesis function.

**Example:**

$$\theta = \begin{bmatrix} 5 \\ -1 \\ 0 \end{bmatrix}$$

$$y = 1 \text{ if } 5 + (-1)x_1 + 0x_2 \geq 0$$

$$5 - x_1 \geq 0$$

$$-x_1 \geq -5$$

$$x_1 \leq 5$$

In this case, our decision boundary is a straight vertical line placed on the graph where  $x_1 = 5$ , and everything to the left of that denotes  $y = 1$ , while everything to the right denotes  $y = 0$ .

Again, the input to the sigmoid function  $g(z)$  (e.g.  $\theta^T X$ ) doesn't need to be linear, and could be a function that describes a circle (e.g.  $z = \theta_0 + \theta_1 x_1^2 + \theta_2 x_2^2$ ) or any shape to fit our data.